# RUSSIAN MARITIME REGISTER OF SHIPPING

CIRCULAR LETTER	No. 311-09-1922c	2c dated 12.04.2023					
Re:							
amendments to the Rules ND No. 2-020101-174-E	for the Classification	and Construction	of Sea-Going Ships, 202				
Item(s) of supervision:							
ships under construction and t	echnical documentation						
Entry-into-force date: 01.06.2023							
Cancels / amends / adds Circu	ular Letter No.	312-10-1898	dated 17.02.2023				
Number of pages: 1 + 6	3						
Appendices:							
Appendix 1: information on an	nendments introduced by	y the Circular Letter					
Appendix 2: text of amendmer	nts to Part I "Classification	on"					
Director General	Sergey A. Kulikov						
Text of CL:							
We hereby inform that the R amended as specified in the A	ules for the Classificati ppendices to the Circula	on and Construction ar Letter.	n of Sea-Going Ships shall l				
It is necessary to do the follow	/ing:						
1. Bring the content of the Circular Letter to the notice of the RS surveyors, interested organizations and persons in the area of the RS Branch Offices' activity.							
2. Apply the provisions of the	2. Apply the provisions of the Circular Letter during review and approval of the technical documentation						
on snips (or equipment inst contracted for construction	alled on board the ships, or conversion on or aff	, or products/machin	ery installed on board the ship e absence of a contract, duri				
review and approval of the technical documentation on ships requested for review on or							
after 01.06.2023.							
3. Apply the provisions of the Circular Letter during review of the technical documentation on ships under construction and in service upon request of the interested parties.							
List of the amended and/or introduced paras/chapters/sections:							
Part I: para 3.2.8							
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"Thesis" System No. 23-55824

# Information on amendments introduced by the Circular Letter (for inclusion in the Revision History to the RS Publication)

Nos.	Amended	Information on amendments	Number	Entry-into-force
	paras/chapters/		and date of the	date
	sections		Circular Letter	
1	Para 3.2.8	Requirements for the scope of documentation to be submitted have been specified	311-09-1922c of 12.04.2023	01.06.2023

## **RULES FOR THE CLASSIFICATION AND CONSTRUCTION OF SEA-GOING SHIPS, 2023**

# ND No. 2-020101-174-E

#### PART I. CLASSIFICATION

#### **3 TECHNICAL DOCUMENTATION**

Para 3.2.8 is replaced by the following text:

## "3.2.8 Documentation on automation equipment.

#### 3.2.8.1 General documentation.

No.	Description of documentation	Stamp	TD	DD	PAD	Remarks
.1	Technical description of automation systems and devices with indication of their	AG	•			
	purpose and principle of operation					
.2	Technical description of automation systems and devices with indication of their purpose, principle of operation, their functions, configuration, self-diagnosis principles, with mandatorily designated system integrator (shipyard or, by cooperation, contracted alternative organization/supplier) for each system as well as consoles and control and monitoring switchboards in the main machinery control room and on the navigation bridge	AG			•	
.3	List of controlled parameters with indication of unique identifier, parameter description, type of signal (i.e. analogue/digital, input/output, etc.), distribution by automation systems and devices depending on the signal intended functional purpose (control, alarms, protection, indication), distribution by automation equipment groups	A	•		•	
.4	General arrangement plans of automation equipment in the main machinery control room and on the navigation bridge	A	•		•	

No.	Description of documentation	Stamp	TD	DD	PAD	Remarks
.5	Diagrams of power supply for automation systems: alarm and monitoring systems (AMS), centralized monitoring systems and integrated control systems and AMS, remote automated control systems for main machinery and propellers.	A	•	•	•	
	automation systems of auxiliary engines and electric power plant, automation					
	systems of boiler plant, automation systems of compressor plants, automation					
	system of bilge and ballast systems, remote level indicating systems					
-	Technical background containing the design intent of a dynamic positioning	AG	•		•	
+.6	system with indication of the equipment redundancy level for ships with					
	distinguishing marks DYNPOS-2 or DYNPOS-3 in the class notation, with					
	substantiation of the worst-case failure design intent when, after occurrence of					
	the worst-case failure, the ship will be able to keep heading and/or position in the					
	specified environmental conditions					
.7	Failure modes and effects analysis (FMEA — failure mode and effects analysis,	AG	•	•	•	
	refer to 8.2.1 of Part XV "Automation") of dynamic positioning system taking into					
•	account the design intent as specified in 3.2.8.1.6 of this Part	•				
.0	including thrusters/propulsion unit switchboards and papels of dynamic	A	•		•	
	nositioning system with indication of main and back-up (if any) control stations					
	automated manual and emergency controls emergency stops position reference					
	systems and external force sensors					
.9	Drawings of cable runs (power and control cables) with indication of their	А	•	•	•	
	penetrations through watertight and fire-fighting bulkheads of ships with					
	distinguishing mark <b>DYNPOS-3</b> in the class notation					
.10	Arrangement plans of the dynamic positioning system equipment on ships with	A	•		•	
	distinguishing mark DYNPOS-3 in the class notation with indication of boundaries					
	formed by fire-fighting bulkheads of "A-60" class and watertight bulkheads. The					
	plans shall specify the layout of ventilation equipment, pipelines of fuel oil system,					
	cooling system and other equipment affecting dynamic positioning system					
	operation, as well as specify passive fire protection ("A-60" class fire-protective					
44	ducts), if any	^				
	Functional diagrams of thruster and steering gear loop monitoring systems if the	A	•		•	
	aller is a part of the dynamic positioning system, including diagrams of					
12	Technical description of thruster/propulsion system on ships with dynamic	AG	•			
.12	nositioning system including performance and consumption diagrams	AG	•			
	assessment of performance loss resulting from interaction with the hull and other					
	devices, time delays when changing the value and direction of thrust with					
	indication of all protection settings that may restrict device performance					

#### 3.2.8.2 Documentation on individual automation systems, consoles and control and monitoring switchboards.

Technical documentation listed in 3.2.8.2 shall be submitted by the designer or system integrator specified in 3.2.8.1.2 of this Part. In the latter case, the documentation shall be developed taking into account the solutions adopted in technical documentation listed in 3.2.8.1 of this Part, and submitted for approval at the stage of delivery and installation to the RS Branch Office for technical supervision during construction together with the documentation according to 1.4.1 of Part XV "Automation" of these Rules approved during technical supervision of automation equipment as required by Section 12 of Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision during Construction of Ships and Manufacture of Materials and Products for Ships.

No.	Description of documentation	Stamp	TD	DD	PAD	Remarks
.1	Functional diagrams of AMS, centralized monitoring systems, computer-based	A	•			
	and integrated control systems and AMS, including diagrams of power supply					
.2	Technical documentation on alarm and monitoring systems (AMS), centralized	A			•	
	monitoring systems and integrated control systems and AMS, including functional					
	diagrams, face panels of consoles and control and monitoring switchboards with					
	indication of all devices, diagrams of power supply					
.3	Technical documentation on remote automated control for main engines and	A	•		•	
	propellers: including functional diagrams, remote automated control console					
	panels with indication of all devices, diagrams of power supply of remote					
	automated control					
.4	Technical documentation on automation of auxiliary engines and electric power	A	•		•	
	plant, functional diagrams and face panels of consoles and control and monitoring					
	switchboards for electric power plant with indication of all devices	-				
.5	Technical documentation on automation of boiler plant: functional diagrams and	A	•		•	
	face panels of consoles and control and monitoring switchboards with indication					
	of all devices					
.6	Functional diagrams of automation of compressor plants	A	•		•	
.7	Functional diagrams of automation and remote control of bilge and ballast	A	•		•	
	systems	-				
.8	Functional diagrams of remote level indicating systems	A	•		•	
.9	Diagrams of electric connections for automation systems and equipment: alarm	A		•	•	
	and monitoring systems (AMS), centralized monitoring systems and integrated					
	control systems and AMS, remote automated control systems for main machinery					
	and propellers, automation system of auxiliary engines and electric power plant,					
	automation system of boiler plant, automation system of compressor plants,					
	automation system of bilge and ballast systems, remote level indicating systems					
	(with indication of cable types and places of installation of all system elements					
	and devices)					

No.	Description of documentation	Stamp	TD	DD	PAD	Remarks
.10	Drawings of face panels of consoles and control and monitoring switchboards in the main machinery control room and on the navigation bridge with indication of all devices	A			•	
.11	Failure modes and effects analysis of dynamic positioning system if it is not included in the document specified in 3.2.8.1.7	AG	٠		•	
.12	Drawings of panels of main and back-up (for <b>DYNPOS-3</b> ) control stations of dynamic positioning system with indication of location of controls, thruster emergency stops, alarm devices, indicators and internal communications	A	•		•	
.14	List of critical components of dynamic positioning system	AG	٠	•	•	
.15	Blackout recovery procedure for dynamic positioning system	AG		•	•	
.16	Capability plots demonstrating ship's position keeping capacity at least for fully effective dynamic positioning system and post worst-case failure condition for particular environmental conditions	AG		•	•	
.17	Functional diagrams of computer-based dynamic positioning control system with indication of inputs and outputs with feedbacks and power supplies	A		•	•	
.18	List of alarm signals displayed on the main control station by dynamic positioning system	AG		•	•	
.19	Specification of means of two-way internal communication including the list of equipment, characteristics, operation conditions, connection diagrams, description of user interface for ships with dynamic positioning system	AG		•	•	
.20	Functional diagrams of fire protection system including control system over spraying of fire extinguishing medium, including all control panels and control circuit monitoring system for ships having distinguishing mark <b>DYNPOS-2</b> in the class notation	A	•		•	
.21	Specification of protection system of electrical power plant for ships having distinguishing mark <b>DYNPOS-2</b> and <b>DYNPOS-3</b> in the class notation in a form of analysis of protection means that may include: results of short circuit calculation; report with description of selective protection for power distribution systems; FMEA from system manufacturers/suppliers, in particular, for common elements and automatic changeover systems between redundancy groups; results of factory acceptance tests for system with extended generator protection; analysis of matching of protection means groups including engine revolution regulators, control systems of electric power plant and automatic voltage regulators; test reports on systems for immunity to short circuit	AG	•		•	
.22	Diagrams of electric connections and power supply of the dynamic positioning system equipment (with indication of cable types and places of installation of all system elements)	A		•	•	

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