GUIDELINES
ON TECHNICAL SUPERVISION
OF SHIPS UNDER CONSTRUCTION

ND No. 2-030101-042-E

St. Petersburg
GUIDELINES ON TECHNICAL SUPERVISION OF SHIPS UNDER CONSTRUCTION

The present version of the Guidelines on Technical Supervision of Ships under Construction of Russian Maritime Register of Shipping (RS, the Register) has been approved in accordance with the established approval procedure and comes into force on 1 July 2024.

The present version is based on the version dated 1 January 2024 and Rule Change Notice No. 24-80499 taking into account the amendments and additions developed immediately before publication (refer to the Revision History).
## GUIDELINES ON TECHNICAL SUPERVISION OF SHIPS UNDER CONSTRUCTION

### REVISION HISTORY

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Remarks</th>
</tr>
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<tbody>
<tr>
<td>Section 2, Table 2.5.1, item 2.2, column &quot;Reference&quot;</td>
<td>As was</td>
<td>As is</td>
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<tr>
<td></td>
<td>Section 6, IACS Rec. No. 47, 2.1.15, Part XIV of the Rules</td>
<td>Section 6, IACS Rec. No. 47, 2.1.14, Part XIV of the Rules</td>
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<tr>
<td>Section 2, Chapter 2.7</td>
<td>Form’s number has been updated (322-01 replaced by 221-01)</td>
<td>Form’s number has been updated (322-02 replaced by 221-02)</td>
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<tr>
<td>Section 2, Chapter 2.12 and Annex 3</td>
<td>Form’s number has been updated (322-08 replaced by 221-08)</td>
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<td>Section 11, Appendix 3, Formula 3.2-2</td>
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<td></td>
<td>$Q_{tc} = G_c \times C_r (t_{ic} - t_{fc})/3600Z$ (3.2-2)</td>
<td>$Q_{tc} = G_c \times C_r (t_{ic} - t_{fc})/3600Z$ (3.2-2)</td>
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<td></td>
<td>(for refrigerated kinds of cargo)</td>
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<td>where $G_c =$ capacity of the refrigerated space for a particular cargo for the reefer transport ship or daily delivery of produce into the refrigerated space for the catching and processing fishing ships, kg; $i_{ic}$ and $t_{ic} =$ enthalpy, in kJ/kg, and temperature, in °C, of the cargo (product) incoming into the refrigerated space respectively;</td>
<td>where $G_c =$ capacity of the refrigerated space for a particular cargo for the reefer transport ship or daily delivery of produce into the refrigerated space for the catching and processing fishing ships, kg; $i_{ic}$ and $t_{ic} =$ enthalpy, in kJ/kg, and temperature, in °C, of the cargo (product) incoming into the refrigerated space respectively; $i_f$ and $t_f =$ enthalpy, in kJ/kg, and temperature, in °C, respectively, at the end of the thermal treatment process, i.e. enthalpy of cargo (product) at specified storage temperature and the specified storage temperature; $C_r =$ specific heat of cargo (product), in kJ/kg°C; $Z =$ for the reefer transport ships, the design cargo refrigeration time, in h. For the catching and processing fishing ships, $Z = 24$ h.</td>
</tr>
</tbody>
</table>

1 With the exception of amendments and additions introduced by Rule Change Notices (RCN), as well as of misprints and omissions.
1 GENERAL

1.1 SCOPE OF APPLICATION

1.1.1 Guidelines on Technical Supervision of Ships under Construction\(^1\) are applied in technical supervision during construction of ships subject to technical supervision of Russian Maritime Register of Shipping\(^2\) and have been developed in elaboration of Section 13, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision during Construction of Ships and Manufacture of Materials and Products for Ships\(^3\).

1.1.2 The provisions of the Guidelines may apply with due regard to the details and differences in the processes of ship's construction inherent in the country of the Register technical supervision, and/or specific shipyard.

1.1.3 The Guidelines are intended for the RS experts and surveyors, designers and shipbuilders.

1.1.4 Provisions related to surveys and testing associated with technical supervision of the materials and products applied during construction, as well as to the welders' certification and welding procedure approval are given in Part III "Technical Supervision during Manufacture of Materials" and Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

1.1.5 The requirements of the Guidelines apply in full to the Russian Navy auxiliary vessels with regard to specific requirements given in Section 4 of the Guidelines on Technical Supervision during Design and Construction of Auxiliary Vessels of the Russian Navy.

1.1.6 Requirements for technical supervision during construction of nuclear ships and floating facilities, and nuclear support vessels are given in the Guidelines on Technical Supervision during Construction of Nuclear Ships and Floating Facilities, Nuclear Support Vessels, Manufacture of Materials and Products.

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\(^1\) Hereinafter referred to as "the Guidelines".

\(^2\) Hereinafter referred to as "the Register, RS".

\(^3\) Hereinafter referred to as "the Rules for Technical Supervision".
1.2 TERMS AND DEFINITIONS

1.2.1 Terms, definitions and abbreviations related to the general terminology applied in the Register normative documents are given in Section 1, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision. Specific terms and definitions are given the relevant sections of the Guidelines.

1.2.2 For the purposes of the Guidelines, the ship also means the mobile offshore drilling unit (MODU), floating offshore oil-and-gas product unit (FPU), floating crane, floating dock and other floating facilities, wig craft, fixed offshore platform (FOP).
1.3 REQUIREMENTS TO MEASURING EQUIPMENT

1.3.1 Measuring equipment (including instruments and gauges), the readings of which the RS surveyor relies on to make decisions affecting surveys, measurements and tests to determine the ship compliance with the applicable requirements of the RS rules, international conventions and national requirements, shall be individually identified and verified/calibrated to the recognized national or international standards, instructions.

1.3.2 The RS surveyor may accept simple measuring means (e.g. rulers, measuring tapes, weld gauges, micrometers) without individual identification or confirmation of verification/calibration, provided they are of standard commercial design, properly maintained and periodically compared with other similar equipment or test pieces.

1.3.3 The RS surveyor may accept measuring equipment fitted on board a ship and used in survey of the ship's equipment and machinery (e.g. pressure, temperature or rpm gauges and meters) based either on documents, confirming verification/calibration or comparison of readings with other similar equipment.

1.3.4 The RS surveyor shall satisfy himself that other equipment (e.g. tensile test machines and ultrasonic thickness measurement equipment) is verified/calibrated to the recognized national or international standard, manufacturer's instructions or MA requirements.
1.4 REGISTER TECHNICAL SUPERVISION

1.4.1 Technical supervision during construction of the ship hull, installation and testing of machinery, equipment, arrangements and outfit is performed by the RS surveyor.

1.4.2 Technical supervision is performed by supervision of items of technical supervision according to the List of Items of Technical Supervision¹ (refer to 13.2 and 13.3, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision), patrol (refer to 13.4, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision) and review of technical documentation taking into account the provisions of the relevant sections of the Guidelines.

¹ Hereinafter referred to as "the List".
1.5 VERIFICATION OF TECHNICAL DOCUMENTATION

1.5.1 Prior to the survey beginning, technical documentation related to an item of technical supervision shall be submitted to the RS surveyor, including the following:

.1 a set of the RS-approved technical documentation for ship under construction, including approved by/agreed with RS amendments and/or additions;

.2 shipyard’s standards agreed with RS according to 2.18, Part I “General Regulations for Technical Supervision” of the Rules for Technical Supervision and the relevant sections of the Guidelines;

.3 type production processes (or general technical requirements) related to installation of systems, arrangements, equipment and outfit;

.4 specifications, methods, detailed design documentation and other normative documents containing the data to verify the compliance with the Register requirements and related to production processes or scope and procedures of the Register technical supervision.
2 HULL

2.1 GENERAL

2.1.1 This Section regulates the procedure, mode and scope of technical supervision to fit the most widespread type production processes adopted in ship's construction with use of sectional, blocked methods or the combinations thereof when the hull is constructed at the building berth with pyramidal, island or block-building technologies.

If other building methods are used or new process is implemented which are omitted in the Section, the relevant requirements shall be developed by the RS Branch Office carrying out technical supervision of the ship\(^1\) with due regard to particular conditions of production and the specific character of an item.

2.1.2 If the items of technical supervision are fully or partially manufactured in cooperation and supplied to the shipbuilding yard as hull products, these latter are covered by the appropriate chapters of the Section with due regard to Section 2, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

2.1.3 The scope of the Section requirements includes the following RS surveyor main activities:

1. examination of the parts of the ship covered by RS rules and by applicable statutory regulations for hull construction, to obtain appropriate evidence that they have been built in compliance with the specified rules and regulations, taking account of the relevant RS-approved drawings;

2. appraisal of the manufacturing, construction, control and qualification procedures, including welding consumables, welding procedures, welded connections and assemblies, with indication of the relevant approval tests;

3. witnessing inspections and tests as required in the RS rules used for ship construction, including materials, welding and assembling, specifying the items to be examined and/or tested and how (e.g. by hydrostatic, hose or leak testing, non-destructive examination (testing), verification of geometry) and by whom.

2.1.4 Technical supervision during manufacture of materials and equipment used for ship construction at the firm (manufacturer) is not included in these requirements.

2.1.5 Details of requirements for hull and machinery steel forgings and castings and for normal and higher strength hull structural steel are given in 3.2, 3.7 and 3.8, Part XIII "Materials" of the Rules for the Classification and Construction of Sea-Going Ships\(^2\). Acceptance of these items is verified through the survey process carried out at the firm (manufacturer) and the issuing of the appropriate certificates in compliance with 2.4, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision.

2.1.6 Additional requirements for oil tankers and bulk carriers subject to regulation II-1/3-10 of the International Convention for the Safety of Life at Sea, 1974 (SOLAS-74), as amended, contracted for construction on or after 1 July 2016 are given in 2.11.

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\(^1\) Hereinafter referred to as "the RS Branch Office".

\(^2\) Hereinafter referred to as "the Rules for the Classification and Construction".
2.2 DEFINITIONS

2.2.1 The hull structure is defined as follows:
.1 hull envelope including all internal and external structures;
.2 superstructures, deckhouses and casings;
.3 welded foundations, e.g. main engine seatings;
.4 hatch coamings, bulwarks;
.5 all penetrations fitted and welded into bulkheads, decks and shell;
.6 the fittings of all connections to decks, bulkheads and shell, such as air pipes and ship side valves — all items covered by the International Convention on Load Lines, 1966 (LL-66), as amended;
.7 welded attachments to shell, decks and primary members, e.g. crane pedestals, bitts and bollards, but only as regards their interaction on the hull structure.

2.2.2 Reference to documents also includes electronic transmission or storage.

2.2.3 Definition of survey methods which the RS surveyor is directly involved in: patrol, review, witness.

2.2.3.1 Patrol is the act of checking on an independent and unscheduled basis that the applicable processes, activities and associated documentation of the shipbuilding functions identified in Table 2.5.1 conform to the RS and statutory requirements.

2.2.3.2 Review is the act of examining documents in order to determine traceability, identification and to confirm that processes continue to conform to the RS and statutory requirements.

2.2.3.3 Witness is the attendance at scheduled inspections in accordance with the agreed inspection and test plan or equivalent to the extent necessary to check compliance with the survey requirements.

2.2.4 Part is a product manufactured from the material of one brand without assembly.

2.2.5 Unit is a technologically complete section of the hull structure consisting of several parts.

2.2.6 Section is technologically complete, separately manufactured hull section consisting of several units and parts.

2.2.7 (Section) block is a part of the ship’s hull cut off, in major cases, by the planes parallel to the midship section and sometimes by the decks, and formed by sections, units and parts.

2.2.8 Critical structural areas (critical areas) are locations which have been identified from calculations to require monitoring or from the service history of similar or sister ships to be sensitive to cracking, waviness, buckling or corrosion, which may impair the structural integrity of the ship.

2.2.9 Welding procedure specification (WPS) is a document compiled by the manufacturer of welded structures and containing all the necessary information on welding of a particular joint, including specifications for materials, welding method, edge preparation data and all process parameters.

2.2.10 Building berth, for the purpose of the Section, is any building berth place where the ship's hull is constructed.

2.2.11 Shipyard is a shipbuilding utility or group of shops constructing ships and manufacturing hull structures.

2.2.12 Laying-down of a ship is installation at the building berth of a base section or block (island) in section or block (island) construction respectively, or such a stage of construction at which the mass of the hull part assembled comprises at least 501 or 1 % of the design mass of all hull materials, whichever is less.

2.2.13 Launching is a launch from a building berth under the hull mass, floating in a building or flooding dock, a mechanized launch including the ship's transfer onto the water using cargo-handling means, etc.
2.3 APPLICATION

2.3.1 The Section requirements cover in full the hull survey of all new construction of steel ships intended for classification and for international voyages except for:
   .1 those defined in regulation 1/3 of SOLAS-74 (i.e. ships of war and troopships; cargo ships of less than 500 gross tonnage; ships not propelled by mechanical means; wooden ships of primitive build; pleasure yachts not engaged in trade, and fishing vessels);
   .2 high speed craft as defined in 1.3.1, Chapter 1 of the International Code of Safety for High-Speed Craft, 2000 (2000 HSC Code);
   .3 mobile offshore drilling units (MODU) as defined in 1.2.1, Chapter 1 of the Code for the Construction and Equipment of Mobile Offshore Drilling Units, 2009 (2009 MODU Code).

2.3.2 These requirements cover all statutory items relevant to the hull structure and coating, i.e. Load Line and SOLAS-74 Safety Construction.

2.3.3 These requirements do not cover the manufacture of equipment, fittings and appendages regardless whether they are made inside or outside of the shipyard, examples being as follows:
   .1 hatch covers;
   .2 doors and ramps integral with the shell and bulkheads;
   .3 rudders and rudder stock;
   .4 all forgings and castings integral to the hull.

   Evidence of acceptance of these items shall be provided by the RS certificates and accompanying documentation from the firm (manufacturer) and verified at the shipyard.

2.3.4 These requirements apply to the installation into the ship, welding and testing of the following:
   .1 items listed in 2.3.3;
   .2 equipment forming part of the watertight and weathertight integrity of the ship.

2.3.5 These requirements apply to the hull structures and coating constructed at any of the following:
   .1 shipyard facilities;
   .2 sub-contractors at the shipyard facilities;
   .3 sub-contractors at their own facilities or at other remote locations.

2.3.6 Provisions of this Section may apply to the hulls of the ships and floating facilities specified in 2.3.1.1 – 2.3.1.3, as well as to the ships with aluminum alloy hulls, as far as it is practicable and in cases when it is regulated by other Register normative documents.

2.3.7 Steel ship- and pontoon-shaped FPU are covered by the general requirements of this Section. Steel semi-submersible, self-elevating, gravity (including reinforced concrete and steel concrete), tension leg and moored FPU are covered by the requirements of 2.14 "Survey of MODU and FOP Hulls".
2.4 QUALIFICATION AND ACTIVITY MONITORING OF RS PERSONNEL

2.4.1 The RS surveyor shall confirm through patrol, review and witness as defined in 2.3.1.1 – 2.3.1.3 that the ships are built using the RS-approved plans in accordance with the relevant RS and statutory requirements. The RS surveyor shall be qualified to be able to carry out the tasks and procedures shall be in place to ensure that his/her activities are monitored. Details are specified in Instruction for Activity Monitoring of RS Surveyors and RHO Experts and Procedure for Training and Qualification Maintenance of RS Engineering-Technical Personnel.
2.5 SURVEY OF THE HULL STRUCTURE

2.5.1 Table 2.5.1 provides a list of surveyable items for the hull structure and coating covered by the requirements of the Section, including:

.1 description of the shipbuilding functions;
.2 RS and statutory survey requirements;
.3 survey method required for classification;
.4 relevant RS and statutory requirement references;
.5 documentation to be available for the RS surveyor during construction;
.5.1 the shipyard shall provide the surveyors access to documentation required by classification, this includes documentation retained by the shipyard or other third parties;
.5.2 the list of documents approved or reviewed by RS for the specific new construction are as follows:
  plans and supporting documents;
  examination and testing plans;
  NDT plans;
  welding consumable details;
  welding procedure specifications;
  welding plan or details;
  welders’ qualification records;
  NDT operator’s qualification records;
.6 documents to be inserted into the Ship Construction File (SCF) (refer to 2.10);
.7 a list of specific activities which are relevant to the shipbuilding functions. This list is not exhaustive and may be modified to reflect the construction facilities or specific ship type.

2.5.2 Evidence is also to be made available, as required, by the shipyard, to the RS surveyor whilst the construction process proceeds to prove that the material and equipment supplied to the ship has been built or manufactured under survey relevant to the RS and statutory requirements.

2.5.3 Additional comments and explanations related to surveys of the items of technical supervision listed in Table 2.5.1 are given in 2.12.
### Hull Survey Requirements

<table>
<thead>
<tr>
<th>No.</th>
<th>Item</th>
<th>Shipbuilding function</th>
<th>Survey Requirements for Classification</th>
<th>Survey Method required for Classification</th>
<th>Reference*</th>
<th>Statutory requirements and relevant reference</th>
<th>Documentation available to RS surveyor during construction</th>
<th>Documentation for ship construction file</th>
<th>Specific activities</th>
<th>RS proposals for the project</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Welding:</td>
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<tr>
<td>1.1</td>
<td>welding consumables</td>
<td>classification approved separately at the manufacturer, (i.e. RS tested and approved at the firm (manufacturer))</td>
<td>review approval status and patrol, verify storage, handling and treatment in accordance with the firm (manufacturer’s) requirements</td>
<td>IACS URW 17, Section 4.1, IACS Rec. No. 47, Section 4, Part XIV of the Rules**</td>
<td>consumable specification, and approval status, copies of Certificate of Approval for Welding Consumables (COOM), delivery notes, certificates for ancillary materials, packing for materials. Handling and delivery records of welding consumables.</td>
<td>not required</td>
<td>identify consumables against approved list.</td>
<td></td>
<td></td>
<td>e.g. kept dry, covered, where applicable heated. Perform drying of electrodes and welding fluxes according to the manufacturer's specification. Results for control of materials’ handling, treatment and use shall be recorded in accordance with the shipyard's established order.</td>
</tr>
<tr>
<td>1.2</td>
<td>welders' qualification</td>
<td>qualified welders welding of hull structures shall be carried out by the qualified welders certified with the Welder Approval Test Certificate (СДС)</td>
<td>review of welder certification and patrol</td>
<td>Section 3.1, IACS Rec. No. 47, Section 5, Part XIV of the Rules, Section 4, Part III of the Rules for Technical Supervision***</td>
<td>shipyard’s records with individual’s identification</td>
<td>not required</td>
<td>verify welder qualification standard, (availability of СДС, validity terms, welder approval range as per welding positions, welders’ identification)</td>
<td></td>
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<tr>
<td>1.3</td>
<td>welding — mechanical properties (welding procedures)</td>
<td>all weld joint configurations, positions and materials to be covered by weld procedures (ТТІТС), approved by RS or by another IACS member</td>
<td>documentation review and patrol</td>
<td>IACS UR W28, Section 3.2, IACS Rec. No. 47.</td>
<td>approved Table of the ship’s hull welding, approved hull structural drawings, Welding</td>
<td>not required</td>
<td>verify that WPS are available at relevant workstations</td>
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</tbody>
</table>

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<table>
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<tr>
<td>13a</td>
<td>welding equipment</td>
<td>correctly calibrated and maintained</td>
<td>patrol and review</td>
<td>plans, schedules of machinery and equipment maintenance and calibration, records</td>
<td>not required</td>
<td>verify in cooperation with the committed personnel of the shipyard condition of welding equipment and machinery</td>
<td>verify competence of the personnel performing calibration</td>
<td>verify calibration carried out in accordance with the firm</td>
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<td></td>
<td>RS witnesses all new weld procedure qualification tests carried out in the shipyard</td>
<td>witness Rules for Technical Supervision</td>
<td>Procedure Approval Test Certificate (COTTCC), welding procedure specifications (WPS)</td>
<td>not required</td>
<td>review of technical documentation on manufacture of hull structures aimed at identification of welding procedure and their correlation with the approved CTC and COTTCC at the shipyard</td>
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<tr>
<td>1.3b</td>
<td>welding environment</td>
<td>satisfactory environment</td>
<td>patrol</td>
<td>Section 2, IACS Rec. No. 47. Chapter 2.1, Part XIV of the Rules</td>
<td>operational instructions on performing welding works</td>
<td>not required</td>
<td>verify welding areas clean, dry, well lit</td>
<td>2. verify relevant measures taken for any pre or post heat treatment, drying of surfaces prior to welding</td>
<td>3. verify welding consumables used and fluxes are protected against adverse environmental conditions and adequately prepared prior to use</td>
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<tr>
<td>1.3c</td>
<td>welding supervision</td>
<td>sufficient number of skilled personnel available at the shipyard, trained and certified by the competent body to carry out welded joint inspection and their quality assessment</td>
<td>review and patrol</td>
<td>IACS UR W33, Section 2.3, 3.3, IACS Rec. No. 47, Section 3, Part XIV of the Rules</td>
<td>verify supervision is effective (patrols of weld procedures and weld joint testing efficiency by the shipbuilder)</td>
<td>verify that NDT is carried out in accordance with recommendations</td>
<td></td>
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<tr>
<td>1.4</td>
<td>welding — surface discontinuities</td>
<td>substantially free from significant indications, satisfactory profile and size</td>
<td>visual examination, surface detection techniques, review of documents and patrol of operator</td>
<td>IACS UR W33, IACS Rec. No. 47, Part XIV of the Rules</td>
<td>shipbuilder’s and agreed standards containing criteria for weld joint quality assessment: , and Rules, as applicable, welding and NDT plans.</td>
<td>not required</td>
<td>Identify workstations where NDT is carried out, e.g. panel line butt welds, castings into hull structure</td>
<td>verify that NDT is carried out in accordance with recommendations</td>
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<tr>
<td>1.5</td>
<td>welding — embedded discontinuities</td>
<td>NDT is to be carried out by qualified operators capable of ensuring that welds are substantially free from significant indications</td>
<td>radiography and ultrasonic testing, review of documents and patrol of operator, examination of films</td>
<td>IACS UR W33, IACS Rec. No. 47, Chapters 3.2 and 3.3, Part XIV of the Rules</td>
<td>NDT reports, operator qualifications</td>
<td>not required</td>
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<td>2</td>
<td>Steel preparation and fit up:</td>
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<td></td>
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<tr>
<td>2.1</td>
<td>surface preparation, marking and cutting</td>
<td>traceability and acceptability of material, check of steel plates &amp; profiles, materials type, scantling identification, testing marks</td>
<td>patrol</td>
<td>Sections 4, 5, IACS Rec. No. 47</td>
<td>material certificates, shipbuilder's marking/cutting production documents at the workstage – documents retained at the facility</td>
<td>not required</td>
<td>verify stockyard storage satisfactory</td>
<td>verify material traceability, e.g. stamping identification against material certification, archiving of records</td>
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<th>Specific activities</th>
<th>RS proposals for the project</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.2</td>
<td>straightening</td>
<td>approval of straightening methods/procedures against deformation</td>
<td>patrol and review</td>
<td>Section 6, IACS Rec. No. 47; 2.1.15, Part XIV of the Rules</td>
<td>shipbuilder’s standards agreed with RS, procedures/technological processes approved by/agreed with RS</td>
<td>not required</td>
<td>verify that straightening processes are approved for the grade and type of steel, e.g. tmcp, z plate applied during construction</td>
<td>verify that plates and sections are within approved tolerances</td>
<td></td>
</tr>
<tr>
<td>2.3</td>
<td>forming</td>
<td>maintain material properties acceptance of forming method against improper deformations</td>
<td>patrol</td>
<td>IACS Rec. No. 47</td>
<td>RS agreed shipbuilder’s procedure for hot forming</td>
<td>not required</td>
<td>verify that temperature control is exercised by the</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Guidelines on Technical Supervision of Ships under Construction (Section 2)

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<thead>
<tr>
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<tbody>
<tr>
<td>2.4</td>
<td>conformity with alignment/fit up/gap criteria</td>
<td>verify mutual positioning and edge preparation of details to be connected for compliance with the agreed standards, СПС and approved drawings</td>
<td>patrol</td>
<td>Sections 7, 8, 8, IACS Rec. No. 47, 2.2.1, Part XIV of the Rules. The shipbuilder's standards agreed with RS</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>operator during hot forming</td>
<td>verify that suitable methods of temperature control are available when forming special steels and materials</td>
</tr>
</tbody>
</table>

2.4 conformity with alignment/fit up/gap criteria

verify mutual positioning and edge preparation of details to be connected for compliance with the agreed standards, СПС and approved drawings

patrol

Sections 7, 8, 8, IACS Rec. No. 47, 2.2.1, Part XIV of the Rules. The shipbuilder's standards agreed with RS

shipbuilder's standards agreed with RS, СПС, approved drawings, Table of welding

not required

verify the processes to ensure satisfactory fit up and alignment at all workstations

verify that edge preparations are reinstated where lost during fitting operations

verify remedial procedures are in place to compensate for wide gaps and alignment deviations

| 2.5 | conformity for critical areas, when defined, with alignment/fit up or weld configuration | verify mutual positioning and edge preparation of details to be connected for compliance with the agreed standards, СПС and approved drawings | witness and review | Sections 7, 8, 8, IACS Rec. No. 47, 2.2.1, Part XIV of the Rules. The shipbuilder's standards agreed with RS. Special instructions in | | | | | verify that the information relevant to the latest approved drawings is available at the workstations (yard facilities) | verify the processes to ensure satisfactory |
## Guidelines on Technical Supervision of Ships under Construction (Section 2)

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<td></td>
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<td></td>
<td>the approved drawings</td>
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<td></td>
<td>fit up and alignment at all workstations (yard facilities)</td>
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<td></td>
<td>verify that edge preparations are reinstated where lost during fitting operations</td>
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<td></td>
<td></td>
<td>verify remedial procedures are in place to compensate for wide gaps and alignment deviations</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Steelwork process, e.g. sub assembly, block, grand and mega block assembly, preerection and erection, closing plates</td>
<td>compliance with approved drawings, visual examination of welding and material, check alignment and deformations</td>
<td>patrol of the steel-work process and witness of the completed item</td>
<td>Sections 6, 7, 8, IACS Rec. No. 47, Parts II, XIV of the Rules</td>
<td>1.1.6, Part II of the Rules</td>
<td>approved plans, shipbuilders inspection records, Shipbuilders and recognized standards and Rules as applicable, construction plan (steelwork subdivision)</td>
<td></td>
<td></td>
<td>verify that the information relevant to the latest versions of approved drawings are available at the workstations (yard facilities), working drawings comply with the latest version of approved drawings</td>
<td>verify that correct weld sizes have been adopted</td>
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<td></td>
<td>verify operation of the welding processes at different work stages is satisfactory</td>
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<td>verify that piece parts are identifiable</td>
<td></td>
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</table>
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</thead>
<tbody>
<tr>
<td>4</td>
<td>Remedial work and alteration</td>
<td>welding, check against deformation, alignment</td>
<td>review shipbuilder’s records and witness</td>
<td>Section 9, IACS Rec. No. 47</td>
<td>permanent record of shipyard surveyable items (notices, flowchart of deviations, bearer’s notices, etc. on effects elimination and hanges to ship configuration)</td>
<td>verify that records have been maintained on recording of significant deviations from the approved documentation (miscut openings/trimming of framing members for pipe tunnels/ cable runs, equipment installation, etc.)</td>
<td>verify that all deviations brought to the attention of the RS by the shipbuilder and pertaining to the classification are approved by RS</td>
<td>confirm that steelwork is in accordance with the approved plan</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Tightness testing, including</td>
<td>absence of leaks</td>
<td>review and witness of the test</td>
<td>UR IACS S14, Appendix 1 to Regulation III-1/11 of</td>
<td>approved plan of testing the hull for</td>
<td></td>
<td></td>
<td>confirm that tank testing is carried</td>
<td></td>
</tr>
</tbody>
</table>
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<tr>
<td>6</td>
<td>Structural testing</td>
<td>structural adequacy of the compartments and tanks design</td>
<td>review and witness of the test</td>
<td>UR IACS S14, Appendix 1 to Part II of the Rules</td>
<td>Regulation II-1/11 of SOLAS, as amended</td>
<td>approved plan of testing the hull for watertightness, shipbuilder’s inspection records on testing performed</td>
<td>approved plan of testing the hull for watertightness</td>
<td>confirm the tank testing is carried out in accordance with the approved plan</td>
<td>confirm that correct test pressures maintained for testing are satisfactory (with the approved plan testing the hull for watertightness)</td>
<td>verify that adequate records of the tank testing results have been maintained</td>
</tr>
</tbody>
</table>

*Reference: SOLAS, as amended*
<table>
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<tr>
<td>7</td>
<td>Corrosion protection system (coatings, cathodic protection, cathodic protection systems with impressed current except for coating system subject to PSPC)</td>
<td>salt water ballast tanks with boundaries formed by the hull envelope, and also bulk carrier hold internal surfaces, coamings and hatch covers shall have an efficient protective coating. Safety aspects of cathodic protection systems to be dealt with separately</td>
<td>review and report on builder’s &amp; manufacturer’s documentation</td>
<td>UR IACS Z8, UR IACS Z9, UI IACS SC122, UR IACS F1. 1.2.5.1 and 3.3.5.1, Part II, 2.4.15, Part VI of the Rules</td>
<td>Regulation II-1/3-2 of SOLAS, as amended</td>
<td>the firm (manufacturer’s) and builder’s specification</td>
<td>corrosion protection specifications</td>
<td>verify that applied coatings are approved and review records of application</td>
<td>verify that adequate records have been maintained and copied to the ship construction file</td>
<td></td>
</tr>
<tr>
<td>7.1</td>
<td>application of protective coatings for dedicated seawater ballast tanks in all types of ships and double-side skin spaces of bulk carriers subject to PSPC</td>
<td>monitor implementation of the coating inspection requirements</td>
<td>documentation review and patrolling</td>
<td>UI IACS SC223, 3.2, Part III of the Rules for Technical Supervision, 2.12.7 of the Guidelines on Technical Supervision of Ships under Construction</td>
<td>Regulation II-1/3-2 of the International Convention SOLAS-74, as amended</td>
<td>surface preparation and coating processes agreement signed by the shipyard, shipowner and coating manufacturer (the Tripartite Agreement)</td>
<td>Coating Technical File (CTF)</td>
<td>verify that applied coatings are approved and review records of application in accordance with Chapter 7 of Annex to IMO MSC.215(82), as amended</td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>Installations, welding and testing of the following:</td>
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</tr>
<tr>
<td>8.1</td>
<td>hatch covers</td>
<td>tightness and securing</td>
<td>witness</td>
<td>IACS Rec. 14, UR IACS S14, Appendix 1 to Part II, including 7.10, Part III of the Rules</td>
<td>Reg. 13, 14, 15 and 16 of the International Convention on Load Lines 1966</td>
<td>approved drawing with proper information on covers</td>
<td>approved plan of testing the hull for watertightness</td>
<td>details of equipment forming part of the watertight and watertight integrity of the ship, structural drawings</td>
<td>confirm leak test of hatch covers</td>
<td>confirm feasible cover operation</td>
</tr>
</tbody>
</table>
### Guidelines on Technical Supervision of Ships under Construction (Section 2)

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<tr>
<td>8.2</td>
<td>doors and ramps integral with the shell and bulkheads</td>
<td>tightness and securing</td>
<td>witness</td>
<td>UR IACS S14. Appendix 1 to Part II of the Rules</td>
<td>Regulation II-1/18 International Convention SOLAS-74, as amended. Regulations 12 and 21 of the International Convention on Load Lines, 1966</td>
<td>approved plan of testing the hull for watertightness, shipbuilder’s inspection records on testing performed</td>
<td>details of equipment forming part of the watertight and watertight integrity of the ship, structural drawings</td>
<td>and proper securing test</td>
<td>confirm leak tests</td>
</tr>
<tr>
<td>8.3</td>
<td>rudders</td>
<td>fitting</td>
<td>witness</td>
<td>UR IACS S14. Appendix 1 to Part II of the Rules</td>
<td>approved drawings, shipbuilder’s inspection records</td>
<td>details required, structural drawings</td>
<td>confirm alignment and mounting and fitting up to the connection to the tiller</td>
<td>confirm function tests</td>
<td>verify fitting of pintles and all securing bolts</td>
</tr>
<tr>
<td>8.4</td>
<td>forgings and castings</td>
<td>compliance with approved drawings, visual examination of welding and material, check alignment and deformations</td>
<td>patrol of the process and witness of the completed item</td>
<td>IACS UR No. W7, W8, 3.7 and 3.8, Part XIII of the Rules</td>
<td>approved plans, shipbuilder’s inspection records, shipbuilder’s and recognised standards, and Rules as applicable, construction plan</td>
<td>copies of certificates of forgings and castings</td>
<td>verify casting and forgings against material certificate</td>
<td>verify that correct welding and fit up requirements specified in reference 1, 2.4 and 2.6 of this</td>
<td>confirm feasible cover operation and proper securing test</td>
</tr>
</tbody>
</table>

*UR = Unified Requirements
<table>
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<tbody>
<tr>
<td>26</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>(steelwork subdivision)</td>
<td>Table have been adopted</td>
<td></td>
<td>verify that material certificates are included in the ship construction file</td>
<td></td>
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<tr>
<td></td>
<td>appendages</td>
<td></td>
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<td></td>
<td></td>
<td></td>
<td></td>
<td>verify that correct welding and fit up requirements specified in reference 1, 2.4 and 2.5 of this Table have been adopted</td>
<td></td>
</tr>
<tr>
<td>8.5</td>
<td>equipment forming the watertight and weathertight integrity of the ship, (overboard discharges, air pipes, ventilators, etc.)</td>
<td>tightness and securing</td>
<td>witness</td>
<td>4.4 and 21.4, Part VIII of the Rules</td>
<td>Regulation II-1/16 and II-1/16-1 of the International Convention SOLAS-74, as amended; Regulations 17, 18, 19, 20, 22, 23 of the International Convention on Load Lines, 1966</td>
<td>approved plan of testing the hull for watertightness, shipbuilder’s inspection records</td>
<td>details required</td>
<td>verify that correct welding and fit up requirements specified in reference 1, 2.4 and 2.5 of this Table have been adopted</td>
<td>verify compliance with Convention on Load Lines 1966 as amended — i.e. all fittings in accordance with the record of freeboard assignment</td>
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<td></td>
<td>verify air pipes, vents etc closing device are approved type</td>
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<td></td>
<td>verify material certificates for overboard discharges where applicable</td>
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<tr>
<td>No.</td>
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</tr>
<tr>
<td></td>
<td>freeboard marks and draft marks</td>
<td>within allowable tolerances and in accordance with the freeboard assignment</td>
<td>witness</td>
<td>UI IACS LL4 2.3.3 Rules on Load Lines for the Sea-Going Ships, Regulations 4, 5, 6, 7 and 8 of International Convention on Load Lines 1966</td>
<td>approved load line drawings, shipbuilder's records</td>
<td>details required</td>
<td>Verify freeboard marks in accordance with load line assignment</td>
<td>Verify draft marks in accordance with the agreed tolerances specified by the builder unless more onerous flag state requirements</td>
<td></td>
</tr>
<tr>
<td></td>
<td>principal dimensions</td>
<td>within allowable tolerances and in accordance with the freeboard assignment</td>
<td>review and witness</td>
<td>IACS Rec. No. 47</td>
<td>shipbuilder's records</td>
<td>details required</td>
<td>Verify principal dimensions in accordance with recognised standard</td>
<td>verify dimensions included in ship construction file</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Safety Construction certification</td>
<td>no outstanding imperfections or defects</td>
<td>witness</td>
<td>Regulation I/7 or I/10 of the International Convention SOLAS-74, as amended, as appropriate</td>
<td></td>
<td></td>
<td>verify that Administration requirements have been incorporated into the hull structure</td>
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</table>
### Guidelines on Technical Supervision of Ships under Construction (Section 2)

#### 8.6 Watertight Cable Transit Seal Systems

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<tbody>
<tr>
<td>Watertight cable transit seal systems compliance with approved drawings, visual examination of fitting, check alignment and securing</td>
<td>patrol of the process and witness of the completed item</td>
<td>verify that correct welding and fit up requirements, including as specified in reference 1, 2.4 and 2.5 of the Table have been adopted</td>
<td>verify watertight cable transit seal systems are type approved</td>
<td>verify the format and content of the Register</td>
</tr>
</tbody>
</table>

* IACS recommendations are not mandatory requirements.
** Rules for the Classification and Construction of Sea-Going Ships.
*** Rules for Technical Supervision during Construction of Ships and Manufacture of Materials and Products for Ships.

<table>
<thead>
<tr>
<th>Shipbuilder's name</th>
<th></th>
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</thead>
<tbody>
<tr>
<td>Project</td>
<td></td>
</tr>
<tr>
<td>Project duration</td>
<td></td>
</tr>
<tr>
<td>Kick off meeting date</td>
<td></td>
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<tr>
<td>Representing builder</td>
<td></td>
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<tr>
<td>Representing RS</td>
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</tr>
</tbody>
</table>

Additional explanations to items of Table 2.5.1 — refer to 2.12.
2.6 REVIEW OF SHIPYARD CONSTRUCTION FACILITIES

2.6.1 The RS surveyor shall familiarize with the shipyard construction facilities, management processes and safety for review in compliance with the requirements for survey given in Table 2.5.1 prior to any steelwork or construction:

.1 where RS has none or no recent experience of technical supervision during construction of facilities (typically after a one year lapse) or when significant new infrastructure has been added;

.2 where there has been a significant management or personnel re-structuring having an impact on the ship construction process; or

.3 where the shipyard contract has been signed to construct a ship of a different type or substantially different in design.

2.6.2 Based on review results of construction facilities of the shipyard and its sub-contractors using their own construction facilities, the RS surveyor issues the Shipyard Construction Facilities Review Record (form 6.3.19 Z23).
2.7 SURVEY PLANNING

2.7.1 Prior to commencement of surveys for any newbuilding project, the RS Branch Office shall discuss with the shipyard at a kick-off meeting the items listed in Table 2.5.1. The purpose of the meeting is to review and agree how the list of specific RS surveyors' activities relating to the ship construction process and shown in Table 2.5.1 shall be addressed. The meeting shall take into account the shipyard construction facilities and ship type, including the list of proposed subcontractors. A Record (Minutes) of the meeting (form 221-01) shall be made, based upon the contents of Table 2.5.1. (Table 2.5.1 may be used as the record (form 221-02) with comments made into the appropriate column and attached to the Record). If the RS Branch Office has nominated the RS surveyor for a specific newbuilding project, then the surveyor shall attend the kick-off meeting.

The shipyard shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the shipyard shall agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the shipyard shall be requested to agree to suspend relevant construction activities if warranted by the severity of the problem.

2.7.2 The records shall take note of specific published Administration requirements and interpretations of statutory requirements.

2.7.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick-off meeting and these shall be documented in the survey plan. E.g. if the shipyard chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

2.7.4 Shipbuilding quality standards for the hull structure during new construction shall be reviewed and agreed during the kick-off meeting. Structural fabrication shall be carried out in accordance with IACS Recommendation No. 47 "Shipbuilding and Repair Quality Standard" (refer to Appendix 1 to the Section), or another recognized fabrication standard (RFS) which has been agreed with RS prior to the commencement of fabrication. The work shall be carried out in accordance with the RS rules and under technical supervision of the Register.

The Register may accept a RFS as an alternative to IACS Recommendation No. 47, provided the requirements of 2.7.4.1 or 2.7.4.2 are met, as applicable.

2.7.4.1 Where a RFS is well established and has well documented history (3 or more years prior to the new ship contract) of successful application to similar designs as the new ship and that history is for the same shipyard as the new ship. Then the shipyard shall create a summary document referencing the RFS to be used in construction and highlighting any limitations to usage of the selected RFS. This summary document shall be included with the Record (Minutes) of kick-off meeting (form 221-01) for the ship.

The summary document shall also be included in the Ship Construction File (SCF) (for tankers and bulk carriers subject to SOLAS Chapter II-1 Part A-1 Regulation 3-10 per item 11, Table 2.11.3.1.2, Tier II), as applicable.

2.7.4.2 Where a RFS is new or revised or otherwise not as per 2.7.4.1, the following steps shall be carried out:

.1 the tolerances and fabrications standards of the RFS shall be compared with those of IACS Recommendation No. 47. Any that are less stringent than those of IACS Recommendation No. 47 shall be identified;
2 the tolerances and fabrication standards of the RFS identified in 2.7.4.2.1 shall be assessed to determine the acceptability for use and/or any restrictions for usage for the subject (or proposed) design. Details of how the acceptability for use and/or restrictions shall be recorded; and

3 a summary document including the outcomes of 2.7.4.2.1 and 2.7.4.2.2 shall be compiled. This document shall also include a reference to the RFS, details of the tolerance and fabrication standards not analyzed as part of 2.7.4.2.2 and any limitations to the usage of the RFS.

The summary document shall be included with the Record (Minutes) of the kick-off meeting (form 221-01) of the ship. The summary document shall also be included in the SCF (for tankers and bulk carriers subject to SOLAS Chapter II-1 Part A-1 Regulation 3-10 per item 11, Table 2.11.3.1.2, Tier II) as applicable.

2.7.5 The kick-off meeting may be attended by other parties as defined in the Procedure for Supply of Information to Customers (shipowner, representative of Administration, etc.) subject to agreement by the shipyard.

2.7.6 In the event of series ship production¹, the requirement for a kick-off meeting in 2.7.1 may be waived for the second and subsequent ships provided that no changes to the specific activities agreed in the kick-off meeting for the first ship are introduced. Any changes of decisions taken during the kick-off meeting shall be agreed and documented.

¹ Series ship production means ships in the series subsequent to the first one (prototype), i.e. sister ships built in the same shipyard.
2.8 EXAMINATION AND TEST PLAN FOR NEWBUILDING ACTIVITIES
(List of items of technical supervision)

2.8.1 The shipyard shall provide RS the plans of the items, which are intended to be examined and tested. These plans need not be submitted for approval and examination at the time of the kick-off meeting, however, in any case they shall be submitted to the RS surveyor prior to commencement of the relevant survey.

They shall include:
.
.1 proposals for the examination of completed steelwork — generally referred to as the block and section plan and shall include details of joining sections and blocks together at the pre-erection and erection stages or at other relevant stages;
.2 proposals for fit up examinations where necessary;
.3 proposals for testing of the hull structure (leak and hydrostatic) as well as for all watertight and weathertight closing appliances;
.4 proposals for non-destructive testing;
.5 any other proposals specific to the ship type or to the statutory requirements.

2.8.2 The plans and any modifications to them shall be submitted to the RS surveyor in sufficient time to allow review before the relevant survey activity commences.

2.8.3 Additional requirements for oil tankers and bulk carriers subject to regulation II-1/3-10 of SOLAS-74, as amended, contracted for construction on or after 1 July 2016 are given in 2.11.
2.9 PROOF OF THE CONSISTENCY OF SURVEYS

2.9.1 The RS Branch Office shall be able to provide evidence, e.g. through records, check lists, inspection and test records, etc. that its surveyors have complied with the requirements of the newbuilding survey planning and duly participated in the relevant activities shown in the shipyard examination and test plans (lists).

2.9.2 In addition, the RS surveyor shall maintain records of deficiencies found during the patrolling activities required in Table 2.5.1 and described in 2.2.3.1. Records shall include the date when deficiency was found, description of the deficiency and the date when the deficiency was cleared.

2.9.3 The RS Branch Office shall keep records of the results of surveys performed by means of the Construction module in the "Thesis" System intended for electronic recording of the technical supervision process during construction of ships.

2.9.4 In case of dual class, another method of record keeping of the technical supervision process may be used upon agreement with the Register Head Office (RHO).
2.10 SHIP CONSTRUCTION FILE

2.10.1 The requirements of this Chapter are applicable to all ships except for oil tankers and bulk carriers subject to SOLAS-74 regulation II-1/3-10, for which the requirements in 2.11 shall be applied.

2.10.2 The shipyard shall deliver documents for the Ship Construction File (SCF). In the event that items have been provided by another party such as the shipowner and where separate arrangements have been made for document delivery which excludes the shipyard, that party has the responsibility.

The Ship Construction File (SCF) shall be reviewed for content in accordance with the requirements of 2.10.3.

2.10.3 It is recognized that the purpose of documents held in the Ship Construction File (SCF) on board the ship, shall facilitate inspection (survey) and repair and maintenance, and, therefore, shall include in addition to documents listed in Table 2.5.1, but not be limited to:

.1 as-built structural drawings including scantling details, material details, and, as applicable, wastage allowances, location of butts and seams, cross section details and locations of all partial and full penetration welds, areas identified for close attention and rudders (refer to Part III "Additional Surveys of Ships Depending on Their Purpose and Hull Material" of the Rules for the Classification Surveys of Ships in Service);

.2 manuals required for classification and statutory requirements, e.g. loading and stability, bow doors and inner doors and side shell doors and stem doors — operations and maintenance manuals (refer to 7.4 and 7.15, Part III "Equipment, Arrangements and Outfit" of the Rules for the Classification and Construction);

.3 Ship Structure Access Manual, as applicable;

.4 copies of the RS certificates on forgings and castings welded into the hull (refer to 3.7 and 3.8, Part XIII "Materials" of the Rules for the Classification and Construction);

.5 details of equipment forming part of the watertight and weathertight integrity of the ship;

.5.1 a Cable Transit Seal Systems Register prepared by the shipyard. The Register can be in either a hard copy or digitized media. The recommendatory sample of the Register is given in Appendix 8.

The Register shall include:

information on marking/identification system of cable transits;

reference to the accompanying documentation, namely:

.5.1.1 manufacturer manuals for each type of cable transit installed,

.5.1.2 Type Approval Certificate (CTO) for each type of transit system, as applicable (refer to 2.12.11.4),

.5.1.3 applicable installation drawings;

sections to record condition of each installed cable transit documenting the result after completion of all works and final inspection in the shipyard.

The Register shall also include sections to record any inspection, modification, repair or maintenance of cable transits;

.6 tank testing plan, including details of the test requirements (refer to Appendix 1 to Part II "Hull" of the Rules for the Classification and Construction);

.7 corrosion protection specifications (refer to 1.2.5.1 and 3.3.5.1, Part II "Hull" of the Rules for the Classification and Construction; 5.2.2.3.2 of Part III "Additional Surveys of Ships Depending on Their Purpose and Hull Material" of the Rules for the Classification Surveys);

.8 details for the in-water survey, if applicable, for information for divers, clearances measurements instructions, etc. tank and compartment boundaries;

.9 docking plan and details of all penetrations normally examined at dry docking;

1 Hereinafter referred to as "the Rules for the Classification Surveys".
.10 Coating Technical File, for ships subject to compliance with the IMO Performance Standard for Protective Coatings (PSPC) (refer to IMO resolution MSC.215(82), as amended) as the RS requirement under Part XVIII "Common Structural Rules for Double Hull Oil Tankers" and Part XIX "Common Structural Rules for Bulk Carriers" of the Rules for the Classification and Construction, as well as 2.12.7 of the Guidelines).
2.11 REQUIREMENTS FOR OIL TANKERS AND BULK CARRIERS SUBJECT TO SOLAS CHAPTER II-1 PART A-1 REGULATION 3-10. GOAL-BASED SHIP CONSTRUCTION STANDARDS FOR BULK CARRIERS AND OIL TANKERS

2.11.1 Examination and test plan for new building activities.

2.11.1.1 The shipbuilder shall provide plans of the items which are intended to be examined and tested in accordance with the RS rules in a document known as the Survey Plan, taking into account the ship type and design. This Survey Plan shall be reviewed at the time of the kick-off meeting, and shall include:

.1 a set of requirements, including specifying the extent and scope of the construction surveys and identifying areas that need special attention during the surveys, to ensure compliance of construction with mandatory ship construction standards including:

.1.1 types of surveys (visual, non-destructive examination, etc.) depending on location, materials, welding, casting, coatings, etc.;

.1.2 establishment of a construction survey schedule for all assembly stages from the kick-off meeting, through all major construction phases, up to delivery;

.1.3 inspection/survey plan, including provisions for critical areas identified during design approval;

.1.4 inspection criteria for acceptance;

.1.5 interaction with shipyard, including notification and documentation of survey results;

.1.6 correction procedures to remedy construction defects;

.1.7 list of items that would require scheduling or formal surveys;

.1.8 determination and documentation of areas that need special attention throughout ship's life, including criteria used in making the determination;

.2 a description of the requirements for all types of testing during survey, including test criteria.

2.11.2 Design transparency.

2.11.2.1 For ships subject to compliance with IMO resolutions MSC.287(87), MSC.290(87), MSC.454(100), as amended and IMO circular MSC.1/Circ.1343, as amended, readily available documentation shall include the main goal-based parameters and all relevant design parameters that may limit the operation of the ship.

2.11.3 Ship Construction File (SCF).

2.11.3.1 A Ship Construction File (SCF) with specific information on how the functional requirements of the Goal-Based Ship Construction Standards for Bulk Carriers and Oil Tankers have been applied in the ship design and construction shall be provided upon delivery of a new ship, and kept on board the ship and/or ashore and updated as appropriate throughout the ship's service. The contents of SCF shall conform to the requirements below.

2.11.3.1.1 The following design specific information shall be included in SCF:

.1 areas requiring special attention throughout the ship's life (including critical structural areas);

.2 all design parameters limiting the operation of a ship;

.3 any alternatives to the rules, including structural details and equivalency calculations;

.4 as-built drawings and information which are verified to incorporate all alterations approved by the Register or Administration during the construction process including scantling details, material details, location of butts and seams, cross section details and locations of all partial and full penetration welds;

.5 net (renewal) scantlings for all the structural constituent parts, as built scantlings and voluntary addition thicknesses;

.6 minimum hull girder section modulus along the length of the ship which shall be maintained throughout the ship's life, including cross section details such as the value of the area of the deck zone and bottom zone, the renewal value for the neutral axis zone;
Guidelines on Technical Supervision of Ships under Construction (Section 2)

.7 a listing of materials used for the construction of the hull structure, and provisions for documenting changes to any of the above during the ship's service life;
.8 copies of the RS certificates on forgings and castings welded into the hull (refer to 3.7 and 3.8, Part XIII "Materials" of the Rules for the Classification and Construction);
.9 details of equipment forming part of the watertight and weathertight integrity of the ship;
.9.1 Cable Transit Seal Systems Register prepared by the shipyard. Requirements for the Register contents are specified in 2.10.3.5.1;
.10 tank testing plan including details of the test requirements (refer to Appendix 1 to Part II "Hull" of the Rules for the Classification and Construction);
.11 details for the in-water survey, when applicable, information for divers, clearances measurements instructions, etc. tank and compartment boundaries;
.12 docking plan and details of all penetrations normally examined at dry docking;
.13 Coating Technical File (CTF), for ships subject to compliance with the IMO Performance Standard for Protective Coatings (PSPC')

2.11.3.1.2 The details of information to be included in SCF are given in Table 2.11.3.1.2. This information shall be kept on board the ship and/or ashore and updated as appropriate throughout the ship's life in order to facilitate safe operation, maintenance, survey, repair and emergency measures.

2.11.3.1.3 It shall be noted that parts of the content of SCF may be subject to various degrees of restricted access and that such documentation may be appropriately kept ashore.

2.11.3.1.4 SCF shall include the list of documents constituting SCF and all information listed in Table 2.11.3.1.2, which is required for a ship's safe operation, maintenance, survey, repair and in emergency situations. Details of specific information that is not considered to be critical to safely might be included directly or by reference to other documents.

2.11.3.1.5 When developing SCF, all of the columns in Table 2.11.3.1.2 shall be reviewed to ensure that all necessary information has been provided.

2.11.3.1.6 It may be possible to provide information listed in IMO resolution MSC.287(87), as amended under more than one Tier II functional requirement as a single item within SCF, for example, the Coating Technical File required by the PSPC is relevant for both "Coating life" and "Survey during construction".

Note. Tier II items mean the functional requirements included in the International Goal-Based Ship Construction Standards for Bulk Carriers and Oil Tankers (GBS), adopted by IMO resolution MSC.287(87), as amended.

2.11.3.1.7 SCF shall remain with the ship and, in addition, be available to RS and Administration throughout the ship's life. Where information not considered necessary to be on board is stored ashore, procedures to access this information shall be specified in the onboard SCF. The intellectual property provisions within the SCF shall be duly complied with.

2.11.3.1.8 SCF shall be updated throughout the ship's life at any major event, including, but not limited to, substantial repair and conversion, or any modification to the ship structure.

2.11.3.2 SCF shall be reviewed, at the time of new building, in accordance with the requirements of 2.11.3.1.1 and 2.11.3.1.2, and the normal storage location shall be distinguished.

Note. "Review" means the examination of SCF that is carried out by the RS surveyor, at the end of the newbuilding process, in order to confirm that drawings/documents required under this Chapter, and the possible additional drawings/documents provided by the shipyard as per the SCF list of drawings/documents are present in the copies of SCF stored on board the ship and in the shore archive.

1 Performance Standard for Protective Coatings for Dedicated Seawater Ballast Tanks in all Types of Ships and Double-Side Skin Spaces of Bulk Carriers, adopted by IMO resolution MSC.215(82), as amended and Performance Standard for Protective Coatings for Cargo Oil Tanks of Crude Oil Tankers adopted by IMO resolution MSC.288(87), as amended.
The "review" shall not be intended as an assessment of the drawings/documents in order to verify their compliances with the applicable rules/regulations.

2.11.3.2.1 For SCF stored on board the ship, the RS surveyor shall verify that the information is placed on board the ship, upon completion of the ship construction.

2.11.3.2.2 For SCF stored in the shore archive, the RS surveyor shall verify that the information is stored in the shore archive by examining the list of information included in the shore archive, upon completion of the ship construction.

2.11.4 Determination of number of surveyors.

2.11.4.1 RS shall assign adequate number of suitable qualified surveyors for newbuilding projects according to the construction progress of each ship to meet appropriate coverage of the examination and testing activities as agreed in the Survey Plan.

Table 2.11.3.1.2

List of information to be included in the Ship Construction File (SCF)

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Tier II items</th>
<th>Information to be included</th>
<th>Further explanation of the content</th>
<th>Example documents</th>
<th>Normal storage location</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Design life</td>
<td>assumed design life in years</td>
<td>statement or note on midship section</td>
<td>SCF-specific</td>
<td>on board ship</td>
</tr>
<tr>
<td>2</td>
<td>Environmental conditions</td>
<td>assumed environmental conditions</td>
<td>statement referencing data source or RS rules (specific rule and data) or; in accordance with the RS rules (date and revision)</td>
<td>SCF-specific</td>
<td>on board ship</td>
</tr>
<tr>
<td>3</td>
<td>Structural strength</td>
<td>applied RS rules (date and revision)</td>
<td>applied design method alternative to the RS rules and subject structure(s)</td>
<td>SCF-specific</td>
<td>on board ship</td>
</tr>
<tr>
<td>3.1</td>
<td>General design</td>
<td>applied alternative to the RS rules</td>
<td>capacity plan</td>
<td>on board ship</td>
<td></td>
</tr>
<tr>
<td>3.2</td>
<td>Deformation and failure modes</td>
<td>calculating conditions and results</td>
<td>allowable loading pattern</td>
<td>loading manual</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>assumed loading conditions</td>
<td>maximum allowable hull girder bending moment and shear force</td>
<td>trim and stability booklet</td>
<td>on board ship</td>
</tr>
<tr>
<td>3.3</td>
<td>Ultimate strength</td>
<td>operational restrictions due to structural strength</td>
<td>allowable cargo density or storage factor</td>
<td>maximum loading instrument instruction</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>manual operation and maintenance manuals</td>
<td>strength calculation</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>on shore archive</td>
</tr>
<tr>
<td>3.4</td>
<td>Safety margins</td>
<td>strength calculation results</td>
<td>bulky output of strength calculation</td>
<td>plan showing highly stressed areas (e.g. critical structural areas) prone to yielding and/or buckling</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>areas prone to yielding and/or buckling</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>gross hull girder section modulus</td>
<td>on board ship</td>
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<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>minimum hull girder section modulus along the length of the ship to be maintained throughout the ship’s life, including cross section details such as the value of the area of the deck zone and bottom zone, the</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>general arrangement plan</td>
<td>on board ship</td>
</tr>
<tr>
<td>Nos.</td>
<td>Tier II items</td>
<td>Information to be included</td>
<td>Further explanation of the content</td>
<td>Example documents</td>
<td>Normal storage location</td>
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</tr>
<tr>
<td>39</td>
<td></td>
<td>renewal value for the neutral axis zone</td>
<td>structural drawings</td>
<td>key construction plans</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>gross scantlings of structural constituent parts</td>
<td>rudder and stern frame</td>
<td>rudder and rudder stock plans</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>net scantlings of structural constituent parts, as built scantlings and voluntary addition thicknesses</td>
<td>structural details of typical members</td>
<td>structural details</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>yard plans</td>
<td>on shore archive</td>
</tr>
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<td></td>
<td></td>
<td></td>
<td></td>
<td>dangerous area plan</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>hull form</td>
<td>hull form information indicated in key construction plans</td>
<td>lines plan</td>
<td>on shore archive</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>hull form data stored within an onboard computer necessary for trim and stability and longitudinal strength calculations</td>
<td>or equivalent</td>
<td>on board ship</td>
</tr>
<tr>
<td>4</td>
<td>Fatigue life</td>
<td>applied RS rules (date and revision)</td>
<td>applied design method alternative to the RS rules and subject structures</td>
<td>SCF-specific</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>applied alternative to the RS rules</td>
<td>calculating conditions and rates</td>
<td>structural details</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>assumed loading conditions</td>
<td></td>
<td></td>
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</tr>
<tr>
<td></td>
<td></td>
<td>fatigue life calculation results</td>
<td>bulky output of fatigue life calculation</td>
<td>fatigue life calculation</td>
<td>on shore archive</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>plan showing areas (e.g. critical structural areas) prone to fatigue</td>
<td>areas prone to fatigue</td>
<td>on board ship</td>
</tr>
<tr>
<td>5</td>
<td>Residual strength</td>
<td>applied RS rules (date and revision)</td>
<td>SCF-specific</td>
<td>on board ship</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Protection against corrosion</td>
<td></td>
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</tr>
<tr>
<td>6.1</td>
<td>Coating life</td>
<td>coated areas and target coating life and other measures for corrosion protection in holds, cargo and ballast tanks, other structure-integrated deep tanks and void spaces</td>
<td>plans showing areas (e.g. critical structural areas) prone to excessive corrosion</td>
<td>SCF-specific</td>
<td>on board ship</td>
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</tr>
<tr>
<td>6.2</td>
<td>Corrosion addition</td>
<td>specification for coating and other measures for corrosion protection in holds, cargo and ballast tanks, other structure-integrated deep tanks and void spaces</td>
<td></td>
<td>Coating Technical File required by PSPC</td>
<td>on board ship</td>
</tr>
<tr>
<td></td>
<td></td>
<td>gross scantlings of structural constituent parts</td>
<td>key construction plans</td>
<td>on board ship</td>
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<tr>
<td></td>
<td></td>
<td>net scantlings of structural constituent parts, as built scantlings and voluntary addition thicknesses</td>
<td></td>
<td>on board ship</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>Structural redundancy</td>
<td>applied RS rules (date and revision)</td>
<td>SCF-specific</td>
<td>on board ship</td>
<td></td>
</tr>
</tbody>
</table>
### Watertight and Weathertight Integrity

- **8 Watertight and Weathertight Integrity**
  - **Applied RS Rules (Date and Revision):** SCF-specific
  - Key factors for watertight and weathertight integrity
  - Details of equipment forming part of the watertight and weathertight integrity
  - Structural details of hatch covers, doors and other closings integral with the shell and bulkheads

### Human Element Considerations

- **9 Human Element Considerations**
  - List of ergonomic design principles applied to ship structure design to enhance safety during operations, inspections and maintenance of ship

### Design Transparency

- **10 Design Transparency**
  - **Applied RS Rules (Date and Revision):** SCF-specific
  - Applicable industry standards for design transparency and IP protection
  - Reference to part of SCF information kept ashore

### Construction

- **11 Construction Quality Procedures**
  - **Applied Construction Quality Standard:** SCF-specific
  - Recognized national or international construction quality standard

### Survey During Construction

- **12 Survey During Construction**
  - **Survey Regime Applied During Construction:** SCF-specific
  - Information on non-destructive examination
  - Copies of certificates of forgings and castings welded into the hull
  - Tank testing plan
  - Non-destructive testing plan

### Survey and Maintenance

- **13 Survey and Maintenance**
  - **Survey and Maintenance Plan:** SCF-specific
  - Plan showing highly stressed areas (e.g. critical structural areas) prone to yielding, buckling, fatigue and/or excessive corrosion
  - Operation and maintenance manuals (e.g. hatch covers and doors)
  - Arrangement (docking plan) and details of all penetrations normally examined at dry-docking
  - Docking plan
  - Gross hull girder section plan
  - Details for dry-docking
  - Dangerous area plan
  - Minimum hull girder section modulus along the length of the ship to be maintained throughout the ship’s life, including cross section details such as the value of the area of the deck zone and bottom zone, the renewal value for the neutral axis zone
  - Details for in-water survey
  - Ship Structure Access Manual
  - Means of access to other

### In-Service Considerations

- **Coating Technical File Required by PSPC (on board ship)**
<table>
<thead>
<tr>
<th></th>
<th></th>
<th>structure-integrated deep tanks</th>
<th>Coating Technical File required by PSPC</th>
<th>on board ship</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>gross scantlings of structural constituent parts</td>
<td>key construction plans</td>
<td>on board ship</td>
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<tr>
<td></td>
<td>net scantlings of structural constituent parts, as built scantlings and voluntary addition thicknesses</td>
<td>rudder and rudder stock</td>
<td>on board ship</td>
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<tr>
<td></td>
<td></td>
<td>structural details</td>
<td>on board ship</td>
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<td></td>
<td></td>
<td>yard plans</td>
<td>on shore archive</td>
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<td></td>
<td></td>
<td>hull form information indicated in key construction plans</td>
<td>lines plan</td>
<td>on shore archive</td>
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<td></td>
<td></td>
<td></td>
<td>or</td>
</tr>
<tr>
<td>14</td>
<td>Structural accessibility</td>
<td>means of access to holds, cargo and ballast tanks and other structure-integrated deep tanks</td>
<td>Ship Structure Access Manual on board ship</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>plans showing arrangement and details of means of access</td>
<td>on board ship</td>
<td></td>
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<tr>
<td></td>
<td></td>
<td>means of access to other structure-integrated deep tanks</td>
<td>on board ship</td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>Recycling</td>
<td>identification of all materials that were used in construction and may need special handling due to environmental and safety concerns</td>
<td>list of materials used for the construction of the hull structure</td>
<td>SCF-specific</td>
</tr>
</tbody>
</table>

**RECYCLING CONSIDERATIONS**

**Notes:**
1. "SCF-specific" means documents to be developed especially to meet the requirements of these GBS guidelines (MSC.1/Circ.1343, as amended).
2. "Key construction plans" means plans such as midship section, main oil tight and water tight transverse bulkheads, construction profiles/ plans, shell expansions, forward and aft sections in cargo tank (or hold) region, engine-room construction, forward construction and stern construction drawings.
3. "Yard plans" means a full set of structural drawings, which include scantling information of all structural members.
4. "Hull form" means a graphical or numerical representation of the geometry of the hull. Examples shall include the graphical description provided by a lines plan and the numerical description provided by the hull form data stored within an onboard computer.
5. "Lines plan" means a special drawing which is dedicated to show the entire hull form of a ship.
6. "Equivalent (to Lines plan)" means a set of information of hull form to be indicated in key construction plans for SCF purposes. Sufficient information shall be included in the drawings to provide the geometric definition to facilitate the repair of any part of the hull structure.
7. "Normal storage location" means a standard location where each SCF information item shall be stored. However, those items listed as being on board in the Table above shall be on board as a minimum to ensure that they are transferred with the ship on a change of owner.
8. "Shore archive" shall be operated in accordance with applicable international standards.
2.12 ADDITIONAL EXPLANATIONS AND COMMENTS TO SOME ITEMS OF **TABLE 2.5.1** (IN BRACKETS)

2.12.1 **Inspection of materials in use (items 1.1, 2.1, 3).**
- **2.12.1.1** The proper use of hull materials in accordance with a ship's technical design approved is subject to the Register control.
- **2.12.1.2** Provision shall be made for an accurate system for inspection of material supplied to the shipyard, for parts marking including cases when the material used lacks the per sheet marking in manufacturing.

The shipyard's document on a procedure for recording, storage and use of materials shall be presented to the RS Branch Office. That procedure shall provide an opportunity to present to the RS surveyor a certificate for the metal of which parts of the hull are manufactured at any stage of its construction.

2.12.1.3 In survey according to the List, the RS surveyor inspects the materials used at a particular item of technical supervision, at that the following shall be checked:

- **1.** Availability of the RS certificate or supplier's certificates witnessed by the RS surveyor for plates, sheets, strips, sections, bars, pipes, castings and forgings or cast and forged products. Welding consumables (electrodes, wire, fluxes, etc.) shall be accompanied with the documents confirming their testing and RS approval at the firm (manufacturer);
- **2.** Compliance of the material with particulars of a certificate and/or supplier's certificate;
- **3.** Compliance of material brands with the requirements of the RS-approved design.

2.12.1.4 At patrol, the RS surveyor checks the practiced procedure for recording, storage and use of materials.

2.12.1.5 In survey according to the List and in performance of periodical inspections, the RS surveyor shall make sure in the absence of metal defects like cracks, exfoliations, cavities, blisters, scabs, fissures, rolled-in scale, etc. To reveal internal flaws, the surveyor can, if justified, require checking the metal with use of non-destructive or other techniques.

2.12.1.6 Where it is impossible to identify material and where defects are detected, or where material is not in compliance with the requirements of a drawing, rules and recognized standards, or documents for material are lacking or inadequate, and etc., the surveyor shall prevent its use for a given structure or permit the elimination of defects according to the agreed procedure and demand additional check tests and analyses, and changes in the procedure for material inspection in the shipyard.

2.12.2 **Welder qualification (item 1.2).**
- **2.12.2.1** The welders may be admitted to perform welding of items under the RS technical supervision, having drawing up a Welder Approval Test Certificate (СДС) (form 7.1.30), granting the right for performing the relevant types of welding of those materials required to fabricate structures subject to technical supervision by the Register.
- **2.12.2.2** A possibility of recognition of welder's qualification records issued by another classification society or duly authorized competent authority shall be determined in each particular case by the RS Branch Office to an extent sufficient to confirm their compliance with the requirements of Section 4, of Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision. The results of considering the above mentioned documents and confirmation of possible admission for welders shall be issued as a Report (form 6.3.29).

2.12.2.3 Upon agreement with the RS Branch Office (or at approval of design documentation of the ship under construction), the welders who passed approval tests in compliance with the international (ISO 9606-1:2012/COR 2:2013, ASME Sec. IX, ANSI/AWS D1.1) and/or national standards are permitted to perform welding operations.
2.12.3 Testing of welding procedures (paras 1.3, 1.3b, 1.3c, 2.4, 2.5, 3).
2.12.3.1 Prior to any checks of welded joints the RS surveyor shall mandatorily ascertain
that the welding procedure specifications (WPS), available at the shipyard and RS approved, cover
all weld joint configurations/types applied in the RS approved project (indicated in the approved
drawings and/or hull welding table). Otherwise, the RS Branch Office shall notify the shipyard
of the necessity to start the procedure of approval of joint welding procedures without the approved
welding procedure specifications (WPS) in accordance with the provisions of Section 6 of Part III
2.12.3.2 During surveys as per the List and in performance of periodical inspections, the
surveyor shall make sure that all welding works are performed in accordance with the
approved WPS. The structural requirements for the WPS shall be verified for compliance with
the actual condition of welded joints as well as provisions of the RS approved project.
2.12.3.3 The main and welding consumables, design and technical parameters and also
welding conditions specified in WPS shall be examined and/or validated according to
Table 6.8.2.3, Section 6, Part III “Technical Supervision during Manufacture of Materials” of
the Rules for Technical Supervision.
2.12.3.4 Additional requirements are given in 2.12.4 and 2.12.5.
2.12.4 Surveys of units, sections and blocks (items 1.4, 1.5, 2.2, 2.3, 2.4, 2.5, 3).
2.12.4.1 Manufacture of flat plate panels, framing girders including deep frames, sections
and single units forming hull structures of the main hull, superstructures and deckhouses is
subject to the Register technical supervision.
2.12.4.2 The selected production process chart for assembling and welding of hull
structures, as well as assembly jigs and welding equipment is within the competence of the
shipyard and it shall be specified in the relevant shipyard standard.
2.12.4.3 In construction of series-built ship's hulls specified in 2.3.6, the RS Branch Office
may recognize sufficient to restrict itself to periodical examinations of completed sections and
single units without their submitting to the RS surveyor for survey according to the List.
The resolution concerning sufficiency of periodical examinations of completed sections and
single units without submitting them as per the List shall be issued in the form of the report
with participation of the RS Branch Office, shipyard and other parties concerned (upon the
shipyard agreement). The report shall contain the technical justification of the resolution,
confirming positive experience of technical supervision during construction of sister ships.
2.12.4.4 The scope of survey for units, sections, blocks shall be made prior to the ship
construction commencement compliant to 2.8. The shipyard shall submit the scheme of hull
division into sections and blocks as well as production sequence of the assembly and welding
operations to the RS Branch Office for agreement of survey scope.
2.12.4.5 The sections subject to survey under the List shall only be submitted after the
fully completed assembly and welding, apart from the operations provided by the welding
procedure at a later stage, such as:
- individual components of a hull structure;
- parts of hull outfitting and/or welded attachments;
- cutouts, etc.

The above fact shall be indicated in the shipyard document for the completed section
(block) or by another adopted way so that the shipyard's technical control body may present
and the surveyor may check the fulfilment of incomplete works in due time.
2.12.4.6 The blocks to be surveyed according to the List shall be submitted complete and
fit for the hull construction directly at the building berth.

To the sites of blocks manufacture the sections and single units shall be conveyed fully
completed, accepted by the shipyard's technical control body and, if specified by the List,
surveyed by the Register. With the parallel performance of the hull and assembly works, the
blocks may be presented at two steps; the possibility and scope of each step shall be agreed
with the RS surveyor regarding the necessary availability of access to all the hull structures.
2.12.4.7 In periodical inspections of assembly before welding, the RS surveyor checks compliance of the edge preparation of the parts to the requirements of drawings, welding tables as well as CFIC, in which the structural elements of edges shall be specified.

2.12.4.8 During any inspections of welding works performance, the RS surveyor shall make sure that welding is carried out in accordance with the production process approved by the Register. (see also para 2.12.3). In so doing, one shall regard the limiting conditions, if these are specified in technical documentation on a welding method and in the production process, including those for material brands, thicknesses, welding positions, welding directions, an ambient air temperature, etc.

2.12.4.9 During any inspections the RS surveyor shall make sure that the welding defects, if any, are within the permissible limits specified in the agreed quality standards. Where defects are regular, the surveyor shall require from the shipyard the elimination of their causes and develop measures for defects rectification.

2.12.4.10 The RS surveyor shall control the conformity with the applicable requirements for welding given in Section 2, Part XIV "Welding" of the Rules for the Classification and Construction. The RS surveyor is entitled to require the additional inspection of welding quality from the shipyard if welding is executed under adverse conditions.

2.12.4.11 The RS surveyor shall control timely (once in 6 months) submission by the shipyard of the information on percentage of welded joint defects according to 3.3.7, Part XIV "Welding" of the Rules for the Classification and Construction and require an increase in the number of controlled weld lengths by 10 % if the percentage of defects is more than 5.

2.12.4.12 Sections and/or blocks manufactured at another subcontractor shall be subject to the Register survey prior to delivery to the shipyard and shall be supplied with the Register appropriate documents (refer also to Section 2 "Hull" of Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision).

2.12.5 Hull survey at the building birth (item 3).

2.12.5.1 Scope of survey at the building birth shall be defined prior to the ship construction according to 2.8.

2.12.5.2 Sections and blocks shall be conveyed to the building berth fully completed, accepted by the shipyard's technical control body and surveyed by the RS surveyor.

2.12.5.3 Hull survey during its construction at the building berth includes inspections of all the hull structures in the sequence of the approved construction process and specified in the agreed List. Special consideration shall be paid to the mounting couplings.

2.12.5.4 To survey are presented hull spaces (including compartments, tanks, etc.) according to the List and scheme of spaces after completion of assembly, welding, riveting and straightening, and having fitted all the outfitting components related to the equipment, etc. being joined directly to hull structures.

2.12.5.4.1 Single outfitting components may be ignored by agreement with the RS surveyor, but the missing components shall be specified in the shipyard's document on the availability of the item of supervision to be submitted to the Register for survey. The RS surveyor in his/her conclusion states the conditions for the follow-up control over fitting the lacking outfitting components.

2.12.5.4.2 Following the survey of a space by the RS surveyor, any working associated with thermal cutting, chipping, welding and riveting may be performed with the surveyor's consent and approval provided they do not effect structure strength or tightness.

2.12.5.5 In periodical inspections during the ship's hull construction at the building berth, the RS surveyor checks the sequence of operations to prevent excess stresses and deformations of the hull, monitors checking the hull position at the building berth; and its compliance with the agreed standards.

2.12.5.6 When executing the joints, the sequence of operations and quality shall be under control.
2.12.5.7 Cutting-out of holes and welding of structures into the closed contour shall be performed according to RS-approved drawings and/or the production processes or standards agreed with the Register.

The shipyard shall submit to the RS Branch Office for approval the scheme of temporary cutouts, the practice of their execution and of the subsequent quality control.

2.12.6 Hull tightness and structural testing (items 5, 6).

2.12.6.1 Hull testing for leakproofness and structural tests shall be carried out and witnessed by the Surveyor, and as a rule, once a space or structure is fully prepared for testing, filled with a medium to the head (pressure) set and checked by the shipyard's technical control body in compliance with the RS-approved test procedure to be developed according to Appendix 1 to Part II "Hull" of the Rules for the Classification and Construction.

2.12.6.2 In periodical inspections, the RS surveyor checks the availability of spaces (compartments, structures) for testing, verifies the procedure and sequence of basic operations during preliminary, major and check tests (both prior to and in the process of test submitting by the shipyard’s technical control body), the test conditions, validity of tightness estimation and checks the defects elimination.

2.12.7 Hull protection against corrosion, coatings (items 7, 7.1).

2.12.7.1 General concept of technical supervision during application of protective coatings.

2.12.7.1.1 In general, technical supervision during application of protective coatings shall be carried out based on the Register-approved specification of protective coatings being submitted in the scope of plan approval documentation of the ship under construction.

2.12.7.1.2 Subject to technical supervision are protective coatings listed in the Nomenclature of Items of the Register Technical Supervision1 and submitted together with the documents to prove their manufacture under the Register technical supervision (refer also to 6.5, Part XIII "Materials", 2.1.1.6, 2.1.1.7, Part VI "Fire Protection" of the Rules for the Classification and Construction and 3.1.1, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision).

2.12.7.1.3 Technical supervision of surface preparation and application of protective coating shall be carried out by the RS surveyor mainly by visual examination during periodical inspections and verification of the data specified on the packing, in the documents confirming manufacture of coating materials under the Register technical supervision, on the protective coating specifications, records of work completion.

The records mean the documents issued by the shipyard and/or its subcontractors and confirming the completion of work on surface preparation for protective coating application. The Final Inspection Report may be used as such record (the recommended form is given in Appendix 2 to this Section).

2.12.7.1.4 Technical documentation of the coating system used, the scheme for the selection, application, maintenance of the coating system shall be kept in the RS Branch Office.

2.12.7.2 Technical supervision of protective coatings for ballast tanks in compliance with the Performance Standard for Protective Coatings (PSPC) adopted by IMO resolution MSC.215(82), as amended.

2.12.7.2.1 Technical supervision during application of protective coatings for ballast tanks in compliance with PSPC shall be carried out based on:

- surface preparation and coating processes agreement signed by the shipyard, shipowner and coating manufacturer2 (shall be agreed with the RS Branch Office prior to commencement of works and shall at least contain the information specified in 3.2.3.3, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision);

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1 Hereinafter referred to "the RS Nomenclature".
2 Hereinafter referred to "the Tripartite Agreement".)
the following documentation from the Coating Technical File (CTF): coating specification, including selection of areas (spaces) to be coated, selection of coating system, surface preparation and coating process, the RS Certificate for the coating system (documentation shall be agreed with the RS Branch Office prior to commencement of works, refer to 3.2.3.2, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision);

2.12.7.2.2 In compliance with PSPC CTF consists of the following:
1 copy of a Type Approval Certificate for the coating system;
2 copy of documentation defining the coating properties, composition and characteristics (Technical Data Sheet), technical conditions, specifications, technological regulations, instructions or descriptions, etc. as appropriate);
3 shipyard's work records of coating application, including:
   - applied actual space and area of each compartment, m²;
   - applied coating system;
   - time of coating, thickness, number of layers, etc.;
   - ambient condition during coating;
   - method of surface preparation;
4 procedures for inspection and repair of coating system during ship construction;
5 coating log issued by the coating inspector, stating that the coating was applied in accordance with the specifications to the satisfaction of the coating supplier representative and specifying deviations from the specifications (examples of daily log and non-conformity report are given in PSPC);
6 shipyard's inspection report on the surface preparation for coating application verified by the coating inspector including:
   - completion date of inspection;
   - result of inspection;
   - remarks (if given);
   - coating inspector signature;
7 procedures for in-service maintenance and repair of coating system (in compliance with the documents specified in 3.1.2.2.5, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision).

2.12.7.2.3 Any deviations in the procedure relative to the PSPC noted during the review shall be raised with the shipyard, which is responsible for identifying and implementing the corrective actions.

2.12.7.2.4 To ensure compliance with the PSPC requirements, the surface preparation and coating application shall be inspected by qualified coating inspector(s) certified to "NACE¹, Coating Inspector Level II", "FROSIO². Coating Inspector Level III" or equivalent as verified by the Register (refer to 3.2.9, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision). The organization involved in training of the inspectors having equivalent qualification shall have the Certificate of Firm Conformity (form 7.1.27) with code 22017020 (refer to Table 12.1.1, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision). Certificate of Competence confirming the coating inspectors' qualification is recommended to be indicated in the Tripartite Agreement and a copy of the Certificate to be included in CTF.

2.12.7.2.5 During the CTF review and technical supervision during application of protective coatings for ballast tanks in compliance with PSPC, the RS surveyor shall perform the following:

¹ NACE — National Association of Corrosion Engineers.
² FROSIO — Norwegian Professional Council for Education and Certification of Inspectors for Surface Treatment.
.1 check that the documentation specified in 2.12.7.2.2.2 and the Type Approval Certificate comply with PSPC;
.2 check that the coating identification on representative containers is consistent with the coating identified in the documentation specified in 2.12.7.2.2.2 and the Type Approval Certificate;
.3 check that the coating inspector is qualified in accordance with 2.12.7.2.4;
.4 check that the coating inspector’s reports of surface preparation and the coating’s application indicate compliance with the manufacturer's documentation specified in 2.12.7.2.2.2 and the Type Approval Certificate;
.5 by periodical inspections monitor implementation of the coating inspection requirements of the coatings subject to inspection (refer to 3.2.10.1, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision and item 7.1 of Table 2.5.1 of the Guidelines);
.6 any deviations from PSPC shall be raised initially with the coating inspector, who is responsible for identifying and implementing the corrective actions. Moreover, in the event that corrective actions are not acceptable to the Register or in the event that corrective actions are not closed out then the shipyard shall be informed;
.7 a Passenger Ship Safely Certificate or Cargo Ship Safely Certificate or Cargo Ship Safety Construction Certificate, as appropriate, shall not be issued until all required corrective actions have been closed to the satisfaction of the Register.

2.12.7.3 Technical supervision of protective coatings for cargo tanks of crude oil tankers of 5000 t deadweight and over, in compliance with Performance Standard for Protective Coatings for Cargo Oil Tanks of Crude Oil Tankers (PSPC-COT) adopted by IMO resolution MSC.288(87), as amended.

2.12.7.3.1 Technical supervision during application of protective coatings for oil tanker ballast tanks in compliance with PSPC-COT is carried out based on:

- Tripartite Agreement (shall be agreed with the RS Branch Office prior to commencement of works and shall at least contain the information specified in 3.2.3.3 and 3.3.3.1, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision);
- the following documentation from CTF: coating specification, including selection of areas (spaces) to be coated, selection of coating system, surface preparation and coating process, the RS Certificate for the coating system (documentation shall be agreed with the RS Branch Office prior to commencement of works, refer to 3.2.3.2 and 3.3.3.1, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision);
- technical specification of protective coatings (approved by the Register in the scope of plan approval documentation of ship under construction).

2.12.7.3.2 CTF consists of the documents similar to those indicated in 2.12.7.2.2 but applicable to PSPC-COT.

2.12.7.3.3 To ensure compliance with the PSPC requirements, the surface preparation and coating application shall be inspected by qualified coating inspector(s) certified to “NACE”. Coating Inspector Level II”, "FROSIO®. Coating Inspector Level III" or equivalent as verified by the Register (refer to 3.2.9, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision). The organization conducting training of the inspectors having equivalent qualification shall have the Certificate of Firm Conformity (form 7.1.27) with code 22017020 (refer to Table 12.1.1, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision). The certificate confirming the coating inspectors’ qualification is recommended to be indicated in the Tripartite Agreement and a copy of the certificate to be included in CTF.

2.12.7.3.4 During the CTF review and technical supervision during application of protective coatings in compliance with PSPC, the RS surveyor shall perform the following:

- check that the documentation specified in 2.12.7.2.2.2 and the Type Approval Certificate comply with PSPC-COT;
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.2 check that the coating identification on representative containers is consistent with the coating identified in the documentation specified in 2.12.7.2.2.2 and the Type Approval Certificate;
.3 check that the coating inspector is qualified in accordance with 2.12.7.3.3;
.4 check that the coating inspector's reports of surface preparation and the coating's application indicate compliance with the manufacturer's documentation specified in 2.12.7.2.2.2 and the Type Approval Certificate;
.5 by periodical inspections monitor the compliance with the requirements to coating inspection (refer to 3.3.10, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision).
2.12.7.3.5 In respect of PSPC-COT the requirements shall be applied similar to those specified in 2.12.7.2.3 and 2.12.7.2.5.6.
2.12.7.3.6 Cargo Ship Safely Certificate or Cargo Ship Safety Construction Certificate shall not be issued until all required corrective actions have been closed to the satisfaction of the Register.
2.12.7.4 Technical supervision of protective coatings for cargo spaces, hatch coamings and hatch covers of bulk carriers.
2.12.7.4.1 The requirement applies to the technical supervision of protective coatings specified in 3.3.5.1, Part II "Hull" of the Rules for the Classification and Construction.
2.12.7.4.2 Technical supervision shall be carried out in compliance with the general concept of technical supervision during application of protective coatings specified in 2.12.7.1.
2.12.7.4.3 In the records of work completion on surface preparation and protective coating application the information shall be stated in the scope recommended by the Final Inspection Report (refer to Appendix 2 to this Section).
2.12.7.5 Technical supervision of anti-fouling coatings of ship hulls.
2.12.7.5.1 Technical supervision during application of anti-fouling coatings of ship hulls shall be carried out in compliance with 2.4.3, Part III "Survey of Ships in Compliance with International Conventions, Codes, Resolutions and Rules for the Equipment of Sea-Going Ships" of the Guidelines on Technical Supervision of Ships in Service.
2.12.7.6 Technical supervision of ice resistant protective coatings of ships, to which character of classification the distinguishing mark ICE-COAT is added and in which Classification Certificate a special entry is made on reduction of allowance for corrosion wear and abrasion when special measures are taken to protect the shell plating (refer to 3.10.4.1, Part "Hull" and 6.5.3 Part XIII "Materials" of the Rules for the Classification and Construction).

Requirements of 2.12.7.6.1–2.12.7.6.6 do not apply to ice resistant protective coatings of the ships, to which character of classification the distinguishing mark ICE-COAT is added at the shipowner's discretion (i.e. without reducing the annual reduction of shell plating).
2.12.7.6.1 Technical supervision during application of ice resistant protective coatings shall be carried out based on:

Tripartite Agreement signed by the shipyard, shipowner and coating manufacturer and agreed with the Register (refer to 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision),
documentation from the CTF in accordance with Table 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision, except the Final Inspection Report on Surface Preparation for Protective Coating Application;
technical specifications of protective coatings approved by the Register in the scope of the plan approval documentation of ship under construction.
Prior to commencement of works, the Tripartite Agreement and specified documentation as part of CTF shall be agreed with the RS Branch Office.
2.12.7.6.2 CTF (upon completion of all works) consists of the following:
.1 copy of a Type Approval Certificate for the ice resistant coating system;
.2 copies of documentation defining the coating properties, composition and characteristics (Technical Data Sheet), technical conditions, specifications);
.3 technological regulations, instructions or descriptions, etc. as appropriate);
.4 procedures for inspection and repair of ice resistant coating system during ship construction;
.5 daily logs and non-conformity reports (if any);
.6 Final Inspection Report on Surface Preparation for Protective Coating Application (refer to Appendix 2 to this Section) verified by the coating inspector certified to "NACE. Coating Inspector Level II", "FROSIO. Coating Inspector Level III" or equivalent (refer to 3.5.11.2, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision).

2.12.7.6.3 Any deviations from 3.5.3 — 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision noted during the review of the mentioned documentation shall be raised with the shipyard, which is responsible for identifying and implementing the corrective actions.

2.12.7.6.4 To ensure compliance with the requirements in 3.5.3 — 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision, the surface preparation and coating application shall be inspected by qualified coating inspector(s) certified to "NACE. Coating Inspector Level II", "FROSIO. Coating Inspector Level III" or equivalent as verified by the Register (refer to 3.5.11.2, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision). The organization conducting training of the inspectors having equivalent qualification shall have the Certificate of Firm Conformity (form 7.1.27) with code 22017202 (refer to Table 12.1.1, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision). The certificate confirming the coating inspectors' qualification is recommended to be indicated in the Tripartite Agreement and a copy of the certificate to be included in CTF.

2.12.7.6.5 During the CTF review and technical supervision during application of protective coatings for ballast tanks in compliance with the requirements in 3.5.3 — 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision, the RS surveyor shall perform the following:

.1 check that the documentation specified in 2.12.7.6.2 and the Type Approval Certificate comply with 3.5.3 — 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision;
.2 check that the coating identification on representative containers is consistent with the coating identified in the documentation specified in 2.12.7.6.2 and the Type Approval Certificate;
.3 check that the coating inspector is qualified in accordance with 2.12.7.6.4;
.4 check that the coating inspector's reports of surface preparation and the coating's application indicate compliance with the manufacturer's documentation specified in 2.12.7.6.2.2 and the Type Approval Certificate;
.5 by periodical inspections monitor implementation of the coating preparation and application requirements.

2.12.7.6.6 Any deviations from the requirements in 3.5.3 — 3.5.11, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision shall be raised initially with the coating inspector, who is responsible for identifying and implementing the corrective actions. Moreover, in the event that corrective actions are not acceptable to the Register or in the event that corrective actions are not closed out then the shipyard shall be informed.

2.12.7.7 Technical supervision during cathodic protection.

2.12.7.7.1 For ships constructed in compliance with IACS Common Structural Rules for Bulk Carriers and Oil Tankers when attaching the sacrificial anodes additionally the requirements of para 2, Section 4, Chapter 3, Part 1 of the Common Structural Rules for Bulk Carriers and Oil Tankers shall be met.

2.12.8 Hull availability for launching (items 1.4, 1.5, 3.4, 5.6, 7, 7.1, 8.2, 8.3, 8.5).

2.12.8.1 The hull launch shall be carried out with the ship's readiness corresponding to the agreed construction process. If hull works or/and works on bottom-and-side fittings or/and azimuth thrusters installation are incomplete, the opportunity and conditions of launching shall
be checked, for which purpose the shipyard shall submit to the RS surveyor the technical substantiation.

2.12.8.2 The building berth, dock, etc. preparation, launch performance with due regard to longitudinal and local strength, as well as the documents on the ship's expected design trim after launching (i.e. heel, trim and midship draught) are within the shipyard's responsibility and not subject to the Register technical supervision.

2.12.8.3 Prior to launching, the shipyard shall finally check the hull position on the building berth, its dimensions, the presence of hull deformations with measurements of their values, and to make other checks in compliance with the agreed standards. The results obtained are used for monitoring as-built deformations of the hull, and also for the receipt of data needed for filling in the ship's documents, for which purpose the scope of dimensions checking shall be agreed with the RS Branch Office.

Deviations for the main dimensions of the hull shall not exceed the limits specified in the agreed standards.

2.12.8.4 Prior to the ship launching, the RS surveyor shall make sure that assembly, welding, straightening and testing for tightness, painting of the underwater hull, installation of bottom-and-side fittings and azimuth thrusters in the scope of pre-launching readiness are completed, and detected defects are rectified and checked.

2.12.8.5 The RS surveyor examines the underwater hull to make sure that damages and deformations, openings, protruding temporary parts, etc., which may cause the hull damages or flooding, are lacking.

The presence of single temporary parts of the launching cradle being removed afloat may be allowed.

2.12.8.6 Drawing-up of the check results of the ship launching readiness, as well as conditions of remaining classification in case of deficiencies/requirements for the underwater hull shall be performed by the RS surveyor in the form of a Check List of the Ship Launching Readiness (form 221-08) (Check List example is given in Appendix 3 to this Section).

2.12.8.6.1 The RS surveyor shall require the submission for survey of the underwater hull in a dock if a ship was launched when the Register requirements were available for the proper condition of items of the RS technical supervision prior to the ship launching, has damages of the underwater hull during launching or a leakage is found, serious reasons are identified or available for potential inadmissible defects at the underwater hull after outfitting and trials or due to other reasons.

In substantiated cases, on agreement with the RS Branch Office, examination of the underwater hull in a dock may be replaced by the survey without docking using the contemporary technical means.

2.12.9 Surveys after launching (items 3, 4, 5, 6, 8.1, 8.2, 8.5).

2.12.9.1 In the hull outfit afloat, the installation of single structures of the hull, superstructures, deck-houses, etc., unless these are mounted on the building berth, the joining of hull parts after their separate launching, as well as the performance of other works with hull structures are subject to technical supervision.

2.12.9.2 The joining of hull parts afloat shall be carried out according to the RS-agreed procedure.

2.12.9.2.1 In inspections during the hull joining afloat, the RS surveyor shall make sure that:

.1 hull parts are thoroughly aligned in the centerplane;
.2 in welding of the erection joint, the position of one part related to another is monitored;
.3 welding is performed as approved and in accordance with the RS-approved process, its quality is checked by the shipyard's technical control body after each run.

2.12.9.2.2 Survey of field joints.

2.12.9.2.2.1 When afloat, field joints are submitted to the RS surveyor after completion of assembly and welding.
Depending on the joining procedure, production conditions and results of periodical inspections, the RS surveyor may require to submit other operations and works or documents on their workmanship.

2.12.9.2.2 The assembly of the joint fully prepared for welding, assembly for welding of associated parts and units in way of the field joint are checked by an external examination.

2.12.9.2.3 The measurements are made to check the adjustment of parts by check lines and also in way of field joints.

2.12.9.2.4 Non-destructive testing and tightness testing of connection joints are effected according to the RS-approved diagrams.

2.12.9.3 Surveys during laying of solid ballast.

2.12.9.3.1 The material, quantity and locations for laying solid ballast are checked for compliance with the RS-approved design. The ballast shall be laid in its standard locations only after hull tightness tests.

2.12.9.3.1.1 The ballast shall be made as metal or concrete bars (slabs) apiece or as a concrete (concrete-metal) homogeneous mixture. Use of unspecified metallic waste, crushed (quarry) stone, etc. as ballast is not allowed.

2.12.9.3.1.2 The metallic filler used for ferroconcrete mixtures shall consist of equally shaped and sized elements (e.g. metallic shot) facilitating their uniform distribution in the concrete mixture.

2.12.9.3.2 Prior to laying, the ballast shall be weighed: apiece, by batches for each place of laying or in a measuring tank for the liquid concrete mixture. Hull structures in way of ballast placement shall be thoroughly cleaned, and for the piece-ballast also painted.

The piece-ballast shall be secured so as to prevent its shifting in service. The ballast surface in way of its placement shall be protected against the penetration of moisture to the plating and framing under the ballast. The concrete mixture shall be compacted and completely fill the entire volume provided.

2.12.9.3.3 In surveying the laid ballast, the RS surveyor verifies the scheme of its laying, the scheme approval, the document of the shipyard's technical control body on ballast laying and weighing according to laying places and/or on the quantity of concrete mixture laid according to the scheme, as well as, in external examination, verifies the compliance of the laying place with the scheme, the quantity, level and workmanship of the concrete mixture surface (absence of cracks, separations from metal, cavities and irregularities) and of waterproofing for the places of piece-ballast laying. The liquid concrete mixture shall be placed considering its mass change due to a drying loss.

2.12.9.3.4 At patrol the RS surveyor checks the cleaning and/or painting of places for ballast laying, its weighing (check weighing shall be witnessed by the surveyor, an error therewith shall be within ±1 %) and the quality of placement (uniformity, compaction of the concrete mixture, securing of the piece-ballast) and waterproofing.

The RS surveyor shall make sure that the data on quantity and laying places of solid ballast are given in the ship records and Stability Booklet.

2.12.10 Load line surveys (item 8.5).

2.12.10.1 The correct marking of the load line on ship's sides according to the RS-approved drawings developed in line with the freeboard calculation as per the Load Line Rules for Sea-Going Ships \(^1\) or International Convention on Load Lines, 1966 (LL-66), as amended is checked.

2.12.10.2 When confirming the load line marking according to the RS-approved design, the RS surveyor shall check the fulfilment of the structural requirements of the approved design and the Register rules with regard to the following:

.1 doors in end bulkheads of enclosed superstructures and in trunks of machinery spaces;

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\(^1\) Hereinafter referred to as "the Load Line Rules".
Guidelines on Technical Supervision of Ships under Construction (Section 2)

.2 cargo and other hatches, hatches of machinery space trunks, hatches of boiler spaces, smoke funnels, manholes, scuttles, ventilation and air pipes located on open decks;
.3 scuppers, sea outlets and inlets of pipelines with their valves, gate valves and drives;
.4 freeing ports;
.5 bulwark, guard rails and life lines;
.6 gangways or underdeck passages;
.7 special structural requirements in assignment of the timber freeboard.

The above conditions for assigning the load line shall be indicated by the RS surveyor in the Record of Conditions of Assignment of Load Lines (form 6.7.3).

2.12.10.3 Where the design specifies doubled load lines for the ship, the RS surveyor checks their correct marking on ship’s sides according to the RS-approved drawings.

2.12.10.4 Checking the load line, the RS surveyor shall take into account the results of the ship's inclining/ weighing test. In so doing, if the stability verification results in the change of the previously-approved freeboard value, the issue of a load line position is reviewed by the RS Branch Office.

2.12.10.5 Load line parts may be of superimposed type, punched or indicated by the other way agreed with the Register. Superimposed parts shall be welded all around or tightly attached with rivets. The cutting-out of a parts contour with a chisel is not allowed. The lines shall be plainly visible and provide an opportunity to control the freeboard value within ±2 mm. A tolerance for the accuracy of parts fitting is ±1 mm. The load line parts are painted white or yellow on a dark background or black on a light background.

2.12.10.6 Refer also to the applicable section of STORM Checklist (form 6.1.01).

2.12.11 Watertight cable transit seal systems (item 8.6).

2.12.11.1 During kick-off meeting with the shipyard, it shall be agreed on which stages of hull construction the completed items shall be submitted and indicate the agreed method of submission (as part of sections/blocks or during structure final verification after completion of all welding and heating works (if provided) or individual submission as per the List) in the column "RS proposals".

2.12.11.2 Watertightness of the cable transit installation through the hull structure shall be tested in scope as per item 5 of Table 2.5.1 considering 2.12.6.

2.12.11.3 Watertightness of the cable transit seal shall be tested in accordance with Appendix 2 to Section 10 in scope specified in 10.3.3 with regard to recommendations in 10.4 of Appendix 1 to Section 10.

2.12.11.4 The cable transit seal systems installed in "A" or "B" class watertight bulkheads/decks shall be accompanied by the documents confirming approval by the classification society (Type Approval Certificate (CTO), Type Approval Certificate for Fire-Proof Division (CTTK)) and compliance of systems with the requirements of the Rules for the Classification and Construction as well as IMO instruments on fire safety and integrity of protected structure (SOLAS-74 Regulation II-2/9.3.1, Part 3 of the International Code for Application of fire test procedures, 2010 (FTP Code)). Herewith, the certificate shall confirm the item tightness testing within the scope of the fire tests conducted.

The surveyor carrying out survey of completed cable transit seal system installation in the "A" or "B" class bulkheads/decks shall make sure in the availability of the relevant accompanying documents.
2.13 SURVEY OF HULLS OF REINFORCED CONCRETE SHIPS

2.13.1 General.
2.13.1.1 The provisions of this Chapter apply in technical supervision during construction of sea-going reinforced concrete ships, floating docks and other floating facilities according to the requirements of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete.
2.13.1.2 The matters of technical supervision ignored in this Chapter shall be handled following Section 2 (with regard to 2.3.6).
2.13.1.3 Description of the basic methods for manufacturing reinforced concrete hulls and superstructures, requirements for the building berth condition, general requirements for manufacture and installation of structures, requirements for concrete and elimination of concreting defects, etc. are given in Section 4, Part I "General Requirements for Construction" of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete.
2.13.1.4 Numerical criteria for hull structures during manufacture and elimination of defects given in this Chapter are provided for reference. Prior to commencement of construction, other quality criteria given in the recognized national or international standards may be agreed with the RS Branch Office.

2.13.2 Definitions and explanations.
2.13.2.1 Definitions and explanations related to the general terminology are given in Section 1, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision. Specific terms and definitions are given in 1.2, Part I "General Requirements for Construction" of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete.

2.13.3 Register technical supervision.
2.13.3.1 Prior to the technical supervision, the RS surveyor shall make sure that the shipyard is prepared for manufacturing ship’s reinforced concrete structures:
- proper storage, record and use of building materials, notably cement, are assured;
- at any stage of construction, the shipyard shall additionally confirm the quality of material and its conformity with the RS-approved design and requirements of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete;
- laboratory can perform all the necessary tests;
- production equipment ensures the manufacture of high-quality concrete having steady parameters;
- stands, platforms, steam-curing chambers, building berths, depots provide the proper quality, the observance of production requirements and storage conditions;
- quality of reinforcing fabrics for cages is assured.
2.13.3.2 Technical supervision is performed by the RS surveyor by performing surveys according to the List based on Table 2.13.3.2 and agreed with the RS Branch Office.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Technical supervision item</th>
<th>Verification of technical documentation</th>
<th>Inspection of material</th>
<th>External examination</th>
<th>Control of dimensions</th>
<th>Tightness test</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.1</td>
<td>reinforcing fabrics and cages</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>1.2</td>
<td>embedded parts (a splicing joint, system boxes, sockets, etc.)</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>1.3</td>
<td>sections (reinforcing, concrete placement, thermal treatment, concrete curing)</td>
<td>+/−</td>
<td>+</td>
<td>−</td>
<td>+</td>
<td>−</td>
</tr>
<tr>
<td>2</td>
<td>Preparation of the building berth</td>
<td>+</td>
<td>−</td>
<td>+</td>
<td>+</td>
<td>−</td>
</tr>
<tr>
<td>3</td>
<td>Mounting of reinforced concrete sections on the building berth</td>
<td>+</td>
<td>−</td>
<td>+</td>
<td>+</td>
<td>−</td>
</tr>
<tr>
<td>4</td>
<td>Reinforcing, butt welding, installation of connecting rods</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>–</td>
</tr>
</tbody>
</table>
2.13.4 Surveys by List.

2.13.4.1 Survey of sections.

The survey of sections prior to their mounting on the building berth is carried out after removal of forms or breaking of panels off matrices, and includes:

.1 verification of documentation according to 1.5 (additionally to be checked is a scheme of defect places for each section prepared by the shipyard’s technical control body);

.2 inspection of material wherein verified are the documents on the quality of original materials of sections, the data of the shipyard's technical control body or laboratory on the concrete tests performed (including those by the time of submission), as well as on other tests and analyses, and a certificate for the reinforcement and embedded parts metal;

.3 external examination wherein verified are the conformity of sections with drawings and technical documentation specified in these latter, the quality of the protective coat and surface, including the absence of defects, and also the condition of connecting rods (bending of deformed bars is not allowed).

The RS surveyor shall check surfaces by hammering. A dull sound evidences the presence of defects of which the nature is determined by stripping.

Defects mean cracks, nonconcrete parts, porosity, concrete segregation, reinforcement baring and protective coat reduction, laitance leak, etc. Cracks on concrete surface are not allowed.

Pores and cavities allowed on the surface of panels shall have the following dimensions: for internal elements (bulkheads, platforms, enclosures) — within 20 mm, up to 4 mm deep and not more than 5 mm in diameter, for the outer (bottom, sides, decks) — within 10 mm, up to 2 mm deep and not more than 5 mm in diameter, per 1 m²;

.4 measurements when drawing dimensions of a section and its main elements, as well as dimensions of the defects revealed with due regard to the tolerances, which shall not exceed those specified in Table 2.13.5.2.2 or other quality standards agreed with the RS Branch Office, are checked;

.5 if comments are lacking, the RS surveyor signs the document, which form is developed by the shipyard and agreed with the RS Branch Office.

If the List provides for the survey of the most typical sections and the technical supervision over the manufacture of the others is limited to patrol, the document of a section, which is not presented to the RS surveyor, is signed by the shipyard's technical control body only.
The sections produced in cooperation for supplying another shipyard shall be presented to the surveyor signing the document.

2.13.4.2 Surveys at building birth.

2.13.4.2.1 With the cast-in-place hull construction on the building berth, the technical supervision shall be effected as in sections survey.

If the hull is constructed on the building berth from sections, the survey includes the following steps:
- availability for concreting;
- concreting completion;
- forms removal and defects rectification.

2.13.4.2.2 In survey the availability for concreting: the documents for section manufacturing, the documents of the shipyard's technical control body on checking the positions of mounted sections and the log book of functional inspections are verified; external examination wherein the correct position of a section, the quality of mounting reinforcement and embedded parts of interpanel joints and grouting areas considering the tolerances according to Table 2.13.5.2.2 (in so doing, the reinforcement in way of joining, if bared above the old concrete for more than half its diameter or slackened, shall be fully cleared of concrete with a minimum gap of 5 mm), the quality of concrete surface preparation, measurements after forms construction, cleanliness of joint places and the tight fit of forms to the structure to prevent the leak of laitance, is carried out. The gap between forms and the structure shall not exceed 2 mm.

2.13.4.2.3 Following concreting and forms removal, external examination and measurements similarly to 2.13.4.1 are carried out. The forms removal shall be performed with the permission of the shipyard's technical control body after the concrete reaches at least 50% of the grade strength. The availability of drain holes and scuppers in framing for water and air flow is checked. Defects are noted and the quality in their rectification is checked.

2.13.4.3 Joining of hull parts afloat.

2.13.4.3.1 It is allowed to join hull parts afloat from separately-built floating blocks, provided that the applied structures and process of joining the blocks in a single whole ensure strength and watertightness of the grouted hull in accordance with a design.

In supervision of joining (mating), the relevant provisions of this Chapter shall be followed. In addition, the RS surveyor shall draw attention to the following:

- accuracy in alignment of single units with due regard for coordinates throughout the height and lengthwise, for the location of bulkheads and single connecting rods affecting the parts alignment, as well as the quality in joining single hull parts;
- ballasting calculations of single hull areas shall be made or overloads in way of mating prevented;
- in joining afloat, steady positions of mated parts during welding of reinforcement and concreting of butts, as well as during the time while the butts concrete gains the required strength shall be assured. The water area shall be protected against waves effect. The shipyard shall monitor the condition of ballast, heel and trim of single parts and the hull as a whole, the mutual position of parts, etc.;
- other factors which can effect joining.

2.13.4.4 Inspection of defects rectification and elimination.

2.13.4.4.1 Cavities of a depth equal to the protective coat thickness and over, reinforcement barings, pores, irregularities and roughness exceeding tolerances, voids, places of foreign inclusions (with rust inclusive) and concrete segregations of depth over the protective coat thickness, nonconcreted areas with the protective coat reduced by more than 2 mm, elements and parts having deviations above the permissible shall be rectified by reconcreting.

2.13.4.4.2 The elimination of concreting defects shall be carried out by mechanical removal of all the lowstrength concrete (the reinforcement is rectified if needed) followed by closing the defect place with the same quality concrete that is used for concreting interpanel
joints. Defects like cracks or small holes (blisters) shall be prepared along their edges for a width sufficient for proper filling with concrete through the entire depth.

2.13.4.4.3 Rectifying defect places by reconcreting, the increased thickness, roughness and sags of concrete within – 2 to + 25 mm in ballast tanks, and within – 2 to + 8 mm on other surfaces (an outer perimeter, dry compartments, tunnels) may be ignored.

2.13.4.4.4 To eliminate small defects, epoxy plastic concrete and also cement colloidal adhesives according to the RS-approved instruction may be used.

2.13.4.4.5 The rectification of defect places usually shall be performed prior to the mounting of a section on the building berth according to the procedure approved by the RS Branch Office.

2.13.4.4.6 The locations of the major defects or of those in the critical parts of the hull shall be given in the ship's final documentation.

2.13.5 Patrol.

2.13.5.1 At patrol, the RS surveyor selectively checks the fulfilment of the following requirements:

.1 all the components of concrete mixture and reinforcement received at the shipyard are subject to the incoming inspection in the scope stipulated by the standards agreed with the RS Branch Office. In so doing, the amount of clay and dust-like particles in sand shall not exceed 1% and in broken stone, 0.5% in mass; reinforcement shall be cleaned of rust and scale, grease stains, dirt, paint, cement film, etc. ;

.2 the mix design of new concrete compositions shall be carried out by a competent organization with the following presentation of the results on all the types of tests (for strength, watertightness, frost resistance, etc.) to the Register for verification and approval;

.3 in preparation of concrete mixture and placing it in structures, the requirements of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete and the RS-approved standards shall be followed. In so doing:

.3.1 the concrete prepared for grouting shall comply with the composition approved by RS for a given structure;

.3.2 permissible deviations from the dosage set for cement and water are ± 1%, for aggregates ± 2%;

.3.3 placing of concrete in a structure shall be completed within not more than 60 min since the time of mixing with water; the total time since concrete preparation till its placing shall not exceed the time when the concrete starts to lose its mobility;

.3.4 addition of water to concrete mixture is forbidden;

.3.5 breaks in concrete placing in one structure shall not exceed 1 h at an ambient air temperature above +25 °C, in other cases, 2 h. With more prolonged breaks, concrete placement shall be stopped and may be resumed after concrete hardening; to remove the cement film therewith, the indentation shall be surfaced by one of the RS-approved ways;

.3.6 prior to the final set, horizontal surfaces shall be wiped off by the RS-approved way and covered with sackcloth, tarpaulin, etc. for protection from sun rays, draughts and precipitation;

.3.7 after the final set until the attainment of grade strength, all concrete surfaces (including panels and concrete structures closed with wooden forms) shall be poured with water suitable for concrete preparation; the watering is conducted three times at an air temperature above +25 °C and at least two times per shift at the other temperature;

.3.8 loading, turning-over and transportation of panels, their testing for tightness, movement on the building berth, etc., as well as concrete freezing until it attains the strength specified in 2.13.5.2.4 are forbidden;

.3.9 samples are taken from every batch of at least 9 m³ in volume. By a batch is meant a concrete mixture of the same composition and identical by a production process which is used for the manufacture of one section or butts and monolithic elements per one shift, but not more than 50 m³. The cubes shall be stored under the same conditions as the concrete of a structure;
.3.10 a slump is measured with a slump cone at places of concrete preparation and placement at least once per shift for each composition of concrete;
.3.11 to prevent segregation, only one-fold manual relaying of concrete is allowed;
.3.12 free drop of heavyweight concretes (2.5 t/m³) from a height of over 2 m and over 1.5 m for the lightweight ones is not allowed;
.3.13 permissible deviations of the protective coat shall be within 1 — 3 mm;
.3.14 installation of holders of the protective coat shall prevent the penetration of water to the reinforcement;
.4 the following methods of concrete inspection shall be used at the shipyard:
  .4.1 check of the grade strength by testing standard cubes of concrete at 28 days; in questionable cases, the Register may demand strength tests of cubes chipped out from the hull structure;
  .4.2 with hidden reinforcement, the protective coat thickness is checked with reinforcement boring or the ultrasonic method; the protective coat at panel ends may be measured with a scale rule;
.5 the assembly and welding of reinforcing fabrics, cages and connecting rods shall be in compliance with the requirements of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete and standards. In this case:
  .5.1 no pores in welding are allowed;
  .5.2 in beading, 2 — 3 pores not exceeding 0.5 mm in diameter per the weld length, as well as undercuts not more than 0.5 mm deep per 30 % of the weld length are allowed;
  .5.3 in overlapping welding of the reinforcement, the weld discontinuity is allowed in way of transverse bars passage retaining the total length of a weld;
  .5.4 any welding-on to connecting rods within 50 mm off the concrete surface is not allowed;
  .5.5 in spliced fabrics, two outer rows of reinforcement overlaps along the fabric perimeter shall be stiffened.
2.13.5.2 At patrol the RS surveyor keeps under control:
  .1 concrete:
  regular checking of physical and mechanical properties of cement for conformity with the requirements of a standard and cement certificate;
  concrete plant operation;
  particular emphasis is placed on the accuracy of components dosage;
  manufacture and storage of concrete samples;
  concrete components (absence of foreign inclusions, dirt, clay, dust, chips, etc.). If shortcomings are revealed, the shipyard shall check concrete components in samples taken in the presence of the RS surveyor;
  correspondence of cement grades for butt joints and sections;
  .2 reinforcement:
  conformity with design documentation;
  conformity of reinforcing fabrics, cages, connecting rods, embedded parts and other metallic elements with the requirements of the RS-approved drawings (including bar diameters and spacing, their welding and anchoring, mounting, reinforcement cleaning of rust, dirt, oil, concrete, coordinates of connecting rods and embedded parts);
  observance of tolerances for manufacturing fabrics, cages and connecting rods (refer to Table 2.13.5.2.2);
  .3 concreting process:
  condition of molds for manufacturing sections, their tight closing, lubrication, boundary forms, etc. The forms shall be sufficiently strong and tight to prevent the laitance leak from concrete;
  proper mounting and attachment of embedded parts and outfitting components;
  mounting and attachment of holders of the protective coat which assure its set value;
  the holders shall be consistent with the grade of concrete in use;
conformity of the composition of the concrete prepared with the RS-approved one, its homogeneity and mobility; concrete transportation and placement;

4. thermal treatment:

observance of a treatment cycle;

inspection of concrete strength after the cycle completion. Sections may be broken away from molds when the concrete strength reaches the value, which is not less than the one assumed in the strength calculation of sections and other prefabricated elements of the hull during construction according to 2.1.9, Part I "General Requirements for Construction" of the Rules for the Construction of Hulls of Sea-Going Ships and Floating Facilities with Use of Reinforced Concrete, but at least 20 MPa in axial compression. If the concrete has not gained the strength required, the section shall be additionally treated or cured under natural conditions at a positive temperature until gaining the required strength;

Table 2.13.5.2.2

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Normable quantity</th>
<th>Tolerance, in mm</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Overall dimensions of finished fabrics:</td>
<td>±25</td>
</tr>
<tr>
<td></td>
<td>without face strips</td>
<td>±10</td>
</tr>
<tr>
<td></td>
<td>with face strips</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Difference of lengths of finished fabric diagonals</td>
<td>±10</td>
</tr>
<tr>
<td>3</td>
<td>Displacement of bars from a straight line in the fabric plane</td>
<td>±5</td>
</tr>
<tr>
<td>4</td>
<td>Dimensions of single meshes</td>
<td>±5</td>
</tr>
<tr>
<td>5</td>
<td>Dimensions of finished cages and connecting rods:</td>
<td>±25</td>
</tr>
<tr>
<td></td>
<td>lengthwise</td>
<td>±3</td>
</tr>
<tr>
<td></td>
<td>across a width and through a thickness</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Spacing of longitudinal bars of the cage</td>
<td>±5</td>
</tr>
<tr>
<td>7</td>
<td>Clamps spacing</td>
<td>±10</td>
</tr>
<tr>
<td>8</td>
<td>Nonperpendicularity of cage clamps to principal reinforcement</td>
<td>5°</td>
</tr>
<tr>
<td>9</td>
<td>Spacing of fabrics in plates</td>
<td>±3</td>
</tr>
<tr>
<td>10</td>
<td>Deviation lengthwise of and across the section:</td>
<td></td>
</tr>
<tr>
<td></td>
<td>before scratching</td>
<td>±10; −15</td>
</tr>
<tr>
<td></td>
<td>after scratching</td>
<td>−100</td>
</tr>
<tr>
<td>11</td>
<td>Thickness and height of framing ribs</td>
<td>±5; −3</td>
</tr>
<tr>
<td>12</td>
<td>Nonperpendicularity of ribs to the plate</td>
<td>1 per height of 100 mm, but not more than 5</td>
</tr>
<tr>
<td>13</td>
<td>Ribs displacement from the marking-out line</td>
<td>±3</td>
</tr>
<tr>
<td>14</td>
<td>Plate thickness:</td>
<td></td>
</tr>
<tr>
<td></td>
<td>up to 100 mm</td>
<td>±3</td>
</tr>
<tr>
<td></td>
<td>over 100 mm</td>
<td>±4</td>
</tr>
<tr>
<td>15</td>
<td>Curvilinearity of the section plane</td>
<td>0.001 panel length, but not more than 8</td>
</tr>
<tr>
<td>16</td>
<td>Local unevenness of the section surface in measurements with a meter rule:</td>
<td></td>
</tr>
<tr>
<td></td>
<td>for outer surfaces</td>
<td>±5</td>
</tr>
<tr>
<td></td>
<td>for others</td>
<td>±8</td>
</tr>
<tr>
<td>17</td>
<td>Roughness of the section surface</td>
<td>±2</td>
</tr>
<tr>
<td>18</td>
<td>Deflection of embedded part axes from the marking-out line in plan if the relevant instructions in a drawing are lacking</td>
<td>±5</td>
</tr>
<tr>
<td>19</td>
<td>Deflection of embedded parts from the set position relative to the verticals</td>
<td>±2 mm per 100 mm of the part height</td>
</tr>
<tr>
<td>20</td>
<td>Displacement of face strip axes from the marking-out line</td>
<td>±3</td>
</tr>
<tr>
<td>21</td>
<td>Deviation of the height of the embedded part position from the theoretical surface of the section</td>
<td>±3</td>
</tr>
<tr>
<td>22</td>
<td>Deflections construction of sections of horizontal structures:</td>
<td>±10</td>
</tr>
<tr>
<td></td>
<td>from the theoretical plane (displacement, misalignment)</td>
<td>±10</td>
</tr>
<tr>
<td></td>
<td>lengthwise and across a width, respectively, from transverse and longitudinal check lines on the building berth</td>
<td>±10</td>
</tr>
<tr>
<td>23</td>
<td>Deflections in erection of sections of ship's sides and outer walls of superstructures:</td>
<td>±10</td>
</tr>
<tr>
<td></td>
<td>of the outer surface of the panel from the theoretical line of the ship's</td>
<td>±10</td>
</tr>
<tr>
<td></td>
<td>overall dimension lengthwise and through the height, respectively, from horizontal and vertical check lines on the building berth</td>
<td>±10</td>
</tr>
<tr>
<td></td>
<td>trim per the panel length</td>
<td>±10</td>
</tr>
<tr>
<td>24</td>
<td>Deflections in construction of sections of transverse and longitudinal bulkheads:</td>
<td>±15</td>
</tr>
<tr>
<td></td>
<td>of the bottom edge lengthwise of the ship for transverse bulkheads and across the ship's breadth for longitudinal bulkheads from theoretical</td>
<td>±15</td>
</tr>
</tbody>
</table>
chambers and stands for thermal treatment shall ensure uniform heating, temperature control in various points and be tight. To reduce the works time on the building berth, the thermal treatment of concrete placed in joints and monolithic areas may be allowed subject to uniform heating, tight construction shelters, draught-free and other compulsory conditions; regulation and control of steam curing conditions, as a rule, shall be carried out with an automation system covering all the thermal treatment operations; checked are the results of automatic recording the process of steam curing, the maintenance and contents of a log or other document of the shipyard's technical control body or testing laboratory wherein the operation of thermal treatment shall be recorded;  

winter concreting:  
at an air temperature below 0 °C, the concrete mixture shall be conveyed to the place of concrete deposit being heated up to + 40 °C;  
temperature of cages shall be at least + 15 °C;  
immediately after concreting, the concrete shall be encased for warmth-keeping using construction shelters with steam supply or by another approved way until the concrete gains 70 % of the grade strength;  

the concreting area after being frozen is rejected;  
steam shall be wet and uniformly distributed over all the surfaces of the structure concreted;  
steam jets shall not hit the freshly laid concrete;  
abundant concentrated fall-out of drops on the concrete shall be prevented;  
concrete heating by other ways (electric heating, chargrills, etc.) shall be agreed with the RS Branch Office;
in winter, concreting is allowed with the additive of sodium nitrite in percentage of the cement mass:

<table>
<thead>
<tr>
<th>°C</th>
<th>−5...0</th>
<th>−10...−5</th>
<th>−15...−10</th>
</tr>
</thead>
<tbody>
<tr>
<td>%</td>
<td>3</td>
<td>5</td>
<td>7</td>
</tr>
</tbody>
</table>

.6 storage and transportation of sections:
after manufacturing, sections shall be stored at specially equipped warehouses and areas under conditions preventing their deformations and damages;
sections of ship's vertical structures (of bulkheads, sides, etc.) shall be stored vertically in cassettes or pyramids, all the others, stacked horizontally;
section stacks shall rest on wooden spacers placed on the levelled horizontal foundation. Every section shall be separated with spacers arranged in the vertical with their axes deviations within 10 mm. The spacers thickness shall be at least 25 mm and not less than a height of projecting parts. The spacers of one row shall be of the same material;
number of sections in a stack is established depending on the quality of spacers material, their strength and that of structures;
transportation shall be carried out with use of special traverses assuring uniform loading on every lifting eye of the section;
turning-over shall be performed in special tilters preventing damages to panels or their connecting rods;
.7 works on the building berth including:
preparation of the building berth for hull laying including the availability of the shipyard's report containing the levelling data;
sequence of sections installation;
reinforcing and welding of reinforcement;
in single cases, it is allowed to clear the reinforcement lengthwise to ensure its fair displacement or to use intermediate bars;
preparation of sections or the indentation for concreting, scratching, removal of concrete in way of the reinforcement, of the cement skin along edges, washing. Working of edges of concrete elements being joined to remove the cement skin shall be performed across the entire area of contact with the grouting concrete for all the elements of the structure bearing design forces;
verification of used materials correspondence with the method of reinforcement and metallic elements welding;
installation of forms (their strength, tightness, surface quality). Gaps between form section boards shall not be more than 1 mm. The leak of cement grout is not allowed;
preparation for concreting, at a negative ambient air temperature inclusive;
.8 for concreting of interpanel joints and monolithic parts of the hull, the concrete used shall have the same main characteristics as the one for section manufacture. In so doing, it shall be taken into account that the maximum size of an aggregate grain in the concrete mixture is not to exceed 10 mm and the mobility of the latter for horizontal butts shall be with a slump not more than 8 cm, for vertical butts, not more than 15 cm. The necessary and sufficient strength of concrete of butt joints before dismantling their shuttering is specified by the designer by calculation on the basis of the ship's (floating dock's) construction process in use, and in any case it shall not be less than:
10 MPa for vertical butts;
15 MPa for horizontal butts.

2.13.6 Tightness tests.
2.13.6.1 Tightness tests for reinforced concrete hulls is carried out after the elimination of defects, revealed by external examination, and the completion of mounting embedded parts and welded-on outfitting components.
Standards and types of tests are given in Table 2.13.6.1. Tightness tests are conducted according to the procedure approved by the Register wherein may be initially specified the performance of preliminary and then final tests. To ensure the hull launch, tightness tests may be performed by taking water up to the launching waterline in ship's spaces or in the pit. In the latter case, provision shall be made to prevent a premature hull shift; or rise. Prior to taking water, the interior of spaces up to the launching waterline shall be submitted for surveying. Final tests may be performed afloat as the spaces are available and submitted to the RS surveyor.

Floating docks are additionally tested for tightness by submersion up to the maximum draught. In submersion, watertightness of dry compartments, passage tunnels, the safely deck above ballast compartments, the unit of the reinforced concrete pontoon joint with metallic wing walls (composite docks) is tested.

Defect places revealed in tests shall be rectified according to the procedure approved by the RS Branch Office.

2.13.7 Readiness for launching.

2.13.7.1 In inspection of the availability for launching, the RS surveyor checks the elimination of defects identified in tests and surveys. The permit for ship's launching or floating out is executed with the shipyard's document signed by the RS surveyor.

### Table 2.13.6.1 Standards of tightness tests of reinforced concrete ships and floating facilities

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Spaces</th>
<th>Type of test</th>
<th>Hull parts to be examined</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Forepeak and afterpeak used as ballast compartments</td>
<td>By filling with water to the top of an air pipe, but at least 1 m above the bulkhead deck</td>
<td>Shell plating, watertight bulkheads, deck, chain locker, sealing glands</td>
</tr>
<tr>
<td>2</td>
<td>Forepeak and afterpeak not intended for filling with water</td>
<td>By filling with water to a head of 0.3 m above the deck and hose testing above that level</td>
<td>Ditto</td>
</tr>
<tr>
<td>3</td>
<td>Double-bottom compartments</td>
<td>By filling with water to the top of an air pipe</td>
<td>Shell plating, inner bottom, watertight floors and stringers</td>
</tr>
<tr>
<td>4</td>
<td>Dry cargo compartments, engine room, air compartments of double-bottomed ships</td>
<td>By filling with water up to the launching draught and hose testing above that level</td>
<td>Shell plating, watertight bulkheads, deck, hatch covers and coamings</td>
</tr>
<tr>
<td>5</td>
<td>Ditto for ships with no double bottom</td>
<td>By filling with water up to the launching draught and hose testing above that level</td>
<td>Ditto</td>
</tr>
<tr>
<td>6</td>
<td>Compartments and tanks being filled with water and oil products, as well as ballast compartments (excepting docks)</td>
<td>By filling with water to a head up to the top of an air pipe, but at least 2.5m above the deck or plating bounding the compartment from above</td>
<td>Shell plating, deck (platform, plating), watertight bulkheads, hatch covers and coamings</td>
</tr>
<tr>
<td>7</td>
<td>Ballast compartments of docks</td>
<td>Prior to launching: by filling the docking basin with water up to the level of the launching draught and hose testing above that level.</td>
<td>Shell plating</td>
</tr>
<tr>
<td></td>
<td></td>
<td>After launching: by taking water in turns up to the maximum possible head, considering the strength, but at least 1 m above the pontoon deck (refer to Note 12)</td>
<td>Shell plating, watertight bulkheads, deck, covers</td>
</tr>
<tr>
<td>8</td>
<td>Dry compartments of docks, passage tunnel</td>
<td>By filling with water up to the launching draught and hose testing above that level (refer to Note 12)</td>
<td>Shell plating, watertight bulkheads, covers and coamings</td>
</tr>
<tr>
<td>9</td>
<td>Compartment in tweendecks</td>
<td>Hose testing over the entire surface (refer to Note 12)</td>
<td>Ditto</td>
</tr>
<tr>
<td>10</td>
<td>Chain locker</td>
<td>By filling with water to a head of 1 m above the bulkhead deck</td>
<td>Locker contour</td>
</tr>
<tr>
<td>11</td>
<td>Superstructures, deckhouses including companions and open parts of trunks of the engine room and similar spaces</td>
<td>Hose testing for all outer surfaces</td>
<td>Sides, decks, outer walls</td>
</tr>
<tr>
<td>12</td>
<td>Coamings of hatches and vent pipes located in open parts of decks</td>
<td>Ditto</td>
<td>Outer walls</td>
</tr>
<tr>
<td>13</td>
<td>Closing appliances for openings in tight parts of the hull (doors in hold and tween-deck bulkheads, covers of skylights and companion hatches, upper deck scuttles and side scuttles of the main hull, scuttles</td>
<td>Hose testing</td>
<td>Doors, covers, scuttles</td>
</tr>
</tbody>
</table>
### Guidelines on Technical Supervision of Ships under Construction (Section 2)

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Spaces</th>
<th>Type of test</th>
<th>Hull parts to be examined</th>
</tr>
</thead>
<tbody>
<tr>
<td>14</td>
<td>Cofferdams</td>
<td>By filling with water to a head of 1 m above the bounding deck, but at least up to the bulkhead deck (refer to Note 12)</td>
<td>Entire contour</td>
</tr>
<tr>
<td>15</td>
<td>Watertight trunks</td>
<td>By filling with water up to the bulkhead deck; hose testing if the trunks are located above the bulkhead deck</td>
<td>Ditto</td>
</tr>
<tr>
<td>16</td>
<td>Joint of dock’s reinforced concrete pontoon</td>
<td>Hose testing (refer to Note 12)</td>
<td>Entire joint perimeter</td>
</tr>
</tbody>
</table>

**Notes:**
1. The level of watertightness shall be assessed by the following indications:
   - wetting = darkening of the surface without forming single drops;
   - watering = appearance of single fixed drops;
   - drip leakage = movement of single drops without forming a continuous jet;
   - jet leakage = continuous flow of water with no single drops visible.
2. Contours, compartments and structures being adjacent to seawater in service are considered watertight if wetting occurs. Watering is admissible on external sides of ballast compartments and on watertight bulkheads.
3. Fuel oil tanks are considered tight if no wetting is visible at a head of 1 m above the tank crown. Wetting is admissible at a head up to the top of an air pipe.
4. Water tanks are considered watertight if no drops appear at a head of 1 m above the tank crown, and no drop runs, at a head up to the top of an air pipe.
5. The watertightness test may be performed at the above-zero ambient air temperature only.
6. By the hose testing shall be understood the watering with a hose having the nozzle diameter of at least 12 mm and the minimum pressure of at least 200 kPa. A distance from the nozzle to the surface under test shall not exceed 1.5 m and shall be reduced to 1 m in special cases (presence of pores on the surface, etc.). The test duration is at least 10 min per each 10 m² of the surface under test. Vertical surfaces shall be be watered from the bottom upwards.
7. Cable boxes and sealing glands are subject to the tightness test by the compressed air jet.
8. The level of structure watertightness shall be determined by the time of defect occurrence since the test beginning: 20 min and over – for the hose testing, 3 h and over since the time of filling (submersion) completion – for the filling of compartments with water and in testing the compartments for a dock submersion.
9. Test standards for hull structures missing in this Table shall be set by agreement with the Register considering the operational conditions and purpose.
10. When justified, the spaces not bordering on the outer contour may be tested afloat.
11. With the precast construction of reinforced concrete hulls, if approved by the Register, the hose testing of all surfaces may be replaced by that of grouting joints only.
12. The tests of compartments and structures as per items 7, 8 and 16 are preliminary. The final watertightness tests are carried out in dock submersion for a limiting draught.
13. In questionable cases, the Register reserves the right to demand the performance of other types of tests at its discretion.
2.14 SURVEY OF MODU AND FOP HULLS

2.14.1 General.

2.14.1.1 Provisions of this Chapter supplement the requirements of Section 2, Part IV "Technical Supervision during Manufacture of Products" and Section 2 of the Guidelines regarding the procedure, methods and scope of the Register technical supervision during manufacture and installation of the MODU/FOP hull structures.

The procedure and methods of technical supervision during manufacture of the MODU/FOP hull structures shall meet the requirement of this Chapter.

2.14.1.2 The materials used for manufacture of the MODU/FOP hull structures and components shall meet the requirements in 1.5, Part II "Hull", Part XII "Materials" and Part XIII "Welding" of the Rules for the Classification, Construction and Equipment of Mobile Offshore Drilling Units and Fixed Offshore Platforms.

2.14.1.3 The definitions and explanations relating to general terminology are given in the General Regulations for the Classification and Other Activity, Part "Hull" of the Rules for Classification and Construction, in Parts I "Classification" and II "Hull" of the MODU/FOP Rules, as well as in Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision.

In this Part, the following definitions and explanations are applied.

The MODU/FOP hull means:

.1 hull envelope including all internal and external structures;
.2 superstructures, deckhouses and casings;
.3 welded foundations, e.g. main engine seatings;
.4 hatch coamings, bulwarks;
.5 all penetrations fitted and welded into bulkheads, decks and shell;
.6 the fittings of all connections to decks, bulkheads and shell, such as air pipes and ship side valves — all items covered by the International Convention on Load Lines, 1966, as amended;
.7 welded attachments to shell, decks and primary members, e.g. crane pedestals, bitts and bollards, but only as regards their interaction on the hull structure.

Section means a completed three- or two-dimensional part of the hull structure.

Section block means a completed three- or two-dimensional part of the hull structure consisting of several sections.

Block means a three-dimensional structure of a hull or superstructure fitted with machinery, special equipment, devices, systems, etc. as provided by design.

Module block means a standard modular unit, which dimensions and design specifications are similar to those of the block.

2.14.1.4 The procedure, methods and scope of the Register technical supervision are regulated depending on whether MODU/FOP are constructed of sections, blocks, block sections or module blocks and the hulls of self-elevating and semi-submersible MODU afloat are assembled of blocks or module blocks.

2.14.2 Surveys.

2.14.2.1 Checks, control and inspections performed in the course of technical supervision during manufacture of hull structures including the MODU/FOP specific hull structures are given in Table 2.5.1.

For MODUs, watertight cable transit seal systems shall be inspected in accordance with item 8.6 of Table 2.5.1.

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1 Hereinafter referred to as "the MODU/FOP Rules".
2.14.2.2 If the blocks and module blocks are manufactured and assembled at the same shipyard, technical supervision during hull construction shall be performed in full compliance with 2.14.2.2 and 2.14.2.3.

2.14.2.3 When carrying out survey of the MODU/FOP specific hull structures, the RS surveyor shall follow the requirements 2.14.5 with regard to the following:

.1 when verifying technical documents, a set of the RS-approved technical documentation on the item of technical supervision shall be verified by the RS surveyor in compliance with Part I "Classification" of the MODU/FOP Rules;

.2 the minimum scope of non-destructive testing of welds shall be specified in compliance with Section 3, Part XIII "Welding" of the MODU/FOP Rules at that the welded joints of primary and special structural members, which provide no access for inspection or may be difficult to be tested during the MODU/FOP operation, shall be subject to non-destructive testing in the full scope;

.3 items shall be tested for tightness according to 2.12.6 and Appendix 6 to this Section.

2.14.3 Documents.

2.14.3.1 When carrying out technical supervision of the MODU/FOP specific items, the RS surveyor shall follow the requirements in technical documentation in compliance with Part I "Classification" of the MODU/FOP Rules with regard to the applicable requirements in Part II "Technical Documentation" of the Rules for Technical Supervision.

2.14.4 Manufacture of hull structures.

2.14.4.1 Manufacture of single structural components and units, flat plate panels, framing girders, shell plates forming the MODU/FOP hull structures shall be subject to technical supervision.

2.14.4.2 When carrying out technical supervision during manufacture of the welded hull structures (units, sections, blocks), the requirements in 2.14.4.3, 2.14.4.4 and 2.14.4.8 shall be met. When checking the dimensions and geometric layout of the welded hull structures (units, sections, blocks), the requirements of Appendices 1 and 7 to this Section shall be met. When performing survey of the hull structures, divided by expansion gap, during the manufacture (installation) of the hull structures, the availability of minimum clearances shall be checked in excess of design shifting of adjacent structures.

2.14.4.3 Manufacture of units and sections.

2.14.4.3.1 Manufacture of flat plate panels, framing girders including deep frames, two- and three-dimensional sections and single units forming hull structures of the main hull, superstructures and deckhouses is subject to the Register technical supervision.

2.14.4.3.2 Where units and sections are manufactured as cooperation products, as well as when it is recognized as necessary to survey them prior to mounting of blocks or the hull at the berth, they shall be presented to the RS surveyor according to the List.

The necessity of such a survey is determined by the RS Branch Office with due regard to the details of a design and methods, quality of manufacture, a degree of section integration, etc.

2.14.4.3.3 In construction of series-built MODU/FOP hulls, the RS Branch Office may recognize sufficient to restrict itself to periodical examinations of completed sections and single units without their submitting to the surveyor for survey according to the List. The resolution concerning sufficiency of periodical examinations of completed sections and single units without submitting them as per the List shall be issued in writing, approved by the management of the RS Branch Office engaged in technical supervision during construction and shall contain a detailed technical justification of the resolution including references to the documents confirming positive experience of technical supervision during construction of sister MODU/FOP. In this case, their survey shall be performed at the following stages of hull construction, i.e. as part of section blocks, hull parts in pre-slipway positions or as part of the hull at the building berth.

2.14.4.3.4 Survey of sections under the List.

1 Block sections and modules manufactured in a sectional assembling and welding workshops may also be classified as sections.
2.14.4.3.4.1 The sections to be surveyed by the Register are presented as applicable for further assembling into blocks at pre-slipway sites or positions, or immediately at the berth. Where section enlargement or block sections mounting are performed at the workshop before they are transferred into the berth (pre-slipway position), the RS surveyor shall be submitted with these enlarged sections and block sections surveyed likewise the sections. Where the shipyard's workshops manufacture the MODU/FOP block sections, the surveyor is submitted with the block sections with hull outfitting installed, but without any other outfitting which may hamper surveying hull structures and eliminating the defects revealed. At the same time with the sections, the associated units and parts used in assembly are submitted.

If another procedure for submission is used, it shall be submitted with a proper substantiation by the shipyard to the RS Branch Office for approval.

2.14.4.3.5 Where single components of a hull structure, parts of hull outfitting, cutouts, etc. specified in drawings are ignored during construction of sections (blocks, modules) for the purpose of their unification, this shall be clearly indicated in production documentation agreed with the RS surveyor. It also indicates at which stage of the hull construction the required shall be performed.

The above fact shall be indicated in the document for the completed section or by another adopted way so that the shipyard's technical control body may present and the RS surveyor may check the fulfillment of incomplete works in due time.

2.14.4.3.6 The RS surveyor performs a check according to 2.5 of the Guidelines.

2.14.4.3.7 Patrols.

2.14.4.3.7.1 Assembly of units and sections.

2.14.4.3.7.1.1 The choice of a production process chart for assembling and welding of hull structures, as well as assembly jigs and welding equipment is within the competence of the shipyard, which shall account the relevant instructions of a designer. The sequence of assembling works performance shall be specified in production documentation.

Required accuracy of the assembly shall be provided, as well as measures shall be taken to keep to the minimum residual and welding deformations in a structure.

2.14.4.3.7.1.2 The shipyard shall apply, as far as possible and justified, for mechanized ways of assembling and welding. The applicable equipment, jigs and tooling in use shall provide the necessary accuracy and quality during the above operations.

2.14.4.3.7.1.3 Production processes for assembly and welding the units and hull structures on automated and semi-automated lines, for hull parts working as specified, etc. shall be approved by the Register. For this purpose, laboratory and production tests according to the programme approved by the Register shall be carried out at a given shipyard.

Implementing automated and semi-automated lines for assembly and welding of framing or sections at large, the following shall be ensured: high accuracy of accessories manufacture; consistency of forces produced by clamps with dimensions of parts to prevent inadequate pressing or excessive stresses; sufficient pressing time needed for welds cooling down to a temperature of not more than 500 °C and etc. In plasma arc cutting, one shall be convinced of the absence of raised saturation of a cut surface with gases (nitrogen, hydrogen) to prevent poor quality of welds. The proper quality of the cut surface along free edges shall be provided.

2.14.4.3.8 Welding of hull structures.

2.14.4.3.8.1 In hull welding, provisions of Part XIII "Welding" of the MODU/FOP Rules shall be followed.

The methods of hull welding shall be approved by the Register and implemented by the shipyard. The welding procedures used in a given shipyard shall be approved by the RS Branch Office. The RS surveyor shall make sure that welding is carried out in accordance with the production process approved by the Register. In so doing, one shall account limiting conditions, if these are specified in technical documentation on a welding method and in the production process, including those for material brands, thicknesses, welding positions, welding directions, an ambient air temperature, etc.
2.14.4.3.8.2 The welding of the units and sections shall be carried out after the acceptance of an assembly for welding by the shipyard's technical control body. The welding shall be performed according to the technical documentation for welding approved by the Register as applied to a specific structure. In single cases of outsized sections, the assembly and welding may be performed in parallel. In this case, the production process with division of the section into zones of works performance and with a sequence of assembly and welding operations specified shall be developed and approved by the RS Branch Office. In welding of units and sections, the joints resulting in the maximum shrinkage of a structure are welded first. When there are butt and tee joints in a structure, the tee ones are welded first. With manual welding in place of the semi-automatic one, leg lengths and weld throats shall be retained. With automatic welding in place of the manual and semiautomatic ones, single-pass welds of tee and fillet joints without through penetration may have design legs of at least 0.7 of the initial value. The replacement of the welding method shall be agreed with the RS surveyor.

2.14.4.3.9 Straightening of hull structures.

2.14.4.3.9.1 The straightening of hull structures shall be carried out if general and local deformations during manufacture exceed the permissible values specified by the requirements of technical documentation, and given in Appendix 1 to this Section.

The elimination of general and local deformations of hull structures by straightening is allowed if the deformation value does not exceed five tolerance values. With larger deformations, the procedure for structure rebuilding is established by the shipyard and designer by agreement with the Register.

2.14.4.3.9.2 Procedures for structure straightening are established by the shipyard and agreed with the RS Branch Office. The straightening shall be performed in compliance with the technical documentation approved by the Register.

The straightening shall be carried out prior to structure testing for tightness. Examining the structure condition after the test, the RS surveyor shall make sure that cracks, fractures, depressions, dents, craters and metal surface fusion are lacking.

On the RS surveyor's request, the check tests of mechanical properties of the material straightened, as well as non-destructive testing of welds and the base metal shall be carried out.

2.14.4.4 Survey of welded structures.

2.14.4.4.1 The RS surveyor shall check the following:

1. execution of rounding-off of cutout comers;
2. quality of the surface of free edges of sheer strake plates, continuous coamings of cargo hatches, shelf plates of stools, corrugated bulkheads, plate sections used as framing girders, cutouts (of cargo hatches, in particular), etc.;
3. execution of knee joints of framing girders (butt and overlap joints, presence of the flange or face plate of a knee, welding-on of girders to be joined or its absence, welding of girder ends to the shell or plating and a permissible gap therewith, web girder joints);
4. proper tapering of face plates and/or webs of framing girders at their ends, as well as of ends of knee face plates or flanges;
5. spacing of butts of knee and framing girder face plates from the knee ends; angle between knee and girder face plates;
6. structural design of joining lower ends of frames to bilge brackets or floors;
7. spacing between web and face plate butts at welded (of plate material) framing girders;
8. width of brackets and stiffeners where these are welded to girder face plates;
9. total height of cutouts reducing the girder cross section (web members inclusive) and their location along the length and throughout the height of the girder;
10. adequacy of spacings from edges of floor and web member cutouts to those for traversing of framing girders; location of cutouts on webs of girders;
11. shape of cutouts for traversing of framing girders, units of their anchoring at the points of traversing the permeable structures;
12. bevelling of the thicker plate to be butted;
.13 availability of holes in the tank framing (including double bottom tanks and oil tankers’ tanks) for the free inflow of air to air pipes and for the flow of a liquid;
.14 availability and the proper shape of cuts of knee corners, section webs and other permeable plate structures at the points of welds traversing;
.15 arrangement of access holes in the inner bottom plating, vertical keel, stringers and floors with due regard for their size, location, arrangement of bulkheads, pillars, etc., as well as for availability of access to all the hull structures;
.16 proper arrangement, number and dimensions of cutouts in decks, side and bottom plating, superstructures and deckhouses, rounding-off of corners and, if needed, cutouts stiffening;
.17 closing of temporary technological cutouts;
.18 availability of stiffeners and other parts which prevent “hard spots” in the shell and plating of structures, at edges of girder face plates and ends of knees at the points of girders (knees) traversing or termination, as well as at the points of superstructure and deckhouse shell joining with the plating of underlying decks.

Particular emphasis is placed upon areas of active vibration, as well as upon tight structures;
.19 continuity of longitudinals, alignment of members (including those separated with a plate);
.20 gradual changes of dimensions and cross sections of sections and plate thicknesses of longitudinals, including those separated with transverses, structural design of their termination, areas of changing the framing system or strength properties of steel;
.21 height and anchoring of carlings, the vertical keel and bottom stringers in areas of their termination;
.22 anchoring of longitudinals ends at the points of their termination at transverses (relates to girders of the bottom and inner bottom plating, sides and longitudinal bulkheads of tankers in areas of active vibration, as well as to underdeck girders of decks used for the carriage of containers, trailers, vehicles, or of decks bounding tanks);
.23 installation of seatings and reinforcements under equipment directly on framing girders or availability of reliable ties with these;
.24 gradual smooth reduction of a height of bulwarks, bilge keels, gutterway bars, etc. in way of their interruption or termination;
.25 attachment of bilge keels to the shell plating (intermediate members, the weakened weld, cutouts, end horizontal strips);
.26 execution of movable joints;
.27 arrangement of welds in areas of stress concentration (in ways of a drastic change in a members cross-section, of cutouts, etc.);
.28 absence of welds congestion, intercrossing at an acute angle, of nearby parallel welds;
.29 arrangement of butts of shell and plating plates relative to bulkheads and web members, parallel butts;
.30 welding all around knee edges and section webs;
.31 presence of welding from both sides at ends of framing girders;
.32 presence of welding from both sides and lull penetration welding with a smooth change from a weld to a part surface in areas of active vibration, as well as in oil- and lubricating oil-tight structures;
.33 presence of weldings on the weld underside in continuous welding from one side of tee-joints;
.34 weld reinforcements in ways of joining beams, deck longitudinals, bulkhead stiffeners and other girders with their supporting members (carlings, web beams, shelves, etc.);
.35 absence of a laminated fracture in ways where significant welding-effected stresses in a direction to a rolled products thickness may occur;
.36 other elements of welded structures; details of a hull structure, workmanship of assembly and welding, etc. therewith shall be taken into account.
2.14.4.5 During survey of welded hull structures, special attention shall be given to control of the joint edges alignment according to 2.7.1.11, Part XIII "Welding" of the MODU/FOP Rules.

2.14.4.6 Temporary parts shall be removed on the special structures. On the main structures the temporary pars shall be removed on the strength deck (plates and longitudinal framing), bottom (plates and longitudinal framing), sides, sheer strake and bilge strake (plates and longitudinal framing), bulkheads bounding tanks, web framing in tanks, structures in areas of active vibration.

Temporary parts may be removed at any stage of hull construction at the discretion of the shipyard. The existing concentrators (flay marks and other damages of the base metal, remains of weld metal and tacks, etc.) shall be welded up and dressed with a smooth transition to the base metal; in this case, thicknesses within the tolerances for butt weld reinforcements of the relevant structures are allowed. The areas of the temporary fastenings shall be checked by magnetic power inspection in the scope of 100 %. On other structures, temporary parts up to 10 mm high may be retained (not completely cut out) with the edge rounding-off, if agreed with the RS surveyor. Removal of the temporary fastenings shall be made only by arc-air gouging, gas or mechanical cutting.

2.14.4.7 When performing survey of hull structures (trunks for legs, tubular legs, leg tanks, stability columns, braces, cross ties, etc), which may be subject to significant stresses in the rolled products thickness direction during welding or operation, the plates shall be made of Z-steel and tested for laminated fracture.

When steel without Z-properties is used, the rolled products shall be tested prior to its use for plybond strength according to 3.1.4, Part XIII "Materials" of the Rules for the Classification and Construction, as well as based on the satisfactory results of the tests, after welding of hull structures in the area of the welded joints, the ultrasonic testing in the scope of 100 % shall be performed to determine possible laminated fracture.

2.14.4.8 The RS surveyor shall survey the MODU/FOP sections and blocks according to 2.14.4.8.1 — 2.14.4.8.4. When the hull is assembled of section blocks supplied as cooperation products at the builder’s, these section blocks shall be subject to survey at the manufacturer based on the List of Items of the Register Technical Supervision agreed with the RS Branch Office.

2.14.4.8.1 Manufacture of blocks at pre-slipway sites or a berth including mobile trolleys is subject to technical supervision.

To the sites of blocks manufacture, sections and single units shall be conveyed fully completed, accepted by the shipyard’s technical control body and, if specified by the List, surveyed by the Register.

The sequence of structures assembly and welding in blocks is determined by the designer and shipyard.

2.14.4.8.2 When carrying out of the blocks technical supervision, the main attention shall be given to the assembly and welding in ways of interpanel joints following therewith the instructions in 2.14.4.3.4 and 2.14.4.3.7 as far as these are applicable to blocks assembly.

2.14.4.8.3 The blocks to be surveyed according to the List are presented complete and fit for the hull construction at the berth. The MODU/FOP blocks with the considerable amount of piping, equipment, etc. may be submitted for survey given the proper access to all the hull structures to be surveyed. With the parallel performance of the hull and assembly works, as an exception, the blocks may be presented at two steps; the possibility and scope of each step shall be agreed with the RS surveyor and specified in the List.

Survey of sections as part of blocks shall be performed according to 2.14.4.3.4. The sections surveyed during manufacture shall be provided with the Register documents.

2.14.4.8.4 In periodical inspections the RS surveyor shall make sure that:

1. quality of sections being part of blocks provides continuity of hull members; butting of hull longitudinalss providing longitudinal strength shall be thoroughly examined;
.2 associated parts and units ensure quality assembly in intersectional joints;
.3 sections and associated units and parts have adequate allowances; cutouts for proper performance of butt and tee welds in way of joints are available;
.4 welding of joints over the shell plating is first carried out on the inside and, following the root removal, on the outside of the hull; another procedure or special welding processes shall be approved by the Register;
.5 measures to reduce local welding deformations of the shell and plating (angular distortions) are taken.

2.14.5 Hull construction.
2.14.5.1 Technical supervision during construction of hull or its single parts (sections, section blocks, blocks) at the building berth, during testing of compartments and spaces for tightness, check for availability of the hull or its parts for launching and surveys during hull outfitting afloat shall be performed according to the applicable requirements in 2.5 — 2.12 with regard to the requirements in 2.14.2 — 2.14.4 and the following:
.1 process documentation for construction of FOP, submersible or semi-submersible MODU with the hull construction afloat shall include stress analysis for the primary structural members depending on the MODU heel, trim, draught and, where necessary, ballast;
.2 at the hull construction afloat, the MODU heel, trim and draught shall be monitored as appropriate in the course of hull assembly;
.3 in the hull outfit afloat, to prevent hazardous stresses, the MODU heel, trim and draught shall be monitored and compared to the design values according to 2.14.5.1.1. The items shall be submitted for survey by the RS surveyor based on the List of Items of Technical Supervision during Construction of MODU.
2.14.5.2 In addition to 2.12.9.3, when filling the hull structure volumes with concrete, the maximum permissible pouring height shall be taken into account based on provision of strength of enclosing structures (during hull design without regard to the loads due to concrete mixture pouring), for example, when filling the volumes of inner skin, cofferdams and similar vertical volumes.

2.14.6 Welding during installation of the MODU topside.
2.14.6.1 The MODU topside are characterized by large size and weight. During the topside construction they are distorted by welding, during the transfer to a transportation and mounting frame, rolling up on the transportation barge and during transfer of topside to the MODU. Thus, as a rule, in some supporting MODU assemblies the welding gaps are formed exceeding the allowable standards. Large gaps may be eliminated by inserting a plate with Z-steel properties, during the installation of tubular tower on the tubular structure of the supporting base. The insert shall be welded from both sides by a tee-weld with full penetration. For tubular supporting assembly to be welded on the supporting base plane, the deposition of gaps by welding is allowed. Therewith, the deposition and dressing of the weld on the supporting base are performed to provide the standard gap up to 4 mm with farther check of the deposition by ultrasonic and magnetic particle inspections. Therewith, the heating temperature shall be monitored. To ensure root welding, the electrodes of small size shall be used. In the points of large gaps the final non-destructive examination shall be carried out not earlier than in 48 h after the welding completion. Because the topside welding is performed in the marine environment, the place of welding shall be secured from wind, rain and draft. As the deposition of large gaps differs from the standard welding procedure, for the topside installation the procedure for welding of large gaps and repair of welds and especially cracks shall be approved by the Register.

2.14.7 Inclining test.
2.14.7.1 Inclining test of MODU shall be performed according to Appendix 4 to this Section.
2.14.7.2 If the MODU hull outfit and tests shall be performed not at the shipbuilder’s and/or the water depth is not sufficient for inclining test at the design draught, to check the MODU
stability during passage, the inclining test in transit position shall be performed. The inclining test shall be performed and the report shall be prepared in compliance with Appendix 4 to this Section. Information on MODU stability being the guidance for providing the MODU stability during the passage shall be prepared based on inclining test results for MODU in transit position, and then agreed with the Register.

2.14.7.3 Inclining tests for drilling ships shall be performed according to Appendix 4 to this Section.

2.14.8 Load Line.
2.14.8.1 The MODU load line shall be surveyed by the RS surveyor according to 2.12.10.
IACS RECOMMENDATION NO.47

No. 47

Shipbuilding and Repair Quality Standard

Part A Shipbuilding and Remedial Quality Standard for New Construction

Part B Repair Quality Standard for Existing Ships

PART A
SHIPBUILDING AND REMEDIAL QUALITY STANDARDS FOR NEW CONSTRUCTION

1. Scope

2. General requirements for new construction

3. Qualification of personnel and procedures
   3.1 Qualification of welders
   3.2 Qualification of welding procedures
   3.3 Qualification of NDT operators

4. Materials
   4.1 Materials for structural members
   4.2 Surface conditions

5. Gas Cutting

6. Fabrication and fairness
   6.1 Flanged longitudinals and flanged brackets
   6.2 Built-up sections
   6.3 Corrugated bulkheads
   6.4 Pillars, brackets and stiffeners
   6.5 Maximum heating temperature on surface for line heating
   6.6 Block assembly
   6.7 Special sub-assembly
   6.8 Shape
   6.9 Fairness of plating between frames
   6.10 Fairness of plating with frames
   6.11 Preheating for welding hull steels at low temperature

7. Alignment

8. Welding Joint Details
   8.1 Typical butt weld plate edge preparation (manual welding and semi-automatic welding)
   8.2 Typical fillet weld plate edge preparation (manual welding and semi-automatic welding)
   8.3 Butt and fillet weld profile (manual welding and semi-automatic welding)
   8.4 Typical butt weld edge preparation (Automatic welding)
   8.5 Distance between welds

9. Remedial
   9.1 Typical misalignment remedial
   9.2 Typical butt weld plate edge preparation remedial (manual welding and semi-automatic welding)
   9.3 Typical fillet weld plate edge preparation remedial (manual welding and semi-automatic welding)
   9.4 Typical fillet and butt weld profile remedial (manual welding and semi-automatic welding)
   9.5 Distance between welds remedial
   9.6 Erroneous hole remedial
   9.7 Remedial by insert plate
   9.8 Weld surface remedial
   9.9 Weld remedial (short bead)
REFERENCES

A1. IACS Recommendation No. 76 "Bulk Carriers - Guidelines for Surveys, Assessment and Repair of Hull Structure"
A2. TSCF "Guidelines for the inspection and maintenance of double hull tanker structures"
A3. TSCF "Guidance manual for the inspection and condition assessment of tanker structures"
A4. IACS UR W7 "Hull and machinery steel forgings"
A5. IACS UR W8 "Hull and machinery steel castings"
A6. IACS UR W11 "Normal and higher strength hull structural steels"
A7. IACS UR W13 "Thickness tolerances of steel plates and wide flats"
A8. IACS UR W14 "Steel plates and wide flats with specified minimum through thickness properties ("Z" quality)"
A9. IACS UR W17 "Approval of consumables for welding normal and higher strength hull structural steels"
A10. IACS UR W28 "Welding procedure qualification tests of steels for hull construction and marine structures"
A12. IACS UR Z23 "Hull survey for new construction"
A13. IACS UR W33 "Non-destructive testing of ship hull steel welds"
A14. IACS Recommendation No. 96 "Double Hull Oil Tankers — Guidelines for Surveys, Assessment and Repair of Hull Structures"
A15. IACS Recommendation No. 55 "General Dry Cargo Ships — Guidelines for Surveys, Assessment and Repair of Hull Structures"
A16. IACS Recommendation No. 84 "Container Ships — Guidelines for Surveys, Assessment and Repair of Hull Structures"
A17. IACS UR W31 "YP 47 Steels and Brittle Crack Arrest Steels"
A18. IACS UR W32 "Qualification scheme for welders of hull structural steels"
A19. IACS UR W34 "Advanced non-destructive testing of materials and welds"
A20. IACS UR W35 "Requirements for NDT Suppliers"
A21. IACS UR S33 "Requirements for Use of Extremely Thick Steel Plates in Container Ships".

STANDARDS

EN 10163-1:2004 "Delivery requirements for surface condition of hot-rolled steel plates, wide flats and sections – Part 1: General requirements".
1. **Scope**

It is intended that these standards provide guidance where established and recognized shipbuilding or national standards accepted by the Classification Society do not exist.

1.1 This standard provides guidance on shipbuilding quality standards for the hull structure during new construction and the remedial standard where the quality standard is not met.

Whereas the standard generally applies to

- conventional merchant ship types,
- parts of hull covered by the rules of the Classification Society,
- hull structures constructed from normal and higher strength hull structural steel,

the applicability of the standard is in each case to be agreed upon by the Classification Society.

The standard does generally not apply to the new construction of

- special types of ships as e.g. gas tankers
- structures fabricated from stainless steel or other, special types or grades of steel

1.2 In this standard, both a "Standard" range and a "Limit" range are listed. The "Standard" range represents the target range expected to be met in regular work under normal circumstances. The "Limit" range represents the maximum allowable deviation from the "Standard" range. Work beyond the "Standard" range but within the "Limit" range is acceptable. In cases where no 'limit' value is specified, the value beyond the 'standard' range may be accepted subject to the consideration of the Classification Society.

1.3 The standard covers typical construction methods and gives guidance on quality standards for the most important aspects of such construction. Unless explicitly stated elsewhere in the standard, the level of workmanship reflected herein will in principle be acceptable for primary and secondary structure of conventional designs. A more stringent standard may however be required for critical and highly stressed areas of the hull, and this is to be agreed with the Classification Society in each case. In assessing the criticality of hull structure and structural components, reference is made to ref. A1, A2, A3, A11, A13, A14, A15, A16, A19 and A21.

1.4 Details relevant to structures or fabrication procedures not covered by this standard are to be approved by the Classification Society on the basis of procedure qualifications and/or recognized national standards.

1.5 For use of this standard, fabrication fit-ups, deflections and similar quality attributes are intended to be uniformly distributed about the nominal values. The shipyard is to take corrective action to improve work processes that produce measurements where a skew distribution is evident. Relying upon remedial steps that truncate a skewed distribution of the quality attribute is unacceptable.

2. **General requirements for new construction**

2.1 In general, the work is to be carried out in accordance with the Classification Society rules and under the supervision of the Surveyor to the Classification Society.
2.2 Welding operations are to be carried out in accordance with work instructions accepted by the Classification Society.

2.3 Welding of hull structures is to be carried out by qualified welders, according to approved and qualified welding procedures and with welding consumables approved by the Classification Society, see Section 3. Welding operations are to be carried out under proper supervision by the shipbuilder. The working conditions for welding are to be monitored by the Classification Society in accordance with UR Z23 (ref. A12).

3. Qualification of personnel and procedures

3.1 Qualification of welders

3.1.1 Welders are to be qualified in accordance with IACS UR W32 (ref. A18) or other recognized standard accepted by the Classification Society. Recognition of other standards is subject to submission to the Classification Society for evaluation. Subcontractors are to keep records of welders qualification and, when required, furnish valid approval test certificates.

3.1.2 Welding operators using fully mechanized or fully automatic processes need generally not pass approval testing provided that the production welds made by the operators are of the required quality. However, operators are to receive adequate training in setting or programming and operating the equipment. Records of training and operation experience shall be maintained on individual operator’s files and records, and be made available to the Classification Society for inspection when requested.

3.2 Qualification of welding procedures

Welding procedures are to be qualified in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.

3.3 Qualification of NDT operators

Personnel performing NDT for the purpose of assessing quality of welds in connection with new construction covered by this standard, are to be qualified in accordance with Classification Society rules or to a recognized international or national qualification scheme. Records of operators and their current certificates are to be kept and made available to the Surveyor for inspection.

In case, of non-destructive examination carried out by an independent firm from the shipbuilder, such firm shall comply with IACS UR W35 (ref. A20).

4. Materials

4.1 Materials for Structural Members

All materials, including weld consumables, to be used for the structural members are to be approved by the Classification Society as per the approved construction drawings and meet the respective IACS Unified Requirements (see ref. A4, A5, A6, A7, A8, A9 and A17). Additional recommendations are contained in the following paragraphs.
All materials used should be manufactured at a works approved by the Classification Society for the type and grade supplied.

4.2 Surface Conditions

4.2.1 Definitions

<table>
<thead>
<tr>
<th>Minor Imperfections</th>
<th>Pitting, rolled-in scale, indentations, roll marks, scratches and grooves</th>
</tr>
</thead>
<tbody>
<tr>
<td>Defects</td>
<td>Cracks, shells, sand patches, sharp edged seams and minor imperfections exceeding the limits of Table 1</td>
</tr>
<tr>
<td>Depth of Imperfections or defects</td>
<td>The depth is to be measured from the surface of the product</td>
</tr>
</tbody>
</table>

4.2.2 Acceptance without remedies

Minor imperfections, in accordance with the nominal thickness ($t$) of the product and the limits described in Table 1, are permissible and may be left as they are.

<table>
<thead>
<tr>
<th>Imperfection surface area Ratio(%)</th>
<th>15～20%</th>
<th>5～15%</th>
<th>0～5%</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t &lt; 20$ mm</td>
<td>$0.2$ mm</td>
<td>$0.4$ mm</td>
<td>$0.5$ mm</td>
</tr>
<tr>
<td>$20$ mm $\leq t &lt; 50$ mm</td>
<td>$0.2$ mm</td>
<td>$0.6$ mm</td>
<td>$0.7$ mm</td>
</tr>
<tr>
<td>$50$ mm $\leq t$</td>
<td>$0.2$ mm</td>
<td>$0.7$ mm</td>
<td>$0.9$ mm</td>
</tr>
</tbody>
</table>

Table 1 Limits for depth of minor imperfection, for acceptance without remedies
Imperfection surface area Ratio (%) is obtained as influenced area / area under consideration (i.e. plate surface area) x 100%.

For isolated surface discontinuities, influenced area is obtained by drawing a continuous line which follows the circumference of the discontinuity at a distance of 20 mm. (Figure 1)

For surface discontinuities appearing in a cluster, influenced area is obtained by drawing a continuous line which follows the circumference of the cluster at a distance of 20 mm. (Figure 2)
4.2.3 Remedial of Defects

Defects are to be remedied by grinding and/or welding in accordance with IACS UR W11 \(^{(ref. A6)}\).

4.2.4 Further Defects

4.2.4.1 Lamination

Investigation to be carried out at the steelmill into the cause and extent of the detected laminations. Severe lamination is to be remedied by local insert plates. The minimum breadth or length of the plate to be replaced is to be:

- 1600 mm for shell and strength deck plating in way of cruciform or T-joints,
- 800 mm for shell, strength deck plating and other primary members,
- 300 mm for other structural members.

Local limited lamination may be remedied by chipping and/or grinding followed by welding in accordance with sketch (a). In case where the local limited lamination is near the plate surface, the remedial may be carried out as shown in sketch (b). For limitations see paragraph 4.2.2.

4.2.4.2 Weld Spatters

Loose weld spatters are to be removed by grinding or other measures to clean metal surface (see Table 9.13), as required by the paint system, on:

- shell plating
- deck plating on exposed decks
- in tanks for chemical cargoes
- in tanks for fresh water and for drinking water
- in tanks for lubricating oil, hydraulic oil, including service tanks

5. Gas Cutting

The roughness of the cut edges is to meet the following requirements:

<table>
<thead>
<tr>
<th>Free Edges:</th>
<th>Standard Limit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Strength Members</td>
<td>150 µm 300 µm</td>
</tr>
<tr>
<td>Others</td>
<td>500 µm 1000 µm</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Welding Edges:</th>
<th>Standard Limit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Strength Members</td>
<td>400 µm 800 µm</td>
</tr>
<tr>
<td>Others</td>
<td>800 µm 1500 µm</td>
</tr>
</tbody>
</table>
6. **Fabrication and fairness**

6.1 Flanged longitudinals and flanged brackets (see Table 6.1)
6.2 Built-up sections (see Table 6.2)
6.3 Corrugated bulkheads (see Table 6.3)
6.4 Pillars, brackets and stiffeners (see Table 6.4)
6.5 Maximum heating temperature on surface for line heating (see Table 6.5)
6.6 Block assembly (see Table 6.6)
6.7 Special sub-assembly (see Table 6.7)
6.8 Shape (see Table 6.8 and 6.9)
6.9 Fairness of plating between frames (see Table 6.10)
6.10 Fairness of plating with frames (see Table 6.11)
6.11 Preheating for welding hull steels at low temperature (see Table 6.12)

7. **Alignment**

The quality standards for alignment of hull structural components during new construction are shown in Tables 7.1, 7.2 and 7.3. The Classification Society may require a closer construction tolerance in areas requiring special attention, as follows:

- Regions exposed to high stress concentrations
- Fatigue prone areas
- Detail design block erection joints
- High tensile steel regions

8. **Welding Joint Details**

Edge preparation is to be qualified in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.

Some typical edge preparations are shown in Table 8.1, 8.2, 8.3, 8.4 and 8.6 for reference.

8.1 Typical butt weld plate edge preparation (manual and semi-automatic welding) for reference — see Table 8.1 and 8.2
8.2 Typical fillet weld plate edge preparation (manual and semi-automatic welding) for reference — see Table 8.3 and 8.4
8.3 Butt and fillet weld profile (manual and semi-automatic welding) — see Table 8.5
8.4 Typical butt weld plate edge preparation (Automatic welding) for reference — see Table 8.6
8.5 Distance between welds - see Table 8.7

9. **Remedial**

All the major remedial work is subject to reporting by shipbuilder to the Classification Society for approval in accordance with their work instruction for new building.

Some typical remedial works are shown in Tables 9.1 to 9.13.

9.1 Typical misalignment remedial — see Tables 9.1 to 9.3
9.2 Typical butt weld plate edge preparation remedial (manual and semi-automatic welding) — see Table 9.4 and 9.5
9.3 Typical fillet weld plate edge preparation remedial (manual and semi-automatic welding) — see Tables 9.6 to 9.8
9.4 Typical fillet and butt weld profile remedial (manual and semi-automatic welding) — see Table 9.9
No. 47 (cont)

9.5 Distance between welds remedial — see Table 9.10
9.6 Erroneous hole remedial — see Table 9.11
9.7 Remedial by insert plate — see Table 9.12
9.8 Weld surface remedial — see Table 9.13
9.9 Weld remedial (short bead) — see Table 9.14
**Guidelines on Technical Supervision of Ships under Construction (Section 2)**

**TABLE 6.1 – Flanged Longitudinals and Flanged Brackets**

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Breadth of flange compared to correct size</td>
<td>± 3 mm</td>
<td>± 5 mm</td>
<td></td>
</tr>
<tr>
<td>Angle between flange and web compared to template</td>
<td>± 3 mm</td>
<td>± 5 mm</td>
<td>per 100 mm of (a)</td>
</tr>
<tr>
<td>Straightness in plane of flange and web</td>
<td>± 10 mm</td>
<td>± 25 mm</td>
<td>per 10 m</td>
</tr>
</tbody>
</table>
### No. 47 (cont)

**TABLE 6.2 – Built Up Sections**

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frames and longitudinal</td>
<td>± 1,5 mm</td>
<td>± 3 mm</td>
<td>per 100 mm of a</td>
</tr>
<tr>
<td>Distortion of face plate</td>
<td>$d \leq 3 + a/100$ mm</td>
<td>$d \leq 5 + a/100$ mm</td>
<td></td>
</tr>
<tr>
<td>Distortion in plane of web and flange of built up longitudinal frame,</td>
<td>± 10 mm</td>
<td>± 25 mm</td>
<td>per 10 m in length</td>
</tr>
<tr>
<td>transverse frame, girder and transverse web.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 6.3 – Corrugated Bulkheads

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mechanical bending</td>
<td>$R \geq 3t \text{ mm}$</td>
<td>$2t \text{ mm}$</td>
<td>Material to be suitable for cold flanging (forming) and welding in way of radius</td>
</tr>
<tr>
<td>$R \geq 4,5t \text{ mm for CSR ships} \quad \text{Note 1}$</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Depth of corrugation</td>
<td>$\pm 3 \text{ mm}$</td>
<td>$\pm 6 \text{ mm}$</td>
<td></td>
</tr>
<tr>
<td>Breadth of corrugation</td>
<td>$\pm 3 \text{ mm}$</td>
<td>$\pm 6 \text{ mm}$</td>
<td></td>
</tr>
<tr>
<td>Pitch and depth of swedged corrugated bulkhead compared with correct value</td>
<td>$h : \pm 2.5 \text{ mm}$</td>
<td>$h : \pm 5 \text{ mm}$</td>
<td>Where it is not aligned with other bulkheads $P : \pm 9 \text{ mm}$</td>
</tr>
<tr>
<td></td>
<td>Where it is not aligned with other bulkheads $P : \pm 6 \text{ mm}$</td>
<td></td>
<td>Where it is aligned with other bulkheads $P : \pm 2 \text{ mm}$</td>
</tr>
<tr>
<td></td>
<td>Where it is aligned with other bulkheads $P : \pm 3 \text{ mm}$</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Notes:**
1. For CSR Bulk Carriers built under the "Common Structural Rules for Bulk Carriers" with the effective dates of 1 July 2010 and 1 July 2012, the standard is $R \geq 2t \text{ mm}$. 
2. For CSR ships, the allowable inside bending radius of cold formed plating may be reduced provided the following requirements are complied with.

When the inside bending radius is reduced below 4.5 times the as-built plate thickness, supporting data is to be provided. The bending radius is in no case to be less than 2 times the as-built plate thickness. As a minimum, the following additional requirements are to be complied with:

   a) For all bent plates:
      • 100% visual inspection of the bent area is to be carried out.
      • Random checks by magnetic particle testing are to be carried out.

   b) In addition to a), for corrugated bulkheads subject to lateral liquid pressure:
      • The steel is to be of Grade D/DH or higher.

The material is impact tested in the strain-aged condition and satisfies the requirements stated herein. The deformation is to be equal to the maximum deformation to be applied during production, calculated by the formula $t_{as-built} / (2r_{bdg} + t_{as-built})$, where $t_{as-built}$ is the as-built thickness of the plate material and $r_{bdg}$ is the bending radius. One sample is to be plastically strained at the calculated deformation or 5%, whichever is greater and then artificially aged at 250 °C for one hour then subject to Charpy V-notch testing. The average impact energy after strain ageing is to meet the impact requirements specified for the grade of steel used.
### TABLE 6.4 – Pillars, Brackets and Stiffeners

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pillar (between decks)</td>
<td></td>
<td>4 mm, 6 mm</td>
<td></td>
</tr>
<tr>
<td>Cylindrical structure diameter (pillars, masts, posts, etc.)</td>
<td>± (D/200) mm (\pm 5) mm max.</td>
<td>± (D/150) mm max. 7,5 mm</td>
<td></td>
</tr>
<tr>
<td>Tripping bracket and small stiffener, distortion at the part of free edge</td>
<td>(a \leq t/2) mm</td>
<td>(t)</td>
<td></td>
</tr>
<tr>
<td>Ovality of cylindrical structure</td>
<td>(d_{\text{max}} - d_{\text{min}} \leq 0,02 \times d_{\text{max}})</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 6.5 – Maximum Heating Temperature on Surface for Line Heating

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Conventional Process AH32-EH32 &amp; AH36-EH36</td>
<td>Water cooling just after heating</td>
<td>Under 650 °C</td>
<td></td>
</tr>
<tr>
<td>TMCP type AH36-EH36 ($C_{eq}$ &gt; 0.38%)</td>
<td>Air cooling after heating</td>
<td>Under 900 °C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Air cooling and subsequent water cooling after heating</td>
<td>Under 900 °C (starting temperature of water cooling to be under 500 °C)</td>
<td></td>
</tr>
<tr>
<td>TMCP type AH32-DH32 &amp; AH36-DH36 ($C_{eq}$ ≤ 0.38%)</td>
<td>Water cooling just after heating or air cooling</td>
<td>Under 1000 °C</td>
<td></td>
</tr>
<tr>
<td>TMCP type EH32 &amp; EH36 ($C_{eq}$ ≤ 0.38%)</td>
<td>Water cooling just after heating or air cooling</td>
<td>Under 900 °C</td>
<td></td>
</tr>
</tbody>
</table>

**NOTE:**

\[
C_{eq} = C + \frac{Mn}{6} + \frac{Cr + Mo + V}{5} + \frac{Ni + Cu}{15}\%
\]
### TABLE 6.6 – Block Assembly

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Flat Plate Assembly</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Length and Breadth</td>
<td>± 4 mm</td>
<td>± 6 mm</td>
<td></td>
</tr>
<tr>
<td>Distortion</td>
<td>± 10 mm</td>
<td>± 20 mm</td>
<td></td>
</tr>
<tr>
<td>Squareness</td>
<td>± 5 mm</td>
<td>± 10 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation of interior members from plate</td>
<td>5 mm</td>
<td>10 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Curved plate assembly</strong></td>
<td></td>
<td></td>
<td>measured along the girth</td>
</tr>
<tr>
<td>Length and Breadth</td>
<td>± 4 mm</td>
<td>± 8 mm</td>
<td></td>
</tr>
<tr>
<td>Distortion</td>
<td>± 10 mm</td>
<td>± 20 mm</td>
<td></td>
</tr>
<tr>
<td>Squareness</td>
<td>± 10 mm</td>
<td>± 15 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation of interior members from plate</td>
<td>5 mm</td>
<td>10 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Flat cubic assembly</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Length and Breadth</td>
<td>± 4 mm</td>
<td>± 6 mm</td>
<td></td>
</tr>
<tr>
<td>Distortion</td>
<td>± 10 mm</td>
<td>± 20 mm</td>
<td></td>
</tr>
<tr>
<td>Squareness</td>
<td>± 5 mm</td>
<td>± 10 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation of interior members from plate</td>
<td>5 mm</td>
<td>10 mm</td>
<td></td>
</tr>
<tr>
<td>Twist</td>
<td>± 10 mm</td>
<td>± 20 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation between upper and lower plate</td>
<td>± 5 mm</td>
<td>± 10 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Curved cubic assembly</strong></td>
<td></td>
<td></td>
<td>measured along with girth</td>
</tr>
<tr>
<td>Length and Breadth</td>
<td>± 4 mm</td>
<td>± 8 mm</td>
<td></td>
</tr>
<tr>
<td>Distortion</td>
<td>± 10 mm</td>
<td>± 15 mm</td>
<td></td>
</tr>
</tbody>
</table>
No. 47 (cont)

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Squareness</td>
<td>± 10 mm</td>
<td>± 10 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation of interior members from plate</td>
<td>± 5 mm</td>
<td>± 25 mm</td>
<td></td>
</tr>
<tr>
<td>Twist</td>
<td>± 15 mm</td>
<td>± 15 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation between upper and lower plate</td>
<td>± 7 mm</td>
<td>± 15 mm</td>
<td></td>
</tr>
</tbody>
</table>

**TABLE 6.7 – Special Sub-Assembly**

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Distance between upper/lower gudgeon</td>
<td>± 5 mm</td>
<td>± 10 mm</td>
<td></td>
</tr>
<tr>
<td>Distance between aft edge of boss and aft peak bulkhead</td>
<td>± 5 mm</td>
<td>± 10 mm</td>
<td></td>
</tr>
<tr>
<td>Twist of sub-assembly of stern frame</td>
<td>5 mm</td>
<td>10 mm</td>
<td></td>
</tr>
<tr>
<td>Deviation of rudder from shaft center line</td>
<td>4 mm</td>
<td>8 mm</td>
<td></td>
</tr>
<tr>
<td>Twist of rudder plate</td>
<td>6 mm</td>
<td>10 mm</td>
<td></td>
</tr>
<tr>
<td>Flatness of top plate of main engine bed</td>
<td>5 mm</td>
<td>10 mm</td>
<td></td>
</tr>
<tr>
<td>Breadth and length of top plate of main engine bed</td>
<td>± 4 mm</td>
<td>± 6 mm</td>
<td></td>
</tr>
</tbody>
</table>

**NOTE:**

Dimensions and tolerances have to fulfill engine and equipment manufacturers’ requirements, if any.
### TABLE 6.8 – Shape

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Deformation for the whole length</td>
<td></td>
<td>± 50 mm</td>
<td>per 100 m against the line of keel sighting</td>
</tr>
<tr>
<td>Deformation for the distance between two adjacent bulkheads</td>
<td></td>
<td>± 15 mm</td>
<td></td>
</tr>
<tr>
<td>Cocking-up of fore body</td>
<td></td>
<td>± 30 mm</td>
<td>The deviation is to be measured from the design line</td>
</tr>
<tr>
<td>Cocking-up of aft-body</td>
<td></td>
<td>± 20 mm</td>
<td></td>
</tr>
<tr>
<td>Rise of floor amidships</td>
<td></td>
<td>± 15 mm</td>
<td>The deviation is to be measured from the design line</td>
</tr>
<tr>
<td>Item</td>
<td>Standard</td>
<td>Limit</td>
<td>Remarks</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>-------------------------------</td>
<td>--------------------------------------</td>
<td>-------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Length between perpendiculars</td>
<td>±(L/1000) mm</td>
<td></td>
<td>Applied to ships of 100 metre length and above. For the convenience of the measurement the point where the keel is connected to the curve of the stem may be substituted for the fore perpendicular in the measurement of the length.</td>
</tr>
<tr>
<td>Moulded breadth at midship</td>
<td>±(B/1000) mm</td>
<td></td>
<td>Applied to ships of 15 metre breadth and above, measured on the upper deck.</td>
</tr>
<tr>
<td>Moulded depth at midship</td>
<td>±(D/1000) mm</td>
<td></td>
<td>Applied to ships of 10 metre depth and above, measured up to the upper deck.</td>
</tr>
</tbody>
</table>
## TABLE 6.10 – Fairness of Plating Between Frames

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Shell plate</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parallel part (side &amp; bottom shell)</td>
<td>4 mm</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fore and aft part</td>
<td>5 mm</td>
<td>8 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Tank top plate</strong></td>
<td></td>
<td>4 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Bulkhead</strong></td>
<td></td>
<td>6 mm</td>
<td></td>
</tr>
<tr>
<td>Longl. Bulkhead</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Trans. Bulkhead</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Swash Bulkhead</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Strength deck</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parallel part</td>
<td>4 mm</td>
<td>8 mm</td>
<td></td>
</tr>
<tr>
<td>Fore and aft part</td>
<td>6 mm</td>
<td>9 mm</td>
<td></td>
</tr>
<tr>
<td>Covered part</td>
<td>7 mm</td>
<td>9 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Second deck</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bare part</td>
<td>6 mm</td>
<td>8 mm</td>
<td></td>
</tr>
<tr>
<td>Covered part</td>
<td>7 mm</td>
<td>9 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Forecastle deck</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bare part</td>
<td>4 mm</td>
<td>8 mm</td>
<td></td>
</tr>
<tr>
<td>Covered part</td>
<td>6 mm</td>
<td>9 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Super structure deck</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bare part</td>
<td>4 mm</td>
<td>6 mm</td>
<td></td>
</tr>
<tr>
<td>Covered part</td>
<td>7 mm</td>
<td>9 mm</td>
<td></td>
</tr>
<tr>
<td><strong>House wall</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Outside wall</td>
<td>4 mm</td>
<td>6 mm</td>
<td></td>
</tr>
<tr>
<td>Inside wall</td>
<td>6 mm</td>
<td>8 mm</td>
<td></td>
</tr>
<tr>
<td>Covered part</td>
<td>7 mm</td>
<td>9 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Interior member (web of girder, etc)</strong></td>
<td>5 mm</td>
<td>7 mm</td>
<td></td>
</tr>
<tr>
<td><strong>Floor and girder in double bottom</strong></td>
<td>5 mm</td>
<td>8 mm</td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 6.11 – Fairness of Plating with Frames

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Shell plate</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parallel part</td>
<td>±2 (l/1000) mm</td>
<td>±3 (l/1000) mm</td>
<td></td>
</tr>
<tr>
<td>Fore and aft part</td>
<td>±3 (l/1000) mm</td>
<td>±4 (l/1000) mm</td>
<td>(l = ) span of frame (mm)</td>
</tr>
<tr>
<td>Strength deck</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>(excluding cross deck) and</td>
<td>±3 (l/1000) mm</td>
<td>±4 (l/1000) mm</td>
<td>To be measured between on trans.</td>
</tr>
<tr>
<td>top plate of double bottom</td>
<td></td>
<td></td>
<td>space (min. (l = 3000) mm)</td>
</tr>
<tr>
<td>Bulkhead</td>
<td></td>
<td>±5 (l/1000) mm</td>
<td></td>
</tr>
<tr>
<td>Accommodation above</td>
<td></td>
<td>±5 (l/1000) mm</td>
<td>±6 (l/1000) mm</td>
</tr>
<tr>
<td>the strength deck</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>and others</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

To be measured between one trans. space.

\(l = \) span of frame

(minimum \(l = 3000\) mm)
**TABLE 6.12 – Preheating for welding hull steels at low temperature**

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Base metal temperature needed preheating</td>
<td>Minimum preheating temperature</td>
<td></td>
</tr>
<tr>
<td>Normal strength steels</td>
<td>A, B, D, E</td>
<td>Below -5 °C</td>
<td></td>
</tr>
<tr>
<td>Higher strength steels</td>
<td></td>
<td>Below 0 °C</td>
<td>20 °C 1)</td>
</tr>
<tr>
<td>(TMCP type)</td>
<td>AH32 – EH32</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>AH36 – EH36</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Higher strength steels</td>
<td></td>
<td>Below 0 °C</td>
<td></td>
</tr>
<tr>
<td>(Conventional type)</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Note)

1) This level of preheat is to be applied unless the approved welding procedure specifies a higher level.
### Table 7.1 – Alignment

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Alignment of butt welds</strong>&lt;br&gt;<img src="image1" alt="Diagram" /></td>
<td>$a \leq 0.15t$&lt;br&gt;Strength member&lt;br&gt;$a \leq 0.2t$&lt;br&gt;Other but maximum 4.0 mm</td>
<td>$t$ is the lesser plate thickness</td>
<td></td>
</tr>
<tr>
<td><strong>Alignment of fillet welds</strong>&lt;br&gt;<img src="image2" alt="Diagram" /></td>
<td>Strength member and higher stress member:&lt;br&gt;$a \leq t_1/3$&lt;br&gt;Other:&lt;br&gt;$a \leq t_1/2$</td>
<td>Alternatively, heel line can be used to check the alignment.&lt;br&gt;Where $t_3$ is less than $t_1$, then $t_3$ should be substituted for $t_1$ in the standard.</td>
<td></td>
</tr>
<tr>
<td><strong>Alignment of fillet welds</strong>&lt;br&gt;<img src="image3" alt="Diagram" /></td>
<td>Strength member and higher stress member:&lt;br&gt;$a \leq t_1/3$&lt;br&gt;Other:&lt;br&gt;$a \leq t_1/2$</td>
<td>Alternatively, heel line can be used to check the alignment.&lt;br&gt;Where $t_3$ is less than $t_1$, then $t_3$ should be substitute for $t_1$ in the standard.</td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 7.2 – Alignment

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Alignment of flange of T-longitudinal</td>
<td>Strength member ( a \leq 0.04b ) (mm)</td>
<td>( a = 8.0 ) mm</td>
<td></td>
</tr>
<tr>
<td>Alignment of height of T-bar, L-angle bar or bulb</td>
<td>Strength member ( a \leq 0.15t )</td>
<td>( a = 3.0 ) mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Other ( a \leq 0.20t )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Alignment of panel stiffener</td>
<td>( d \leq L/50 )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Gap between bracket/intercostal and stiffener</td>
<td>( a \leq 2.0 ) mm</td>
<td>( a = 3.0 ) mm</td>
<td></td>
</tr>
<tr>
<td>Alignment of lap welds</td>
<td>( a \leq 2.0 ) mm</td>
<td>( a = 3.0 ) mm</td>
<td></td>
</tr>
<tr>
<td>No. 47 (cont)</td>
<td>TABLE 7.3 – Alignment</td>
<td></td>
<td></td>
</tr>
<tr>
<td>--------------</td>
<td>-----------------------</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Detail</strong></td>
<td><strong>Standard</strong></td>
<td><strong>Limit</strong></td>
<td><strong>Remarks</strong></td>
</tr>
<tr>
<td>Gap between beam and frame</td>
<td>$a \leq 2,0 , \text{mm}$</td>
<td>$a = 5,0 , \text{mm}$</td>
<td></td>
</tr>
<tr>
<td>Gap around stiffener cut-out</td>
<td>$s \leq 2,0 , \text{mm}$</td>
<td>$s = 3,0 , \text{mm}$</td>
<td></td>
</tr>
</tbody>
</table>
**TABLE 8.1 – Typical Butt Weld Plate Edge Preparation (Manual Welding and Semi-Automatic Welding) for Reference**

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Square butt $t \leq 5 \text{ mm}$</td>
<td>$G \leq 3 \text{ mm}$</td>
<td>$G = 5 \text{ mm}$</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Single bevel butt $t &gt; 5 \text{ mm}$</td>
<td>$G \leq 3 \text{ mm}$</td>
<td>$G = 5 \text{ mm}$</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Double bevel butt $t &gt; 19 \text{ mm}$</td>
<td>$G \leq 3 \text{ mm}$</td>
<td>$G = 5 \text{ mm}$</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Double vee butt, uniform bevels</td>
<td>$G \leq 3 \text{ mm}$</td>
<td>$G = 5 \text{ mm}$</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Double vee butt, non-uniform bevel</td>
<td>$G \leq 3 \text{ mm}$</td>
<td>$G = 5 \text{ mm}$</td>
<td>see Note 1</td>
</tr>
</tbody>
</table>
NOTE 1
Different plate edge preparation may be accepted or approved by the Classification Society in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.

For welding procedures other than manual welding, see paragraph 3.2 Qualification of weld procedures.

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single Vee butt, one side welding with backing strip (temporary or permanent)</td>
<td>$G = 3$ to $9$ mm</td>
<td>$G = 16$ mm</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Single vee butt</td>
<td>$G \leq 3$ mm</td>
<td>$G = 5$ mm</td>
<td>see Note 1</td>
</tr>
</tbody>
</table>

NOTE 1
Different plate edge preparation may be accepted or approved by the Classification Society in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.

For welding procedures other than manual welding, see paragraph 3.2 Qualification of welding procedures.
Table 8.3 – Typical Fillet Weld Plate Edge Preparation (Manual Welding and Semi-Automatic Welding) for Reference

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tee Fillet</td>
<td>( G \leq 2 \text{ mm} )</td>
<td>( G = 3 \text{ mm} )</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Inclined fillet</td>
<td>( G \leq 2 \text{ mm} )</td>
<td>( G = 3 \text{ mm} )</td>
<td>see Note 1</td>
</tr>
<tr>
<td>Single bevel tee with permanent backing</td>
<td>( G \leq 4 \text{ to } 6 \text{ mm} ) ( \theta^\circ = 30^\circ \text{ to } 45^\circ )</td>
<td>( G = 16 \text{ mm} )</td>
<td>Not normally for Strength member also see Note 1</td>
</tr>
<tr>
<td>Single bevel tee</td>
<td>( G \leq 3 \text{ mm} )</td>
<td></td>
<td>see Note 1</td>
</tr>
</tbody>
</table>

**NOTE 1**
Different plate edge preparation may be accepted or approved by the Classification Society in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.
For welding procedures other than manual welding, see paragraph 3.2 Qualification of welding procedures.
Table 8.4 – Typical Fillet Weld Plate Edge Preparation (Manual Welding and Semi-Automatic Welding) for Reference

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single ‘J’ bevel tee</td>
<td></td>
<td></td>
<td>$G = 2.5$ to $4 \text{ mm}$</td>
</tr>
<tr>
<td>Double bevel tee symmetrical $t &gt; 19 \text{ mm}$</td>
<td></td>
<td></td>
<td>$G \leq 3 \text{ mm}$</td>
</tr>
<tr>
<td>Double bevel tee asymmetrical $t &gt; 19 \text{ mm}$</td>
<td></td>
<td></td>
<td>$G \leq 3 \text{ mm}$</td>
</tr>
<tr>
<td>Double ‘J’ bevel tee symmetrical</td>
<td></td>
<td></td>
<td>$G = 2.5$ to $4 \text{ mm}$</td>
</tr>
</tbody>
</table>

**NOTE 1**
Different plate edge preparation may be accepted or approved by the Classification Society in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.
For welding procedures other than manual welding, see paragraph 3.2 Qualification of welding procedures.
Table 8.5 – Butt And Fillet Weld Profile (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
</table>
| Butt weld toe angle            | $\theta \leq 60^\circ$  
$h \leq 6$ mm          | $\theta \leq 90^\circ$ |                                                          |
| Butt weld undercut             | $D \leq 0,5$ mm   
for strength member      | $D \leq 0,8$ mm  
for other            |
| Fillet weld leg length         | $s \geq 0,9s_d$   
$a \geq 0,9a_d$         | $s_d = \text{design s}$
$a_d = \text{design a}$ |
| Fillet weld toe angle          | $\theta \leq 90^\circ$ |               | In areas of stress concentration and fatigue, the Classification Society may require a lesser angle. |
| Fillet weld undercut           | $D \leq 0,8$ mm   |                |}

$s = \text{leg length; } a = \text{throat thickness}$
Table 8.6 – Typical Butt Weld Plate Edge Preparation (Automatic welding) for Reference

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Submerged Arc Welding (SAW)</td>
<td></td>
<td>0 ≤ G ≤ 0,8 mm</td>
<td>G = 2 mm</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>See Note 1.</td>
</tr>
</tbody>
</table>

**NOTE 1**

Different plate edge preparation may be accepted or approved by the Classification Society in accordance with UR W28 (ref. A10) or other recognized standard accepted by the Classification Society.

For welding procedures other than manual welding, see paragraph 3.2 Qualification of welding procedures.
### Table 8.7 – Distance Between Welds

<table>
<thead>
<tr>
<th>Detail</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scallops over weld seams</td>
<td></td>
<td>for strength member ( d \geq 5\text{mm} ) \nfor other ( d \geq 0\text{mm} )</td>
<td>The “( d )” is to be measured from the toe of the fillet weld to the toe of the butt weld.</td>
</tr>
<tr>
<td>Distance between two butt welds</td>
<td>( d \geq 0\text{ mm} )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Distance between butt weld and fillet weld</td>
<td>for strength member ( d \geq 10\text{ mm} ) \nfor other ( d \geq 0\text{ mm} )</td>
<td>The “( d )” is to be measured from the toe of the fillet weld to the toe of the butt weld.</td>
<td></td>
</tr>
<tr>
<td>Distance between butt welds</td>
<td>for cut-outs ( d \geq 30\text{ mm} ) \nfor margin plates ( d \geq 300\text{ mm} )</td>
<td>150 mm</td>
<td></td>
</tr>
<tr>
<td>No.</td>
<td>47</td>
<td></td>
<td></td>
</tr>
<tr>
<td>-----</td>
<td>-----</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>(cont)</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Table 9.1 – Typical Misalignment Remedial</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>Detail</strong></td>
<td><strong>Remedial Standard</strong></td>
<td><strong>Remarks</strong></td>
</tr>
</tbody>
</table>
| | **Alignment of butt joints** | Strength member  
\[ a > 0.15t_1 \] or \( a > 4 \text{ mm} \)  
release and adjust  
Other  
\[ a > 0.2t_1 \] or \( a > 4 \text{ mm} \)  
release and adjust | \( t_1 \) is lesser plate thickness |
| | **Alignment of fillet welds** | Strength member and higher  
stress member  
\[ t_1/3 < a \leq t_1/2 \] — generally  
increase weld throat by 10%  
\[ a > t_1/2 \] — release and adjust  
over a minimum of 50\( a \)  
Other  
\[ a > t_1/2 \] — release and adjust  
over a minimum of 30\( a \) | Alternatively,  
heel line can be  
used to check the alignment.  
Where \( t_3 \) is  
less than \( t_1 \) then  
\( t_3 \) should be substituted for \( t_1 \) in standard |
| | **Alignment of flange of T-longitudinal** | When \( 0.04b < a \leq 0.08b \),  
max 8 mm:  
grind corners to smooth taper over  
a minimum distance \( L = 3a \)  
When \( a > 0.08b \) or 8 mm:  
release and adjust over a  
minimum distance \( L = 50a \) |  |
| | **Alignment of height of T-bar, L-angle bar or bulb** | When 3 mm < \( a \) < 6 mm:  
build up by welding  
When \( a > 6 \text{ mm} \):  
release and adjust over minimum  
\( L = 50a \) for strength member and  
\( L = 30a \) for other |  |
| | **Alignment of lap welds** | 3 mm < \( a \) ≤ 5 mm:  
weld leg length to be increased by  
the same amount as increase in  
gap in excess of 3 mm  
\[ a > 5 \text{ mm} \]:  
members to be re-aligned |  |
### Table 9.2 – Typical Misalignment Remedial

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial Standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Gap between bracket/intercostal and stiffener</td>
<td></td>
<td></td>
</tr>
<tr>
<td><img src="image1.png" alt="Diagram" /></td>
<td>When $3 \text{ mm} &lt; a \leq 5 \text{ mm}$: weld leg length to be increased by increase in gap in excess of 3 mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>When $5 \text{ mm} &lt; a \leq 10 \text{ mm}$: chamfer $30^\circ$ to $40^\circ$ and build up by welding with backing</td>
<td></td>
</tr>
<tr>
<td></td>
<td>When $a &gt; 10 \text{ mm}$: increase gap to about 50 mm and fit collar plate</td>
<td></td>
</tr>
<tr>
<td></td>
<td>[ b = (2t + 25) \text{ mm}, \text{ min. 50 mm} ]</td>
<td></td>
</tr>
<tr>
<td>Gap between beam and frame</td>
<td></td>
<td></td>
</tr>
<tr>
<td><img src="image2.png" alt="Diagram" /></td>
<td>$3 \text{ mm} &lt; a \leq 5 \text{ mm}$: weld leg length to be increased by the same amount as increase in gap in excess of 3 mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$a &gt; 5 \text{ mm}$ release and adjust</td>
<td></td>
</tr>
<tr>
<td>No. 47 (cont)</td>
<td><strong>TABLE 9.3 – Misalignment Remedial</strong></td>
<td></td>
</tr>
<tr>
<td>--------------</td>
<td>------------------------------------</td>
<td></td>
</tr>
<tr>
<td><strong>Detail</strong></td>
<td><strong>Remedial standard</strong></td>
<td><strong>Remarks</strong></td>
</tr>
<tr>
<td>Position of scallop</td>
<td>When $d &lt; 75$ mm web plate to be cut between scallop and slot, and collar plate to be fitted</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Or fit small collar over scallop</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Or fit collar plate over scallop</td>
<td></td>
</tr>
<tr>
<td>Gap around stiffener cut-out</td>
<td>When $3 \text{ mm} &lt; s \leq 5 \text{ mm}$ weld leg length to be increased by the same amount as increase in gap in excess of $2 \text{ mm}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>When $5 \text{ mm} &lt; s \leq 10 \text{ mm}$ nib to be chamfered and built up by welding</td>
<td></td>
</tr>
<tr>
<td></td>
<td>When $s &gt; 10 \text{ mm}$ cut off nib and fit collar plate of same height as nib</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$20 \text{ mm} \leq b \leq 50 \text{ mm}$</td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 9.4 – Typical Butt Weld Plate Edge Preparation Remedial (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Square butt</td>
<td>When $G \leq 10$ mm chamfer to 45° and build up by welding</td>
<td>When $G &gt; 10$ mm build up with backing strip; remove, back gouge and seal weld; or, insert plate, min. width 300 mm</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Single bevel butt</td>
<td>When $5$ mm $&lt; G \leq 1.5t$ (maximum 25 mm) build up gap with welding on one or both edges to maximum of $0.5t$, using backing strip, if necessary. Where a backing strip is used, the backing strip is to be removed, the weld back gouged, and a sealing weld made.</td>
<td></td>
</tr>
<tr>
<td>Double bevel butt</td>
<td>Different welding arrangement approved by using backing material approved by the Classification Society may be accepted on the basis of an appropriate welding procedure specification.</td>
<td></td>
</tr>
<tr>
<td>Double vee butt, uniform bevels</td>
<td></td>
<td>When $G &gt; 25$ mm or $1.5t$, whichever is smaller, use insert plate, of minimum width 300 mm</td>
</tr>
<tr>
<td>Double vee butt, non-uniform bevel</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 9.5 – Typical Butt Weld Plate Edge Preparation Remedial (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial Standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single vee butt, one side welding</td>
<td>When $5 \text{ mm} &lt; G \leq 1.5t \text{ mm}$ (maximum 25 mm), build up gap with welding on one or both edges, to &quot;Limit&quot; gap size preferably to &quot;Standard&quot; gap size as described in Table 8.2. Where a backing strip is used, the backing strip is to be removed, the weld back gouged, and a sealing weld made. Different welding arrangement by using backing material approved by the Classification Society may be accepted on the basis of an appropriate welding procedure specification.</td>
<td></td>
</tr>
<tr>
<td>Single vee butt</td>
<td>When $G &gt; 25 \text{ mm}$ or $1.5t$, whichever is smaller, use insert plate of minimum width 300 mm. Limits see Table 8.2</td>
<td></td>
</tr>
</tbody>
</table>

Limits see Table 8.2
###TABLE 9.6 – Typical Fillet Weld Plate Edge Preparation Remedial (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tee Fillet</td>
<td>3 mm &lt; G ≤ 5 mm – leg length increased to Rule leg + (G-2)</td>
<td>5 mm &lt; G ≤ 16 mm or G ≤ 1,5t — chamfer by 30° to 45°, build up with welding, on one side, with backing strip if necessary, grind and weld.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>G &gt; 16 mm or G &gt; 1,5t use insert plate of minimum width 300 mm</td>
</tr>
</tbody>
</table>
| Liner treatment |                                                                                    | t₂ ≤ t ≤ t₁  
G ≤ 2 mm  
\( a = 5 \text{ mm} + \text{fillet leg length} \) | Not to be used in cargo area or areas of tensile stress through the thickness of the liner |

- **G** is the gap between the edges of the plate.
- **t** is the plate thickness.
- **a** is the distance from the edge of the plate.
- **t₂** and **t₁** are the thicknesses of the plate and the liner, respectively.
- **b** is the distance between the plates.

In this table, **Tee Fillet** refers to a type of weld where the weld is applied at the intersection of two plates. **Liner treatment** is a method used to ensure uniform weld penetration in the thickness of the plate. The table provides guidelines for preparing and remedying welds to ensure structural integrity and compliance with construction standards.
### Table 9.7 – Typical Fillet Weld Plate Edge Preparation Remedial (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single bevel tee</td>
<td>3 mm &lt; ( G ) ≤ 5 mm build up weld</td>
<td>5 mm &lt; ( G ) ≤ 16 mm — build up with welding, with backing strip if necessary, remove backing strip if used, back gouge and back weld. ( G &gt; 16 ) mm new plate to be inserted of minimum width 300 mm</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( G &gt; 16 ) mm new plate to be inserted of minimum width 300 mm</td>
</tr>
</tbody>
</table>
TABLE 9.8 – Typical Fillet Weld Plate Edge Preparation Remedial (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single 'J' bevel tee</td>
<td>as single bevel tee</td>
<td></td>
</tr>
<tr>
<td>Double bevel tee symmetrical</td>
<td></td>
<td>When $5 \text{ mm} &lt; G \leq 16 \text{ mm}$ build up with welding using ceramic or other approved backing bar, remove, back gouge and back weld.</td>
</tr>
<tr>
<td>Double bevel tee asymmetrical</td>
<td></td>
<td>When $G &gt; 16 \text{ mm}$-insert plate of minimum height 300 mm to be fitted.</td>
</tr>
<tr>
<td>Double 'J' bevel symmetrical</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 9.9 – Typical Fillet and Butt Weld Profile Remedial (Manual Welding and Semi-Automatic Welding)

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fillet weld leg length</td>
<td>Increase leg or throat by welding over</td>
<td></td>
</tr>
<tr>
<td>Fillet weld toe angle</td>
<td>( \theta &gt; 90^\circ ) grinding, and welding, where necessary, to make ( \theta \leq 90^\circ )</td>
<td>Minimum short bead to be referred Table 9.14</td>
</tr>
<tr>
<td>Butt weld toe angle</td>
<td>( \theta &gt; 90^\circ ) grinding, and welding, where necessary, to make ( \theta \leq 90^\circ )</td>
<td></td>
</tr>
<tr>
<td>Butt weld undercut</td>
<td>For strength member, where ( 0.5 &lt; D \leq 1 ) mm, and for other, where ( 0.8 &lt; D \leq 1 ) mm, undercut to be ground smooth (localized only) or to be filled by welding. Where ( D &gt; 1 ) mm undercut to be filled by welding</td>
<td></td>
</tr>
<tr>
<td>Fillet weld undercut</td>
<td>Where ( 0.8 &lt; D \leq 1 ) mm undercut to be ground smooth (localized only) or to be filled by welding. Where ( D &gt; 1 ) mm undercut to be filled by welding</td>
<td></td>
</tr>
</tbody>
</table>
TABLE 9.10 – Distance Between Welds Remedial

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scallops over weld seams</td>
<td>Hole to be cut and ground smooth to obtain distance</td>
<td></td>
</tr>
</tbody>
</table>

No. 47 (cont)
**TABLE 9.11 – Erroneous Hole Remedial**

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Holes made erroneously $D &lt; 200$ mm</td>
<td>Strength member open hole to minimum $75$ mm dia., fit and weld spigot piece</td>
<td>Fillet weld to be made after butt weld</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The fitting of spigot pieces in areas of high stress concentration or fatigue is to be approved by the Classification Society.</td>
</tr>
</tbody>
</table>

- $\theta = 30 - 40^\circ$
- $G = 4 - 6$ mm
- $1/2t \leq t_1 \leq t$
- $l = 50$ mm

- $t_1 = t_2$
- $L = 50$ mm, min

| Holes made erroneously $D \geq 200$ mm | Strength member open hole and fit insert plate | |
| | Other open hole to over $300$ mm and fit insert plate | |
| | Or fit lap plate | |
| | $t_1 = t_2$
| | $L = 50$ mm, min | |
### TABLE 9.12 – Remedial by Insert Plate

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remedial by insert plate</td>
<td>$L = 300 \text{ mm minimum}$</td>
<td>(1) seam with insert piece is to be welded first</td>
</tr>
<tr>
<td></td>
<td>$B = 300 \text{ mm minimum}$</td>
<td>(2) original seam is to be released and welded over for a minimum of 100 mm.</td>
</tr>
<tr>
<td></td>
<td>$R = 5t \text{ mm}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>100mm minimum</td>
<td></td>
</tr>
<tr>
<td>Remedial of built section by insert plate</td>
<td>$L_{\text{min}} \geq 300 \text{ mm}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Welding sequence $(1) \rightarrow (2) \rightarrow (3) \rightarrow (4)$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Web butt weld scallop to be filled during final pass (4)</td>
<td></td>
</tr>
</tbody>
</table>
### TABLE 9.13 – Weld Surface Remedial

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weld spatter</td>
<td>1. Remove spatter observed before blasting with scraper or chipping hammer, etc.</td>
<td>In principle, no grinding is applied to weld surface.</td>
</tr>
<tr>
<td></td>
<td>2. For spatter observed after blasting:</td>
<td></td>
</tr>
<tr>
<td></td>
<td>a) Remove with a chipping hammer, scraper, etc.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>b) For spatter not easily removed with a chipping hammer, scraper, etc.,</td>
<td></td>
</tr>
<tr>
<td></td>
<td>grind the sharp angle of spatter to make it obtuse.</td>
<td></td>
</tr>
<tr>
<td>Arc strike</td>
<td>Remove the hardened zone by grinding or other measures such as overlapped weld bead etc.</td>
<td>Minimum short bead to be referred Table 9.14</td>
</tr>
</tbody>
</table>

(HT steel, Cast steel, Grade E of mild steel, TMCP type HT steel, Low temp steel)
**TABLE 9.14 – Welding Remedial by Short Bead**

<table>
<thead>
<tr>
<th>Detail</th>
<th>Remedial standard</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Short bead for remedying scar (scratch)</td>
<td>a) HT steel, Cast steel, TMCP type HT steel (C_{eq} &gt; 0.36%) and Low temp steel (C_{eq} &gt; 0.36%)</td>
<td>Preheating is necessary at 100 ± 25°C</td>
</tr>
<tr>
<td></td>
<td>Length of short bead ≥ 50 mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>b) Grade E of mild steel</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Length of short bead ≥ 30 mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>c) TMCP type HT steel (C_{eq} ≤ 0.36%) and Low temp steel (C_{eq} ≤ 0.36%)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Length of short bead ≥ 10 mm</td>
<td></td>
</tr>
<tr>
<td>Remedying weld bead</td>
<td>a) HT steel, Cast steel, TMCP type HT steel (C_{eq} &gt; 0.36%) and Low temp steel (C_{eq} &gt; 0.36%)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Length of short bead ≥ 50 mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>b) Grade E of mild steel</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Length of short bead ≥ 30 mm</td>
<td></td>
</tr>
<tr>
<td></td>
<td>c) TMCP type HT steel (C_{eq} ≤ 0.36%) and Low temp steel (C_{eq} ≤ 0.36%)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Length of short bead ≥ 30 mm</td>
<td></td>
</tr>
</tbody>
</table>

**NOTE:**

1. When short bead is made erroneously, remove the bead by grinding.
2. \(C_{eq} = C + \frac{Mn}{6} + \frac{Cr + Mo + V}{5} + \frac{Ni + Cu}{15} \) (\%)
PART B
Shipbuilding and Repair Quality Standard for Existing Ships
Part B - Shipbuilding and Repair Quality Standard for Existing Ships

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REFERENCES

B1. IACS Recommendation 76 "Bulk Carriers — Guidelines for Surveys, Assessment and Repair of Hull Structure"
B2. TSCF "Guidelines for the inspection and maintenance of double hull tanker structures"
B3. TSCF "Guidance manual for the inspection and condition assessment of tanker structures"
B4. IACS UR W11 "Normal and higher strength hull structural steels"
B5. IACS UR W17 "Approval of consumables for welding normal and higher strength hull structural steels"
B7. IACS UR Z3 "Voyage repairs and maintenance"
B8. IACS UR W33 "Non-destructive testing of ship hull steel welds"
B9. IACS Recommendation No. 96 "Double Hull Oil Tankers — Guidelines for Surveys, Assessment and Repair of Hull Structures"
B10. IACS Recommendation No. 55 "General Dry Cargo Ships — Guidelines for Surveys, Assessment and Repair of Hull Structures"
B11. IACS Recommendation No. 84 "Container Ships — Guidelines for Surveys, Assessment and Repair of Hull Structures"
B12. IACS UR W28 "Welding procedure qualification tests of steels for hull construction and marine structures"
B13. IACS UR W32 "Qualification scheme for welders of hull structural steels".

STANDARDS

ASME BPVC, Section IX:2019 "Boiler and Pressure Vessel Code, Section IX: Welding and Brazing Qualifications".
GB 712:2011 "Ship and ocean engineering structural steel".
ISO 4950-2:1995/Amd 1:2003 "High yield strength flat steel products — Part 2: Products supplied in the normalized or controlled rolled condition — Amendment 1".
JIS G 3106:2015 /Amd 1:2017 "Rolled steels for welded structure (Amendment 1)".
1. Scope

1.1 This standard provides guidance on quality of repair of hull structures. The standard covers permanent repairs of existing ships.

Whereas the standard generally applies to

- conventional ship types,
- parts of hull covered by the rules of the Classification Society,
- hull structures constructed from normal and higher strength hull structural steel, the applicability of the standard is in each case to be agreed upon by the Classification Society.

The standard does generally not apply to repair of

- special types of ships as e.g. gas tankers
- structures fabricated from stainless steel or other, special types or grades of steel

1.2 The standard covers typical repair methods and gives guidance on quality standard on the most important aspects of such repairs. Unless explicitly stated elsewhere in the standard, the level of workmanship reflected herein will in principle be acceptable for primary and secondary structure of conventional design. A more stringent standard may however be required for critical and highly stressed areas of the hull, and is to be agreed with the Classification Society in each case. In assessing the criticality of hull structure and structural components, reference is made to ref. B1, B2, B3, B6, B8, B9, B10, B11.

1.3 Restoration of structure to the original standard may not constitute durable repairs of damages originating from insufficient strength or inadequate detail design. In such cases strengthening or improvements beyond the original design may be required. Such improvements are not covered by this standard, however it is referred to ref. B1, B2, B3, B6, B8, B9, B10, B11.

1.4 IACS UR W33 (ref. B8) scope is for new construction only, however, for the purpose of NDT applicability within this Recommendation, UR W33 may be used as reference for NDT methods and acceptance standards.
2. General requirements for repairs and repairers

2.1 In general, when hull structure covered by classification is to be subjected to repairs, the work is to be carried out under the supervision of the Surveyor to the Classification Society. Such repairs are to be agreed prior to commencement of the work.

2.2 Repairs are to be carried out by workshops, repair yards or personnel who have demonstrated their capability to carry out hull repairs of adequate quality in accordance with the Classification Society's requirements and this standard.

2.3 Repairs are to be carried out under working conditions that facilitate sound repairs. Provisions are to be made for proper accessibility, staging, lighting and ventilation. Welding operations are to be carried out under shelter from rain, snow and wind.

2.4 Welding of hull structures is to be carried out by qualified welders, according to approved and qualified welding procedures and with welding consumables approved by the Classification Society, see Section 3. Welding operations are to be carried out under proper supervision of the repair yard.

2.5 Where repairs to hull which affect or may affect classification are intended to be carried out during a voyage, complete repair procedure including the extent and sequence of repair is to be submitted to and agreed upon by the Surveyor to the Classification Society reasonably in advance of the repairs. See Ref. B7.
3. Qualification of personnel

3.1 Qualification of welders

3.1.1 Welders are to be qualified in accordance with IACS UR W32 (ref. B13) or to a recognized national or international standard, e.g., ISO 9606-1:2012/COR2:2013, ASME BPVC Section IX:2019, ANSI/AWS D1.1:2020. Recognition of other standards is subject to submission to the Classification Society for evaluation. Repair yards and workshops are to keep records of welders qualification and, when required, furnish valid approval test certificates.

3.1.2 Welding operators using fully mechanised or fully automatic processes need generally not pass approval testing, provided that production welds made by the operators are of the required quality. However, operators are to receive adequate training in setting or programming and operating the equipment. Records of training and production test results shall be maintained on individual operator’s files and records, and be made available to the Classification Society for inspection when requested.

3.2 Qualification of welding procedures

Welding procedures are to be qualified in accordance with IACS UR W28 (ref. B12) or a recognized national or international standard, e.g. EN ISO 15607:2019, ISO 15614-1:2017, ASME BPVC, Section IX:2019, ANSI/AWS D1.1:2020. Recognition of other standards is subject to submission to the Classification Society for evaluation. The welding procedure should be supported by a welding procedure qualification record. The specification is to include the welding process, types of electrodes, weld shape, edge preparation, welding techniques and positions.

3.3 Qualification of NDT operators

3.3.1 Personnel performing NDT for the purpose of assessing quality of welds in connection with repairs covered by this standard, are to be qualified in accordance with the Classification Society rules or to a recognised international or national qualification scheme. Records of operators and their current certificates are to be kept and made available to the Surveyor for inspection.
4. Materials

4.1 General requirements for materials

4.1.1 The requirements for materials used in repairs are in general the same as the requirements for materials specified in the Classification Society’s rules for new constructions, (ref. B4).

4.1.2 Replacement material is in general to be of the same grade as the original approved material. Alternatively, material grades complying with recognised national or international standards may be accepted by the Classification Societies provided such standards give equivalence to the requirements of the original grade or are agreed by the Classification Society. For assessment of equivalency between steel grades, the general requirements and guidelines in Section 4.2 apply.

4.1.3 Higher tensile steel is not to be replaced by steel of a lesser strength unless specially approved by the Classification Society.

4.1.4 Normal and higher strength hull structural steels are to be manufactured at works approved by the Classification Society for the type and grade being supplied.

4.1.5 Materials used in repairs are to be certified by the Classification Society applying the procedures and requirements in the rules for new constructions. In special cases, and normally limited to small quantities, materials may be accepted on the basis of alternative procedures for verification of the material’s properties. Such procedures are subject to agreement by the Classification Society in each separate case.

4.2 Equivalency of material grades

4.2.1 Assessment of equivalency between material grades should at least include the following aspects:

- heat treatment/delivery condition
- chemical composition
- mechanical properties
- tolerances

4.2.2 When assessing the equivalence between grades of normal or higher strength hull structural steels up to and including grade E40 in thickness limited to 50 mm, the general requirements in Table 4.1 apply.

4.2.3 Guidance on selection of steel grades to certain recognised standards equivalent to hull structural steel grades specified in Classification Societies’ rules is given in Table 4.2...
<table>
<thead>
<tr>
<th>Items to be considered</th>
<th>Requirements</th>
<th>Comments</th>
</tr>
</thead>
</table>
| Chemical composition  | - C; equal or lower  
                        - P and S; equal or lower  
                        - Mn; approximately the same but not exceeding 1,6%  
                        - Fine grain elements; in same amount  
                        - Detoxification practice | The sum of the elements, e.g. Cu, Ni, Cr and Mo should not exceed 0,8% |
| Mechanical properties | - Tensile strength; equal or higher  
                        - Yield strength; equal or higher  
                        - Elongation; equal or higher  
                        - Impact energy; equal or higher at same or lower temperature, where applicable | Actual yield strength should not exceed Classification Society Rule minimum requirements by more than 80 N/mm² |
| Condition of supply   | Same or better | Heat treatment in increasing order;  
                        - as rolled (AR)  
                        - controlled rolled (CR)  
                        - normalised (N)  
                        - thermo-mechanically rolled (TM) ¹  
                        - quenched and tempered (QT) ¹  
¹) TM- and QT-steels are not suitable for hot forming |
| Tolerances             | Same or stricter | Permissible under thickness tolerances;  
                        - plates: 0,3 mm  
                        - sections: according to recognised standards |

Table 4.1 Minimum extent and requirements to assessment of equivalency between normal or higher strength hull structural steel grades
## Steel grades according to Classification Societies’ rules (ref.B4)

<table>
<thead>
<tr>
<th>Grade</th>
<th>Yield stress $R_{eH}$ min. (N/mm$^2$)</th>
<th>Tensile strength $R_m$ (N/mm$^2$)</th>
<th>Elongation $A_5$ min. (%)</th>
<th>Average impact energy for $t \leq 50$ mm (J, min.)</th>
<th>Test temp. (°C)</th>
<th>$L$</th>
<th>$T$</th>
<th>EN 10025:1990 (2)</th>
<th>EN 10025:2004</th>
<th>ASTM A 131</th>
<th>GB 712-2011</th>
<th>JIS G 3106</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>235</td>
<td>400 – 520</td>
<td>22</td>
<td></td>
<td>+ 20</td>
<td>0</td>
<td>20</td>
<td>Fe 360B</td>
<td>S235JR</td>
<td>A</td>
<td>SM400B</td>
<td></td>
</tr>
<tr>
<td>B</td>
<td></td>
<td></td>
<td>22</td>
<td></td>
<td>-20</td>
<td>27</td>
<td>20</td>
<td>Fe 360C</td>
<td>S235J0</td>
<td>B</td>
<td>SM400B,</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-40</td>
<td>27</td>
<td>20</td>
<td>Fe 360D</td>
<td>S235J2</td>
<td>D</td>
<td>SM400C</td>
<td></td>
</tr>
<tr>
<td>E</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S275NL, S275ML</td>
<td>E</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A 27</td>
<td>265</td>
<td>400 — 530</td>
<td>22</td>
<td></td>
<td>0</td>
<td>-20</td>
<td>20</td>
<td>S275J0</td>
<td>S275J2, S275N,</td>
<td>A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>D 27</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S275M S275NL,</td>
<td>B</td>
<td>SM400B,</td>
<td></td>
</tr>
<tr>
<td>E 27</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S275ML</td>
<td>D</td>
<td>SM400C</td>
<td></td>
</tr>
<tr>
<td>A 32</td>
<td>315</td>
<td>440 — 570</td>
<td>22</td>
<td></td>
<td>0</td>
<td>-20</td>
<td>20</td>
<td>S355J0</td>
<td>S355J2, S355N,</td>
<td>A</td>
<td>SM500B</td>
<td>AH32</td>
</tr>
<tr>
<td>D 32</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S355M S355M</td>
<td>S355NL, S355ML</td>
<td>D</td>
<td>SM500C</td>
<td>DH32</td>
</tr>
<tr>
<td>E 32</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>E</td>
<td>EH32</td>
<td></td>
</tr>
<tr>
<td>A 36</td>
<td>355</td>
<td>490 — 630</td>
<td>21</td>
<td></td>
<td>0</td>
<td>-20</td>
<td>24</td>
<td>S355J0</td>
<td>E355E</td>
<td>AH36</td>
<td></td>
<td></td>
</tr>
<tr>
<td>D 36</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S355J2, S355N,</td>
<td>S355M</td>
<td>SM520B,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>E 36</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S355M S355M</td>
<td>E355E</td>
<td>SM520C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A 40</td>
<td>390</td>
<td>510 — 660</td>
<td>20</td>
<td></td>
<td>0</td>
<td>-20</td>
<td>26</td>
<td>S420N/M</td>
<td>E430CC</td>
<td>AH40</td>
<td></td>
<td></td>
</tr>
<tr>
<td>D 40</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S420N/M</td>
<td>E430DD</td>
<td>DH40</td>
<td></td>
<td></td>
</tr>
<tr>
<td>E 40</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>S420NL/ML</td>
<td>E430E</td>
<td>EH40</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note:** (1) In selecting comparable steels from this table, attention should be given to the requirements of Table 4.1 and the dimension requirements of the product with respect to Classification Society rules. Some steel grades as per national or international standard are defined with specified yield and tensile strength properties which depend on thickness. For thicknesses with tensile properties specified lower than those of the Classification Society’s Rules, case-by-case consideration shall be given with regards to design requirements. (2) EN 10025:1990 is superseded by EN10025:2019 (e.g. EN 10025-2:2019, EN 10025 3:2019, EN 10025-4:2019).

**Table 4.2 Guidance on steel grades comparable to the normal and high strength hull structural steel grades given in Classification Society rules**
5. General requirements to welding

5.1 Correlation of welding consumables with hull structural steels

5.1.1 For the different hull structural steel grades welding consumables are to be selected in accordance with IACS UR W17 (see Ref. B5).

5.2 General requirements to preheating and drying out

5.2.1 The need for preheating is to be determined based on the chemical composition of the materials, welding process and procedure and degree of joint restraint.

5.2.2 A minimum preheat of 50 °C is to be applied when ambient temperature is below 0 °C. Dryness of the welding zone is in all cases to be ensured.

5.2.3 Guidance on recommended minimum preheating temperature for higher strength steel is given in Table 5.1. For automatic welding processes utilising higher heat input e.g. submerged arc welding, the temperatures may be reduced by 50 °C. For re-welding or repair of welds, the stipulated values are to be increased by 25 °C.

<table>
<thead>
<tr>
<th>Carbon equivalent 1)</th>
<th>Recommended minimum preheat temperature (°C)</th>
<th>$t_{comb} \leq 50$ mm 2)</th>
<th>$50 \text{ mm} &lt; t_{comb} \leq 70$ mm 2)</th>
<th>$t_{comb} &gt; 70$ mm 2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$c_{eq} \leq 0,39$</td>
<td>—</td>
<td>50</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$c_{eq} \leq 0,41$</td>
<td>—</td>
<td>—</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$c_{eq} \leq 0,43$</td>
<td>—</td>
<td>50</td>
<td></td>
<td>100</td>
</tr>
<tr>
<td>$c_{eq} \leq 0,45$</td>
<td>50</td>
<td>100</td>
<td></td>
<td>125</td>
</tr>
<tr>
<td>$c_{eq} \leq 0,47$</td>
<td>100</td>
<td>125</td>
<td></td>
<td>150</td>
</tr>
<tr>
<td>$c_{eq} \leq 0,50$</td>
<td>125</td>
<td>150</td>
<td></td>
<td>175</td>
</tr>
</tbody>
</table>

Table 5.1 Preheating temperature

5.3 Dry welding on hull plating below the waterline of vessels afloat

5.3.1 Welding on hull plating below the waterline of vessels afloat is acceptable only on normal and higher strength steels with specified yield strength not exceeding 355 MPa and only for local repairs. Welding involving other high strength steels or more extensive repairs against water backing is subject to special consideration and approval by the Classification Society of the welding procedure.

5.3.2 Low-hydrogen electrodes or welding processes are to be used when welding on hull plating against water backing. Coated low-hydrogen electrodes used for manual metal arc welding should be properly conditioned to ensure a minimum of moisture content.

5.3.3 In order to ensure dryness and to reduce the cooling rate, the structure is to be preheated by a torch or similar prior to welding, to a temperature of minimum 5 °C or as specified in the welding procedure.
Guidelines on Technical Supervision of Ships under Construction (Section 2)

No. 47 (cont)

Notes:

1) \[ C_{eq} = C + \frac{Mn}{6} + \frac{Cr + Mo + V}{5} + \frac{Ni + Cu}{15} \text{(%)} \]

2) Combined thickness \( t_{comb} = t_1 + t_2 + t_3 + t_4 \), see figure
6. Repair quality standard

6.1 Welding, general

---

**Fig 6.1 Groove roughness**

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Material Grade</td>
<td>Same as original or higher</td>
<td></td>
<td>See <strong>Section 4</strong></td>
</tr>
<tr>
<td>Welding Consumables</td>
<td>IACS UR W17 (ref. B5)</td>
<td>Approval according to equivalent international standard</td>
<td></td>
</tr>
<tr>
<td>Groove / Roughness</td>
<td>See note and Fig 6.1</td>
<td>d &lt; 1.5 mm</td>
<td>Grind smooth</td>
</tr>
<tr>
<td>Pre-Heating</td>
<td>See Table 5.1</td>
<td>Steel temperature not lower than 5°C</td>
<td></td>
</tr>
<tr>
<td>Welding with water on the outside</td>
<td>See <strong>Section 5.3</strong></td>
<td>Acceptable for normal and high strength steels</td>
<td>- Moisture to be removed by a heating torch</td>
</tr>
<tr>
<td>Alignment</td>
<td>As for new construction</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weld Finish</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NDT</td>
<td>IACS UR W33 (ref. B8)</td>
<td>At random with extent to be agreed with attending surveyors</td>
<td></td>
</tr>
</tbody>
</table>

Note:

Slag, grease, loose mill scale, rust and paint, other than primer, to be removed.
### No. 47 (cont)

#### 6.2 Renewal of plates

![Diagram showing renewal of plates](image)

R = 5 x plate thickness
min. 100mm

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Size Insert</td>
<td>Min. 300 x 300 mm R = 5 x thickness Circular inserts: ( D_{\text{min}} = 200 \text{ mm} )</td>
<td>Min. 200 x 200 mm Min R = 100 mm</td>
<td></td>
</tr>
<tr>
<td>Material Grade</td>
<td>Same as original or higher</td>
<td></td>
<td>See <a href="#">Section 4</a>.</td>
</tr>
<tr>
<td>Edge Preparation</td>
<td>As for new construction</td>
<td></td>
<td>In case of non compliance increase the amount of NDT</td>
</tr>
<tr>
<td>Welding Sequence</td>
<td>See Fig 6.2 Weld sequence is 1 → 2 → 3 → 4</td>
<td>For primary members sequence 1 and 2 transverse to the main stress direction</td>
<td></td>
</tr>
<tr>
<td>Alignment</td>
<td>As for new construction</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weld Finish</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NDT</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Fig 6.2 Welding sequence for inserts**
6.3 Doublers on plating

Local doublers are normally only allowed as temporary repairs, except as original compensation for openings, within the main hull structure.

![Diagram of doublers on plates]

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Existing Plating</td>
<td></td>
<td>General: ( t \geq 5 ) mm</td>
<td>For areas where existing plating is less than 5 mm plating a permanent repair by insert is to be carried out.</td>
</tr>
<tr>
<td>Extent / Size</td>
<td></td>
<td>min 300 x 300 mm</td>
<td></td>
</tr>
<tr>
<td>Thickness of Doubler (td)</td>
<td>( t_d \leq t_p ) ( R \geq 50 ) mm</td>
<td>( t_d &gt; tp/3 )</td>
<td></td>
</tr>
<tr>
<td>Material Grade</td>
<td></td>
<td>Same as original plate</td>
<td>See Section 4</td>
</tr>
<tr>
<td>Edge Preparation</td>
<td>As for newbuilding</td>
<td>new construction</td>
<td>Doublers welded on primary strength members: ( L_e ): leg length when ( t &gt; L_e + 5 ) mm, the edge to be tapered (1:4)</td>
</tr>
<tr>
<td>Welding</td>
<td>As for newbuilding</td>
<td>new construction</td>
<td>Welding sequence similar to insert plates.</td>
</tr>
<tr>
<td>Weld Size (throat thickness)</td>
<td></td>
<td>Circumferencial and in slots: 0.6 x ( t_d )</td>
<td></td>
</tr>
<tr>
<td>Slot Welding</td>
<td>Normal size of slot: (80 –100) x 2 ( t_d ) Distance from doubler edge and between slots: ( d \leq 15 t_d )</td>
<td>Max pitch between slots 200 mm ( d_{max} = 500 ) mm</td>
<td>For doubler extended over several supporting elements, see Figure 6.3</td>
</tr>
<tr>
<td>NDT</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
6.4 Renewal of internals/stiffeners

Fig 6.4 Welding sequence for inserts of stiffeners

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Size Insert</td>
<td>Min. 300 mm</td>
<td>Min. 200 mm</td>
<td></td>
</tr>
<tr>
<td>Material Grade</td>
<td>Same as original or</td>
<td></td>
<td>See Section 4.</td>
</tr>
<tr>
<td></td>
<td>higher</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Edge Preparation</td>
<td>As for new construction. Fillet weld stiffener web / plate to be released over min. (d = 150\ mm)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Welding Sequence</td>
<td>See Fig 6.4</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Welding sequence is (1 \rightarrow 2 \rightarrow 3)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Alignment</td>
<td>As for new construction</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weld Finish</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NDT</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
6.5 Renewal of internals/stiffeners – transitions inverted angle/bulb profile

The application of the transition is allowed for secondary structural elements.

![Diagram of transition between inverted angle and bulb profile]

### Table 6.5 Transition between inverted angle and bulb profile

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>( (h_1 - h_2) )</td>
<td>( \leq 0.25 \times b_1 )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(</td>
<td>t_1 - t_2</td>
<td>)</td>
<td>2 mm</td>
</tr>
<tr>
<td>Transition Angle</td>
<td>15 degrees</td>
<td>At any arbitrary section</td>
<td></td>
</tr>
</tbody>
</table>
| Flanges               | \( t_f = t_{f_2} \)\[1\]
                        | \( b_f = b_{f_2} \)\[2\] |                |                             |
| Length of Flatbar     | \( 4 \times h_1 \) |                |                             |
| Material              |          |                | See Section 4.              |
6.6 Application of Doubling Straps

In certain instances, doubling straps are used as a means to strengthen and reinforce primary structure. Where this has been agreed and approved, particular attention should be paid to:

- the end termination points of the straps, so that toe support is such that no isolated hard point occurs.
- in the case of application of symmetrical or asymmetrical-ended straps, the corners at the end of the tapering should be properly rounded.
- any butts between lengths of doubling straps, so that there is adequate separation of the butt weld from the primary structure below during welding, and so that a high quality root run under controlled circumstances is completed prior to completing the remainder of the weld. Ultrasonic testing should be carried out on completion to verify full penetration.

![Diagram of Doubling Straps]

**Fig 6.6 Application of Doubling Straps**

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tapering</td>
<td>$l/b &gt; 3$</td>
<td></td>
<td>Special consideration to be drawn to design of strap terminations in fatigue sensitive areas.</td>
</tr>
<tr>
<td>Radius</td>
<td>$0.1 \times b$</td>
<td>min 30 mm</td>
<td>See paragraph 2.0 General requirement to materials.</td>
</tr>
<tr>
<td>Material</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weld Size</td>
<td></td>
<td></td>
<td>Depending on number and function of straps. Throat thickness to be increased 15% toward ends.</td>
</tr>
<tr>
<td>Welding</td>
<td>Welding sequence from middle towards the free ends</td>
<td></td>
<td>See sketch. For welding of lengths &gt; 1000 mm step welding to be applied.</td>
</tr>
</tbody>
</table>
No. 6.7 Welding of pitting corrosion

Notes:

Shallow pits may be filled by applying coating or pit filler. Pits can be defined as shallow when their depth is less that 1/3 of the original plate thickness.

Fig 6.7 Welding of pits

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Extent / Depth</td>
<td>Pits / grooves are to be welded flush with the original surface.</td>
<td>If deep pits or grooves are clustered together or remaining thickness is less than 6 mm, the plates should be renewed.</td>
<td>See also IACS UR W11 (ref. B4)</td>
</tr>
<tr>
<td>Cleaning</td>
<td>Heavy rust to be removed</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Pre-Heating</td>
<td>See Table 5.1</td>
<td>Required when ambient temperature &lt; 5 °C</td>
<td>Always use propane torch or similar to remove any moisture</td>
</tr>
<tr>
<td>Welding Sequence</td>
<td>Reverse direction for each layer</td>
<td></td>
<td>See also IACS UR W11 (ref. B4)</td>
</tr>
<tr>
<td>Weld Finish</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NDT</td>
<td>IACS UR W33 (ref. B8)</td>
<td>Min. 10% extent</td>
<td>Preferably MPI</td>
</tr>
</tbody>
</table>

Reference is made to TSCF Guidelines, Ref. B2 & B3.
6.8 Welding repairs for cracks

In the event that a crack is considered weldable, either as a temporary or permanent repair, the following techniques should be adopted as far as practicable. Run-on and run-off plates should be adopted at all free edges.

Fig 6.8.a Step back technique

Fig 6.8.b End crack termination

Fig 6.8.c Welding sequence for cracks with length less than 300 mm
Guidelines on Technical Supervision of Ships under Construction (Section 2)

No. 47 (cont)

Fig 6.8.d Groove preparation (U-groove left and V-groove right)

<table>
<thead>
<tr>
<th>Item</th>
<th>Standard</th>
<th>Limit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Groove Preparation</td>
<td>$\theta = 45-60^\circ$</td>
<td>$r = 5$ mm</td>
<td>For through plate cracks as for newbuilding. Also see Fig 6.8.d</td>
</tr>
<tr>
<td>Termination</td>
<td>Termination to have slope 1:3</td>
<td></td>
<td>For cracks ending on edges weld to be terminated on a tab see Fig 6.8.b</td>
</tr>
<tr>
<td>Extent</td>
<td>On plate max. 400 mm length. Vee out 50 mm past end of crack</td>
<td>On plate max 500 mm. Linear crack, not branched</td>
<td></td>
</tr>
<tr>
<td>Welding Sequence</td>
<td>See Fig 6.8.c for sequence and direction</td>
<td>For cracks longer than 300 mm step-back technique should be used Fig 6.8.a</td>
<td>Always use low hydrogen welding consumables</td>
</tr>
<tr>
<td>Weld Finish</td>
<td>IACS UR W33 (ref. B8)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NDT</td>
<td>IACS UR W33 (ref. B8)</td>
<td>100 % MP or PE of groove</td>
<td>100 % surface crack detection + UE or RE for butt joints</td>
</tr>
</tbody>
</table>
## FINAL INSPECTION REPORT ON SURFACE PREPARATION FOR PROTECTIVE COATING APPLICATION

(Recommended form)

<table>
<thead>
<tr>
<th>FINAL INSPECTION REPORT No.</th>
<th>on surface preparation for protective coating application</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>(object, area, in m²)</td>
</tr>
</tbody>
</table>

### 1 General information

<table>
<thead>
<tr>
<th>1.1 Name of ship</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1.2 Shipowner</td>
<td></td>
</tr>
<tr>
<td>1.3 Shipyard</td>
<td></td>
</tr>
<tr>
<td>1.4 Place and duration of works</td>
<td></td>
</tr>
<tr>
<td>1.5 Coating system</td>
<td>(brand, type colour, number of layers, thickness, in μm, RS Certificate of Conformity No.)</td>
</tr>
<tr>
<td>1.6 Paint/Coating manufacturer</td>
<td>(name)</td>
</tr>
</tbody>
</table>

### 2 Preparation of metal rolled products surface

<table>
<thead>
<tr>
<th>2.1 Work performer</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>2.2 Abrasive</td>
<td>(brand, type, firm (manufacturer))</td>
</tr>
<tr>
<td>2.2.1 Size</td>
<td>2.2.2 Copper</td>
</tr>
<tr>
<td>2.2.5 Moisture</td>
<td>2.2.6 Water–soluble impurities, mS/m</td>
</tr>
<tr>
<td>2.2.7 Storage conditions</td>
<td></td>
</tr>
<tr>
<td>2.3 Surface preparation:</td>
<td></td>
</tr>
<tr>
<td>2.3.1 Fresh water washing</td>
<td>2.3.2 Degree of cleaning</td>
</tr>
<tr>
<td>2.3.3 Roughness, μm</td>
<td>2.3.4 Oil</td>
</tr>
<tr>
<td>2.3.6 Water–soluble impurities, mg/m²</td>
<td></td>
</tr>
<tr>
<td>2.4 Environmental conditions in works performance</td>
<td>(temperature of air and steel, humidity, dew point)</td>
</tr>
<tr>
<td>2.5 Shop primer</td>
<td></td>
</tr>
<tr>
<td>2.5.1 Firm (Manufacturer)</td>
<td>(brand, type, colour, thickness, in μm)</td>
</tr>
</tbody>
</table>

### 3 Preparation of hull structures and outfitting components

| 3.1 Executor of work       |                                  |
| 3.2 Preparing of sharp edges |                                  |
| 3.3 Dimensions of holes and openings |                   |
| 3.4 Condition of welds and the adjacent zone |                         |
| 3.5 Fitting of outfitting components and protectors |                       |

### 4 Preparation of hull structures surface

| 4.1 Executor of work       |                                  |
| 4.2 Abrasive               | (brand, type, firm (manufacturer)) |
| 4.2.1 Size                 | 4.2.2 Mohs' hardness             | 4.2.3 Copper                   | 4.2.4 Oil                      |
| 4.2.5 Moisture             | 4.2.6 Dust                      | 4.2.7 Water–soluble impurities, mS/m |
| 4.3 Surface preparation:   |                                  |
| 4.3.1 Fresh water washing  | 4.3.2 Degree of surface cleaning |
| 4.3.3 Cleanliness of damages and welds |                         |
| 4.3.5 Oil                  | 4.3.6 Way of abrasive removal   |
| 4.3.7 Water–soluble contamination, mg/m² |                     |
| 4.3.8 Antifouling system removed, % |                         |
Guidelines on Technical Supervision of Ships under Construction (Section 2)

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4.4 Environmental conditions in works performance \((T_{st} - T_{dew} > 3 \degree C)\):

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Parameters</th>
<th>Minimum value</th>
<th>Maximum value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Date/Time</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Air temperature ((T_{air}), \degree C)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Air humidity ((R% H), %)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>Steel temperature ((T_{st}), \degree C)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Dew point ((T_{dew}), \degree C)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

5 Coating system application

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Object</th>
<th>Paint and operation name</th>
<th>Environmental conditions ((T_{st} - T_{dew} &gt; 3 \degree C))</th>
<th>Minimum</th>
<th>Maximum</th>
<th>Thinner, %</th>
<th>Batch No. and paint colour</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>Date/Time</td>
<td>Air</td>
<td>Steel</td>
<td>Air</td>
<td>Steel</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td>Date</td>
<td>Time</td>
<td>Temperatures, °C</td>
<td>RH, %</td>
<td>Temperatures, °C</td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1 List of operations: application of shop primer, strip and basic layers of coatings; curing of each coating layer and heat treatment of the finished coating.

5.1 Work performer ______________________________ (name)

6 Thickness of finished coating

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Coating name(^1)</th>
<th>Thickness, in μm</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Specified</td>
<td>Actual</td>
</tr>
<tr>
<td></td>
<td>Wet layer</td>
<td>Dry film</td>
</tr>
<tr>
<td></td>
<td>Minimum</td>
<td>Nominal</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1 List of coatings: shop primer; basic and common layers of coatings.
7 Coatings defects
7.1 Sags ____________________________ 7.2 Curtains ____________________________ 7.3 Orange peel ____________________________
7.4 Craters ____________________________ 7.5 Fish eye ____________________________ 7.6 Wrinkling ____________________________
7.7 Irregular gloss ____________________________ 7.8 Dust of film ____________________________
8 Fully cured ____________________________
9 Spark test ____________________________

(equipment, results and standard)

The works have been carried out in accordance with the shipyard technical documentation ____________________________

(name of document)

Agreed with the coating manufacturer ____________________________

The Report has been executed by the painting surveyor of the organization ____________________________

(name)

Coating inspector ____________________________

(signature, full name and date)
### APPENDIX 3

**CHECK LIST OF THE SHIP LAUNCHING READINESS**

<table>
<thead>
<tr>
<th>№</th>
<th>Объект освидетельствования</th>
<th>Результаты освидетельствования</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Проверка отчетной документации по испытаниям и проверкам выполненным до спуска: The reporting documentation on tests and inspections carried out before launching have been verified:</td>
<td></td>
</tr>
<tr>
<td>1.1</td>
<td>главных размерений корпуса of hull Main Dimensions</td>
<td></td>
</tr>
<tr>
<td>1.2</td>
<td>выполнении работ по окраске корпуса ниже ватерлинии of work on application protective coating below waterline</td>
<td></td>
</tr>
<tr>
<td>1.3</td>
<td>о полном окончании работ по сборке, сварке, правке и испытаниям на непроницаемость в объеме предспусковой готовности completion of assembly, welding, straightening and testing for tightness in the scope of pre-launching readiness</td>
<td></td>
</tr>
<tr>
<td>1.4</td>
<td>документов о выполнении неразрушающего контроля сварных швов в соответствии со схемой of the records on a welding control plan</td>
<td></td>
</tr>
<tr>
<td>1.5</td>
<td>об установке дейдвудных труб, гребных валов, винтов и насадок, подруливающих устройств, САУС fitting stern tubes, propeller shafts, propellers and nozzles, thrusters, azimuth thrusters (unless these are fitted afloat)</td>
<td></td>
</tr>
<tr>
<td>1.6</td>
<td>об установке пера руля и баллера fitting rudder blade and rudder stock</td>
<td></td>
</tr>
<tr>
<td>1.7</td>
<td>об установке и испытаниях донно-бортовой арматуры installation and tests of outboard fittings</td>
<td></td>
</tr>
<tr>
<td>1.8</td>
<td>об укладке твердого балласта, если таковой предусмотрен laying the solid ballast if any</td>
<td></td>
</tr>
<tr>
<td>1.9</td>
<td>об установке забортных аппаратов и устройств и проверке на непроницаемость в местах прохода через наружную обшивку связанных с ними кабелей, труб и т. п., а также крепления к корпусу fitting outboard apparatus and arrangements, and tightness tests in ways where cables, pipes, etc. associated with these pass through the shell plating, as well as attachments to the hull</td>
<td></td>
</tr>
</tbody>
</table>
1. **Guidelines on Technical Supervision of Ships under Construction (Section 2)**

Отчёт о проверке готовности спуска судна на воду

**Report on the survey of ship launching readiness**

### 2. Кингстонные / ледовые ящики

<table>
<thead>
<tr>
<th></th>
<th>Sea / Ice chests</th>
</tr>
</thead>
</table>
| 2.1 | Проверка насыщения
Outfitting inspection |
| 2.2 | Проверка установки элементов защиты от коррозии на соответствие чертежам
Inspection of corrosion protection elements fitted according to drawings |
| 2.3 | Проверка закрепления решеток
Inspection of griddles locking |

### 3. Эхолот

<table>
<thead>
<tr>
<th></th>
<th>Echo sounder</th>
</tr>
</thead>
</table>
| 3.1 | Проверка на непроницаемость в местах прохода через наружную обшивку связанных с эхолотом кабелей, труб и т. п.
Tightness tests in ways where cables, pipes, etc. associated with echo sounder pass through the shell plating etc. |
| 3.2 | Проверка крепления к корпусу
Fitting inspection to the hull |

### 4. Лаг

<table>
<thead>
<tr>
<th></th>
<th>Speed log</th>
</tr>
</thead>
</table>
| 4.1 | Проверка на непроницаемость в местах прохода через наружную обшивку связанных с лагом кабелей, труб и т. п.
Tightness tests in ways where cables, pipes, etc. associated with speed log pass through the shell plating etc. |
| 4.2 | Проверка крепления к корпусу
Fitting inspection to the hull |

### 5. Спускные пробки

<table>
<thead>
<tr>
<th></th>
<th>Drain plugs</th>
</tr>
</thead>
</table>
| 5.1 | Проверка установки
Mounting inspection |
| 5.2 | Испытания на непроницаемость
Tightness test |

### 6. Марки углубления и знаки грузовой марки

<table>
<thead>
<tr>
<th></th>
<th>Draught-marks and load line marks</th>
</tr>
</thead>
</table>
| 6.1 | Проверка соответствия нанесения марок углубления чертежу
Inspection of measurement of draught-marks, according to the drawing |
| 6.2 | Проверка соответствия нанесения знаков грузовой марки чертежу
Inspection of measurement of load line marks, according to the drawing |

### 7. Наружная обшивка

<table>
<thead>
<tr>
<th></th>
<th>Shell plating</th>
</tr>
</thead>
</table>
| 7.1 | Визуальный осмотр наружной обшивки ниже ватерлинии
Visual inspection of shell plating below waterline |
### Recommendations

<table>
<thead>
<tr>
<th>№ пункта</th>
<th>Содержание</th>
<th>Срок устранения</th>
</tr>
</thead>
<tbody>
<tr>
<td>item No.</td>
<td>Description</td>
<td>To be dealt by</td>
</tr>
</tbody>
</table>

### ЗАКЛЮЧЕНИЕ

В результате проведенного освидетельствования выявлено, что техническое состояние судна полностью / не полностью* соответствуют применимым требованиям для спуска на воду.

**CONCLUSION**

During the survey now held it was found that technical condition of vessel completely / not completely* fulfill the applicable requirements for launching.

__________________

Инженер-инспектор PC
Surveyor to RS

__________________

Инженер-инспектор PC
Surveyor to RS

__________________

Инженер-инспектор PC
Surveyor to RS

* Ненужное зачеркнуть
Delete as appropriate
INSTRUCTIONS ON INCLINING TEST OF SHIPS

1 APPLICATION

1.1 The Instructions on the Inclining Test of Ships shall be used in determination of the weight and position of the centre of gravity of the light ship in accordance with the requirements of 1.5, Part IV “Stability” of the Rules for the Classification and Construction.

2 DEFINITIONS AND EXPLANATIONS

2.1 For the purpose of the Instructions, the following terms are used.

Inclining test is a series of sequential transverse movements of the test weight on board the ship to cause some inclinations and to measure the relevant angles of heel, as well as to survey the light ship and read draughts needed for determination of the light ship weight and coordinates of its centre of gravity using calculating methods of the ship theory.

Draught is a vertical distance measured from the base line to the waterline.

Survey of a light ship is the inspection of the ship's condition related to missing, redundant or movable objects. The weight and position of each object centre of gravity shall be precisely determined and recorded as on the basis of these data and also of the inclining measurements and results will be obtained the values of the light ship weight and coordinates of its centre of gravity.

Survey of the test weights is the verification of the mass marked on test weight. The survey shall be carried out close enough in time the inclining test.

Light ship is a ship of which construction (updating, repair) is completed, but without cargo, stores, crew and their effects, and other components of deadweight.

Fully pressed-up tank is a fully filled tank without voids due to heel, trim or inadequate ventilation. Any level of filling below 100 %, e.g. 98 %, when the tank is considered full for operational purposes, is not allowed. After tanks pressing-up, the ship shall be subjected to inclinations to remove air therefrom. The above procedure shall be completed prior to the final measurements of a liquid level. To prevent pollution, special precautions shall be taken in pressing-up oil tanks.

Empty tanks are tanks wherein water is absent. Generally it is inadequate to empty tanks using pumps until they stop to pump out water. After liquid pumping-out, the tank shall be examined from the inside to decide whether is the final stripping with portable pumps or manually needed. The exception is very narrow tanks or the ones in way of the drastic rise of the bottom as the free surface will be insignificant. All empty tanks, to which all access holes shall be opened, shall be examined, and the very tanks, properly vented and recognized safe for entry. A safe device for checking a sufficient level of oxygen and minimal level of toxic gases shall be ready for use. A document issued by a competent body and confirming the safe access to all tanks and enclosed spaces shall be onboard the ship.
3 PREPARING SHIP TO INCLINING TEST

3.1 In good time prior to the inclining test, the ship’s instruction on inclining performance as applied to the particular ship shall be developed and submitted to the Register for examination and approval. The instruction shall contain the following particulars:

1. name and hull number of the ship, if applicable;
2. date, time and location of the test;
3. inclining weight data:
   3.1 type;
   3.2 total mass and composition (number of units and mass of each);
   3.3 way of transfer from side to side;
   3.4 procedure for test weights transfer;
   3.5 anticipated maximum angle of heel to each side;
4. measuring devices:
   4.1 pendulums — approximate location and length;
   4.2 U-tubes — approximate location and length;
   4.3 inclinographs — location and calibration details;
5. estimated parameters of trim and initial stability of the ship for the time of the inclining test;
6. condition of tanks;
7. estimated mass and coordinates of the centre of gravity of missing, redundant or movable objects;
8. scheme of ship’s positioning;
9. specific instructions on measurements performance;
10. detailed description of any computer software to be used to aid in calculations during the inclining test; and
11. name and telephone number of the person responsible for conducting the inclining test.

3.2 General condition of ship.

3.2.1 The ship’s construction shall be close to its end by the time of the inclining test. Load of the ship during the inclining test shall be as nearly as possible to displacement of the light ship. The mass of missing cargoes shall not exceed 2 % of displacement of the light ship and the mass of surplus cargoes (excluding test weight and ballast for provision of the required trim and stability) — 4 %.

3.2.2 Considering that the scope and type of works to be completed (the expected missing mass) impact an accuracy of determining a light ship displacement, such works shall be well known. If it is impractical to precisely determine the mass and position of a centre of gravity for the missing object, the inclining test shall be carried out after the installation of such an object in the ship.

3.2.3 Prior to the inclining test, all the materials like packing, scaffolding, sand, garbage, etc. being temporarily on board the ship shall be reduced to a minimum. Crew members or the personnel directly not involved in the inclining test shall leave the ship before the test.

3.2.4 Any rainwater, snow or ice accumulated on board shall be removed prior to the test.

3.2.5 Hopper barges, dredgers and other vessels of dredging fleet in which the watertight integrity of their hoppers cannot be achieved due to the structural peculiarities may be inclined with water in the hoppers which communicate easily with sea water.

3.2.6 The anticipated liquid loading for the test shall be included in the Instructions on the Inclin ing Test. The number of slack tanks shall be kept to an absolute minimum. The viscosity of the fluid, the depth of the fluid and the shape of the tank shall be such that the mass, coordinates of centre of gravity and free surface effect can be accurately determined.

The Report of Liquid Cargoes Condition shall be drawn up which shall include liquid cargoes available on board at the time of the inclining test.
3.2.7  The ship shall be moored in the protected part of a water area which is free of disturbing forces caused by, for example, waves of passing ships, swell or sudden discharges from land utility systems. The wind velocity shall not exceed 3.5 m/s. In inclining, the current and ship's trim shall be taken into account. To prevent ship's touching the bed, the water depth shall be measured and recorded in appropriate locations prior to the test. The water density shall be precisely measured. The ship shall be moored so that nothing prevents its inclination. Gangboards for access to the ship shall be removed. The number of cables, hoses, etc. from the shore shall be minimal and an opportunity of their loosening shall always be provided.

3.2.8  The ship shall be in the upright position and have the sufficient draught to avoid drastic changes of the waterline area in inclinations. The ship's trim shall not exceed 1% of the ship's length if hydrostatic data are used in calculations; otherwise, direct calculations with due regard for the actual trim shall be performed. In all cases, drastic changes of the waterline area in ship's inclinations shall be avoided. The ship's heel shall be within 0.5° with the test weight in its initial position.

3.2.9  The total mass of the test weight shall be adequate to ensure the ship's heel within 1° – 4° to each side. The test weight shall be compact and ensure the precise determination of coordinates of its centre of gravity. Each test weight unit shall be marked with its number and mass specified. Each test weight unit shall be surveyed before each inclining test. Provisions shall be made for cargo cranes of the adequate lifting capacity and outreach, or for other arrangements for the quick and safe transfer of the test weight.

Where the use of solid weights to produce the inclining moment is demonstrated to be impracticable, the movement of water ballast may be permitted, provided the requirements in 2.3.4, Annex 1 to Part B of the International Code on Intact Stability, 2008 (2008 IS Code) are met.

3.2.10  The use of 3 pendulums is recommended but a minimum of 2 shall be used to allow identification of bad readings at any one pendulum station. Pendulums shall be located in an area protected from the wind. Their length shall provide a deflection of at least 15 cm across the measuring scale with the test weight at one side.

One or more pendulums may be substituted by other Register-approved measuring devices (U-tubes or inclinographs). The use of inclinographs or other measuring devices is recommended in conjunction with at least one pendulum.

3.2.11  The reliable two-way communication shall be provided between the inclining control station and the personnel moving the heeling ballast and making the measurements. The leadership during the inclining test shall be carried out by one person at the control station.

4  DOCUMENTATION

4.1  The following documentation shall be onboard the ship during the inclining test:

- lines plan;
- hydrostatic curves or hydrostatic data;
- general arrangement plan;
- capacity plan showing capacities and centers of gravity of cargo spaces, tanks, etc. When water ballast is used as inclining weight, the centers of gravity for the applicable tanks for each angle of inclination, must be available;
- tank sounding tables;
- draught marks locations; and
- docking drawing with keel profile (for ships with the design trim) and draught mark corrections;
- stability calculations and preliminary Stability Booklet.
5 PROCEDURE FOR INCLINING PERFORMANCE

5.1 The inclining shall be carried out in accordance with the Register-approved Instructions on Inclining Test and Detailed Guidance for the Conduct of an Inclining Test given in Annex 1 to Part B of 2008 IS Code.

5.2 The inspection of the ship shall be conducted prior to the beginning of the inclining test to check the availability for inclining.

5.3 To determine the waterline position and calculate the displacement, the draughts and freeboard shall be read. The freeboard measurements are recommended in amounts of five readings for each side. These measurements shall be made immediately before and after inclining.

5.4 The standard test consists of the following movements given in Table 5.4.

To obtain acceptable data, the "heeling moment-tangent of a deflection angle" plot to monitor measurements is recommended to be kept. Plotting all the readings of each pendulum facilitates the detection of wrong readings. The points plotted shall fall on a straight line or close thereto. Deflections from the straight line imply the action of other moments on the ship during the inclining test.

If the straight line is obtained after the beginning of counting-off and test weight movements, then the second check of zero point (movement No. 8/No. 12) may be omitted. If the straight line is not obtained, the test weight movements, which failed to provide acceptable points, shall be repeated or explained.

Table 5.4

<table>
<thead>
<tr>
<th>Number of groups</th>
<th>Side</th>
<th>Movements</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>0</td>
</tr>
<tr>
<td>2</td>
<td>P</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>S</td>
<td>1</td>
</tr>
<tr>
<td>4</td>
<td>P</td>
<td>2, 4</td>
</tr>
<tr>
<td></td>
<td>S</td>
<td>1, 3</td>
</tr>
<tr>
<td>6</td>
<td>P</td>
<td>2, 4, 6</td>
</tr>
<tr>
<td></td>
<td>S</td>
<td>1, 3, 5</td>
</tr>
</tbody>
</table>

Note: Heeling ballast groups are designated with figures.

5.5 The following accuracy of measurements shall be ensured in the process of preparation and during the inclining test:

- pendulum length ................................................................. 5 mm;
- draught and freeboard ........................................................................ 10 mm;
- arms of test weight transfer and coordinates of cargoes centre of gravity .................................................. 10 mm;
- pendulum deflections ........................................................................ 1 mm;
- measurements in heeling tables, ......................................................... 0.2 mm;
- mass of test weight (persons) .............................................................. 1 %
- density. ......................................................................................... 0.1%

5.6 The results of the inclining test shall be executed as the report and submitted to the Register for review. Based on the positive results of the review, the Register representative signs and stamps the front page of the record with the surveyor's seal.

5.7 The model form recommended for the inclining test record is given in Appendices 4-1 — 4-13.
5.8 When during the test the plot to monitor measurements was not kept, then the record shall contain the assessment of the inclining test performance in accordance with 1.5.9, Part IV "Stability" of the Rules for the Classification and Construction.

5.9 All calculations performed during the inclining test and in preparation of an inclining test report may be carried out by a suitable computer program. Output generated by such a program may be used for presentation of all or partial data and calculations included in the test report if it is clear, concise, well documented, and generally consistent in form and content with the form given in 5.7.

5.10 The record shall be translated into English for ships engaged in international voyages.

6 PROCESSING OF INCLINING TEST RESULTS

6.1 The measurements made in the inclining test and ship’s service documentation are assumed as the initial data in the processing of inclining test results.

6.2 The ship’s sag is taken into account by any reasonably precise way in calculating the displacement and z-coordinate of the centre of gravity.

6.3 The displacement and coordinates of the centre of gravity are determined depending on a value of trim.

6.4 The displacement and coordinates of the centre of gravity are determined from the following formulae:

.1 at a trim $\psi < 0,005L$ and the ship’s hull sag below $0,0025L$:

$$\Delta = \gamma V;$$

$$z_g = r + z_c - h_k;$$

$$x_g = x_c + R \tan \psi;$$

$$y_g = h_k \tan \theta_0;$$

where $\Delta$ = weight displacement of the ship, in t;
$\gamma$ = water density, in t/m$^3$;
$V$ = water content, in m$^3$;
$r$ = transverse metacentric radius, in m;
$h_k$ = transverse metacentric height in conditions of the inclining test, in m;
$x_c, z_c$ = coordinates of the ship’s centre of buoyancy, in m;
$x_g, y_g, z_g$ = coordinates of the ship’s centre of gravity, in m;
$R$ = longitudinal metacentric radius, in m;
$\theta_0$ = initial angle of heel, in deg.

Theoretical elements are determined by use of hydrostatic curves;

.2 at a trim $\psi \geq 0,005L$, or the ship’s hull sag $\geq 0,0025L$:

$$\Delta_\psi = \theta_0 V_\psi;$$

$$z_{g\psi} = z_{c\psi} + (r_\psi - h_k) \cos \psi;$$

$$x_{g\psi} = x_{c\psi} - (r_\psi - h_k) \sin \psi;$$

$$y_{g\psi} = h_k \tan \theta_0.$$  

The values $V_\psi, z_{c\psi}, x_{c\psi}$ and $r_\psi$ are determined with due regard to the trim $\psi$ and ship’s hull bending on the basis of lines drawing and Bonjean curves.
6.5 The metacentric height according to the results of separate measurements of $h_i$, is determined in Table 6.5.

In the inclining test of the floating crane using its own crane, the metacentric height, in m, is determined according to the results of separate measurements by the formula

$$h_i = \frac{(R-r)\psi_i}{\theta_i-\psi_i}.$$  \hspace{1cm} (6.5)

Table 6.5

<table>
<thead>
<tr>
<th>Measurement number</th>
<th>Increment</th>
<th>$h_i$, in m</th>
<th>$h_i - h_k$, in m</th>
<th>$(h_i - h_k)^2$, in m²</th>
</tr>
</thead>
<tbody>
<tr>
<td>I</td>
<td>II</td>
<td>III</td>
<td>IV</td>
<td>V</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>.</td>
<td></td>
<td></td>
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<td>.</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>n</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

6.6 The metacentric height, in m, in the inclining test is determined by the formula

$$h_k = \sum h_i / n.$$ \hspace{1cm} (6.6)

6.7 The displacement and coordinates of the light ship's centre of gravity are determined in Table 6.7. Permanent liquid cargoes, including liquid cargoes remaining in the hull, which are taken into account in the mass loading of a light ship during design, but are lacking on board the ship in the inclining test, shall be considered in processing of the inclining test results as missing cargoes.

Table 6.7

<table>
<thead>
<tr>
<th>Loading</th>
<th>Mass, in t</th>
<th>Arms, in m</th>
<th>Moment, in t·m</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>X</td>
<td>Y</td>
<td>Z</td>
</tr>
<tr>
<td>Ship in inclining test</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Missing cargoes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Redundant cargoes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Light ship</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

7 CALCULATION RESULTS

The light ship elements from the inclining data are presented in comparison with the effective ones.

Table 7

<table>
<thead>
<tr>
<th>Ship's elements</th>
<th>Design values</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>by data of inclining test</td>
</tr>
<tr>
<td></td>
<td>By design (or from the effective Stability Booklet)</td>
</tr>
<tr>
<td>$\Delta$, in t</td>
<td></td>
</tr>
<tr>
<td>$x_p$, in m</td>
<td></td>
</tr>
<tr>
<td>$y_p$, in m</td>
<td></td>
</tr>
<tr>
<td>$z_p$, in m</td>
<td></td>
</tr>
<tr>
<td>$h$, in m</td>
<td></td>
</tr>
<tr>
<td>$d_c$, in m</td>
<td></td>
</tr>
<tr>
<td>$d_a$, in m</td>
<td></td>
</tr>
<tr>
<td>$M_w$, in t·m</td>
<td></td>
</tr>
</tbody>
</table>
INCLINING TEST RECORD

(Place of inclining test)

“___” __________ 20_

1. Ship

Name, hull number __________________________________________________________

Type and purpose __________________________________________________________

Shipyard, year of built ______________________________________________________

Shipowner, port of registry __________________________________________________

Length $L$ _________________________________________________________________

Breadth $B$ ________________________________________________________________

Depth $D$ _________________________________________________________________

2. Organization of inclining test

Purpose of inclining test ____________________________________________________

(after construction, repair, conversion, etc.)

Performers of inclining test: __________________________________________________

Leader _________________________________________________________________ (position, full name)

Participants _____________________________________________________________ (positions, full names)

The Register representative witnessing the inclining test __________________________

________________________________________________________ (full name)

Time period of inclining test:

Started ________ h _________ min

Ended ________ h _________ min

The inclining test has been performed in accordance with __________________________

________________________________________________________ (guidance document)

3. Inclining test conditions

Wind speed ______________________________________________________________ m/s

Current speed ____________________________________________________________ m/s

Water surface state _________________________________________________________

Air temperature __________________________________________________________ °C

Water density _____________________________________________________________ t/m³

Under-keel clearance _____________________________________________________ m

Ice conditions ____________________________________________________________
4. Preparation

4.1 The ship is prepared for the inclining test (refer to Appendices 4.2 — 4.6).

4.2 Scheme of ship positioning. Specified are ship's position and securing, wind and current direction, etc.

4.3 Foreign objects, cargo remains, building waste, snow are removed from the ship. Icing of outside and internal surfaces, the underwater hull inclusive, is absent. Redundant and missing cargoes are taken into account (refer to Appendices 4.2 and 4.3).

<table>
<thead>
<tr>
<th>Cargoes including liquid ones</th>
<th>Percentage of light displacement</th>
<th>Mass, in t</th>
<th>Arms, in m</th>
<th>Moments, in t·m</th>
</tr>
</thead>
<tbody>
<tr>
<td>Redundant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Missing</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

4.4 The effect of free surfaces of liquid cargoes and running machinery on inclining test performance has been practically prevented.

4.5 Service documentation used in the inclining test

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Name</th>
<th>Document No.</th>
<th>Performer</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

4.6 The solid ballast __________________________________ is placed in the ship.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Location</th>
<th>Mass, in t</th>
<th>Coordinates, in m</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>X from middle</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Y from central plane</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Z above base line</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>In all</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

4.7 The metacentric height assured is about ____________m.

Liquid ballast taken therewith is ____________t (refer to Appendix 4.4).

4.8 The following requirement concessions are admitted in the inclining test

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Concession nature</th>
<th>Concession reasoning</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
5. Inclining test

5.1 The draughts and freeboard taken into account (refer to Appendix 4-7).

<table>
<thead>
<tr>
<th>Place of measurement</th>
<th>Draught, in cm</th>
<th>Freeboard, in cm</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frame No.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The ship's hull sag in the inclining test is ______________ mm (refer to Appendix 4-7).

5.2 In measurements of angles of heel, mooring lines were slackened and the ship was free to list.

5.3 Heeling moments and angles of heel taken into account (refer to Appendices 4-5 and 4-8).

Notes: 1. Signatures in copies of the inclining test record shall be confirmed by the tracing holder if signing the materials tracings on the spot is impractical.

2. Appendices 4-2 and 4-13 are the integral part of the inclining test record.

<table>
<thead>
<tr>
<th>Measurement Nos.</th>
<th>test weight mass, in t</th>
<th>Movement arms, in m</th>
<th>Increment of heeling moment II×III, in t·m</th>
<th>Increment of angle of heel, in deg./rad.</th>
</tr>
</thead>
<tbody>
<tr>
<td>I</td>
<td>II</td>
<td>III</td>
<td>IV</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>VI</td>
</tr>
<tr>
<td></td>
<td>1</td>
<td>2</td>
<td></td>
<td>VI</td>
</tr>
<tr>
<td></td>
<td></td>
<td>.</td>
<td></td>
<td>VII</td>
</tr>
<tr>
<td></td>
<td>.</td>
<td>.</td>
<td></td>
<td>VIII</td>
</tr>
<tr>
<td></td>
<td>n</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Pendulum bob (device) No. 1
Pendulum bob (device) No. 2
Pendulum bob No. 3

5.4 To measure the rolling period, the ship was swung with a __________ of __________ t in mass. (load)

The rolling period of the ship in the inclining test \( \tau = \) __________ s (refer to Appendices 4-8 and 4-11).

6. Remarks

(at the discretion of the inclining test leader)

7. Processing of inclining test results

The inclining test results are processed by __________________________

(name of the enterprise being the tracing holder of inclining test materials)
8. Conclusions

The inclining test performance is satisfactory.

The following actual data of the light ship are considered to be ascertained resulting the inclining test:

displacement $\Delta_0 = \underline{\phantom{0000}}$ t;

$z$-coordinate of the centre of gravity $z_g = \underline{\phantom{0000}}$ m;

abscissa of the centre of gravity $x_g = \underline{\phantom{0000}}$ m.

Leader of the inclining test ____________________________ (full name)

Participants of the inclining test ____________________________ (full name)

Surveyor witnessing the inclining test ____________________________ (full name)
### LIST OF REDUNDANT CARGOES

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Cargo</th>
<th>Mass, in t</th>
<th>Arms, in m</th>
<th>Moments, in t·m</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>$X$ from middle</td>
<td>$Y$ from central plane</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

In total:

List executed by ____________________________  (full name)
**LIST OF MISSING CARGOES**

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Cargo</th>
<th>Mass, in t</th>
<th>Arms, in m</th>
<th>Moments, in t·m</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>(X) from middle</td>
<td>(Y) from central plane</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**In total:**

List executed by _________________________________________________________________

(full name)
APPENDIX 4-4

Ship ________________________________
“” “” 20

LIQUID CARGOES STATE REPORT

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Name</th>
<th>Liquid type</th>
<th>Mass, int</th>
<th>Arms, in m</th>
<th>Moments, in tm</th>
<th>Weight group</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X from middle</td>
<td>Y from central plane</td>
<td>Z above base line</td>
</tr>
<tr>
<td>1</td>
<td>Tank No.</td>
<td>Drinking water</td>
<td></td>
<td></td>
<td>M_x M_y M_z</td>
<td>Redundant cargo</td>
</tr>
<tr>
<td>2</td>
<td>Tank No.</td>
<td>Lube oil</td>
<td></td>
<td></td>
<td></td>
<td>Ditto Light ship</td>
</tr>
<tr>
<td>3</td>
<td>Liquid cargo remains in the hull¹</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Ditto Missing cargo</td>
</tr>
<tr>
<td>4</td>
<td>Liquid cargoes in machinery, installations, systems, piping ensuring their operational condition¹</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Water in the swimming pool</td>
<td>Sea water</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Liquid ballast</td>
<td>Ditto</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

In total:
redundant cargoes
missing cargoes

¹ To be specified design data.

The metacentric height of about ________m is assured by ballast as per item 6 of Table.

Tanks Nos. _________ are fully pressed up to a top of air pipes. Valves of service lines are closed and sealed.

Report is executed by ________________________________ (full name)
Guidelines on Technical Supervision of Ships under Construction (Section 2)

APPENDIX 4-5

REPORT ON AVAILABILITY AND TEST WEIGHT TRANSFER

1. Test weight __________________ is weighed on a balance rated at __________ kg with precision (to be specified) measurements of __________ kg.

The balance and balance weights have passed the calibration test on "___" __________ 20 ___.

<table>
<thead>
<tr>
<th>Group</th>
<th>Mass, in kg</th>
<th>Centre of gravity coordinates, in m</th>
<th>Number of test weight units</th>
<th>Marking</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>X from middle</td>
<td>Y from central plane</td>
<td>Z above base line</td>
</tr>
</tbody>
</table>

2. Test weight is arranged in the __________ according to the scheme (ship's name)

The design and shape of test weight ensure its proper securing and determining the coordinates of its centre of gravity.

3. Sequence of test weight transfer.

<table>
<thead>
<tr>
<th>Indices</th>
<th>Movements</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 2 3 4 5 6 7 8 n</td>
<td>P 24 4 - 1 13 123 1234 234 24 -</td>
</tr>
<tr>
<td>S 13 123 1234 234 24 - 1 13 -</td>
<td></td>
</tr>
<tr>
<td>Arms, in m</td>
<td>a_2 a_4 -a_1 -a_2 -a_4 a_4 a_3 a_3</td>
</tr>
</tbody>
</table>

Report is executed by ____________________________________________________________ (full name)
**APPENDIX 4-6**

Ship ___________________________________________________________________

" " __________ 20 ___________________________________________________________________

**DEVICES AVAILABILITY REPORT**

For inclining test performance, the devices approved by ________________________________

(organization and document) 

_____________________________ are prepared and their type is _______________________________

The devices are in good repair, fitted in the ship and ready for operation according to the instruction. The calibration of devices is carried out immediately before the inclining test, which results are given in Table.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Manufacturer of device</th>
<th>Hull No.</th>
<th>Interim specification for supply</th>
<th>Scale of records</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>by certificate</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>by calibration</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>angles, in mm/deg.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>angles, in mm/deg.</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Report is executed by ________________________________

(full name)

Surveyor witnessing calibration ________________________________

(full name)
DRAUGHTS AND FREEBOARD MEASUREMENTS REPORT

1. Measurements are made with use of ____________________________ (gadget)

<table>
<thead>
<tr>
<th>Place of measurement</th>
<th>Time of measurement</th>
<th>Reading level</th>
<th>Draught by mark, in cm</th>
<th>Measurement from mark (deck), in cm</th>
<th>Measurement value, in cm</th>
<th>Correction (thickness of keel or deck stringer)</th>
<th>Theoretical value, in cm</th>
<th>Theoretical mean value, in cm</th>
<th>Design value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>P S 4-5 S 4-6</td>
<td></td>
<td></td>
<td>P S 4-5 S 4-6</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Draught</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fore frame No.</td>
<td>Prior to inclining</td>
<td>Mark 30</td>
<td>20 22</td>
<td>22 280 278 278</td>
<td>2 278 276 276</td>
<td>277 275</td>
<td>276 275 276 276</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>After inclining</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Middle frame No.</td>
<td>Prior to inclining</td>
<td>Loadline mark</td>
<td>400</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>After inclining</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stern frame No.</td>
<td>Prior to inclining</td>
<td>Mark 34</td>
<td>340</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>After inclining</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Freeboard</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frame No.</td>
<td>Prior to inclining</td>
<td>Upper deck</td>
<td>229 228 227 224</td>
<td>2 227 226 225 222 226 224 225</td>
<td>225</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>After inclining</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frame No.</td>
<td>Prior to inclining</td>
<td>Upper deck</td>
<td>228 224</td>
<td>2</td>
<td>2 227 226 225 222 226 224 225</td>
<td>225</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>After inclining</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

2. Design values of draughts and freeboard are plotted on ____________________________ (drawing)

3. Resulting measurements, the ship's sag in the inclining test was ____________mm.

4. Water density sampled at a depth of ____________m was ____________t/m³.

Report is executed by ____________________________________________________ (full name)
**REPORT ON PENDULUM DEFLECTION MEASUREMENTS**

Pendulum No. 1 (2,3). Their locations ________________________________

Length of the pendulum $\lambda = \underline{\text{______________}}$ mm.

<table>
<thead>
<tr>
<th>Measurement No.</th>
<th>Pendulum deflections, in mm</th>
<th>Sum $\frac{i}{\Sigma}$</th>
<th>Pendulum reading, $b = \Sigma_i$</th>
<th>Angle of heel, $\theta = \frac{b}{\lambda}$, in rad.</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>S P S P S P S P</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>1 2 3 4 5 6 i – 1</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Measurements are executed by ________________________________ (full name)

<table>
<thead>
<tr>
<th>Measurements</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of full oscillations</td>
<td>$k$</td>
<td>5</td>
<td>6</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Period by inclinograph</td>
<td>$b$ mm</td>
<td>$t_1 = \frac{b}{m_2}$ s</td>
<td>$\tau_1' = \frac{t_1}{k}$ s</td>
<td>$\Sigma \tau_1'$</td>
<td>$\tau' = \Sigma \tau_1'/n$</td>
</tr>
<tr>
<td>Period by stopwatch</td>
<td>$t_2$ s</td>
<td>$t_2'' = \frac{t_2}{k}$ s</td>
<td>$\Sigma t_2''$</td>
<td>$t'' = \Sigma t_2''/n$</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th></th>
<th>$\Sigma t_1'$</th>
<th>$\tau' = \Sigma t_1'/n$</th>
<th>$t = \tau' + t''$</th>
</tr>
</thead>
</table>

Recording and heeling table processing by ________________________________ (full name)

Witnessing surveyor ________________________________ (full name)
PLOT OF ON-LINE CONTROL OVER INCLINING TEST

Leader of inclining test (full name)
**HEELING TABLE 1 (2, 3)**

Inclinograph ser. No.

<table>
<thead>
<tr>
<th>Measurements</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Heel</td>
<td>a, in mm</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$\theta^o = a/m_i$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Member of commission**

(full name)

**Register representative**

(full name)
REPORT ON ROLLING PERIOD MEASUREMENTS

<table>
<thead>
<tr>
<th>Swinging</th>
<th>1st observer</th>
<th>2nd observer</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Number of full oscillations $k$</td>
<td>Total time $t$, in s</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sum</td>
<td></td>
<td>$\Sigma\tau$</td>
</tr>
<tr>
<td>$\tau_{an} = \Sigma\tau/n$</td>
<td>$\tau_1$</td>
<td>$\tau_{design} = \frac{\tau_1 + \tau_2}{2}$</td>
</tr>
</tbody>
</table>

Report is executed by:
1st observer ________________________________________________
(full name)
2nd observer ________________________________________________
(full name)
APPENDIX 4-12

CALCULATION OF SHIP’S ELEMENTS FROM INCLINING TEST DATA

Ship

_________________________________________________

Guidelines on Technical Supervision of Ships under Construction (Section 2)

164
EXAMPLES OF RECORDS MADE WITH INCLINOGRAPH

Good record and its correct processing

Record distorted due to side-to-side liquid flow

Record displays the presence of an obstacle for free oscillations of the ship or device pendulum (see the record of the 2nd and 3rd runnings across the ship)

Record displays the reduced number of people running across the ship (distance between the axes of the 1st and 3rd runnings across the ship is drastically reduced)
INSTRUCTIONS ON LIGHT-WEIGHT CHECK

1 GENERAL

1.1 A light-weight check of a ship means determining the light-ship weight and its longitudinal centre of gravity on the basis of ship survey and draught measurements.
1.2 Preparations for light-weight check and its performance shall be carried out in compliance with instructions on light-weight check developed in advance and reviewed by the Register. The instructions shall contain the particulars given in 3.1.1, 3.1.2, 3.1.5, 3.1.7, 3.1.8 of Appendix 4.
1.3 The light-weight check shall be witnessed by the Register representative.
1.4 The waters in the area where the light-weight check is conducted shall be free from floating objects and ice which might restrict draught measurements. The depth of water under the keel shall not be less than 0.5 m.
1.5 The light-weight check shall be carried out in calm weather, in a sheltered area. Conduct of a light-weight check under icing is not permitted.

2 PREPARATIONS FOR LIGHT-WEIGHT CHECK

2.1 The ship shall drift freely or be held by lines. Mooring lines, hoses and power lines connected to the ship shall be slack. The access ramps shall be removed.
2.2 The angle of heel shall not exceed 1°.
2.3 The ship's metacentric height at the time of the light-weight check shall be positive.
2.4 Cargo in the holds is not permitted. The number of missing items and surplus items, which weight and coordinates of the centre of gravity can be accurately determined, is unrestricted at the time of the light-weight check. Where this is impracticable, the surplus items shall be removed from the ship, and the missing items, loaded on board the ship.
2.5 The equipment, outfit, spares, etc., shall be in their regular positions.
2.6 The chance of the liquid cargoes carried on board the ship flowing (transferring) from tank to tank shall be excluded. Pipeline valves shall be closed and sealed.
2.7 Technical documentation to establish the weight and location of the surplus and missing items shall be in place prior to the light-weight check.
2.8 Any unwanted objects, debris, snow, ice, etc., shall be removed from the ship.
2.9 A light-weight check can be conducted with auxiliary machinery running, provided this does not impair the check results.
2.10 The persons involved in the light-weight check shall be briefed and efficient communications between those involved in the check provided.
2.11 Prior to the light-weight check, lists of surplus and missing items shall be drawn up, with indication of their name, location, weight and coordinates of the centre of gravity. The lists shall be approved by the person in charge of the check and submitted to the Register representative. The inspection of the ship shall be carried out by the board and the Register representative prior to the check shall verify that the lists mentioned above are complete, and the ship properly prepared.
2.12 Instructions of the person in charge shall be followed for commencing and completing the light-weight check.
3 LIGHT-WEIGHT CHECK

3.1 Measurements of the ship's draughts shall be performed by draught marks and by freeboard readings to be taken in at least 5 locations over the length of the ship. A report on draught measurement results shall be drawn up.

3.2 In case of discrepancy between the ship's draughts obtained from draught marks and those obtained from freeboard readings, the freeboard readings shall be authoritative.

3.3 The specific gravity of the water shall be determined on the basis of a sample taken from a depth equal to half the mean draught of the ship at the time of the light-weight check.

3.4 The deflection of the ship may be taken into account when calculating the displacement using any method of adequate accuracy.

3.5 The ship's displacement at the time of the test and the abscissa of its centre of gravity are determined depending on the ship's hull trim and bending in accordance with the requirements in 6.4 of Appendix 4. In this case, $x_g \psi$ shall be determined by the formula

$$x_g \psi = x_c \psi - (z_g - z_c) \sin \psi$$

where $z_g$ = $z$-coordinate of the ship's centre of gravity in test conditions computed on the basis of the data of the effective Stability Booklet.

3.6 The displacement and the longitudinal centre of gravity of a light ship at light-weight check shall be determined according to Table 3.6.

<table>
<thead>
<tr>
<th>Load</th>
<th>Weight, in t</th>
<th>Longitudinal centre of gravity, in m</th>
<th>Moment, in t•m</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ship during check Missing items Surplus items</td>
<td>$x$</td>
<td>$M_x$</td>
<td></td>
</tr>
</tbody>
</table>

3.7 In preparation and during the light-weight check readings shall be accurate to the following:

draught................................................................. 10 mm;
freeboard................................................................ 10 mm.

3.8 The recommended form of the Report is given in the Annex to these Instructions.

3.9 The results of the light-weight check shall be executed as the report and submitted to the Register for review. Based on the positive results of the review, the Register representative signs and stamps the front page of the record with the surveyor's seal.

3.10 If the ships are engaged on international voyages, the report shall be translated into English.
Annex to the Instructions on Light-Weight Check
LIGHT-WEIGHT CHECK REPORT

No. __________ "___" ______________ 20 ___.

1 Ship particulars

1.1 Name.
1.2 Type.
1.3 Builder.
1.4 Hull number.
1.5 Year of build.
1.6 RS number.
1.7 IMO number.
1.8 Port of registry.
1.9 Principal dimensions.

2 Organization and conditions of light-weight check

2.1 Location of check (country, port).
2.2 Date and time of check.
2.3 Person in charge and check performers (names, positions).
2.4 The RS surveyor witnessed the check (name position).
2.5 Area and weather conditions:
   .1 name of area;
   .2 current speed;
   .3 condition of water surface;
   .4 ice conditions;
   .5 temperature of water;
   .6 specific gravity of water;
   .7 minimum depth under keel;
   .8 wind speed.
2.6 Preparation of the ship for light-weight check:
   .1 brief description of the ship's condition;
   .2 initial heel of ship;
   .3 mooring lines (type, number, method of attachment).

3 Light-weight check

3.1 The ship's draughts by draught marks (Table 3.1).

<table>
<thead>
<tr>
<th>Name</th>
<th>Draughts by draught marks</th>
<th>Draughts at marks $d_{\text{mean}}$</th>
<th>Draughts at perpendiculares</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>PS</td>
<td>SB</td>
<td>–</td>
</tr>
<tr>
<td>Draught forward, mm</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Draught aft, in m</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Draught amidships, in m</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
3.2 Ship's draughts by freeboard readings (Table 3.2).

<table>
<thead>
<tr>
<th>Locations of freeboard readings, in ft</th>
<th>Freeboard values, in m</th>
<th>Averaged freeboard values, in m</th>
<th>Moulded draughts at perpendiculars and amidships</th>
</tr>
</thead>
<tbody>
<tr>
<td>PS</td>
<td>SB</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The following values of draughts are assumed for the calculation:

\[ d_f = \]
\[ d_u = \]
\[ d_{\text{mean}} = \]

3.3 Calculation of displacement and hydrostatic components (computer printout attached).

3.4 Missing items.
The following missing items are assumed for the calculation (Table 3.4).

<table>
<thead>
<tr>
<th>Identification of items</th>
<th>Weight</th>
<th>Longitudinal centre of gravity, ( X_g )</th>
<th>Moment, ( M_x )</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>in t</td>
<td>in m</td>
<td>in tm</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>( n )</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>In total:</td>
<td>( \Sigma P )</td>
<td></td>
<td>( \Sigma M_x )</td>
</tr>
</tbody>
</table>

3.5 Surplus items.
The following surplus items are assumed for the calculation (Table 3.5).

<table>
<thead>
<tr>
<th>Identification of items</th>
<th>Weight</th>
<th>Longitudinal centre of gravity, ( X_g )</th>
<th>Moment, ( M_x )</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>in t</td>
<td>in m</td>
<td>in tm</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>( n )</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>In total:</td>
<td>( \Sigma P )</td>
<td></td>
<td>( \Sigma M_x )</td>
</tr>
</tbody>
</table>

3.6 Permanent solid cargo having a weight of \( \underline{\text{__________}} \) t is carried on board the ship, stowed according to sketch \( \underline{\text{__________}} \).

3.7 The design metacentric height \( h \) was \( \underline{\text{______}} \) m at the time of the light-weight check.
3.8 The following departures from the present Instructions were made during the light-weight check (Table 3.8):

<table>
<thead>
<tr>
<th>No.</th>
<th>Nature of departures</th>
<th>Explanation of departures</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 3.8

3.9 Determination of the light-ship displacement and the ship's longitudinal centre of gravity on the basis of light-weight check (Table 3.9).

<table>
<thead>
<tr>
<th>Load</th>
<th>Weight</th>
<th>Longitudinal centre of gravity, ( X_g )</th>
<th>Moment, ( M_x )</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ship during check</td>
<td>in t</td>
<td>in m</td>
<td>in tm</td>
</tr>
<tr>
<td>Missing items</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Surplus items</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Light ship</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 3.9

4 CONCLUSION

The light-weight check of the ship was conducted in accordance with the Register Instructions on Light-Weight Check.

The following experimental data were obtained for the lightship based on the results of the light-weight check:
- displacement ________;
- longitudinal centre of gravity ________ m forward (aft) of the midship section (after perpendicular).

Signed:
Person in charge of light-weight check______________________________
(signature; name)

Board members______________________________________________
(signature; name)

Surveyor to the Register________________________________________
(signature; name)
TESTING OF MODU HULL STRUCTURES FOR TIGHTNESS

<table>
<thead>
<tr>
<th>No.</th>
<th>Structure</th>
<th>Tests methods and standards</th>
<th>Additional instructions</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Compartments of lower hulls (pontoons) of semisubmersible MODU¹</td>
<td>Flood test by filling with water up to the top of air pipe</td>
<td>–</td>
</tr>
<tr>
<td>2</td>
<td>Braces and cross ties of semi-submersible MODU submerging at the maximum draught</td>
<td>Air pressure test under over-pressure of 0.03 MPa</td>
<td>–</td>
</tr>
<tr>
<td>3</td>
<td>Compartments of stability columns of semi-submersible and submersible MODU below the MODU margin line¹</td>
<td>Flood test by filling with water up to the top of air pipe</td>
<td>–</td>
</tr>
<tr>
<td>4</td>
<td>Compartments of stability columns of semisubmersible and submersible MODU above the MODU margin line:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4.1</td>
<td>dry</td>
<td>Hose test by water jet under pressure</td>
<td>–</td>
</tr>
<tr>
<td>4.2</td>
<td>intended for different liquids¹</td>
<td>Flood test by filling with water up to the top of air pipe</td>
<td>–</td>
</tr>
<tr>
<td>5</td>
<td>Legs of self-elevating MODU</td>
<td>Air pressure test under over-pressure of 0.03 MPa</td>
<td>Other testing methods may be used for continuous-walled tubular columns as upon agreement with the Register</td>
</tr>
<tr>
<td>6</td>
<td>Tanks for legs of self-elevating MODU¹</td>
<td>Flooding to the head equal to the pressure inside the tank blowing system</td>
<td>–</td>
</tr>
<tr>
<td>7</td>
<td>Jack house enclosed cavities for legs</td>
<td>Air pressure test under over-pressure of 0.03 MPa</td>
<td>–</td>
</tr>
<tr>
<td>8</td>
<td>Integral tanks with chemicals for drilling and cement grouts¹</td>
<td>Flood test by filling with water up to the top of air pipe</td>
<td>–</td>
</tr>
<tr>
<td>9</td>
<td>Tanks for oil collection when testing a well¹</td>
<td>Flood test by filling with water up to the top of air pipe</td>
<td>–</td>
</tr>
<tr>
<td>10</td>
<td>Integral tanks for drilling grout¹</td>
<td>Flood test by filling with water up to the top of air pipe</td>
<td>–</td>
</tr>
</tbody>
</table>

¹ Structural tests shall be performed for at least one tank of the same construction (i.e. the tanks of the same structural design and configuration and same workmanship) on each MODU/FOP, provided all subsequent tanks shall be subjected to air test. However, where structural adequacy of a tank was verified by structural testing on the prototype MODU/FOP, the subsequent MODU/FOP in series (i.e. sister MODU/FOP built at the same shipyard) may be exempted from such testing for other tanks, which have the same structure as the tested tank, provided that the watertightness in all boundaries of exempted tanks are verified by leak tests and thorough examination. In any case, structural testing shall be carried out for at least one tank for each MODU/FOP in order to verify structural adequacy.
### APPENDIX 7

**PERMISSIBLE DIMENSIONAL AND GEOMETRICAL DEVIATIONS DURING MANUFACTURE OF MODU WELDED HULL MEMBERS AND STRUCTURES**

<table>
<thead>
<tr>
<th>MODU hull structures</th>
<th>Deviation</th>
<th>Main dimension</th>
<th>Direction of measured section</th>
<th>Permissible value of deviation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Leg tanks, jack houses of legs and drilling derrick</td>
<td>Skewness as a distortion of inclination angle between flanges and web:</td>
<td>Face plate width $b$</td>
<td>Across the girder</td>
<td>0,01$b$ but not less than 4 mm</td>
</tr>
<tr>
<td></td>
<td>in midsections</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>in end sections</td>
<td></td>
<td></td>
<td>0,01$b$ but not less than 2 mm</td>
</tr>
<tr>
<td>Ditto</td>
<td>Shrinkage distortion of face plates:</td>
<td>Face plate width $b$</td>
<td>Across the girder</td>
<td>0,05$b$</td>
</tr>
<tr>
<td>Ditto</td>
<td>girder with transverse stiffeners</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ditto</td>
<td>girder without transverse stiffeners</td>
<td></td>
<td></td>
<td>0,025$b$</td>
</tr>
<tr>
<td>Ditto</td>
<td>Bulge of webs</td>
<td>Bulge height $h$</td>
<td>Across the girder</td>
<td>0,002$h$</td>
</tr>
<tr>
<td>Ditto</td>
<td>Deflection of grillage between brackets and bulge between stiffeners</td>
<td>Distance between brackets/ stiffeners $S$</td>
<td>Any plane</td>
<td>0,0005$S$</td>
</tr>
<tr>
<td>Truss legs</td>
<td>Deviation of truss components centrelines from design geometrical lines</td>
<td>$-$</td>
<td>Ditto</td>
<td>$\pm$ 5 mm</td>
</tr>
<tr>
<td>Ditto</td>
<td>Deflection of rods between truss units</td>
<td>Rod length $l$</td>
<td>Ditto</td>
<td>0,001$l$</td>
</tr>
<tr>
<td>Ditto</td>
<td>Mutual displacement of cross-bar pipe axes and racks with braces</td>
<td>$-$</td>
<td>$-$</td>
<td>0,1 mm/m</td>
</tr>
<tr>
<td>Continuous walled tubular legs</td>
<td>Column diameter deviation</td>
<td>$-$</td>
<td>$-$</td>
<td>$\pm$ 5 mm</td>
</tr>
<tr>
<td>Ditto</td>
<td>Deviation of centreline from design geometrical line</td>
<td>$-$</td>
<td>$-$</td>
<td>0,5 mm/m</td>
</tr>
<tr>
<td>Legs</td>
<td>Deviation of rack end section from horizontal plane (flatness deviation)</td>
<td>$-$</td>
<td>$-$</td>
<td>5 mm/m</td>
</tr>
<tr>
<td>Ditto</td>
<td>Rack deflection</td>
<td>$-$</td>
<td>Any plane</td>
<td>1 mm/m</td>
</tr>
<tr>
<td>Stability columns</td>
<td>Column radius deviation</td>
<td>$-$</td>
<td>$-$</td>
<td>$\pm$ 4 mm</td>
</tr>
<tr>
<td>Ditto</td>
<td>Obliqueness between column vertical axis and base</td>
<td>$-$</td>
<td>$-$</td>
<td>0,5 mm/m</td>
</tr>
<tr>
<td>Braces and cross ties</td>
<td>Length deviation</td>
<td>Brace/cross tie length $l$</td>
<td>$-$</td>
<td>$\pm$ 0,0005$l$</td>
</tr>
</tbody>
</table>
### RECOMMENDATORY SAMPLE — CABLE TRANSIT SEAL SYSTEM REGISTER

<table>
<thead>
<tr>
<th>Название судна</th>
<th>IMO/IMO №</th>
<th>Место</th>
<th>Дата</th>
<th>Проверено</th>
</tr>
</thead>
<tbody>
<tr>
<td>GIA-07-1047-000-883</td>
<td>TT-MCT-011</td>
<td>C</td>
<td>d = 50 x</td>
<td>NVD</td>
</tr>
<tr>
<td>GIA-07-1047-000-883</td>
<td>TT-MCT-012</td>
<td>C</td>
<td>450 x 200 x</td>
<td>NVD</td>
</tr>
<tr>
<td>GIA-07-1047-000-883</td>
<td>TT-MCT-013</td>
<td>C</td>
<td>550 x 200 x</td>
<td>NVD</td>
</tr>
</tbody>
</table>

**ПРОХОД / TRANSIT**
- **Идентификационный номер (ID)/Drawing number**
- **Расположение/Location**
- **Марка/BRAND**
- **Корпус/FRAME**
- **Тип/Type**
- **Модуль/Modulus**
- **Размер/Size**
- **Состояние (хорошее, удовлетворительное, плохое)/Condition (Good, Fair, Poor)**
- **Ремонт выполнен/Repaired**
- **Изменено/Modified**
- **Техническое обслуживание выполнено/Maintained**

**ПРИМЕЧАНИЯ/NOTES**
- C — Compound (not known brand)/уплотнитель (марка неизвестна)
- R — Smith blocks/блоки Смита
- B — MCT Williams/многокабельные проходы (МКП) Вильямс
- H — Heavy corrosion/сильная коррозия
- N = Nelson, Terasaki/ (МКП) Терасаки
- MB = Mixed brands/разные марки
- MM = Mixed modulus sizes/разные размеры модуля
- NVD = No Visible Defects/без видимых дефектов
- CPA = Checkpoints rectangular frame/контрольная точка на прямоугольном корпусе
- CPB = Checkpoints round frames/контрольная точка на круглом корпусе

**Дата/DATE**
- Проверено/Checked by
<table>
<thead>
<tr>
<th>GIA-07-1047-000-B83</th>
<th>TT-MCT-014</th>
<th>C</th>
<th>750 x 200</th>
<th>x</th>
<th>Open, drilled hole not closed</th>
<th>PTO</th>
<th>26/02/2015</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
3 EQUIPMENT, ARRANGEMENTS AND OUTFIT

3.1 GENERAL

3.1.1 This Section specifies the scope and procedure of technical supervision during installation and testing of the ship equipment, arrangements and outfit.

3.1.2 General provisions for the organization of the technical supervision are given in Section 1.

3.1.3 Technical documentation.

3.1.3.1 Installation and testing of the equipment, arrangements and outfit shall be performed under the Register technical supervision according to the RS-approved technical documentation.

3.1.4 Technical supervision of the Register.

3.1.4.1 Surveys during installation and testing of the equipment, arrangements and outfit shall be performed according to the examination and testing plan developed by the shipyard according to 3.2.1 based on Table 3.1.4.1, taking into account 3.3.

Table 3.1.4.1

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Verification of technical documentation</th>
<th>Installation on board ship</th>
<th>Control</th>
<th>Mooring trials</th>
<th>Sea trials</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>marking, branding</td>
<td>of installation and arrangement onboard</td>
<td>of fixing dimensions</td>
<td>in operation</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Rudder and steering gear:</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>1.1</td>
<td>rudder stocks, including their flanges</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.2</td>
<td>rudder axles including their flanges</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.3</td>
<td>rudder blade and steering nozzle in assembly</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.4</td>
<td>rudder and steering nozzle pintles</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.5</td>
<td>pintle bushes</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.6</td>
<td>rudder stock bearings</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.7</td>
<td>parts of connections: rudder stocks, rudder stock with rudder blade, with steering nozzle; rudder axle with stemframe; tiller or quadrant with rudder stock</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.8</td>
<td>tillers, rudder quadrants</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.9</td>
<td>rudder, steering nozzle stops and their parts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.10</td>
<td>parts of spindle drive of steering gears</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.11</td>
<td>steering chains</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.12</td>
<td>active means of ship's steering2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Anchor arrangements:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.1</td>
<td>anchors</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.2</td>
<td>chain cables and parts of their securing of 13 mm and over in diameter</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.3</td>
<td>anchor stoppers</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.4</td>
<td>device for releasing the inboard end of the chain cable or rope</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.5</td>
<td>anchor hawses3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Mooring arrangements:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.1</td>
<td>bollards, cleats, fairleaders, rollers and stoppers</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.2</td>
<td>Ropes and joining shackles</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>Towing arrangements:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4.1</td>
<td>3rd, bollards, fairleads, rollers and stoppers</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Guidelines on Technical Supervision of Ships under Construction (Section 3)

<table>
<thead>
<tr>
<th>No.</th>
<th>Item of technical supervision</th>
<th>Installation on board ship</th>
<th>Mooring trials</th>
<th>Sea trials</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Verification of</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>technical documentation</td>
<td>marking, branding</td>
<td>of installation and arrangement on board</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>low hooks and towing rails with fastenings for securing these parts to ship's hull, tow line releasing device</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3</td>
<td>snatch-blocks</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4</td>
<td>towing rails</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>5</td>
<td>emergency towing arrangement</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>6</td>
<td>metal, wooden and glass reinforced plastic masting, fixed gear of masts and their standing rigging</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>7</td>
<td>loose gear of standing rigging</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>8</td>
<td>Openings in hull, 1st and 2nd tiers of superstructures and deckhouses and their closing appliances</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>9</td>
<td>side and flush deck scuttles (deckhouse windows), round and square</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>10</td>
<td>doors in outside plating</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>11</td>
<td>outside doors in superstructures and deckhouses</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>12</td>
<td>covers of companionways and ventilation trunk</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>13</td>
<td>ventilators</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>14</td>
<td>covers of tank manholes</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>15</td>
<td>doors in main watertight bulkheads</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>16</td>
<td>hatch covers of dry cargo holds, holds fitted for alternate carriage of liquid in bulk and dry cargoes, tweendecks, covers of cargo tanks</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>17</td>
<td>Equipment of spaces:</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>18</td>
<td>ceiling, battens, lining of cargo holds</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>19</td>
<td>doors in ship's spaces on escape routes</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>20</td>
<td>stairways and vertical ladders</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>21</td>
<td>guard rails, bulwark and gangways</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>22</td>
<td>guiding fittings in holds of container carriers</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>23</td>
<td>devices for securing movable decks, platforms, ramps and similar structures in non-working position</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>24</td>
<td>low-location lighting systems (photoluminescent, electrically powered)</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>25</td>
<td>Arrangements for securing of timber deck cargo (strengthened bulwark or guard railing, sockets or other fittings for uprights, joint rings, lashings)</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>26</td>
<td>items made of ropes for all applications</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>27</td>
<td>Emergency outfit:</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>28</td>
<td>soft collision mats, rigid collision mats with outfit</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>29</td>
<td>tools of emergency outfit</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>30</td>
<td>materials of emergency outfit</td>
<td>+</td>
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<td>+</td>
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<tr>
<td>31</td>
<td>Hoisting gear for shipborne barges</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
</tbody>
</table>

1. According to the approved program.
2. Refer to 3.3.1.4.
3. Supervision is performed according to Section 2.
4. The RS supervision of the drives is performed according to Sections 6 and 10, if uncovering and covering of openings is carried out both in ports and at sea.
5. Ship's List of Supplies.
3.1.5 Tests and checks specified in this Section are based on an assumption that the arrangements, equipment and outfit have been tested at the firm (manufacturer) in compliance with the requirements of Section 3, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of the arrangements, equipment and outfit in substantiated cases.
3.2 SURVEY PLANNING

3.2.1 Prior to commencement of survey of the arrangements, equipment and outfit of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 3.1.4.1. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1 and with due regard to 3.3.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

3.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

3.2.3 Quality standards for installation and testing of the arrangements, equipment and outfit shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

3.2.4 Any changes to the kick-off meeting records shall be agreed and documented.
3.3 CHECKS AND TESTS

3.3.1 Steering gear.

3.3.1.1 Survey of the steering gear shall be performed according to Table 3.1.4.1.

3.3.1.2 During the mooring trials, the following shall be checked:

.1 operation of the rudder and steering gear by means of continuous putting the rudder from hard over to hard over with alternate actuation of the starboard and port units during a period stated in the approved program of trials taking into account the salient feature of the power unit of the steering gear;

.2 control of the rudder or steering nozzle from the wheel house and other locations by means of changing over the control system, as well as from the steering gear compartment in case of manual control;

.3 capability of the main steering gear to put the rudder over from 35° on one side to 35° on the other side, and that of the auxiliary steering gear to put the rudder over from 15° on one side to 15° on the other side;

.4 operation of the steering gear with two cylinders (in line, adjacent, etc.) functioning, instead of four;

.5 operation of the rudder or steering nozzle stops;

.6 operation of safely valves when the slide block is against the stops fitted on the steering gear. The lift; pressure of the safety valves shall meet the requirements of 6.2.4.1, Part IX “Machinery” of the Rules for the Classification and Construction with due account of the operating instruction for the steering gear;

.7 correctness of the rudder or steering nozzle angle indicator readings as compared to their actual position determined from the dial of the mechanical indicator on the steering gear (refer to 2.9.15, Part III “Arrangements, Equipment and Outfit” of the Rules for the Classification and Construction);

.8 operation of the auxiliary steering gear;

.9 direction of the steering wheel rotation and direction of the rudder or steering nozzle deflection;

.10 power supply systems of the electrical units of the steering gear from the main and emergency sources of electrical power, remote and local control systems, alarm system and the technical condition of the whole electrical equipment in accordance with the requirements of Section 10;

.11 operation of the hydraulic drive in accordance with the requirements of 5.16.7 and 8.3.2.7;

.12 operation of the main and/or auxiliary manually operated steering gear — of spindle, steering rope and other type, including check of their assemblies and components in operation;

.13 possibility of using a rudder tackle and hand tiller on board ships where they may be employed as an auxiliary steering gear;

.14 operation of the braking device;

.15 operation of the torque-limiting clutch when the tiller quadrant is against the stops in case of electric steering gear, check of the clutch adjustment;

.16 intact position of the rudder blade angled to either side with one hydraulic pump in operation, as well as with two hydraulic pumps in parallel operation.

3.3.1.3 During the sea trials, the following shall be checked:

.1 operation of the main steering gear to put continuously the rudder or nozzle rudder over from 35° on one side to 35° on the other side within the time specified in the program of trials approved by the Register, at the deepest seagoing draught and ahead speed, with alternate operation of the starboard and port units, and being controlled alternately from all control stations. Where it is impractical to demonstrate compliance with this requirement during sea trials with the ship at its deepest sea-going draught and running ahead at the speed corresponding to the number of maximum continuous revolutions of the main engine and
maximum design pitch, ships regardless of date of construction may demonstrate compliance with this requirement by one of the following methods:

during sea trials the ship is at even keel and the rudder fully submerged whilst running ahead at the speed corresponding to the number of maximum continuous revolutions of the main engine and maximum design pitch; or

where full rudder immersion during sea trials cannot be achieved, an appropriate ahead speed shall be calculated using the submerged rudder blade area in the proposed sea trial loading condition. The calculated ahead speed shall result in a force and torque applied to the main steering gear which is at least as great as if it was being tested with the ship at its deepest sea-going draught and running ahead at the speed corresponding to the number of maximum continuous revolutions of the main engine and maximum design pitch; or

the rudder force and torque at the sea trial loading condition have been reliably predicted and extrapolated to the full load condition. The speed of the ship shall correspond to the number of maximum continuous revolutions of the main engine and maximum design pitch of the propeller.

On all occasions when trials are conducted with the ship not at the deepest sea-going draught, the loading condition can be accepted on the conditions that either:

- the rudder is fully submerged (at zero speed waterline) and the ship is in an acceptable trim condition;
- the rudder torque at the trial loading condition have been reliably predicted (based on the system pressure measurement) and extrapolated to the maximum sea-going draught condition using the following method to predict the equivalent torque and actuator pressure at the deepest sea-going draught:

\[
Q_F = Q_T \alpha; \tag{3.3.1.3.1-1}
\]

\[
\alpha = 1.25 \left( \frac{A_F}{A_T} \right) \left( \frac{V_T}{V_F} \right)^2 \tag{3.3.1.3.1-2}
\]

where \(\alpha\) = extrapolation factor; 
\(Q_F\) = rudder stock moment for the deepest service draught and maximum service speed condition; 
\(Q_T\) = rudder stock moment for the trial condition;
\(A_F\) = total immersed projected area of the movable part of the rudder in the deepest sea-going condition;
\(A_T\) = total immersed projected area of the movable part of the rudder in the trial condition;
\(V_F\) = contractual design speed of the ship corresponding to the maximum continuous revolutions of the main engine at the deepest sea-going draught;
\(V_T\) = measured speed of the ship (considering current) in the trial condition.

Where the rudder actuator system pressure is shown to have a linear relationship to the rudder stock torque, the above equation can be taken as:

\[
P_F = P_T \alpha \tag{3.3.1.3.1-3}
\]

where \(P_F\) = estimated steering actuator hydraulic pressure in the deepest sea-going draught condition; 
\(P_T\) = maximum measured actuator hydraulic pressure in the trial condition.

Where constant volume fixed displacement pumps are utilized, then the regulations can be deemed satisfied if the estimated steering actuator hydraulic pressure at the deepest draught is less than the specified maximum working pressure of the rudder actuator. Where a variable delivery pump is utilized, pump data shall be supplied and interpreted to estimate the delivered flow rate corresponds to the deepest sea-going draught in order to calculate the steering time and allow it to be compared to the required time.

Where \(A_T > 0.95A_F\), there is no need for extrapolation methods to be applied.
Alternatively, the designer or shipbuilder may use computational fluid dynamic (GFD) studies or experimental investigations to predict the rudder stock moment at the full sea-going draught condition and service speed. These calculations or experimental investigations shall be approved by RS;

.2 operation of the steering gear with the cylinders of the power unit disconnected in possible variants;

.3 correctness of the rudder or steering nozzle angle indicator readings as compared to their actual position determined from the dial of the mechanical indicator on the steering gear (refer to 2.9.15, Part III "Arrangements, Equipment and Outfit" of the Rules for the Classification and Construction);

.4 operation of the rudder or steering nozzle stops;

.5 operation of the sealing arrangements (gland) on the rudder stock;

.6 tightness of the hydraulic part of the steering gear power unit;

.7 intact position of the rudder blade angled to either side;

.8 absence of excess of the nominal parameters of the steering gear when the rudder of nozzle rudder is put over from one side to the other side (refer to 6.2.1.5, Part IX "Machinery" of the Rules for the Classification and Construction);

.9 time required to put the rudder or steering nozzle over from 35° on one side to 30° on the other side under conditions specified in 3.3.1.3.1, which shall not exceed 28 s; in oil tankers and combination carriers, gas carriers, chemical carriers and other ships intended for the carriage of dangerous goods (refer to 1.2, Part VI "Fire Protection" of the Rules for the Classification and Construction of Sea-Going Ships) of 10000 gross tonnage and upwards, in passenger ships of 7000 gross tonnage and upwards and in all nuclear ships the main steering gear shall ensure the above time with each one of the available identical power units being inoperative;

.10 time required for the auxiliary steering gear to put the rudder or steering nozzle over from 15° on one side to 15° on the other side at the deepest seagoing draught (refer to 3.3.1.3.1) and the ahead speed of the ship equal to one half of its maximum a head service speed or 7 knots, whichever is greater; the time required to put the rudder or steering nozzle over shall not exceed 60 s;

.11 operation of the steering gear when putting the rudder or steering nozzle over at astern speed contemplated by the design;

.12 parameters of the electrical and hydraulic equipment in accordance with the requirements of Sections 5 and 10;

.13 operation of the main and/or auxiliary steering gear by putting the rudder from hard over to hard over as outlined in 3.3.1.3.1, 3.3.1.3.9 and 3.3.1.3.10.

The force applied to the steering wheel handles of the main steering gear when handled by one man shall not exceed 120 N with the number of rotations, when shifting the rudder from hard over to hard over, not more than 9/R where R is arm (radius) of the steering wheel up to the middle of its handle length. The force applied to the steering wheel handles of the auxiliary manually operated steering gear when handled by not more than four men shall not exceed 160 N per helmsman.

In the series-built, non-self-propelled ships, the said tests, on agreement with the RS surveyor, may be carried out during the mooring trials. In this case, the required forces applied to the steering wheel handles shall be determined by comparing their values obtained during mooring and sea trials.

3.3.1.4 Technical supervision of the active means of ship's steering shall be performed in case where the installation thereof is accepted to ensure the specified steerability of the ship at the low speed by simultaneous operation of the steering gear. The RS Branch Office shall establish the scope and procedure of the surveys and approve the test program.

In other cases, the RS surveyor shall only make sure that the design and construction of the active means of ship's steering do not affect adversely the overall safety of the ship.
3.3.2 Anchor arrangements.

3.3.2.1 Survey of the anchor arrangement installation on board the ship shall be performed according to Table 3.1.4.1.

3.3.2.2 During the mooring trials of the anchor arrangement the following shall be checked:

1. test in operation of the anchor machinery at no-load condition during a period of time specified by the program of ship trials approved by RS;
2. reliability of engagement and disengagement of the chain sprockets;
3. operation of the band brakes;
4. operation of the drive;
5. dropping of the anchors from the hawses with disconnected clutches of the windlass (capstan) chain sprockets and released chain cable stoppers;
6. passing of the chain cable through the sprocket, chain stopper, guide rollers and anchor hawse and chain pipes;
7. absence of chain kinks, impacts against hawses, twisting and skipping over the sprocket;
8. operation of the stoppers and guide rollers;
9. entering of the anchor into hawse, absence of overturning when approaching the hawse and fit of the anchor to the ship hull at three points;
10. adjustment of the torque-limiting clutches;
11. correctness of the anchor cable counter's indications; the length of the chain cable paid out shall be determined by the number of shackles which have passed through the chain sprocket of the machinery (visually, by marks on the chain) and by comparing with the readings of the receivers-indicators;
12. absence of the releasing of the brake in the event of de-energization of the remote control system or driving gear of the main anchor machinery;
13. operation of the device for securing and releasing of the inboard end of the chain cable by means of turning the flywheel until the hooks are completely open and the first shot of the chain cable in the chain locker releases;
14. operation of the interlock system ensuring safe functioning of the anchor arrangement and set sequence of operations;
15. operation of the alarm on fulfilling the set anchor operations at the remote control station;
16. functioning of the anchor arrangement being manually operated (with the aid of capstan bars, levers, etc.) or with the use of other deck machinery.

3.3.2.3 During mooring trials of the anchor arrangement, the following shall be additionally checked in prototype ships:

1. passing of the joining links and inboard end chain length through the chain sprocket and stopper;
2. anchor heaving-on speed;
3. free passing of the anchor relative to the hull, especially in ships with bulbous bow, having regard to service heel and trim;
4. self-stowing of the entire heaved-in chain without dragging apart in the chain locker, whereupon the chain shall be veered away overboard; in so doing, the chain shall not be jammed in the chain locker and deck pipe.

3.3.2.4 During the sea trials of the anchor arrangement the following shall be checked:

1. alternate dropping of the chain cable for its whole length and hoisting thereof with breaking the chain cable out from a depth not less than 82.5 m (with three shackles in suspended condition). The average heaving-in speed measured on the length of two shackles shall be not less than 9 m/min. On agreement with the RS Branch Office, in series-built ships, exclusive of the prototype ship, the anchor arrangement which machinery has been exhaustively tested on bench during manufacture, including the test for nominal null may be tested at lesser depth but not less than at 45 m;
2. operation of the band brake of the anchor machinery by dropping and abrupt braking from one to two times on each chain cable length;
.3 proper run of the chain cable, normal engagement of the chain cable with the chain sprocket. No twisting, slip, impacts of the chain cable are allowed; the chain shall leave the sprocket and pass through the stoppers and hawses without sharp kinks and rotations;

.4 dropping of anchor to a depth specified in 3.3.2.4.1 with the use of the anchor machinery drive;

.5 checking of the hand drive; the heaving-in speed shall be not less than 2.5 m/min, and the force applied to the handles shall be not more than 160 N per man handling the drive; for series-built ships the check may be performed in the prototype ship and also selectively in some ships of a series;

.6 electrical equipment of the anchor arrangement in accordance with the requirements of Section 10, operation of the remote control (if any);

.7 operation of the device to ensure automatic braking by the band brake with the anchor machinery drive disconnected from the sprocket; in this case, the maximum speed of paying-out shall not exceed 3 m/s and the minimum speed shall be not less than 1.4 m/s, ignoring the initial speed-up. Attention shall be given to the absence of skipping of links over the sprocket cams;

.8 reliability of riding the ship at anchor; it is necessary to check securing the stoppers, their operation, possibility of releasing the stopper when the chain cable is stretched taut (it is recommended that the check is performed with the ship running at slow speed astern); no skipping of links over the sprocket cams shall be allowed when riding at anchor with the sprocket stopped;

.9 operation of the indicator of the paying out speed of the cable (in ships with Equipment Number of 400 and less).

3.3.2.5 On agreement with the RS Branch Office, use of simulation methods may be permitted for testing the anchor arrangement without proceeding to sea to the depths specified in 3.3.2.4.1 and 3.3.2.4.4. Such testing shall be preceded by an experimental check of the simulation method in some number of series-built ships according to a program agreed with the RS Branch Office.

The program and procedure of the simulation tests shall be approved by the Register Head Office (RHO).

3.3.2.6 Windlass shall be permanently marked with the following information:
nominal size of the windlass (e.g. "100/3/45" is the size designation of a windlass for 100 mm diameter chain cable of Grade 3, with a holding load of 45 % of the breaking load of the chain cable);
maximum anchorage depth, in m.

3.3.3 Mooring arrangements.

3.3.3.1 Survey of the mooring arrangement installation on board the ship shall be performed according to Table 3.1.4.1.

3.3.3.2 During the mooring trials of the mooring arrangement the following shall be checked:
.1 each mooring machinery in operation in idle run and at rated pull during a period of time specified in the program of trials approved by RS;
.2 heaving-in speed of the mooring line;
.3 each machinery loaded to develop 1.25 times the rated pull; along with that, it is necessary to check operation of the brakes under abrupt braking condition;
.4 operation of the automatic mooring winches;
.5 manual control of the automatic winches from local positions;
.6 operation of the manual and remote drives of the band brake from each control station with verifica-tion of the operation of the alarm and limit switches;
.7 operation of the drive of the device for limiting the veered out length of the rope and its alarm;
.8 operation of all interlocks;
.9 actuation and operation of the emergency alarms released at the consoles and remote alarm for the emergency mode;
.10 proper operation of the hydraulic system component when the mode switch is set to "automatic", "drum", "warping head", "stop" position;
.11 maximum speed of heaving-in of an unloaded mooring line and reeling-up of the line on the winch drum;
.12 range of the winch operation forces in "pay out" and "haul in" modes;
.13 operation of the limiter of the mooring line paid out length, automatic drum braking and alarm.

3.3.4 Towing arrangements.
3.3.4.1 When surveying (according to the List) the towing arrangement of a ship assigned the descriptive notation "tug" in the class notation, in addition to the issues specified in Table 3.1.4.1, the following shall be checked:
.1 installation and securing of the towing winches on the ship's seating;
.2 number, design, location and securing of towing bollards and chocks, bitts, rails, availability of cable stoppers;
.3 type, diameter or circumference, as well as length of the tow line;
.4 adjustment of the mechanical lock of the tow hook which shall be so adjusted that under no towing pull condition the force required to relieve the lever is from 30 to 50 N;
.5 location of the towing winch control position (no operating position shall be located within the zone of tow line run);
.6 location and arrangement of guide rollers, blocks preventing the line from slipping-off and from friction against the hull structures;
.7 arrangement, installation and enclosure class (casings) of the electrical equipment, installation of cable runs, securing, connection and choice of cross-sections of the cables to supply the electrical driving units, towing arrangement control system, alarm system in according with the requirements of Section 10, and where hydraulic drive is provided, Section 8.
3.3.4.2 When surveying the towing arrangements of other ships, the requirements in 3.2 shall be met, as well as the requirements relevant to the ship concerned which are set out in 3.3.4.1.
3.3.4.3 During the mooring trials the following shall be checked:
.1 towing winches (if any) in operation at the rated pull during the period of time specified in the RS-approved program of ship trials;
.2 operation of the device for governing the tension of the towline and possibility of checking the value of tension at every moment;
.3 operation of the fairlead;
.4 operation of the remote driving machinery;
.5 reliability of the hook lock closing and opening; opening shall be checked three times at a load equal to the rated pull; force applied to the release lever shall not exceed 120 N;
.6 release of the towline from the main hook in three positions — extreme deflections of the towline and in the mid-position. In every position the towline shall be released:
   under no load condition;
   at a load equal to the rated pull;
.7 release of the towline at the maximum load at hook with the use of the automatic control unit of the limiting heel angles.
For winch emergency release systems provided on towing winches that are used on towing ships within close quarters, ports or terminals, including those ships normally not intended for towing operation in transverse direction:

the full functionality of the emergency release system shall be tested as part of the shipboard commissioning trials to the satisfaction of the RS surveyor. Testing shall be conducted either during a bollard pull test or by applying the towline load against a strong point on the deck of the tug that is certified to the appropriate load;

where the performance of the winch in accordance with 6.6.3.1, Part IX "Machinery" of the Rules for the Classification and Construction has previously been verified, the load applied for the installation trials shall be at least the lesser of 30% of the maximum design load or 80% of vessel bollard pull;

.8 operation of the sound and light warning alarm (if any) activated when the maximum permissible length of towline is veered out;

.9 manual operation of the automatic winches from a site at the winch;

.10 proper laying of the towline (the line shall not touch the hull structures);

.11 side-to-side run of the towline;

.12 operation of the device for remote release of the tow hook under no load and under load conditions with measurement of the pull;

.13 passing of the standard towline and towing bridle (semi-bridle) from forward and aft, from the regular shipboard positions, and securing thereof for sea; absence of the line brushing against articles and other structures;

.14 appropriate power supply of the towing arrangement, operation of the controls and the alarm, proper condition of the electrical equipment and electrical power parameters to suit the requirements of Section 10;

.15 proper operation of the driving machinery in all control positions;

.16 operation of the winch in idle run and in "haul in" and "pay out" modes;

.17 towline hauling-in speed;

.18 operation of all interlocks;

.19 towline counter;

.20 adjustment of the torque-limiting clutch.

3.3.4.4 When carrying out surveys on the tugs and ships intended for towing operations, to confirm the total pull of the ship using special towing equipment on different main engine operating conditions and to issue the Bollard Pull Certificate (form 6.3.45) the requirements of 6.11, Part I "General Provisions" of the Guidelines on Technical Supervision of Ships in Service and the Bollard Pull Testing Procedure (Appendix 1 to Annex 28 to the Guidelines on Technical Supervision of Ships in Service) shall be met.

Results of the total pull tests conducted on the prototype ship and/or subsequent ship(s) of a series (refer to 1.1.2, Part I "Classification" of the Rules for the Classification and Construction) may be credited for ship(s) of a series, provided the RS surveyor confirms the following:

- a letter of guarantee justifying the impossibility of conducting tests has been provided by the customer;
- main propulsion plant and screw-rudder system are technically identical on all ships of a series, including the prototype ship;
- results of the total pull tests obtained for the first ship of a series and/or subsequent ship(s) of a series are practically identical;
- the RS technical supervision during construction of the prototype ship and ship(s) of a series has been carried out with satisfactory results.
In this case, the data may be used obtained upon results of the actual total pull tests conducted on the prototype ship and/or subsequent ship(s) of a series and witnessed by the RS surveyor, provided the full (detailed) report on the tests of the main propulsion plant and screw-rudder system for the ships of a series considered is submitted to the RS surveyor and the absence of deviations in the data and results compared to the prototype ship/ship(s) of a series is confirmed in the Report on the Survey of the Ship (form 6.3.10).

3.3.5 Signal masts.
3.3.5.1 General.
3.3.5.1.1 Subject to the Register technical supervision shall be stayed and unstayed signal masts made of steel of a normal and higher strength, light alloys, glass-reinforced plastic or wood including masts of special construction: bipod, tripod and other similar masts.

The Register technical supervision of the masts, which carry derrick booms and other cargo handling gear in addition to the signal means, shall be performed in accordance with the requirements of the Rules for the Cargo Handling Gear of Sea-Going Ships.

Technical supervision of the equipment of the signal masts and location thereof shall be performed in accordance with the requirements of Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and Section 14 of the Guidelines.

3.3.5.2 Survey of the signal masts installation on board the ship shall be performed according to Table 3.1.4.1.

3.3.5.3 During the mooring and sea trials of the ship, particular emphasis shall be placed upon the magnitude of the mast vibration under various operating conditions of the main engine.

3.3.6 Openings in hull, superstructures and deckhouses and their closing appliances.
3.3.6.1 Survey (according to the List) of the closing appliances shall be performed in accordance with the requirements of 3.2 and Table 3.3.6.1.

3.3.7 Equipment of spaces.
3.3.7.1 When surveying, in addition to the matters specified in 3.1.3, it is necessary to check the following spaces and equipment listed under 3.3.7.1.1–3.3.7.1.4.

3.3.7.1.1 As regards dry cargo holds, the following shall be checked:
1. Placing of wooden ceiling on top of the floors in ships with no double bottom. The ceiling shall be solid and extend to the bilge.

In holds intended for the carriage of grain and other bulk cargoes, the wooden ceiling shall be fitted so as to prevent wells, bilges and suction pipes from clogging;

<table>
<thead>
<tr>
<th>No.</th>
<th>Check pattern</th>
<th>Scuttes</th>
<th>Hatches</th>
<th>Dors in watertight subdivision bulkheads</th>
<th>Doors in ships intended for carriage of vehicles</th>
<th>Cargo hatch covers of:</th>
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<td></td>
<td></td>
<td>side scuttes</td>
<td></td>
<td>doors in superstructure and deckhouse</td>
<td>ventilation ducts</td>
<td>hold covers: dry cargo holds and holds for carriage of dry and bulk liquid cargoes ensuring tightness using: tarpaulins</td>
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<td>Even fitting of the gasket in secured position</td>
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1 Hereinafter referred to as "the Rules for the Cargo Handling Gear".
Guidelines on Technical Supervision of Ships under Construction (Section 3)

<table>
<thead>
<tr>
<th>Nos.</th>
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<th>Cargo hatch covers of:</th>
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<td>doors in bulkheads</td>
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<tr>
<td>8</td>
<td>Glass seal</td>
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<td>+ + + + + +</td>
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</tr>
<tr>
<td>9</td>
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<td>+ + + +</td>
<td>+ + + +</td>
<td>+ + + +</td>
<td>+ + + +</td>
</tr>
<tr>
<td></td>
<td>from inside</td>
<td>+ 8 + + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
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<tr>
<td></td>
<td>from outside</td>
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<td>+ + + + + + +</td>
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</tr>
<tr>
<td></td>
<td>from both sides</td>
<td>+ + + +</td>
<td>+ + + +</td>
<td>+ + + +</td>
<td>+ + + +</td>
<td>+ + + +</td>
</tr>
<tr>
<td>10</td>
<td>Height of coamings</td>
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<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
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<tr>
<td>11</td>
<td>Quality of welds at the junctions of the closing appliances with the hull, superstructures and deckhouses</td>
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<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
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<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
</tr>
<tr>
<td></td>
<td>by hose testing</td>
<td>+ + + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
</tr>
<tr>
<td></td>
<td>by filling with water or air testing</td>
<td>+ + + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
</tr>
<tr>
<td></td>
<td>together with the compartment</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
<td>+ + + + + + +</td>
</tr>
</tbody>
</table>

1. Dents, tears, non-rounded off corners are unacceptable.
2. Cracks, cavities, bedding, paint, oil are unacceptable.
3. Continuity of fit is checked by a chalk test and shall be ensured at indentation depth not more than 1 mm, except for closures listed in columns 8, 20, 22, having an area of 15 m² and over.
4. Gaps are verified by feeler gauge or by other agreed methods.
5. The denting value shall comply with the requirements of the technical documentation.
6. To be checked are the firm’s (manufacturer’s) documents, absence of cracks and scratches on the glass, direct contact of the glass with the frame metal, glass thickness.
7. To be checked are the firm’s (manufacturer’s) documents, measures to prevent the sealant from being pressed out during installation of the glass.
8. To be checked also is the performance of special nuts required in particular cases by Rules for the Classification and Construction depending on the position of the scuttle on board ship.
9. To be checked is the operation of the power gear and hand gear if the latter is contemplated by Sections 5 and 10, as well as the operation of the emergency hand gear used for closing and securing when the power gear is inactivated.
10. If in addition to their intended purpose, hatches are used as emergency escape, the securing device shall be such that it can be operated from both sides.
11. To be checked is the control from the local positions only, operation of the devices precluding their opening by incompetent persons, and indicators showing automatically that each door is closed and all dogs are secured.
12. Fastening of portable shields for the glasses, made of the same material as the covers, being at least 3 mm thick.
13. Fastening in ships of less than 100 m in length of the ventilator covers which shall be permanently attached, while in ships of 100 m in length and over they may be portable, stowed near the ventilators.
14. To be checked is locking of portable beams in their sockets of the coamings, reliability of locking the rolling portable beams when the hatchway is either closed or open, tight pressing of tarpaulins against the hatchway coamings with the aid of battens and wedges, presence of steel bars or other equivalent means to efficiently and independently secure each section of hatchway covers after the tarpaulins are battened down.
15. The following shall be checked:
   - for the hatch covers of holds intended for the carriage of flammable and dangerously explosive cargoes – absence of wear between the movable steel parts through the use of materials not creating a spark-like couple;
   - presence of the plating of two adjacent sections in one plane in “secured” position;
   - fit of the bearing end and side vertical plates of the sections to the lower edges or the flanges to the bearing parts of the coaming in “secured” position;
   - lack of load on the running wheels of the sections in “secured” position.
16. To be checked additionally is the operation of the remote drive from a readily accessible position, located above the bulkhead deck, with the use of a flywheel or other similar device, operation of the indicators showing in which position of the flywheel, handle or other similar device the door will be open and at which position it will be closed, to be measured is the force at the flywheel, handle or other similar device during the movement of the door leaf and the time needed to close the door completely, which shall be consistent with the guidelines of the technical documentation.
.2 availability of protective wooden screens, grids, chutes, etc. fitted on the manholes, air pipes, sounding pipes, etc. in places subject to impacts of cargo, grabs or other hoisting devices;
.3 fitting of cargo battens made of wood or metal, attached so as to be readily removed or replaced. The fastenings of the cargo battens shall not be welded to the head of the offset bulb plate and to the edges of the face plates of the framing girders;
.4 thickness of the wooden ceiling;
.5 thickness of the wooden cargo battens;
.6 attachment of the guide uprights for containers to the hull structures, quality of welds;
.7 basic dimensions of the uprights and distance between the uprights, weld throats.

3.3.7.1.2 As regards exits, doors, corridors, stairways and vertical ladders, the following shall be checked:
.1 location and ready access of persons from spaces to the places of embarkation into lifeboats and liferafts;
.2 availability and location of two exits in accordance with the requirements of the Rules for the Classification and Construction and drawings;
.3 consistence between the type and dimensions of doors and the requirements of the drawing;
.4 capability of the exit doors or ladderway covers to be operated from both sides and operation of devices ensuring this;
.5 direction in which the door can open;
.6 availability of detachable panels in the lower portion of the doors of accommodation spaces, as well as the inscription: "Means of escape – knock out in case of emergency" in the passenger ships;
.7 length of the dead-end corridors;
.8 width of exits from the cinema halls and sizes of the ladderways from cargo holds;
.9 sizes of the detachable panels;
.10 width of main corridors in way of passengers' and crew's accommodation spaces;
.11 width of stairways and sizes of landings.

3.3.7.1.3 As regards guard rails, bulwark and gangways, the following shall be checked:
.1 quality of welded joints of the bulwark and gangways;
.2 convenience and safely of passage from the level of the gangway to some crew's accommodation spaces in "A" type ships;
.3 opening below the lowest course of the guard rails and spacing between the other courses of rails, openings in the bulwark;
.4 height of the bulwark and guard rails;
5. availability, location and arrangement of the life rails and other means ensuring the safety of passage;
6. location and arrangement of the bulwark freeing ports and their covers.

3.3.7.1.4 As regards movable decks, platforms, ramps and other similar structures, the following shall be checked:
1. reliability of installation of the movable decks, platforms, ramps and other similar structures in working and non-working positions, consideration shall be given to the surveys of these structures and also their supporting elements at ship's sides, decks and bulkheads, the pillars and suspensions therefor, ensuring their installation in the working position, which have been previously carried out during the survey of the hull;
2. structural elements for securing of the movable decks, platforms, ramps, etc. in the non-working position and also quality of installation thereof;
3. movement of the decks, platforms, ramps and other similar structures with the use of regular driving units from the working position to the non-working position and vice versa, in so doing, movement shall be smooth, no jerks, cocking, etc. are accepted;
4. operation of the arrangements ensuring securing of the movable decks, platforms, ramps and other similar structures in the non-working position, reliability of securing; the hoisting gear and elements thereof shall not generally be kept under load;
5. operation of electric and hydraulic drive, limiting switches, alarm and interlocking systems in accordance with the requirements of Sections 5 and 10;
6. strength of the movable decks, platforms, ramps and other similar structures, pillars or suspensions therefor and also their supporting elements at ship's sides, decks at the operating load in accordance with the RS-approved program (in prototype ship);
7. scope and procedure of test for an arrangement (dockside trials of the ship) including the test thereof under load shall be established by the designer with due account of the salient features of the design and use of the arrangement; the test program shall be agreed upon with the Register.

3.3.8 Arrangements for securing of timber deck cargo.
3.3.8.1 Subject to the supervision of the Register shall be the strengthened bulwark or guard rails, sockets or other fittings for uprights, stanchions, joint rings and lashings.
3.3.8.2 When surveying (according to the List) the arrangements for securing of timber deck cargo, in addition to the matters specified in 3.1.3, the following shall be checked:
1. installation of uprights and attachment thereof to the hull;
2. special strengthening of bulwark at places where the stanchions are installed, and quality of welds;
3. arrangements of joint rings for lashings, quality of welding;
4. means provided to protect the steering gear and steering ropes from the deck timber;
5. spacing between uprights;
6. circumference of ropes, diameter of chains;
7. distance between joint rings.

3.3.9 Ship's wire, fibre and synthetic ropes of all purposes.
3.3.9.1 During survey the ropes shall be checked in accordance with the provisions of 3.2 and also of the relevant chapters of this Section.

3.3.10 Emergency outfit.
3.3.10.1 Subject to the technical supervision of the Register shall be completing, arrangement and securing of the items of the emergency outfit on board ship, taking into account the requirements in 9.1.1, Part III "Technical Supervision during Manufacture of Materials" of the Rules for Technical Supervision.
3.3.10.2 During survey, in addition to the matters specified in 3.2, the following shall be checked:

1. lantern of explosion-proof type;
2. location of emergency stations and availability of identification inscriptions;
3. availability of items of the emergency outfit in accordance with the list;
4. reliability of securing of the items in their regular positions;
5. possibility of the outfit items being rapidly used with verification of the release device;
6. completeness of collision mats;
7. marking of items of the emergency outfit;
8. width of free passage to the emergency station;
9. sizes of collision mates, bars, planks, wedges, plugs, canvas, rubber, felt;
10. diameter of wire, construction shackles, bolts and washers, etc.;
11. quantity of cement (brand of the quick-setting cement according to the certificate),

concrete setting accelerator, minium, technical fat, oakum and sledge hammers.

3.3.11 Hoisting gear of shipborne barges.

3.3.11.1 During survey (according to the List), the hoisting gear of shipborne barges to be lifted on board the barge carrier shall be checked in accordance with the provisions of 3.2 and also proceeding from the additional requirements set forth by the designer on the particular features of the design and manufacture process.
3.4 SURVEY OF MODU/FPU/FOP EQUIPMENT, ARRANGEMENTS AND OUTFIT

3.4.1 General.

3.4.1.1 Unless otherwise provided in this Chapter, all the requirements of Section 3 shall apply to the MODU/FPU/FOP equipment, arrangements and outfit subject to technical supervision of the Register during manufacture, installation and testing.

3.4.1.2 This Chapter contains the requirements for technical supervision during installation and testing of the MODU/FPU/FOP specific arrangements during the MODU/FPU/FOP construction.

3.4.1.3 Materials used for manufacture of products shall meet the requirements in Parts III “Equipment, Arrangements and Outfit of MODU/FOP”, XII “Materials” and XIII ”Welding” of the MODU/FOP Rules.

3.4.1.4 Additional requirements for the scope of technical supervision of the FPU equipment, arrangements and outfit is given in 1.3, Part III “Equipment, Arrangements and Outfit” of the Rules for the Classification and Construction of Floating Offshore Oil-and-Gas Product Units¹.

3.4.2 Surveys.

3.4.2.1 The survey scope and procedure when carrying out technical supervision during manufacture of products, installation and testing of the MODU/FOP specific arrangements are given in Table 3.4.2.1.

<table>
<thead>
<tr>
<th>No.</th>
<th>Item of technical supervision</th>
<th>Verification of technical documentation</th>
<th>Control during manufacture</th>
<th>Installation on board MODU</th>
<th>Verification of technical documentation on products</th>
<th>Verification of mounting dimensions</th>
<th>Test in operation</th>
<th>Mooring trials</th>
<th>Sea trials</th>
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<tbody>
<tr>
<td>1</td>
<td>Jacking system of self-elevating MODU:</td>
<td>Verification of technical documentation</td>
<td>Control during manufacture</td>
<td>Installation on board MODU</td>
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<td>Verification of mounting dimensions</td>
<td>Test in operation</td>
<td>Mooring trials</td>
<td>Sea trials</td>
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<td>Arrangements for lifting and lowering columns of submersible sea water pumps¹:</td>
<td>Verification of technical documentation</td>
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<td>Verification of technical documentation on products</td>
<td>Verification of mounting dimensions</td>
<td>Test in operation</td>
<td>Mooring trials</td>
<td>Sea trials</td>
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<td>Fixing arrangements of MODU legs²:</td>
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¹ Hereinafter referred to as "the FPU Rules".
### Guidelines on Technical Supervision of Ships under Construction (Section 3)

<table>
<thead>
<tr>
<th>No.</th>
<th>Item of technical supervision</th>
<th>Control during manufacture</th>
<th>Installation on board MODU</th>
<th>Verification of</th>
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<td>+</td>
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</table>

---

3.4.2.2 Manufacture of products, equipment, arrangements and outfit at the manufacturer shall be performed according to the technical documentation approved by the Register in compliance with Section 4, Part I “Classification” of the MODU/FOP Rules and assembly drawings for the items given in Table 3.4.2.1.

3.4.2.3 The list of items shall be prepared also with regard to Table 3.4.2.1.

3.4.3 Survey of MODU jacking system.

3.4.3.1 In addition to Table 3.4.2.1, when performing survey of jacking system of MODU during its manufacture according to the RS Nomenclature, the following shall be checked:

1. finish coating of rubbing parts;
2. quality of coatings of catcher supports;
3. minimum bending radii in areas where cross-sections change abruptly.

3.4.3.2 In addition to Table 3.4.2.1, when performing survey of jacking system of MODU during installation according to the RS Nomenclature, the following shall be checked:

1. compliance of installation tolerances during assembly of parts and units with those specified in technical documentation;
2. no unacceptable displacement in moving parts of the arrangements;
3. proper alignment of slider guides;
4. water drainage from cavities and jack houses of legs, where necessary;
5. proper fitting of teeth of pinions and gear wheels (the checked items shall be branded by the Register);
6. proper locking of the fasteners to prevent their self-releasing;
7. proper arrangement and wiring of the electrical equipment in compliance with Section 10;
8. proper laying of the hydraulic pipes in compliance with Section 8 and proper wiring of the machinery in compliance with Section 5.

3.4.3.3 Test in operation for single units of jacking system of MODU, mooring and sea trials (for hydraulic system).
3.4.3.3.1 Depending on particular construction conditions (shallow water, inability to provide lull-load conditions in water area, etc.), surveys and tests in operation for single units shall be performed after completion of main construction works on board MODU. These surveys and tests shall include the following:
visual examination;
no-load tests;
mooring trials;
tests for intended purpose (sea trials).

3.4.3.3.2 During visual examination, the following shall be checked:
proper attachment of the hydraulic cylinder plates to the jack house metal structures;
proper coupling of the catchers and guides with sliders; proper attachment of the hydraulic cylinder rods and screws of stopping device to the sliders;
proper fitting of the catches, stairways and guard rails;
verification of the serviceable instruments by the competent authority.

3.4.3.3.3 During no-load tests the following shall be checked:
free and smooth movement of the sliders along the jack house guides (the sliders are lifted and lowered with catchers disengaged and as prescribed by technical documentation);
absence of hits, seized, jammed and skewed moving and rotating parts; no spontaneous check movement of the hull and/or legs; movement of the sliders within the design tolerances and proper operation of the limit switches;
proper operation of diagonal pairs of catchers: catchers shall properly move back and forth into the slots of leg rack (number of movements shall be specified during tests);
misalignment of diagonal catchers is less than the value specified in technical documentation;
hydraulic cylinder rods are not loaded by forces when the catchers are moving horizontally;
proper operation of screw-type stopping device; special consideration shall be given to make sure that the screws are passing freely through jack house cross beam sleeves and the upper and lower nuts are screwed on freely (this check shall be performed after the lifting cylinders are locked in the outermost upper and lower positions of the slider and in three intermediate positions);
proper operation of all machinery, electric drives, control and monitoring system in compliance with the relevant sections of the Guidelines.

3.4.3.3.4 When performing survey of the jacking system at the mooring trials, the following shall be done:
with the hull afloat, the arrangement shall be tested for proper lifting and lowering of all legs in turn by inserting the catchers into the rack grooves and switching two diagonal catchers to the lowering mode when hydraulic cylinders of the second pair of catchers are locked with time delay of 10 min under working pressure inside the hydraulic cylinders. Pressure in the lower cavity of the hydraulic cylinders shall not exceed the design value;
the test shall be repeated with the load transferred to the screw-type device, test its operating capability with the catchers taken out, pistons kept in the upper positions and upper and lower nuts properly tightened by pressurizing the upper or lower cavity of the hydraulic cylinders with time delay of at least 10 min;
each screw-type device shall be tested under the maximum load by transferring the weight of pontoon taken out of water at allowable height and applying the additional load equal to the maximum possible weight of stock on board MODU (drilling pipes, muds, tools, etc.) by means of a free bank of hydraulic cylinders with time delay of at least 10 min;
after the tests survey shall be performed for defects or residual deformations of parts and units (jack house metal structures and columns in way of a jack house, catch bearers, sliders, yokes for securing hydraulic cylinders, catchers, slider guides, threaded joints, etc.);
the legs shall be lifted and lowered at allowable height alternatively and simultaneously.

3.4.3.3.5 At the mooring trials of the jacking system, the RS surveyor shall make sure that:
jacking system is capable of being operated as prescribed by the technical documentation;
no abnormal vibrations, heating and hits are observed; units and components are readily and safely accessible for inspection, functional test and maintenance; machinery, electrical equipment and control and monitoring system components are operating properly.
3.4.3.3.6 When performing survey of the jacking system during tests for intended purpose (sea trials), the following tests and inspections shall be performed:

- the MODU hull supported by columns shall be lifted to a height of clearance at the minimum allowable depth, kept on hydraulic cylinders and screw-type stopping device within the period specified in the technical documentation and required for survey of the loaded parts and units;
- the MODU hull shall be lowered to the maximum allowable depth, legs shall be lowered and the MODU hull shall be lifted at a height of clearance, then kept sequentially on four diagonal hydraulic cylinders within the period specified in the technical documentation and required for survey of the loaded parts, units and checking operation of fixing arrangement;
- load shall be transferred to the screw-type stopping device and kept within the period specified in the technical documentation and required for survey of the loaded parts and units;
- then the MODU hull shall be lowered and legs shall be pulled out from the seabed; jacking system shall be checked for proper operation in the specified modes by monitoring them from local and remote control stations;
- during tests of the jacking system, proper fastening of parts and units, smooth moving of sliders and catchers along the guides without jamming, proper load applied to legs shall be checked;
- the appropriate test parameters shall be recorded.

3.4.4 Survey of arrangements for lifting and lowering columns of submersible sea water pumps.

3.4.4.1 Arrangements for lifting and lowering columns of submersible sea water pumps shall be subject to manufacture quality control in compliance with Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision.

3.4.4.2 In addition to checks mentioned in Table 3.4.2.1, during survey of arrangements for lifting and lowering columns of submersible sea water pumps during installation according to the list of items under technical supervision, the following shall be checked:
- availability of guides in the columns allowing their proper motion along the trunks;
- free moving of the columns with the pumps fitted along the trunks and no deformations which may lead to jamming;
- free and proper operation of stoppers on column supports;
- secure locking of the fastenings to prevent their self-releasing;
- proper fitting and secure mounting of the columns on supports in outermost positions.

3.4.4.3 In separate cases, with regard to particular conditions (contamination of water area, shallow waters, etc.), survey of arrangements for lifting and lowering columns of submersible sea water pumps may be performed, in whole or in part, during the MODU tests for intended purpose, upon agreement with the Register. In any case, the following shall be checked:
- smooth lifting and lowering of each column (at least three times);
- brakes operation when the column is lowered and lifted at the maximum allowable speed to a height of almost 3 m and during hard braking (the test shall be repeated at least three times in each direction);
- normal and proper operation of stoppers in the lower, upper and intermediate positions of the column;
- proper motion and laying of wire rope; operation of limit switches;
- position of submersible pump relative to water with the column lower position and the hull lifted to a height of clearance;
- time required for lowering the column from the outermost upper position to the outermost lower position according to 10.2.8, Part III in "Equipment, Arrangements and Outfit of MODU/FOP" of the MODU/FOP Rules;
- proper operation of electrical equipment machinery and control and monitoring system in compliance with the relevant sections of the Guidelines.

3.4.4.4 In case the full-scale mooring trials of these arrangements are performed in the water area of the MODU builder, operability of these arrangements during the MODU tests for intended purpose shall be checked.
3.4.5 Survey of fixing arrangements of the MODU legs.
3.4.5.1 The Register technical supervision during manufacture of fixing arrangements of the MODU legs shall be limited to review and approval of technical documentation.
3.4.5.2 When performing survey of fixing arrangements of the MODU legs during installation, in addition to Table 3.4.2.1, absence of contact between pull rods and legs metal structure and the hull shall be checked.
3.4.5.3 When testing fixing arrangements of the MODU legs in operation, the following shall be checked:
   - free movement of the rods along the guides;
   - free movement of the sliders along the slots of wedge boxes;
   - tight contact of the wedge box plates to leg teeth, and in the reverse stoke, to the wedge boxes;
   - free movement of the nuts along the screws;
   - rapid release of fixed legs.
3.4.5.4 The fixing arrangements of the MODU legs shall be tested simultaneously with the MODU jacking system. In addition, secure attachment of the legs by fixing arrangements shall be checked when MODU is in sea position under weather conditions appropriate for its transit.

3.4.6 MODU/FOP mooring and boarding arrangements.
3.4.6.1 The Register technical supervision during manufacture of items of the mooring and boarding arrangements shall be limited to review and approval of technical documentation.
3.4.6.2 When performing survey during installation, secure attachment of the mooring and boarding arrangements to the MODU/FOP hull shall be checked.
3.4.6.3 When testing the folding/sliding mooring and boarding arrangements in operation, the following shall be checked:
   - tight fitting of the mooring bows, platforms and boarding stairways in working position to supporting structures;
   - free movement of carrying ropes along the guide pulleys;
   - actuation of the limit switches when folding/sliding mooring and boarding arrangements are set to the outermost positions as well as of the stoppers stowing the mooring bows, platforms and boarding stairways in working and sea positions.

3.4.7 Anchoring MODU/FOP position mooring systems.
3.4.7.1 The Register technical supervision during manufacture of components of anchoring MODU/FOP position mooring system (anchors, connecting shackles, anchor lines consisting of chain, wire, synthetic or fibre rope, fairleads, guide devices, windlasses and winches) shall be carried out in compliance with the RS Nomenclature.
3.4.7.2 When performing survey of the anchoring MODU/FOP position mooring system during installation, in addition to Table 3.4.2.1, the following shall be checked:
   - security of fixing winches, windlasses and anchor line tension device to the MODU/FOP hull;
   - use of fairleads and guides to prevent excessive bending and wearing of anchor lines;
   - sufficient length of anchor lines;
   - fixing of anchors to prevent their shift during transit.
3.4.7.3 The following shall be checked in operation:
   - operation of winch brakes during hoisting and anchoring;
   - safe operation of stopper of the anchor line tension device;
   - free passage of anchor line through the fairleads and roller guides; upon placement at the anchor test point for testing the anchor line by design load.

3.4.8 Towing arrangement.
3.4.8.1 Technical supervision during manufacture of items of the towing arrangement shall be carried out in compliance with the RS Nomenclature.
3.4.8.2 When performing survey during installation, the installation of winches, tow line sections fixed to the MODU/FOP hull, secure fixing of strength components of the towing arrangement to the MODU/FOP hull (Smith brackets) shall be checked.
3.4.8.3 During test of the towing arrangement in operation, free passage of carrying ropes through the hawse pipes and guide units, secure fixing of the towing bridle components to the MODU/FOP hull shall be checked.
4 FIRE PROTECTION

4.1 GENERAL

4.1.1 This Section specifies the scope and procedure of technical supervision during installation and tests of the fire divisions and systems and during equipping ships with firefighting outfit to ensure fire protection of the ship (refer to Table 4.1.1).

Table 4.1.1

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Installation and assembly</th>
<th>Mooring trials</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Check of documents and brands for materials and products</td>
<td>Check of assembly and arrangement onboard</td>
</tr>
<tr>
<td>1</td>
<td>Structural protection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.1*</td>
<td>Fire-proof bulkheads, ceilings and decks</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>1.2*</td>
<td>Fire doors</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>1.3*</td>
<td>Fire dampers for ventilation dumps</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>1.4</td>
<td>Fuses for self-closing dampers</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>2</td>
<td>Materials (fire protective properties)</td>
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</tr>
<tr>
<td>2.1*</td>
<td>Insulation materials</td>
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<td>+</td>
</tr>
<tr>
<td>2.2*</td>
<td>Materials of internal bulkheads</td>
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<td>+</td>
</tr>
<tr>
<td>2.3*</td>
<td>Grounds</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2.4*</td>
<td>Linings</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2.5*</td>
<td>Finishing materials</td>
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<td>+</td>
</tr>
<tr>
<td>2.6*</td>
<td>Deck coverings</td>
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<td>+</td>
</tr>
<tr>
<td>2.7</td>
<td>Textiles</td>
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<td>+</td>
</tr>
<tr>
<td>2.8</td>
<td>Carpets</td>
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<td>–</td>
</tr>
<tr>
<td>3</td>
<td>Fire extinguishing systems1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.1*</td>
<td>Water fire main system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.2*</td>
<td>Sprinkler system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.3*</td>
<td>Pressure water-spraying system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.4</td>
<td>Water screen system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.5</td>
<td>Drenching system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.6*</td>
<td>Foam fire extinguishing system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.7*</td>
<td>Carbon dioxide smothering system</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.8*</td>
<td>Fire extinguishing systems for machinery spaces and cargo pump rooms</td>
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<td>+</td>
</tr>
<tr>
<td>3.9*</td>
<td>Dry powder system</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3.10</td>
<td>Liquified gas system for domestic use</td>
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<td>+</td>
</tr>
<tr>
<td>4</td>
<td>Fire fighting outfit</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4.1*</td>
<td>Fire hoses complete with couplings</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>4.2*</td>
<td>Fire hose nozzles</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>4.3*</td>
<td>Air-foam nozzles</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4.4*</td>
<td>Portable foam generators</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>4.5*</td>
<td>Portable foam set</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4.6</td>
<td>Foam extension pipes</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4.7</td>
<td>Extension pipes for foam generators</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4.8*</td>
<td>Water fog applicator</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4.9*</td>
<td>Portable fire extinguishers</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
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<td>45 l and 135 l foam fire extinguishers</td>
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<td>+</td>
</tr>
<tr>
<td>4.11*</td>
<td>16 kg and 45 kg CO2 or powder fire extinguishers</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4.12*</td>
<td>Sand receptacles</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4.13</td>
<td>Fire smothering blankets</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4.14*</td>
<td>Fireman’s protective clothing and protective clothing for handling dangerous goods</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4.15*</td>
<td>Portable safe manual lantern</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4.16*</td>
<td>Breathing apparatus</td>
<td>+</td>
<td>+</td>
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<tr>
<td>4.17*</td>
<td>Lifeline</td>
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<td>+</td>
</tr>
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<td>4.18</td>
<td>Portable fire motor-pumps</td>
<td>+</td>
<td>+</td>
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<tr>
<td>4.19*</td>
<td>International shore connection</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4.20*</td>
<td>Foam concentrate</td>
<td>+</td>
<td>–</td>
</tr>
</tbody>
</table>
Guidelines on Technical Supervision of Ships under Construction (Section 4)

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<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Installation and assembly</th>
<th>Mooring trials</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Check of documents and brands for materials and products</td>
<td>Check of assembly and arrangement onboard</td>
</tr>
<tr>
<td>4.21*</td>
<td>Extinguishing medium</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>4.22</td>
<td>Spares and tools</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4.23*</td>
<td>Gas analyser for vapours of oil products and for oxygen content</td>
<td>+</td>
<td>–</td>
</tr>
</tbody>
</table>

1 Operability of the system items shall be checked at random in association with the system.
2 To be checked for operability on all ships.


Symbols:
"+" – to be carried out;
"–" – not to be carried out.

4.1.2 General provisions for the organization of the technical supervision are given in Section 1.

4.1.3 Technical documentation.

4.1.3.1 Installation and testing of the fire-fighting equipment shall be performed under the Register technical supervision according to the RS-approved technical documentation.

4.1.4 Technical supervision of the Register.

4.1.4.1 Surveys during installation and testing of the fire-fighting equipment shall be performed according to the examination and testing plan developed by the shipyard according to 4.2.1 based on Table 4.1.1, taking into account 4.3.

4.1.5 Tests and checks specified in this Section are based on an assumption that the structures, systems and firefighting outfit have been tested at the firm (manufacturer) in compliance with the requirements of Section 4, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of the fire-fighting means in substantiated cases.
4.2 SURVEY PLANNING

4.2.1 Prior to commencement of survey of the fire-fighting means of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 4.1.1. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1 and with due regard to 4.3.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

4.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

4.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change subcontractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

4.2.4 Quality standards for installation and testing of the fire-fighting means shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

4.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
4.3 STRUCTURAL FIRE PROTECTION

4.3.1 The structural fire protection shall be checked against the RS-approved design documentation, in which the types of the applied fire-proof divisions, products and materials shall be indicated.

4.3.2 When surveying the fire-proof divisions and materials used for insulation, finishing and deck coverings of spaces, their compliance with the RS-approved drawings, as well as with the Type Approval Certificate/Type Approval Certificate for Fire-Proof Division shall be checked.

Additional structural fire protection shall be checked on FPU, for example, application of epoxy intumescent coatings on the outer surfaces of load-bearing structures (as a rule, of tubular or I-beam section, as well as on bulkheads and decks) that may be affected by two-phase fire (initial jet fire followed by pool fire), as well as fixed or removable components of passive fire protection of the critical equipment (as a rule, steel casings and soft heat-resistant jackets with fire insulation inside) required by Tables 2.3.2, 2.3.3 and 2.3.4 of Part VI "Fire and Explosion Protection" of the FPU Rules.

The RS surveyor is entitled to require submission of the relevant documents, confirming equivalence of substitutes accepted. In doubtful cases, the surveyor may require additional information, including test performance.

4.3.3 When surveying the fire doors (refer also to 4.3.2) and other closures of openings, the following shall be checked in fire-proof divisions:

- correct installation, operability and tightness of closing according to the instruction of the manufacturer;
- possibility of opening and closing doors by a single man's effort;
- operation of closing facility of the self-closing doors when activated from the door position and when remotely activated (if provided);
- operation of controls for opening and closing of skylights;
- operation of the fire ventilation dampers.

4.3.4 Availability and location of the fire control plans drawn up with the use of colour symbols in agreement with IMO resolution A.952(23), as amended, as well as the construction and marking of the enclosure for stowage of the duplicate set of the plans shall be checked.
4.4 FIRE EXTINGUISHING SYSTEMS

4.4.1 The systems shall be verified for compliance with the RS-approved documentation and for the presence of certificates or Type Approval Certificate for the equipment forming part of the systems.

Verification on board ship shall be carried out in accordance with Table 4.1.1.

In the process of verification of the system components for compliance with the requirements of the technical documentation, the requirements of 8.3.1.2 shall be met.

4.4.2 When checking the system components for correctness and reliability of arrangement, the requirements of 8.3.1.3 shall be met.

4.4.3 General.

4.4.3.1 These provisions cover the ship’s systems referred to in Table 4.1.1.

The purpose of the operational tests of the systems is to confirm their availability for immediate action, operability, compliance of their parameters with the RS-approved technical documentation.

4.4.3.2 Prior to operational test, all the fire extinguishing systems shall be completely assembled, supplied with organic equipment, instruments, spares and furnished with necessary technical documentation (instructions, data sheets, records and certificates), as well as with seals and brands.

4.4.3.3 Prior to operational test, the fire extinguishing systems shall be tested by test pressure according to Table 3.13.1, Part VI “Fire Protection” of the Rules for the Classification and Construction (refer to also the requirements of 8.3.1.8).

4.4.3.4 The operational testing of the systems shall be conducted in conformity with the RS-approved programs with the observance of the relevant instructions and guidelines on operation and maintenance of fire extinguishing systems.

4.4.3.5 If the systems are arranged for remote starting, the remote starting system shall be tested simultaneously with the fire extinguishing system.

4.4.3.6 Upon testing, the fire smothering systems shall be made operable (the supplies of extinguishing medium in bottles including the remote starting bottles shall be replenished).

4.4.3.7 Duration of testing the systems shall be sufficient for comprehensive check of their operability.

4.4.3.8 If a prototype ship is provided with a system which has not undergone major modifications against some earlier system arranged by the shipyard involved on a ship of a different type and already subjected to tests in accordance with the program for the prototype ship, testing of the system in accordance with the program for seriesbuilt ships may be accepted.

If a system, before being installed on board ships, underwent tests according to an agreed program, the amount of testing on board the prototype ship may be reduced.

4.4.3.9 In systems fitted with alarm to warn of the fire extinguishing medium release, operation of the alarm shall be checked and actual time of alarm operation until the system starting determined. At the same time, check shall be made on the possibility to evacuate a person in this interval of time from the remotest area of the protected space, as well as on the visibility and audibility of alarms from any area of the protected space with the machinery running.

4.4.3.10 In the water fire main and foam extinguishing systems, reliability of the remote and local starting of pumps shall be checked.

4.4.4 Water fire main system.

4.4.4.1 During the testing of the water fire main system, all the main fire pumps shall be put into operation; along with that, water delivered to the fire main shall be discharged through regular fire hoses and nozzles. Delivery of water to each consumer specified by the system shall be also checked.

4.4.4.2 Part of the fire hoses shall be connected to the remotest and highest hydrants.
4.4.4.3 On the prototype ship, two hydrants most distant in longitudinal extent and one hydrant most distant in vertical extent shall be fitted with pressure gauges to determine water pressure, which shall not be lower than that given in Table 3.2.1.1, Part VI "Fire Protection" of the Rules for the Classification and Construction.

4.4.4.4 On the prototype ship, the capability of ensuring the delivery of two water jets to any area of each space, deck and empty hold shall be checked visually.

4.4.4.5 Where the fire pumps are intended also for other fire extinguishing systems, simultaneous testing of these systems shall be conducted in conformity with the requirements of 3.2.1.11, Part VI "Fire Protection" of the Rules for the Classification and Construction and the sufficiency of water quantity and pressure for parallel operation of all systems shall be checked.

4.4.4.6 Where an emergency fire pump is provided on board, its operation for the intended purpose to supply the common fire main with the closed stop valves in accordance with the requirements of 3.2.4.6 and 3.2.4.7, Part VI "Fire Protection" of the Rules for the Classification and Construction shall be checked.

4.4.4.7 Tests of the permanently installed fire monitors shall be conducted to determine compliance with their specifications.

4.4.4.8 On ships with the water fire main systems kept permanently under pressure, subject to check are existence of pressure in the fire main and automatic actuation of the fire pump when the pressure in the system drops. On ships with remote starting of the pumps, delivery of water to the main without any additional openings of valves in the pump room shall be checked.

4.4.5 Sprinkler system.

4.4.5.1 The following shall be checked prior to the system testing:

- existence of pressure in the system and pressure tank;
- pressure at the remotest sprinklers in accordance with 3.3.2.2, Part VI "Fire Protection" of the Rules for the Classification and Construction.

4.4.5.2 On board ships, operability of the system shall be checked by delivering water through a special test valve on one of the control arrangements. In doing so, the following shall be checked:

1. constancy of pressure in the system with the sprinkler pump running;
2. operation of the pressure maintaining device and the tank water level control device, as well as the timeliness of automatic actuation of the sea water pump;
3. operation of an alarm signal at the control arrangements, at the main fire control station and machinery space. At the main fire control station and machinery space the signal shall indicate section containing the test valve which has opened;
4. operation of the non-return stop valve preventing the water from penetrating from the sprinkler system into the fire main.

After the testing, the system shall be filled with fresh water.

4.4.5.3 On the prototype ship, a test opening-up of at least three sprinkler heads shall be made, whereby the following shall be checked:

1. constancy of pressure in the system with the sprinklers opened up and sprinkler pump running;
2. operation of the pressure maintaining device and the tank water level control device as well as the timeliness of automatic actuation of the sea water pump;
3. operation of an alarm signal at the control arrangements, at the main fire control station and machinery space. At the main fire control station and machinery space the signal shall indicate section containing the sprinkler which has opened.

4.4.5.4 Operability of equivalent sprinkler systems developed on the basis of the Guidelines adopted by IMO resolution A.800(19), as amended, is checked in compliance with the manufacturer recommendations according to the Register-approved program.
4.4.6 Pressure water-spraying system.

4.4.6.1 On prototype ships, the pressure water-spraying system shall be tested in operation; in doing so, the following shall be determined, where possible:

.1 uniform distribution of the sprayed water along the vertical extent and over the area of the protected space, as well as over the surfaces;

.2 agreement between the actual discharge of water provided by one spray nozzle and the design or rated one (a spray nozzle shall be chosen close to the water supply source).

4.4.6.2 On series-built ships, test shall be conducted by actuation of the system sections, and water from the spray nozzles may be carried off through a special water carrying-off arrangement.

4.4.7 Water-screen and drenching system.

4.4.7.1 The water-screen or drenching system on board the prototype ships shall be tested in operation to verify its capability of providing a solid water obstruction or of drenching the protected surfaces; in doing so, the following shall be checked:

.1 consistency between the obtained data of supply rate provided for in the RS-approved design for such systems;

.2 consistency of the actual water discharge and pressure of individual spray nozzles with the rated or design data (at random);

.3 operation of the automatic actuation of the pressure water-screen system (if provided).

On series-built ships, the test shall be conducted by actuation of a single system section, and water from the spray nozzles may be carried off through a special water carrying-off arrangement.

4.4.8 Foam fire extinguishing system.

4.4.8.1 On prototype ships, the foam fire extinguishing system shall be tested in operation; in doing so, the following shall be checked:

.1 availability of the Register Type Approval Certificate;

.2 content of the foam concentrate in water solution, %;

.3 solution pressure before the foam generating equipment;

.4 ensuring normal operability of a design number of the foam applicators or foam generators with at least two water nozzles operating simultaneously;

.5 foam or solution supply rate, in l/min·m²;

.6 foam expansion ratio and drainage time, if prototype tests of the foam-making equipment (monitors, foam applicators and/or foam generators) for type approval in accordance with 4.3.9 and 4.3.14, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision have not been done or have been done using other type (make) of foam concentrate. Instead of testing onboard, these tests may be performed at the laboratory or by the manufacturer. The foam expansion and drainage time of the foam produced shall not differ more than ±10 % of that determined in item 8 of Table 4.3.6 of the above mentioned Part;

.7 technical data of the fixed monitors and consistency of their technical documentation for manufacture with the specifications, as well as operation of the changing-over devices;

.8 arrangement of the monitors basing on the condition of supplying foam to any tank deck area.

4.4.8.2 On series-built ships, the percentage of foam concentrate in the solution in accordance with 4.4.8.1.2 shall be determined, and the entire system shall be checked for operability.

4.4.8.3 On series-built ships where foam of 1000:1 expansion ratio is used, it is necessary to check additionally the functioning of the foam generator discharge orifice closing device (refer to 3.4.3.2.6, Part VI "Fire Protection" of the Rules for the Classification and Construction).

Verification of the requirements in 4.4.8.1.5 and 4.4.8.1.6 shall be made by means of delivering foam by the changing-over device to a measuring tank during at least 30 s.
4.4.9 Carbon dioxide smothering system.

4.4.9.1 To be checked prior to the tests are the presence of brands and documents on the cylinders and tanks, correctness of laying the pipes to the protected spaces, absence of detachable joints if the pipes pass through the accommodation spaces.

4.4.9.2 During the test, the release valves shall be opened for each protected space, and through a test release of the compressed air at a pressure not lower than 0.5 MPa to each protected space in turn air outflow from all nozzles of the space concerned shall be checked.

The tests by releasing carbon dioxide, as specified in 4.4.9.5 and 4.4.9.6, may be dispensed with if there are system calculations confirming proper choice of the manifold, pipe and nozzle outlet diameters, as well as the absence of drastic pressure drops in the system when carbon dioxide flows through it.

4.4.9.3 On ships provided with the low-pressure system, it is necessary to check the pressure in tank and the liquid carbon dioxide level, as well as the actuation of alarm signals:
- at the relief valve operation pressure;
- when carbon dioxide penetrates into the protected space;
- when the level in the tank is lowered;
- in case of one refrigerating plant failure.

4.4.9.4 On prototype ships provided with the low-pressure system, it is necessary to check during the filling of the tanks with carbon dioxide:
- alarm to indicate lowering of the liquid carbon dioxide level;
- alarm to indicate failure of the refrigerating plant;
- agreement between the indications of the device for direct monitoring of the liquid carbon dioxide level and the indications of the remote-reading instrument;
- automatic change-over of the refrigerating plant from the main to emergency source of power as well as automatic starting of one plant when the other plant is rendered inoperative.

4.4.9.5 On prototype ships, the high-pressure system shall be tested by test supply of the rated amount of carbon dioxide into one of the protected spaces (machinery space or hold) with the duration of supply measured in accordance with 3.8.1.5, Part VI "Fire Protection" of the Rules for the Classification and Construction. In so doing, simultaneous opening of the valves of cylinders used in groups shall be ensured.

4.4.9.6 Operation of the breathing valves or their substitutes (refer to 3.1.2.6, Part VI "Fire Protection" of the Rules for the Classification and Construction) shall be checked.

4.4.9.7 Operation of the refrigerating plants of low-pressure system shall be checked (in the same manner as the operation of marine refrigerating installations).

4.4.9.8 Upon finalization of all the tests, at the surveyor's discretion, the cylinders may be subjected to random control weighing, or the amount of carbon dioxide shall be determined in a different approved way.

In the tanks of low-pressure systems, the amount of carbon dioxide shall be determined by special devices or instruments. It shall be not less than the rated one. Admissible deviation is 5%.

4.4.10 Fire-extinguishing systems in machinery spaces and cargo pump rooms.

4.4.10.1 Test in operation for gas fire-extinguishing systems equivalent to carbon dioxide fire-extinguishing systems approved by RS in compliance with IMO circular MSC/Circ.848, as amended; water-based and water mist fire-extinguishing systems approved by RS in compliance with IMO circular MSC/Circ.1165, as amended, as well as fixed water-based local application fire-fighting systems approved by RS in compliance with IMO circular MSC.1/ Circ.1387, as amended, shall be performed in compliance with the manufacturer’s recommendations according to the Register-approved program.

4.4.11 Dry powder system.

4.4.11.1 On prototype ship, tests shall be carried out by putting one powder installation of the fully filled system into action.

In doing so, it is necessary to check: system for remote release from a local hose station; all the filings which may be remotely opened; time from the beginning of release until the
moment when the powder emanates from the spraying gun (not exceeding 30 s); consistency between the spraying gun performance and the specified data.

Where monitors are available, their specified parameters shall also be checked.

4.4.11.2 On series-built ship, the system shall be checked by test release from one of the local hose stations with empty container. In such a case, the cylinders may contain compressed air.

4.4.12 Aerosol fire extinguishing system.

4.4.12.1 On prototype and series-built ships, it is necessary to check the arrangement of the generators of fire extinguishing aerosol (refer to 3.11.1.7 and 3.11.1.8, Part VI "Fire Protection" of the Rules for the Classification and Construction).

4.4.12.2 On prototype and series-built ships, tests shall be conducted by simulating start-up of the generators disconnected from the starting circuits.

During the tests, special simulators shall be connected instead of the generators. Along with that, it is necessary to monitor:

- visual and audible indication of the fire extinguishing remote control device;
- time delay and simulation of the generator start-up;
- disconnection of ventilation in the protected space; activation of the emergency alarm system in the protected space.

4.4.12.3 On prototype and series-built ship, it is necessary to check resistance of the system to false operation through connecting a special simulator of the starting unit to each starting circuit with the generators disconnected from the starting circuits.

The tests shall be conducted under operating conditions when all the consumers of electrical power are loaded to the practical maximum.
4.5 FIRE-FIGHTING OUTFIT, SPARE PARTS AND TOOLS

4.5.1 Subject to the Register technical supervision are completion, marking, location and attachment of the items of fire-fighting outfit, spare parts and tools referred to in Table 4.1.1. During survey of fire-fighting outfit items, their compliance with Type Approval Certificate or certificates issued by the Register shall be checked.

4.5.2 During survey (according to sheet or List), it is necessary to check location of fire-fighting outfit, spare parts and tools in accordance with the RS-approved fire plans.

4.5.3 Portable fire motor-pumps shall be checked for reliable operation (refer to 5.1.17, Part VI “Fire Protection” of the Rules for the Classification and Construction) at the lightest seagoing draught.
4.6 SURVEY OF MODU/FOP FIRE PROTECTION

4.6.1 General.

4.6.1.1 Technical supervision during manufacture of the MODU/FOP fire protection products shall be performed in compliance with Section 4, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and technical supervision during installation and testing – in compliance with Section 4 of the Guidelines.

4.6.1.2 Technical supervision during manufacture of the fire detection system and alarm system on rise of explosive gases concentration shall be performed in compliance with Section 10, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and technical supervision during installation and testing — in compliance with Section 10 of the Guidelines.

4.6.1.3 The present Chapter contains additional requirements to installation and testing of water fire main system and fixed gas detection and alarm system.

4.6.2 Technical supervision.

4.6.2.1 Water fire main system.

4.6.2.1.1 When performing technical supervision during installation and testing of water fire main system, in addition to 4.4 the following shall be checked:

- protection of the main pipeline by the MODU/FOP structures against damages and its arrangement with regard to hazardous zones;
- arrangement of the shut-off valves on the main pipeline to provide its optimum operation when any of its part is damaged;
- capability of remote operation of the fire and submersible sea water pumps and hard-to-reach valves are capable from the main control station, and of those located on non-self-propelled MODU, from the central control station;
- total capacity and head of the fire pumps (for the prototype MODU/FOP); sufficient capacity of the sea water storage tank for operation of two hand-operated fire monitors within a period prescribed by Part VI "Fire Protection" of the MODU/FOP Rules when the submersible pumps are non-operative (for prototype self-elevating MODU). Check shall be performed with the minimum sea water in tanks.

4.6.2.2 Gas detection and alarm system.

4.6.2.2.1 During survey of the automatic fixed gas detection and alarm system during installation, the following shall be checked:

- arrangement of the sampling devices or oil gas and vapour detectors in compliance with 4.3.8 and 4.3.9, Part VI "Fire Protection" of the MODU/FOP Rules;
- arrangement of the sampling devices or hydrogen sulphide detectors in compliance with 4.3.10, Part VI "Fire Protection" of the MODU/FOP Rules;
- compliance of design of the detectors and devices located in hazardous zones and areas with 2.11, Part X "Electrical Equipment" of the MODU/FOP Rules; availability and composition of the portable oil gas and vapour detectors;
- availability and composition of the portable hydrogen sulphide detectors.

4.6.2.2.2 When testing the automatic fixed gas detection and alarm system, the following shall be checked:

- maximum time required for supply of sample air to any detector not more than 1 min;
- giving of visual and audible signals at the appropriate local control station, drill master's cabin and central control station when the concentration of oil gases and vapours is not more than 25 % and 60 % of the lower explosive limit;
- automatic starting of ventilation for operation of the maximum air changes (least 20 air changes per hour) when the gas concentration in the room reaches 20 ± 10 % of the lower explosive limit;
automatic cutting-off of the sampling devices or oil gas and vapour detectors operating on thermochemical principle when hydrogen sulphide concentration reaches 10 mg/m³ with a signal being given to the central control station;
giving alarm signal to indicate failure in the gas detection and alarm system. To reach the above parameters, the system shall be tested in operation under the most realistic conditions, and the detectors and devices to be tested shall have the documents confirming the results of their satisfactory tests on the manufacturer’s test bed under actual conditions.
5 MACHINERY

5.1 GENERAL

5.1.1 The provisions of this Section apply in technical supervision of the machinery listed in the RS Nomenclature.

The Section establishes the procedure of the technical supervision to be performed by the Register during installation and testing of machinery on board the ship and FOP.

5.1.2 General provisions for the organization of the technical supervision are given in Section 1.

5.1.3 For the purpose of this Section, the following abbreviations have been adopted:

   AT — astern turbine;
   BDC — bottom dead centre;
   CCP — controllable pitch propeller.
   FOP — fixed offshore platform;
   FPU — floating offshore oil-and-gas product unit;
   GT — gas turbine;
   GTI — gas turbine installation;
   HPC — high-pressure compressor;
   ICE — internal combustion engine;
   LPC — low-pressure compressor;
   MGTI — main geared turbine installation;
   MODU — mobile offshore drilling unit;
   TDC — top dead centre.

5.1.4 Prior to installation, the RS surveyor shall check the presence of the RS-approved documentation as required by Parts I "Classification", VII "Machinery Installations" and IX "Machinery" of the Rules for the Classification and Construction.

5.1.4.1 Quality standards of the shipyard (or machinery manufacturer) for installation and testing of the ship machinery shall be reviewed and agreed prior to commencement of technical supervision (refer also to 5.3).

5.1.5 When surveying the installation, it is necessary to check compliance with the requirements of the RS-approved technical documentation, as well as of the Rules for the Classification and Construction imposed on the equipment of machinery spaces, control stations, arrangement of passageways, means of escape and ladders, free access for maintenance and repair of machinery, boilers, piping, fittings, etc.

5.1.6 When installing electrified equipment, the requirements of Section 10 shall be met.

5.1.7 Pipelines of the machinery and machinery installations shall be verified and subjected to hydraulic tests in accordance with the requirements of Section 8.

5.1.8 Surveys of the automatic control, monitoring, alarm and protection systems for the machinery shall be carried out in accordance with Section 12.

5.1.9 The RS surveyor shall ascertain that the machinery has documents confirming manufacture thereof under the technical supervision of the Register (refer also to 5.1.11).

5.1.10 Numerical values for test modes and duration, as well as numerical criteria for installation works given in this Section are provided for reference. Prior to commencement of construction, other quality criteria given in the recognized national or international standards, or manufacturers’ documents/instructions may be agreed with the RS Branch Office.

5.1.11 Tests and checks specified in this Section are based on an assumption that the machinery has been tested at the firm (manufacturer) in compliance with the requirements of Section 5, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and have the documents confirming their manufacture and testing under the Register technical supervision.
5.1.12 In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of the machinery in substantiated cases.
5.2 SURVEY PLANNING

5.2.1 Prior to commencement of survey of the machinery of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account production process of the specified ship at the shipyard (refer to 13.3, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision). The agreement shall be in accordance with Tables 5.4.1, 5.6.1, 5.9.1, 5.11.1, 5.12.1 and with due regard to the requirements of appropriate chapters of the Section. The Register and the shipyard shall agree the procedure for verification of the report on failure analysis of propulsion and steering on passenger ships specified in Section 11, Part VII "Machinery Installations" of the Rules for the Classification and Construction.

The shipbuilder shall be informed about that at a kick-off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

5.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

5.2.3 Quality standards for installation and testing of the machinery shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

5.2.4 Any changes to the kick-off meeting records shall be agreed and documented.
5.3 GENERAL PROVISIONS FOR THE TECHNICAL SUPERVISION DURING INSTALLATION OF MACHINERY

5.3.1 When installing machinery on seatings, the quality of retention of the bench assembly shall be checked; in doing so, use shall be made of the bases, method of attachment and method of control, admissible deviations and initial data specified by the shipyard or manufacturer and which make it possible to carry out installation and control without stripping down the sets.

5.3.2 It shall be confirmed that the installation and mounting of the main machinery on board the ship is performed upon finalization of all assembly and welding operations on the ship's hull in way of the machinery and boiler compartment.

5.3.3 The machinery is attached to the seating by the method agreed with the Register. When the procedure for installation and mounting of the machinery is agreed, the recommendations given in Appendix 2 to this Section may be taken into account.

5.3.4 No matter what the method of mounting the machinery on seating, the following requirements shall be met:

.1 holes in the seatings used for the fastening bolts shall be so arranged that the distance from their centres to the edge of seatings, stiffeners or vertical plates is not less than 1,5 the bolt diameter;

.2 joints by tightly fitted bolts shall be made to shrinkage fit tolerances with marking of the bolts in their positions;

.3 bolt heads and nuts shall fit tightly to one another, for which purpose the places where the bolt heads and nuts fit against the seatings and feet or frames of machinery shall be undercut, with the perpendicularly to the hole axis being observed, to a depth not exceeding 10 % of the thickness of the machinery foot and machinery frame and seating flange;

.4 fastening bolt tightening forces shall comply with the requirements of drawings;

.5 fastening bolts and nuts shall be reliably protected against working loose;

.6 pipes, cables, etc. shall be connected to the completely attached machinery without any tension, angularity and displacement of the coupling flanges and other joint components.

5.3.5 Irrespective of the mounting and aligning methods of the main machinery, final check of these operations shall be carried out while the ship is afloat.

Any deviations from the RS-agreed procedure of installation and mounting of machinery shall be agreed with the Register in each particular case upon submission of the relevant technical background.

5.3.6 During technical supervision of the mounting of the attached machinery, piping equipment, fittings and instruments removed from the engine during transportation, it is necessary to make sure that they were installed having regard to the requirements of drawings and that, after assembly, their joints were subjected to tightness test.

5.3.7 When testing the insulation of heated surfaces, it is necessary to make sure that the surfaces of machinery, equipment and piping with temperatures above 220 °C, which may be impinged as a result of a fuel system failure, shall be properly insulated, as well as structural measures shall be taken to prevent any oil that may escape under pressure from any pump, filter or heater from coming into contact with heated surfaces. The insulating materials and surface of insulation shall be in accordance with the requirements of 2.1.1.5, Part VI "Fire Protection" of the Rules for the Classification and Construction.
5.4 MAIN AND AUXILIARY INTERNAL COMBUSTION ENGINES OF POWER OUTPUT
55 KW AND OVER

5.4.1 Surveys during mounting and testing of the engines on board the ship shall be performed according to Table 5.4.1.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Types of verification</th>
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<tbody>
<tr>
<td></td>
<td></td>
<td>Review of documents</td>
</tr>
<tr>
<td></td>
<td></td>
<td>and visual examination</td>
</tr>
<tr>
<td>1</td>
<td>Installation on seating</td>
<td>+</td>
</tr>
<tr>
<td>2</td>
<td>Assembly and alignment of engine</td>
<td>+</td>
</tr>
<tr>
<td>3</td>
<td>Alignment of engine</td>
<td>–</td>
</tr>
<tr>
<td>4</td>
<td>Mounting of attached machinery</td>
<td>+</td>
</tr>
<tr>
<td>5</td>
<td>Tests of alarm and protection systems</td>
<td>+</td>
</tr>
<tr>
<td>6</td>
<td>Tests of machinery and accessories supporting operation of engine</td>
<td>+</td>
</tr>
<tr>
<td>7</td>
<td>Operational tests of engine</td>
<td>+</td>
</tr>
</tbody>
</table>

5.4.2 During survey of the mounting of the main engines installed on board the ship as a unity set, the scope of supervision may be restricted by items 1, 3, 5, 6 and 7 of Table 5.4.1.

5.4.3 When the main engine is installed on board the ship in knock-down form, it is necessary to check the assembly operations in accordance with the procedure of the manufacturer, beginning from the mounting of the bed plate.

The method of check and accepted deviations of the bed plate from rectilinearity and planeness shall be established by the engine manufacturer.

5.4.4 Technical supervision over the correctness of the assembly and alignment of the engine components and units shall consist in verification of the compliance of the mounting clearance with the manufacturer's recommendations or data obtained on the manufacturer's bench.

The check shall be performed by verification of the clearance tables submitted by the manufacturer and by selective measurements.

5.4.5 Alignment of the crankshaft (flange joint) with the thrust shaft or reduction gear shall be checked simultaneously with the alignment of the shaft line or thereafter.

The procedure of checking the alignment shall be specified depending on the design and location of the thrust bearing, flywheel, coupling and the method of checking in the workshop and during mounting.

Alignment of the main engine with the shaft line or reduction gear shall be checked simultaneously with the alignment of the shaft line or thereafter.

Alignment of the engine or reduction gear with the shaft line shall be performed in accordance with the requirements of Section 6.

5.4.6 In case of rigid connection of the aligned shafts, deviations from the rectilinearity of the bed plate, fit of the crankshaft journals to the bearings, deformation of the crank throws (crank web deflection), run-out of the adjacent journals of the crankshaft and shaft mated therewith shall not exceed values specified by the engine manufacturer.
5.5 AUXILIARY INTERNAL COMBUSTION ENGINES OF POWER OUTPUT BELOW 55 KW

5.5.1 Survey during mounting of the auxiliary ICE intended for connection with the driven machinery by means of non-rigid joint as well as engines mated with the driven units at the firm (manufacturer) and installed on board ship shall be carried out in accordance with items 1 and 7 of Table 5.4.1.

During survey of mounting of the auxiliary ICE mated rigidly with the driven units on board ship, it is necessary to check also the alignment of shaft on common bed plate.
5.6 MAIN STEAM TURBINES AND ELECTRIC GENERATOR TURBINES

5.6.1 Survey during mounting and testing of main turbines and geared turbine installations on board the ship shall be carried out in accordance with Table 5.6.1.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Types of verification</th>
<th>Review of documents and visual examination</th>
<th>Check of mounting</th>
<th>Trials</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Installation of turbines, reduction gears on seating</td>
<td></td>
<td>+</td>
<td>+</td>
<td>–</td>
</tr>
<tr>
<td>2</td>
<td>Installation of controls, attached machinery and devices</td>
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<td>–</td>
</tr>
<tr>
<td>3</td>
<td>Alignment of turbines with shaft lines and reduction gears</td>
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<td>–</td>
<td>+</td>
</tr>
<tr>
<td>4</td>
<td>Systems, machinery and devices supporting the unit</td>
<td></td>
<td>+</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>5</td>
<td>Check in operation</td>
<td></td>
<td>+</td>
<td>–</td>
<td>+</td>
</tr>
</tbody>
</table>

5.6.2 When checking the mounting of the MGTI and electric generator turbines on seating it is necessary to be guided by the requirements of the RS-approved drawings.

5.6.3 The turbines and geared turbine installations delivered assembled (as unity sets) to ships shall be subjected to check as follows:

1. installation of the turbine casing and reduction gear on seating on the load gauges shall be checked with the bench loads represented thereon; along with that, it is necessary to check the engagement contact in the gearing and alignment of the turbine and reduction gear with the installed ship’s shafting in accordance with the provisions of Section 6.

The installation may be performed also by other method approved by the Register;

2. fitting of the chocks (shims) to the turbine casing flanges, reduction gear to the seating shall be checked by feeler gauge and by blueing;

3. alignment of the turbine and reduction gear and installation thereof on seatings shall be checked;

4. all the checks shall be performed with the pipes connected;

5. displacement and sag of the turbine rotors shall be checked;

6. condition of the sliding supports of the turbines and clearances therein shall be checked.

5.6.4 When checking the installation of the controls, attached machinery and devices on the turbine set, it is necessary to make sure that:

1. the upper part of the stator has been fastened by standard bolts and studs;

2. the manoeuvring and isolating, shut-off and nozzle, throttle and bleed valves, servomotors, slides and overspeed devices, regulators and their actuators, as well as all other steam distribution, regulation and protection devices have been installed in conformity with drawings and marking;

3. the condenser has been fastened with the tightness of the detachable joints ensured and the installation of its spring supports and piping allows sufficient mobility during thermal displacements of the turbine and condenser;

4. fixing of the casing expansion and axial rotor position indicators corresponds to the cold state of the turbine;

5. mounting of the pipes connected to the turbine set has been carried out with due regard to the possibility of compensating for the thermal elongation of pipes and turbine casings;

6. fasteners for the mounting of assemblies operating under high temperature conditions have no thread damages, deformations and other defects.
5.6.5 The alignment of the turbine rotors with reduction gear by half-couplings shall be checked with the use of two pairs of pointers or by other RS-approved method which precludes axial displacement of the rotors and reduction gear shafts; in doing so, it is necessary to make sure that:

.1 the turbine set has been completely attached to the seating;
.2 appropriate measures have been taken to preclude misalignment during thermal displacements of the turbine casings on movable supports;
.3 actual angularities and displacements of the shafts to be aligned do not exceed those given in drawings;
.4 the alignment of the reduction gear shaft with the shaft line has been performed in accordance with Section 6.

5.6.6 Where the turbine sets are delivered to ship in knock-down form or when these are repaired on board ship, the verification thereof shall be based on the appropriate requirements of Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.
5.7 AUXILIARY STEAM TURBINES

5.7.1 Surveys during mounting and testing of the auxiliary steam turbines shall be performed according to Table 5.6.1.
5.8 GAS TURBINE ENGINES AND ELECTRIC GENERATOR GAS TURBINES

5.8.1 Survey of GTI and electric generator gas turbines shall be performed according to Table 5.6.1.

5.8.2 The requirements for fastening, mounting, as well as other provisions set out in 5.3 and 5.6 cover the GTI depending on the type and purpose thereof.

5.8.3 The control over the fastening of the GTI casings to seating shall consist in verification that the requirements of the manufacturer stemming from the design features of the units and the requirements of drawings have been met.

5.8.4 The alignment of the GTI sets with one another, with the thrust bearing and with the shaft line shall be checked with the measurements of angularities and displacements of the shaft axes; along with that, it is necessary to make sure that:

.1 the deformation measured with the use of rules, strings, hydrostatic levels, optical devices and other means with an accuracy not less than 30 % of the established tolerance does not exceed values specified by the manufacturer of the set;

.2 the alignment of the shaft line with the GTI sets or the main thrust bearing (unless it is incorporated into the GTI) shall be carried out in accordance with the requirements of Section 6;

.3 the shafts of the GTI sets have been installed in axial direction in positions specified in the service log (if the service log contains no instructions, the shafts shall be shifted to mid-position) with clearances for thermal expansion ensured;

.4 the mutual position of the shafts to be aligned corresponds to the marking;

.5 the GTI frame has been properly fastened to the gas vent housing and the latter has been properly fastened to the seating;

.6 the gas vent housing is clean.
### 5.9 GEARS AND DISENGAGING COUPLINGS OF MAIN MACHINERY

**5.9.1** Survey during mounting and testing of the gears and disengaging couplings of the main machinery on board the ship shall be performed in accordance with Table 5.9.1.

**5.9.2** Mounting of the gears and disengaging couplings of the main machinery, alignment with the engine and shaft line on board the ship shall be performed in accordance with the RS-approved drawings depending on their type and design and with due regard to the manufacturer’s recommendations (refer also to 5.6.5).

**5.9.3** During survey of the gears and couplings, particular attention shall be given to fastening of the assemblies and components to the driving and driven shafts involved in transmitting torque; installation of shafts and couplings shall provide for necessary clearances uniformly distributed around the entire circumference of the driving and driven parts with the couplings in disengaged position.

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<td>–</td>
<td>–</td>
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<tr>
<td>2</td>
<td>Alignment with shaft line</td>
<td></td>
<td>+</td>
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</tr>
<tr>
<td>3</td>
<td>Check in operation</td>
<td></td>
<td>+</td>
<td>–</td>
<td>+</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Types of verification</th>
<th>Review of documents and visual examination</th>
<th>Check of mounting</th>
<th>Trials</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Installation of gears and disengaging couplings on seating</td>
<td></td>
<td>+</td>
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<td>–</td>
</tr>
<tr>
<td>2</td>
<td>Alignment with shaft line</td>
<td></td>
<td>+</td>
<td>–</td>
<td>–</td>
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<tr>
<td>3</td>
<td>Check in operation</td>
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</tbody>
</table>

Once the shaft line flanges or other power consumer have been connected with the gear, it is necessary to check the gearing teeth-contact pattern which shall not be less than specified in Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.
5.10 GEARS OF AUXILIARY MACHINERY

5.10.1 Survey during mounting and testing of the gears of the auxiliary machinery on board the ship shall be performed in accordance with the requirements of 5.9 and Table 5.9.1, depending on the gear type.

When checking the gear engagement contact, the teeth-contact pattern shall not be less than specified in Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.
5.11 AUXILIARY MACHINERY

5.11.1 Survey during mounting and testing of the auxiliary machinery on board the ship shall be performed in accordance with Table 5.11.1.

5.11.2 Technical supervision during the mounting and testing of the auxiliary machinery driven by the main machinery shall be performed during the survey of the main machinery.

5.11.3 The methods of installing the auxiliary machinery on seating, as well as the methods of checking the quality of the mounting and alignment shall comply with the manufacturer’s requirements and the RS-approved drawings.

5.11.4 When checking the alignment of the auxiliary machinery installed on common bed plate and the machinery installed directly on seating, it is necessary to make sure that they have been securely fastened.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Types of verification</th>
<th>Review of documents and visual examination</th>
<th>Installation on seating</th>
<th>Alignment</th>
<th>Trials</th>
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<tr>
<td>1</td>
<td>Starting air compressors</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2</td>
<td>Turbochargers</td>
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<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3</td>
<td>Main boiler blowers</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>4</td>
<td>Pumps:</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td></td>
</tr>
<tr>
<td></td>
<td>- cooling water pumps of main engines</td>
<td></td>
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<tr>
<td></td>
<td>- circulating pumps of main condensers</td>
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<tr>
<td></td>
<td>- lubricating oil pumps of main diesel engines</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td>+</td>
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<tr>
<td></td>
<td>- boiler feed water pumps</td>
<td>+</td>
<td>+</td>
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<td>+</td>
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<tr>
<td></td>
<td>- condensate pumps</td>
<td>+</td>
<td>+</td>
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<td>+</td>
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<tr>
<td></td>
<td>- boiler burner pumps</td>
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<tr>
<td></td>
<td>- fuel oil transfer pumps</td>
<td>+</td>
<td>+</td>
<td>—</td>
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<tr>
<td></td>
<td>- bilge pumps</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td>—</td>
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<tr>
<td></td>
<td>- fire pumps</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
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<tr>
<td></td>
<td>- ballast pumps</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
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<tr>
<td></td>
<td>- cargo pumps</td>
<td>+</td>
<td>+</td>
<td>—</td>
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<td>5</td>
<td>Motor-pumps:</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
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<tr>
<td></td>
<td>- fire motor-pumps</td>
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<tr>
<td>6</td>
<td>Steam-jet ejectors of condensers</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td>—</td>
</tr>
<tr>
<td>7</td>
<td>Circulating pumps of waste-heat boilers</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>8</td>
<td>Oil fuel and lubricating oil separators</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>Bilge ejectors</td>
<td>+</td>
<td>+</td>
<td>—</td>
<td>+</td>
<td>—</td>
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<tr>
<td>10</td>
<td>MODU and FPU submerged replenishment pumps</td>
<td>+</td>
<td>+</td>
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<td>+</td>
<td>+</td>
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<tr>
<td>11</td>
<td>Arrangements for lifting and lowering of:</td>
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<td>+</td>
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<td>+</td>
</tr>
<tr>
<td></td>
<td>MODU and FPU</td>
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<tr>
<td></td>
<td>MODU and FPU pipes</td>
<td>+</td>
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<td>—</td>
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<td>—</td>
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</tbody>
</table>

5.11.5 Coaxiality of the shafts of machinery delivered to ship aligned on a common bed plate may be checked subject to availability of the machinery manufacturer’s requirements or in cases of possible misalignment.

5.11.6 Coaxiality of the shafts of mated machinery with the drive and actuating mechanism enclosed in a single casing shall generally not be checked.

5.11.7 When checking the alignment of the auxiliary machinery, their disalignment, depending on the joint type, shall not exceed the standards specified in the drawings.
5.12 DECK MACHINERY

5.12.1 Survey during mounting and testing of the deck machinery on board the ship shall be performed in accordance with Table 5.12.1.

5.12.2 Technical supervision during the mounting, installation and testing of the electrical equipment, systems, pressure vessels, hydraulic and diesel engine drives used in the deck machinery shall be performed in accordance with the relevant sections of the Guidelines.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Types of verification</th>
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<tbody>
<tr>
<td></td>
<td></td>
<td>Review of documents and visual examination</td>
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<tr>
<td></td>
<td></td>
<td>mooring</td>
</tr>
<tr>
<td>1</td>
<td>Steering gears</td>
<td>+</td>
</tr>
<tr>
<td>2</td>
<td>Windlasses and anchor capstans</td>
<td>+</td>
</tr>
<tr>
<td>3</td>
<td>Mooring capstans and winches</td>
<td>+</td>
</tr>
<tr>
<td>4</td>
<td>towing</td>
<td>+</td>
</tr>
<tr>
<td></td>
<td>boat</td>
<td>+</td>
</tr>
</tbody>
</table>

5.12.3 Before the deck machinery is installed onboard ship, the following shall be checked:

1. availability of brands and documents according to the supervision type established by the RS Nomenclature;
2. completeness of delivery.

5.12.4 Upon completion of the mounting work, the deck machinery shall be examined in order to scrutinize quality of the mounting and to verify its compliance with the RS-approved working drawings for installation.
5.13 MECHANICAL TELEGRAPHS

5.13.1 When surveying the mechanical telegraphs, it is necessary to check the correctness in executing orders to go ahead and to go astern, alternately, in all ranges.

5.13.2 It is necessary to check the interlocking device, which ensures correctness in executing the given order.
5.14 FANS OF MACHINERY AND OTHER SPACES

5.14.1 Mounting of the fans shall be performed in accordance with the drawings and the requirements of 5.11.

5.14.2 Surveys during mounting and testing of the fans on board the ship shall be performed in accordance with the RS-approved program.
5.15 MOTORS AND PUMPS OF HYDRAULIC SYSTEMS

5.15.1 Mounting of the motors and pumps of hydraulic systems on board the ship shall be performed in accordance with the requirements of 5.11 and drawings.

5.15.2 Surveys during mounting and testing of the motors and pumps of hydraulic systems on board the ship shall be performed in accordance with the RS-approved program together with the systems, which incorporate them.
5.16 MOORING TRIALS

5.16.1 General.
5.16.1.1 Operational tests of the main and auxiliary machinery on mooring trials are aimed at verifying the quality of their mounting and adjusting, as well as verifying the readiness of this machinery for the sea trials of the ship.
5.16.1.2 The mooring trials of machinery and sets shall be conducted in the presence of the RS surveyor in accordance with a program approved by the Register.
5.16.1.3 Machinery and equipment, which survey does not require putting the ship to sea trials, shall be definitely tested in operation on mooring trials.
5.16.1.4 When verifying machinery in operation on the mooring trials, the checks of machinery area may be combined with checks of electrical and ship's service areas.
5.16.1.5 Mooring trials of electrified auxiliary machinery may be conducted with power supply from the shorebased power sources.
5.16.1.6 In case of forced interruptions in operation of the machinery during their trials, on the agreement with the RS surveyor, a decision shall be taken to continue the operation mode, to increase its duration or to repeat it with due account of the causes of the machinery stopping.
5.16.1.7 It is necessary to take down the values of the propulsion plant parameters and to check compliance thereof with the specified ones.
5.16.1.8 The machinery shall be submitted to mooring trials upon finalization of mounting work, verification of the quality of mounting, assembly and adjustment in association with systems and devices.
5.16.1.9 During the mooring trials, it is necessary to check the manual, remote and automatic control, check the instruments, mechanisms, protection, interlocking and alarm devices in operation for their designated purposes, as well as to check the facilities for communications between the machinery space and navigation bridge and other control stations.
5.16.1.10 Trials shall include verification of the fulfillment of the requirements in 2.1.6, 2.1.9, 3.1.2 – 3.1.6, 3.1.8 – 3.1.11, 3.2.2, 3.2.3, 3.2.6, 3.3.1, 3.3.3 and 3.3.5, Part VII "Machinery Installations" and 6.1.2 – 6.1.4, Part IX "Machinery" of the Rules for the Classification and Construction.
5.16.1.11 When testing the remote and automatic systems, alarm and protection systems, the requirements of Section 12 shall be met.

5.16.2 Main and auxiliary ICE.
5.16.2.1 Tests of the machinery, devices and systems supporting operation of the engine shall precede testing of the engine in order to check their availability for operation; whilst so doing, the following systems shall be checked together with machinery, devices, apparatus and facilities: lubricating oil, water cooling, fuel oil, starting air, exhaust gas.
5.16.2.2 Starting properties of the engine shall be checked on the engine prepared for operation as required by the manufacturer’s manual; in so doing, the following parameters shall be checked:
   .1 ambient temperature in machinery space;
   .2 water temperature in cooling system;
   .3 lubricating oil temperature in lubrication system;
   .4 number and sequence of starts and reversals without replenishment of air receivers (in case of reversible engines, starts shall be performed alternately between ahead and astern);
   .5 duration of starts and reversals;
   .6 pressure in air receivers before and after each start and reversal;
   .7 minimum pressure in air receivers that provides starting;
   .8 number of starts and voltage of storage battery at the beginning and end of the tests in case of electrically started engines.
5.16.2.3 When the engine operates in the modes stipulated by the program approved by the Register, it is necessary to check the following parameters:

1. power output;
2. speed;
3. gas temperature in exhaust piping;
4. water temperature and pressure in cooling system;
5. pressure and temperature in lubrication system, delivery of cylinder oil;
6. back pressure in exhaust piping;
7. temperature of air entering the engine;
8. barometric pressure;
9. compression pressure in cylinders;
10. maximum combustion pressure;
11. mean indicated pressure;
12. exhaust gas temperature by cylinders;
13. scavenging air pressure (in case of two-stroke engines);
14. cooling water temperature at cylinder outlet;
15. lubricating oil temperature at cooler inlet and outlet;
16. fluid pressure and temperature at inlet of piston cooling system;
17. fluid temperature at outlet of piston cooling system (by cylinders);
18. temperature at cooler inlet and outlet in closed cooling system;
19. speed of independently-driven air blowers and turbochargers;
20. air pressure in scavenging manifold;
21. exhaust gas pressure and temperature at gas turbine inlet;
22. air temperature at air cooler inlet and outlet;
23. pressure (vacuum) in crankcase;
24. fuel oil temperature and viscosity at engine inlet.

5.16.2.4 Parameters shall be measured at the steady thermal state of the engine not less than twice in the operation modes with a duration not over 2 h and at least once during the subsequent full 2 h or part thereof.

5.16.2.5 Some parameters need not be measured if the design of the engine or set eliminates the possibility of making the measurements.

5.16.2.6 Test modes of ICE on mooring trials shall be determined from Appendix 1 to this Section.

The duration of the mode-to-mode transfer shall depend on the thermal state of the engine and termination of all transients.

5.16.2.7 Engines of diesel-electric ships, as well as engines driving CPP or tested with the use of loading devices may be checked during the mooring trials in the sea trials modes and the findings at the rated power and speed shall be consistent with the engine specifications and bench test data.

5.16.2.8 When testing speed governors and over-speed devices of the main and auxiliary engines, it is necessary to check stability of their operation, as well as consistency of their characteristics with the requirements of the RS-approved documentation in case of manual or remote (non-automatic) control of the speed governors. Subject to checking are the following:

1. the value and duration of the dynamic over-speeding when the load changes abruptly. Change of the load shall be determined depending on the purpose of the diesel installation, method of transmitting power to the consumer and availability of special requirements for the installation concerned in the RS-approved documentation;
2. the statistical error of the engine speed governing system shall be determined by changing the load on the engine from 0 to 100 % of the rated load at unchanged speed setting of the governor (for the static governors only);
3. the stability of maintenance of the set speed (insensitivity of the governing system);
.4 the possibility of obtaining, with the use of governor, a stable speed over the entire range of speed changing;
.5 the power distribution among the engines operating in parallel only with the use of the speed governors;
.6 the operation of devices built in the governor or connected directly therewith and intended to limit the maximum fuel feed depending on various parameters (e.g. during starting of engine, low pressure of scavenging air, depending on the set or true speed, etc.), as well as operation of devices precluding operation of the engine within the critical speed zone and devices limiting the engine load (CPP).

5.16.3 Main and auxiliary steam turbines and turbine installations.

5.16.3.1 During the mooring trials the following shall checked:
.1 absence of steam leaks in the turbine joints;
.2 absence of abnormal noise during starting and operation of the turbines and reduction gears;
.3 absence of leaks and watering of the lubricating oil;
.4 performance of the expansion joints on the main steam line, manifolds and other steam pipes;
.5 performance of the movable supports of turbines and condensers;
.6 operation of the steam suction and gland-sealing system during manual and automatic regulation;
.7 operation of the blowing system to ensure complete removal of condensate from all stages and spaces of the turbine;
.8 steadiness in maintaining the required vacuum in the condenser;
.9 time of free run-out and sufficiency of lubricating oil for the time of run-out;
.10 performance of the chokes on the branches of the circulating lubrication line;
.11 operation of the overspeed devices and speed governor in conformity with 5.16.2.8.

5.16.3.2 When the installation operates in steady thermal modes, it is necessary to note:
.1 turbine and propeller (generator) speed;
.2 pressure and temperature of the live steam;
.3 steam pressure in the intermediate stages and bleed chambers of turbines;
.4 steam pressure in the gland-sealing system and vacuum in the suction chambers;
.5 vacuum in the condenser;
.6 lubricating oil pressure in the lubrication and regulation system;
.7 lubricating oil temperature at oil cooler inlet and outlet;
.8 axial position of the rotor and thermal expansion of the turbine casings;
.9 condensate temperature, level and salinity in the condenser.

5.16.4 Main and auxiliary gas turbines and gas turbine installations.

5.16.4.1 During the mooring trials of GTI, it is necessary to check the following characteristics with due account of the GT design:
.1 free rotation of the turbine rotors by measuring the run-out time during turbine motoring;
.2 operation of the starting devices of the GTI and the starting and main fuel oil systems;
.3 steady maintenance of the set rates throughout the whole range of operating speed;
.4 reliability of the actuation and shut-down of the necessary units in the "starting", "operation", "stop" and "manoeuvring" modes;
.5 operation of the unified control of GTI and CPP;
.6 absence of gas leaks through the joints of the turbines and compressors in all operation modes;
.7 reliable performance of the end seals of the turbines and compressors the total air leaks through which shall not exceed 1.5 % of the low-pressure compressor capacity;
.8 automatic reduction of the fuel supply when the gas temperature before the turbine nozzles exceeds the allowable one;
.9 steady burning of the fuel in all the operating modes of GTI; ease of maintaining the installation and possibility of replacing the burners and inspecting the flame tubes without the installation being out of action;

.10 effectiveness of cleaning the burners, regenerators, compressors and turbines without the necessity of stopping the GTI by methods recommended by the firm (manufacturer);

.11 absence of the compressor surge and vibration of the installation components, induced by the GTI operation;

.12 absence of the critical speed zone within 120 % of the GTI maximum speed;

.13 possibility of the GTI operation without any limitation in time with the power not less than 20 % of the rated power at full interruption of the water supply to the air cooler;

.14 steady continuous astern operation of the AST during not less than 15 min with a speed not less than 70 % of the rated speed and with power not less than the rated ahead power;

.15 time required for transfer to operation of one GT where more than one GT driving a single propeller shaft are available;

.16 time required for resetting the valves from the "full ahead" to "full astern" position for GTI with AST;

.17 reliable starting and operation of GTI at the CPP fixed pitch;

.18 operation of the torsiometer within the operating speed;

.19 automatic reduction of fuel supply when the lubricating oil pressure drops and interruption of fuel supply when the speed exceeds the permissible value;

.20 air pressure in the systems:
  - turbine overspeeding protection;
  - reversing device control;
  - AST friction clutch control;
  - air lead tape control;
  - starting;
  - LPC, HPC space relieving;

.21 smooth growth of the electric starter current during 4 — 6 s:
  - during motoring,
  - during false starting,
  - during starting;

.22 time required for GTI to be put on idling mode;

.23 HPC idling speed;

.24 LPC idling speed.

5.16.4.2 When testing machinery, devices and systems supporting the GTI, it is necessary at the same time to check correctness of their mounting and adjustment, as well as readiness of the GTI for operational tests; along with that it is necessary to check:

.1 operation of the fuel oil, lubricating oil, water cooling and air systems with supporting machinery, instruments, apparatus and devices;

.2 shaft-turning gear and its interlocking with the GTI starting device;

.3 proper performance of the local and remote control, alarm and protection systems;

.4 reliability of the local and remote control and operation of the quick-closing devices for emergency shut-down of GTI in any operation mode;

.5 operation of the device preventing the burners to be removed unless the fuel oil and gas are preliminarily shut off;

.6 possibility of igniting the fuel oil in other chambers from the chamber with ignition unit where the combustion chambers are of modular construction;

.7 operation of the reduction gear and shafting brakes;

.8 presence of the clearance for thermal expansion of the gas vents and other piping connected to GTI, and the tightness thereof;
During the tests it is necessary to note:
parameters defining the operation of the speed governors and overspeed devices of GTI in accordance with 5.16.2.8:
temperature of the working medium at various cycle points;
thermal expansion of the GTI casings from the standard indicators;
pressure and temperature of the lubricating oil, cooling water and fuel oil.

5.16.5 Main gearing.
5.16.5.1 Gearing, reduction gears and disengaging couplings when checked in operation during mooring and sea trials in association with main machinery and sets shall operate without extraneous noise and impermissible heating of the components and bearings; along with that, it is necessary to check:
.1 pressure and temperature of the medium in the lubrication, control and protection systems;
.2 operation of the emergency alarm and protection systems;
.3 operation and interlocking of the shaft-turning gear;
.4 performance of the emergency connections between the driving and driven parts of the gearing for maintaining the running mode.

Where malfunctions have been detected during the mooring trials, the RS surveyor may require the gearing to be opened up in order to elucidate the causes of malfunctions.

5.16.6 Auxiliary machinery.
5.16.6.1 Each machinery shall be subjected to trials in accordance with Table 5.11.1.
5.16.6.2 Pumps of all types and purposes shall be tested in operation for their intended service, in steady mode, with the characteristics close to the specified ones; along with this, it is necessary to check the following parameters:
.1 power consumption;
.2 capacity (if necessary);
.3 speed;
.4 pressure, head;
.5 suction vacuum.

5.16.6.3 During operational tests of the pumps it is necessary to check:
.1 control from local and remote positions;
.2 availability of the instrumentation and their working life;
.3 operation of the lubricating and cooling devices, gland seals and self-priming devices;
.4 operation of the safely and by-pass devices and reliability of the measures taken to prevent hydraulic impacts;
.5 tightness of the pipe connections and pump casing joints.

5.16.6.4 Air compressors of all types shall be tested in operation for their intended service, with characteristics close to the specified ones; along with that, it is necessary to check:
.1 consumed power;
.2 compressed air pressure after each stage;
.3 air temperature at the cooler outlet;
.4 temperature and pressure in the cooling system;
.5 temperature and pressure in the lubrication system.

5.16.6.5 During the compressor testing it is necessary to check:
.1 operation of the alarm and protection system;
.2 operation of the local and remote control devices and ease of handling them;
.3 safety devices;
.4 time required to fill the air receiver by air and the capacity.
5.16.6 Blowers, fans, chargers of all types and purposes, as well as fuel oil and lubrication oil separators shall be tested in operation for their intended service; along with this the following parameters shall be checked for compliance with the specifications:

.1 consumed power;
.2 capacity;
.3 effectiveness of operation in conformity with the design purpose;
.4 other characteristics stemming from the specifications depending on the design features of the machinery.

5.16.7 It is necessary to check operation of the local and remote auxiliary machinery control systems.

5.16.8 Shaft generators, generators and electric motors being part of the unitized machinery, as well as the driving devices and gearing shall be tested together with the machinery in conformity with their purpose.

5.16.7 Steering gear.

5.16.7.1 The steering gear shall be tested as a part of the rudder steering arrangement in accordance with its purpose; the following shall be checked:

.1 time required to put the rudder by the main, spare, emergency and hand-operated steering gear;
.2 protection against overload, reverse rotation and operation of the braking devices;
.3 operation of the limit switches and rudder indicators;
.4 operation of the automatic alarm and protection devices;
.5 operation of the control stations;
.6 forces applied to the handles;
.7 time required to change over from the main to spare, emergency or hand-operated steering gear with due regard to 6.2.1.3, Part IX "Machinery" of the Rules for the Classification and Construction;

.8 continuous shifting the rudder from hard over to hard;
.9 steady keeping the rudder on the course.

5.16.8 Windlasses and anchor capstans.

5.16.8.1 The windlasses and anchor capstans shall be tested as part of the anchor arrangement; the following shall be checked:

.1 heaving-in speed of the anchor chain;
.2 possibility of adjusting the heaving-in speed of the anchor chain;
.3 operation of the disengaging couplings;
.4 operation of the torque-limiting clutch;
.5 operation of the brakes;
.6 operation of the alarms and protection devices;
.7 operation of the automatic devices;
.8 continuous operation for heaving up and dropping the anchors;
.9 operation of the remote control of the anchor machinery;
.10 operation of the anchor chain counters.

5.16.9 Mooring capstans and winches.

5.16.9.1 The mooring capstans and winches shall be tested for their design purpose; the following shall be checked:

.1 speed of heaving-in of a mooring line and the possibility of adjusting it;
.2 reliable operation of the machinery at a rated pull and overload;
.3 overload and other protections;
.4 operation of the brakes;
.5 operation of the automatic devices and alarms;
.6 force applied to the handles;
.7 operation of the manual drive.
5.16.10 Towing and boat winches.
5.16.10.1 When testing the towing and boat winches, the following shall be checked:
   .1 speed of heaving-in of a line;
   .2 reliable operation of the winches at a rated pull and overload;
   .3 operation of the fairlead;
   .4 overload and other protections;
   .5 operation of the brakes;
   .6 operation of the automatic devices and alarms;
   .7 force applied to the handles;
   .8 speed of lowering of the boats;
   .9 operation of the interlocking devices of the boat winches.

5.16.11 The mechanical and other telegraphs shall be tested for their design purpose together with the machinery for the correctness of executing orders and interlocking at all settings; the following shall be checked:
   .1 consistency of the order given on the bridge with that in the engine room;
   .2 interlocking, which precludes starting of the machinery in the direction opposite to the one ordered.

5.16.12 Testing of the fans of machinery spaces and spaces containing explosive equipment shall be conducted according to the program with all the specified parameters being checked.

5.16.13 The motors and pumps of the hydraulic systems shall be tested in operation for their design purpose together with the machinery, arrangements or systems they belong to.
5.17 SEA TRIALS

5.17.1 The sea trials shall be carried out in the presence of the RS surveyor according to the program approved by the Register. If specific operational characteristics have been defined by the manufacturer, these shall be included in the test plan.

5.17.2 The sea trials shall be carried out with the aim to check all the main parameters of the machinery installation, operation from all control positions during manoeuvring ahead and astern, reversing capabilities of the installation (including CPP), operation and maintenance of the auxiliary machinery and sets under conditions closely approximating the service conditions.

5.17.3 The program of the sea trials of the propulsion plant, sets and machinery, reduction gears and couplings shall provide for checking of all parameters of the relevant machinery and sets referred to in 5.16, as well as checking of the vibrations at various rates of speed of the ship.

The vibrations of the machinery, equipment and structures on prototype ships, and, if necessary, on series-built ships shall be measured at all the rates of speed of the ship.

5.17.4 The duration of the test modes of the main machinery shall be set in accordance with Appendix 1 to this Section. The frequency of noting the operational parameters of the main machinery shall be established in accordance with 5.16.2.4.

5.17.5 The auxiliary machinery, which check has been finalized on the mooring trials, shall be checked on the sea trials in operation for its design purpose.

5.17.6 The deck machinery shall be tested in modes contemplated for the testing of relevant arrangements in accordance with Section 3.

5.17.7 During the sea trials, the mechanical and other telegraphs shall be checked in operation for their design purpose together with the main machinery for the correct and failure-free execution of the orders at all settings with the interlocking devices to be checked in operation.

5.17.8 During the sea trials of the main hydraulic and electromagnetic couplings, it is necessary to test the emergency connection thereof with the aim to verify maintenance of the running condition of the ship at the speed ensuring manoeuvrability thereof.

5.17.9 The issue concerning replacement of the sea trials of main machinery by the mooring trials with the application of simulation means shall be settled in accordance with the requirements of 18.5.

5.17.10 Where the constructed/converted ship is intended for the carriage of liquefied gases and/or uses gas as fuel, the equipment and machinery related to gas transfer and use shall be checked during gas trials according to 18.7.
5.18 REVISION OF MACHINERY AND CHECK TESTS

5.18.1 Upon finalization of the sea trials, the revision of the machinery and sets shall be performed. The extent of the revision shall be determined by the RS surveyor basing on the trial results. The specified extent shall be defined more exactly in the course of the revision of the machinery.

5.18.2 Subject to stripping-down shall be assemblies and components the examination of which is required to confirm the reliable operation of the machinery or set.

5.18.3 Depending on the extent and results of the revision of machinery, check tests shall be carried out within the scope to be established in each particular case.
5.19 SURVEY OF MODU/FPU/FOP PROTECTION

5.19.1 General.

5.19.1.1 The requirements of this Chapter apply to the MODU/FPU/FOP specific machinery and supplement Section 5, Part IV "Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision and Section 5 of the Guidelines.

5.19.1.2 This Chapter establishes the requirements to technical supervision during manufacture, installation and testing of the MODU/FPU/FOP machinery given in the RS Nomenclature.

5.19.1.3 Materials used for manufacture of the products given in Table 5.19.2.1 shall meet the requirements in Part VII "Machinery Installations and Machinery", Part XII "Materials" of the MODU/FOP Rules, Part XIII "Materials" of the FPU Rules.

5.19.2 Technical supervision.

5.19.2.1 Procedure and scope of technical supervision during manufacture, installation and testing of the MODU/FPU/FOP specific machinery are given in Table 5.19.2.1. The certificates to be issued are given in the RS Nomenclature.

Table 5.19.2.1

<table>
<thead>
<tr>
<th>No.</th>
<th>Item of technical supervision</th>
<th>Verification of technical documentation</th>
<th>Control during manufacture</th>
<th>Installation on board MODU/FOP</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Verification of technical documentation</td>
<td>Material test</td>
<td>Visual examination</td>
</tr>
<tr>
<td>1</td>
<td>MODU/FPU jacking system¹:</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.1</td>
<td>hydraulic cylinder assembly</td>
<td>+</td>
<td>-</td>
<td>+</td>
</tr>
<tr>
<td>1.2</td>
<td>hydraulic cylinders with covers</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>1.3</td>
<td>pistons with rods</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>1.4</td>
<td>securing plates of hydraulic cylinders</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>1.5</td>
<td>fastenings</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2</td>
<td>Arrangements for lifting and lowering columns of submersible sea water pumps¹:</td>
<td></td>
<td></td>
<td>+</td>
</tr>
<tr>
<td>2.1</td>
<td>main and intermediate shafts</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2.2</td>
<td>gear wheels and pinions</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2.3</td>
<td>brakes</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>3</td>
<td>Submersible sea water pumps²</td>
<td></td>
<td></td>
<td>-</td>
</tr>
<tr>
<td>4</td>
<td>Ventilation system in hazardous and enclosed spaces maintained in overpressure³ and shielding gas supply and ventilation systems for electrical equipment with enclosure under overpressure</td>
<td></td>
<td></td>
<td>-</td>
</tr>
<tr>
<td>5</td>
<td>Compressors for tensioning systems</td>
<td></td>
<td></td>
<td>-</td>
</tr>
</tbody>
</table>

1. If the gearing is used as a drive, the types and scope of supervision shall be defined as per the item of technical supervision "Auxiliary machinery reduction gear" with code 09070000 in the RS Nomenclature.

2. When performing technical supervision during manufacture of the components of the submersible pumps and compressors of tensioning system, refer to 5.8, Part IV "Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.

3. When performing technical supervision during manufacture of the ventilation system components, refer to 5.10 and Table 5.10.1, Part IV "Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.

5.19.2.2 During manufacture of the prototypes as well as during surveys, the products with the type of technical supervision provided in the form of a Type Approval Certificate shall be checked by the RS surveyor for compliance with Table 5.19.2.1.
5.19.2.3 Procedure and scope of survey of the electrical equipment, control, monitoring and protection systems as part of machinery are given in the appropriate parts of the Rules for Technical Supervision and sections of the Guidelines.

5.19.2.4 Prior to manufacture of the machinery products, their installation on board MODU/FPU/FOP and testing, the set of approved documents and the list of equivalents shall be checked.

5.19.2.5 The list of items of technical supervision shall be prepared with regard to Table 5.19.2.1.

5.19.2.6 MODU/FPU jacking system.

5.19.2.6.1 When checking the materials during manufacture of the jacking system parts, special consideration shall be given to availability of the material certificates.

5.19.2.6.2 During visual examination of parts and assembly of the jacking system, the following requirements shall be met:

- internal surfaces of the hydraulic cylinders and external surfaces of the rods shall be free of sharp edges and abrupt transitions;
- surfaces of the hydraulic cylinders subject to chrome-plating shall be uniformly coated. Lead-in chamfers and grooves may be partially coated;
- all parts and units prepared for final assembly shall be subject to visual examination. Special consideration shall be given to condition of rubber seals and walls of hydraulic cylinder liners;
- fastenings of hydraulic cylinders shall be securely locked. The nuts of hydraulic cylinder covers shall be tightened with torque wrenches with the torque specified in technical documentation.

5.19.2.6.3 The items given in items 1.2, 2.1 and 2.2 of Table 5.19.2.1 shall be subject to ultrasonic testing, and the fastenings of hydraulic cylinder covers shall be subject to magnetic particle testing.

5.19.2.6.4 During hydraulic testing of the hydraulic cylinder assembly, the following requirements shall be met:

- one hydraulic cylinder from the series may be subject to testing;
- tests shall be performed with the working fluids specified in standards or specifications for the hydraulic cylinders. Working fluids shall be properly filtered according to the regulatory documents;
- parameters shall be measured in compliance with the current standards. When testing the serial hydraulic cylinders, parameters may be subject to a single acceptance test.

Each hydraulic cylinder shall be tested to a test pressure equal to 1.5 times the working pressure. The pressure shall be gradually increased to the test value, then held for at least 10 min and again decreased to the working value. The tested cylinder shall be visually examined. The cavities of cylinders shall be sequentially pressurized. The hydraulic cylinder under test shall be hinge-mounted in rigid supports of the test bed in the rod stroke position of 0.96S. In addition, the cylinder shall be tested to pressure equal to 1.25 times the working pressure for at least 5 min. The cylinder tightness shall be provided after at least five double strokes of rod at working pressure.

5.19.2.6.5 The prototype hydraulic cylinder shall be subject to bench tests according to the procedure approved by the Register.

5.19.2.6.6 When conducting bench tests of serial products, the requirements in 5.11, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision shall be met.

5.19.2.6.7 Based on satisfactory results of the tests, the Register shall brand the nameplate of the hydraulic cylinder.

5.19.2.6.8 When the prototype product (batch) is tested, hydraulic cylinders shall be subject to inspection.
5.19.2.6.9 When performing technical supervision during installation of the MODU/FPU jacking system, the applicable requirements in 5.1, 5.3, 5.11, and 5.12, shall be met. The following shall be checked:

- tight contact of yokes when fitted onto journals of the hydraulic power cylinders (when tightened, the 0.2 mm thick feeler gage may be inserted into the 100 mm junction to the maximum depth of 50 mm);
- tight contact of the hydraulic power cylinder plates and jack house metal structures (when tightened, the 0.2 mm thick feeler gage may be inserted into the 100 mm junction to the maximum depth of 50 mm around the plates);
- proper tightening of the bolts fastening yokes to the hydraulic cylinder journals with torque wrenches, as well as tight fitting of the hydraulic cylinder rods and support screws to sliders according to the technical documentation;
- reliable locking of the hydraulic cylinder rods, support screws and other fasteners to prevent their self-release;
- displacement of the hydraulic cylinders by height, if provided in the technical documentation.

5.19.2.6.10 The MODU/FPU jacking system shall be tested for intended purpose according to 3.3 and 5.16. The following shall be checked:

- start and shutdown of high-, medium- and low-pressure pumps from all control stations provided;
- actuation of safety valves when high-pressure valves are closed;
- operation of pressure relief valves;
- operation of the hydraulic power cylinders by lifting and lowering the sliders three times along the guides of two diagonal pairs of hydraulic cylinders with catchers disengaged.

5.19.2.7 Arrangements for lifting and lowering columns of submersible sea water pumps.

5.19.2.7.1 Technical supervision during manufacture of parts, assembly and bench tests of arrangements for lifting and lowering columns of submersible sea water pumps shall be performed according to 5.9 and Table 5.19.2.1.

5.19.2.7.2 When performing technical supervision during installation of arrangements for lifting and lowering columns of submersible sea water pumps, the applicable requirements in 5.1, 5.3, and 5.12 shall be met, at that:

- control stations shall be arranged to provide easy maintenance and monitoring of machinery operation;
- limit switches actuating upon the column reaching of the outermost positions shall be provided according to the technical documentation.

5.19.2.7.3 Arrangements for lifting and lowering columns of submersible sea water pumps shall be tested for intended purpose according to 3.3.4.3 and 5.16. The following shall be checked:

- reliable operation of winch;
- operation of brakes;
- operation of alarm and safely devices.
5.19.2.8 Submersible sea water pumps.

5.19.2.8.1 Technical supervision during manufacture of parts, assembly and bench tests of submersible sea water pumps shall be performed according to Table 5.8.1 and 5.9, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision. The following shall be checked:
- passage section of suction strainer complies with the requirements of the Rules for the Classification and Construction;
- motor is filled with insulating liquid and appropriate tightness is provided;
- appropriate tightness of check valve is provided.

5.19.2.8.2 When performing technical supervision during installation of submersible make-up pumps, the applicable requirements in 5.1, 5.3, and 5.11. The following shall be checked:
- pump intake shall be fitted with filter and non-return valve;
- pump is readily accessible for examination and emergency repair when the column is set to the upper position;
- pump motor is filled with insulating fluid.

5.19.2.8.3 Submersible pumps shall be tested along with the MODU/FPU/FOP sea water supply system during mooring trials according to 5.16 and Section 6.

5.19.2.9 Fans of hazardous and enclosed spaces under overpressure.

5.19.2.9.1 Surveys during installation and testing of fans on board MODU/FPU/FOP shall be performed according to Table 5.19.2.1.

5.19.2.9.2 During installation and testing of fans on board MODU/FPU/FOP, the appropriate checks shall be performed to make sure that all documents as prescribed by the RS Nomenclature are available. The fans shall be visually inspected. The RS surveyor shall make sure that:
- fans are of spark proof type (for those located in hazardous spaces);
- fans’ capacity is sufficient to provide air changes in spaces as required by the MODU/FOP Rules;
- fan case is free of defects;
- fans are installed according to the approved working drawings.

5.19.2.9.3 The fans shall be tested as part of ventilation systems intended for hazardous and enclosed spaces under overpressure during mooring and sea trials according to 8.5.2.3.4 и 8.5.2.3.5.

5.19.2.10 Compressors for tensioning systems.

5.19.2.10.1 Technical supervision during manufacture of parts, assembly and bench tests of compressors for tensioning systems shall be performed according to Table 5.8.1 and requirements of 5.9, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

5.19.2.11 Machinery inspection.

5.19.2.11.1 After sea trials, all machinery and units shall be inspected according to 5.18.
DURATION OF TESTING OF THE MAIN AND AUXILIARY MACHINERY ON MOORING AND SEA TRIALS

1 Mooring and sea trials of internal combustion engines
1.1 The mooring and sea trials of internal combustion engines (ICE) shall be carried out in compliance with Appendix 7 to Section 5, Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.

2 Mooring trials of steam and gas turbines
2.1 Mooring trials of the machinery the load of which changes according to power-propeller revolutions curve shall be carried out in modes given in Table 2.1.
2.2 Mooring trials of the turbogenerators shall carried out in modes given in Table 2.2.

### Table 2.1

<table>
<thead>
<tr>
<th>No. of mode</th>
<th>Torque % of rated value</th>
<th>Duration of trials, h, at main machinery power, in kW</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>up to 750</td>
</tr>
<tr>
<td>1</td>
<td>39</td>
<td>0,25</td>
</tr>
<tr>
<td>2</td>
<td>63</td>
<td>0,25</td>
</tr>
<tr>
<td>3</td>
<td>83</td>
<td>0,25</td>
</tr>
<tr>
<td>4</td>
<td>100</td>
<td>1,00</td>
</tr>
<tr>
<td>5</td>
<td>Run astern</td>
<td>0,50</td>
</tr>
</tbody>
</table>

### Table 2.2

<table>
<thead>
<tr>
<th>No. of mode</th>
<th>Torque % of rated value</th>
<th>Duration of trials, h, at main machinery power, in kW</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>up to 750</td>
</tr>
<tr>
<td>1</td>
<td>Idling</td>
<td>0,25</td>
</tr>
<tr>
<td>2</td>
<td>25</td>
<td>0,25</td>
</tr>
<tr>
<td>3</td>
<td>50</td>
<td>0,25</td>
</tr>
<tr>
<td>4</td>
<td>75</td>
<td>0,25</td>
</tr>
<tr>
<td>5</td>
<td>100</td>
<td>1,00</td>
</tr>
<tr>
<td>6</td>
<td>110</td>
<td>0,25</td>
</tr>
</tbody>
</table>

2.3 Main steam and gas turbines driving CPP or generators the load of which changes according to power-propeller revolutions curve may be tested in modes given in Table 2.1 subject to subsequent tests thereof on the sea trials.

3. Sea trials of steam and gas turbines
3.1 Sea trials of main machinery, which load changes according to power-propeller revolutions curve, shall be carried out in modes given in Table 3.1.
3.2 Sea trials of the main machinery operating according to load curve shall be carried out in modes given in Table 3.2.
3.3 Duration of the trials given in Tables 3.1 and 3.2 does not take into account the time required to test the propulsion plant in case of unattended operation as specified in Section 12.

3.4 The main machinery driving CPP, depending on the design of the control and regulation (engine — CPP) system, may be tested according to both the power-propeller revolutions curve and the load curve or according to combined curve.

3.5 Time required to trial the prototype ships in 100 % mode shall be doubled.

3.6 The main machinery made as unity sets, including turbines, gearing, couplings, generators, driving gear, shall be tested according to specially developed programs agreed with the Register and accounted for various operation variants of the set.

The modes and duration of testing the set shall be established in each particular case, depending on the features thereof.
RECOMMENDATIONS ON INSTALLATION AND MOUNTING OF MACHINERY

1 General requirements
1.1 The Recommendations set the requirements in the absence of specified and agreed shipbuilding standards or national standards, which application is agreed with the Register.

2 Machinery mounted on metal chocks
2.1 Where the machinery is mounted on metal chocks, generally, the following conditions shall be met:
   .1 inclination angle of the chocks, their dimensions, arrangement and surface finish shall comply with the requirements of the mounting drawings;
   .2 chocks and their positions shall be marked;
   .3 fit of the chock surfaces to be mated with the machinery and seating shall be checked before the seating bolts are tightened.

3 Machinery mounted on spherical spacers
3.1 Where the machinery is mounted on spherical spacers, generally, the following conditions shall be met:
   .1 diameter of the spherical spacer shall be such that the specific pressure on the spacer, induced by the mass forces and bolt tightening forces does not exceed the one shown on the drawings;
   .2 diameter of the spacer shall not exceed the width of machinery foot or frame, however, if the specific pressure exceeds the standards shown on drawings, the spacer diameter shall be increased in comparison with the width of the machinery foot or frame flange;
   .3 no spherical spacer protruding from the seating shall be generally permitted;
   .4 displacement of the upper half of the spacer in relation to the lower one, as well as the displacement of the spacer in relation to the machinery foot or frame flange shall not be permitted;
   .5 to prevent displacement of the spacers during drilling, the spacers may be tacked together and to the seating by electrical welding.

4 Machinery mounted on adjustable chokes
4.1 Where the machinery is mounted on adjustable chokes, generally, the following conditions shall be met:
   .1 diameters of the adjustable chocks shall be taken depending on the specific pressure thereon, and the greatest diameter shall not exceed the width of the seating flange and machinery foot;
   .2 shift of the upper chock part to one side in relation to the lower part shall not exceed the one shown on drawings;
   .3 diameter of the hole for normal bolt shall exceed the bolt diameter by the value of shift of the both chock parts;
   .4 to prevent displacement of chocks when the holes are machined for tight-fitting bolts, the both chock halves may be tacked together and to the seating by electrical welding.

5 Machinery mounted on steel levelling spacers
5.1 Where the machinery is mounted on the steel levelling spacers, generally, the following conditions shall be met:
   .1 the levelling spacer shall consist of at most two plates whose contact surfaces shall have the required quality;
   .2 fitting the spacers in place is not needed, they may be tacked by electrical welding;
   .3 fit of the spacer surfaces to be mated with the bearing surface of machinery and the seating shall be checked before the fastening bolts are tightened.
6 Machinery mounted on shock absorbers

6.1 Where the machinery is mounted on the shock absorbers, design of the used shock absorbers shall comply with the requirements of the technical documentation approved by the Register at that, generally, the following conditions shall be met:

   .1 machinery aligned together may be mounted on shock absorbers only when there is a common bed plate;
   .2 shafts of the aligned machinery mounted on the shock absorbers shall allow free relative movement of the machinery in operation;
   .3 all connections to the machinery mounted on the shock absorbers shall allow free relative movement of the machinery in operation;
   .4 places where the shock absorbers are installed on the bearing surface of the seating shall be so machined that the freely installed shock absorbers fit snugly to the seating and frame or to the machinery foot;
   .5 tight fit of the levelling washers to the bearing surfaces of the machinery feet or frames installed on vertical and ceiling foundations shall be checked with two bolts tightened and the remaining bolts slightly loosened; in so doing, indications of deformation of all the shock absorbers shall be detectable and misalignment of the machinery attachment plane in relation to the foundation plane shall not exceed the requirements of drawing.

7 Machinery mounted on wooden chocks

7.1 Where the machinery is mounted on the wooden chocks, generally, the following conditions shall be met:

   .1 places for installation of the wooded chocks shall be conditioned and painted;
   .2 the wooden chocks shall be manufactured of Grade 1 hardwood (oak, yew, ash, beech); the chocks shall be free of cracks and the moisture content of the wood shall not exceed the prescribed one;
   .3 in specific cases, the wooden chocks may be made of several parts, each part being fastened by at least two anchor bolts;
   .4 the minimum and maximum thickness of the wooden chock shall be indicated in the technical documentation;
   .5 the quality of fit of the wooden chocks shall enable the machinery foot or frame to be snug against the chock and also the chock against the bearing surface of the foundation;
   .6 prior to installation, the wooden chocks shall be boiled thoroughly in drying oil or treated otherwise in order to protect against decay;
   .7 no wooden chocks shall be used in oil storages, cofferdams, machinery and pump spaces of oil tankers.

8 Machinery mounted on plastic pads

8.1 General requirements.

8.1.1 The present requirements may be applied in technical supervision during installation of the plastic pads when mounting machinery on seatings, unless otherwise specified in the technical documentation approved by the Register.

8.1.2 Machinery shall be mounted on plastic pads in compliance with the instructions and recommendations of plastics manufacturers and machinery or arrangements manufacturers.

8.1.3 Material used for the pads shall be approved by the Register (supplied with a copy of the Type Approval Certificate (CTO)).

8.1.4 Machinery shall be mounted on the plastic pads using agreed instructions and under technical supervision of the Register.

8.2 Requirements for the plastics and their testing in the process of the RS approval.

8.2.1 Plastics used for pads shall be tested in compliance with the requirements of 6.10, Part XIII "Materials" of the Rules for the Classification and Construction, unless otherwise specified in the technical documentation approved by the Register.
8.3 Technical documentation.

8.3.1 The following documentation shall be submitted to the RS surveyor (within the design documentation of the ship or in each individual case):

.1 drawings showing installation and attachment of machinery to seating with the use of plastic pads with indication of location and dimensions of pads, stops and anchor bolts including tightly-fitted bolts, as well as positions of the checkpoints for measurements in operation. Moreover, the said drawing shall contain the following information: mass of the machinery, expected and/or allowable temperature of the pads in operation, mechanical characteristics of the material, tightening torques and design of locking devices for the anchor bolts as well as the value of propeller thrust for the main machinery;

.2 calculations of specific loads for the assumed dimensions of the plastic pads, due to machinery mass and anchor bolt tightening, as well as the calculations of the anchor bolt tightening torques and associated stresses in the bolts;

.3 data on the material properties (in accordance with 8.2);

.4 instruction for preparation of the plastic.

8.4 Design requirements

8.4.1 The RS surveyor shall make sure by examinations and review of the QCD documents that:

.1 the allowable specific load on the plastic pads due to machinery mass is determined by the formula

\[ p_{allow} \leq \sigma_{comp}/200 \]  

(8.4.1.1)

where \( \sigma_{comp} \) = compression strength of the plastic, in MPa, but in any case the allowable load shall not be taken more than 0,7 MPa;

.2 the specific load on the plastic pads due to tightening of anchor bolts is not less than 1,75 MPa.

Along with this, the stress in the anchor bolts shall not exceed 0,8 the yield strength of the material;

.3 the maximum allowable total specific load on the plastic pads due to machinery mass and anchor bolt tightening is:

\[ p_{\text{max}} < 5p_{allow} \]  

(8.4.1.3)

where for \( p_{allow} \) refer to 8.4.1.1.

Maximum allowable total specific load \( p_{\text{max}} \) may be increased above \( 5p_{allow} \) upon submission of the relevant technical background.

8.4.2 To ensure that the seatings can take tangential forces including propeller thrust, provision shall be made for special stops or tightly fitted bolts. The bores of these bushes shall be calibrated by simultaneous reaming of holes in the machinery foot and in the seating flange. Tightly fitted bolts shall be installed in way of the plastic pad according to the procedure agreed with the RS Branch Office.

8.4.3 For the machinery to be aligned, provision shall be made for devices to measure position of the machinery in relation to the seating. These devices shall ensure determination of the machinery position on both sides along the length of the machinery. Machinery whose length to width ratio is not over 1,5 shall have devices for measuring at not less than two points and those with length to width ratio over 1,5, at not less than three points on each side.
8.5 Requirements for mounting machinery on the plastic pads.

8.5.1 When moulding the pads, each plastic mixture to be prepared shall be used for producing test specimens being cured under the same conditions as the pads. These specimens shall be subjected to check test for compression and hardness in conformity with 8.2.2.1 and 8.2.2.6 to confirm specified characteristics of the plastic moulded into pads.

8.5.2 Before the plastic is moulded, the anchor bolts, surfaces of machinery and seating which are in contact with the plastic pads shall be coated by anti-adherent compound.

8.5.3 The thickness of the plastic pads shall not exceed 40 mm. Use of the plastic pads of a greater thickness shall be confirmed by the relevant technical background.

8.5.4 For the machinery to be aligned, as well as in other cases where it is deemed necessary, account during installation of the machinery on the plastic pads and during determination of their thickness shall be taken of the plastic shrinkage during curing (refer to 8.2.2.5), as well as the plastic creep (refer to 8.2.2.4) at the appropriate design temperature and specific load.

8.5.5 Before the anchor bolts are tightened, it is necessary to make sure that the plastic pads are fully cured. This shall be effected by checking the hardness unless the plastic manufacturer specifies other methods of checking curing (refer to 8.5.1).

8.5.6 After the anchor bolts are tightened, it is necessary, if need be, to check alignment of machinery, measure crank web deflection, etc. The values of the anchor bolt tightening torques, their equivalent stresses in the bolt bodies or the values of oil pressure in the device for hydraulic tightening of bolts shall be entered in special data cards or measurement tables. Furthermore, after the bolts are tightened, it is necessary to check machinery position using devices referred to in 8.4.3. The results of measurements obtained during such check shall be also entered in the data card or measurement tables.

8.5.7 During moulding and curing of the plastic pads, work which may result in change of the machinery position, that is work causing vibration, shocks, displacement of masses, etc. shall not be performed in way of the machinery.

8.5.8 The main engine and other machinery shall be installed on the plastic pads after completing assembly thereof and alignment of shafts.
6 SHAFTING

6.1 GENERAL

6.1.1 The provisions of this Section apply in technical supervision of the shafting and components thereof listed in the RS Nomenclature.


6.1.2 The Section lays down the procedure of the Register technical supervision during mounting and testing of the shafting and components thereof on board the ship.

6.1.3 The procedure and scope of the checks, surveys and tests of the shafting on board the ship are determined by the shipyard on the basis of examination and testing plan developed according to 6.2.1 of the Guidelines, as well as to 13.3, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision.

6.1.4 The methods of inspection, tools and devices for measuring and testing shall be specified by the shipyard, indicated in the process documentation and, if necessary, agreed with the Register.

6.1.5 Numerical values for test modes and duration, as well as numerical criteria for installation works given in this Section are provided for reference. Prior to commencement of construction, other quality criteria given in the recognized national or international standards, or manufacturers' documents/instructions may be agreed with the RS Branch Office.

6.1.6 Testing and checks stipulated by this Section are performed, provided the materials, completing equipment and products to be subjected to the Register technical supervision according to the RS Nomenclature and incoming for the mounting of the shafting have been manufactured and tested at the manufacturer's and have the documents confirming the Register technical supervision during their manufacture and testing.

6.1.7 In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of machinery in substantiated cases.
6.2 SURVEY PLANNING

6.2.1 Prior to commencement of survey of the stern tube arrangement and shafting of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 6.2.1, 6.3 – 6.7 of the Guidelines and 5.9, Part VII "Machinery Installations" of the Rules for the Classification and Construction. The shipbuilder shall be informed about that at a kick-off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

6.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

6.2.3 Quality standards for installation and testing of the stern tube arrangement and shafting shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

6.2.4 Any changes to the kick-off meeting records shall be agreed and documented.

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<tr>
<td>stern tube seals and glands</td>
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6.3 TECHNICAL DOCUMENTATION

6.3.1 When performing technical supervision, the RS surveyor shall be guided by the technical documentation approved by the Register within the scope required by Part I "Classification" of the Rules for the Classification and Construction and agreed technological processes for mounting and aligning shafting.

6.3.2 Prior to mounting, the RS surveyor shall check the availability of the following technical documentation agreed with the Register:

- the procedure for mounting struts and stern tubes;
- the procedure for attaching the stern tube to the stern boss and for pressing the stern bearing directly in the stern boss;
- the procedure for installing bearings on pads of polymer materials.

6.3.3 Documents on all committed deviations from the RS-approved technical documentation on shafting, as well as on correction of troubles noted at the previous stages of technical supervision shall be submitted to the RS surveyor.
6.4 MOUNTING OF STERN TUBE ARRANGEMENTS

6.4.1 Mounting and installation monitoring of stern tube arrangements shall be performed according to the procedure agreed with the Register. During agreement of the procedure for mounting and installation monitoring of stern tube arrangements the recommendations given in Appendix 2 to this Section may be taken into account.
6.5 MOUNTING AND ALIGNMENT OF SHAFTING

6.5.1 Mounting and alignment of shafting shall be performed according to the procedure agreed with the Register. During agreement of the procedure for mounting and alignment of shafting the recommendations given in Appendix 3 to this Section may be taken into account.

6.5.2 Mounting and check of installation of the detachable couplings including couplings installed using hydropress method, as well as mounting and check of installation of the flexible, disengaging and sound-insulating couplings with shafts shall be performed in accordance with the requirements and guidelines of the technical documentation agreed with the Register.

6.5.3 Mounting, assembly and check of installation of the shaft-turning gear, torsiometer and tachometer sensor, as well as flange couplings and other devices in the shafting – CPP arrangement shall be performed in accordance with the requirements of the technical documentation given in 6.3.

6.5.4 The protection of propeller shafts against exposure to sea water shall be checked with due regard to 5.2.15 — 5.2.20, Part VII "Machinery Installations" of the Rules for the Classification and Construction. Propeller shaft liners shall be made of corrosion resistant materials and shall be shrunk on the shaft in such a way as to provide tight interference between mating surfaces. The portion of the shaft between the liners shall be protected against the action of sea water by a method approved by the Register. To prevent water from reaching the propeller shaft cone, appropriate sealing shall be provided.

6.5.5 In case of an end nut securing the propellers or coupling on the shaft, its stoppers shall be secured to the shaft in accordance with 5.4.1, Part VII "Machinery Installations" of the Rules for the Classification and Construction.

6.5.6 During mounting the securing and locking items of propeller blades, hub cones, end nut of propeller, stern tubes, sternbushes and sealings shall be checked that they are made of corrosion-resistant materials in accordance with 2.4.6, Part VII "Machinery Installations" of the Rules for the Classification and Construction.

6.5.7 After mounting and alignment of shafting, performance of the breaking device shall be checked in accordance with 5.8.1 and 5.8.3, Part VII "Machinery Installations" of the Rules for the Classification and Construction.
6.6 MOORING AND SEA TRIALS

6.6.1 Following the mounting on board ship in compliance with Table 6.2.1 the shafting shall be checked in operation simultaneously with the mooring and sea trials of the main machinery. The shafting shall be checked in operation during the mooring and sea trials according to the program being a constituent part of a general ship's program, and using a test procedure approved by the Register.

6.6.2 The readiness of the shafting for trials, on agreement with the Register, shall be determined by positive results of all the specified surveys and verifications performed in the course of the shafting mounting as well as from the measurement tables (records, service log of the shafting).

Based on the results of mooring trials, the possibility of conducting the sea trials shall be determined.

6.6.3 The positive results of the mooring and sea trials shall be determined by the temperature conditions of shafting components specified by the service manual; absence of extraneous noise, shocks, rather high vibrations and other indirect indications of abnormal operation; satisfactory operation of systems, instruments and devices serving the shafting in accordance with the service manual of these systems, instruments and devices, as well as the results of torsional vibration measurement.

6.6.4 The necessity for the revision of assemblies and components of the shafting, stern tube, as well as for the inspection test of the shafting alignment shall be decided basing on the results of sea trials with due account of the design features of the shafting.
6.7 CALCULATIONS AND MEASUREMENTS OF TORSIONAL VIBRATION OF SHAFTING OF THE SHIP’S PROPULSION PLANT AND AUXILIARIES

6.7.1 General.

6.7.1.1 This Chapter contains requirements for calculations and measurements of torsional vibration of shafting of the propulsion plant and auxiliaries (refer to 8.1.1, Part VII "Machinery Installations" of the Rules for the Classification and Construction).

6.7.1.2 The documents on the torsional vibration to be submitted to the Register include:

1. shafting torsional vibration calculation;
2. program of shafting torsional vibration measurements;
3. preliminary conclusion on the results of shafting torsional vibration measurements;
4. report on shafting torsional vibration measurements.

6.7.1.3 The program of shafting torsional vibration measurements (refer to 6.7.1.2), in its contents shall comply with the requirements set out in the Instruction on Drawing up Documents on Torsional Vibrations of Shafting of the Ship's Propulsion Plants and Auxiliaries (refer to Appendix 1 to this Section).

6.7.1.4 The program of the torsional vibration measurements (refer to 6.7.1.2.2) is based on the results of the torsional vibration calculation and shall be submitted to RHO or the RS Branch Office before commencement of measurements on the ship under consideration.

6.7.1.5 The preliminary conclusion on the results of shafting torsional vibration measurements (refer to 6.7.1.2.3) shall be made and submitted to the RS Branch Office within the terms, as agreed with the shipyard (in case of ship construction) or with the shipowner (when the ship is in service) upon the completion of measurements in order to make a prompt decision on the permit for operation of the ship's propulsion plant or auxiliaries.

6.7.1.6 The report on measurements (refer to 6.7.1.2.4) shall be submitted to the RS Branch Office not later than 3 months after testing, provided the requirements of 6.7.1.5 are complied with. Otherwise, the decision on the permit for the operation of the ship's propulsion plant or auxiliaries may be taken only after the report on measurements have been submitted to the RS Branch Office.

6.7.1.7 The results of the torsional vibration measurements made on board the prototype ship shall apply to all ships of this series and shall be reflected in the Register documents issued to series-built ships.

6.7.2 Requirements for torsional vibration measurements.

6.7.2.1 The shafting torsional vibration measurements shall be performed for all variants and conditions possible in operation of the installation for which the torsional vibration calculations are required in compliance with 8.1.2, Part VII "Machinery Installations", taking into account the installation design, provided the operation in these conditions is allowed by the manufacturer.

6.7.2.2 Selection of shafting portions and cross sections for installation of torsional vibration sensors depends on the shafting design and, to verify the reliability of torsional vibration calculation, those system sections where according to the calculation tangible displacement amplitudes or twisting are expected to be recorded with the appropriate natural frequency modes.

6.7.2.3 The shafting torsional vibration measurements shall be made at smooth increasing and decreasing of the shaft speed (from the minimum steady speed up to maximum speed) over the entire working speed range. If necessary (depending on the ship purpose), the measurements may be performed at starts, stops and reverses.

Within the areas of resonance speed and at rated speed, the repeated measurements shall be made at fixed speeds (by points).
Where a barred speed range is required, passages through this barred speed range, both accelerating and decelerating, shall be demonstrated (refer to 4.5.1 of Appendix 7 to Section 5, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision). The times taken shall be recorded and shall be equal to or below those times stipulated in the RS-approved documentation, if any. This also includes when passing through the barred speed range in reverse rotational direction, especially during the stopping test.

6.7.2.4 Where a remote automatic control system (RAC) is available, measurements shall be made with the engine being controlled both by RAC and manually.

6.7.2.5 In sophisticated plants containing several engines, power take-off devices, disengaging couplings, etc. it is necessary to make measurements at various variants of connection of the engines and power consumers for which calculations have been made.

6.7.2.6 On ships equipped with CPP, torsional vibration shall be measured at the nominal and zero pitch but, if necessary, also at the intermediate pitch values.

6.7.2.7 Torsional vibration shall be measured during sea trials of the ship after mounting of all attached standard machinery and adjustment, verification of the main machinery and CPP for compliance with the specified parameters (refer to 6.7.2.3).

The torsional vibration of the shafting may be measured when the ship is in ballast or loaded condition.

6.7.2.8 On ships equipped with CPP, the measurements may be performed during mooring trials, provided the operation of the plant is ensured over the entire speed range (from the minimum steady speed up to maximum speed) by varying the propeller pitch.

6.7.2.9 Torsional vibration of the shafting of auxiliaries or the engine vibrations of "motor" modes shall be measured by the auxiliaries or engine manufacturer and the safe development of their torsional vibration shall be ensured by the manufacturer concerned ("motor" mode of vibration is the mode determined by the elastic-and-inertia parameters of the engine).

If an engine in auxiliaries is mated with a standard generator, compressor, pump, etc. at the shipyard, the measurements shall be made on board ship.
RECOMMENDATIONS ON DRAWING UP DOCUMENTS
ON TORSIONAL VIBRATION OF SHAFTING
OF THE SHIP'S PROPULSION PLANTS AND AUXILIARIES

1 General

1.1 The Recommendations establish the procedure for drawing up documents on torsional vibration of shafting of ship's power plants and auxiliaries when submitted to the Register in accordance with the requirements of Section 8, Part VII "Machinery Installations" of the Rules for the Classification and Construction.

The Recommendations set out requirements for the contents and presentation of the calculation and report on shafting and auxiliaries torsional vibration measurements.

2 Recommendations on the contents and drawing up the torsional vibration calculation for shafting of ship's propulsion plants or auxiliaries

2.1 When submitted to the Register, the shafting torsional vibration calculations shall be made out in conformity with the provisions of this Section of the Recommendations. The accepted form of the documents submitted by foreign companies may be different but it shall contain all the required information.

2.2 The torsional vibration calculations, generally, shall contain the information listed below.

2.2.1 The introductory part shall contain grounds for the calculations (development of technical design, modernization of propulsion plant, replacement of propeller, damper diagnostics, etc.). This part shall contain a reference to the calculation procedure and algorithms.

2.2.2 Brief summary specification of the ship and description of its propulsion plant shall be given. The ship's type, project number, as well as the ship's name (if assigned by this time) shall be indicated.

For power plant or auxiliaries, a functional diagram shall be given with indication of each component position and interpretation thereof; as well as the shafting sketch, design torsional diagram including the components of the ship's propulsion plant or auxiliaries.

2.2.3 The basic characteristics and dimensions of the shafting components of the torsional system shall be specified.

2.2.4 Modes specified for operation of the propulsion plant shall be given with indication of speed, and for the installations with CPP – pitch values for various modes. If change in the modes is associated with change in the gear ratio of the reduction gear or with connection of additional auxiliaries, this information shall be given for each mode.

2.2.5 A summary table of data describing the torsional diagram of the system shall be given. The table shall contain description of the masses and portions of the shafting, diameter, length, compliance (stiffness) and minimum section modulus of the shafting portions, mass inertia moments. The torsional diagram of the system shall be also shown here.

For diesel electric propulsion plants, for plants with hydraulic or electromagnetic couplings as well as for plants with variety of connection of the system components, the calculation schemes shall be given separately for each part of the plant (e.g. "main diesel-generator" and "propulsion motor – propeller" or "diesel – driving half-coupling" and "driven half coupling – propeller") or for each variant of connection of the components.

2.2.6 The calculation shall contain the results of determination of natural frequencies for all modes of vibration having a resonance up to the 12th order inclusive within the speed range \((0 – 1.2)n_p\), for each independent part of the plant or each variant of its connection.
2.2.7 The permissible values of stresses (torques and temperature) shall be taken as required in 8.2 – 8.6, Part VII "Machinery Installations" of the Rules for the Classification and Construction, and in case of their absence, according to the data presented by the manufacturers of the relevant equipment or the other normative documents.

2.2.8 Where it is necessary to consider the simultaneous effect of disturbing moments of several orders, the calculation shall contain determination of total stresses (torques). Along with that, the orders being summed up shall be indicated.

2.2.9 Based on the results of calculation, stress (torque) curves shall be presented with indication of permissible values for continuous running and rapid passage and of barred speed ranges.

Along with that, the following shall be taken into consideration:
the width of the barred speed ranges shall be determined according to 8.8, Part VII "Machinery Installations" of the Rules for the Classification and Construction;
the permissible stresses for the portion of the propeller shaft positioned within the stern tube shall be estimated:
- for stern tube with non-metal bearings, as in the case of propeller shaft;
- for stern tubes with oil-lubricated metal bearings, as in the case of intermediate shaft.

2.2.10 In the conclusion of the calculation, inferences shall be drawn as to the absence of the barred speed ranges within the entire working speed range, as well as during start-stop or as to the necessity of assigning the barred speed range, its position and width. Where necessary, recommendations shall be given on alterations of some plant components (supported by an appropriate calculation) or specified operation conditions of the plant.

2.2.11 The calculation shall contain the requirement for checking the calculation results by measuring the torsional vibration on the ship with indication of measuring equipment and measurement points depending on the purpose of research, with due account of the calculation of the relative amplitudes of the most visible natural frequency modes.

3 Recommendations on the contents and drawing up the program of shafting torsional vibration measurements

3.1 The program of shafting torsional vibration measurements is a basic document being developed on the basis of results of the torsional vibration calculation and agreed with RHO or relevant RS Branch Office.

3.2 In terms of their content the programs of shafting torsional vibration measurements are divided into integrated and special.

3.2.1 An integrated program is generally developed for the prototype ship of the series in order to verify the results of the torsional vibration calculations for all the system components where critical loads are expected to occur.

3.2.2 A special program is developed for series-built ships aimed at the torsional vibration periodic inspection of some components of the system ensuring its safety (usually dampers). In particular, the guidelines on the contents and drawing up the special program are given in the Procedure for Diagnosing and Determining the Residual Lifetime of Silicone Dampers of Marine Internal Combustion Engines (ICE) (refer to Annexes to the Guidelines on Technical Supervision of Ships in Service).

3.3 In general an integrated program of torsional vibration measurement shall contain the following data corresponding to the given below guidelines on the contents and drawing up the report on shafting torsional vibration measurements (refer to 5.1):

.1 grounds for making measurements (prototype ship, modernization of plant, replacement of propeller, etc.), ship class, project number, name of the ship, as well as the name and number of the documents on torsional vibration calculations with an indication as to who has made the measurements and when these were done and agreed. In case this document has not been submitted previously, it shall be attached to the program;

.2 a sketch of the ship's propulsion plant and its description with the list and basic characteristics of its components;
.3 design torsional diagram of the system and the relevant graphs of natural frequencies for all basic modes of vibration. The recommended positions of the measurement sensors corresponding to the maximum amplitudes of displacement or twisting of the system components shall be shown on a design torsional diagram;

.4 requirements for the conditions under which the sea or mooring trials of the ship and plant (ship's loading and draught, sea state, engine adjustment, shafting condition, etc.) shall be performed;

.5 requirements for variants of the plant components connection and plant operation modes during measurements (speed range and variations, fixed speeds, operation with the cylinder disconnected, manoeuvres, manual or remote automatic control of the engine, etc.);

.6 requirements for measuring systems (range of frequencies and amplitudes measured, types of sensors, the principle of signal transmission and conversion from the sensor to the recording and processing unit), as well as the software intended for processing and spectrum and harmonic analysis on PC, etc.

The measuring systems shall provide the following inaccuracy of measurements:

- up to 5 % when measuring vibration amplitudes,
- up to 5 % when measuring stress amplitudes,
- up to 3 % when measuring vibration frequency;

.7 requirements for installation of sensors and other components of a measuring system including mounting devices and power supply under shipboard conditions.

3.4 The program shall contain requirements for the methods of processing and analysis of torsional vibrations records (including statistical methods) to provide reliability of estimates of the resonance speeds and amplitudes, as well as the total stresses due to forced vibrations.

3.5 The program shall contain the forms of submission of the report on measurements meeting the requirements specified in 5.1.9 – 5.1.12 of the Recommendations.

4. Recommendations on the contents and drawing up the preliminary conclusion on the results of torsional vibration calculations

4.1 The preliminary conclusion shall contain the following details:

- name of the ship and project number;
- date, place and conditions of taking measurements (ship's loading and draught, sea state, etc.);
- person who takes the measurements;
- used measuring equipment and points of measurements;
- basic measurement modes.

4.2 To be presented are: maximum resonance amplitudes and stresses at sections under consideration with indication of the resonance speeds, vibration orders and modes as well as stresses and loads in the most stressed shafting portions recalculated as a consequence of the measurement results, and measured temperatures of the rubber components of the flexible couplings. For the components listed, the permissible stresses (torques) of these values shall be presented.

4.3 The inferences in the conclusion shall point at the necessity of assigning barred speed range or at the absence of the same. In case where the barred speed range is assigned, it is necessary to indicate position and width thereof, as well as to provide temporary recommendations on the use of the plant with due account of the torsional vibration for the period immediately ahead (until the final report is issued).

5. Recommendations on the contents and drawing up the report on shafting torsional vibration measurements

5.1 The report on shafting torsional vibration measurements shall contain the following data:

- grounds for making measurements (prototype ship, modernization of plant, replacement of propeller, etc.), ship's class, project number, name of ship, as well as the number of the previously submitted documents on torsional vibration calculations with an indication as to who has made the measurements and when these have been made;
.2 date, place and conditions of measurements (ship's loading and draught, sea state, etc.), results of the engine adjustment verification.

Brief description and sketch of the ship's propulsion plant and design torsional diagram of the system shall be given here.

If the inertia moment of the propeller when passing through resonance, combined with the mean torque corresponding to the resonance speed, according to the calculation exceeds 2.5 \( M_{\text{nom}} \), it is necessary to indicate the propeller interference fit (diametric interference fit \( \delta \) or axial pull-up \( \delta_{ax} \) and taper of the propeller) and its corresponding friction torque in the shaft to propeller connection;

.3 brief characteristic of the used measuring systems and sensors therein and recording and processing equipment (type, model, firm (manufacturer), natural frequency, range of frequencies and amplitudes measured, inaccuracy of measurements.

The measuring systems shall provide the inaccuracy of measurements as specified in 3.3.6;

.4 position of the sensors (when measurements are not made at the fore end of the engine – coordinates of sections being torsiographed or strain measured). Position of the sensors shall be shown on the shafting sketch or calculation scheme of the system;

.5 method of connection of sensors and instruments;

.6 type of time and shaft speed markers;

.7 scales of amplitude or stress records, calibration curves, scale of time marking;

.8 brief description of the plant operation conditions under which measurements have been made (range and rate of the speed measurement, fixed speed, manoeuvres, manual or remote automatic control of the engine, etc.);

.9 graphs of changes (depending on the engine speed) in the vibration amplitudes of the sections being torsiographed and stress amplitudes at the sections being strain measured with indication of the resonance speeds, orders and modes of the resonance vibrations. The results of the harmonic analysis of torsiograms (oscillograms) shall be also presented.

Samples or copies of the torsiograms (oscillograms) at the resonance and nominal speeds shall be presented here. These samples shall indicate the speed, vibration order, record scale, values of the maximum amplitudes and stresses, time marking scale;

.10 comparison of the calculated frequencies, amplitudes of vibrations and stresses with the measured ones.

In case of discrepancy between the frequencies by more than 5 %, recalculation of natural frequencies for the revised torsional diagram of the system shall be presented;

.11 table of measured or recalculated, as a consequence of the measurement results, resonance stresses (torques) due to torsional vibration at various shafting portions (shafts, couplings, reduction gears, etc.), deformations and temperatures of the flexible components of couplings. Where necessary, the values of stresses due to combined resonance and forced vibrations shall be also presented.

A comparison shall be made between the cited values and corresponding permissible values according the Register rules or other normative documents.

For FPP, the table shall give the inertia moment values when passing through the resonance, combined with the mean torque corresponding to the resonance speed. The total of these shall be compared for the vibration orders under consideration with the friction torque in the shaft to propeller connection;

.12 graphs showing relationship between the stresses, torques and other values and the engine speed, obtained during direct measurements or recalculated proceeding from the results of these for various shafting portions: propeller, intermediate, thrust, crank shafts, couplings, reduction gear. The curves of the relevant, permissible for continuous running and rapid passage values shall be plotted on the graphs. If there are barred speed ranges, they shall be marked on the graphs. If the measured stresses and torques do not exceed 80 % of the permissible values the graphs need not be submitted (enough information in tabular form in accordance with 5.1.11);
.13 inferences on the absence of the barred speed range within the entire operational speed range or on the necessity of assigning the barred speed range, its position and width;

.14 recommendations for making arrangements aimed at reduction of the torsional vibration or detrimental impact thereof under operation conditions (shift of the specified operation modes of the plant in relation to the resonance ones, installation of a unit for rapid passage of the barred speed range in the remote automatic control system and re-adjustment thereof, passage of the barred speed range in case of manual or remote automatic control of the engine, additional adjustment of the engine, more frequent examination of flexible couplings, etc.).

5.2 When it is necessary to make structural alterations in the shafting system, it is recommended to correct the results of relevant calculations (torsional vibration calculation under recommended change in the mass inertia moments of the system or in the compliance of the shafting portions, installation of additional flywheels, damper or antivibrator, change in the firing timing, calculation to be made when the necessary interference fit of the propeller is selected, etc.).
RECOMMENDATIONS ON MOUNTING OF STERN TUBE ARRANGEMENTS

1. The Recommendations set the requirements in the absence of specified and agreed shipbuilding standards or national standards, which application is agreed with the classification society.

2. To mark out the boring of fitness holes in shaft struts and stern tubes, the theoretical axis of the shafting may be laid out using an optical device, steel round line or a light beam. Axis may be laid out by means of the steel round line only for shafting not exceeding 15 m in length. In specific cases, if this follows from the calculation of the technological parameters of alignment, in order to achieve judicious loads on the bearings, the axis position for the shaft stem and stern tube boring shall be shifted relative to the theoretical axis of the shafting by displacing the markers across the end faces of the surfaces bored for the value of the calculated boring ordinates.

   The accuracy of installing the markers at calculated positions in relation to the theoretical axis of shafting shall be not less than 0.05 mm. Control circles: one of a diameter equal to boring size and another — larger by 10 mm shall be marked from the centres of the markers on the faces of the struts and stern tube.

   With the main machinery secured, it is necessary, when marking out boring, to take into account the mounting clearances.

3. Diameters of the fitment holes, length of the fitment holes, form deviations of the fitment holes, surface roughness shall comply with the guidelines of the technical documentation. The permissible deviation of the axis of the bored fitment holes relative to the control circle centres on the faces of the strut, stern boss and welded-on pad of the afterpeak bulkhead shall not exceed 0.5 mm. Non-perpendicular position of the machined surface of the end faces of the strut, stern boss and welded-on piece of the afterpeak bulkhead to the axis of the bored holes shall not exceed 0.2 mm/m. To verify the perpendicular position, it is recommended to use a boring bar.

4. The external fitment holes of the stern tube, strut bush mated with the fitment holes of the strut, stern boss and welded-on pad of the afterpeak bulkhead shall be made to the mean actual diameter values of the mated fitment holes of the strut, stern boss with due account of the mean assured interference indicated in the technical documentation (mean interference shall be determined separately for each fitment hole), as well as the permissible clearance in the hole of the welded-on piece of the afterpeak bulkhead. Strut, stern boss and welded-on piece of the afterpeak bulkhead may be bored to actual dimensions taken from the finished fitness holes of the stern tube and strut bush with the requirements for ensuring a predetermined interference in the connection of the bush with strut, stern tube with stern boss and a clearance between the stern tube and welded-on piece of the afterpeak bulkhead met.

5. Prior to installation and during press-fit of the strut bush, stern tube and stern bearings it is necessary to verify that:
   - all the articles to be installed comply with the accompanying documentation;
   - actual dimensions of the mated surfaces will afford fit (interference, clearance) required by the drawings. For this purpose, prior to press-fit of the strut bush, stern tube and stern bearings the fitment holes of the strut, stern boss welded-on piece of the afterpeak bulkhead as well as the fitment holes of the articles to be installed shall be subjected to check measurement. The measurement results of the fitment holes shall be entered in measurement
tables (record, service log of the shafting) with indication of the ambient temperature during measurements;

technological measures for ensuring press-fit have been put into effect; along with that, the press-fit has been performed by application of forces specified by the technical documentation. Actual press-fit forces read from the indications of pressure gauges of the hydraulic devices shall be entered in the measurement tables (record, service log of the shafting).

6. Once the press-fit has been made, it is necessary to check security of fastening the strut bushes, stern tubes and stern bearings as well as locking the fasteners.

7. The stern bearings, including strut and bossing bearings shall be finished with the mounting clearances, conditions for subsequent alignment of the shafting and tight fit of the stern and propeller shaft to the lower halves of the stern bearings ensured.

The stern tube may be installed in assembly with the stern bearings the internal surfaces of which have been finished on a machine tool.

After completing mounting of the stern tube it is necessary to make check measurements of the internal diameter of the stern bearings at the stern tube fitment holes section, as well as to examine the stern bearings.
RECOMMENDATIONS ON MOUNTING AND ALIGNMENT OF SHAFTING

1. The Recommendations set the requirements in the absence of specified and agreed shipbuilding standards or national standards, which application is agreed with the classification society.

2. After installation and welding, the supporting surfaces of the foundations for bearings shall be machined. The supporting surfaces of the foundations may be machined prior to installation of the foundations on board ship. In this case, after installation it is necessary to check the supporting surfaces of the foundations in accordance with the requirements of this Section.

3. The supporting surfaces of the foundations shall be machined with a slope outwards in the range from 1:150 to 1:50. In accordance with the guidelines of the technical documentation, the bearing foundations may be machined with no slope. The supporting surfaces shall have no slope inwards the foundations.

4. The limiting deviations from non-planeness of the supporting surfaces, machined surface finish as well as thickness of the supporting plates of the foundations, after being machined, shall comply with the requirements of the technical documentation. Individual reductions in thickness shall be accepted for supporting plates with size not more than 10 % of the nominal one. The supporting surfaces of the foundations may have also local unevenesses and cavities up to 0,15 mm in depth which shall be dispersed and have a total length not exceeding 1/3 the nominal length of the supporting surface.

5. The machining quality and flange slope of the foundation shall be checked by rule and feeler gauge. The planeness of the machined foundation surfaces shall be verified by placing the rule over the surface and by measuring the clearances between the rule and supporting foundation surface with the use of the feeler gauge.

6. Prior to installation of the propeller shaft, it is necessary to verify that:
   - the propeller shaft together with all associated articles to be installed complies with the accompanying documentation;
   - the propeller and half-coupling have been fitted to the propeller shaft;
   - the technological measures for drawing in the shafts have been put into effect (lubrication of bearings, liners, etc.);
   - the results of check measurement of the propeller (stern) shaft working journals and the bearing bores meet the requirements of the technical documentation in respect to the clearance value in the stern bearings and strut bearing.

   The results of measurement shall be entered in the measurement tables (record, service log of the shafting).

7. After completing installation of the shaft, it is necessary to check, with the use of feeler gauges, the clearances in strut and stern bearings from the bearing faces in the upper part. The clearances shall meet the requirements of the technical documentation. The difference in side clearances shall not exceed one-half the nominal clearance. The side clearances in the oil-lubricated stern bearings shall be measured at points located at an angle of 30° upward from the horizontal axis. The clearance in the oil-lubricated bearings may be checked by direct measurement of the shaft diameter and internal diameter of the stern bearings. The results of measurement shall be entered in the measurement tables (record, service log of the shafting).
8. The axial position of the propeller (stem) shaft in the stern tube shall be noted. The result shall be entered in the measurement tables (record, service log of the shafting). For the oil-lubricated stern tubes it is also necessary to measure the position of the propeller shaft by the shaft sag gauges (if gauges and standard instrument are available). The results of measurements shall be entered in the measurement tables (record, service log of the shafting).

9. As regards the stern glands, it is necessary to check perpendicular position of the end face of the stern tube or welded-on piece of the afterpeak bulkhead in relation to the shaft surface, the perpendicular position misalignment in this case shall not exceed 0.2 mm/m. Misalignment between the stern tube gland casing and shaft shall not exceed 25% of the diametral clearance between the closing sleeve and shaft.

The butts of the gland packing rings shall be cut off to an angle of 90°. Packing shall be placed into the gland box in such a manner that the butts are positioned at an angle not less than 90°. When placing packing, no clearance in the butts shall be accepted. The covering sleeve, with the compressed packing set down, shall enter into the journal box of the gland to a depth not less than 5 mm.

Mounting, testing and control of the fore and after seals of the stern tube with oil-lubricated bearings shall be carried out in accordance with the requirements and guidelines of the technical documentation. As a rule, test shall be conducted with the propeller shaft being turned over. The propeller shaft shall be turned over at the working oil pressure in the lubrication systems of the stern bearings with the spaces between lip seals drained.

A similar method of control shall be applied to the seals of stern tubes with fresh water lubricated bearings.

10. Prior to installation of shafts and alignment of shafting it is necessary to verify that:
    all the installed articles comply with the accompanying documentation;
    foundations for bearings have been checked and their machining finalized according to 2–5;
    results of check measurements of the shaft journal diameters and bores of the bearing bushes meet the requirements of the technical documentation in respect to the value of the bearing clearances. The measurement results shall be entered in the measurement tables (record, service log of the shafting);
    rolling bearings have been mounted on intermediate shafts. When the optical method of alignment is used, the shafts shall be removed from the rolling bearings for a period when a false shaft with an optical device is installed;
    shafting bearings have been installed on foundation with temporary fixtures for mounting and alignment of shafts and bearings, including installation of adjusting bearings;
    shafts have been laid and turned relative to each other until the check marks scribed on flanges, when the shafts have been mated in the workshop, match each other. Some shaft connections may be mated on board ship in case where it seems impossible to perform this work in a workshop. In such a case, both the radial and axial run-out of the shaft flanges and journals shall not exceed the values given in Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision;
    propeller (FPP or CPP) has been mounted on the propeller shaft in accordance with the requirements of Section 7.

11. The shafting shall be aligned so that at any ship loading conditions and allowable wears of shaft and bearings under service conditions the loads on bearings and stresses in shafts for a given design of the shafting and its bearings do not exceed allowable values and that the possibility of arising alternating loads or negative reactions is also eliminated. For the shafting connected with reduction gear it is necessary to take into consideration the thermal expansion of the reduction gear (when the shafting is connected with a mechanism of other type, consideration of such expansion is recommended). For ships with the intermediate shaft diameter over 500 mm, it is recommended to take into consideration the action of the propeller
hydrodynamic moment on the shafting. The said conditions of alignment shall be confirmed by an analysis with necessary calculations made using generally accepted methods. In this case, it is recommended to take the following values as the allowable shaft stresses and bearing loads:

1. normal bending stresses arising in shafts during mounting and service: not more than 25 MPa – for propeller and tail shafts and not more than 35 MPa – for intermediate shafts;
2. mean pressure on the lower half of bearings due to the action of load on the bearing in the range:
   50 – 500 kPa — for babbit-lined bearings;
   50 – 300 kPa — for non-metal bearings.

12. The method of aligning the shafting shall be dictated by the salient features of its design and established by the shipyard (designer), proceeding from the calculation of the process parameters of alignment with due account of the values of shaft stresses and bearing loads as stated in item 11. The alignment process parameters include: values of loads on the stern, journal and thrust bearings; values of angularities and displacements in the shaft couplings; lack of coaxiality of the bearings in relation to the optical axis of the device, etc.

13. Alignment may be performed by one of the methods listed below:
   1. by loads on the bearings, for which the values of the shafting bearing loads shall be assumed as the design alignment process parameters;
   2. by design angularities and displacements in the shaft couplings, for which the values of the angularities and displacements in the shaft couplings shall be assumed as the design alignment process parameters;
   3. by an optical method in case of shafting with rolling bearings, for which the values of the lack of coaxiality of the bearings in relation to the optical axis of the device shall be assumed as the design process parameters;
   4. by angularities and displacements in the flange connections within the specified tolerances, namely:
      by displacement — 0,1 mm;
      by angularities — 0,15 mm/m.

Use of one or other method of alignment shall be agreed with the Register.

14. The alignment of the shafting by angularities and displacements in the shaft couplings shall not be permitted if deflection of the shaft ends due to own weight with the shafts lying freely on two journal (or adjusting) bearings exceeds 0.3 mm.

15. No matter what the alignment method is used, the tolerances for the angularities and displacement or other values in the connection of the shafting with the output flange of the main engine (reduction gear) shall comply with the requirements of the main engine (reduction gear) manufacturer.

Along with that, additional loads due to shafting on the bearing of machinery mated with the shafting shall be minimum and lie within the limits permitted by the machinery manufacturer.

16. The shafting may be aligned in a module or assembled hull of the ship while afloat, on building berth or in dock. During the installation of the stern tube and shafting, change in the ship's hull position in way of the shafting and machinery space shall be within ±3 mm in relation to its position noted at the beginning of the work.

17. The alignment of the shafting shall be checked while the ship is afloat at the displacement not less than 85 % of the light displacement with installed (in the vicinity of the shafting and machinery space) main machinery, boilers, basic heavy auxiliary machinery and special arrangements with a mass more than 1 % of the total mass of machinery and arrangements in this area.

The possibility of checking the alignment and complete mounting of the shafting on the building berth (in dock) shall be agreed with RS upon submission of the relevant technical background.
18. The check measurement of the alignment process parameters shall be made after fitting of shims for bearings. The check measurement of the loads on the bearings shall be made by alternate weighing of the bearings with the use of dynamometers. In so doing, the bearings shall not separate from the shims by more than 0.1 mm. The measurement of the loads on the bearings may be made by simultaneous weighing them with the use of dynamometers. The allowable deviation of the actual load from the calculated one and the difference in the dynamometer readings shall be determined by calculation.

The check measurement of the angularities and displacements in the shafting couplings shall be made with the use of the following:
- twin pointers with indicators;
- twin pointers or rule and feeler gauge;
- special fixture.

Measurement with the use of a rule and feeler gauge may be used when the flange diameter is over 200 mm. The allowable deviations from the calculated values of angularities and displacements shall be determined by calculation.

When the shafting is aligned by optical method, the rolling bearings shall be installed with the use of a special fixture. The slope of the false shaft axis in relation to the axis of the device or round line shall not exceed 0.6 mm/m.

After alignment, the deviations of the bearing positions from the optical axis of the device shall not exceed the allowable values determined by calculation.

The results of measurement of the shafting alignment process parameters shall be entered in the measurement tables (records, service log of the shafting) which shall contain also the calculated process parameters including the allowable deviations from these values.

19. The connecting bolts of coupling flanges may be manufactured to actual size of holes with the fit specified by the technical documentation ensured. The holes for bolts shall be finished jointly for both flanges of adjacent shafts. Not more than one collar mark up to 1 mm in width and up to 0.3 mm in depth may be permitted on the hole surface over a length of 15 mm, after finish machining.

The completely assembled flange connections shall be tightly squeezed by the bolts. The nuts and heads of the bolts shall fit snugly to the flange planes; a feeler of 0.05 mm in thickness shall not pass between flanges as well as between the bolt head or nut and the flange plane. Fasteners of the flange connections shall be securely locked in compliance with the requirements of the technical documentation.

20. Upon finalization of the alignment, it is necessary to check the position of shafts in the bearings and the fit of the supporting bearing shells to the shaft journals. Such check shall be performed when all the couplings have been completely assembled including coupling with the main machinery as well as with the shafting bearings completely secured. In so doing, a feeler of 0.05 mm in thickness shall not pass to a depth over 10 mm in the lower part of the bearing over an envelope arc of 50 – 70°. Side clearances shall be equal to one-half of the nominal oil clearance. The allowable difference in side clearances shall be equal to 1/6 the oil clearance.

Position of the thrust bearing with non-adjustable thrust pads shall be checked by clearances between the thrust shaft and thrust bearing pads. The difference in fore and aft clearances shall not exceed one-half of the oil clearance.

21. The quality of matching pads to the supporting feet of the bearing housings shall be checked with the bolts loose. A feeler of 0.05 mm in thickness shall not pass between the pads and foundations as well as between the shims and supporting surface of the bearing housing feet.

In some places, the total extent of which does not exceed 1/3 the pad perimeter a clearance up to 0.1 mm may be allowed. The pads shall not hang down from the foundation and protrude from under the bearing housing feet for more than 5 mm. Once the pads have been placed into their positions, they may be tack welded by electric welding.
22. Holes in the foundation shall be positioned so that the distances from the hole centres to foundation edges, stiffeners or to vertical plates are at least of 1.5 the bolt diameter.

Holes for the tightly fitted bolts extending through the supporting foot of the bearing housing, pad and foundation shall be machined simultaneously. No more than one collar mark up to 1 mm in width and up to 0.3 mm in depth may be allowed on the machined surface of the hole over a length of 15 mm along the generatrix. To eliminate intolerable cavities and scores on the hole surface the diameter may be increased to 10 % of its nominal value.

The foundation tightly fitted bolts shall be manufactured to actual sizes of holes with the fit specified by the technical documentation ensured.

23. After securing, the bolt heads and nuts shall fit snugly to the foundation or bearing housing foot. A feeler of 0.05 mm in thickness shall not pass under the nut and bolt head over the length of not less than 2/3 the perimeter. Fit of the nuts and heads of the tightly fitted bolts need not be checked. To ensure fit, feet and foundations may be undercut. The depth of the undercut shall not exceed 10 % of the bearing housing foot or foundation flange. The bolt shall not be sunk into the nut. Upon finalization of mounting of the bearings, the fasteners shall be securely locked in accordance with the requirements of the technical documentation.
7 PROPELLERS

7.1 GENERAL

7.1.1 The provisions of this Section apply in the technical supervision of the propellers and their components listed in the RS Nomenclature.


7.1.2 The Section sets forth the procedure of the Register technical supervision during mounting and testing of the propellers and their components on board the ship.

7.1.3 The procedure and scope of the checks, surveys and tests of the shafting during their mounting on board the ship shall be determined by the shipyard based on the examination and testing plan developed in compliance with 7.2.1 of the Guidelines, as well as with 13.3, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision.

7.1.4 Numerical values for test modes and duration, as well as numerical criteria for installation works given in this Section are provided for reference. Prior to commencement of construction, other quality criteria given in the recognized national or international standards, or manufacturers’ documents/instructions may be agreed with the RS Branch Office.

7.1.5 Tests and checks specified in this Section are based on an assumption that the materials, component parts and products subject to the Register technical supervision according to the RS Nomenclature and supplied for the propeller installation have been manufactured and tested at the firm (manufacturer) and have the documents confirming their manufacture and testing under the Register technical supervision.

7.1.6 In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of the fire-fighting means in substantiated cases.
7.2 SURVEY PLANNING

7.2.1 Prior to commencement of survey of the propellers of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 7.2.1 and 7.4 – 7.7. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

7.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

7.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

7.2.4 Quality standards for installation and testing of the propellers shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

7.2.5 Any changes to the kick-off meeting records shall be agreed and documented.

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<th>No.</th>
<th>Item of technical supervision</th>
<th>Review of document for the article</th>
<th>External examination</th>
<th>Check of mounting</th>
<th>Hydraulic tests, check for tightness</th>
<th>Mooring trials</th>
<th>Sea trials</th>
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7.3 TECHNICAL DOCUMENTATION

7.3.1 When performing the technical supervision, the RS surveyor shall be guided by the technical documentation approved by the Register within the scope required by Part I "Classification" of the Rules for the Classification and Construction and agreed process procedures for installation and testing of propellers.

7.3.2 Documents confirming the Register technical supervision during manufacture of the materials, related equipment and products to be supervised and incoming for the mounting of propellers on board the ship in accordance with the supervision form stipulated by the RS Nomenclature shall be submitted.

7.3.3 Documents on all committed deviations from the approved technical documentation on propellers, as well as on the rectification of drawbacks detected at the previous stages of technical supervision shall be submitted to the RS surveyor.
7.4 FIXED PITCH PROPELLERS

7.4.1 General provisions concerning technical supervision and mounting of fixed pitch propellers (FPP) on board the ship are set out in 7.1.

7.4.2 Before the FPP is fitted, it is necessary to make sure that:

.1 the propeller cone and shaft cone are free of dents, corrosion and other defects preventing contact of the mated surfaces;

.2 the propeller cone fits to the shaft cone as required by the technical documentation (refer to also Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision);

.3 if there are keyed joints, keys are matched as required by the technical documentation;

.4 a control mark has been drawn on the shaft or the fixture for monitoring axial displacement of the propeller being fitted on the cone after the initial position has been determined.

7.4.3 When the FPP is being fitted, it is necessary to monitor axial displacement of the propeller in relation to the shaft, pressure when hydro-press fitting is used, determining axial force and pressure exerted on the mated surfaces.

7.4.4 When mounting the FPP, it is necessary to check installation of the nut and its locking, tests of the propeller (propeller shaft) seal.

7.4.5 When exercising control over the fastening of the detachable parts of FPP, it is necessary to check the tightening force, fastening parts of the detachable blades, nut and fairing.

7.4.6 The securing devices of the bolts (studs), by which the blades are fastened to the detachable-blade propellers of ice class ships, shall be recessed in the blade flange.

7.4.7 It is necessary to check that the space inside the propeller cap, as well as the empty spaces between the boss and shaft cone are filled with non-corrosive mass (refer to 6.3.2, Part VII "Machinery Installations" of the Rules for the Classification and Construction).
7.5 CONTROLLABLE PITCH PROPELLERS AND THEIR SUPPORTING SYSTEMS

7.5.1 General provisions concerning the supervision during the mounting and testing of controllable pitch propellers (CPP) and their supporting systems on board the ship are set out in 7.1.

7.5.2 Prior to mounting of the CPP on board ship, it is necessary to check the mated surfaces of blades, boss with propeller shaft, pitch actuating mechanisms, as well as their fastening parts in order to make sure that they have not been damaged during transportation or storage.

7.5.3 When mounting the CPP on board ship, it is necessary to monitor:

.1 force to make the coupling pressfit on the propeller shaft, tightening torque and quality of locking the securing items in flange joints;
.2 condition of the propeller shaft, boss and blade sealing;
.3 turning-over units and agreement between the blade position and the pitch indicators;
.4 requirements in 7.4.6 and 7.4.7 shall be met.

7.5.4 Upon finalization of mounting, CPP and oil pipes shall be tested for tightness by a hydraulic pressure in compliance with Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.
7.6 VERTICAL AXIS PROPELLERS

7.6.1 General provisions concerning the technical supervision during mounting and testing of vertical axis propellers (VAP) on board the ship are set out in 7.1.

7.6.2 Prior to the VAP mounting on board the ship, it is necessary to check the flanges of the VAP housing and foundation, foundation bolts and nut for the absence of dents, rust and other defects.

7.6.3 When mounting VAP on board the ship, it is necessary to check:
   .1 clearances between the rotor bottom and hull shell plating, between the vanes and guard;
   .2 shaft line alignment;
   .3 tightening torques of the VAP attachment to the seating;
   .4 rotor shaft seals.

7.6.4 Upon finalization of the mounting, VAP shall be tested in compliance with Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.
7.7 STEERABLE PROPELLERS

7.7.1 Prior to mounting of steerable propellers on board the ship, the requirements of 7.1 shall be met. Moreover, it is necessary to check the surfaces of flanges on the foundation and steerable propeller housing, rudder stock, propeller and nozzle in order to make sure that they have no dents, corrosion and other defects.

7.7.2 When mounting steerable propellers on board ship, it is necessary to check:
   .1 tightening of the attachment of the steerable propellers to foundation and their locking;
   .2 alignment of the driving shaft with driving mechanism.

7.7.3 Upon finalization of the mounting, the steerable propeller shall be tested according to the test program approved by RS.
7.8 MOORING TRIALS OF THE PROPELLERS

7.8.1 Once mounted on board ship, the propellers shall be checked in operation simultaneously with tests of the main machinery in accordance with Section 5.

7.8.2 The mooring trials shall be applied to the standard machinery, equipment, apparatus and control system according to a program approved by the Register.

7.8.3 During mooring trials of CPP, it is necessary to check:

   .1 agreement between the remote pitch indicators and position of the manoeuvring handles and the local mechanical pitch indicator;
   .2 position of the blades and controls of the CPP corresponding to zero-thrust of the propeller;
   .3 operation of CPP when the blades are turned over from “full ahead” to “full astern” from each control console;
   .4 operation of the control, alarm, automatic and protection systems in compliance with Section 12;
   .5 time required to turn over the blades from each console and by each pump set.
7.9 SEA TRIALS OF THE PROPELLERS

7.9.1 The sea trials of the propellers shall be carried out according to a program approved by the Register, simultaneously with the tests of the main machinery in compliance with Section 5.

7.9.2 During the sea trials of CPP, it is necessary to check:
- .1 zero-position of the blades at which the ship has no way with the CPP rotating;
- .2 agreement between the CPP blade position and the power output of the main machinery, the propeller shaft speed and ship speed under various specified operation conditions;
- .3 operability of the CPP under all conditions during the time stipulated for checking the main machinery;
- .4 reversing properties of the CPP when the blades are turned over from "full ahead" to "stop" and back; from "full astern" to "stop" and back; in so doing, it is necessary to measure the turning-over time and oil pressure in the hydraulic system;
- .5 emergency locking of the blades in ahead position, start and operation of the main machinery with the blades locked, as well as reversing of the main engine, if provided;
- .6 operation of the device preventing the engine from overloading;
- .7 turning-on of the stand-by power supply set of the hydraulic system when turning-out of the main set is simulated;
- .8 operation of the control, alarm and protection systems.

7.9.3 During sea trials of VAP, it is necessary to check:
- .1 agreement between the position of the main machinery power control lever and the propeller speed, ship speed or traction force under various operation conditions of the ship;
- .2 operability of VAP under various conditions during the time stipulated for checking the main machinery;
- .3 joint and separate shifting of the handles to control the propulsion and steering servomotors under various operation conditions of the ship;
- .4 time required to shift the control lever from zero position to astern and ahead positions;
- .5 operation of the emergency manual VAP control system;
- .6 operation of the control, alarm and protection systems.

7.9.4 Trials shall include verification of the fulfillment of the requirements in 2.1.4, 2.1.5 and 2.1.8 (for ships of river-sea navigation), Part VII "Machinery Installations" of the Rules for the Classification and Construction.
8 SYSTEMS AND PIPING

8.1 GENERAL

8.1.1 This Section specifies the scope and procedure of technical supervision during installation and testing of the ship systems.
8.1.2 General provisions for the organization of the technical supervision are given in Section 1.
8.1.3 Technical documentation.
8.1.3.1 Installation and testing of systems and piping shall be performed under the Register technical supervision according to the RS-approved technical documentation.
8.1.4 Technical supervision of the Register.
8.1.4.1 Verification of the installation and testing of the systems and piping shall be generally carried out in conjunction with the associated machinery, pressure vessels and equipment.
8.1.4.2 The system components shall have documents confirming the Register technical supervision during the manufacture thereof in accordance with the supervision type stipulated by the RS Nomenclature.
8.1.4.3 Surveys during installation and testing of systems and piping shall be performed in compliance with the examination and testing plan developed by the shipyard according to 8.2.1 based on Table 8.1.4.3 taking into account 8.3.

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Items of technical supervision</th>
<th>Installation</th>
<th>Special checks</th>
<th>Mooring</th>
<th>Trials</th>
<th>Sea</th>
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<tr>
<td></td>
<td>Review of technical documentation</td>
<td>External examination with checks of system elements and inspection</td>
<td>for tightness under working conditions</td>
<td>in modes specified for supporting mechanisms, vessels and other devices in operation</td>
<td>special checks in operation</td>
<td>special checks</td>
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<td>1</td>
<td>Ship's service systems:</td>
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<td></td>
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<tr>
<td>.1</td>
<td>bilge</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>–</td>
<td>–</td>
</tr>
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<td>.2</td>
<td>ballast, heel and trim</td>
<td>+</td>
<td>+</td>
<td>+</td>
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<td>.5</td>
<td>heating systems of fuel and lub oil tanks, ballast water tanks and cargo tanks of oil tankers</td>
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<td>+</td>
<td>+1</td>
<td>+</td>
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<td>.6</td>
<td>ventilation</td>
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<td>+</td>
<td>+</td>
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<td>.9</td>
<td>voice pipes</td>
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<td>+</td>
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<td>cargo systems of chemical carriers, gas carriers and oil tankers</td>
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<td>+</td>
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<td>.12</td>
<td>inert gases</td>
<td>+</td>
<td>+</td>
<td>–</td>
<td>+</td>
<td>–</td>
</tr>
</tbody>
</table>

1 Tightness tests according to 8.3.2.4.4 and 8.3.3.1.7.
8.1.4.4 When surveying the systems and piping, the RS surveyor, in addition to checking for the fulfilment of the working documentation requirements, shall exercise control over the compliance thereof with the schematic diagrams of the approved design.
8.2 SURVEY PLANNING

8.2.1 Prior to commencement of survey of the systems and piping of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 8.1.4.3. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 8.3 and 8.4.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

8.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

8.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

8.2.4 Quality standards for installation and testing of the ship systems and piping shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

8.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
8.3 TECHNICAL SUPERVISION DURING INSTALLATION OF SYSTEMS AND PIPING

8.3.1 General requirements.
8.3.1.1 Surveying the installation of the systems and piping referred to in Table 8.1.4.3 shall provide for checking:
   .1 compliance of the system components with the requirements of the technical documentation;
   .2 proper arrangement of the piping, fittings, instrumentation and other components;
   .3 the system as a whole for tightness under the working conditions according to Table 8.1.4.3.
8.3.1.2 In the process of checking the compliance of the system components with the requirements of technical documentation it is necessary to make sure that:
   .1 the completeness of the system complies with the technical documentation;
   .2 articles of the required dimensions and types have been used as the system components;
   .3 the system fittings have the Register documents confirming the Register technical supervision during their manufacture;
   .4 prior to installation on board ship, the system components have been subjected to hydraulic tests by an appropriate pressure.
8.3.1.3 When checking the proper arrangement of the system components, fulfilment of the following requirements shall be monitored:
   .1 assembly, welding and testing of the ship hull, including partition bulkheads, foundations, manholes, etc. shall be finalized;
   .2 fitting-out parts of the hull structures (welded-on pieces, bulkhead/deck pieces, scuppers, etc.) shall be installed;
   .3 installation of machinery, vessels and other equipment being part of the system shall be finalized and adopted by the firm (manufacturer) inspection body;
   .4 bottom, side, shut-off and other fittings and instruments shall be installed;
   .5 standard gaskets, fasteners and hangers shall be installed on the pipes, the latter shall be securely fastened;
   .6 flanges of adjacent pipelines shall be dispersed and not be tangent to the pipes running in parallel;
   .7 presence of devices intended for purging and draining of the medium, absence of visible places of liquid stagnation and air pocket formation; other measures to preclude hydraulic shocks;
   .8 presence of identification plates of the fittings and indicators of the shut-off valve position;
   .9 existence of cathodic protection;
   .10 existence of insulation in the appropriate areas, devices for leak collection, as well as casings which protect the electrical equipment and hot surfaces against contact with the conveyed medium from the detachable joints;
   .11 ease of operation of the local and remote controls of the fittings, reliable access to these controls.
8.3.1.5 Special requirements for the survey of installation of the systems which take account of the salient features of the design and purpose of each system are set out in 8.3.2 and 8.3.3.
8.3.1.6 Allowable misalignment of metal piping during assembly. Unless otherwise specified by the Register, the tolerances for the misalignment of the pipes to be welded shall be as follows:
   .1 for pipes of all diameters and thicknesses welded with remaining backing ring – 0,5 mm;
   .2 for pipes welded without backing ring:
      .2.1 with internal diameter less than 150 mm and wall thickness up to 6 mm inclusive – 1 mm or 1/4 the wall thickness, whichever is less;
      .2.2 with internal diameter less than 300 mm and wall thickness up to 9,5 mm inclusive – 1,5 mm or 1/4 the wall thickness whichever is less;
8.3.1.8 Check of the systems for tightness (except those especially indicated in 8.3.1.8.1) in accordance with 21.2.3, Part VIII "Systems and Piping" of the Rules for the Classification and Construction after their assembly on board the ship shall be generally performed under working conditions during the mooring trials of the systems.

If such conditions make it impossible to judge the tightness of the individual system components (air, sounding and overflow pipes, pipelines which are not easily accessible for examination, etc.) these components shall be subjected to special tightness tests at working pressure prior to testing the systems in operation.

8.3.1.8.1 Butt joints welded on board the ship shall be subjected to hydraulic tests in accordance with 21.2.1, Part VIII "Systems and Piping" of the Rules for the Classification and Construction. In so doing, the fittings of the systems shall be safeguarded against damage by test pressure.

8.3.1.8.2 If the hydraulic tests of the pipeline in assembly are conducted on board the ship, the strength and tightness tests may be combined.

8.3.1.8.3 When carrying out hydraulic tests, attention shall be given to possible formation of air pockets in the upper parts of the piping, and in connection with this, it is necessary to provide appropriate devices for air expulsion.

8.3.1.8.4 Use of compressed air as substitution for the tightness test under working conditions may be accepted only for systems specified in the relevant technical documentation approved by the Register.

8.3.1.8.5 The procedure of testing the piping by compressed air shall make it possible for the RS surveyor to make sure that no leaks from the joints and no impermissible air pressure drop occur in the system.

8.3.1.9 Protective anticorrosive coatings shall be used in accordance with 1.4.2, Part VIII “Systems and Piping” of the Rules for the Classification and Construction and the technical documentation approved by the Register.

During survey the applicable requirements of 2.12.7 of the Guidelines shall be met.

8.3.1.10 Materials containing asbestos shall not be used for installation and assembly of systems and piping on board the ship.

During survey of installation of systems and piping, the documents confirming the absence of asbestos in the materials of connection gaskets shall be submitted.

If the material of a sealing element is a material that has no Type Approval Certificate (except for copper and copper-base alloys, as well as rubber and ftorooplast) the Register reserves the right to require the performance of chemical analysis of the sample of the sealing material. The application of the rubber gaskets is allowed for systems and piping with the working medium temperature not more than 100 °C, ftorooplast – not more than 150 °C.

8.3.2 Special requirements for survey of installation of the ship’s service systems.

8.3.2.1 When surveying the installation of the bilge system, the following matters shall be checked in addition to those outlined in 8.3.1:

1. arrangement of the bilge suctions in all spaces to be drained to determine whether they comply with the design as regards their number and location (depending on the purpose, dimensions and configuration of the bottom part of the space);
.2 installation of non-return and non-return shut-off valves on distributing boxes and bilge suctions in accordance with the design;
.3 ease of access for cleaning mud boxes and strainers without having to disassemble the suctions and absence of superfluous bends between the boxes and bilges;
.4 installation of automatic alarms to give warning in the event of excess of permissible level in the wells;
.5 possibility for free access of water into the bilges or wells where a ceiling or removable covers are fitted;
.6 reliability of the means to disconnect the bilge system from other ship’s service systems.
8.3.2.2 When surveying the installation of the ballast system, the following matters shall be checked in addition to those outlined in 8.3.1:
.1 arrangements of suctions in accordance with the design;
.2 arrangement of ballast suctions and discharges in relation to the sea inlet boxes and pipes of other systems;
.3 availability of reliable means to disconnect the ballast system from other systems and from ballast tanks used for storage of fuel oil.
8.3.2.3 When surveying the installation of the sewage system and scupper pipe system, the following matters shall be examined in addition to those outlined in 8.3.1:
.1 proper installation of the side non-return valves, connecting pieces and scupper pipes;
.2 existence of pipe slopes ensuring reliable run-off of liquid;
.3 measures to prevent possible flooding of adjacent watertight compartments through the sewage pipes led to the machinery space bilges and shafting tunnels;
.4 absence of liquid run-off from the non-refrigerated cargo spaces into the bilges of refrigerated cargo spaces;
.5 operation of the hydraulic seals or equivalent devices;
.6 access to self-closing and non-return shut-off valves and their actuators.
8.3.2.4 When surveying the installation of the heating systems of fuel oil, lubricating oil and water ballast tanks, the following matters shall be checked in addition to those outlined in 8.3.1:
.1 mutual arrangement of the suction ends of pipes and heating coils in the fuel oil and lubricating oil tanks having regard to the requirements of 13.3.2 and 13.3.3, Part VIII "Systems and Piping" of the Rules for the Classification and Construction;
.2 availability of arrangements to monitor escape of the heating steam condensate from the fuel oil and lubricating oil tanks;
.3 availability of arrangements to monitor the fuel oil and lubricating oil heating temperature;
.4 tightness of the fuel oil heating coils when tested by hydraulic pressure of \(1.5P_{\text{work}}\) but not less than 0.4 MPa.
8.3.2.5 When surveying the installation of the ventilation system, the following matters shall be checked in addition to those outlined in 8.3.1:
.1 avoidance of the ventilation duct penetrations through watertight bulkheads;
.2 arrangement of fire dampers, existence of identification painting of the places where these are installed, operation of the automatic and manual drives and ease of access to the damper control, indicators of the damper positions;
.3 gastightness of the ducts for removal of explosion and fire-dangerous vapours and gases, installation of flamearresting fittings, absence of conditions for spark formation during closing of the ducts;
.4 availability of the closing arrangements for ducts operated from spaces fitted with smothering facilities;
.5 location of the ventilator heads of supply ducts and the air inlets to preclude the risk of drawing in contaminated air and admission of sea water;
.6 height of the ventilator coamings;
.7 independence of the ventilation ducts of stairway enclosures from ducts from other spaces in passenger ships;
.8 fitting of exhaust ducts from galley ranges;
.9 avoidance of the passage of the ventilation ducts intended for ventilation of machinery spaces in passenger ships through the accommodation and service spaces and control stations specified in the RS rules as well as ventilation ducts from the accommodation and service spaces and control stations through these machinery spaces;
.10 presence of devices monitoring operation of fans in enclosed spaces and holds of ships intended for the carriage of motor vehicles and ro-ro machinery;
.11 equipment of the ventilation of battery rooms and boxes to determine compliance with the requirements of the RS rules, namely: supply and removal of air; absence of the flame-arresting fittings; presence of coatings of the ventilation ducts and fan to protect them against the exposure to exhaust gases. In case of natural ventilation, it is necessary to check additionally the angle of duct deflection from the vertical, as well as the duct length. In case of mechanical exhaust ventilation, it is necessary to check additionally the free access for the air to the inlets of exhaust ducts;
.12 possibility of free flow of air to the inlets of exhaust ducts of the cargo pump rooms and location of these inlets;
.13 gastightness of the ducts outside the pump rooms, independence thereof from other ventilation systems and the device for emergency ventilation operating in the event of the inlets located below the floor plates being flooded;
.14 measures to prevent spark formation when the ducts from pump rooms are being closed, location of the outlets relative to other openings, oil vapour ignition sources and the inlets of ventilation ducts;
.15 location of the suction ventilation inlets relative to cargo area, cargo tank openings, open outlets of vent pipes, as well as availability of flame-arresting fittings;
.16 absence of trapped zones in holds intended for the carriage of dangerous cargoes. 8.3.2.6 When surveying the installation of the air, vent, overflow and sounding pipes, the following matters shall be examined in addition to those outlined in 8.3.1:
.1 availability of air pipes for each tank intended for the storage of liquid and each filled cofferdam, as well as the ice and sea inlet boxes;
.2 places where the air pipes are connected to the tanks and their location relative to filling pipes;
.3 fitting of shut-off valves directly on the ice and sea inlet boxes;
.4 places where the air pipes are fitted with due regard to fire safety and their height above the deck;
.5 correspondence of the clear area through the flame-arresting fittings to the cross-sectional area of the air pipe;
.6 fitting of automatic devices to prevent the sea water from getting into tanks through the outlets of air pipes;
.7 arrangement of the air pipes to preclude the formation of hydraulic seals under ship heel and trim conditions;
.8 absence of detachable connections of the air pipes of fuel oil and lubricating oil tanks in way of accommodation and refrigerated cargo spaces, as well as under the lining;
.9 presence of identification plates on the outlets of air pipes;
.10 secure attachment of the air pipes to hull structures and protection thereof against damage by deck cargo;
.11 presence of flame arresters and shut-off devices on vent pipes led from each tank; presence of flame arresters on pipes through which the tanks can communicate, their location which shall preclude the entry of liquid cargo into the flame arresters;
.12 compliance of the flame-arresting fittings of vent pipes (with due account of the ease of disassembly), crosssectional area, direction of the flow of the gas and air mixture being exhausted, devices for removing liquid installed, where necessary, with the requirements of the RS rules;
.13 height of the vent pipe outlets above the cargo deck and location thereof well away from the sources of ignition;
.14 reliability of special measures to ensure safely of the vent systems in ships carrying boiling petroleum products;
.15 pressure of pressure/vacuum valve operation for opening and closing (at the surveyor's discretion);
.16 location of the common header or pipe to which the overflow pipes are led in relation to the deepest damage and load waterlines;
.17 ease of observation and access to devices to indicate overflow of fuel oil;
.18 location and ease of access to the upper ends of sounding pipes led from tanks, bilges and wells;
.19 ease of passing a sounding rod in the sounding pipes;
.20 reliability of protection of the transparent inserts fitted on level indicators against damages;
.21 location of self-closing arrangements of the sounding pipes fitted in double-bottom fuel oil and lubricating oil tanks relative to the level of floor plates, heated surfaces and electrical equipment and fitting of self-closing control cocks thereon;
.22 protection of the bottom platting from damaging by a sounding rod;
.23 reliability of sealing of the upper ends of sounding pipes and presence of marking (identification plates) thereon;
.24 measures to protect the sounding pipes projecting above the open decks against damaging during the operation of the ship;
.25 reliability of protection against spark formation when taking soundings in fuel oil and lubricating oil tanks;
.26 measures to prevent the formation of air cushions in the upper parts of the sounding pipes.

8.3.2.7 When surveying the installation of the hydraulic drives of machinery and equipment, the following matters shall be examined in addition to those outlined in 8.3.1:
.1 arrangements for draining off the working fluid upon operation of the safely valves;
.2 arrangements for air expulsion from machinery and piping;
.3 arrangements for replenishment of the working fluid leakage and for drainage of the working fluid from the system;
.4 proper installation of filters upstream of the hydraulic pumps and possibility of maintaining filters in operation;
.5 measures to prevent the working fluids both from getting on hot surfaces and electrical equipment and from self-ignition when the pressure rises.

8.3.2.8 When surveying the installation of the liquid cargo systems of oil tankers, the following matters shall be examined in addition to those outlined in 8.3.1:
.1 elevation of the filling pipe terminations above the bottom;
.2 absence of the by-pass valves and other connecting fittings between the cargo tanks and cofferdams dividing them;
.3 absence of the cargo pipe passages through tanks not intended for the storage of cargo, and connections with other tanks and pipes, as well as presence of two shut-off devices on the pipe sections connecting different types of cargo;
.4 fulfillment of the requirements of the Rules for the Classification and Construction concerning pipe laying and the cargo and slop tanks;
.5 gastightness of the sealing glands of the spindles used to operate the valves placed inside the tanks;
.6 reliability of the venting system and electric connections according to Section 10;
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.7 absence of detachable connections of pipes in way of the superstructures;
.8 reliability of the measures to preclude spark formation, including the cases of hose connections from shore installations, installation of earthing system and operation of the rubbing parts of valve drives;
.9 presence of the spectacle flanges, spool pieces and blank flanges on pipes in way of the superstructure and on the discharging ends of the pipeline;
.10 fulfilment of the requirements of the RS rules concerning arrangement of driving machinery of cargo pumps, devices used for emergency shut-down of cargo pumps and instruments on delivery piping;
.11 reliability of measured to prevent oil from getting on heated surfaces;
.12 possibility of discharging oil residues from cargo and stripping pipelines.

8.3.2.9 When surveying the installation of the compressed air system for tyfon, clearing of side and bottom fittings, air controlled automatic devices and fittings, the following matters shall be checked in addition to those outlined in 8.3.1:
.1 presence of arrangements to protect the tyfon against penetration of condensate therein;
.2 use of non-return shut-off valves for clearing the sea inlet boxes;
.3 protection of the air controlled automatic components against leaks in the hydraulic pipes where arranged jointly in units;
.4 presence of the duplex reducing valves in the feed lines of air controlled automatic systems.

8.3.2.10 Inert gas system (IGS).
8.3.2.10.1 On prototype and series-built ships, IGS shall be tested in operation thereof to full capacity by delivering gas into the protected spaces.

On series-built ships, IGS may be checked in two steps: by delivering air into the protected space and by venting gas through the deck main to the atmosphere.

8.3.2.10.2 On prototype and series-built ships, it is necessary to check:
- stability in delivery of gas with oxygen content and temperature in accordance with 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction and pressure within limits prescribed by design; moreover, operation of the system in ventilation mode shall be checked;
- stability in maintaining design water pressure in cooling systems and water level in water seals;
- operation of the water seal heating system;
- operation of the device maintaining safe pressure in the cargo tanks;
- operation of the automatic monitoring and regulating devices and the equipment supporting operation of the system (pumps, blowers).

8.3.2.10.3 On prototype and series-built ships, by changing the mode, working parameters which fall outside the set limits shall be simulated. In doing so, it is necessary to check:
.1 visual and audible alarms in the following cases:
- low water pressure or low water flow rate to the scrubber;
- increase of gas temperature in excess of 65 °C for cargo tanks and 50 °C for dry cargo holds;
- oxygen content in the inert gas more than 14 % by volume in cargo holds;
- oxygen content in the inert gas main more than 8 % by volume;
- failure of the power supply to the automatic control system for the gas regulating valve and to the indicating devices referred to in 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction;
- low water level in the deck water seal;
- gas pressure drop down to 1 kPa;
- when gas pressure reaches 10 kPa;
- high water level in the scrubber (when using flue gas of boilers);
- blower failure (when using flue gas of boilers);
- insufficient fuel feed to the generator;
- failure of power supply to automatic generator control system;
.2 automatic shutdown of the inert gas blowers (when using flue gas of the boilers) in the following cases:
  low water pressure or low water flow rate to the scrubber;
  increase of gas temperature in excess of 65 °C for cargo tanks and 50 °C for dry cargo holds;
  high water level in the scrubber;
.3 automatic shutdown of the gas regulating valve in the following cases:
  low water pressure or low water flow rate to the scrubber;
  increase of gas temperature in excess of 65 °C for cargo tanks and 50 °C for dry cargo holds;
  high water level in the scrubber (when using flue gas of the boilers);
  failure of power supply to the generator;
  failure of inert gas blowers (when using flue gas of the boilers);
.4 cut-off of fuel supply to the generator in the following cases:
  low water pressure or low water flow rate to the scrubber;
  increase of gas temperature in excess of 65 °C for cargo tanks and 50 °C for dry cargo holds;
  failure of power supply to the generator;
.5 shut-down of the cargo pumps when the pressure in the main drops to 0.5 kPa or, instead of shutting down the pumps, operation of the alarms may be checked (refer to 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction).

8.3.2.10.4 On ships equipped with the system with inert gas supplied from cylinders (refer to 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction), it is necessary to check the presence of brands and documents on the cylinders as well as the value of pressure therein.

Verification of the cylinders shall be carried out in accordance with 9.7.4, and verification of the whole system, in accordance with 8.3.1 and 8.4.1 of the Guidelines.

8.3.2.10.5 On ships equipped with nitrogen generator system, it is necessary to check:
  audible and visual alarms indicating parameters given in 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction;
  automatic stop of the compressor (refer to 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction);
  automatic locking of arrangements, which maintain permanent pressure of the inert gas in the system (refer to 9.16, Part VIII "Systems and Piping" of the Rules for the Classification and Construction);
  operation of the system as required in 4.4.10.1 and 4.4.10.2 of the Guidelines.

8.3.3 Special requirements for surveying installation of machinery installation systems.

8.3.3.1 When surveying the installation of the fuel oil system, the following matters shall be checked in addition to those outlined in 8.3.1:
.1 piping laying and availability of drip trays in necessary places to prevent spillage of fuel on the engines, turbines, gas exhaust piping, boilers, electrical equipment, etc.;
.2 presence of means for emergency shut-down of pumps;
.3 availability of actuators for quick-closing valves and their operation;
.4 availability of drainage arrangements and arrangements for collection leakage fuel;
.5 availability of alarm devices to give warning if the fuel oil reaches the upper predetermined level in the drain and service tanks;
.6 reliability of installation of the non-metal flexible joints and availability of documents on fire-resistance thereof;
.7 tightness of the system when tested by test hydraulic pressure of $1,5P_{work}$ but not less than 0.4 MPa;
.8 presence of thermal compensators on heavy oil pipelines to compensate thermal expansion;
.9 operation of the fuel oil filter interlock so that the filters cannot be opened when under pressure and that fuel oil cannot be supplied therein, when opened;
.10 presence of safely devices to preclude over-pressure in fuel oil heaters and pumps;
.11 operation of arrangements to preclude mixing of different fuel grades.

8.3.3.2 When surveying the installation of the lubricating oil system, the following matters shall be checked in addition to those outlined in 8.3.1:

.1 termination of the lubricating oil drain pipes in the oil drain tank;
.2 reliability of arrangements to prevent mixing of fuel oil and lubricating oil, as well as of lubricating oils of different specifications where common separators are provided;
.3 arrangement of pumps to ensure their suction operation;
.4 measures to prevent the engine room from being flooded through the oil drain tanks in the event when the shell plating is damaged;
.5 arrangements to drain off the lubricating oil upon operation of the safely valve;
.6 arrangement of filters, heaters and other equipment, as well as ease of access thereto;
.7 piping and tanks to make sure that they are free of scale, sand, filings and other foreign objects and matter.

8.3.3.3 When surveying the installation of the cooling water system, the following matters shall be checked in addition to those outlined in 8.3.1:

.1 arrangement of expansion tanks and steam-outlet pipes to exclude formation of trapped zones and ensure cooling of the highest cooled surfaces;
.2 interconnection of sea inlets and location of the isolating valves relative to suction;
.3 access to filters and means enabling the filters to be cleaned without having to stop the cooling pumps;
.4 arrangements to monitor the tightness of fitting of the sea inlets and gate valves to be closed;
.5 measures to protect the system components against electrochemical corrosion.

8.3.3.4 When surveying the installation of the compressed air system, the following matters shall be checked in addition to those outlined in 8.3.1:

.1 presence of non-return shut-off valves in places specified by the design;
.2 presence of pipe slope and arrangements for draining the accumulations of oil and water and to prevent them from penetration into the main starting valve of the engine;
.3 absence of blind off-takes and blanked nipple unions in the piping, which contribute to the accumulation and self-ignition of oil sediments;
.4 absence of connections between the starting and filling pipes.

8.3.3.5 When surveying the installation of the gas-exhaust system, the following matters shall be checked in addition to those outlined in 8.3.1:

.1 arrangements precluding the possibility of sea water entering the engine;
.2 laying of gas-exhaust pipes and arrangement thereof relative to the oil fuel tanks;
.3 availability and arrangement of manholes, hatches and vertical ladders for cleaning of the uptakes, gas-exhaust pipes, silencers and spark arresters;
.4 availability of cocks to drain tar;
.5 arrangements to prevent the entry of water from the waste heat boilers into the engine and availability of hydraulic seals in these arrangements to preclude the entry of gases into the machinery spaces.

8.3.3.6 When surveying the installation of the steam and blow-off systems, the following matters shall be checked in addition to those outlined in 8.3.1:

.1 presence of slopes along the whole length of the pipes, sufficient to provide run-off of the condensate in the direction of steam movement;
.2 protection of the shell plating of the ship against the action of water during blowing-off;
.3 installation of the steam line well away from the pipelines and equipment of the oil fuel and lubricating oil systems as well as from the electrical equipment, entrances, control stations and other permanently manned places;
.4 availability of arrangements to drain condensate, arrangement of the steam lines in spaces, termination of the open ends of the pipes for steam line blow-off;
.5 measures to reduce the stresses due to thermal expansion, producing of prestressing of the steam lines, possibility of displacement of supports, etc.;
.6 agreement between the clear area through the steam discharge connections and the cross-sectional area of the safely valves;
.7 reliability the installation of the steam discharging pipes for steam line blow-off and absence of detrimental effect of the discharged steam on equipment.

8.3.3.7 When surveying the installation of the condensate and feed water system, the following matters shall be checked in addition to those outlined in 8.3.1:
.1 mutual arrangement of the condensate collector, discharge pipe and condensate pump to preclude flooding of the lower row of pipes, and to ensure the required positive pressure and smooth delivery of the condensate to the pump;
.2 availability of the protective screen on the steam lines of ejectors;
.3 possibility of free thermal displacement of the piping and equipment.

8.3.4 Requirements for the survey of installation of fittings.
8.3.4.1 Survey of the installation of fittings of all types and purposes, except the bottom and side fittings, shall be performed together with the verification of the installation of systems, to which the said fittings belong.
8.3.4.2 Survey of the bottom and side fittings may be performed immediately before launching of the ship; irrespective of the degree of readiness of the systems and piping connected with these fittings.
8.3.4.3 When surveying the installation of the bottom and side fittings, it is necessary to check:
.1 compliance of the fittings with the requirements of technical documentation (refer to 8.3.1.2);
.2 compliance of the arrangement of the fittings relative to hull structures and methods of securing to the shell plating with the requirements of technical documentation;
.3 material of gaskets and seals of the fittings. Materials, which would readily deteriorate in the event of fire, shall not be used;
.4 presence of arrangements for clearing, recirculation, heating, as well as gratings;
.5 operation of the local and remote controls, installation of valve position indicators, ease of access to the driving means;
.6 proper installation of the non-return valves of scuppers and overboard discharge pipes;
.7 availability of means for preventing the discharged water from passing inboard, into lifeboats and liferafts;
.8 installation and attachment of protectors and insulation of the contacts between different metals.

8.3.4.4 The securing parts of the bottom and side fittings shall be strong enough, gaskets shall have no tears, cracks and notches and not protrude beyond the sealed surfaces, the material shall comply with the drawings approved by the Register.

8.3.4.5 The bottom and side fittings installed on sea inlet and ice boxes or distance pieces shall be tested together with them for tightness of closing and tightness of connection in accordance with Appendix 1 to Part II "Hull" of the Rules for the Classification and Construction.

The overboard discharge fittings shall be tested for tightness by the clearing medium pressure which shall not exceed 0.5 MPa.
8.4 SURVEY OF SYSTEMS AND PIPING DURING MOORING AND SEA TRIALS

8.4.1 General requirements for the survey of systems in operation.
8.4.1.1 Survey of the systems in operation shall be performed upon finalization of the installation thereof and upon completion of construction work on board the ship.
8.4.1.2 Prior to the beginning of testing the systems in operation, the program and procedure for testing the systems shall be submitted.
Special requirements for survey of the systems in operation, taking into consideration the peculiar features of their design and purpose, are set out in 8.4.2 and 8.4.3.
8.4.1.3 The final survey of the ship's service systems shall be generally performed during the mooring trials. In this case, in the process of mooring trials of the ship, supervision of the normal functioning of these systems in operation for their designated purpose shall be carried out.
8.4.1.4 In specific cases, considering particular conditions of ship construction (water area pollution, shallow waters, impossibility of creating full loading conditions, etc.), final full or partial verification of the systems: bilge, ballast, ballast water heating, ventilation, air, venting, cargo vapour discharge, overflow pipes, compressed air for air controlled automatic devices and fittings may be performed, on agreement with the Register, during the sea trials of the ship.
8.4.1.5 Survey of the systems of machinery installation during mooring trials shall be performed with the aim to check the readiness of these systems for the sea trials of the ship's machinery installation. Final survey of the systems of machinery installations shall be performed in the course of the sea trials. Checks and tests performed previously during the mooring trials and not associated with operation of the systems for their designated purpose shall not be carried out over again on the sea trials.
8.4.1.6 Mooring trials of the systems of machinery installations, as well as the following ship's service systems: bilge, ballast, fuel tank heating, cargo on oil tankers and ballast water, ventilation, clearing of bottom and side fittings, air-controlled automatic devices and fittings shall be conducted under the conditions stipulated by the trial program. Subject to special agreement with the Register, the driving means of machinery serving the systems may be supplied from shore power sources (steam, air, electricity).
8.4.1.7 Survey of ship's service systems not specified in 8.4.1.6 during the mooring trials, as well as verification of the systems of machinery installations during the sea trials shall be performed in operation, unless this Section and trial program stipulate any particular, especially created conditions for their checking.
8.4.1.8 Prior to testing a system in operation, it is necessary to make sure that the system components have not received damages caused by installation work, that the devices, fittings, machinery and equipment stipulated by the technical documentation are available.
8.4.1.9 The firm (manufacturer) inspection body shall be responsible for the organization of trials, keeping of documentation, making of measurements, suitability of devices, fidelity of entries, etc.
8.4.1.10 As a result of the survey of the system in operation, the RS surveyor shall make sure that:
.1 all operations stipulated by the technical documentation can be performed;
.2 fittings and their controls operate reliably;
.3 there are no working medium leakage and air inleakage;
.4 standard instruments are suitable and give correct readings;
.5 there are no impermissible vibrations, heating, noise;
.6 insulation of piping and system equipment is adequate;
.7 operational settings of signalling, regulating and preventing facilities and fittings are correct;
.8 unattended operation and remote control of system equipped by automation devices is possible provided a distinguishing automation mark has been added to class notation of the ship;
.9 system components are conveniently and safely maintained in operation and stipulated repair work can be performed;
.10 main and stand-by machinery, vessels and other equipment which are verified in compliance with the requirements of the relevant sections are reliable.

8.4.2 Special requirements for the survey of ship's service systems in operation.

8.4.2.1 When surveying the bilge system during mooring trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 possibility of draining any compartment by each available bilge pump or by their substitutes, as well as possibility of emergency drainage of machinery space except when this is not provided for by the technical documentation;
.2 operation of the arrangements preventing sea water from passing inboard, as well as from one watertight compartment into another;
.3 operation of the self-priming pumps or vacuum arrangements;
.4 possibility of simultaneous drainage of the machinery spaces through direct suctions and of other compartments by other pumps;
.5 actual capacity of bilge pumping arrangements and effectiveness of draining places where water is likely to accumulate (on prototype ships only);
.6 drainage of machinery spaces with the use of equipment preventing pollution from ships.

8.4.2.2 When surveying the ballast system during the mooring trials, the following matters shall be examined in addition to those outlined in 8.4.1:
.1 loading and pumping-out of ballast from each ballast tank by the means intended for this purpose (by pumps, ejectors, gravity, from peaks);
.2 operation of self-priming pumps when pumping out ballast from double bottom tanks;
.3 operation of interlocks and local controls of fittings in the event of failure of the remote control system;
.4 actual capacity of ballast pumps when pumping-out ballast from the remotest tanks and actual highest pressure in ballast compartments when water overflows through the air pipes (on prototype ships only).

8.4.2.3 When surveying the sewage system during the mooring trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 operation of non-return and non-return shut-off protective devices;
.2 effectiveness of functioning of waste pipes including that in enclosed spaces when water is supplied to simulate fire suppression by shipboard facilities;
.3 operation hydraulic seals or their equivalent;
.4 operation of facilities to prevent pollution from ships.

8.4.2.4 When surveying the heating system of fuel oil, lubricating oil, ballast water tanks and cargo tanks of oil tankers during the mooring trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 maximum temperature of fuel oil and lubricating oil heating which shall be by 15 °C lower than the flash point;
.2 purity of steam condensate from the heaters of fuel oil and lubricating oil tanks;
.3 operation of devices reducing steam pressure;
.4 effectiveness of heating of the ballast tanks and ballast system fittings.

8.4.2.5 When surveying the ventilation system during the mooring trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 gas-tightness of ventilation ducts and operation of distributing devices;
.2 operation of self-closing fire dampers and gate valves;
.3 reliability of means of closure of the ventilation ducts and existence of measures to preclude admission of water into the ducts;
.4 in prototype ships, it will be necessary to measure the actual capacity of ventilation of mechanical type used to monitor the rate of air changes required by the Rules for the Classification and Construction, and to check the effectiveness of ventilation in the following
spaces: machinery spaces; enclosed holds intended for the carriage of motor vehicles and ro-ro machinery; refrigeration machinery rooms; refrigerated cargo spaces, battery rooms; foam fire extinguishing stations and smothering stations; control stations; helicopter hangars; holds for the carriage of dangerous cargoes, as well as battery boxes.

8.4.2.6 When surveying the system of air, venting, overflow and sounding pipes during the mooring trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 operation of air pipes when tanks are filled and drained through the relevant pipelines;
.2 operation of arrangements preventing sea water from admission through the pipes the outlets of which are situated on open deck;
.3 absence of hydraulic seals in air pipes at the permissible angles of heel and trim of the ship;
.4 operation of flame-arresting fittings of the vent pipes when tanks are filled and drained and reliability of measures to preclude penetration of cargo oil therein;
.5 direction of the flow of the discharged gas-air mixtures;
.6 pressure in compartments at which the pressure/ vacuum valves open and close;
.7 effectiveness of operation of the overflow pipes precluding egress of fuel oil through air pipe in the event of overflow;
.8 reliability of measures to preclude the possibility of liquid flowing from one tank into another and liquid vapours entering adjacent tanks through the overflow pipes;
.9 ease of using sight glasses and operation of alarm devices giving warning of overflow;
.10 operation of the overflow tank filling alarms;
.11 operation of self-closing and control cocks of sounding pipes;
.12 operation of alarms of the cargo vapour discharge system, which produce alarm signal at high and low pressure in cargo tanks.

8.4.2.7 When surveying the hydraulic drives of machinery and equipment during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 drain of working fluid upon operation of safety valves;
.2 operation of arrangements for air expulsion from system;
.3 possibility of filling the system with working fluid and replenishing leakage and complete draining the system;
.4 operation of filters, regulating fittings and hydraulic accumulators.

8.4.2.8 When surveying the system of voice pipes during sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 ease of using the system, reliability of operation of call signals (whistles, bells);
.2 audibility and clearness of the given orders;
.3 absence of extraneous background noise in pipes passing through the spaces with high noise level.

8.4.2.9 When surveying the compressed air system for tyfon, clearing of bottom and side fittings, air-controlled automatic devices and fittings during mooring trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 operation of fittings to control the tyfon, which shall give distinct and abrupt audible signals producing the appropriate sound intensity, tone and clear sounding;
.2 operation arrangements reducing pressure of air for clearing bottom and side fittings;
.3 degree of air purification and drying in the air-controlled automatic systems, possibility of changing over the air purifying and drying arrangements, as well as of replacing filtering elements without interruption of air supply to the system.
8.4.3 Special requirements for the survey of the system of machinery installation in operation.

8.4.3.1 When surveying the oil fuel system during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:

.1 effectiveness of arrangements for collection of leakage fuel, filtering and purification of fuel oil;
.2 operation of arrangements for remote stopping of pumps (refer to Section 10);
.3 operation of controls of quick-closing valves;
.4 possibility of cleaning filters without interrupting the supply of fuel to consumers;
.5 operation of arrangements for regulation and automatic maintenance of the fuel oil temperature and level within the prescribed limits.

8.4.3.2 When surveying the lubricating oil system during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:

.1 uniform and sufficient supply of lubricating oil to consumers;
.2 effectiveness of arrangements for heating, filtering and purification of lubricating oil;
.3 alarms to warn of limiting pressure and level of the lubricating oil, automatic start-up of standby pumps;
.4 operation of sight devices and throttles, as well as protective devices.

8.4.3.3 When surveying the cooling water system during mooring and sea trials, the following matters shall be examined in addition to those outlined in 8.4.1:

.1 uniform and sufficient water supply by main and standby means;
.2 reliability of water supply regulation to ensure the most favourable operating conditions for consumers;
.3 operation of the system to maintain machinery in the hot stand-by mode;
.4 effectiveness of operation of the sea inlets, their heating, recirculation and clearing;
.5 means provided to enable the filters to be cleaned without having to interrupt operation of the system;
.6 operation of expansion tanks, filling with water of the highest cooled spaces, absence of trapped zones;
.7 transfer to the emergency sea water cooling mode (on prototype ships only);
.8 operation of arrangements for control and automatic maintenance of the cooling water temperature within the prescribed limits.

8.4.3.4 When surveying the compressed air system during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:

.1 capacity of the main, standby and replenishing compressors with determination of time required to fill air receivers;
.2 sufficiency of the amount of starting air to provide the specified number of starts and reversals of the main and auxiliary engines, operation of tyfon and for other purposes;
.3 operation of arrangements enabling starting of main compressors according to 16.2.3, Part VIII "Systems and Piping" of the Rules for the Classification and Construction (on prototype ships only);
.4 temperature of air entering the receiver and operation of appropriate coolers;
.5 operation of arrangements for draining the accumulations of oil and water, as well as arrangements for relieving internal pressure of the pipes;
.6 operation of alarms to warn of the pressure drop and arrangements for automatic control of the compressors.

8.4.3.5 When surveying the exhaust-gas system during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:

.1 gas-tightness of connections and thermal compensators under vibration and high temperature conditions;
.2 reliable operation of safely devices of the common exhaust lines and by-pass dampers in the composite waste heat/oil fired boilers;
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.3 effectiveness of insulation and reliability of its protection against breaking-down;
.4 operation of arrangements to prevent the entry of water from the waste heat boilers and wet-type spark arresters into the engines;
.5 operation of arrangements for extinguishing fire in spark arresters, silencers and waste heat boilers.

8.4.3.6 When surveying the steam and blow-off system during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 operation of arrangements for compensating thermal expansion of the pipelines;
.2 operation of arrangements for draining condensate from the housings of fittings and from pipelines;
.3 absence vibration;
.4 operation of steam-driven machinery, pressure vessels and other equipment (refer to the relevant sections);
.5 sufficiency of cross-sectional area of safety devices.

8.4.3.7 When surveying the condensate-feed water system during mooring and sea trials, the following matters shall be checked in addition to those outlined in 8.4.1:
.1 operation of arrangements for separating oil and petroleum products;
.2 operation of heat exchangers, metering devices, water samplers;
.3 transfer of feed water in all variants stipulated by the technical documentation;
.4 operation of regulating, protective and safety devices;
.5 reliability of feeding means when operating separately and in parallel.

8.4.4 Where the constructed/converted ship is intended for the carriage of liquefied gases and/or uses gas as fuel, the systems and piping related to gas transfer, shall be checked during gas trials according to 18.7.
8.5 SURVEY OF MODU/FPU/FOP SYSTEMS AND PIPING

8.5.1 General.
8.5.1.1 This Chapter applies to the MODU/FPU/FOP specific systems and piping given in Table 8.1.4.3 of the Guidelines, Part VIII "Systems and Piping" of the MODU/FOP Rules and Part VIII "Systems and Piping" of the FPU Rules.
8.5.1.2 The Chapter contains additional requirements for technical supervision during installation as well as mooring and sea trials of systems of the MODU/FPU/FOP under construction.
8.5.1.3 When performing technical supervision during manufacture of piping components and systems, the requirements in Section 8, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and Section 8 of the Guidelines shall be met.

8.5.2 Technical supervision.
8.5.2.1 The scope and procedure of technical supervision during installation, mooring and sea trials of the MODU/FPU/FOP specific systems and piping are given in Table 8.1.4.3.
8.5.2.2 Technical supervision during MODU/FPU/FOP installation.
8.5.2.2.1 Hydraulic drive system for jacking system of self-elevating MODU/FPU.
When performing technical supervision during installation of hydraulic drive system for jacking system of self-elevating MODU/FPU, in addition to mentioned in 8.3.2.7, the following requirements shall be met:

1. piping shall be laid with the extensions, bends and crossing kept to the minimum. The process (for tightening joints) and thermal compensations shall be provided;
2. layout and number of fasteners shall prevent displacement and vibration of pipes and fittings;
3. flexible cables shall not be twisted for all positions of moving parts;
4. means for collecting oil leakage and its return into hydraulic system shall be provided;
5. discharge piping of control system shall be not under hydrostatic pressure;
6. piping laid on decks and platforms shall be protected against mechanical damages;
7. hydraulic drive daily service tanks shall be fitted with high and low level alarms.
8.5.2.2.2 Sea water supply system of self-elevating MODU/FPU.
When performing technical supervision during installation of sea water supply system of self-elevating MODU/FPU, in addition to 8.3.1.1, the following shall be checked:

1. proper protection of piping against possible damages during process operations;
2. proper protection of suction piping for each submersible pump against mechanical damages;
3. means of heating and/or insulation (including sea water storage tanks) are provided, if prescribed by technical documentation;
4. supply system and sea water storage tanks are equipped with instrumentation and alarms, fittings and arrangements according to approved technical documentation.
8.5.2.2.3 Ventilation system of hazardous and enclosed spaces under overpressure.
When performing technical supervision during installation of ventilation system of hazardous and enclosed spaces under overpressure, in addition to 8.3.2.5, the following requirements shall be met:

1. inlets of the suction type ventilation of specified spaces shall be arranged outside the hazardous areas;
2. ventilation systems of specified spaces shall be completely isolated from those in other spaces;
3. ventilation systems shall be fitted with arrangements for fan operation and duct pressure control;
4. exhaust ventilation ducts of hazardous spaces as well as the ducts passing through these spaces shall be of gastight type.
8.5.2.2.4 Riser tensioning system and heave compensating device.
When performing technical supervision during installation of riser tensioning systems and
heave compensating devices, the requirements in 8.3.2 and 8.3.4 of the Guidelines shall be
met so far as applicable based on the scope of technical supervision mentioned in 1.3.2.3,
Part VII "Machinery Installations and Machinery" of the MODU/FOP Rules.
8.5.2.2.5 Fuel oil system.
When performing technical supervision during installation of fuel oil system, in addition
to 8.3.3.1, the following shall be checked:
.1 means for collecting oil leakage from internal combustion engines, process
equipment and helicopter fuel tanks are provided;
.2 pipelines are properly routed and filing pipes are properly laid relative to hazardous
spaces and areas;
.3 fuel pipelines located in working sites or in areas where they may be damaged are
protected against mechanical damages and free of detachable joints;
.4 fuelling arrangements comply with requirements of the MODU/FOP Rules.
8.5.2.2.6 Lubricating oil system.
When performing technical supervision during installation of lubricating oil system,
in addition to 8.3.3.2, the following shall be checked:
.1 means for collecting oil leakage from process equipment in areas of possible
leakage, waste pipe discharge into special-purpose containers are provided;
.2 self-contained lubricating oil systems are provided in way of internal combustion
engines and standby system with standby pumps.
8.5.2.2.7 Cooling water system.
When performing technical supervision during installation of cooling water system,
in addition to 8.3.3.3, the following shall be checked:
.1 absence of connections between cooling pipelines of the MODU/FPU/FOP safely
arrangements and those serving the process equipment;
.2 standby cooling system is provided in internal combustion engines.
8.5.2.2.8 Compressed air system.
When performing technical supervision during installation of compressed air system, in
addition to 8.3.2.9 and 8.3.3.4, the following shall be checked:
.1 absence of connections between starting air piping and compressed air piping for
process needs; where compressed air is used for process needs in the starting air system, the
non-return valve shall be provided;
.2 pipelines on weather decks and working areas are properly protected against
mechanical damages.
8.5.2.2.9 Exhaust gas system.
When performing technical supervision during installation of exhaust gas system,
in addition to 8.3.3.5, the following shall be checked:
.1 spark arresters of the Register-approved type, including exhaust gas pipelines of
internal combustion engines, funnels of boilers and any galleys shall be provided;
.2 exhaust gas pipe outputs shall be located outside hazardous areas.
8.5.2.2.10 Blowing and flooding system for leg tanks.
During survey of blowing and flooding system for leg tanks, the applicable requirements in 8.3.2.
8.5.2.2.11 Shielding gas supply and ventilation system for electrical equipment with
enclosure under overpressure.
When performing technical supervision during installation of shielding gas supply and
ventilation system for electrical equipment with enclosure under overpressure, in addition
to 8.3.1, the following shall be checked:
.1 compliance of materials used with the technical documentation;
.2 location of exhaust gas pipe outputs outside hazardous areas;
.3 installation and location of ventilation units with regard to hazardous areas.
8.5.2.3 Survey of systems during mooring and, if applicable, sea trials.

8.5.2.3.1 Hydraulic drive systems for the MODU/FPU jacking system shall be subject to mooring and sea trials along with the MODU/FPU jacking system. The scope and procedure of tests are given in 3.4.3.3.

8.5.2.3.2 During survey of hydraulic drive systems for the MODU/FPU jacking system, in addition to 8.3.2.7, the following shall be checked:
- operability of the system with any of high-, medium- and low-pressure pumps being sequentially switched off;
- absence of abnormal vibration of system components and hydraulic impacts in the system;
- absence of twisted flexible connections and provision of their free movement for all positions of moving parts of legs and jack house;
- system tightness under working conditions;
- compliance of instrument readings with values given in technical documentation.

8.5.2.3.3 During survey of sea water supply system of self-elevating MODU/FPU during mooring and sea trials, in addition to 8.4, the following shall be checked:
- independent sea water pipeline with fittings and control actuators are capable of being operated from each submersible pump for at least 2 h;
- all sea water consumers operating concurrently are capable of being operated from one submersible pump;
- filter fitted on the suction pipeline of the tank is capable of being cleaned without interruption of submersible pump;
- system is capable of being operated automatically according to Section 8;
- readings of local and remote control instruments;
- head and capacity of each submersible pumps when the MODU/FPU is lifted at the maximum permissible height at sea level and at the minimum permissible depth of submersible pump (for the prototype MODU/FPU).

8.5.2.3.4 During survey of ventilation systems of hazardous spaces during mooring trials, in addition to 8.4.2.5, the following shall be checked:
- capacity of ventilation system is adjustable in the range of 10 to 20 air changes for hazardous spaces in area 1;
- operation of local and remote control instruments;
- air pressure in suction ventilation ducts penetrating through hazardous spaces shall exceed the pressure in these spaces;
- fans are capable of being automatically switched into the other capacity with regard to gas concentration within the spaces;
- air direction with the door opened from the less hazardous space to the more hazardous spaces.

8.5.2.3.5 During survey of ventilation systems of enclosed spaces under overpressure during mooring trials, in addition to 8.4, the following shall be checked:
- air pressure in air locks between spaces and areas of different zones, and pressure within hazardous spaces adjacent to these air chambers; automatic operation of fans according to Section 7;
- air pressure in ducts penetrating through hazardous spaces and/or areas shall exceed the pressure in these spaces.

8.5.2.3.6 During survey of cooling water system of the self-elevating MODU/FPU power plant during mooring and sea trials, in addition to 8.4.3.3, operation of closed-loop standby cooling system shall be checked. For the prototype MODU/FPU, the power plant shall be capable of being operated by this closed-loop standby cooling system without refilling of sea water tank for a period required for starting of the standby submersible sea water pump.
8.5.2.3.7 During survey of shielding gas supply and ventilation system for electrical equipment with enclosure under overpressure during mooring trials, in addition to 8.4.1, the following shall be checked:

- overpressure of shielding gas within gas pipelines, at input of electrical equipment enclosure and at instruments connection point;
- operation of protection, control and interlocking arrangements and their response times;
- fan operation according to 7.5.2.6.

8.5.2.3.8 Survey of the MODU/FPU ballast system for intended purpose during the MODU/FPU sea trials shall be performed by immersion of MODU/FPU being stowed in sea position to the working position and its surfacing from the working position to sea position. The proper operation of the ballast system shall be checked. At least two independently driven pumps shall be capable of reception and discharge of ballast from any ballast tank.
INSTRUCTIONS ON THE INSTALLATION OF FLEXIBLE JOINTS

1. GENERAL INSTRUCTIONS FOR THE INSTALLATION OF FLEXIBLE HOSES ARMOURD WITH METAL

1.1 To avoid sharp bends.

There are many cases when the hose can be subjected to numerous sharp bends as a consequence of a wrong installation. Below are given some examples (refer to Figs. 1.1-1 and 1.1-2). If restrictions caused by the arrangement of piping render the conventional method of installation unacceptable, it is recommended to use a protective sleeve over the crimped portion of the hose. Such protection will reduce stiffness of the bent portion of the hose and extend the service life of its crimped portion and the hose itself.

Fig. 1.1-1
1.2 To avoid kinking.

The hose is liable to kinking, i.e. can be subjected to the action of torque (refer to Fig. 1.2) in the following cases:

*During installation.* In order to minimize the possibility for the hose to receive damage because of this, it is recommended to install coupling or movable flange at one end of each hose connection.

*At flexure.* The hose shall always be installed so that the bend occurs in one plane.
Fig. 1.2
2. GENERAL INSTRUCTIONS FOR THE INSTALLATION OF FLEXIBLE HOSES NOT ARMoured WITH METAL

2.1 Under the action of pressure, the hose length can change. Provision shall be always made for some sag of the hose in the event of its contraction or elongation (refer to Fig. 2.1).

![Diagram](Wrong)

![Diagram](Right)

Fig. 2.1

2.2 When the hose lines run in the vicinity of exhaust pipes or other heat sources, they shall be insulated by fire resistant casing, fire hose or metal screen. In any case, brackets and clips hold the hoses and reduce attrition. When the use of these arrangements do not preclude attrition of the hose surfaces, a protective metal or plastic taping or a casing (sleeve) resistant to attrition shall be provided over the hose (refer to Fig. 2.2).

![Diagram](Wrong)

![Diagram](Right)

Fig. 2.2
2.3 Use of elbows and adapters during the installation relieves stresses in the joint, facilitates the installation itself and provides better access for examinations and maintenance. It shall be borne in mind that the metal end fittings are not considered to be a part of the flexible portion of the joint (refer to Fig. 2.3).

![Fig. 2.3](image)

**Wrong**  **Right**

2.4 If there exists considerable vibration or bend, a hose of increased length shall be used. The end metal fittings are not flexible components and, therefore, installation effected correctly protects them against extraordinarily high stresses and can be helpful in avoiding overbending of the hose (refer to Fig. 2.4).

![Fig. 2.4](image)

**Wrong**  **Right**
2.5 If the hose was kinked in the process of installation, high working pressure tends to return it to non-kinked state. This can loosen the nut. Kinking can result in the damage of armouring and the hose can burst at the most stressed portion (refer to Fig. 2.5).

![Fig. 2.5](image)

2.6 At bends it is necessary to ensure a sufficient length of the hose in order to increase the radius of bend. A hairpin bend constricts the hose and restricts the flow of liquid. The hose can even bend over and completely shut-off the flow of liquid. In many cases, use of suitable fittings or adapters can eliminate bends or overbends (refer to Fig. 2.6).

![Fig. 2.6](image)
2.7 When installing the hose, it is necessary to avoid its wear due to friction and attrition against structures. Clips are often required to support long hoses or to keep them clear of the moving parts. It is important that the clips are of suitable size. If the clip is too large, the hose will move therein with consequent attrition at the place involved (refer to Fig. 2.7).

![Fig. 2.7](image-url)
9 BOILERS, HEAT EXCHANGERS AND PRESSURE VESSELS

9.1 GENERAL

9.1.1 The provisions of this Section apply in technical supervision during installation and testing of boilers, heat exchangers and pressure vessels on board ship.


9.1.2 Prior to the installation of boilers, heat exchangers and pressure vessels it is necessary to make sure that all seating assembly and welding operations have been completed and the items themselves have the document confirming that they have been manufactured under the Register technical supervision.

9.1.3 Boilers, heat exchangers and pressure vessels shall be installed on and secured to the seatings in accordance with the technical documentation approved by the Register.

9.1.4 Dimensional discrepancies given in this Section may be accepted, unless otherwise specified in the approved technical documentation.
9.2 SURVEY PLANNING

9.2.1 Prior to commencement of survey of the boilers, heat exchangers and pressure vessels of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 9.2.1. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1 and with due regard to 9.3.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

Table 9.2.1

<table>
<thead>
<tr>
<th>Item of technical supervision</th>
<th>Check of installation on seating and securing</th>
<th>Internal examination</th>
<th>Hydraulic test</th>
<th>Steam test</th>
<th>Check in operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Steam boilers</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>Heat exchangers</td>
<td>+</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>+</td>
</tr>
<tr>
<td>Pressure vessels</td>
<td>+</td>
<td>+</td>
<td>–</td>
<td>–</td>
<td>+</td>
</tr>
</tbody>
</table>

9.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

9.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change subcontractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

9.2.4 Quality standards for installation and testing of the ship boilers, heat exchangers and pressure vessels shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

9.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
9.3 INSTALLATION

9.3.1 Installation of steam boilers.

9.3.1.1 Boilers shall be installed on seating in accordance with the installation drawing defining the position of the boiler in relation to the centre and base planes, transverse bulkhead or moulded frame.

9.3.1.2 The boiler frame shall be secured to the seating in accordance with the drawing.

9.3.1.3 Mounting and thermal gaps of movable supports with the keeper plates fastened shall comply with the drawing; the value of gap between the base of the main boiler supports and bed plates shall be checked by feeler gauge.

9.3.1.4 Pads fitted between the transition frame and bed plate of the seating shall be at least 3 mm thick.

9.3.1.5 Nut and heads of bolts listening the boiler to the frame or transition plate of the seating shall fit to the surface of the fixed support, keeper plates or transition parts of the seating so that a feeler of 0,05 mm thick cannot pass in between over a length equal to 1/3 the circumference of the nut or bolt head. The fastening bolts and studs shall be prevented from making loose.

9.3.1.6 Local gaps between the pads and flanges of the seating as well as the transition frame with the bolts pressed shall not exceed 0,4 mm; along with that, the zone of contact between the mated surfaces of the pad, flanges of the seating and frame shall be provided over an arc equal to at least 2/3 of the support. On the remaining part, gaps shall be spaced apart.

Note. Place where the feeler leaf of 0,05 mm thick passes to a depth not more than 10 mm shall be considered as the contact point.

9.3.1.7 Overlap of the pads in relation to the seating bed plate shall not exceed 5 mm.

9.3.1.8 Installation and securing of the economizer as well as securing the boiler in its upper part by braces shall be performed in accordance with the requirements of the drawing.

9.3.1.9 Supervision during the installation of alarm and automation systems shall be performed in accordance with Sections 10 and 12.

9.3.2 Installation of heat exchangers and pressure vessels.

9.3.2.1 Installation of heat exchangers and pressure vessels shall be checked in accordance with the requirements of the working documentation for installation.

9.3.2.2 Bearing between heat exchanger or pressure vessel shell and the seating and embracing thereof by the upper band shall correspond to at least 2/3 of semi-circumference.

9.3.2.3 Length of the threaded part of fastening bolts and the gap between the band lug and seating shall be sufficient to tighten up the bands. The fastening bolts and studs shall be prevented from working loose.

9.3.2.4 Pads between the seating, band and the heat exchanger or pressure vessel shall be reliably pressed and not have cracks, tears across the internal and external edges.

9.3.2.5 When installing heat exchangers and pressure vessels, the applicable requirements of 9.3.1 shall be also met.
9.4 INTERNAL EXAMINATION

9.4.1 Internal examination of boilers.
9.4.1.1 The internal examination of a boiler shall be carried out by the RS surveyor upon finalization of installation work thereon, as well as installation of the boiler on seating and securing thereof.
9.4.1.2 The boiler components on the steam and water space side shall be re-activated and cleaned.
9.4.1.3 Ends of the generating, waterwall tubes and downcomers on the steam and water space side of headers shall have no damages, and the welds of drums, headers, end plates, flanges, branches for fittings and other essential components shall have no tears, cracks and other defects.
Using calibrated balls, it is necessary to make sure that the generating, waterwall tubes and downcomers are not deformed and blocked up.
9.4.1.4 During examination, it is also necessary to make sure that:
- all hatches and manholes and attachments of the boiler are acceptable for examination, access inside the boiler is provided;
- water level indicators have been installed in relation to the water level in accordance with the requirements of the Rules for the Classification and Construction;
- internal outfitting of the drums and headers suits the drawing and the outfitting items have been reliably secured;
- brickwork of the firing space has not been damaged;
- fittings and gauges installed on the boiler are in compliance with the drawing and the impressions of brands and seals of the metrologic organization on the control gauges are not overdue;
- drums and headers of the boilers, as well as headers of the steam superheaters are protected against direct effect of radiant heat.

9.4.2 Internal examination of heat exchangers and pressure vessels.
9.4.2.1 Internal examination of heat exchangers and pressure vessels, except air receivers, shall be carried out by the firm (manufacturer) inspection body. Air receivers shall be verified by the RS surveyor.
The internal examination shall be carried out before heat exchangers and pressure vessels are prepared for operational testing on board ship in order to confirm that all their components are in proper condition, re-activated and cleaned, heat exchangers and pressure vessels are fitted with appropriate fittings and devices in accordance with the approved technical documentation.
9.5 HYDRAULIC TESTS

9.5.1 Hydraulic tests of boiler for tightness by permission and in the presence of the RS surveyor.

During the test it is necessary to check the fulfilment of the requirements of Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision as far as they are applicable, as well as the completion of all works associated with the installation of valves and gauges. Tightness of the safety valves shall be ensured by inactivating the regular springs.

9.5.2 Boilers with fittings installed thereon shall be tested on board the ship by a pressure in accordance with Table 1.7.1, Part X "Boilers, Heat Exchangers and Pressure Vessels" of the Rules for the Classification and Construction.

9.5.3 The test pressure during the test of the boiler shall be maintained within 5 — 10 min, then it shall be reduced down to the working pressure and maintained constant until the examination is completed.

9.5.4 A boiler shall be considered to have passed the test if no leakage or sweating is detected in welds, water leaks are not detected in expanded joints, as well as in connecting flanges, connections of valves and gauges.
9.6 STEAM TEST OF BOILER

9.6.1 Steam test of boiler shall be carried out after its installation on board ship, prior to mooring trials of the boiler plant, under working pressure.

9.6.2 During the steam test, the boiler and main steam line shall be maintained under the working pressure within 4 — 8 h.

At that the steam from the boiler is not consumed, all main steam line and boiler valves shall be closed, except the shut-off valve and the valve for blowing down the header.

The water level in the boiler shall be within working range, marked on the water-gauge column.

9.6.3 Steam boiler and fittings shall be insulated in such a manner as to provide a possibility of performing checks mentioned in 9.5.4.

9.6.4 During the steam test of the boiler it is necessary to check its welds, boiler and uptake casing, all fittings and connections for tightness, as well as the value of thermal gaps of movable supports.

The results of the steam test shall be considered as satisfactory if no water and steam leaks from the welds, connections and fittings, as well as smoke and hot gas leaks from the boiler and uptake casing have been detected, as well as if the value of thermal gaps of the movable supports is sufficient.

Note. During the steam test, flange joints and fastenings of the fittings on boiler shall not be pressed in order to eliminate the water leaks.
9.7 MOORING AND SEA TRIALS OF BOILER PLANTS

9.7.1 General.

9.7.1.1 General provisions concerning the procedure of supervision during mooring and sea trials of ships, machinery, arrangements, systems and equipment are set out in Section 18.

This Chapter sets forth additional provisions concerning the procedure, scope and methods of supervision during mooring and sea trials of marine boiler plants.

9.7.1.2 The purpose of mooring and sea trials of the main and auxiliary boiler plant for essential services shall check the boilers and their supporting auxiliary machinery, equipment and systems in operation for the designated purpose, to identify their compliance with the approved technical documentation.

9.7.1.3 The non-essential boiler plants and waste heat plants shall be checked in operation for the designated purpose in order to verify safe operation of the boilers and their supporting auxiliary machinery, equipment and systems.

9.7.1.4 Prior to trials, the following documents shall be submitted to the RS surveyor:

- trial program approved by the Register;
- technical documentation on the boiler (specifications, drawings) approved by the Register, diagrams of steam lines, condensate piping, feed water piping, fuel and air supply piping, diagrams of electrical equipment and automatic systems and other diagrams at the RS surveyor's request;
- document of the shipyard inspection body, confirming that the boiler plant is ready for trials;
- data sheets and certificates on the boilers and other supervised items of the boiler plants;
- description and instruction manual for the boilers and equipment of boiler plants;
- documents on fitness of the gauges for use on trials;
- procedure of the trials;
- trials schedule (to be agreed with the RS surveyor).

9.7.1.5 Mooring and sea trials shall be carried out after completing the installation of all boilers, their auxiliary machinery, automation equipment and electrical equipment, supporting systems, piping and equipment, after hydraulic test of the boilers with steam line, air test of the boiler casing for tightness and steam test of the boilers and main steam line.

9.7.1.6 The trials shall be conducted using the fuel specified in the technical documentation on the boiler and adopted for the boilers of the ship concerned. In case the boiler is intended for operation on fuel of several grades, in the prototype ships, the operation of the boiler plant shall be checked using the most and the least viscous fuels of those adopted for the ship concerned. The prototype boiler shall necessarily be tested using the most and the least viscous fuels of those indicated in the technical documentation on the boiler.

9.7.1.7 Steam load of the boiler can be generated by the regular and other ship's consumers. Check of the operation of all regular consumers on board ship shall be compulsory.

9.7.1.8 Each boiler installed on board ship shall be subjected to trials within the scope specified in 9.7.2 and 9.7.3.

9.7.1.9 The automation systems and equipment of the boiler plants during mooring and sea trials shall be checked in operation in accordance with 12.4 and 12.5.6.

9.7.1.10 It is necessary to check the operation of the electrical equipment and to measure the resistance of insulation of the electric circuits before and after the trials (refer to Section 10).

9.7.1.11 Throughout the period of mooring and sea trials it is necessary to monitor operation of all systems and auxiliary machinery being part of the boiler plant, including:
Guidelines on Technical Supervision of Ships under Construction (Section 9)

.1 operation of each fuel pump and fuel filter, attention being given to operation of the valves, fuel heaters, service tank;
.2 visual monitoring of the combustion quality under all operational conditions of the boiler, the combustion shall be considered satisfactory if the flame-jet does not fluctuate, does not burn at the tuyere edge, unburnt fuel does not get the heating surface and lining;
.3 operation of each feed pump and feed water filter, each feed valve, feed water intake from the hot well and tank, purity (absence of oil) of the condensate in hot well and in monitoring tank. It is necessary to check operation of the deaerator with regular fittings, gauges and alarms and the feed water intake therefrom;
.4 operation of each fan, air dampers, tightness of air heaters and air valves;
.5 tightness of the boiler casing and uptake casing under all operational condition of the boiler. For better determination of the gas-tightness, smoke boxes may be used.

9.7.1.12 Under all operational conditions of boiler plants in prototype ships it is necessary to determine the vibration level of the boiler fronts and uptakes, as well as the level of boiler oscillations in the longitudinal and transversal directions, in way of the steam and water header. The vibrations shall not exceed the standards of the Register or permissible values specified in the RS-approved technical documentation.

9.7.1.13 If during the trials the deviations of the monitored parameters have exceeded the values per-mitted by the approved technical documentation, it is necessary to re-adjust and re-test the boiler basing on the same parameters and under the same loading.

9.7.1.14 Where during the trials defects or faults are detected, which can cause an emergency situation or affect the safely of the ship or people, the trials shall be interrupted until such defects and faults are corrected. The scope of the repeat trials of the equipment after the defects and faults have been corrected shall be determined by the RS surveyor particularly in each case.

9.7.1.15 Upon finalization of all types of trials of the boiler plant, it is necessary to carry out revision (internal examination) of the boiler and other equipment in order to check the condition of main components and to detect defects and faults which have occurred in the process of operation.

The scope and sequence of the revision shall be decided by the surveyor particularly in each case.

All the detected defects and faults shall be rectified. The need for repeat trials or checks after these have been rectified shall be decided by the RS surveyor in each case.

9.7.1.16 Based on the results of the mooring and sea trials of the boiler plants, the RS surveyor shall evaluate their technical condition which shall be reflected in the appropriate documents of the Register, issued to the ship.

9.7.2 Mooring trials.
9.7.2.1 General.
9.7.2.1.1 Mooring trials of auxiliary boiler plants shall be carried out within the following scope:

.1 external examination;
.2 trials of the boiler in starting and shutdown modes;
.3 trials of the boiler in steady modes;
.4 manoeuvring trials of the boiler;
.5 check of the boiler operation under manual control;
.6 trials of the parallel operation of boilers.

Tests of the auxiliary boilers on mooring trials are generally final tests (refer to also 9.7.3.1.3).

9.7.2.1.2 Mooring trials of the main boiler plant shall generally be limited by external examination (refer to 9.7.2.2) and trials in starting and shutdown modes (refer to 9.7.2.3). The remaining categories of trials shall be conducted in conjunction with the trials of the ship’s main propulsion plant (refer to 9.7.3).
9.7.2.1.3 Waste heat boiler plants shall be generally tested within the full scope on the sea trials of the ship's main propulsion plant (refer to 9.7.3).

9.7.2.2 External examination.

9.7.2.2.1 External examination of boilers complete with the fittings, equipment, supporting machinery and heat exchangers, systems and piping shall be conducted with the steam up, at working pressure.

9.7.2.2.2 During external examination it is necessary to check:

.1 proper condition of the water level gauges (water level gauge glasses, test cocks, remote water level indicators, etc.) and operation of the manual drive for closing shut-off devices of the water level gauges from the boiler room floor;

.2 proper condition of the remote operated shut-off valves of the main and auxiliary steam lines;

.3 proper functioning of the blow-down and scum valves;

.4 possibility of shutting down the fuel pumps from a space outside the boiler room;

.5 adjustment of the safely valves (refer to 9.7.2.2.3), their discharge capacity (refer to 9.7.2.2.4), as well as proper functioning of the hand-operated easing gear for lifting the safely valves from the boiler room and outside thereof;

.6 operation of the automatic equipment of the boiler (refer to 9.7.2.2.5);

.7 quality of the boiler insulation.

9.7.2.2.3 Adjustment of the boiler safely valves shall be checked under manual operation of the boiler by raising the steam pressure in boiler until the safely valves adjusted with due account of the requirements of 3.3.6.4, Part X "Boilers, Heat Exchangers and Pressure Vessels" of the Rules for the Classification and Construction come into action. Operation of each valve shall be checked three times. In so doing, it is necessary to record the values of the valve lifting and seating pressure, which shall be within the limits stated in the technical documentation.

Safely valves of the steam superheaters shall open slightly before the main safety valve installed on the steam and water header.

9.7.2.2.4 On the prototype boiler it is necessary to check the discharge capacity of the safely valves. Such check shall be performed at full burning in the furnaces and with the shut-off valves closed. The maximum permissible pressure during the operation of the safety valve shall not exceed the steam working pressure by more than 10 %, unless the pressure value to which the valve is set is especially specified.

9.7.2.2.5 When checking the boiler automatic systems in operation, it is necessary to make sure that the alarms, protection and interlocking devices operate trouble-free and come into action in proper time when the water level in the boiler drops below the permissible one, air supply to the furnace is cut off, flame-jet is cut off at the burner and in other cases provided for by the automatic system.

9.7.2.2.6 Where the results of the external examination and check of the safely valve adjustment are satisfactory, one of the boiler main safety valves shall be sealed by the RS surveyor to which effect an appropriate note shall be made in the Register documents.

9.7.2.3 Trials of the boiler in starting and shutdown modes.

9.7.2.3.1 It is necessary to check the cold starting of an automated boiler from a local control station. In so doing, attention shall be given to the ignition cycle: duration of pre-ventilation of the boiler furnace, duration and time of switching-on and off of the ignition spark, as well as time of pilot and main fuel supply.

In the event of ignition failure or flame-jet cut-off, re-ignition may be permitted if provided for by the algorithm.

9.7.2.3.2 It is necessary to check the shut of the boiler from remote and local control stations. In so doing, attention shall be given to the positive operation of the quick-closing valves of the oil burner unit. The quick-closing valves shall close simultaneously with the shutdown of the boiler (time of operation not more than 1 s). Time of flame extinction shall not
exceed that specified in the RS-approved technical documentation. Such check shall be performed three times.

9.7.2.4 Trials of the boiler in steady modes.

9.7.2.4.1 A mode shall be considered as steady if no changes in bleeding-off are made.

The steady mode shall be reckoned not less than in 20 min after the boiler has been put in the prescribed mode and shall be defined by three (successively taken) measurements of the following values: fuel consumption, steam capacity of the boiler, superheated steam temperature, steam pressure in the boiler, flue-gas temperature, air head at the oil burner unit inlet.

Fluctuations of the values of measured parameters shall not exceed the permissible values stipulated by the technical documentation.

9.7.2.4.2 Trials of the boiler in steady mode shall be carried out in accordance with Table 9.7.2.4.2 unless otherwise provided in the RS-approved technical documentation.

The total duration of the trials of an automated boiler plant shall be not less than 6 h for prototype ships and 4 h for ships of a series, in case of unattended operation under all possible operational conditions and operation for regular consumers.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Steam loading of boiler, in %</th>
<th>Duration of mode, in h, not less than</th>
</tr>
</thead>
<tbody>
<tr>
<td>Zero</td>
<td>0</td>
<td>0.5 (1)</td>
</tr>
<tr>
<td>Minimum</td>
<td>10 — 20</td>
<td>1 (2)</td>
</tr>
<tr>
<td>Medium</td>
<td>approx 50</td>
<td>1 (2)</td>
</tr>
<tr>
<td>Full</td>
<td>approx 100</td>
<td>1 (2)</td>
</tr>
</tbody>
</table>

Note. The time of trials of prototype boilers is given in brackets.

9.7.2.4.3 For boilers operating on "on – off" cycle, in the zero load mode, the following parameters shall be monitored: steam pressure (at the beginning and end of the cycle) in the boiler and steam super-heater;

fuel temperature at the burner inlet (at the beginning and end of the cycle);

fuel viscosity; and water level in the boiler.

9.7.2.4.4 In the modes of minimum, medium and full load the following parameters shall be monitored:

steam capacity (only for the prototype boiler);

steam pressure in the boiler;

steam pressure and temperature in the steam superheater;

fuel pressure at the burner inlet (only for the pressure-jet burners);

pressure of the atomizing medium (for the steam-assisted pressure-jet burners) and feed water pressure;

air pressure difference at the air heater;

fuel viscosity;

fuel temperature at the burner inlet, feed water and air temperature in the boiler room and air temperature at the air heater outlet and exit gas temperature;

water level in the boiler;

salt content of the boiler water; and

fuel and feed water consumption.

9.7.2.4.5 To measure the parameters, standard gauges shall be used and for the prototype boilers, control gauges verified by a competent organization shall be used in addition.

9.7.2.4.6 The number of measurements of each parameter in each mode shall not be less than five for the full load mode and not less than three – for the remaining modes.

9.7.2.4.7 The time interval between two regular measurements shall not exceed 20 min.
9.7.2.5 Manoeuvring trials of boilers.
9.7.2.5.1 The manoeuvring trials of a boiler shall be conducted under the following variations in the steam load: 0 – 100%; 100 – 0%; 50 – 100%; 100 – 50%, as well as at other loads if this is contemplated by the trial program.
9.7.2.5.2 The trials for each variation in load shall be conducted not less than two times in case of serial boilers and not less than three times – for prototype boilers.
9.7.2.5.3 The time of load variation shall be taken as specified in the RS-approved technical documentation.
9.7.2.5.4 Boilers with automatic feed water and combustion regulation shall undergo the trials under an automatic control.
9.7.2.5.5 During manoeuvring, it is necessary to monitor the steam pressure and water level in the boiler. Change of the said parameters may be allowed within the levels which do not cause actuation of the highest steam pressure and water level alarms and the operation of safe valves.
9.7.2.6 Trials of a boiler under manual control.
9.7.2.6.1 When an automated boiler is subjected to trials under manual control, it is necessary to check:
- cold starting of the boiler (two times);
- increase of the boiler steam load up to the full one;
- operation of the boiler at full load;
- reduction of the boiler load from the full down to minimum one;
- shutdown of the boiler.
   The duration of the trials shall be not less than 1 h and the boiler prototype shall undergo all checks not less than three times with the total duration of not less than 2 h.
9.7.2.6.2 Operation of the interlocking and protective devices of the oil burner unit shall be checked (refer to 9.7.1.9).
9.7.2.7 Trials of the parallel operation of boilers.
9.7.2.7.1 Parallel operation of boilers shall be checked when the ship is fitted with two and more boilers operating to a common steam line. It is necessary to check: parallel operation of boilers under automatic control in the modes specified in 9.7.2.4 (except the position control mode), change-over from the parallel operation of boilers to a single boiler operation and vice versa (with a corresponding change of load) and emergency shutdown of each boiler by one of the parameters.
9.7.2.7.2 During the parallel operation of boilers and during change-over from one mode to another, safely valves as well as the steam pressure and water level alarms shall not be actuated.
9.7.3 Sea trials.
9.7.3.1 General.
9.7.3.1.1 During sea trials it is necessary to check the operation of the main and waste-heat boilers, as well as their supporting machinery, systems and equipment in accordance with the RS-approved trials program.
9.7.3.1.2 As regards the trial modes and duration, the trials programs of the main and waste-heat boiler plants shall be co-ordinated with the pertinent trials of the main propulsion plant of the ship (refer to Section 5).
9.7.3.1.3 During the sea trials of the ship, it is necessary to monitor also the operation of the auxiliary boiler plants to serve their direct service.
9.7.3.2 Main boiler plant.
9.7.3.2.1 The main boiler plant shall be tested during the sea trials of the main steam power plant of the ship within the following scope:
.1 testing of the boilers in steady modes in accordance with 9.7.2.4 and 9.7.3.2.2 – 9.7.3.2.4;
.2 manoeuvring trials of boilers in accordance with 9.7.2.5;
.3 check of operation of boilers under manual control in accordance with 9.7.2.6;
.4 trials of parallel operation of boilers in accordance with 9.7.2.7.
9.7.3.2.2 During the trials of main boilers in steady modes, in addition to the modes indicated in Table 9.7.2.4.2, it is necessary to conduct trials of boilers in the maximum steam load (approx. 110 %) mode with a duration of not less than 1 h, if such trials are contemplated also for the main steam power plant.

9.7.3.2.3 Steam capacity and feed water consumption (refer to 9.7.2.4.4) for the main prototype boilers shall be measured by flowmeters, while for the serial boilers these parameters may be determined by calculations using the approved procedures.

9.7.3.2.4 The total duration of the trials of the main boiler plants on board ship assigned an automation mark added to the character of classification shall be not less than 4 h in case of unattended operation.

9.7.3.3 Waste-heat boiler plants.

9.7.3.3.1 The trials of the waste-heat boiler plants shall be conducted within the following scope:

- external examination;
- checks of safety valve settings and operation of the governing and alarm system in operation; operation of the plants in starting and stopping modes, in steady modes, under manual control; parallel operation of the waste-heat boilers as well as the waste-heat and auxiliary boilers (if this is contemplated by the technical documentation).

9.7.3.3.2 During the external examination of a waste-heat boiler plant it is necessary to check proper functioning of water level indicators, blow-down valves and feeding devices, as well as the gas damper.

9.7.3.3.3 The settings of the safely valves shall be checked in accordance with 9.7.2.2.3.

9.7.3.3.4 For the unattended waste-heat boiler plants it is necessary to check the operation of the alarms to warn of the minimum and maximum water level in boiler or steam collector (depending on the waste-heat plant design). The check shall be effected by blowing down the boiler or steam collector (minimum level) and by filling it with water by the feed-water pump controlled manually (maximum level). In case of composite boilers fitted with a change-over device, operation of this device shall be checked when the exhaust gas heating is changed over to the fuel oil heating. The check shall be effected by creation of working conditions where the change-over is performed.

9.7.3.3.5 Automated waste-heat boiler plants shall be checked for automatic starting of the boiler according to the automatic control algorithm. Along with that, attention shall be given to smooth movement of the gas duct damper, if any, as well as to the proper functioning of the damper position ("closed – open") indicator.

Similar check shall be performed in case of automatic shutdown of the boiler (stoppage). It is necessary to monitor the exhaust gas temperature at which the waste-heat boiler is automatically started and shut down.

9.7.3.3.6 It is necessary to check the operation of the waste-heat boiler plant in steady modes specified in the approved technical documentation.

In so doing, the steam pressure in the boiler (steam collector), exhaust gas temperature at the boiler inlet and outlet, as well as the boiler (steam collector) water level and steam pressure alarms shall be monitored.

Under steady mode conditions, the safely valves and the boiler (steam collector) water level and steam pressure alarms (if such alarms are provided) shall not be actuated.

9.7.3.3.7 If the technical documentation provides for the operation of an automated waste-heat boiler plant under manual control, this shall be checked by testing in all steady modes specified in the technical documentation, as well as in starting and shutdown (stoppage) modes and parallel operation modes.

9.7.3.3.8 Where provision is made on board the ship for parallel use of several waste-heat boilers, their joint operation shall be checked on sea trials. Similar check shall be performed, if provision is made for parallel operation of a waste-heat boiler and auxiliary boiler.
The check shall be performed in steady modes, specified in the technical documentation. The values of the major parameters (steam pressure, exhaust gas temperature at the waste-heat boiler inlet and outlet), as well as the water level in the boiler (steam collector) shall be within the limits established by the RS-approved technical documentation. No actuation of the safely valves as well as the alarms provided for by the design circuit to warn of the plant faults shall take place.
9.8 CHECK OF HEAT EXCHANGERS AND PRESSURE VESSELS IN OPERATION

9.8.1 Heat exchangers and pressure vessels shall be checked during the mooring and sea trials in operation according to a program approved by the Register.

9.8.2 Readiness for the trials shall be confirmed by a document issued by the inspection body.

9.8.3 Heat exchangers shall be verified in operation together with supporting systems, piping and devices.

In so doing, it is necessary to check:
- quality of installation;
- operation at specified parameters of the working medium;
- performance of the fittings, gauges and governors;
- adjustment of the safety devices, their fastening and possibility for thermal expansion.

9.8.4 Verification of the pressure vessels in operation shall provide for the check of their installation quality and performance reliability.

In so doing, it is necessary to check: proper functioning of the fittings, gauges and governors, as well as discharge capacity and adjustment of the safety devices.

The discharge capacity of the safety valves shall be checked on the prototype pressure vessels. When the discharge capacity is checked, the maximum permissible pressure during operation of the safety valves shall be such that under no conditions the working pressure is exceeded by more than 15%.

Safety valves shall be set to a pressure, which exceeds the working pressure by not more than 10%, unless the pressure to which the safety valve is set is especially specified.

When lifted, safety valves shall be completely closed in case of the pressure drop in the air receiver by not more than 15% of the working pressure. Performance of the drainage devices shall be also checked.
9.9 ISSUANCE OF DOCUMENTATION

9.9.1 The results obtained from the technical supervision during the installation and tests of boilers and pressure vessels shall be identified in the reports or checklists issued on the basis of the initial survey.
10 ELECTRICAL EQUIPMENT

10.1 GENERAL

10.1.1 The provisions of this Section specify the scope and procedure for technical supervision during installation and testing of electrical installations on board the ships under construction, and of essential electrical equipment referred to in 1.3.2, Part XI "Electrical Equipment" of the Rules for the Classification and Construction and in the RS Nomenclature.

10.1.2 General provisions for the organization of the technical supervision are given in Section 1.

10.1.3 Technical documentation.

10.1.3.1 Installation and testing of electrical installations and essential electrical equipment on board the ship shall be performed under the Register technical supervision according to the RS-approved technical documentation.

10.1.4 Technical supervision of the Register.

10.1.4.1 Surveys during installation and testing of electrical installations and essential electrical equipment shall be performed according to the examination and testing plan developed by the shipyard according to 10.2.1, taking into account 10.3.

10.1.5 Tests and checks specified in this Section are based on an assumption that the electrical plants and critical electrical equipment have been tested at the firm (manufacturer) in compliance with the requirements of Section 10, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of the electrical plants and critical electrical equipment in substantiated cases.

10.1.6 The following definitions and explanations have been adopted for the purpose of this Section:

.1 essential electrical equipment are essential services defined in 1.2, Part XI "Electrical Equipment" of the Rules for the Classification and Construction;

.2 supporting structures are metal structures attached to bulkheads, ceiling, hull framing, etc., where electrical equipment is fitted.

These structures include: brackets, panels, angles, frames, earthing supports, cable supports, suspensions, as well as busbar supports, pipes, shafts, sockets, trays, boxes for cable penetrations, and similar structures.

10.1.7 Patrolls are carried out by the RS surveyor independently of the list and are not associated with the official presentation of items of technical supervision by the shipyard's technical control body.

10.1.8 Survey of the ship's electrical equipment shall be carried out by the RS surveyor at the stage of installation, and of mooring and sea trials. All types of electrical equipment, installation jobs, fittings, materials, etc., which, upon installation, completion of work, going into operation, etc., become inaccessible for survey, shall be submitted to the RS surveyor at a stage when survey is still possible.

10.1.9 The survey shall determine compliance of the electrical equipment and electrical installation as a whole with the RS-approved technical documentation.
10.2 SURVEY PLANNING

10.2.1 Prior to commencement of survey of the electrical plants and critical electrical equipment of the ship under construction, the RS Branch Office shall agree the examination and testing plan of the electrical equipment developed by the shipbuilder taking into account the RS Nomenclature and 10.3. The shipbuilder shall be informed about that at a kick-off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

10.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

10.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick-off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

10.2.4 Quality standards for installation and testing of the electrical plants and critical electrical equipment shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

10.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
10.3 SURVEY OF ELECTRICAL EQUIPMENT AT INSTALLATION

10.3.1 The following shall be checked at verification of electrical equipment mounting on seatings and other supporting structures:
   1. conformity of arrangement to general arrangement plans;
   2. inadmissibility of fitting of electrical equipment on hull plating, walls of fuel oil tanks, lube oil tanks, water tanks, and pressure vessels;
   3. adequacy of distances between electrical equipment and hull plating, combustible materials, sources of heat, emissions of gas, vapour, water, as well as pipelines, tanks, valves and other fittings capable of bringing about conditions that may cause damage to the electrical equipment or cause ignition of the ambient materials.

10.3.2 The following shall be checked at survey of electric propulsion plants:
   1. availability of bilge system suction in dry compartments for propulsion electrical machines, availability of cable runs prepared for lighting of these compartments and heating of electrical machines when they are not in operation;
   2. absence of flanged and threaded joints in pipelines, valves and other fittings except for bilge systems and general ship systems under seatings, in dry compartments or above electric propulsion plant electrical machines.

10.3.3 The following shall be checked at survey of cabling against the requirements in force:
   1. the cable runs were selected such that the distances are as short as practicable, they go in straight lines and are clear of locations subject to prolonged effect of lubricating oil, fuel oil, water, and excessive external heating;
   2. cable supporting structures;
   3. adequacy of and spacing between cable fastenings to supporting structures as well as the material of which clips, holders, hangers, etc. are made for fastening of cables;
   4. separate laying of cables intended for different purposes, of different types and designed to different voltages;
   5. construction and methods of installation of pipes, expansion joints and methods of attachment of cables therein, conduits, trays, shafts, sockets, busbar supports, boxes for cable penetrations, glands and similar arrangements for cable penetrations through bulkheads and decks;
   6. cable laying in hazardous spaces and areas and in spaces having a fire hazard;
   7. protection of cable runs comprising cables that were not tested for flame retardation.

The purpose of survey at this stage of technical supervision shall ascertain that all the pieces of electrical equipment have appropriate brands and documents confirming manufacture under the Register supervision, and that their workmanship, completeness, number, protection, electromagnetic compatibility parameters, cabling, arrangement in ship's spaces and areas, maintenance-friendliness, control and regulation devices, enclosures, fire protection and explosion protection arrangements tightness protection against electric shock, protective earthing, and other characteristics and parameters are such that they fit their intended purpose and ensure: safety of ship's navigation as far as equipment and use of electrical power are concerned.

Methodological recommendations for this Chapter are set out in Appendices 2 and 3 to this Section.
10.4 MOORING AND SEA TRIALS

10.4.1 General.
10.4.1.1 Mooring and sea trials shall be carried out in accordance with the program approved by the Register.

10.4.1.2 The test program shall comprise tests of all the ship's electrical equipment, including electrical machines, systems, arrangements, apparatuses, and other items, when these are operated both individually and together with ship machinery according to their intended purpose.

10.4.1.3 The test program shall address the scope, conditions, duration and succession of tests, specify the parameters and characteristics to be checked, and list the devices, apparatuses, load banks and other auxiliary equipment required for the performance of the tests.

10.4.1.4 Notwithstanding the procedures for testing of electrical equipment in the Guidelines, the Register may require that additions and/or amendments to existing procedures be developed and included in the test program, or that new methodologies be developed, depending on the novelty and complexity of the ship's electrical installation to be tested. The recommendations given in Appendices 1 and 2 to this Section are not exhaustive and all-embracing, their purpose being to set out the key principles for the RS surveyor to follow when performing survey of equipment.

10.4.1.5 Testing of the electrical equipment directly associated with ship's machinery, arrangements and systems, shall, as far as practicable, be performed simultaneously with testing of such equipment for its intended purpose.

10.4.1.6 Prior to commencement of the tests, the RS surveyor shall be provided with technical documentation for electrical equipment to be surveyed as follows:

1. certificates and other documents confirming the RS technical supervision of the electrical equipment during manufacture;

2. specifications, files and instruction manuals;

3. electrical equipment test programs and procedures;

4. documents showing results of tests performed by the shipyard's technical control body, if such tests were performed.

10.4.2 Mooring trials.

10.4.2.1 Mooring trials shall be carried out with all the consumers supplied from ship's generators or from shorebased sources of electrical power having appropriate parameters.

10.4.2.2 Electrical equipment mooring trials may be shifted to coincide with sea trails in justified cases and subject to agreement with the RS surveyor.

10.4.2.3 A comprehensive list of the tests, measurements, checks, examinations, etc., to be included in the mooring trials program is set out in Appendix 4 and the duration of checks and tests is set out in Appendix 7.

The scope of external examination of the entire set of the electrical propulsion plant equipment may be reduced or increased at the discretion of the RS surveyor depending on the work performed by the surveyor.

10.4.2.4 At testing of the equipment for the electric propulsion plant and electric propulsion system, the following checks and measurements shall be performed:

1. air gaps in fore and aft parts of machines;

2. cooling and lubricating systems (availability of lubricating oil level indicators, protective gratings and air intake filters, air and water temperature gages, etc.).

10.4.2.5 The following measurements and checks shall be performed when preparing for starting and at operation tests of the electric propulsion plant:

1. insulation resistance of all the electrical devices of the electric propulsion plant;

2. proper operation of the starting and protective devices, switchgear and control gear;
.3 operation of electrical and mechanical protection devices: maximal, differential, minimal protection, protection against generator overloading, protection against electrical machines and prime movers overspeed, etc.;
.4 availability of electrical measuring instruments and their operation, including insulation monitoring devices in main and auxiliary circuits of the electric propulsion plant, as well as availability of seals, brands and documents of instrument calibration;
.5 availability and operation of interlocks of: switchgear doors in case of application of voltage in excess of 1000 V, shaft-turning gear, possibility of prompt switching with the main circuit energized, shunting of circuits of stopped electric propulsion plant generators in case of series connection of several generators, possibility of connecting of other consumers to electric propulsion plant exciting units;
.6 operation of control and monitoring desks switch;
.7 operation of electric propulsion plant distribution gear and control desks;
.8 activation of visual and audible alarms, including water level alarms in electric propulsion plant spaces, cooling air humidity; bearings temperature; lube oil pressure, machines overloading, availability of power supply to control circuits, operation of exciting units, ventilators, etc.

10.4.2.6 The following shall be checked at electric propulsion system operation test:
.1 starting of electric propulsion plant generators and their loading under various circuit operation modes;
.2 starting, braking (regenerative, if any) and reversing of electric propulsion motors, reversible shaft generators running in motor mode at all intended propulsion plant operating modes and at all possible circuit arrangements, moreover, all electric drives of auxiliary machinery, both main and standby, and all the onboard exciting units shall be operation tested;
.3 proper operation of local and remote controls, alarms, interlocking and protective devices with the propulsion plant running;
.4 proper and reliable operation of power takeoff system used by consumers taking power from electric propulsion plant generators, at all propulsion plant operating modes (if any).

10.4.2.7 The following checks, measurements and tests shall be performed at ship’s electric power plant testing:
.1 main generators running in parallel, devices to change generator driving motor speed from the station from which synchronization is effected; voltage regulation, operation of synchronizing devices and other instruments;
.2 load sharing between main generators when running in parallel, and between generators operated from the main engine (engine-driven generators, shaft generators, turbogenerators operated from exhaust gas boilers during load transfer), including electric power plant short-term unloading, as well as when electric drives of commensurable power operated in regenerative modes (if any);
.3 operation of devices for automatic starting and connection to main switchboard busbars of automated power plant standby generator;
.4 operation of automatic starting system for standby electrical power sources at switching over, shutoff and other operations involving generators operated from main engines (shaft generators, engine-driven generators);
.5 steady operation of main generators running in parallel when loaded in steps to 70 and 30 % (50 and 50 %) of the rated power and when 100 % of the rated power is suddenly thrown off, including electric power plant short-term unloading, as well as when electric drives of commensurable power operated at regenerative modes (if any). Where the power balance is such that a single generator shall supply the ship under running and emergency conditions, this test shall be performed for each individual generator. Moreover, it shall be ascertained that the most powerful electric motor having the greatest starting current and the most severe staring conditions can be started with a single generator running;
.6 operation of automatic devices for generator unloading, frequency and voltage regulation, synchronizing, reactive power compensation, protection against phase break-off, etc.;
.7 operation of protection devices of generators and outgoing feeders;
.8 operation of essential electric drives, including remote starting and shutoff controls (for fire pumps, ventilators, steering engines, anchor and mooring machinery, fuel, fuel transfer, lube oil transfer pumps, separators, etc.);
.9 operation of interlocks and of electric drive sequential starting arrangements after interruption in power supply from the main switchboard (for steering engine, automated machinery, etc.);
.10 operation of emergency installations, including automatic starting of emergency diesel generator, loading, connection of accumulator batteries serving as transitional source of power, emergency accumulator battery and all consumers operating under emergency conditions; measurements shall be taken of the voltage, speed, current strength of the above sources when loaded simultaneously by all emergency consumers. In case of a prototype ship, it shall be checked that the emergency accumulator battery capacity is sufficient to supply all emergency consumers within the specified time period;
.11 operation of boat winch electric drive interlocks;
.12 main and emergency lighting, including lighting in way of all essential machinery, ship's spaces and areas, lifeboats, liferafts, places of stowage of personal life-saving appliances, etc. In the case of a prototype ship, provision shall be made for measurement of luminous intensity according to the standards given in Table 6.7.1, Part XI "Electrical Equipment" of the Rules for the Classification and Construction;
.13 alarm systems: general alarm system, fire detection system, warning alarm of extinguishing system release, automated power plant alarm, etc.;
.14 navigation lights and fault signaling;
.15 internal communication systems: telephone, public address system, electric engine room telegraph;
.16 operation of interlocking circuits of electric heaters of large electrical machines;
.17 availability and proper functioning of electrical power sources and consumers, their electromagnetic compatibility, including measurement of the total harmonic distortion \( K_u \) according to Appendix 10;
.18 operation of charging devices of essential accumulator batteries and their interlocking circuits with accumulator battery room fans.

Brief instructions on mooring trials are set out in Appendix 4.

10.4.2.8 Mooring trials of composite propulsive systems.
10.4.2.8.1 Mooring trials of composite propulsive system shall be conducted concurrently with tests of the main heat engine (ME) referred to in 5.16, Section 5 "Machinery" and EPP tests referred to in 10.4.2, Section 10 "Electrical Equipment".
10.4.2.8.2 During mooring trials of the composite propulsive system, the following shall be checked within the scope and at load allowed by the trial conditions:
   - start of composite propulsive system motors under all design combinations;
   - frequency regulation of composite propulsive system motors under all design combinations;
   - stop of composite propulsive system motors under all design combinations;
   - emergency stop of composite propulsive system motors under all design combinations;
   - reverse of composite propulsive system motors under all design combinations.
10.4.2.8.3 During mooring trials of the composite propulsive system, where provided by the design, the following shall be checked within the scope and at load allowed by the trial conditions:
   - generator operation mode of the electric propulsion motor;
   - electric ME starting from the electric propulsion motor;
   - other modes provided by the composite propulsive system design.
10.4.2.8.4 Where it is impossible to perform individual checks during mooring trials they shall be carried out during sea trials.

10.4.2.9 Mooring trials of static sources of electrical power.

10.4.2.9.1 During mooring trials the following shall be checked:
- proper operation of devices and elements of lithium-ion batteries (LIB), super capacitor systems (SCS), solar-cell arrays (SA) and fuel cells (FC):
  - protection actuation,
  - alarm system,
  - emergency shutdown functions,
  - switch-on and switch-off,
  - charging-discharging units;
- operational check of the LIB, SCS and FC auxiliary systems:
  - ventilation systems,
  - gas detection systems,
  - cooling systems,
  - fire alarm systems,
  - fire extinguishing systems;
- LIB, SCS, SA and FC functioning checks:
  - in autonomous mode (at idle running, under rated load, at load surge and load shedding relief, when consumers are activated),
  - in parallel mode with other sources (at idle running, under share and rated loads, at load surge and load shedding relief, when consumers are activated) (if provided),
  - in buffer mode (if provided).

Where it is impossible to perform separate checks during mooring trials they shall be carried out during sea trials.

10.4.2.9.2 During the FC mooring trials, apart from the above-mentioned checks, automatic changeover to the safe condition and initiation of emergency alarm when simulating following events shall be checked:
- fire detection;
- gas leakage detection;
- failure of ventilation system;
- disconnection of electric power supply;
- protection actuation;
- failure of control system.

10.4.3 Sea trials.

10.4.3.1 During sea trials, the ship's electric power plant shall be functionary tested under all conditions referred to in 10.4.3.5, under actual loads and conditions occurring during ship propulsion, and check shall be performed of the electrical equipment that was not fully tested during mooring trials. The duration of electrical equipment tests and checks shall take into account the time afforded in relevant sections of this Part of the Rules for tests and checks of machinery, systems and arrangements powered by electrical power.

10.4.3.2 During sea trials, functional test of the entire ship's electrical installation and individual pieces of electrical equipment shall be performed according to their intended purpose, and the following shall be checked:

.1 under manoeuvring conditions, operation of electrical equipment associated with change of speed and direction of rotation of main engines, change of pitch and thrust of CPP blades, change of angle of azimuth thruster, and with two or more azimuth thrusters change of mutual angles of azimuth thrusters at different propeller speed, starting and shutting off of thruster electric drives, main engine shutoff;

.2 under emergency conditions with the main generators running, the operation of electric drives of fire pumps, bilge and ballast pumps, sprinkler system pumps and compressors, shutoff of machinery space fans; shutoff of fuel and fuel transfer pumps from
remote control desks; operation of sluice doors, alarms, public address system, service
telephones, warning alarm of extinguishing system release, etc.  

.3 under emergency conditions, with emergency sources of electrical power running,
the operation of all types of electrical equipment designed to be supplied by these sources of
electrical power.

10.4.3.3 At testing of the equipment for the electric propulsion plant and electric
propulsion system, the following shall be checked:

.1 electric propulsion plant generators starting and circuit arrangement at all intended
generator operating conditions;

.2 shutoff of individual generators and circuit operation with the remaining generators
running;

.3 operation of exiter sets, rectifying units and static excitation converters;

.4 starting, shutoff, speed variation, braking and reversing of each electric propulsion
motor for each possible (design) combination of generators and electric propulsion motors;

.5 control of electric propulsion plant from all remote and local control stations and desks;

.6 operation of all the electric drives, machinery and arrangements associated with the
electric propulsion plant; cooling, lubricating, excitation, ventilation, temperature control
systems, electrical measuring instruments, tachometers, etc.;

.7 actuation of alarm systems warning of exceeding the permissible deviation limits of
electric propulsion plant parameters from rated parameters.

10.4.3.4 The above tests of equipment for the electric propulsion plant and
electric propulsion system shall be carried out under all the conditions referred to
in 10.4.3.2.1 – 10.4.3.2.3. Moreover, the following shall be done:

.1 the electric propulsion plant parameters shall be measured, as follows: voltage,
current in main and auxiliary circuits, speed, reversing time, shaft torque, etc.;

.2 electric propulsion plant local and remote control stations and their switches shall
be checked to ascertain that control can be effected only from one station, and that a control
station to be disconnected or connected can only be switched via "stop" position; engine room
telegraphs shall also be checked;

.3 electric propulsion system shall be operation tested to ascertain that it can
simultaneously supply power to electric motors and other ship's consumers in a steady
manner, including regenerative braking modes provided for by the design, if this kind of power
takeoff from the electric propulsion plant generators is provided for by the design;

.4 the electric drives of electric propulsion plant essential machinery and electrical
installations, such as exciter sets, semiconductor frequency converters, static converters,
rectifiers, cooling oil pumps, etc., shall be checked for reliable and steady operation.

10.4.3.5 At testing of the electric propulsion system, the following shall be checked:

.1 steady operation of main generators under all design combinations of running in
parallel and individually for each generator, as well as transfer between generators of load due
to operation of all consumers under running, manoeuvring and emergency conditions;

.2 steady operation of shaft generators, engine-driven generators at change of main
engines speed, as well as their running in parallel for load transfer to main generators with
independent motors;

.3 stable operation of shaft generators with reversible semiconductor frequency
converters when the changeover from generator to motor mode occurs, in the motor mode —
separately and together with the main engine or propulsion motor to the ship's propeller;

.4 steady operation of turbogenerator from exhaust gas or auxiliary steam boiler and
load transfer arrangement to independently generator driven generator;

1 *etc* shall here and after be interpreted as other checks, tests, conditions, measurements, types of equipment,
as may be required by the RS surveyor.
.5 possibility of diesel generator starting within the time of turbogenerator operating from exhaust gas boiler after main engine shutoff without interruption of power supply to ship’s consumers unless provision of made for automatic starting of standby generator.

In case of a prototype ship, actual load of ship’s power plant shall be checked under all operating conditions on the basis of the power balance calculation, with the main sources of electrical power on.

10.4.3.6 At all the checks referred to in 10.4.3.1 – 10.4.3.4, the following electrical installation parameters shall be measured: voltage and its variation limits when connecting and disconnecting loads under all conditions referred to in Section 18, current, generator driving motors speed, active power, frequency, power factor, etc.

All the measurements shall be taken by means of standard instruments for each running generator or generators.

Measurement of voltage variation limits of shaft generators:
- driven by main engines with controllable pitch propeller shall be taken at the same time as main engine load is changed by putting the rudder over to the greatest allowable angles and of the CPP blades from the "full ahead" position to the "full astern" position;
- driven by main engines with fixed pitch propeller and semiconductor frequency converter shall be taken at the same time as main engine speed is changed within the specified speed limits.

10.4.3.7 Electric drives of pumps, compressors, separators, ventilators and other auxiliary machinery shall be tested for their intended purpose, in particular, the following shall be checked: reliability and unfailing performance, starting and shutoff, changeover to emergency set (if any), operation of remote controls starting and shutting off the electric drive, automatic starting of standby electric drives on receipt of signal from the controlled parameters of the operating environment on automated installations, etc.

The above checks shall be carried out through external examination of running electrical equipment and through ascertaining by means of relevant devices that there are no overloads, unacceptable overheating of enclosures, sheathing, panels, bearings, etc. Also to be checked are proper vibrations and the vibrations caused by ship’s propulsion and operation of main and auxiliary machinery (refer to Appendix 6).

10.4.3.8 Steering gear electric drives, their power supply systems (main and backup feeders), control systems, rudder angle indication, electric drive operation and shutoff alarm, automatic starting of electric drives after voltage is restored following a power supply interruption, etc., shall be checked with the steering gear operating under all intended control modes.

10.4.3.9 The check shall be performed both with the two steering gear power units (if fitted) running, and for each individual power unit. These checks shall be performed from all the remote and local control desks with the power unit electric drives and control systems supplied by the main and reserve feeders.

10.4.3.10 The ability of the steering gear to keep steady the ship of a course shall be checked both by means of simple manual, follow-up remote control, and by means of automatic pilot in the case of automatic control, with check of changeover to manual control (refer to Section 16).

10.4.3.11 Check of the arrangement of local control (in steering gear compartment) of electric drive of steering gear main power units shall be performed by the use of standard means of communication between the steering gear compartment and the wheelhouse.

10.4.3.12 Operation of limit switches shall be checked by putting the rudder over to more than 35° on any side.

10.4.3.13 Operation of rudder angle indicators shall be checked in all stations where steering gear remote control desks are fitted simultaneously with testing of steering gear electric drives and control systems.

This check shall be performed by comparing the readings of the mechanical indicator rigidly connected to rudder stock with the readings of electrical indicators.
10.4.3.14 Check of electric drives of anchor and mooring arrangements, boat winches, liferaft davits, shall be performed during the testing of the above arrangements when dropping and heaving up anchor, when leaving berth, when mooring and during anchorage, respectively.

10.4.3.15 Measurements of equipment's insulation resistance shall be taken during the sea trials of the electrical equipment, both by means of panel-mounted instruments for insulation resistance measurement with the equipment running, and by means of a portable megohm meter after putting the equipment out of operation when it is in hot condition and at steady-state temperature.

10.4.3.16 All direct current electrical machines and alternating current commutator machines shall be checked for commutation quality when operating for their intended purpose at a rated load and for condition of commutator and brushes after putting out of operation.

10.4.3.17 Sea trials of composite propulsive systems.

10.4.3.17.1 Sea trials of composite propulsive systems shall be conducted concurrently with the ME tests referred to in 5.17, Section 5 "Machinery" and EPP tests referred to in 10.4.3, Section 10 "Electrical Equipment".

10.4.3.17.2 During sea trials the following shall be checked at the specified loads:
- start of composite propulsive system motors under all design combinations;
- frequency regulation of composite propulsive system motors under all design combinations;
- stop of composite propulsive system motors under all design combinations;
- emergency stop of composite propulsive system motors under all design combinations;
- reverse of composite propulsive system motors under all design combinations.

10.4.3.17.3 During sea trials, where provided by the design, at the specified loads the following shall be checked:
- generator operation mode of the electric propulsion motor;
- electric ME starting from the electric propulsion motor;
- other modes provided by the composite propulsive system design.

10.4.3.18 Sea trials of static sources of electrical power.

10.4.3.18.1 During the LIB, SCS, SA and FC sea trials, the following functioning checks shall be performed:
- in autonomous mode (at idle running, under rated load, at load surge and load shedding relief, when consumers are activated);
- in parallel mode with other sources (at idle running, under share and rated loads, at load surge and load shedding relief, when consumers are activated) (if provided);
- in buffer mode (if provided).

10.4.4 Inspection and check trials.

10.4.4.1 After the sea trials, the RS surveyor shall specify the scope of inspection. The inspection shall comprise the following:

.1 dismantling of electrical machines bearings that were heated in excess of the rated value. When dismantling an electrical machine, attention shall be paid to the following:
- condition of stator winding supporting structures and their fastening;
- possible displacement of stator winding slot wedges;
- possible displacement or detachment of the pole winding;
- possible reduction in winding insulation resistance;
- possible malfunction of rotating parts fastening;
- damage of painting and anticorrosive protection;
- function of protective ralleys in operation;

.2 opening, dismantling and repair of electrical equipment with a reduced insulation resistance if compared with standards;

.3 control of different ralleys, measuring instruments and blocks, the operation of which is not accepted.

10.4.4.2 The necessity and scope of final tests are specified by the RS surveyor.
10.5 SURVEY OF MODU/FOP ELECTRICAL EQUIPMENT

10.5.1 General.

10.5.1.1 All requirements of Section 10, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and Section 10 of the Guidelines shall apply to the MODU/FOP electrical equipment, subject to technical supervision of the Register according to the RS Nomenclature, during manufacture.

10.5.1.2 This Chapter contains provisions for technical supervision during survey of the MODU/FOP specific electrical equipment at the installation, mooring and sea trials.

10.5.1.3 In this Chapter, the following definitions shall apply.

Essential electrical equipment mean the equipment specified in 1.3.2, Part X "Electrical Equipment" of the MODU/FOP Rules.

MODU moving parts mean jack house, supports, derrick, cranes and others.

10.5.2 Technical documentation.

10.5.2.1 When performing technical supervision, the RS surveyor shall refer to technical documentation approved by the Register within the scope required by Part I "Classification" of the MODU/FOP Rules.

10.5.2.2 Electrical equipment subject to installation on board MODU/FOP under construction shall have the documents confirming technical supervision of the Register according to Section 10, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and the RS Nomenclature. The explosionproof electrical equipment shall have documents confirming its explosion-proofness, issued by the recognized authorized organization according to 2.11.2, Part X "Electrical Equipment" of the MODU/FOP Rules.

10.5.3 Survey of electrical equipment during installation.

10.5.3.1 When performing survey during installation, in addition to 10.3, the following shall be checked:

.1 electrical equipment to be installed in hazardous spaces and areas according to 2.11, Part X "Electrical Equipment" of the MODU/FOP Rules shall be of the appropriate safe-proof type;

.2 cable routes laid through the MODU/FOP moving parts shall be properly wired up and protected against mechanical damages;

.3 MODU/FOP power and/or control and instrumentation, and/or telecommunication and data subsea cable lines shall be properly laid and installed;

.4 manifolds of drilling and cement grouts, pneumatic pipelines for powder materials, circulation system, oil combustion system for well testing as well as MODU moving parts shall be properly grounded;

.5 special design requirements and those mentioned in the approved technical documentation shall be met.

During survey of installation works, the applicable instructions given in Appendices 3, 4, 5 and 9 to this Section shall be used.

10.5.4 Survey of electrical equipment during mooring and sea trials.

10.5.4.1 When performing survey of electrical equipment during mooring and sea trials, in addition to 10.4, the following checks shall be performed:

.1 final check for proper arrangement and wiring of electrical equipment according to the approved technical documents and requirements in Part X "Electrical Equipment" of the MODU/FOP Rules;

.2 check for proper electric protection (in power circuits) of the drilling system electrical equipment and check if the operation of this equipment affects the quality of electric power generated by ship's electric plant;

.3 check if the power of emergency power supply is sufficient for supplying the consumers for a period mentioned in 9.3, Part X "Electrical Equipment" of the MODU/FOP Rules;
.4 testing in operation of the consumer emergency shutdown arrangements from all control stations according to 9.6, Part X “Electrical Equipment” of the MODU/FOP Rules.

During these surveys, the applicable instructions given in Appendix 6 to this Section and additional instructions given in 10.5.4.2 shall be used.

10.5.4.2 In addition to checks mentioned in 7.4.1, the following shall be checked during mooring and sea trials:

.1 electric drives of the MODU jacking system:
    starting and stopping of electric motors from the MODU main control station and local control stations (at least three time from each control station);
    operation of hydraulic jacks electromagnet control system from all stations and in all modes specified in the circuit;
    operation of alarms indicating electric drive operation and loss of power, catcher position and limit switch operation in the hydraulic jack control system;
    operation of electric drive for intended purpose during tests according to 3.4.3.3;

.2 electric drives of arrangements for lifting and lowering columns of submersible sea water pumps:
    operation of winch electric motor at all speeds specified in the circuit, in lowering and lifting modes;
    operation of electrohydraulic pusher in braking mode when the master controller handle is switched from operating to neutral position; operation of limit switches;
    alarm actuation when the lifting and lowering limits are reached; operation of electric drive for intended purpose in all modes according to 3.4.3;

.3 electric drives of compressor for tensioning devices air supply system: manual starting and stopping of electric motors from central control station and local control stations (at least three time from each control station);
    automatic starting and stopping of electric motors when the limit pressures are reached inside air receivers;
    operation of electric drives for intended purpose according to 5.19.2.10;

.4 electric drives of fans for oil combustion system for well testing; operation of electric drives for intended purpose;

.5 electric drives of sea water submersible pumps:
    manual starting and stopping of electric motors from central control station and local control stations (at least three time from each control station);
    automatic starting and stopping of electric motors when the limit levels in sea water storage tank are reached;
    operation of electric drives for intended purpose according to 5.19.2.8;

.6 electric drives of fans for enclosed spaces under overpressure: automatic starting of electric motors at drop of overpressure within spaces; actuation of overpressure alarm in the controlled spaces; operation of the electric drive for intended purpose;

.7 emergency shutdown arrangements for consumer and power supply sources: sequence for de-energizing of hazardous consumers and power supply sources when the hazardous areas are beyond the limits as prescribed by the MODU/FOP Rules from all points specified in the design;

.8 alarms:
    output of signal to central control station and appropriate emergency control station when the oil gas and vapour concentration reaches 20 ± 10 % of lower explosive limit and hydrogen sulphide concentration reaches 3 mg/m³. The specified parameters shall be checked under the most realistic conditions:
    output of signal on failure in the jacking system of self-elevating MODU from the central control station;
    output of signal on failure in ventilation system of hazardous spaces to the central and main control stations;
output of signal on high oil level in tanks, bilges, etc. to the central and main control stations (except for self-elevating MODU);
output of signal on pressure drop in ventilation systems of spaces and equipment under overpressure to the central and main control stations (except for self-elevating MODU).
Alarm devices operability shall be checked by simulation of a failure in the item under check.

10.5.4.3 Inspections.

10.5.4.3.1 Upon completion of all tests, single units of electrical equipment shall be checked. The scope of checks shall be determined by the RS surveyor based on the test results. In all cases the requirements in 10.4.4 shall be met.
RECOMMENDATIONS ON INSPECTION OF ELECTRICAL EQUIPMENT
DURING THE SHIP CONSTRUCTION

1. Inspection is one of the most important stages of survey of ship’s electrical equipment during its construction.
2. Inspection shall include external and internal inspections of electrical equipment.
3. External inspection is the inspection of external parts of the electrical equipment itself and external installation on board the ship.
4. Internal inspection – inspection of internal parts and internal mounting of electrical equipment.
5. Inspection shall not cover the matters of electrical or mechanical measurements of any parameters or characteristics, except line measurements of distances regulated by the Rules for the Classification and Construction and related to location and fastening of electrical equipment.
6. Mainly, external inspection shall be visual. All the measurements and tests interesting for the RS surveyor shall be carried out by the representative of the shipyard in the presence of the surveyor.

Survey by the inspection shall be applied at each stage of the supervision, starting with the preparation of rooms and spaces of the ship for installation of electrical equipment up to the sea trials inclusive.

7. During the external inspection the following checks and measurements shall be provided:
   .1 arrangement of electrical equipment in the rooms and spaces of the ship;
   .2 completeness of electrical equipment installed;
   .3 compliance of design of electrical equipment housings with the ambient environmental conditions in the rooms and spaces of the ship;
   .4 arrangement of guards from moving parts, components under voltage or subject to heating above 90 °C;
   .5 measures for protection of electrical equipment from ingress of water, oil, fuel, vapor and other harmful media;
   .6 provision of the possibility and convenience of maintenance of electrical equipment;
   .7 technical condition of electrical equipment regarding the absence of presence of external damages.

8. Instructions to paras 7.1 – 7.7.

8.1 Arrangement of electrical equipment.

8.1.1 Arrangement of electrical equipment shall comply with the general arrangement drawings, working drawings and requirements of effective RS rules. Depending on functional purpose of arrangements and machinery which include electrical equipment this equipment shall be located in compliance with the requirements of such rules to which arrangements and machinery related to. For general purpose electrical equipment the RS surveyor shall check compliance with the requirements of Part XI "Electrical Equipment" of the Rules for the Classification and Construction while its installation.

8.1.2 Check of location of the equipment shall give a comprehensive idea of fulfillment of the requirements of safety, reliable and functionally correct operation of equipment with its accepted location on board the ship.
8.2 Completeness of electrical equipment.

8.2.1 Completeness of each type of electrical equipment shall be checked according to submitted technical documentation, working drawings, certificates, files, etc., as well as the evaluation of adequacy of a set based on the use of equipment by proper purpose.

8.2.2 A set shall include all the separate devices, products and units, including controls, controlling and signaling means both local and remote. At the same time the availability of the Register approval for the inspected equipment for application of such equipment on board ships shall be checked.

8.3 Forms of enclosures.

8.3.1 Forms of enclosure of electrical equipment in respect of protection against ingress of water, restrictions, contacts with moving and live parts shall meet the requirements of 2.4.4.2, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

8.3.2 Besides mentioned in 8.3.1, version of housings shall be checked for compliance with the implosion protection degree established in explosive risk spaces stipulated by 2.9, Part XI "Electrical Equipment" of the Rules for the Classification and Construction. During such inspection the RS surveyor shall be guided also by the documents of a competent and recognized by the Register authority regarding the type and degree of implosion protection of various kinds of electrical equipment and information of the customer or shipyard in respect of the nature of highly explosive mixtures which may take place in ship’s rooms and spaces.

8.4 Protection guards.

8.4.1 Protection guards such as handrails, enclosures, panels, shields, railings, etc. shall be checked for strength and reliability of their fixed installation, applicable materials and insulated coatings, adequacy of dimensions and distances from equipment to be guarded, convenience of their location based on the necessity of equipment maintenance, etc.

8.5 Protection against external actions.

8.5.1 Protection of electrical equipment against detrimental effect of water, oil, fuel, vapors and gases, high temperatures, magnetic and other physical fields, as well as harmful interference shall be checked based on the requirements to remove the sources of such effects from the installed electrical equipment.

8.5.2 Minimum distances to which the sources of detrimental effects shall be removed from electrical equipment are specified in the appropriated parts and paragraphs of the RS rules, as well as in the effective standards.

During the inspection the measurements of distances may be performed, which shall not be less than those given in 5.5, Part VIII "Systems and Piping" of the Rules for the Classification and Construction.

8.6 Maintenance access.

8.6.1 Maintenance access of electrical equipment shall be provided by compliance of the requirements on dimensions of passages and free spaces near electrical equipment, requirements for access to doors, detachable covers, hatches, manholes and the possibility of their opening, extraction of detachable components, parts, cassettes, units, etc.

8.6.2 Conditions and possibilities of maintenance shall be checked by the RS surveyor by means of full-scale tests and measuring distances, which shall not be less than those specified in 4.6.7 and 18.6.2.1.1.2, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

8.7 Technical condition of electrical equipment.

8.7.1 Electrical equipment shall be checked for absence of visual damage of enclosure, framework or casing, such as cracks, dents, bends, chips and other defects. At the same time the RS surveyor shall be sure that the controls may be switched on, rushed through and fixed in proper way, rotating parts have easy smooth running, without excessive backlash or jamming, detachable parts have tight fastening at standard places, fixing devices are properly tighten and have tools against self-unfastening.
8.7.2 Open live parts of equipment, as well as windings, coils, cores, terminal blocks and other components shall be checked for absence of visual damage, taking into consideration that their electrical intactness will be checked during the tests and work by the proper purpose.

8.7.3 Electrical equipment which, as a result of mounting or installation, became inaccessible for visual inspection of the RS surveyor and which was not surveyed earlier shall be dismounted, opened or all the structures blocking the access to inspection of such equipment shall be removed regardless of the extent of work required.

9 In addition to checks stated in 8.7 during the visual inspection the following checks and measurements shall be provided:

.1 fastening of electrical equipment to foundations and other bases and supporting structures including mounting on shock-absorbers;
.2 laying of cables from electric power sources to the switchboards and from the latter to consumers: laying of control, communication, signaling cables, as well as cables for installation between the devices;
.3 quality and ways of contact protective seal termination of cable strands and connection them to the equipment;
.4 deck and bulkhead cable penetrations on board the ship; quality of sealing the penetrations through watertight and fire bulkheads;
.5 performing of all the types of grounding of electrical equipment and ship structures;
.6 ship rooms and spaces in respect of the requirements on installation of electrical equipment.

10 Instructions to paras 9.1 – 9.6

10.1 Fastening of electrical equipment.

10.1.1 Fastening of electrical equipment to foundations and other bases and supporting structures which are specified in 10.1.4.2 shall be strong and secure equipment at its standard place.

During the installation all the holes, pins and other devices provided by the structure shall be used by proper purpose: bolts, screws, nuts, etc. shall have appropriate dimensions, be properly tightened and secured against self-unfastening.

10.1.2 In places of location of electrical equipment where the excessive vibration, shaking, knocks and other mechanical impacts on equipment the RS surveyor may require to reinforce structures of foundations, bases and other supporting structures, application of additional fastenings or shock-absorbers.

Realization of such measures may be postponed till receipt of the results of full-scale tests during the sea trials.

10.1.3 The RS surveyor shall check compliance with the requirements of Part XI “Electrical Equipment” of the Rules for the Classification and Construction referred to fastening of electrical equipment.

10.2 Cable laying.

10.2.1 Check of single, single-row, multi-row and bunch cable laying, correctness of cable path selection, ways of grooming, cabling, intersection of cables in the paths, availability of gaps between crossing paths, fastening of cables on the supporting structures, protection of cables against mechanical damage, inadmissibility of laying the cable of essential circuits through fire risk spaces, joint laying of one bunch of cable intended for over 1000 V with low voltage cables, cables with different types of signals (from the point of view of electromagnetic compatibility (EMC)), with different outer shield or various allowable temperature characteristics, spark-proof circuits or explosion-proof circuits with normal circuits, etc. shall be carried out generally for compliance with the requirements of 2.2, Part XI “Electrical Equipment” of the Rules for the Classification and Construction.

10.2.2 Visual inspection of cables shall be carried out by the RS surveyor on the ship in general, on separate consumers and electric power sources. In all the cases cable paths, cables themselves, cable fastenings, their intactness and absence of visual defects shall be
examined, where possible, along the full length from the electric power source to consumer or distribution device, as well as the control cables shall be examined between the starting devices, local and remote, signaling and communication cables and cables from control devices to the objects under control.

10.2.3 Hidden laid cables shall be submitted for inspection in compliance with 8.7.3 of the Appendix.

10.2.4 When measuring the allowable distances of cable paths to the adjacent structures one shall be guided by the values stated in 16.8.4, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

10.3 Cable conductors termination.

10.3.1 When laying the cables the reliability shall be checked of contact termination of strand connected to electrical equipment. Termination shall be checked both at outlet and inlet cable ends at power sources, distribution devices and essential and non-essential consumers. Contact termination shall be checked for strength of connection of terminal clamp with a cable core, permissibility of the applied method and quality of work performed. While checking the contact terminations by permissible methods the surveyor shall be sure that:

- soldered and tinned joints have good infill, surfaces are smooth, clean, glossy, without porosity, influxes, blistering, sharp edges and other deficiencies, typical for low-quality soldering;
- welded connections cover all the wires of the core when welding to the terminal clamp, fused metal has tear-shape with clean surface, without porosity, blistering, influxes, sharp edges, etc.;
- crimped connections effectively fix the core in the terminal clamp bushing, dimple in the terminal clamp has sufficient depth not cutting the crimped core.

Permissible methods of contact termination depending on the section of cable cores are given in Table 10.3.1.

<table>
<thead>
<tr>
<th>Core section, in mm²</th>
<th>Type of electrical equipment</th>
<th>Type of contact terminal clamp</th>
<th>Way of terminal clamp fastening</th>
</tr>
</thead>
<tbody>
<tr>
<td>from 0.5 up to 0.75</td>
<td>essential and non-essential</td>
<td>Strip, with bushing, circular, from core</td>
<td>Soldering, tinning</td>
</tr>
<tr>
<td>from 1 up to 2.5</td>
<td>Ditto</td>
<td>Ditto</td>
<td>Soldering, tinning, welding, crimped</td>
</tr>
<tr>
<td>from 1 up to 2.5</td>
<td>Non-essential</td>
<td>Circular, from core</td>
<td>Crimping by copper ring</td>
</tr>
<tr>
<td>from 4 up to 300</td>
<td>Essential and non-essential</td>
<td>Strip, with bushing</td>
<td>Soldering</td>
</tr>
<tr>
<td>400</td>
<td>Ditto</td>
<td>Strip, with tubular bushing</td>
<td>Crimping</td>
</tr>
<tr>
<td>All sections above 2.5</td>
<td>&quot;-&quot;</td>
<td>Pin, with bush sleeve</td>
<td>Soldering, crimping</td>
</tr>
<tr>
<td>All sections</td>
<td>&quot;-&quot;</td>
<td>Pin, from core with wire band or without it</td>
<td>Soldering</td>
</tr>
</tbody>
</table>

10.3.2 During the cable laying all the protective and sealing terminations of cable cores shall be checked. Sealing terminations shall be made by banding from polyvinylchloride strips by plastic terminations or by other means enabling safe closure of cuts of cable sheaths and cuts of core insulation against ingress of moisture inside cable and core.

Protective termination of cores shall be provided for all cores with rubber insulation connected to electrical equipment with significant heat evolution (lighting fixtures and heating appliances, etc.). This termination shall be made by means of covering the cores on the top of insulation with tubes to protect rubber insulation against premature drying up and ageing.

10.3.3 While checking terminations of cables and cores fastening of cable and its inputs in the electrical equipment shall be checked. The RS surveyor shall be sure that cable is secured in such a way that permits to eliminate all mechanical loads from clamps of electrical equipment resulted from tension of cable connected (availability of slacks, fastening of cable with cramps, etc.).
10.4 Bulkhead and deck cable penetrations.

10.4.1 Special attention shall be given to ship bulkhead and deck cable penetrations. The RS surveyor shall be sure that structure of straight cable boxes, group and individual glands, performance of work on filling free spaces of such penetrations with packing compound, glands, sealings, etc. provide proper sealing against ingress of water, vapor, gases and other media from adjacent rooms and spaces and conversely.

10.4.2 Sealing of penetrations and stand pipes for deck cable penetrations shall be also checked. Packing compound shall uniformly fill boxes, stand pipes and other penetration arrangements for cables, have no cracks, cavities, voids and other visible leaks. Penetration boxes and glands in the bulkheads and class A decks shall be covered by proper fire insulation.

10.4.3 Engineering procedure of sealing glands and boxes for cable penetration shall be approved by the Register.

10.4.4 Cables in penetration boxes shall be laid with compactness to ensure proper filling of intercable spaces with cable mass and for cable sheath not to touch walls of penetration box.

10.4.5 Cables coming from penetration cable boxes and glands shall have the required slacks to compensate mechanical loads which may occur during the resilience of hull structures.

10.4.6 Means of checking the tightness of penetration cable boxes, group and individual glands are specified in Appendix 2.

10.4.7 Cable penetrations through expansion connections of hull structures shall have the appropriate slacks (loops) for compensation of bends and twists of the ship’s hull at roughness. When pipes, ducts, wells, etc. are used for cable laying through such connections, these steel structures shall have proper compensators.

10.5 Earthing.

10.5.1 All the earthing arrangements of electrical equipment and hull structures shall be surveyed by visual examination for compliance with the requirements of Part XI “Electrical Equipment” of the Rules for the Classification and Construction.

10.5.2 Earthing of enclosures of electrical equipment shall be checked by means of direct contact with hull structures, with the help of earthing conductors of earthing cores in the power supply cable.

10.5.3 Attention shall be given to the fact that direct contact grounding of the enclosures of equipment to hull structures of the ship shall be performed with proper treatment of contact surfaces and their corrosion protection. Section and material of the earthing conductors shall meet the requirements of the Rules for the Classification and Construction (refer to Table 10.5.3), metal sheath of cables – shields, armature, armors, as well as pipelines, ducts, chutes, metal casings for protection of cables from mechanical damage shall be effectively grounded and the access for inspection and continuous supervision of integrity and reliability of electrical contacts of earthing shall be provided.

10.5.4 Also earthing of rigging, static protection device, earthing of superstructures from light-metal alloys shall be checked by means of inspection of earthing points and measurement of transient resistance, etc.

10.6 Inspection of rooms and spaces of the ship according to the requirements on installation of electrical equipment.

10.6.1 The RS surveyor shall perform external inspection of all the rooms and spaces to make sure that:

1. all the rooms and spaces where people may be located are equipped with proper electric lighting, and lighting fixtures, switches, sockets meet the requirements of the Rules for the Classification and Construction and are installed properly;

2. emergency lighting is available in all rooms and spaces where required by the Rules for the Classification and Construction, there are no individual switches in the emergency lighting circuits, besides lighting fixtures specially mentioned in the Rules for the Classification and Construction;
.3 the power supply of the groups of lighting fixtures in one room where people may be located or are always located is carried out by different group distribution boards and via different circuits;
.4 emergency lighting fixtures are installed in such a way that essential equipment located in the room or on the deck is properly illuminated;
.5 ventilation and heating, where necessary, conform the purpose and ensure normal operation of essential equipment;
.6 in the dangerous rooms and spaces the appropriate explosion-proof equipment is used and there are no transit cable paths or prohibited electrical equipment;

<table>
<thead>
<tr>
<th>Table 10.5.3</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Required sections, earthing cable cores and outer conductors for equipment grounding</strong></td>
</tr>
<tr>
<td>Nos.</td>
</tr>
<tr>
<td>---</td>
</tr>
<tr>
<td>1</td>
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<td>5</td>
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<tr>
<td>6</td>
</tr>
</tbody>
</table>

.7 access to cables laid under the space plating or, at least, to terminal and cable boxes;
.8 plating of spaces, bulkheading, pockets, cabinets, recesses, etc., where electrical equipment is installed, are effectively protected from heating due to heat generation of electrical equipment. When such plating is made of combustible material, they have non-combustible plating at the required distances and areas;
.9 no communication or signaling: general alarm, fire alarm, warning, talk-back, service, command broadcasting, etc. cables are laid through the dangerous spaces (galleys, machinery casing, etc.);
.10 special electric spaces are not adjacent with explosive rooms and spaces are properly equipped by protective grids and other things for prevention of open live parts; they do not include pipelines carrying combustible media, etc.
10.7 The Recommendations do not cover all the checks to be performed by the RS surveyor by external examination because, depending on the ship's type, the checks in larger extent may be required.
11 **Internal examination**
11.1 All electrical equipment subject to survey carried out by the RS surveyor shall be checked by internal examination.
11.2 Internal examination shall not foresee special dismounting of equipment, except the cases when the RS surveyor may have doubts that electrical equipment is in fit technical condition.
11.3 Internal examination shall be performed through opening windows, hatches, covers, manholes in the enclosure of electrical equipment.

11.4 During the internal examination of generators and electrical motors of propulsion plant being the main sources of electrical power, emergency generators the following shall be checked:

1. quality of contacts of electrical connections, termination of cables in terminal boxes, grooming of free cable lengths of terminated cores, which exclude their friction on enclosure or between them;

2. availability of means against self-unfastening on the terminals and contact screws and bolts;

3. condition of grooming and insulation of winding, absence of dents, chip and disruptions of insulation on the front sections of stator, rotor and armature windings;

4. condition of collectors or collecting rings, quality of soldering of armature coil ends to collector solder pads;

5. condition of electrical connections of generator with arrangements and devices of self-oscillation, voltage control system and rotating exciters mounted on the generators;

6. availability and setting of safely fuses in the self-oscillation systems, where equipped.

11.5 Special attention shall be given to electrical machines subjected to assembling on board the ship. For such machines the following shall be checked in addition:

1. fastening of active steel of poles, pole and phase winding;

2. brash gear condition;

3. compliance of air gaps at various positions of armature and rotor, from their both ends and between all stator poles with the values given in the firm (manufacturer) logbook;

4. axial displacement of armature or rotor in friction bearings.

11.6 During the internal examination of switchboards the following shall be checked:

1. fastening of automatic switches, switches, fuses and their electrical connection with busbars and switchboard jumper;

2. listening of switchboards mains, condition of busbar insulators, absence of too small distances between busbars and between busbars, absence of bends and damage of busbars, reliability of intersectional connections of busbars;

3. fastening of cables and wires of switchboard internal mounting; absence of mounting wires contact with bare busbars of different polarity;

4. installation, proper fastening and connection of all switchboard devices; splitting and termination of connecting cables, their fastening to commutation and protective equipment; availability of means against self-unfastening.

11.7 During the internal examination of electrical drives of essential machinery the following shall be checked:

1. connection of power cables to the clamps of electrical motors and laying of free lengths in the terminal boxes, starters, remote control panels;

2. reliability of contact terminations and availability of means against self-unfastening;

3. reliability of fastening of contactors, relays of thermal protection, resistors and other components in solenoid starters.
RECOMMENDATIONS ON TESTING FOR TIGHTNESS OF CABLE PENETRATIONS AND PIPES

1. Respective test procedures on cable penetration boxes and glands may be used at the discretion of the RS surveyor.

2. Once group glands, cable penetration boxes, group and individual glands are sealed and externally examined testing shall be performed in accordance with one of the procedures listed below.

Procedure 1. The space through which the cables are run is flooded, whereas on the other side of the bulkhead the structures intended to seal cable penetrations are visually examined to detect water seepage through them. This procedure is used in respect of special category spaces, subject to flooding during normal operation of ship. Duration of the test shall be specified in a test program.

Procedure 2. The doors and scuttles in spaces through which the cables are run shall be closed and an increased pressure of approximately $3 \times 10^4$ Pa shall be built up. The evidence for passing of air through sealing structures is provided by the drop in pressure as shown by the pressure gauge indicating the space pressure. The same result can be obtained by visual examination of cable penetrations covered with soapy liquid solution. This procedure is used in boiler rooms with forced general blowing and a number of other gastight spaces. Duration of the test shall be specified in a test program.

Procedure 3. The sealing structures of cable penetrations are subjected to a jet of compressed water $20 \times 10^4$ Pa. The water is discharged at a 5 m distance over 5 min. The opposite side of sealing structures is being visually examined for the signs of water. This procedure is used to test the sealing arrangements located on the upper decks.

Procedure 4. The sealing structures of cable penetrations are subjected to compressed air blasting from a hose with a diameter not less than 12,5 mm with a pressure of $30 - 40 \times 10^4$ Pa at a 100 mm distance. Passing of air through the sealing structures is determined by visual examination of cable penetrations covered with soapy liquid solution. This procedure is used to check the sealing arrangements located in service and accommodation spaces which can not be tested using the above three procedures.

3. The quality of sealing is considered satisfactory where no passing of air or water is observed in cable penetrations through bulkheads and decks or inside electrical equipment.

4. The RS surveyor may consider and approve other test procedures proposed by the shipyard where their efficiency is not inferior to that of the above procedures.

5. Where sealing epoxy compounds with complete polymerization within 6 – 8 days are used, the tightness quality test shall be performed as a minimum within 2 days after sealing.

6. A pipe with a cable for safe-type electrical equipment is leak tested by air pressure with $15 \times 10^4$ Pa and soapy liquid solution test of all screw and flange joints.
RECOMMENDATIONS ON MEASUREMENT OF ELECTRICAL EQUIPMENT
INSULATION RESISTANCE DURING CONSTRUCTION OF SHIP

1. Insulation resistance condition of shipborne electrical equipment and cabling characterizes to a great degree the technical intactness of ship's electrical installation on the whole and separate types of equipment and allows to decide on the possibility of their further use according to their direct purpose.

2. Insulation resistance shall be measured after the external visual examination of electrical equipment and before it is put under load or voltage. Where the insulation resistance complies with the Table, electrical equipment may be subjected to further testing.

Where the insulation resistance values are below those specified, measures shall be taken to eliminate prohibitive leakages.

### Table

Minimum values for insulation resistance between poles (phases) and to ship's hull for plants with rated voltage up to 500 V

<table>
<thead>
<tr>
<th>Nos</th>
<th>Electrical equipment</th>
<th>Insulation resistance $R_{1}$ at ambient temperature 20±5 °C and normal humidity, in MOhm</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Electrical machine</td>
<td>1.0</td>
</tr>
<tr>
<td>2</td>
<td>Transformers:</td>
<td></td>
</tr>
<tr>
<td>.1</td>
<td>with power up to 100 kW (kV·A):</td>
<td></td>
</tr>
<tr>
<td></td>
<td>in hot condition</td>
<td>2.0</td>
</tr>
<tr>
<td></td>
<td>in cold condition</td>
<td>5.0</td>
</tr>
<tr>
<td>.2</td>
<td>with power 100 up to 1000 kW (kV·A):</td>
<td></td>
</tr>
<tr>
<td></td>
<td>in hot condition</td>
<td>1.0</td>
</tr>
<tr>
<td></td>
<td>in cold condition</td>
<td>3.0</td>
</tr>
<tr>
<td>.3</td>
<td>with power more than 1000 kW (kV·A) or with voltage more than 500V in hot condition</td>
<td>$R^2$</td>
</tr>
<tr>
<td>3</td>
<td>Switchboards</td>
<td>1.0</td>
</tr>
<tr>
<td>4</td>
<td>Switch gear, protective and starting devices (automatic devices, starters, contactors)</td>
<td>5.0</td>
</tr>
<tr>
<td>5</td>
<td>Telegraphs and indicators, telephone switchboards, telephones, bells etc.</td>
<td>20.0</td>
</tr>
<tr>
<td>6</td>
<td>Cooking and heating appliances</td>
<td>1.0</td>
</tr>
<tr>
<td>7</td>
<td>Semiconductor converters</td>
<td>10.0</td>
</tr>
<tr>
<td>8</td>
<td>Power and lighting feeders, cabling for group telephones, telegraphs, bells and other types of direct-current alarm systems</td>
<td>1.0$^3$</td>
</tr>
</tbody>
</table>

1. For voltage more than 500 V the insulation resistance shall be:
   - for item 1: $(U_n/100) + 1$;
   - for items 2-8: $-2000 \text{ Ohm per every V of rated voltage}$.

2. Insulation resistance is determined by the following formula $R = \frac{3v}{p+2000}$
   where $v$ = rated resistance of winding (phase), in V;
   $p$ = rated power, in kW (kV·A).

3. For voltage less than 24 V the insulation resistance shall not be less than 0,3 MOhm, for alternating-current voltage insulation resistance shall be 1,4 times higher than that for direct-current voltage.

Note. Lightning discharger (between mast top and point of down conductors connection to the metal hull or earthing point on the shell plating of a wooden or composite ship) electric connections to the earth termination networks and superstructures made of light alloys to the steel hull shall have resistance not less than 0.02 Ohm.

3. Insulation resistance of substantially heated electrical equipment (electrical machines, cooking and heating appliances, transformers, reactors, ballast resistors etc.) shall be measured immediately after deactivating at steadystate temperature reached during operation under rated load.
4. Insulation resistance of each type of shipborne electrical equipment and of every set of such equipment shall be measured across the terminals of the input and output circuits of each unit, device etc. either part of a set or installed individually. Feeding and connecting cables shall be disconnected.

5. Insulation resistance of all supply feeders for essential and non-essential fixed equipment installed between the switchboard and the consumer or its starting device and between the source and the switchboard shall be measured.

During this measurement supply feeders shall be disconnected from the terminals of consumers and switchgear and protective devices of the switchboards, or such equipment may alternatively be in the "open" position or removed from the switchboard.

6. During insulation resistance measurement of feeders, lighting cables, communications cables, alarm cables, control cables etc., lamps, telephones and other equipment shall be disconnected, or pole-to-pole and phase-to-phase connection circuit units shall be removed from either end of cables for these devices.

7. Insulation resistance of main, section, distribution and other switchboards shall be measured with automatic circuit breakers disconnected, fuses removed, voltage coils disconnected etc.

8. Insulation resistance shall be measured:
   .1 between input and output circuit phase or pole terminals and metal hull or metal parts of electrical equipment;
   .2 between every insulated busbar of the switchboard, busbar system and the hull;
   .3 between busbars of different polars or phases, and also between junction terminals or conductors of coils, reactors, current transformers, main contacts of automatic circuit breakers and other switchgear and the hull;
   .4 between every insulated cable conductors and the hull and between conductors of different poles, phases.

9. Insulation resistance measurement shall be performed with the use of generator type megohmmeter exerting not less than 500 V direct-current voltage. It is allowed to use measuring devices for voltage not less than 100 V with regard to equipment intended for operation with safely voltage (up to 50 V).

10. The measurement of insulation resistance value shall be performed as a minimum within 1 min after test voltage application.

11. During insulation resistance measurement of electric circuits with incorporated electric capacitors with total capacity of more than 2 microfarad, meters and testers operating with constant voltage shall be used or capacitors shall be disconnected.

12. Minimum permissible values of shipborne electrical equipment insulation resistance are given in the Table.

13. The efficiency of electrical equipment enclosure earthing shall be checked along with insulation resistance measurements. The measurements shall be made between the enclosure of electrical equipment, cable braid or armour, cable earthing conductor, earthing socket outlet etc. and the hull. Earthing resistance value shall not exceed, in Ohm:
   for earthing core in the feeding cable – 0,4;
   for earthing with external earthing conductors – 0,1.

14. It is allowed to perform insulation resistance measurement of equipment, cables constituting the circuit and system cables either separately or as a whole with the use of switchboard insulation resistance measuring devices located on the generator or distribution panel of main or emergency switchboard.
RECOMMENDATIONS ON PERFORMANCE
OF MOORING TRIALS OF ELECTRICAL EQUIPMENT

1. Tests of electric propulsion system

1.1 Prior to the beginning of mooring trials, the check of the electric propulsion plant shall be carried out including inspections of:

1.1.1 propulsion plant generators;
1.1.2 exciter sets including static devices of generators and electric motors excitation;
1.1.3 switchboards and control panels;
1.1.4 electric drives of essential machinery;
1.1.5 alarm, interlock and protection devices.

1.2 Once the RS surveyor has made sure that the technical condition of the equipment is satisfactory, and checks and measurements conducted according to the Recommendations (refer to Appendix 1) have not revealed the discordance with the requirements of the Rules for the Classification and Construction and technical documentation of the ship's design, and the additional checks according to 10.4.2.4.2 – 10.4.2.4.4 have demonstrated the satisfactory results, the preoperational checks in the scope specified in 10.4.2.5 shall be carried out.

1.3 Thereafter the electric propulsion plant is started and tested according to 10.4.2.6.

1.4 In starting the electric propulsion plant, the following shall be ascertained:

1.4.1 the main current circuit is designed and consistent with all the required modes of electric propulsion system operation including the mode at the heaviest characteristic of mooring conditions;
1.4.2 loads of driving motors, generators and propulsion motors in all modes of operation including the mode at the transition from the characteristic "open water" to the one "mooring conditions" are within tolerable limits;
1.4.3 the maximum locked-rotor current of propulsion motors, the allowed time under stalling conditions, as well as the locked-rotor torque do not produce an adverse effect on the electric propulsion system;
1.4.4 systems of generators and motors excitation, main changeovers of main current circuits, feedbacks on electric propulsion system current and voltage regulation function properly;
1.4.5 the following interlocks are provided in the devices, blocks or control stations which:
    prevent potential changeovers in main current and field circuits during plant operation;
    prevent the changeover of control stations and the start of propulsion motors from any position, but "stop";
    prevent the start of a propulsion motor with the shaft-turning gear engaged and conflicting operator intervention on the electric propulsion plant operation;
    provide correct drive redundancy and its restart after emergency shutdown;
    provision is made for the signalling system indicating the position of selective switches, of switches of control stations and exciters, the opening and closing of doors of electric propulsion plant switchboards, as well as the presence of water in the cooling system of generators and propulsion motors, the temperature rise of bearings, cooling air, etc. evidencing the break in operation of equipment for electric propulsion plant.

Red lamp signals switching-on shall be supplemented with a sound signal;

1.6 arrangements preventing potential hazards for propulsion motors, generators and prime motors are ensured in the protection circuits provided. Regulators of electric propulsion system provide for: the limitation of current to the rated value under normal operational conditions, the limitation of torque in locking the propulsion shaft, the maintenance of a certain
propulsion motors speed, the limitation of transient processes in starting, braking and reversing, the limitation of reverse power in propeller braking, etc.;
.7 the quick-acting electrical protection against overloads and overvoltage of semiconductor converters, rectifiers, etc. for electric propulsion systems of the dual-type current is provided and operates properly;
.8 a forced-feed lubrication system for machines of the electric propulsion plant is served with one of the two lubricating pumps fitted and a gravity tank in case of the lack of electrical power;
.9 provision is made for at least two cooling pumps in the cooling system of propulsion motors and generators of the electric propulsion plant, which may be switched to separate air coolers of the machines;
.10 monitors of the operator stations correctly display and record possible configurations of the electric propulsion plant modes of operation selected by the electric propulsion plant control system depending on a system component (transformer, rectifier, inverter, etc.) failure;
.11 measures are provided to prevent in one operation the command execution that may enable potentially dangerous working conditions of the equipment.
1.5 All the checks and measurements needed to determine the characteristics specified in 1.4 of this Appendix shall be performed with use of measuring devices being part of the electric propulsion plant as well as by means of other devices not related to the plant.
1.6 Other checks relating to switchgear, the electric protection of generators and electric motors, to the cable network, control panels, etc. are identical to the checks applied to ship's electrical installations (refer to Section 2 of this Appendix).
1.7 The insulation resistance of the entire electrical equipment of the electric propulsion plant specified in 10.4.2.5.1 shall be measured in accordance with Appendix 3, and the d.c. machines commutation performance is checked as per Appendix 5.

2 Test of ship's electric power plant
2.1 Prior to the beginning of mooring trials, the check of the ship's electrical installation shall be carried out including inspections of the following:
.1 main and emergency sources of electrical power, i.e. main generators, emergency generators and accumulator batteries;
.2 electric power converters, i.e. transformers, rotating and static converters;
.3 switchgear, i.e. main and emergency switchboards, remote and local control panels for electrical equipment, control gear, etc.;
.4 electrical drives of essential machinery;
.5 main and emergency lighting, navigation lights;
.6 all systems of intercommunications and alarm;
.7 heating and cooking appliances;
.8 cable network;
.9 earthing devices of all the types and purposes.
2.2 Once the RS surveyor has made sure that the technical condition of the electrical equipment is satisfactory, and checks and measurements conducted according to the Recommendations (refer to Appendix 1) have not revealed the discordance with the requirements of the Rules for the Classification and Construction and technical documentation of the ship's design, and the additional checks according to 10.4.2.4–10.4.2.6, if these are needed for the ship's electrical insulation, have demonstrated the satisfactory results, the tests and checks in the scope specified in 10.4.2.7 shall be carried out.
2.3 Prior to the performance of tests and checks specified in 2.2 of this Appendix, the insulation resistance of each type and piece of the electrical equipment under test shall be measured. These measurements shall be performed in accordance with Appendix 3.
2.4 The check of electrical starting for main generators is carried out as follows:
.1 where the movers of main generators are fitted with electrical starting devices, the start of the generator (generators) prime mover by means of the electrical starting device shall be made after measuring the insulation resistance of generators and the main switchboard or its generator panels;
.2 prior to the start, the condition of a starter accumulator battery (batteries), the density and level of electrolyte, voltage shall be determined;
.3 prime movers shall be cold-started both from local and remote starting panels;
.4 each prime mover of a generator shall be started at least six times on the type ship and at least three times on series-built ships. In so doing, the first three starts may follow one after another in 1 min to 1.5 min, the follow-up ones may be staggered in time within 30 min;
.5 after starting prime movers of all generators with use of the electric starter, the voltage of the starter accumulator battery and the electrolyte density shall be measured. The battery voltage therewith shall correspond to 0.9 of the rated one;
.6 when other additional essential consumers (lighting, alarms, etc.) are supplied from the starter accumulator battery, after all the starts of movers the battery voltage shall remain nominal and additional battery-supplied consumers shall properly operate within the set time.

2.5 Generators check.
2.5.1 After starting and setting the rated values of each generator parameters, the following shall be determined:
.1 limits of voltage variations in regulating the generator excitation with use of automatic or manual regulators at the loading of 50 % of the generator rating, from the formula

\[ \Delta U = \frac{U_{\text{max(min)}} - U_n}{U_n} \cdot 100\%; \]  
(2.5.1.1)

.2 limits of speed variations in the manual action on the prime mover regulator at the loading of 50 % of the generator rating, from the formulae:

\[ \Delta f = \frac{f_{\text{max(min)}} - f_n}{f_n} \cdot 100\%; \]  
(2.5.1.2-1)  
\[ \Delta n = \frac{n_{\text{max(min)}} - n_n}{n_n} \cdot 100\%. \]  
(2.5.1.2-2)

2.5.2 Voltage and frequency time variations arising in transient modes of drives operation shall be such that the normal operation of all essential consumers supplied from these generators may remain intact and deviation values may not exceed those specified in 10.6 and 10.7, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

2.5.3 The field killing device shall be checked three times according to its direct functions. The process of field killing shall be monitored by a standard voltmeter. In so doing, attention shall be given to the stability of initial generator excitation and to switchgear and alarms operation.

2.5.4 When the generator runs in the nominal mode, the functioning of its control equipment at all types of control (local, remote, manual and automatic) shall be checked, the voltage of the generator and exciter (if any), armature (stator) current, field current, speeds, active power, power factor (to be computed if a measuring device is lacking) shall be measured. The power factor shall not differ from the rated value for more than by ± 5 %.

2.5.5 The bearings temperature shall be measured at the end of a mode. Measurements shall be carried out with use of thermometers and thermocouples. After the continuous running of a machine (till a steady-state temperature), the bearings temperature shall not exceed:
  for plain bearings – 80 °C;
  for rolling bearings – 100 °C.
2.5.6 If needed, the axial displacement of an armature or a rotor shall be checked after the stop of the machine with plain bearings in order to determine axial loads on the latter.

2.5.7 For the check specified in 2.5.6, the bearing cover and top shell shall be removed, the shaft position relating to bearing projections shall be noted and a pointer-type indicator for determining a potential shaft displacement shall be fitted at the rear face of the shaft. Following the bearing assembly and the start of the generator mover, the limits of displacements, which shall be within the range determined with the indicator for the inoperative machine, shall be checked by indicator readings. Dynamic measurements shall be performed at various loadings. If the axial shaft displacement revealed in checking is such that shaft shoulders are carried by the bearing shell, the machine shall be stopped to rectify a fault. Permissible standards of the axial displacement are given in Table 1 of Appendix 6.

2.5.8 If water coolers are used, the functioning of a flow relay shall be checked by the temporary suspension of water circulation.

2.5.9 For every electrical machine, to be measured is a temperature of:

- 0.1 cooling medium at the machine inlet and outlet;
- 0.2 stator windings;
- 0.3 an armature or a rotor;
- 0.4 a commutator or contact rings.

All these measurements shall be performed with thermometers or thermocouples (refer to 2.5.9.2 and 2.5.9.3) if embedded temperature sensors are provided in the machine design.

2.5.10 Generators shall be tested for sudden loading and unloading being 70 and 100 % of the generator rating respectively.

For the complete set of main sources according to 2.5.19.1, such tests shall be applied to each generator, and according to 2.5.19.2, to generators running in parallel. In this case, the value of the loading carried shall be at least 70 % of the total rated power of running generators.

For the complete set according to 2.5.19.3, such tests for generators driven by main engines are not needed.

Sudden loading of the generator(s) at the level of 70 % of the generators rating shall be carried out for completely-unloaded generators preset for the rated voltage, frequency and speed.

2.5.11 When the parallel running of generators is not provided at zero or very small loads, the 70 % loading for generators running in parallel shall be carried out at the lowest loading possible for the stable operation of generators, but not more than 20 % of the total rated power of generators.

2.5.12 After loading and the recovery of the mode of the generator set, the generators shall be loaded up to 100 % of the rated power and then suddenly to be completely unloaded or down to the initial loading (refer to 2.5.11) of running in parallel generators.

2.5.13 The results of tests according to 2.5.10 – 2.5.12 shall be consistent with the requirements of 2.11.3.1 – 2.11.3.4 and 2.11.4, Part IX "Machinery" of the Rules for the Classification and Construction. The tests may be performed with the parameters of a suddenly-applied load equal to 50 % of the rated one with the follow-up application of the remaining 50 % load.

2.5.14 In prototype ships, and in ships of a series if needed, the start from generators of the largest electric motor fitted in the ship and having the most severe starting conditions shall be checked.

2.5.15 Such a start of the largest electric motor shall be performed at least two times at the following initial conditions:

- 0.1 generators) runs at 25 – 30 % of the rated power;
- 0.2 (generators) runs at 65 – 70 % of the rated power.

The above checks shall be conducted simultaneously with those specified in 2.5.19 and under all the conditions specified therein.
2.5.16 In the tests specified in 2.5.14 – 2.5.15, any failures in systems supplying the consumers connected, any protection actuations, continuous drastic drops of voltage and speed, changes of switching positions of control equipment, etc. are inadmissible.

2.5.17 In the tests specified in 2.5.10 – 2.5.15, oscillography shall be used in prototype ships for transient processes. Oscillograms shall evidence that variations of single parameters, voltage, current strength, speed, time characteristics of recovery, system damping, new steady-state modes, etc. are within the tolerable limits and consistent with the Rules for the Classification and Construction.

2.5.18 All the synchronization devices shall be tested in operation (synchronizing lamps, synchroscopes, frequency meters, phase meters, speed regulators, etc.) for determining an opportunity of the following:

.1 synchronizing and starting the generator for running in parallel when the operating generator is under the load corresponding to the rated power of the smallest generator, as well as of switching the load to each installed generator with the remote and local control from all the stations on board the ship;

.2 synchronization and steady operation of all the generators fitted in the ship in parallel connection one to another and to the land-based network (if provided) within the time needed to switch the load between generators and to the land-based network and back;

.3 synchronization and steady operation of the generator driven by the main engine with the one having the independent prime mover within the time of load switching;

.3 synchronization and steady operation of the shaft generator, driven by the main engine, directly with the generator having the independent prime mover within the time of load switching;

.4 synchronization and steady operation of the generator, having the independent prime mover, with reversible frequency converter (e.g. semiconductor frequency converter of the shaft generator supplying the ship mains);

.5 checking the possibility of manual synchronization of the generators installed by an operator.

2.5.19 The sufficiency of unit and aggregate power of main generators shall be determined by one of the following ways:

.1 if only two generators are fitted, the most powerful one shall be rendered inoperative and the other running generator shall be loaded to its maximum corresponding to the most severe mode specified: running, manoeuvring or emergency. Loading conditions are established with use of the loading table submitted by the ship's designer. Loading devices shall be used when the load required for the generator cannot be provided by ship's services at the time of mooring trials. Water rheostats and, for synchronous generators, special devices providing loading with a calculated weighted mean power factor, may be used as such devices for d.c. generators by the special agreement with the RS surveyor;

.2 if more than two generators are fitted, the most powerful one also shall be disabled and the rest shall run in parallel and be loaded to its maximum according to 2.5.18.1 of this Appendix;

.3 if one of the generators installed is driven by the main engine, the former shall carry the full loading of all the consumers used in operating conditions. This requirement also covers the generators of which prime movers are turbines operating from exhaust-heat boilers. The remaining one or more generators fitted in the ship and having independent prime movers in separate or parallel running respectively shall be loaded at its maximum under the most severe conditions as specified in 2.5.19.1 of this Appendix.

2.5.20 During the tests specified in 2.5.19 single generator operation and operation in-parallel shall be provided, accordingly, without overloading with the rated voltage (and frequency) kept stable. The total or unit load of generators which in all the cases specified in 2.5.19 shall not exceed 100 % of the rated power of one or more running generators shall also be determined. These loads desirably shall not exceed 80 – 85 % of the relevant generator ratings, i.e.
\[ P \leq 0,85 \Sigma P_g \]

where \( P \) = power of all types of loads determined by the loading table in the most severe conditions; \( P_g \) = aggregate power of all running generators.

2.5.21 The load distribution shall be checked in both type and ships a of a series:

.1 between main generators when only two are fitted, each being capable to supply all the ship’s services, and when their parallel operation is provided either for improved reliability (navigation in narrow waters, special manoeuvring, prevention of incidents) or for load switching;

.2 between main generators when more than two are fitted with one of the most powerful generators disabled. In this case, the load sharing shall be checked between any generators running in parallel of which one is disabled in turn;

.3 between generators with independent prime movers and directly between the generators (shaft generators) driven by main engines, as well as between turbine generators and diesel generators if such modes of main generators operation are provided for continuous or short-time running;

.4 between generators with independent prime movers and reversible frequency converters of the shaft generators driven by main engines.

2.5.22 In all the ships with the main generators intended for running in parallel including the cases in 2.5.21, the parallel running of generators shall be checked so that the RS surveyor may make sure that:

.1 machines are properly balanced and inadmissible vibrations are prevented. If needed, the vibration frequency and amplitude shall be determined with use of the relevant devices;

.2 the speed regularity of running generators is maintained, the speed swing between generators and arbitrary redistribution of loading are lacking. Such a check shall be performed with use of electric measuring instruments;

.3 the static stability of generators and the uniform sharing of loading are maintained in parallel running.

2.5.23 The uniformity of loading sharing shall be checked in the variation of the total loading at, as a minimum 25, 60, 85 and 100 % of the running generators rating. In this check, loading shall supplemented with its removal.

The limits of nonuniformity in dividing active and reactive loads without the manual regulation of running generators shall be set.

2.5.24 The nonuniformity in dividing active and reactive loading between generators shall be determined from the formula

\[ P = \left( \frac{p}{p_r} - \frac{\Sigma p}{\Sigma p_r} \right) \times 100 \% \]  

(2.5.24)

where \( p \) = given generator loading, in kW;
\( p_r \) = given generator rated power, in kW;
\( \Sigma p \) = aggregate loading on all generators running in parallel, in kW;
\( \Sigma p_r \) = aggregate rated power of all generators running in parallel, in kW.

\[ P = \left( \frac{p_{13}}{p_{n1}} - \frac{p_{13} + p_{23}}{p_{n1} + p_{n2}} \right) \times 100 \% \]
The nonuniformity of reactive load distribution between generators shall be determined by the formula

\[
Q = \frac{Q/Q_r - \Sigma Q/\Sigma Q_r}{} \times 100 \%
\]  

(2.5.25-1)

where 

- \( Q \) = reactive load on a given generator, in kWA;
- \( Q_r \) = rated reactive power of a given generator, in kWA;
- \( \Sigma Q \) = aggregate reactive load on all generators running in parallel, in kWA;
- \( \Sigma Q_r \) = aggregate rated reactive power of all generators running in parallel, in kWA.

The reactive power is determined by the formula

\[
Q = P \tan \varphi.
\]  

(2.5.25-2)

2.5.26 All calculations shall be performed by the shipyard’s personnel and presented to the RS surveyor at his request.

2.5.27 If one of the ship’s specified generators or additional generator is automatically started and connected to the main switchboard busbars, the one shall be checked and tested in the presence of the RS surveyor. The checks and tests shall demonstrate the following:

.1 the generator is automatically started and connected to the main switchboard busbars in overloading or with the voltage collapse across busbars.

For this check, the voltage across the main switchboard busbars shall be reduced down to 70% of the rated one or the prime mover of the running generator shall be stopped. A circuit breaker in both cases shall cut out the running generator of the main switchboard busbars.

After the automatic cutting-out of the running generator of the busbars, the standby generator shall be automatically started in about 2 s and on reaching 98% of the rated voltage be connected to the main switchboard busbars. The total time shall be within 45 s;

.2 loading of the running generators is brought up to 105 – 110% of the rated one using ship’s consumers or loading devices, and the time of starting, synchronizing and taking the load by the standby generator, which shall not exceed the one specified in 2.5.27.1, is monitored.

2.5.28 Tests of valve-type generator sets.

2.5.28.1 All electrical equipment being part of a valve-type generator (generator, semiconductor converter, control systems, etc.) shall be tested in compliance with the valid requirements in Sections 10 and 12, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

The valve-type generator set driving motor shall be tested in compliance with Section 5, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

Example of calculation

<table>
<thead>
<tr>
<th>Aggregate load of electric power plant, in %</th>
<th>Generator loading</th>
</tr>
</thead>
<tbody>
<tr>
<td>25</td>
<td>( p_{21} )</td>
</tr>
<tr>
<td>60</td>
<td>( p_{12} )</td>
</tr>
<tr>
<td>85</td>
<td>( p_{13} )</td>
</tr>
<tr>
<td>100</td>
<td>( p_{14} )</td>
</tr>
<tr>
<td>85</td>
<td>( p_{15} )</td>
</tr>
<tr>
<td>60</td>
<td>( p_{16} )</td>
</tr>
<tr>
<td>25</td>
<td>( p_{17} )</td>
</tr>
</tbody>
</table>
2.5.28.2 As regards the valve-type generator sets, the functional integrated tests shall be conducted of the driving motor, generator, semiconductor converter, prime mover speed regulator, generator voltage regulator, semiconductor converter voltage regulator and control system. The functional integrated tests of the valve-type generator sets may be conducted during sea trials. In addition to the tests prescribed for the generators by 2.5.1–2.5.27, the following shall be checked:

.1 absence of mechanical resonance across the operating speed variation range of the valve-type generator set across the entire range specified by the manufacturer, or else the near resonance frequencies shall be excluded from the rotational speed control law;

.2 continuous (hereinafter, in compliance with GOST 18311-80) single valve-type generator running at no load (minimum permissible load) at the minimum speed;

.3 continuous single valve-type generator running at 100 and 110 % load at the rated speed;

.4 continuous single valve-type generator running across the entire speed range specified by the manufacturer at the load prescribed for the relevant speed;

.5 continuous single valve-type generator running via bypass circuit allowing to connect the generator to the switchboard directly, not via the semiconductor converter, if required by design, across the load variation range specified for this operating mode;

.6 start of the most powerful consumer fed from the valve-type generator at the rated and minimum speed;

.7 start of the most powerful consumer fed from the valve-type generator set connected via bypass circuit allowing to connect the generator to the switchboard directly, not via the semiconductor converter, at the rated speed.

2.5.28.3 During the functional integrated tests, the following shall be performed:

.1 electrical parameters monitoring both at the converter output and in electrical circuits connecting the converter and the generator;

.2 oscillography for the steady-state and transient processes;

.3 functional integrated tests of the valve-type generator sets shall be conducted upon installation of all the valvetype generator set equipment onboard the ship;

.4 generators shall be tested together with the semiconductor converter and other converter components across the entire speed range. The tests shall be conducted in all intended operating modes, including motor operation of the valve-type generator, if required by design;

.5 when the generator is connected via bypass circuit to the switchboard directly, not via the semiconductor converter, the generator shall be additionally tested at the rated speed across the entire load range specified for this mode;

.6 as regards the valve-type generator set based on the synchronous generators with permanent magnets not capable of field suppression, the measures shall be provided for rapid deceleration of the generator shaft in case of inner short circuits in the generator or semiconductor converter, or other additional measures for field suppression or emergency localization shall be provided;

.7 semiconductor converters shall be tested together with the generators and other valve-type generator devices across the entire speed range;

.8 test shall be conducted in all intended operating modes, including motor operation of the valve-type generator, if required by design;

.9 when for operation of the valve-type generator semiconductor converter the reactive power source (synchronous condenser) is required, then this source with the required characteristics shall be installed and connected to the mains during the valve-type generator set tests;

.10 when during the valve-type generator set operation an additional device (harmonics filter) is required for reducing the total harmonic distortion \( K_n \) in the ship's mains, then this device with the required characteristics shall be installed and connected to the mains during the valve-type generator set tests;

.11 in case of bypass circuit connection, transfer from bypass circuit to semiconductor converter operation and vice versa shall be checked;
.12 when start of the prime mover of the valve-type generator set using power generated by other mains power sources and then switching into the generator mode are required, then this start shall be checked during sea trials with complete power system. In this case, the parameters of power supply in the ship mains shall comply with the requirements in 2.1.3, Part XI "Electrical Equipment" of the Rules for the Classification and Construction;

.13 when operation of the valve-type generator being part of the shaft generator is required in motor operation mode for the ship moving, then this mode shall be checked during sea trials separately or together with the main engine based on the accepted algorithm of operation.

2.5.28.4 During tests of the valve-type generator set the following shall be measured:

.1 for alternating-current valve-type generators:
  .1.1 generator current in each phase;
  .1.2 converter output current in each phase;
  .1.3 generator line voltages;
  .1.4 line voltages at the generator output;
  .1.5 frequency at the generator output;
  .1.6 frequency at the converter output;
  .1.7 power at the generator output;
  .1.8 power at the converter output;
  .1.9 generator speed;
  .1.10 generator excitation current (if excitation system is available);
  .1.11 total harmonic distortion $K_u$ at the converter input and output;
  .1.12 generator bearings temperature;
  .1.13 generator winding temperature (if sensors are available);
  .1.14 converter power elements temperature (if sensors are available);

.2 for direct-current valve-type generators with alternating-current generator:
  .2.1 generator current in each phase;
  .2.2 current at the converter output;
  .2.3 generator line voltages;
  .2.4 direct-current voltage at the converter output;
  .2.5 frequency at the generator output;
  .2.6 power at the generator output;
  .2.7 power at the converter output;
  .2.8 generator speed;
  .2.9 rectified voltage ripple factor;
  .2.10 total harmonic distortion $K_u$ at the converter input;
  .2.11 generator bearings temperature;
  .2.12 generator winding temperature (if sensors are available);
  .2.13 converter load-bearing element temperature (if sensors are available).

2.6 Check of emergency source of electrical power.

2.6.1 The emergency source of electrical power shall be tested to confirm its adequacy and operation reliability in the collapse of voltage across the main switchboard busbars, namely:

.1 sufficiency of the emergency source of electrical power to supply consumers during the set time as specified in 9.3 and 20.1.2, Part XI "Electrical Equipment" of the Rules for the Classification and Construction shall be ascertained;

.2 where the emergency source is an accumulator battery, then after its examination (refer to 2.1 of this Appendix) all the emergency services shall be connected to it in accordance with the loading table and the fully loaded battery shall be tested until its voltage drops to 0.88 of the rated one.

The test results are recognized satisfactory if the loading duration therewith is not inferior to that set in the Rules for the Classification and Construction;
.3 where the emergency source is a generator, it shall be tested by the maximum possible load corresponding to all the emergency services within the whole design time of its operation;

.4 the accumulator battery being the transient emergency source of electrical power shall be tested for supply of the specified consumers within half an hour. Following that time period, the battery voltage shall be at least 0.88 of the rated one;

.5 the accumulator batteries voltage shall be measured with the consumers connected.

2.6.2 In checking, the electrical start of the emergency generator shall be tested at least six times with use of both an automatic device and a local start from a starter battery.

The local electric start of the emergency generator shall be checked in accordance with the provisions in 2.4 of this Appendix.

The automatic start of the emergency generator shall be checked by deenergizing the main switchboard busbars. It is recommended that the total time since the voltage collapse across the main switchboard busbars until the closing of the circuit breaker of the emergency switchboard and taking the load does not exceed 45 s.

2.6.3 If the accumulator battery is used as the emergency source, its instantaneous connecting to the emergency switchboard after deenergizing shall be checked.

Such a check shall also be performed for the accumulator battery being the transient emergency source of electrical power.

2.6.4 In checking, the requirements on the automatic instantaneous closing of emergency consumers of the accumulator batteries specified in 2.6.3 with the voltage drop across the busbars of the main or emergency switchboards down to 60% of the rated one shall be met.

Such a check shall be performed by reduction of a prime movers speed or by another approved way.

2.7 Check of transformers, converters, rectifiers and other devices of electric power conversion.

2.7.1 The adequacy of power of a transformer or transformers being operative, while the most powerful one fitted in the ship is disconnected, shall be checked. This check shall be performed by closing all the services supplied from transformers and by determining the actual load of the operative transformer or transformers. The reliability of maintaining the transformer output voltage at tolerable variations of generators voltage and frequency also shall be checked.

2.7.2 When emergency services are supplied from the transformer supplied from the emergency switchboard, the check according to 2.7.1 shall be performed for such a transformer as well.

2.7.3 An opportunity to supply essential emergency services both from the transformer supplied by the main generators and from the transformer supplied by the emergency generator shall be checked. This check shall be carried out by the relevant switching and alternate supply of services from both transformers.

2.7.4 The connection of transformers to the main and emergency switchboard busbars, the availability of the necessary switchgear in primary and secondary circuits, of protection equipment and its rating, measuring instruments, etc. shall be checked simultaneously with the above checks of transformers. If oil transformers are used, the availability of pans, expansion devices, etc. shall be checked.

---

1 The duration of emergency generator testing may be reduced with the steady and reliable operation under the load, but in all cases it shall be at least 1/3 of the time the emergency generator operation is designed for. At that the fuel consumption of the diesel generator shall correspond to the passport data, and there shall be enough fuel in the fuel tank of the diesel generator to provide uninterrupted operation of the generator during design time of its operation at the design load, considering the "dead" fuel under adverse conditions of the ship's heel and trim.
2.7.5 In cases, other than those recommended for ship’s electrical plants, when the transformers fitted may operate in parallel, to be checked are switching and protective equipment, and the load sharing between transformers which shall be within the tolerable limits specified for generators running in parallel.

2.7.6 The uniformity of load sharing between single transformer phases at all potential loads of 25 – 100 % of the rated power, if the latter provided by the consumers fitted in the ship, shall be checked. Such a check shall be carried out by phasewise measurements of current with instruments of the main and emergency switchboards.

2.7.7 Rotating converters shall be tested in combination with panels for control, feed and distribution of electric power from converters and in all the loading conditions specified for converters. In testing shall be checked:

.1 accuracy of output parameters, maintenance;
.2 functioning of the speed and voltage regulation system in a sudden change of loading;
.3 functioning of controls, switch-on and switch-off elements of the converter both at local and remote control panels;
.4 functioning of the automatic switching of converter supply, the parallel operation of converters and load sharing between them if appropriate devices and modes are provided.

2.7.8 The static stability of rotating converters operating in parallel shall be determined at total loadings within 25 – 200 % of the output power rating of converters. The uniformity of load sharing in this test shall be checked.

2.7.9 Static converters (including semiconductor ones) shall be checked under load. In this case, input and output parameters, an accuracy of their maintenance and the tolerable limits of their deviations from the rated values shall be monitored.

An impact of static converter operation in the load mode, and of reversible semiconductor frequency converter – in the regenerative modes as well as in the reactive power compensation mode (if provided for by the design), on the distortion of the shape of a curve of voltage in the ship’s electrical network shall be ascertained in the prototype ship.

2.7.10 The functioning of rectifiers, charging devices, inverters, etc. shall be checked when they operate according to their duties, at rated loads and in combination with all their distributing, regulating, starting and protective devices.

2.7.11 The test results are considered satisfactory if the proper functioning of electrical equipment, the conformity of its characteristics and parameters with the requirements of the Rules for the Classification and Construction and with the ship’s demands, specified are demonstrated.

2.8 Check of switchgear, switching, protective and control equipment.

2.8.1 Provision shall be made for checks and tests of main, emergency, sectioned, grouped and other switchboards of essential and nonessential services.

2.8.2 In checking, it shall be ascertained and, if needed, evidenced by tests:

.1 presence of switching and protective equipment in each outgoing feeder, their proper and reliable functioning;
.2 availability of instruments for measuring all the crucial parameters of electrical power, their proper and reliable functioning;
.3 presence of all types of audible and visual alarm on faults in the distribution system or on variations of electrical power parameters beyond the tolerable limits and their proper functioning;
.4 conformity of circuit breakers with the requirements on protection against short circuits and over-loads;
.5 conformity of circuit breaker settings on protection against short circuits and overloads with the characteristics of consumers, supply feeders, breaking and making capacities of circuit breakers and the total rating of generators which may be connected to switchboard busbars;
.6 correct selection of fuse elements for fuses depending on the characteristics of a protected feeder, the magnitude and type of load;
.7  satisfaction of the requirements on arrangement of switching and protective equipment on outgoing feeders of essential services fitted in the double quantity on different distributing sections.

2.8.3  The external and internal examinations of switchgear shall be carried out according to Appendix 1. Any nonconformities with the requirements of the Rules for the Classification and Construction associated with the subjects listed in 2.8.2 shall be revealed by examinations.

2.8.4  Following the external examination, the functioning of controls, switching and protective equipment, and alarms shall be checked and, if faults are lacking, power shall be applied to the switchboard or other switchgear being tested.

2.8.5  The switchgear may be checked being powered from both its own regular sources of electrical power and the land-based network.

2.8.6  When the switchgear is alive, all the versions of switchings provided in the ship's design, the correct alternation of phases or poles of busbars, feeders, the functioning of switching equipment, alarms, measuring instruments, etc. shall be checked.

2.8.7  The uniformity of load sharing between single phases by phased measurements of load current shall be checked using the instruments on the main, emergency and sectioned switchboards.

2.8.8  Electrical protection equipment and devices shall be checked with the use of the proper instruments in compliance with the manufacturer's instructions and due regard to the requirements of 8.1.8, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

2.8.9  The proper adjustment of protection equipment of adjusting circuit breakers and hot-wire relays shall be checked for compliance with settings for:

- .1  operating current of the release in the short circuit zone — for adjusting circuit breakers with the electromagnetic overcurrent release;
- .2  operating current — for overcurrent relays;
- .3  operating current of the release in the short circuit zone, as well as operating current and time in the overload zone — for adjusting circuit breakers with the combined release.

2.8.10  The proper adjustment of protection equipment of selective circuit breakers shall be checked for compliance with settings for the following:

- .1  operating current and time for overload releases;
- .2  operating current and time for overcurrent releases.

2.8.11  The reverse power (current) relay shall be checked for operation using special devices or during the parallel running of generators (refer to 2.5.22 of this Appendix) reducing the speed of one of generator prime movers, and for d.c. generators, reducing the voltage of one of generators running in parallel.

The time since reverse power emergence equal to the relay setting till the moment of operation of the circuit breaker of the generator running at reduced parameters shall be determined by a stopwatch.

Relay settings shall be consistent with those given in 8.2.4, Part XI "Electrical Equipment" of the Rules for the Classification and Construction. Reverse power and reverse current protection relays of each generator shall operate with the above settings within not more than 10 s.

2.8.12  Hot-wire relays of circuit breakers or magnetic starters shall be checked for operating current. The check of a d.c. relay shall be carried out by supplying from a d.c. source with regulated characteristics or with a special a.c. device for ac hot-wire relays.

The relay is preheated with the current equal to 150 – 200 % of the rated current of electric motors until the relay operates (heating shall be within 3 min). Then it shall be cooled down until relay contacts take the initial position. Thereafter check tests with the current equal to 150 % of the rated one shall be performed 2 – 3 times. If relay preheating is not used in the check, the operating current is computed from the formula

\[ I_{op} = k \cdot I_r \]  

(2.8.12)
where \( I_{op} \) = operating current of a relay, in A; 
\( I_r \) = rated current of a relay, in A; 
\( k \) = correction factor for an ambient air temperature:

<table>
<thead>
<tr>
<th>( k )</th>
<th>1.58</th>
<th>1.51</th>
<th>1.43</th>
<th>1.35</th>
</tr>
</thead>
<tbody>
<tr>
<td>( t_{amb} ), in °C</td>
<td>10</td>
<td>20</td>
<td>30</td>
<td>40</td>
</tr>
</tbody>
</table>

The operating time of the relay shall be within 90 to 120 s.

2.8.13 Aside from the shortcut method of hot-wire relays testing given in 2.8.12, the following method may be used.

Hot-wire relays at an ambient air temperature of 40 °C are heated with the rated current of an electric motor during 2 h. Then the current value is increased up to 135 % of the rated one, the relay therewith shall operate (disconnect the electric motor) within 20 min.

2.8.14 The phase-failure and low-voltage protection device shall be checked at the rated load current of the land-based network feeder. The test is carried out as follows: the break of one feeder phase is simulated at the current strength of at least 25 % of the rated one, and the rated load current for the feeder is maintained in two remaining phases.

The operating time for protection is determined since the phase break moment till the signal at the block output. The functioning of the low voltage alarm shall be checked at a time.

2.8.15 Checks as applied to the phase-failure and low-voltage protection device of 30ΦН type shall be carried out for determining sensitivity at the following parameters:

1. in operation of the relay block with current transformers rated at 800 A, 50 Hz or 400 Hz at motor or combined load currents the sensitivity is within 15 A, and for the active load, within 20 A;
2. in operation of the relay block with current transformers rated at 1500 A, 50 Hz at motor or combined load currents the sensitivity is within 30 A, and for the active load, within 50 A;
3. in operation of the relay block with current transformers rated at 1500 A, 400 Hz at motor or combined load currents the sensitivity is within 60 A, and for the active load, within 100 A;
4. the signaling block shall generate a pulse on low voltage at the voltage drop down to 85 – 80 % of the rated one equal to 380 V.

2.8.16 The off-loading device shall be checked by disconnecting nonessential services. This check shall be performed by connecting consumers with the total loading of at least 110 % of the running generators rating to these latter. The first level of nonessential consumers at such a load shall be disconnected within 10 s after load application.

2.8.17 The functioning of the following signaling devices (if any) shall be checked for operation within 5 s and 10 min respectively:

1. on generator frequency increase above 105 % of the rated one;
2. on load reduction down to 35 % of the generators rating.

The above checks shall be carried out by the increase of a generators prime mover speed and by off-loading.

2.8.18 All the checks, tests and measurements performed with regard to switching and protective equipment shall evidence that all the settings on operating currents, time delays, selectivity, breaking and making capacities of circuit breakers are consistent with design and technical characteristics of the protective equipment used.

2.8.19 In single cases, when all the above specified checks of switching and protective equipment for correspondence with the short-circuit currents expected or the calculations of short-circuit currents are questioned, the RS surveyor can demand the performance of tests at full-scale short-circuits.

The program and procedure for such tests shall be developed by the shipyard (ship's designer) and approved by the Register.
2.8.20 The check of short-circuit protection shall be carried out for the following:
1. selectivity of protection operation;
2. electrodynamic stability of electrical equipment elements;
3. proper selection of protective equipment by switching capacity and pickup settings in protection zones;
4. stability of electric generating plant operation under transient operational and emergency conditions.

2.8.21 In performance of full-scale short-circuit tests, oscillography shall be used for the following:
1. currents and voltages in each phase at the point of fault, the voltage (in one phase) at the main switchboard and secondary switchgear, which supply essential services;
2. speeds of prime movers of generators;
3. time of protection operation in the short circuit and supply circuits of essential services of the largest installed power.

2.8.22 Following each full-scale short-circuit test, the switching position of protective equipment of essential services, the proper condition of main and secondary switchboard busbars being part of the short circuit shall be checked.

2.8.23 During functional tests of electrical equipment, infrared thermography shall be used for electrical contact joints in switchboards, boxes and starting devices.

2.9 Check of electric drives of essential machinery.

2.9.1 All the electric drives of essential machinery shall be checked both in idle running and in loading the machine according to its duty if such a load may be applied during the mooring trials.

2.9.2 Where it is impractical to apply the rated or like load to the machine, the electric drive of the machine may be checked for operation according to its duty during the sea trials.

2.9.3 In idle running the electric drive of the machine the following is checked:
1. functioning of switching and control equipment by opening and closing a switch or circuit breaker on a switchboard;
2. manual start and stop of the electric drive at the local control board;
3. remote start and stop of the electric drive at all remote control boards, as well as the stop of electric drives of fuel oil, lubricating oil, fuel oil transfer pumps, fans, etc. which shall be provided with such opening devices;
4. automatic start and stop of the electric drive of a back-up (standby) machine by the stop of the main running electric drive;
5. activation of an audible and visual alarm by signals of the sensor of medium parameters, e.g. air and lubricating oil pressure, temperature, level, etc. The check shall be performed by the variation of the relevant parameters of the medium under control;
6. smoothness of electric drive running, the proper alignment of the electric drive and machine, the lack of beats and intolerable vibrations, and of heating of electrical motor end shields;
7. values of starting currents, reliable operation of contactors in electric drive switching on and off, the lack of arcing, sparking and burning of contact surfaces, switching performance of dc motors and the condition of a commutator after the electric motor stop;
8. functioning of electric motors at all the speeds specified with checking the operation of the zero protection, as well as the repeated automatic switching-on after voltage recovery where it is provided.

2.9.4 The electric drives start and stop specified in 2.9.3 shall be checked at least 3 – 4 times for each electric drive.

2.9.5 The parameters of electric drive operation shall be monitored using standard regular measuring instruments. Clip-on instruments, as well as portable devices may be used.
2.9.6 The check of electric drives functioning at the rated load of the machine shall provide:

1. determination of the load factor and consumed power of the electric motor (in prototype ships);
2. determination of a speed and, if needed according to the conditions of electric drive operation, of the range of tolerable variations of electric dc drives speed as well;
3. determination of starting currents of electric motors of electric drives being switched on under load;
4. check of automatic starting electric motors of electric drives with supply voltage recovery after failure, where such starts are provided;
5. determination of the adequacy of technical parameters of the electric drive to maintain the operational modes specified for the machine.

2.9.7 Electric drives operating under variable loads, e.g. of cargo winches, capstans, windlasses, etc. shall be checked in operation under the heaviest conditions.

2.9.8 The survey and tests of electric drives of machinery are carried out in their operation according to their duty in combination with the unit (diesel, boiler, systems, arrangements, etc.) under test.

2.9.9 In checking the operation of single electric drives of essential machinery, the requirements of 2.9.9.1 – 2.9.9.7 shall be met.

2.9.9.1 Steering gear.

2.9.9.1.1 Following power applying to the steering gear, to be checked are:

- consistency of all electric indicator readings with reference to the mechanical rudder angle indicator, automatic starting the electric motor of a pump (for hydraulically-driven steering gear) at the automatic switching (if provided) of supply from the main source to the backup one and vice versa;
- consistency of rudder angle indicators readings, in deg., in putting the rudder over through each 5° from each control station, i.e. a mismatch value shall not exceed:
  - in centerline...........................................±1;
  - at rudder angles from 0 to 5°..............................±1.5;
  - at rudder angles from 5 to 35°............................±2.5;
- the time of transition from the main control station to the backup one shall not exceed 2 min for the prototype ship;
- proper functioning of limit switches, audible and visual alarms. The electric drive overload alarm shall be checked by the opening of hot-wire relay contacts or by the button of signal checking and the button of signal picking off;
- functioning of the electric drive of the steering gear power unit and of the remote control system supplied from each of two available feeders by their switching in the steering compartment or on switchboards;
- functioning of the main and standby electric drives of the main unit of rudder from the emergency generator (if provided) by starting at the emergency load of the generator or with the load removed;
- putting the rudder from hard over to hard over from all the remote control stations;
- start and stop of the steering gear power unit from the wheel house, independent supply of the rudder angle indicators system and the remote control system from the power units supply system, the opportunity to individually disconnect the supply of the remote control system;
- speed of putting the rudder over with one, two and the backup power units of the steering gear. The check shall be carried out by measuring the time of putting the rudder over according to the requirements in 2.9.2 and 2.9.3, Part III "Equipment, Arrangements and Outfit" of the Rules for the Classification and Construction. The insulation resistance specified in 2.3 of this Appendix for electrical and electrohydraulic steering gear shall be measured on electrical gear, automatic steering devices, feeders, rudder angle indicator circuits, remote control and alarm circuits.

The electrical equipment of the steering gear with direct electrical dc drive shall be checked under stalling conditions during 1 min. The commutation of electrical dc machines
shall be checked during putting the rudder from hard over to hard over. Completing the survey, the condition of a commutator and brushes shall be checked, as well as a temperature of
electrical machine bearing caps by touch.

2.9.9.2 Anchor arrangement.

2.9.9.2.1 Following powering the anchor arrangement in idle running, the electric drive
shall operate within at least 30 min whereupon to be checked are:
functioning of limit and lockout switches;
operation of electromagnetic brakes at the abrupt travel of the handle at the control station
from limiting positions to the zero one;
drive reversal. If the electric drive of the anchor arrangement is provided with the remote
control, to be additionally checked are: functioning of the servomotor control circuit, operation
of limit switches and the alarm of jaw clutches and belt brakes position. Each servomotor shall
be individually checked from the remote control station; time of transition from one control
station to another in the prototype ship;
functioning of the torque-limiting clutch in operation of jaw clutch servomotors. In this case, the
limit switches, which limit the jaw clutch movement, shall be by-passed. If the anchor arrangement
has the remote control, the automatic switching of an electric motor speed and the automatic stop
of the electric motor at anchor entering the hawse pipe shall be checked in heaving the anchor;
the brake shall be checked under load in heaving and dropping the anchor;
stalling conditions during the set time for the given type of a heated electrical motor of the
anchor or mooring arrangements. The electric drive loading shall be provided by screwing up
the cable (rope);
temperature of electric machine bearing caps;
degree of commutator sparking of an electric dc machine and, after the stop, the condition
of brush and commutator surfaces;
electrical anchor cable indicators by comparing with readings of the mechanical indicator
in every 10 m.

2.9.9.3 Mooring arrangement.

2.9.9.3.1 In surveying the mooring machinery, the checks according to 2.9.9.2, as appropriate,
shall be performed additionally to the general checks of electric drives as per 2.9.3 and 2.9.6.

2.9.9.4 Cargo-handling gear.

2.9.9.4.1 The general checks of the cargo-handling gear are defined in 10.3 of the Rules
for the Cargo-Handling Gear. In surveying the cargo-handling gear during the mooring trials,
supplementing the general checks of electric drives specified in 2.9.3 and 2.9.6, the following
shall be checked:
functioning of safety switches (buttons) on the cargo winch (control board, controller). The check shall be carried out at least 3 – 4 times for each winch both in idle running and with
the loaded pendant;
functioning of limiters of crane cabin rotation and other limiting electrical devices, as well
as of switching devices disconnecting the supply of electric drives of the crane in the cabin;
functioning of braking devices. The simultaneous operation of cargo winches for union
purchase with the supply from the ship's electric generating plant shall be checked in the
prototype ship only.

2.9.9.5 Electric drives of watertight doors and of holding devices of fire-resisting doors.

2.9.9.5.1 The check of each watertight or fire-resisting door shall be effected by the five-
fold opening and closing from the local station under manual control. The time of warning
signal actuation and the time of door closing are determined in the prototype ship.

If the centralized remote control of watertight and fire-resisting doors is provided, the doors
closing and the functioning of the audible and visual alarm on the watertight doors position
when supplied from the main and emergency sources of electric power shall be checked.
Electrical devices releasing fire-resisting doors shall be checked for operation 4 – 5 times each
both from the remote panel and the local one at the door.
2.9.9.6 Electrical equipment of lifts.

2.9.9.6.1 In operation of the electrical equipment of lifts, the functioning of interlock switches of locks and trunk doors shall be checked by pushing the call button with one of the trunk doors opened, and the functioning of the interlock switch of the lift car door, by pushing the up (down) button with the lift car door opened (2 – 3 times).

The lift car travel shall be checked by its calling and directing to each platform. Special attention shall be given to the potential sticking of call and up (down) buttons when pushed, and their coming-off with the car stop, to the functioning of floor switches and the foot-operated switch, as well as to the functioning of electric brakes by stopping the moving car with the "stop" button.

Prior to checking the functioning of the switch of an emergency limitation in the upward movement, it is necessary:

move the car till the uppermost entrance station;
set the handle of the winch drive switch in the "Manual" position;
shunt up the uppermost floor switch;
start the electric motor for the upward movement and make sure in switch turning off and motor stopping.

The switch of an emergency limitation in the downward movement is checked in the same manner.

In checking the switches of overspeed governors and gripping devices in movement of the car overloaded by 10 %, the overspeed governor rope shall be prepassed over the pulley of a lesser diameter, and the lift car shall be set on gripping devices by starting the electric drive.

The check of the interlock switch of car securing shall be performed with the car secured in guides with the following attempt to start the electric motor.

2.9.9.7 Electric drives of classed refrigerating plant machinery.

2.9.9.7.1 In operation of the above drives, the checks specified in 2.9.3 and 2.9.6 shall be supplemented with the following ones:

functioning of the emergency protection and remote control with building up the pressure in the compressor system, and the activation of the audible and visible alarm by changing the pressure in the compressor until the relevant sensor is activated;
functioning of the audible alarm from refrigerating chambers, holds and other refrigerated spaces if such an alarm is fitted according to the requirements of the Rules for the Classification and Construction. The check shall be performed by manual closing the buttons in all spaces;
functioning of the interlock preventing the start of a compressor motor with a cooling water pump being inoperative. The check shall be performed by test starts (3 – 4 times);
functioning of the system of automatic connecting and disconnecting the refrigerating plant for maintaining the specified temperature in refrigerated spaces. The check shall be performed in combination with the refrigerating plant test for functioning according to its duty;
functioning of automatic devices for connecting standby electric drives of compressors, pumps and fans if such an automatic change-over is provided. The check shall be effected by stopping the running electric drive. Where ammonia is used as a refrigerant in refrigerating plants, to be additionally checked is the functioning of devices for remote emergency disconnecting the refrigerating plant switchboard from their locations (refrigerating machine spaces, places outside these spaces) which may be contaminated with ammonia at entrances in the refrigerating machines space;
functioning, in combination with the above disconnection, of the system for connecting the emergency ventilation, drenching system, water screen and standby lighting;
functioning of the above systems without disconnecting the refrigerating plant switchboard. Where the group II refrigerant is used in refrigerating plants, to be additionally checked is the functioning of devices for remote disconnecting the refrigerating plant switchboard from their locations;
from the permanent place of refrigerating plant control in the refrigerating machines space;
from the place outside the space of potential contamination with the group II refrigerant in accident in the refrigerating machines space;

from outside and close to each exit from the refrigerating machines space.

2.10 **Check of functioning of main and emergency lighting and navigation lights.**

2.10.1 Supplementing the checks specified in 10.6.1.1 – 10.6.1.4 of Appendix 1 to this Section, the following shall be checked in main electrical lighting systems:

.1 functioning of the main lighting of ship's spaces and areas for compliance of the intensity of lighting using general lighting fixtures. This check shall be effected with use of special devices (luxometers) at the level of 800 mm above the space floor. The check shall be carried out in prototype ships and ships of series if the arrangement, number or type of lighting fixtures, lamp parameters were changed. The illuminance characteristics shall be consistent with those in Table 6.7.1, Part XI "Electrical Equipment" of the Rules for the Classification and Construction;

.2 proper distribution of lighting fixtures by supply groups to provide the uniform lighting of a space or an area when any supply group fails. The check shall be effected by the sequential disconnection of single groups of lighting fixtures supply and by the visual determination of illuminance adequacy for the unimpeded control of personnel over machinery and arrangements. It shall be considered sufficient if the general illuminance with any group of lighting fixtures disconnected accounts for 30 – 40 % of the required in Table 6.7.1, Part XI "Electrical Equipment" of the Rules for the Classification and Construction;

.3 functioning of the switchgear on grouped lighting panels by disconnecting/connecting single lighting groups, proper selection of fuse ratings, if any, and of settings of adjusting circuit breakers.

The RS surveyor can demand short circuiting in the single group of lighting fixtures to check the operation of the adjusting circuit breakers. The procedure and methods of such a check shall be developed at the shipyard and approved by the surveyor;

.4 lack of the unacceptable quantity of lamps in lighting fixtures connected to one end branch of the circuit. This check shall be effected by counting the lamps and their power, and by determining fuse ratings or circuit breakers settings. **Table 2.10.1.4** contains the data on the maximum permissible values of the above characteristics.

.5 functioning of the main lighting in corridors, passageways, at exits to the open deck and in other escape routes for people in accident, of embarkation stations for boarding lifeboats and liferafts, of locations for storage personal life-saving appliances, overboard spaces, etc. The check shall be effected by switching on and off the lighting, by switching off single grouped panels on the main switchboard to evidence the presence of lighting in those places being supplied from the other grouped panel;

**Table 2.10.1.4**

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Space or lighting duty</th>
<th>Maximum permissible values</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Number of filament lamps, 60 W</td>
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<tr>
<td>1</td>
<td>Accommodation and public spaces at voltage, in V: up to 50</td>
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<td>14</td>
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<td>121 to 250</td>
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<td>2</td>
<td>Decorative lighting</td>
<td>Any</td>
</tr>
<tr>
<td>3</td>
<td>Engine rooms, holds, open decks</td>
<td>Any</td>
</tr>
</tbody>
</table>

.6 an opportunity to remotely switch off the outside lighting from the wheelhouse, availability of a visual alarm on grouped panels of holds lighting, proper operation of door switches, if fitted. Checks are effected by test switchings-off and visually;

.7 values of voltage losses or drops at the most remote lighting fixtures connected to the end branch of a circuit. The check shall be performed in the prototype ship only if no changes are made in the main lighting system in ships of a series. The check shall be effected
by comparing the voltage values across the terminals of the transformer, or main or emergency switchboards and the terminals of the most remote lighting fixture. The permissible voltage losses or drops shall not exceed those given in Table 2.10.1.7;

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Consumer</th>
<th>Voltage, in V</th>
<th>Maximum permissible voltage losses or drops, in %</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Lighting and alarm</td>
<td>≤ 50</td>
<td>10</td>
</tr>
<tr>
<td>2</td>
<td>Ditto</td>
<td>&gt; 50</td>
<td>6</td>
</tr>
<tr>
<td>3</td>
<td>Power, cooking and heating consumers</td>
<td>Ditto</td>
<td>6</td>
</tr>
<tr>
<td>4</td>
<td>Power consumers with short-duration and intermitent operation</td>
<td>Ditto</td>
<td>10</td>
</tr>
<tr>
<td>5</td>
<td>Radiostation, radio and electric navigational devices, charging circuits of accumulator batteries</td>
<td>Ditto</td>
<td>5</td>
</tr>
<tr>
<td>6</td>
<td>Ac electric motors with direct starting</td>
<td>Ditto</td>
<td>25 (at starting, during an accelerating period)</td>
</tr>
</tbody>
</table>

.8 insulation resistance of the end branches of circuits of the lighting network shall be measured after the RS surveyor is satisfied that all the lighting fixtures supplied from that branch are switched on and functioning; then the protection on the grouped switchboard is switched off and measurements are carried out using a megohmmeter.

2.10.2 Supplementing the checks specified in 10.6.1.1 – 10.6.1.4 of Appendix 1 to this Section, the following shall be checked in emergency electrical lighting systems:

1 functioning of the automatic switchover of emergency lighting network supply to the emergency source with the voltage failure on the main switchboard. The check shall be performed for emergency networks of lighting from the emergency generator, emergency battery or transient emergency battery by stepping the voltage down to 50 – 60 % or by deenergizing the main switchboard busbars or another way. The time of switching on the emergency lighting from the emergency generator shall be within 45 s, and from accumulator batteries, practically instantaneous;

2 illumination of lighting fixtures of the emergency lighting at all control stations, illumination of indicators of exits to the deck, of corridors, passageways, manual fire detectors, embarkation stations for boarding lifeboats, overboard spaces and other places according to Part XI “Electrical Equipment” of the Rules for the Classification and Construction. The illumination of lighting fixtures of the emergency lighting shall be checked in combination with the checks specified in 2.6 of this Appendix during the time period set therein;

3 intensity of overboard spaces illumination in places of life-saving appliances launching;

4 values of voltage losses or drops at the most remote lighting fixtures and at those of which lamp filaments glow seems to be inadequate.

2.10.3 Check of navigation lights.

2.10.3.1 Following the visual examination of the navigation lights commutator, supply and protection system, cable lines, contact and protection termination of cable conductors, plug-and-sockets, earthings of light housings and cable sheaths, etc., which shall evidence the fulfillment of the requirements of the Rules for the Classification and Construction, the following shall be checked:

1 insulation resistance of all parts and cables of navigation lights;

2 supply of the commutator from the both feeders provided and functioning of the feeders switch;

3 protective devices in switchboards in power feeders and in the commutator in all feeders;

4 functioning of switches in each outgoing feeder;

5 functioning of an alarm on serviceability in circuits of single navigation lights;

6 conformity of the lamps fitted with the types and ratings required.

2.10.3.2 All the checks specified in 2.10.3.1 shall be carried out with the supply from the ship's sources of electrical power using built-in and portable devices, as well as checking instruments. The checks shall be performed for each of the commutators and lights fitted.
2.10.3.3 Where it is possible, the cuts-off of a light flux of navigation lights shall be checked during the mooring trials. Otherwise those checks shall be postponed until the sea trials.

2.10.3.4 The voltage drop or loss across terminals of the most remote navigation lights shall be checked in prototype ships.

2.10.3.5 Methods of the above checks are as follows:

- navigation lights are checked by switching on each light, the functioning of a commutator alarm is checked therewith;
- alarm on lamps burnout is checked by setting the control switch on the commutator in the "Check" position or by switching off the protection in each feeder circuit both with lamps fitted in or removed from lanterns, or by another way recognized by the RS surveyor;
- flashing light is checked using a key;
- impulsive flashing lamps are checked by signalling;
- daytime signalling lamps are checked by signalling, the functioning of a rotary mechanism of lamps and the screens positioning are checked therewith.

2.11 Check of internal communication and alarm systems.

2.11.1 Following the visual examination of internal communication and alarm systems, including the sources of their supply and cable runs, which has demonstrated the satisfactory results, and the measurement of insulation resistance, which has evidenced its consistency with the minimum values according to the Rules for the Classification and Construction, the internal communication and alarm systems shall be subjected to checks.

The methods of these checks are as follows:

- engine room telegraphs shall be surveyed for a smooth movement of handles and a reliable operation of locks. The functioning of engine room telegraphs shall be checked by several transmis-sions of all the orders and by obtaining responses for them. To be checked is the interlock of a mishandled order if provided;
- telephones shall be checked by calling and talking with each subscriber in person and, if provided in the circuit, simultaneously with a group of subscribers as well;
- electric tachometers of the propeller shaft are checked with a clock-type tachometer at 4 – 5 points of the scale in the headway and sternway rotation of propeller shafts. The adequacy of electric indicator scales illumination is determined;
- fire detection system is checked by simulating fire factors depending on the type of the fire detectors fitted. These actions, excepting manual detectors, shall be performed for heat detectors by the simulation of temperature raising (with local drying fans having a thermometer), for smoke detectors by smoke simulators of the aerosol type, with a smoldering wick and etc., for flame detectors by flame simulators. The check shall be effected with supply from the main and backup sources of power. The supply failure alarm at the station and the faults alarm shall be checked;
- at least 50 % of the detectors fitted shall be checked in each section of detectors if their pre-check at the shipyard is documented. Otherwise, all the detectors fitted shall be checked;
- alarm on starting the smothering means is checked by the test operation of contact devices coupled with the release controls of fire-extinguishing agents, and by the visual and audible control over the time of alarm activation, sound intensity and panel visibility.

2.12 Check of cooking and heating appliances.

2.12.1 Cooking appliances are checked in operation in the same manner as lighting, but they are switched on for 1 – 2 h only. In surveying, attention is given to the observance of safely measures (distances from combustible materials, type of enclosures).

2.12.2 Electric heaters are checked during the time needed for reaching the maximum possible temperature on the heater housing. The temperature is assumed steady when the results of three measurements are practically the same.

2.13 Check of cable network and earthing.

2.13.1 The check of a cable network and earthing in the mooring trials shall be performed in the scope which allows to ascertain that the requirements of the Rules for the Classification and Construction are met, and in combination with the electrical equipment being checked.
RECOMMENDATIONS ON CHECKING PERFORMANCE OF ELECTRICAL MACHINES COMMUTATION

1. The check of performance of electrical d.c. machines commutation shall be carried out for the following:
   .1 machines operating in continuous and intermittent conditions — after a lapse of time needed for reaching a steady temperature of the machine windings and frame, but not earlier than in 2 h for machines rated up to 100 kW inclusive;
   .2 machines rated over 100 kW (not earlier than in 4 h).
2. Commutator machines shall operate without sparking at any load from zero to 100 % of the rated one. With the required overloads, reverses and starts of machines, the brush sparking shall not reach a point when the machine brushes and commutator may be damaged.
3. Electrical dc machines intended for operation in continuous conditions at the set rated load shall operate practically without sparking (commutation class 1 — 1.25). Class commutation 1.5 may permitted under particularly severe conditions.
4. The check of machines commutation on board a ship, including also the machines of the electric propulsion plant, shall be performed with machines operating according to their duties at a practically steady temperature of the machine and the existing environmental conditions (at a temperature of air, cooling water, humidity, vibrations, shocks, inclinations, etc. specified in 2.1, Part XI "Electrical Equipment" of the Rules for the Classification and Construction).
A commutation class therewith shall not be below the one specified in 2 and 3 above.
5. Commutation classes depending on the nature of commutator brushes sparking are given in the Table.
6. The characteristic of a sparking degree given in the Table shall be determined visually by watching the sparking under the running-down edge of a brush.

<table>
<thead>
<tr>
<th>Sparking degree (commutation class)</th>
<th>Description of sparking degree</th>
<th>Commutator and brushes condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>No sparking (sparkless commutation)</td>
<td>—</td>
</tr>
<tr>
<td>1.25</td>
<td>Light point sparking under the small part of a brush</td>
<td>No blackening on the commutator and carbon deposit on brushes</td>
</tr>
<tr>
<td>1.5</td>
<td>Light sparking under the large part of a brush</td>
<td>Emergence of blackening traces on the commutator, which are readily wiped out with petrol, as well as of carbon deposit traces on brushes</td>
</tr>
<tr>
<td>2</td>
<td>Sparking under the entire brush edge. Allowed in short time load and overload kicks only</td>
<td>Emergence of blackening traces on the commutator, which cannot be wiped out with petrol, as well as of carbon deposit traces on brushes</td>
</tr>
<tr>
<td>3</td>
<td>Essential sparking under the entire brush edge with large-sized escaping sparks. Allowed only for the moment of direct (without theostat steps) switch-on or reverse of machines if a commutator and brushes therewith remain in the condition suitable for further operation</td>
<td>Essential blackening on the commutator, which cannot be wiped out with petrol, as well as burning and failure of brushes</td>
</tr>
</tbody>
</table>
DATA ON CHECKS AND TESTS OF SHIP'S ELECTRICAL EQUIPMENT

**Table 1**

<table>
<thead>
<tr>
<th>Standards for permissible axial shaft displacements in plain bearings of electrical machines</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power, in kW</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Below 10</td>
</tr>
<tr>
<td>10–30</td>
</tr>
<tr>
<td>30 – 70</td>
</tr>
<tr>
<td>70 – 125</td>
</tr>
<tr>
<td>Over 125</td>
</tr>
</tbody>
</table>

**Notes:**
1. The displacement is set to both the sides from the central position of an armature (a rotor) determined by a magnetic field.
2. For machines with a shaft journal diameter over 250 mm, the displacement may be up to 2 per cent of the journal diameter.

**Table 2**

<table>
<thead>
<tr>
<th>Standards for permissible natural vibrations of electrical machines</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rotor shaft speed, in rpm</td>
</tr>
<tr>
<td>Natural vibrations swing, in mm</td>
</tr>
</tbody>
</table>

**Table 3**

<table>
<thead>
<tr>
<th>Table of conversion of power ratios and voltage ratios to decibels</th>
</tr>
</thead>
<tbody>
<tr>
<td>Voltage ratio</td>
</tr>
<tr>
<td>1,00</td>
</tr>
<tr>
<td>0,89</td>
</tr>
<tr>
<td>0,79</td>
</tr>
<tr>
<td>0,71</td>
</tr>
<tr>
<td>0,63</td>
</tr>
<tr>
<td>0,56</td>
</tr>
<tr>
<td>0,5</td>
</tr>
<tr>
<td>0,45</td>
</tr>
<tr>
<td>0,4</td>
</tr>
<tr>
<td>0,36</td>
</tr>
<tr>
<td>0,32</td>
</tr>
<tr>
<td>0,28</td>
</tr>
<tr>
<td>0,25</td>
</tr>
<tr>
<td>0,22</td>
</tr>
<tr>
<td>0,20</td>
</tr>
<tr>
<td>0,18</td>
</tr>
<tr>
<td>0,16</td>
</tr>
<tr>
<td>0,14</td>
</tr>
<tr>
<td>0,13</td>
</tr>
<tr>
<td>0,11</td>
</tr>
<tr>
<td>0,10</td>
</tr>
<tr>
<td>0,066</td>
</tr>
<tr>
<td>0,032</td>
</tr>
<tr>
<td>0,018</td>
</tr>
<tr>
<td>0,010</td>
</tr>
</tbody>
</table>
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### Table 4

<table>
<thead>
<tr>
<th>Voltage ratio</th>
<th>Power ratio</th>
<th>Amplification</th>
</tr>
</thead>
<tbody>
<tr>
<td>0,006</td>
<td>3,16×10⁻³</td>
<td>45</td>
</tr>
<tr>
<td>0,003</td>
<td>10⁻³</td>
<td>50</td>
</tr>
<tr>
<td>0,002</td>
<td>3,16×10⁻³</td>
<td>55</td>
</tr>
<tr>
<td>0,001</td>
<td>10⁻³</td>
<td>60</td>
</tr>
<tr>
<td>0,0006</td>
<td>3,16×10⁻⁷</td>
<td>65</td>
</tr>
<tr>
<td>0,0003</td>
<td>10⁻⁷</td>
<td>70</td>
</tr>
<tr>
<td>0,0002</td>
<td>3,16×10⁻⁸</td>
<td>75</td>
</tr>
<tr>
<td>0,0001</td>
<td>10⁻⁸</td>
<td>80</td>
</tr>
<tr>
<td>0,00006</td>
<td>3,16×10⁻⁹</td>
<td>85</td>
</tr>
<tr>
<td>0,00003</td>
<td>10⁻⁹</td>
<td>90</td>
</tr>
<tr>
<td>0,00002</td>
<td>3,16×10⁻¹⁰</td>
<td>95</td>
</tr>
<tr>
<td>0,00001</td>
<td>10⁻¹⁰</td>
<td>100</td>
</tr>
</tbody>
</table>

**Marking of safe-type electrical equipment**

<table>
<thead>
<tr>
<th>Protection of electrical equipment</th>
<th>Mark of conformity to protection standards</th>
<th>Type of protection</th>
<th>Group of explosive gases</th>
<th>Temperature class</th>
<th>Application of equipment</th>
<th>Spark-proof circuit</th>
<th>Group of substance</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>d</td>
<td>T1</td>
<td>ia</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>p</td>
<td>T2</td>
<td>ib</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td>q</td>
<td>IIA</td>
<td>T3</td>
<td>X</td>
<td>ic</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Ex or EEx</td>
<td>o</td>
<td>IIB</td>
<td>T4</td>
<td>U</td>
<td>Exd[i...G]</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td>e</td>
<td>IIC</td>
<td>T5</td>
<td>U</td>
<td>[Ex i...D]</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>n</td>
<td>T6</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>m</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Example of marking and its interpretation:** 2 Exd IIB T4 X ia G

Designations:

1. **Protection:**
   - 0 — particularly safe-type electrical equipment;
   - 1 — safe-type electrical equipment;
   - 2 — electrical equipment of increased safety.

2. **Mark of protection:**
   - Ex or EEx.

3. **Types of protection:**
   - d — flameproof enclosure;
   - p — pressurized enclosure;
   - q — sand-filled enclosure;
   - o — oil-immersed enclosure;
   - e — "e"-type protection;
   - n — "n"-type protection;
   - m — compound encapsulation.
4. **Group by the typical representative of explosive gases:**
   - IIA — propane;
   - IIB — ethylene;
   - IIC — acetylene, hydrogen.

5. **Temperature class:**
   - T1 — maximum surface temperature of 450 °C;
   - T2 — maximum surface temperature of 300 °C;
   - T3 — maximum surface temperature of 200 °C;
   - T4 — maximum surface temperature of 135°C;
   - T5 — maximum surface temperature of 100 °C;
   - T6 — maximum surface temperature of 85 °C.

6. **Application of equipment:**
   - X — special conditions of application;
   - U — partially-certified Ex components cannot be applied.

7. **Spark-proof circuit:**
   - ia, ib, ic — levels of spark-proof circuits, differing by the number of accountable damages in the spark-proof circuit resulting in the most hazardous conditions;
   - Exd[i..] — designation of protection for the associated equipment (terminal boxes, connectors) in a flameproof enclosure, which may be installed in a hazardous area;
   - [Ex i..] — designation of protection for the associated equipment (terminal boxes, connectors) which shall be installed in a safe area.

8. **Group of substance:**
   - G — gas;
   - D — dust.
TEST OF ELECTRICAL INSULATION STRENGTH

1. In performance of the technical supervision of electrical equipment during ship's construction, the test of electric insulation strength of single types of equipment is carried out only in the following cases:
   .1 if an electrical machine is delivered on board the ship in parts (in assembly on board the ship, coils fitting, their electrical connection or laying of the winding part are carried out);
   .2 if switchgear (main, emergency and other large switchboards) is delivered on board the ship in parts, and their mechanical and electrical connection and other assembly works need the fitting and removal of coils, transformers, busbars and bus arrangements, the disconnection of (non-plugged) switchgear and protection equipment or the change of insulation distances;
   .3 if there is a reason to think by visual appearance of the cables laid (nicks, twisting, kinks, intolerably small radii of bends and other defects) that insulation integrity may be broken;
   .4 if there is a reason to think that any electrical equipment insulation sustained damages during transportation and storage;
   .5 if the part of insulation of windings, coils and the other were repaired on board the ship.

2. In all the above cases, the test voltage shall not exceed 1.3 times the rated voltage of equipment, and only those sections which were disassembled, repaired, connected, replaced or damaged shall be tested.

3. If the complete disassembly of a machine, the coils removal, rewinding, etc. were carried out on board the ship, such a machine shall be tested for electric insulation strength by the test voltage equal to at least 0.75 of that set for the given type of winding for new machines (refer to Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision).

4. The test shall be performed by 50 Hz alternating current with the practically sine curve at the above-specified effective value of voltage applied between the circuit section being tested and the earth (frame) during 1 min.
## DURATION OF CHECKS AND TESTS OF ELECTRICAL EQUIPMENT IN SHIP’S MOORING AND SEA TRIALS

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Check item</th>
<th>Time, in h</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>Generators, electric motors of the electric propulsion plant, generators of the ship’s electric generating plant, rotary converters under rated conditions at a rated speed, rpm:</td>
<td></td>
<td>Testing the generators, the test duration shall be assumed as the largest value specified in this Appendix and in Appendix 1 to Section 5 for the relevant drive machinery</td>
</tr>
<tr>
<td></td>
<td>below 750</td>
<td>3.0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>750 – 1000</td>
<td>2.5</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1000 – 1500</td>
<td>2.0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>over 1500</td>
<td>1.0</td>
<td></td>
</tr>
<tr>
<td>2.</td>
<td>Electric motors of drives under rated conditions at a rated speed, rpm:</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>below 750</td>
<td>3.0</td>
<td>Enclosure IP 21 to IP 44</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3.5</td>
<td>Enclosure IP 55 and above, a.c. current</td>
</tr>
<tr>
<td></td>
<td>750 – 1000</td>
<td>2.5</td>
<td>Enclosure IP 21 to IP 44</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3.0</td>
<td>Enclosure IP 55 and above, a.c. current</td>
</tr>
<tr>
<td></td>
<td>1000 – 1500</td>
<td>4.0</td>
<td>Ditto</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2.0</td>
<td>Enclosure IP 21 to IP 44</td>
</tr>
<tr>
<td></td>
<td>over 1500</td>
<td>3.0</td>
<td>Enclosure IP 55 and above, a.c. current</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1.0</td>
<td>Enclosure IP 21 to IP 44</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1.5</td>
<td>Enclosure IP 55 and above, a.c. current</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2.0</td>
<td>Ditto, d.c. current</td>
</tr>
<tr>
<td>3.</td>
<td>Switchgear and control panels</td>
<td></td>
<td>Sufficient for performance of all checks</td>
</tr>
<tr>
<td>4.</td>
<td>Accumulators, transformers</td>
<td></td>
<td>As per the Rules for the Classification and Construction of Sea-Going Ships</td>
</tr>
<tr>
<td>5.</td>
<td>Static converters:</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>idle running</td>
<td>0.5</td>
<td></td>
</tr>
<tr>
<td></td>
<td>running under rated load</td>
<td>2.0</td>
<td></td>
</tr>
<tr>
<td>6.</td>
<td>Electromechanical battery chargers:</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>idle running</td>
<td>0.5</td>
<td></td>
</tr>
<tr>
<td></td>
<td>running under rated load</td>
<td>2.0</td>
<td></td>
</tr>
<tr>
<td>7.</td>
<td>Lighting:</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>main</td>
<td>As needed for checking</td>
<td></td>
</tr>
<tr>
<td></td>
<td>emergency</td>
<td>According to 2.6.1.2 and 2.6.1.3 of Appendix 6</td>
<td></td>
</tr>
<tr>
<td>8.</td>
<td>Electric engine room telegraphs, rudder angle indicators, CPP blades position indicator, propeller shaft tachometers</td>
<td></td>
<td>As needed for checking</td>
</tr>
<tr>
<td>9.</td>
<td>Navigation lights</td>
<td>1.0</td>
<td></td>
</tr>
<tr>
<td>10.</td>
<td>Service telephone communication and command broadcasting</td>
<td></td>
<td>As needed for checking</td>
</tr>
<tr>
<td>11.</td>
<td>Alarm systems:</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>general alarm system</td>
<td>Ditto</td>
<td></td>
</tr>
<tr>
<td></td>
<td>fire detection system</td>
<td>Ditto</td>
<td></td>
</tr>
<tr>
<td></td>
<td>warning alarm of smothering system release</td>
<td>Ditto</td>
<td></td>
</tr>
<tr>
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<td>indication of closure of watertight and fire doors</td>
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<td>alarm of emergence of dangerous explosive gas concentrations</td>
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<td>The test duration is assumed in accordance with the type of safe-type electrical equipment</td>
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<td>cooking and heating devices</td>
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<td>Lightning conductor, earthing, cathode protection</td>
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RECOMMENDATIONS ON TECHNICAL SUPERVISION DURING LAYING
AND INSTALLATION OF MODU/FOP POWER AND/OR CONTROL
AND INSTRUMENTATION, AND/OR TELECOMMUNICATION
AND DATA SUBSEA CABLE LINES

1 GENERAL

1.1 When carrying out technical supervision during laying and installation of subsea
cable lines, the RS surveyor shall follow the RS-approved documentation.
1.2 All cables designed for subsea laying shall be identified and visually examined.
1.3 The RS surveyor shall check that cable ends are protected against mechanical
damages and are available for testing. The cables for subsea laying shall be stored in the
conditions protecting against UV irradiation and preventing mechanical damages to the
coating, as well as complying with the instructions (procedures) of the cable manufacturer.
1.4 Cable laying shall be carried out by a method specified in the RS-approved
technical documentation. Unless otherwise is provided by the project, the cable laying shall be
carried out by running method providing continuous performance of the whole scope of work
in the specified production sequence.
1.5 Where it is required to spool a cable on the drum installed on the ship,
the RS surveyor shall check that the spooling procedure is carried out by the RS-approved
method complying with the allowable bend radii of cables, pay-in speed, cable tension values,
correct pay-in, absence of sudden changes in cable tension and cable coils overlap on the
drum.
1.6 The RS surveyor shall make sure that when laying the cable lines in compliance
with the RS-approved project, depth data, current velocity and sea water wave motion on the
route, prevailing directions and values of wind force, profile and content of seabed soil,
including its geological and geotechnical parameters shall be monitored.
1.7 When laying the cable at negative temperatures, the RS surveyor shall check
that the cable coils are free of icing. Cable storage temperature and temperature during
submerging and laying the cable on the seabed shall not be less than the values
recommended by the cable manufacturer.
1.8 When paying-out the cable from the ship, the RS surveyor shall make sure that
the forces imposed on the cable, uniformity of pay-out and absence of sudden changes in
cable tension, bends and fractures due to the coils freezing-up, improper factory pay-in,
sudden change of pay-out speed are monitored.
1.9 The RS surveyor shall check that the cable pulling devices are equipped with the
recorders for cable line tension and length. All measuring equipment shall be calibrated. Prior
to the actual cable laying, pulling force of the devices shall be checked by testing. The specified
static towing force (rated static force of pulling devices) shall exceed the maximum pulling
force during laying.
1.10 Physical contact between a new cable and the existing ones shall be avoided.
The RS surveyor shall verify that the crossings of subsea cable routes and pipelines comply
with the RS-approved documentation (documentation shall be approved according to the
requirements of 8.2.3, Part I "Subsea Pipelines" of the Rules for the Classification and
Construction of Subsea Pipelines (SP Rules)).
1.11 The RS surveyor shall make sure that during cable operations (laying, pulling-in, connection of sections, lowering to the seabed, burial), continuous monitoring is provided that cables are not subjected to mechanical loads exceeding design limits specified by the cable manufacturer, including tension, bending, torsion and compression.

2 CABLE LAYING ON THE SEABED

2.1 The RS surveyor shall check that the method of protection against mechanical damages and/or subsea cable burial depth, considering data on the sea depth, current parameters, seabed profile, geological and geotechnical features of the soil properties, comply with the RS-approved technical documentation. The RS surveyor shall check that in the water areas with seasonal ice cover where the presence of ice gouging is revealed, the burial depth assumed based on the design value of exaration, which may be determined by methods specified in 8.3.1, Part I "Subsea Pipelines" of the SP Rules or other RS-approved methods, shall comply with the RS-approved technical documentation.

2.2 The RS surveyor shall make sure that the cable-laying vessel is equipped with a cable tensioner to create the required tension when laying cable on the seabed and the pulling force corresponds to the rated value.

2.3 The cable-laying vessel shall be equipped with a stern cable laying device (chute, stinger). The RS surveyor shall make sure that the radius of the stern cable laying device at the place of the cable contact shall not be less than the minimum allowable cable bend radius specified by the cable manufacturer. Technical parameters of the chute shall comply with the RS-approved documentation.

2.4 The RS surveyor shall make sure that the length of the lowered cable is constantly monitored on the cable-laying vessel.

2.5 The RS surveyor shall make sure that the subsea cable lines are provided with the protection area 500 m wide in each direction from the cable laying range that shall be indicated in the notices to mariners and plotted on nautical charts.

2.6 The RS surveyor shall check that the technical features of the trenchers allow the cable burial on the design depth.

2.7 Deployment/removal of trenchers shall not be carried out within 50 m radius from each near-bed structure.

2.8 Operations on cable laying on the seabed soil, installation of supports or burial shall be continuously monitored both by means of measurement equipment on the machinery and from the surface by using ROV, navigational systems and echo sounders. The Register shall review examination results for deviations from the values specified in the technical documentation.

2.9 The minimum cable bend radius during laying shall not be less than the value indicated in the documented technical data of the cable manufacturer.

2.10 The Register shall be provided with the materials of monitoring the cable laying on the seabed or cable burial depth performed by means of underwater TV, sonar survey or diver survey after cable laying.

2.11 Immediately after cable laying the Register shall be provided with the examination results of the entire route. The examination shall confirm that the cable laying has been carried out in accordance with the requirements specified in the technical documentation.

2.12 The examination shall include the following:
- determination of the cable position with regard to allowable tolerances;
- determination of burial depth, where applicable, if not ascertained during burial operations;
- identification and quantification of any free spans/non-buried sections with length and gap height;
- positioning and description of previously unidentified wreckage, debris or other objects which may affect the cable line;
localization of damage to cable;
video documentation of the subsea cable system interfaces at offshore units, if applicable and required;
verification that the condition of cable protection is in accordance with the design specification;
recording of length, cross-profiles, covering height of cable protection, if applicable;
check of any existing infrastructure in close vicinity in order to ensure, that the infrastructure has not suffered damage.
If necessary, relevant renewal shall be carried out; herewith, the relevant sections shall be reexamined. The examination results shall be submitted to the Register.

3 PULLING-IN AND INSTALLATION OF THE SUBSEA CABLE ON FOP

3.1 Monitoring of cable pulling in the FOP standpipe shall be carried out by using the following:
equipment to measure the cable tension both on FOP and on cable-laying vessel;
visual cable monitoring by use of ROV and/or diver survey with video documentation or alternative methods of survey near the entry of I- or J-tube to define free span form, length of seabed contact (if any), cable catenary radius and cable twisting, detection of possible loops and kinks.
3.2 The RS surveyor shall make sure that the tensioning device to pull the cable in the protective pipes is equipped with a recorder and automation shutdown device when the maximum allowable tension is reached. The maximum lateral force in bends of protective pipes (standpipes) that does not cause cable deformation during pulling-in shall comply with the design value.
3.3 The RS surveyor shall make sure that to limit the cable bending and avoid its damage, at the entry of J-tube a special bend restrictor shall be fitted limiting the cable bend radius during pulling-in within allowable tolerances specified by the cable manufacturer.
3.4 The RS surveyor shall make sure that the further pulling-in stages of subsea cable on FOP are monitored by divers or ROV-mounted video camera:
pulling-in head movement to the entrance of I- or J-tube bellmouth to avoid its possible locking;
installation of seals and bend restrictor on the entry of I- or J-tube.
The results of examination shall be submitted to the Register.
3.5 The integrity of conductor shall be monitored during laying and pulling-in at intervals specified in the project. In case where the continuity is damaged, the operation shall be abandoned (if provided by the approved procedures) and the conductors shall be tested for electrical resistance.
3.6 The RS surveyor shall make sure that the installation of cable on FOP is not carried out near the heat sources; otherwise the grounds shall be provided that the insulation at rated current withstands the applied temperatures and heat accumulation in these places.
3.7 The RS surveyor shall make sure that the fixing devices are installed in accordance with the technical documentation and are made of steel adequately protected against corrosion or non-metallic materials with appropriate properties.
3.8 The RS surveyor shall make sure that upon completion of the cable pulling in the protective standpipes, the cables are fixed on the standpipe upper flange, the cores are laid in the terminal boxes. In case of the cable hanging, the RS surveyor shall check that it is securely fixed and the mechanical loads are transferred from the cable to the hanging structure.
3.9 Connection and termination of cable cores, earthing of metallic cable sheaths and metallic coupling covers and enclosures shall be carried out in accordance with the approved wiring diagrams. Connecting couplings and termination elements shall comply with the cable parameters and be compatible with switchgear on voltage, dimensions, operating conditions and applied structural materials.
3.10 Upon completion of pulling-in and connection of cable in the witness of the RS surveyor, the following shall be carried out:
- check of damages to sheath and water ingress inside the cable;
- check of cable core integrity (DC resistance of conductor);
- check of cable phases;
- measurement of cable insulation resistance (including fibre optic cable, where applicable);
- cable overvoltage testing (DC or AC beyond low frequency);
- measurement of optical fibre features received by optical reflectometer, which record shall be obtained for each fibre and, if possible, from both ends;
- integrated cable load testing.

Received values shall be compared with the factory test report, any deviations shall be recorded.

3.11 Additional examination shall confirm that the cable and the relevant equipment (e.g. weak link, bend restrictor, protection) are installed in accordance with the specified requirements and all temporary installation devices are removed.
RECOMMENDATIONS ON MEASUREMENT OF THE TOTAL HARMONIC DISTORTION

1. The total harmonic distortion (hereinafter, $K_u$) shall be measured on ships where the aggregate power output of the semi-conductor converters exceeds 20% of the total power output generated by the main supply sources.

2. The total harmonic distortion $K_u$ shall be measured by a power quality analyzer or a similar instrument intended for the appropriate measurements.

3. The measurements may be taken by the standard fixed electrical instruments having function of measuring or recording the total harmonic distortion $K_u$ or the voltage curve harmonic components.

4. Values of the total harmonic distortion $K_u$ are specified for the complete ship’s power system and shall not exceed the values given in 2.2.1.3, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

5. In case of harmonic filters in the system with electrical power distribution (refer to 4.7, Part XI "Electrical Equipment" of the Rules for the Classification and Construction), the total harmonic distortion $K_u$ shall be measured with and without filters. Measurements without filters shall be taken in the permitted operating modes specified in the system integrator report (refer to 4.7.2, Part XI "Electrical Equipment" of the Rules for the Classification and Construction).

6. The total harmonic distortion $K_u$ shall be measured at the locations (electrical instrument connection points) specified in the RS-approved test programme, including but not limited to the following:
   1. on the main alternating-current switchboard busbars;
   2. in supply circuit of the electrical propulsion plant (EPP), if installed on board the ship, and/or the most powerful of the shipboard electric drives with semi-conductor converter;
   3. on agreement with RS, at the circuit segments where, according to the approved documentation, the design values of the total harmonic distortion $K_u$ exceed the values given in 2.2.1.3, Part XI "Electrical Equipment" of the Rules for the Classification and Construction.

7. Measurements shall be taken upon completion of transient processes in supply network in the steady-state operating modes.

8. The total harmonic distortion $K_u$ shall be tested and measured in different operating modes of the ship’s electric power plant (SEPP) and EPP at the points of the maximum estimated (design) total harmonic distortion $K_u$.

9. The total harmonic distortion $K_u$ shall be tested and measured with different number of operating supply sources (single and parallel operation) with the maximum permissible load of semi-conductor converters composing EPP or shipboard electric drive.

10. Modes with the maximum total harmonic distortion $K_u$ are the SEPP operating modes, in which the total power of the operating semi-conductor converters is the maximum in relation to the total power of supply sources operating in these modes.

11. For the ships equipped with EPP, the total harmonic distortion $K_u$ shall be measured, inter alia, during sea trials with the EPP maximum load prescribed for the specific SEPP operating mode.

12. For the ships not equipped with EPP, the total harmonic distortion $K_u$ may be measured during mooring trials with the possible operation of the most powerful semi-conductor transducers in modes close to the rated ones and operation of consumers under conditions close to operating ones.
The total harmonic distortion $K_u$ shall be measured during the period specified in the RS-approved test programme and required for taking measurements considering specifics of the SEPP ad EPP operating modes.

Based on the test results the total harmonic distortion $K_u$ calculation report shall be drawn up containing the following information:

1. measurement points (electrical instrument connection points) and duration;
2. list of the electrical instruments used for measurements and tests;
3. list of the shipboard electrical equipment in operation during measurements and tests. In case of a large number of equipment, it is allowed to indicate the main equipment (the most powerful of semi-conductor converters) and its specifications or references to design documentation;
4. measurement results for each test mode for each electrical instrument connection point.

The test results are considered satisfactory when the following conditions are met:

1. values of the total harmonic distortion $K_u$ during tests and measurements do not exceed the values given in 2.2.1.3, Part XI “Electrical Equipment” of the Rules for the Classification and Construction;
2. in case of exceeding the values given in 2.2.1.3, Part XI "Electrical Equipment" of the Rules for the Classification and Construction, the values of the total harmonic distortion $K_u$ shall correspond to design values given in the equipment design documentation;
3. electrical equipment remains operative in accordance with its purpose during and after tests and measurements. There is no deterioration (decrease) in performance or loss of functions defined in the relevant equipment standard and the manufacturer’s technical documentation.
11 REFRIGERATING PLANTS

11.1 GENERAL

11.1.1 The provisions of this Section shall apply in technical supervision of the marine refrigerating plants (MRP) listed in the RS Nomenclature.

11.1.2 The Section defines the scope, procedure and methods of surveys to be conducted in the process of technical supervision during installation and testing of the MRP on board ships under construction.

11.1.3 When performing the technical supervision of MRP, the RS surveyor shall be guided by the provisions of this Section, Part I "General Regulations for Technical Supervision" and Part II "Technical Documentation" of the Rules for Technical Supervision.

11.1.4 In order to perform technical supervision during the installation and testing of MRP, the shipyard shall submit the documentation approved by the Register within the scope specified by Rules for the Classification and Construction according to the examination and testing plan as specified in 11.1.8.

The related products shall have documents and brands according to the type of technical supervision given in the RS Nomenclature.

11.1.5 The related products and equipment of MRP supplied to the shipyard shall be verified by the RS surveyor against certificates or documents of the firm (manufacturer) in accordance with the type of technical supervision.

11.1.6 The refrigerating equipment and products indicated in the RS Nomenclature and manufactured by the shipyard, which is the builder of the ship, shall be subject to survey and testing prior to their installation in compliance with Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

11.1.7 Technical supervision during the installation and testing of the refrigerating equipment shall be performed in accordance with Table 11.1.7. The scope of individual examinations, measurements, verifications and tests provided for by Table 11.1.7 shall be established on the basis of the requirements of the Rules for the Classification and Construction and the Guidelines.

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<th>Tests</th>
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<td>Heat exchangers, pressure vessels, cooling, freezing and ice making facilities under secondary refrigerant pressure</td>
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### Guidelines on Technical Supervision of Ships under Construction (Section 11)

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</table>

1. Gas-tightness tests.
2. For non-classed MRP — only in refrigerant system.
3. Tests are intended only for the spaces of refrigerating machinery working with Group II refrigerants.

**Notes:**
1. Surveys marked "+" are intended for classed and non-classed MRF.
2. Surveys marked "++" are intended for classed MRP only.
3. Checks indicated under column 3 — in accordance with 11.1.4, 11.1.5.
4. Tests indicated under columns 5, 6 and 7 are conducted upon finalization of installation within systems.
5. Tests indicated under column 7 are intended only for Group I refrigerant systems.

**11.1.8** The scope and procedure of the Register technical supervision of MRP during construction of the ship shall be defined by the examination and testing plan developed in accordance with 13.3, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision, taking into account Table 11.1.7 and Chapters 11.2 and 11.3 of the Guidelines.
The List shall be compiled by the shipyard on the basis of the RS Nomenclature, Part I "Classification" and Part XII "Refrigerating Plants" of the Rules for the Classification and Construction (with due account of the MRP installation and ship construction processes adopted at the shipyard) and agreed with the Register.

11.1.9 The List for the MRP of a series-built ship shall be updated on the basis of the results of technical supervision during construction of a prototype ship and MRP of ships of the design concerned in service. When compiling the List, account shall be taken of surveys at the intermediate and final stages of manufacture of the items of technical supervision.
11.2 SURVEY DURING INSTALLATION

11.2.1 MRP spaces, arrangement and installation of refrigerating equipment.

11.2.1.1 When surveying the MRP spaces, it is necessary to check the fulfilment of the requirements for gastightness, equipment of control stations and maintenance positions, arrangements of passageways, main and emergency escape routes (including ladders), as well as their closing arrangements.

11.2.1.2 Test of the MRP spaces for gas-tightness shall be conducted on completion of the major assemblywelding hull work prior to installation of insulation; in so doing, the test positive air pressure shall be of 2 kPa and the permissible standard for the compressed air pressure drop within one hour shall be not higher than 25 % of the initial test pressure, that is, on the expire of one hour the pressure in the tested space shall be not less than 1,5 kPa.

11.2.1.3 In the course of survey of the MRP installation it is necessary to check:

1. compliance of the arrangement of the refrigerating equipment (including control, monitoring, alarm and protection devices) with the requirements of the approved technical documentation;
2. correctness of piping installation and reliability of their protection against damages;
3. fastening of the refrigerating equipment (the adopted fastening methods shall be suited to the requirements of Section 5);
4. alignment of the MRP machinery;
5. installation of the insulation (only for classed MRP).

11.2.2 Survey of safety valves and devices.

11.2.2.1 Prior to installation on board the ship, the safely valves intended for protection of the MRP machinery, heat exchangers and pressure vessels shall be surveyed and tested, in so doing:

1. the valve shall be set to initial opening pressure not exceeding the design pressure by more than 10 %. When the safety valve is open, the pressure shall not rise by more than 10 % of the initial opening pressure;
2. the valve shall close under the pressure not less than 0,85 the design pressure;
3. the tightness of closure of the valve under water shall be checked by repeat rise of the pressure up to the design pressure after the valve is closed due to its operation.

11.2.2.2 Survey of the change-over fittings of the safety devices shall be carried out in conformity with the requirements of Section 11, Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.

11.2.2.3 Laboratories performing adjustment and tests of the safely valves shall be recognized by the Register in accordance with the requirements of Section 9, Part I “General Regulations for Technical Supervision” of the Rules for Technical Supervision.

11.2.3 Survey of refrigerant system.

11.2.3.1 Inspection of the welded butt joints of the refrigerant piping shall be performed by one of the nondestructive testing methods permitted and accepted by the Register at the shipyard concerned. The lap welded joints and others the quality of which cannot be verified by non-destructive testing may be tested by hydraulic pressure of 1,5P adopted in accordance with 12.1.2, Part XII “Refrigerating Plants” of the Rules for the Classification and Construction.

If the RS surveyor has any doubt concerning the quality of a weld, he shall reserve the right to require that hydraulic tests are conducted.

11.2.3.2 Particular emphasis shall be placed on verification whether the flow area of the pipes for refrigerant dumping and carrying off from the safety valves complies with the documentation approved by the Register. Possibility of the pipes for carrying off the refrigerant from the safely valves shall be checked by delivery of compressed air thereinto, with the pipes disconnected from the safety valves.

11.2.3.3 The shut-off fittings and piping of the classed MRP shall be checked during the leak test of the system by stage-by-stage connecting the system sections to cold consumer groups and raising the pressure in these sections up to 1,1 the design pressure.
11.2.3.4 On completion the installation work, the refrigerant system shall be tested for leak by a test pressure equal to the design pressure, during 18 h. In so doing, the total pressure drop during the test shall be not more than 2 % of the initial pressure. The test shall be conducted using nitrogen, carbon dioxide or dried air with the steam saturation temperature (dew point) not higher than –45 °C.

After the leak tests, in order to verify the refrigerant dumping system the pressure shall be released by alternate opening of valves at the emergency drain station.

11.2.3.5 The refrigerant system shall be tested for tightness as stipulated for the classed refrigeration plants using Group I refrigerants by vacuum test at a residual pressure adopted in accordance with the requirements of 12.2, Part XII “Refrigerating Plants” of the Rules for the Classification and Construction. On completion the vacuum test, the system shall be kept under vacuum during 12 – 18 h. In this period, the pressure in the system shall not rise by more than 0,65 kPa; during the first hour — by not more than 0,15 kPa.

Prior to the tightness test, the system shall be dried, as a rule, by a vacuum test. The vacuum test shall last for 6 h after the pressure in the system reaches the value stipulated for the tightness tests.

11.2.3.6 The system may be filled with the refrigerant only if the results of the tightness and leak tests are satisfactory, the secondary refrigerant system was filled, as well as the ventilation, secondary refrigerant and cooling water system and the fixed gas analyzers (if any) for detecting presence of refrigerant vapours in the MRP spaces were completely surveyed.

After the system is filled with the refrigerant, information on check of the system assemblies for leak with the use of portable leak detector shall be submitted to the RS surveyor.

11.2.4 Survey of secondary refrigerant and cooling water system of classed MRP.
11.2.4.1 Secondary refrigerant and cooling water systems shall be tested for leak by a hydraulic pressure equal to the working pressure with the time of keeping under the pressure not less than 1 h.

11.2.4.2 When surveying the systems, it is necessary to check condition of the expansion compensators, secondary refrigerant and cooling water draining arrangements, bulkhead sockets, piping securing and protection against mechanical damages, cathodic corrosion protection and insulation, local and remote driving gear of fittings, side fittings. It is necessary to check reliability of the shut-off fittings by stage-by-stage connection of the system sections during the hydraulic tests to the cold consumer groups and cooling water circuits, accordingly.

11.2.5 Survey of air cooling systems of classed MRP and space ventilation systems.
11.2.5.1 The installation of air cooling and ventilation systems shall be submitted to the surveyor two times: prior to insulation work and after insulating the air conduits.

11.2.5.2 When surveying the air cooling and space ventilation systems of the MRP, it is necessary to check:

1. air conduit and trunk penetrations through the watertight and fire-resistant divisions;
2. presence of flame-arresting fittings at ventilation outlets of dangerous spaces;
3. intrinsically safe design of fans in dangerous spaces;
4. location of inlets of the supply ventilation in relation to the deck of cargo compartments, venting pipes, etc.;
5. location of outlets of exhaust ventilation of dangerous spaces in relation to the air intakes;
6. gas- and air-tightness of the air conduits (tests shall be earned out in accordance with 11.2.1.2);
7. insulation of the air conduits of the air cooling systems.

11.2.6 Survey of insulation of the refrigerated spaces, systems and apparatus of classed MRP.

11.2.6.1 When surveying the insulation to verify its compliance with the RS-approved documentation, it is necessary to check the applied types (grades) of insulation materials, thickness and attachment of the insulation, assembly units in way of framing and penetrations of pipes, as well as the design of the insulation assemblies of hatches and doors, as well as the reliability of the insulation and lining fastening.
11.3 OPERATIONAL TESTS OF MRP

11.3.1 Scope and procedure of tests.

11.3.1.1 Operational tests of MRP shall be conducted by the shipyard in accordance with a program approved by the Register, in the presence of the RS surveyor.

11.3.1.2 The operational tests of non-classed MRP shall be conducted solely to determine the safety in operation of the equipment which influence the ship safety. When conducting such tests of the MRP, it is necessary to check in operation:

1. the electrical equipment in accordance with the requirements of Section 10;
2. the main and emergency ventilation of the refrigerating machinery space and refrigerant storeroom, spaces containing process equipment under refrigerant pressure and cargo spaces with cooling devices under refrigerant pressure (including determination of the capacity of fans);
3. the drying systems of the MRP spaces in accordance with the requirements of Section 8;
4. the water screen systems of the exits from the MRP spaces in accordance with the requirements of Section 4;
5. the protection automatic devices and remote machinery shutdown devices in accordance with the requirements of Section 12. The maximum permissible settings of the protective devices shall be in agreement with the instructions of the manufacturers of refrigerating equipment and the Register-approved technical documentation on the refrigerating plant (the protective device setting for compressor discharge pressure shall not exceed 0.9 of the design pressure).

11.3.1.3 The tests of classed MRP shall confirm effectiveness in operation of the plant under prescribed environment temperature conditions including the minimum design ones at full design heat load of the refrigerating equipment, as well as the reliability and safety of the plant.

The operational tests of classed MRP shall consist of the following major stages:

1. check of the overall operability of the components in serving their intended services;
2. check of the MRP capability of reaching the temperatures in refrigerated cargo spaces, freezing apparatus and other items of refrigeration down to the lowest specified value. The duration shall be established on the basis of the time actually spent;
3. tests to maintain the specified values of air temperatures in the refrigerated cargo spaces and temperatures of refrigerated media in other items of refrigeration during not less than 24 h. During the said tests it is necessary to check the capacity of the freezing, ice making and cooling facilities (water and process media coolers, etc.). The duration of check shall depend on the design features of a particular facility or device and MRP;
4. determination of the averaged heat gain factor of an insulation structure of the refrigerated cargo spaces using methods approved by the Register;
5. determination of the rate of air temperature change in the refrigerated cargo spaces with the MRP put out of action. Duration of the test is 12 h.

11.3.1.4 When checking the overall operability of classed MRP components, in addition to the equipment and devices specified in 11.3.1.2, it is necessary to survey the machinery, apparatus and systems of the refrigerant, secondary refrigerant, cooling water and cargo space refrigeration, etc.

11.3.1.5 During the tests it is necessary to determine the time required to reach the specified temperatures in the cargo spaces and the refrigerated media temperatures in other items of refrigeration since the MRP is put into operation, as well as the duration of defrosting.

11.3.1.6 When surveying the secondary refrigerant systems, it is necessary to check consistency of the secondary refrigerant density and acid number with the required values, operation of the shut-off and regulating fittings (including those on the secondary refrigerant heater), steam supply to the secondary refrigerant heater, operation of the regulating and protective automatic devices.

11.3.1.7 When surveying the cooling water system it is necessary to check the operation of cooling arrangements, shut-off and regulating fittings; device to provide re-circulation and temperature regulation of water delivered for cooling (or its flow rate change); regulating and protective automatic devices.
11.3.1.8 When surveying the air cooling system it is necessary to check capacity of the fans, circulation ratio and uniformity of air distribution in the cargo spaces, alarm devices to warn of the fan damages and ozone generators (if any).

11.3.1.9 The test conditions are given in Appendix 1 and the requirements for measurement of the MRP performance parameters – in Appendix 2 to this Section.

11.3.1.10 During the operational tests of MRP it is necessary to check the stand-by equipment of the system by disabling individual components of the main equipment and by actuation of corresponding components of the standby equipment. In so doing, the main and stand-by equipment shall be in service not less than 12 h.

11.3.1.11 The tests of MRP shall be conducted with the automatic control and regulating devices functioning. During the tests, local control (if provided) shall be also checked.

11.3.1.12 Measurements of the vibration level under various modes shall be made in accordance with \( \text{18.7}. \)

11.3.1.13 The averaged heat gain factor of the insulation structure of the refrigerated cargo spaces shall be determined in accordance with 11.3.1.3.4 on board the prototype ships, and as regards the series-built ships, the factor shall be determined only when the insulation structure and/or insulation material is changed as compared to the prototype ship.

11.3.1.14 On board the series-built ships, if no significant modifications have been made in the MRP design of the prototype ship (e.g. replacement of the main equipment), the duration of the tests under 11.3.1.3.3 may be reduced down to 16 h.

11.3.2 Processing, presentation and evaluation of classed MRP test results.

11.3.2.1 Test results shall be processed and presented by the shipyard immediately upon finalization of the tests.

11.3.2.2 The processed test results shall be submitted to the RS surveyor prior to final delivery of the MRP with necessary data for execution of the RS documents. A conclusion on the compliance of the MRP and its equipment characteristics with the specified ones shall be attached to the delivery documents on the test results.

11.3.2.3 The specified values of the averaged heat gain factor of insulation structure of the refrigerated cargo spaces shall be considered as confirmed if the values obtained during the tests differ from the design ones by not more than 10%.

11.3.2.4 For the series-built ships, where the insulation structure of the refrigerated cargo spaces has not been significantly modified as compared to that of the prototype ship, the thermal properties of insulation shall be evaluated by comparison of the rate of change in the air temperature in the refrigerated cargo spaces of the ship being tested and prototype ship without especial determination of the averaged heat gain factor value. Along with that, if the obtained value of change of the air temperature in the refrigerated cargo spaces differs from the corresponding value for the prototype ship by not more than 10% the specified values of the heat gain factor shall be considered as confirmed.

In case where the environment temperatures during the series-built ship tests differ from those during the prototype ship tests, the results of the check on the rate of change of the air temperature in the refrigerated cargo spaces of the series-built ship shall be re-calculated to the environment temperature during the tests of the prototype ship using the procedure to be submitted by the ship designer within the program (procedure) of the series-built ship MRP tests.

11.3.3 Documents of the Register.

11.3.3.1 Based on the satisfactory results of the survey and tests, the RS surveyor shall draw up:

- for classed MRP, Report on Survey of Classed Refrigerating Plant (form 6.3.47) and Classification Certificate for Refrigerating Plant (form 3.1.4);
- for non-classed MRP, Report on Survey of Machinery Installation, Systems after Completion of Ship Construction/Initial Survey (form 6.3.3).
TEST CONDITIONS FOR CLASSED MRP

1. During tests of the MRP it is necessary to check the maintenance of all air temperatures in the refrigerated cargo spaces, on board fishing ships – also the air and process media temperatures in other items of refrigeration, provided for by the design, when all the cold consumers operate under the design heat load at the specified refrigerant boiling and condensing temperatures.

2. When during the tests the sea water temperature differs from the design temperature, the condensing temperature can be maintained through re-circulation of water incoming to cool the water condenser or reduce the consumption thereof.

3. If MRP is designed for aftercooling (afterfreezing) the products in the cargo spaces or for cooling the un precooled products therein, then, when conducting tests for the maintenance of the specified values of air temperatures, heaters of the required capacity shall be installed in the refrigerated cargo spaces to simulate the heat load due to cooling (aftercooling, afterfreezing).

   The heaters shall be installed in the refrigerated cargo spaces also in case when the tests are conducted at the environment temperatures differing from the specified ones (to simulate the design heat load under specified conditions).

   The capacity of the heaters installed during the tests shall be calculated by the Ship Designer for various possible values of the environment temperatures during the period of testing according to Appendix 3 to this Section and submitted within the MRP test program (procedure)

4. The design heat load of the refrigerating equipment may be achieved by means of infra-red or radiant heaters fitted with their own fans used in the cargo and other refrigerated spaces, as well as by heating the liquid process media: water, salt brine, etc.

   In case where air cooling system is used in the cargo and other spaces, the heaters used need not be fitted with their own fans.

5. The prescribed temperature in the refrigerated cargo spaces (including the temperature difference at various points of the hold volume) shall be maintained in consistency with the values set by the specifications of the refrigerating plant for particulars kinds of cargoes carried on board ship. When such specifications are lacking, the variations in the prescribed temperature shall be within ±2 °C.

6. When determining the averaged heat gain factor of the insulation structure of the refrigerated cargo spaces, the averaged air temperature difference in the refrigerated spaces and the averaged environment temperature difference shall be not less than 30 °C.

   Depending on the environment temperatures during the tests, the averaged heat gain factor of the insulation structure of the refrigerated cargo spaces may be determined either by heating the air in the spaces being tested or by cooling the same. Preference (if the environment temperatures during the tests permit this) shall be given to the determination of the heat gain factor by heating the air because this method is the simplest and provides superior fidelity of the results.
MEASUREMENT OF THE CLASSED MRP PARAMETERS

1. Prior to the tests, a list (in tabular form) of the gauges used during MRP tests with an indication of the value (parameter) to be measured, gauge type, GOST and/or specifications, measurement ranges, scale division value, accuracy class and date of the last gauge verification shall be submitted to the RS surveyor.

2. Each gauge shall be installed in a fixed position where measurements shall be taken during the entire period of test. The gauge may be replaced only with the consent of the RS surveyor or at his request to which effect an entry shall be made in the log book.

3. During the tests referred to under 11.3.1.3.1 – 11.3.1.3.3, the MRP performance parameters shall be generally measured by regular gauges every 2 h.

4. Additional means shall be provided during the tests referred to under 11.3.1.3.4 and 11.3.1.3.5 to measure the air temperature in the spaces adjacent to the spaces being refrigerated, outdoor and sea water temperatures, as well as, where necessary, in the refrigerated cargo spaces (including measurements to be taken to verify the fulfilment of the requirements under para 5 of Appendix 1 to this Section).

5. Measurements of the air temperatures in the refrigerated cargo spaces and spaces adjacent thereto, as well as of the outdoor and sea water temperatures when the rate of change of the air temperature is determined (refer to 11.3.1.3.5) shall be made every hour.

6. In case when the averaged heat gain factor of the insulation structure of the refrigerated cargo spaces is determined (refer to 11.3.1.3.4 of this Section and paragraph 6 of Appendix 1 to this Section) by cooling method, for the purpose of measuring the MRP performance parameters during the period of tests it is necessary to install additional gauges with the required accuracy of measurements. Measurements shall be made every hour.
TESTS OF THE CLASSED MRP WITH THE USE OF SIMULATION MEANS

1. General

1.1 Classed MRP shall be tested at full design heat load. Because during the MRP tests the environment temperature can differ significantly from the design temperature, heat leakage into the refrigerated cargo spaces will also differ from the design ones. Moreover, during the MRP tests, the opportunity of real cooling (aftercooling, afterfreezing) of the cargo (thermal treatment of cargo and tare) is generally not offered. In such cases, the generation of the full design heat load shall be provided by simulation means — by installation of electrical heaters of required capacity in the refrigerated cargo for the period of test.

The additional heat load generated by the heaters includes two components — variable ($\Delta Q_{\text{var}}$) and permanent ($\Delta Q_{\text{perm}}$).

The variable component of the additional heat load depends on the environment temperatures during the tests and may be different on acceptance tests of various ships of a series and for the same ship during different periods of service.

The permanent component of the additional heat load does not depend on the environment temperature and is the same for all ships of the same type (design) provided that the ship has not undergone conversion or modernization with the resulting alteration of the cargo storage or thermal treatment conditions.

2. Calculation of the variable component of the additional heat load

2.1 The variable component of the additional heat load $\Delta Q_{\text{var}}$, in kW, shall be determined by the formula

$$
\Delta Q_{\text{var}} = 0.001 \cdot \Sigma F_i K_{av} (\Delta t_{av,\text{des}} - \Delta t_{av,\text{test}})
$$

(2-1)

where $\Sigma F_i$ = area of all cooling surfaces of the refrigerated cargo space, in m$^2$;

$K_{av}$ = design averaged heat gain factor of the insulation structure of the boundaries, in W/m$^2\text{°C}$;

$\Delta t_{av,\text{des}}$ = averaged air temperature difference between the refrigerated space and the environment according to design, in °C;

$\Delta t_{av,\text{test}}$ = averaged air temperature difference between the refrigerated space and the environment during tests, in °C.

The calculation of $\Delta t_{av}$ is tabulated. The calculation of $\Delta Q_{\text{var}}$ is displayed below the table (refer to Table 2.1).

$\Delta t_{av}$ mentioned in Table 2.1 is a correction to the temperature of the boundary surface for the solar radiation, which shall be taken into consideration only in calculation of $\Delta t_{av,\text{des}}$.

Calculation of the variable component of the additional heat load $\Delta Q_{\text{var}}$ shall be made for each refrigerated cargo space provided with its own refrigerating system (adjacent hold and tweendeck separated by a perforated deck and having a common refrigerating system shall be considered as one space). Depending on the larger $\Delta t_{av}$ value (design or test), $\Delta Q_{\text{var}}$ may be both positive and negative.
Calculation of the averaged air temperature between the refrigerated space and the environment according to design and during tests and of the variable component of the additional heat load (model form)

<table>
<thead>
<tr>
<th>External boundaries</th>
<th>Adjacent space or medium</th>
<th>Cooling surface area, in m²</th>
<th>Air temperature in cargo space, °C</th>
<th>Medium temperature in adjacent space, °C</th>
<th>Temperature difference Δtₐ, in °C</th>
<th>Fᵢ × Δtᵢ value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ceiling</td>
<td>Fish-processing shop</td>
<td>269</td>
<td>-28</td>
<td>20</td>
<td>15</td>
<td>48</td>
</tr>
<tr>
<td>Bottom</td>
<td>Diesel oil tanks</td>
<td>265</td>
<td>-28</td>
<td>11</td>
<td>0</td>
<td>39</td>
</tr>
<tr>
<td>Starboard side:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>above waterline</td>
<td>Outdoor air</td>
<td>11.5</td>
<td>-28</td>
<td>15</td>
<td>-10</td>
<td>43</td>
</tr>
<tr>
<td>below waterline</td>
<td>Sea water</td>
<td>65.3</td>
<td>-28</td>
<td>11</td>
<td>0</td>
<td>39</td>
</tr>
<tr>
<td>Port side:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>above waterline</td>
<td>Outdoor air with due account of Δtₐ</td>
<td>11.5</td>
<td>-28</td>
<td>29</td>
<td>-10</td>
<td>57</td>
</tr>
<tr>
<td>below waterline</td>
<td>Sea water</td>
<td>65.3</td>
<td>-28</td>
<td>11</td>
<td>0</td>
<td>39</td>
</tr>
<tr>
<td>Forward</td>
<td>Bow thruster trunk</td>
<td>24</td>
<td>-28</td>
<td>15</td>
<td>5</td>
<td>43</td>
</tr>
<tr>
<td>bulkhead</td>
<td>Fresh water tank</td>
<td>16.5</td>
<td>-28</td>
<td>15</td>
<td>5</td>
<td>43</td>
</tr>
<tr>
<td>Fire pump room</td>
<td>14.7</td>
<td>-28</td>
<td>23</td>
<td>0</td>
<td>51</td>
<td>28</td>
</tr>
<tr>
<td>Aft bulkhead</td>
<td>Engine room</td>
<td>56</td>
<td>-28</td>
<td>23</td>
<td>15</td>
<td>51</td>
</tr>
</tbody>
</table>

\[ \Delta Q_{\text{test}} = 0.001 \cdot F_{\text{i}} \cdot k_{\text{e}} (\Delta t_{\text{avg,design}} - \Delta t_{\text{avg,test}}) = 0.001 \cdot 798.8 \cdot 0.4 (43.6 - 34.1) = 3.0 \text{ kW}. \]

3. Calculation of the permanent component of the additional heat load

3.1 The permanent component of the additional heat load shall be determined from the formula

\[ \Delta Q_{\text{perm}} = Q_{\text{tc}} + Q_{\text{tt}} + Q_{\text{h}} + Q_{\text{m}} + Q_{\text{b}} \]  

(3.1)

where

- \( Q_{\text{tc}} \) = heat leakage due to thermal treatment of cargo, in kW;
- \( Q_{\text{tt}} \) = heat leakage due to thermal treatment of tare, in kW;
- \( Q_{\text{h}} \) = heat leakage due to human occupancy, in kW;
- \( Q_{\text{m}} \) = heat leakage due to running of equipment of in-hold mechanization (if any), in kW;
- \( Q_{\text{b}} \) = heat leakage due to "breathing" of vegetables and fruits, in kW.

For reefer transport ships \( Q_{\text{h}} \) and \( Q_{\text{m}} \) shall be neglected. For fishing ships (catching and processing) \( Q_{\text{m}} \) shall be neglected in cases when during the MRP tests the in-hold mechanization equipment is in operation and such equipment is not provided on board ship. \( Q_{\text{h}} \) shall be taken into account only for the universal reefer transport ships intended also for the carriage of fruits and vegetables.

3.2 Heat leakage due to thermal treatment of cargo shall be determined by the formula

\[ Q_{\text{tc}} = C_{\text{c}} \times (i_{\text{ic}} - t_{\text{fc}}) / 3600Z \]  

(3.2-1)

(for frozen meat and fish, as well as butter and fats) or from the formula

\[ Q_{\text{tc}} = C_{\text{c}} \times C_{\text{r}}(t_{\text{ic}} - t_{\text{fc}}) / 3600Z \]  

(3.2-2)

(for refrigerated kinds of cargo)

where

- \( C_{\text{c}} \) = capacity of the refrigerated space for a particular cargo for the reefer transport ship or daily delivery of produce into the refrigerated space for the catching and processing fishing ships, kg;
- \( i_{\text{ic}} \) and \( t_{\text{ic}} \) = enthalpy, in kJ/kg, and temperature, in °C, of the cargo (product) entering into the refrigerated space respectively;
The enthalpy and specific heat of the basic kinds of cargo carried on the reefer transport ships and kinds of produce on the fishing ships are given in Tables 3.2-1 and 3.2-2.

3.3 Heat leakage due to thermal treatment of tare shall be determined by the formula

\[ Q_{tt} = G_t \times C_t (t_{it} - t_{ft}) / 3600Z \]  

(3.3)

where \( G_t \) = mass of tare necessary for packing cargo (products) \( C_t \) (refer to 3.2), in kg;
\( C_t \) = specific heat of tare material, in kJ/kg°C;
\( t_{it} \) and \( t_{ft} \) = initial and final temperature of tare, in °C (correspond to \( t_{ic} \) and \( t_{fc} \) under 3.2);
\( Z \) = same as under 3.2.

The mass of the cardboard tare for frozen fishery products, dressed meat, poultry and meat semiproducts, as well as vegetables and fruits (including banana) shall be assumed to be 10% of the mass of cargo, i.e. \( G_t = 0.1G_c \).

The specific heat of some tare materials is given in Table 3.2-2.

<table>
<thead>
<tr>
<th>Temperature of cargo, in °C</th>
<th>Frozen meat, poultry</th>
<th>Frozen fish</th>
<th>Butter, fats</th>
</tr>
</thead>
<tbody>
<tr>
<td>20</td>
<td>—</td>
<td>—</td>
<td>182.8</td>
</tr>
<tr>
<td>15</td>
<td>—</td>
<td>15</td>
<td>155.3</td>
</tr>
<tr>
<td>12</td>
<td>—</td>
<td>—</td>
<td>138.6</td>
</tr>
<tr>
<td>10</td>
<td>—</td>
<td>—</td>
<td>129.8</td>
</tr>
<tr>
<td>8</td>
<td>—</td>
<td>—</td>
<td>121.4</td>
</tr>
<tr>
<td>6</td>
<td>—</td>
<td>—</td>
<td>114.4</td>
</tr>
<tr>
<td>4</td>
<td>—</td>
<td>—</td>
<td>106.5</td>
</tr>
<tr>
<td>2</td>
<td>—</td>
<td>—</td>
<td>101.4</td>
</tr>
<tr>
<td>0</td>
<td>—</td>
<td>—</td>
<td>95.0</td>
</tr>
<tr>
<td>-2</td>
<td>—</td>
<td>—</td>
<td>60.4</td>
</tr>
<tr>
<td>-4</td>
<td>—</td>
<td>—</td>
<td>44.8</td>
</tr>
<tr>
<td>-6</td>
<td>—</td>
<td>—</td>
<td>36.4</td>
</tr>
<tr>
<td>-8</td>
<td>—</td>
<td>—</td>
<td>29.3</td>
</tr>
<tr>
<td>-10</td>
<td>30.2</td>
<td>74.3</td>
<td>23.5</td>
</tr>
<tr>
<td>-12</td>
<td>46.2</td>
<td>66.4</td>
<td>17.6</td>
</tr>
<tr>
<td>-15</td>
<td>13.0</td>
<td>56.2</td>
<td>10.1</td>
</tr>
<tr>
<td>-18</td>
<td>4.6</td>
<td>47.4</td>
<td>3.8</td>
</tr>
<tr>
<td>-20</td>
<td>0</td>
<td>42.0</td>
<td>0</td>
</tr>
<tr>
<td>-25</td>
<td>—</td>
<td>29.9</td>
<td>—</td>
</tr>
<tr>
<td>-30</td>
<td>—</td>
<td>19.1</td>
<td>—</td>
</tr>
</tbody>
</table>

The specific heat of some tare materials is given in Table 3.2-2.

<table>
<thead>
<tr>
<th>Description of cargo</th>
<th>Specific heat, in kJ/kg°C</th>
<th>&quot;Breathing&quot; heat, in W/kg</th>
</tr>
</thead>
<tbody>
<tr>
<td>Banana</td>
<td>3.35</td>
<td>0.105</td>
</tr>
<tr>
<td>Fruits, vegetables</td>
<td>3.8</td>
<td>0.035</td>
</tr>
<tr>
<td>Tare:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>corrugated board</td>
<td>2.5</td>
<td></td>
</tr>
<tr>
<td>Wooden</td>
<td>2.5</td>
<td></td>
</tr>
<tr>
<td>Cans:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Aluminium</td>
<td>0.88</td>
<td></td>
</tr>
<tr>
<td>Tin</td>
<td>0.45</td>
<td></td>
</tr>
</tbody>
</table>

Note. The average "breathing" heat in the temperature range: for bananas, from 30 to 15 °C, for fruit and vegetables, from 20 to 0 °C.
3.4 The heat leakage due to human occupancy shall be determined by the formula

\[ Q_h = a \cdot n \]  

(3.4)

where \( a = \) heat release from one person when performing work of medium intensity, \( (a = 0,35 \) kW/pers.); \( n = \) number of persons simultaneously working in the refrigerated cargo space.

3.5 Heat leakage due to running equipment of in-hold mechanization shall be determined by the formula

\[ Q_m = \sum (N_i \cdot \frac{1}{\eta_i}) \]  

(3.5-1)

where \( N_i \) and \( \eta_i = \) consumed power and efficiency of the electric motor of the in-hold mechanization equipment respectively.

This heat leakage may be determined also by a simplified formula

\[ Q_m = \sum N_i \]  

(3.5-2)

where \( \sum N_i = \) rated power of all electric motors of the in-hold mechanization equipment.

3.6 The heat leakage due to "breathing" of vegetables and fruit shall be determined by the formula

\[ Q_b = 0,001 \cdot q_b \cdot G_c \]  

(3.6)

where \( q_b = \) "breathing" heat of vegetables and fruit, in W/kg; \( G_c = \) capacity of refrigerated cargo space for a particular kind of vegetables and fruits, in kg.

The "breathing" heat of the fruit and vegetable products is given in Table 3.2-2.

3.7 For ships under construction, the data on the elements of the permanent component of an additional heat load \( Q_{TC}, Q_{TT}, Q_{H}, Q_{M}, Q_{B} \) shall be taken on the basis of thermal analysis of MRP made within the technical design.

4. Procedure of the MRP tests

4.1 The tests of the MRP of the reefer transport ships shall be carried out with the lighting and ventilation switched out and hatches and manholes closed down in the refrigerated cargo spaces.

The electrical heaters of capacity corresponding to the full additional heat load (i.e. \( \Delta Q = Q_{var} + Q_{perm} \)) shall be installed in each refrigerated cargo space and distributed uniformly throughout the space volume.

The fans of the hold air coolers shall operate in mode ensuring the air circulation ratio required for a particular cargo.

The heaters shall be switched on once the specified temperature has been reached in the refrigerated spaces and shall remain switched on throughout the whole period of tests for the maintenance of this temperature.

4.2 The tests of the MRP of the catching and processing fishing ships with a single space for the storage of particular products (e.g. with a single hold for frozen products and/or with a single hold for canned products) shall be carried out with the lighting switched on and with open arrangements for delivery of products into the refrigerated cargo spaces. Installation of the heaters and switching-on of these is identical to that specified under 4.1.

4.3 The tests of the MRP of the catching and processing fishing ships with two or more spaces for the storage of particular products shall be carried out in the following order:

1. the electrical heaters of capacity corresponding to the appropriate full additional heat load \( \Delta Q \), shall be installed in each refrigerated space and distributed uniformly throughout the space volume;
.2 the electrical heaters of capacity corresponding to the variable component of the additional heat load \( \Delta Q_{var} \) shall be switched on once the specified temperature has been reached in the refrigerated spaces and shall remain switched on throughout the whole period of tests for the maintenance of this temperature;

.3 the electrical heaters of capacity corresponding to the permanent component of the additional heat load \( \Delta Q_{perm} \) shall be switched on alternately in each refrigerated space intended for the storage of particular products, for, about, equal periods of time (e.g. if the ship is provided with two holds for the frozen products: these heaters shall be switched on in one hold for one-half of the test duration, and also for one-half thereof — in another hold). When the heaters are switched on in the appropriate space, the lighting is switched on and the arrangements for delivery of products open, while when the heaters are switched out the lighting is also switched out and the above arrangements close.

4.4 In case where the MRP is intended to maintain in the refrigerated spaces different specified air temperatures consistent with the kind of cargo carried, the tests with simulation of the design heat load shall be conducted on board the prototype ship in two modes:

.1 in a mode with the lowest specified air temperature and appropriate additional heat load;

.2 in a mode with the highest additional heat load and appropriate specified air temperature.

On ships of a series, when no significant modifications have been introduced in the MRP design on the prototype ship (e.g. replacement of main equipment) the tests with simulation of the design heat load shall be conducted only in the mode with the lowest specified air temperature and appropriate additional heat load.

5. Evaluation of test results

5.1 The design performance of the MRP for refrigeration of the cargo spaces shall be considered as confirmed if with the heaters switched on the specified air temperatures are maintained in the refrigerated cargo spaces.

6. Documentation

6.1 The ship designer shall submit within the program (procedure) of the acceptance tests of MRP:

.1 form of the tables for the calculation of the averaged air temperature differences \( \Delta t_{av} \) and variable component of the additional heat load \( \Delta Q_{var} \) with the filled-in columns 1, 2, 3, 4, 5, 7, 9 for each refrigerated cargo space and for each specified air temperature stipulated for these spaces;

.2 calculation of the permanent component of the additional heat load \( \Delta Q_{perm} \) for each refrigerated cargo space and for each kind of cargo stipulated for the carriage in these spaces.

All the listed materials shall be handed over to each ship within the delivery documentation.
12 AUTOMATION EQUIPMENT

12.1 GENERAL

12.1.1 The provisions of this Section shall apply in technical supervision of the automation equipment listed in the RS Nomenclature.

12.1.2 The Section contains the requirements for technical supervision of the above-mentioned items of technical supervision during the construction of ships.

12.1.3 General regulations for the organization of technical supervision of the automation equipment during the construction of ships are set out in Part I "General Regulations for Technical Supervision", those concerning the technical documentation — in Part II "Technical Documentation" of the Rules for Technical Supervision.

12.1.4 When conducting mooring and sea trials of the automation equipment, in respect to the general and organisational matters, the requirements of Section 18 shall be met.

12.1.5 The scope and procedure of the Register technical supervision of the automation equipment during the construction of a ship shall be dictated by the List (refer to 13.3, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision). The List shall be compiled by the shipyard on the basis of the RS Nomenclature and the requirements of this Section (with due account of the automation equipment installation and ship construction processes adopted at the shipyard) and agreed upon with the Register.
12.2 SURVEY PLANNING

12.2.1 Prior to commencement of survey of the fire-fighting means of the ship under construction, the RS Branch Office shall agree the examination and testing plan for automation equipment developed by the shipbuilder. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1 and with due regard to 12.3 – 12.6.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

12.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

12.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

12.2.4 Quality standards for installation and testing of the automation equipment shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

12.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
12.3 SURVEY DURING INSTALLATION

12.3.1 The automation equipment delivered for installation on a ship under construction, shall have documents confirming the Register technical supervision during the manufacture thereof.

12.3.2 It is advisable to perform a preliminary (prior to installation on board) verification and adjustment of the automation components, devices and systems on special test benches and simulators.

12.3.3 The installation of the equipment shall be carried out in full compliance with the technical documentation specifying location and arrangement thereof; in so doing, attention shall be given to the fact that the secondary units, amplifiers, sensors and alarms, logic units, connecting units, power supply units and other automation equipment shall be grouped and installed in positions protected against penetration of dirt, fuel oil and water as well as against accidental mechanical damages.

12.3.4 Prior to connection and after the tests (refer to 12.3.5), the pneumatic and hydraulic pipes shall be carefully cleaned.

12.3.5 After installation, the pneumatic and hydraulic systems (including pulse piping) shall be subjected to hydraulic pressure tests in accordance with Section 8.

12.3.6 When performing technical supervision during the installation of the automation equipment, it is necessary to check:

.1 documents confirming the Register technical supervision at the firm (manufacturer) (prior to installation of the automation equipment);
.2 completeness, arrangement and securing of the devices;
.3 ease of access to the devices;
.4 protection of the equipment against penetration of foreign objects thereinto and against accidental mechanical damages;
.5 “safe distance" to the magnetic compass (for devices installed in the wheel house) in accordance with the requirements of Appendix 2 to Section 16;
.6 quality of interior and exterior wiring;
.7 quality of protective earthing and of installation of cabling in accordance with Section 10;
.8 insulation resistance;
.9 installation of components to protect radio reception against interference;
.10 fulfilment of special requirements deriving from the design of the equipment and set forth in the RS-approved technical documentation.
12.4 SURVEY DURING MOORING AND SEA TRIALS

12.4.1 Upon finalization of the installation and adjustment work, all the automation equipment shall be subjected to mooring and sea trials according to the programs approved by the Register and in the presence of the Register representative. The equipment shall be supplied from the ship's mains.

12.4.2 During the mooring trials it is necessary to check:
proper and smooth functioning of the machinery with verification of the sequence of control operations;
agreement between the actual time of operation performance with the required one;
proper interaction between various automation systems.

12.4.3 The operability of the automation systems shall be confirmed by the tests:
.1 for operability of the automatic safety systems by means of variation of the real physical value of the parameter to be protected;
.2 for load surge and load shedding relief in the regulation systems where the static and dynamic irregularity shall be determined; along with that, the extreme values of parameters, as well as insensitivity and time of the transient processes shall not fall outside the set limits specified by the Register standards or shall be consistent with the technical and normative documentation agreed with the Register;
.3 for the capability of system functioning with the fluctuations of the power supply parameters under shipboard conditions (when powerful consumers are activated, etc.);
.4 for effectiveness of the operational and self-monitoring devices of the automation equipment (simulation of the control and monitoring channel troubles);
.5 for check of the main machinery remote control in operation with verification of the proper functioning of changeover devices of all control stations in all specified changeover modes.

Along with that, it is necessary to check the operation of the control station indicator, interlocking facility (impossibility of control from several stations simultaneously), as well as the system operation process when control is changed over from one station to another;
.6 for proper functioning of the signal passage inhibition circuits in case of starting and normal stopping of the machinery (where specified);
.7 for proper functioning of the mnemonics notifying of the execution of orders immediately before the relevant items are placed into service;
.8 for check of the manual control for the entire automated and remotely controlled equipment in operation having regard to the requirements under 4.2.3 — 4.2.5, Part XV "Automation" of the Rules for the Classification and Construction;
.9 for automatic starting of the stand-by machinery and removal of the running machinery from service by creating real conditions affecting the starting and stopping control circuits of these machinery (where provided);
.10 for redundancy of the power supply and for conservatism of the system or fail-safety in the event of loss of power supply.

12.4.4 During the sea trials of ships having the automation mark in the class notation, it is necessary to conduct tests under unattended operation conditions of the machinery spaces and, except for ships covered by the requirements of Section 5, Part XV "Automation" of the Rules for the Classification and Construction, the engine control room throughout 6 h — for the prototype ship and throughout 4 h — for the ships of a series. The requirements under 12.5.2.3 of the Guidelines shall be met.

12.4.4.1 Prior to the tests under unattended operation conditions of the engine room it is necessary to conduct tests of the automated systems and devices involved in such unattended operation.

12.4.4.2 When conducting these tests, the RS surveyor may require a check of the operability of any automation mechanisms and devices (switching-on and off of the mechanisms, operation of the sensors, etc.).
12.4.4.3 During the tests under unattended operation mode, there shall be no faults hindering the normal and safe unattended operation of the ship’s machinery installation. During the unattended operation mode, there shall be no false activation of the safely and alarm system.

12.4.5 On the ships of a series, some types of tests of the automation equipment under sea conditions may be replaced by the relevant simulation tests to be carried out during the mooring trials, which shall be stated in the program of trials (refer also to Section 18).

12.4.6 All defects of the equipment detected during the mooring and sea trials shall be corrected prior to the issuance of the ship’s documents of the Register.

12.4.7 Where the constructed/converted ship is intended for the carriage of liquefied gases and/or uses gas as fuel, the automation equipment and devices related to gas control, shall be checked during gas trials according to 18.7.
12.5 ADDITIONAL INSTRUCTIONS ON TESTING OF INDIVIDUAL AUTOMATION SYSTEMS AND DEVICES

12.5.1 Alarm and indication systems.

12.5.1.1 Upon finalization of the installation and prior to the mooring trials, the alarm and indication systems shall be checked for faultless of the visual display units of alarm systems and audible signalling system and for proper operation for each tested parameter.

To reach the set parameter values the most realistic simulation conditions shall be created and the test instruments used in the process shall have documents or brands to certify timeliness of the state verification, and their accuracy shall exceed that of the monitored equipment.

Check of the alarm systems applied to each parameter shall be performed at least three times. In case of scatter in the obtained values falling outside the permissible limits due to sensor fault, the sensor shall be replaced.

In specific cases, instead of replacement of the sensor, the alarm set point may be readjusted on the basis of the extreme value of the parameter to the safe side.

12.5.1.2 During the mooring and sea trials it is necessary to check the proper performance of the following functions:

1. operation of the alarm system for essential parameters of the machinery installation using an appropriate simulation involving the attainment by these parameters of values which initiate operation of the alarm system; along with that, it is necessary to check the operability of the common alarm system;

2. digital or analogue measurement of the parameter values during the operation of the tested mechanisms by means of selective call thereof and checking them against the direct indication of local instruments;

3. operation of the alarm warning of the alarm system fault by means of simulation of short-circuit, circuit break-off and earth fault in accordance with 2.4.1.2, Part XV "Automation" of the Rules for the Classification and Construction;

4. operation of the audible and visual alarm to apply signals in case of failure of the power supply;

5. possibility of safe operation of the engine with the alarm system switched off with retaining the capability of monitoring by the permanently indicating instruments.

12.5.1.3 The operability of the alarm system shall be conclusively established on sea trials, at the same time the absence of false alarms shall be checked.

During the unattended operation mode, in case of false alarms occurred, their cause shall be identified and a decision on cessation or extension of the mode shall be taken.

12.5.2 Remote automated control systems of main machinery with fixed pitch propellers.

12.5.2.1 During the mooring trials of the remote automated control system shall be checked the following:

1. performance of the systems of starting and stopping of the engine from the wheel house without replenishing the air receivers by means of at least 12 successive starts (alternating "ahead" and "astern") of the engine ready to start;

2. possibility of automatic restart in the event of an ineffective attempt which fails to produce a start, that shall be simulated by shutting off the fuel supply;

3. system response to the cancellation of the last order;

4. reversing under conditions prescribed by the trial program of the ship; in so doing, it is necessary to measure the system characteristics specified in the technical documentation;

5. engine emergency stop device by pressing the appropriate push-button;

6. operability of the alarm system under alternate changeover to all available modes;

7. minimum pressure value of the feeding medium (for pneumatic and hydraulic systems) as well as reduced voltage and frequency of electrical power supply at which control
is possible (bearing in mind that the working pressure of the control air shall be always below or equal to the minimum pressure of the starting air at which the engine can still be started);

.8 adequacy between the speed set point by the control lever from the wheel house and the engine speed in steady mode (irregularity shall not exceed 2.5 % of the full speed). Setting of the speed from the engine control room shall be checked in similar manner;

.9 insensitivity of the system by establishing a minimum interval of the control lever shifting at which the speed remains unchanged, as well as maintenance of the minimum possible engine speed under automated and manual control;

.10 operation of the following alarms:
"ineffective starting attempt" – when checking automatic restarts;
"stop" – in case of normal stop of the engine and passing through "stop" when reversing;
"emergency stop";
"critical speed range" if no automatic passing of this range is provided;
"low starting air pressure" (shall be checked during the test for the number of starts according to 12.5.2.1.1);
"failure of electrical power supply" by means of simulation of the supplying feeder break-off;
"failure of pneumatic, hydraulic power supply" by cutting off the supply;
"protection activated";
"protection disabled";
.11 effectiveness of interlocking systems precluding:
engine reversal with the fuel supply cut on; engine starting with the turning gear engaged;
engine starting in the direction opposite to that set by the engine telegraph;
starting of the engine when the limiting values of the parameters have been reached, for which the engine protection is provided;

.12 automatic switching-on of the standby power supply source;
.13 proper functioning of the mnemonic boards "stand by", "control from ECR (wheel house)" and "finished with engine";
.14 transfer of control between the stations with check of alarm accompanying such transfers;
.15 conservatism of the system. When simulating faults of the remote automatic control system (in the event of the loss of power supply of the system or its individual components having safely devices) the engine shall not (unless otherwise specified) change and especially increase the speed; spontaneous starts of the engine shall not be also permitted;
.16 operation of the system in the event of de-energization of the ship and subsequent restoration of the voltage in the ship's mains.

12.5.2.2 In the course of the mooring and sea trials of the main machinery the following shall be checked:
.1 steady operation of the fresh and sea cooling water temperature, lube oil, scavenging air regulators, as well as the heavy oil temperature and viscosity regulators by changing the operational mode of the main engine in the range from the minimum to maximum load thereof through the change of the sea water temperature (readjustment of the regulator) within 10 – 30 °C. The check shall be performed with due account of the requirements under 12.4.3.2. The check on board the prototype ships shall be performed with the use of recording instruments;
.2 at the same time it is necessary to verify the possibility of the remote (from ECR) and local control by regulating devices. When performing the verification attention shall be given to the absence of the working medium leaks in the regulating devices and by-pass piping (by comparison of the time spent for the maintenance of the regulated parameter within the set limits after engine stoppage or slowdown to the minimum load with the use of the regulator and manually operated valves shutting off the sea water flow through the relevant coolers);
.3 operability of the automatic safety system in accordance with the provisions of 12.4.3.1.
12.5.2.3 During the sea trials it is necessary to check steady unattended operation of the machinery installation during the time given in 12.4.4. Along with that, the installation shall be checked under modes of ahead and astern running and conventional reversing with subsequent putting on the full speed mode not less than two times.

No in-service readjustments of the systems during these trials shall be allowed.

12.5.3 Remote automated control systems of main steam turbines.

12.5.3.1 In the course of the mooring and sea trials of the remote automated control systems (to be conducted in two steps: with and without steam supply to the manoeuvring gear) the following shall be checked:

.1 automated starting of turbine ready for use and automatic performance of the sequential starting steps including automatic performance of intermediate operations to hamper overspeed or reset under adverse conditions of preheating and vibration;

.2 steady operation of the system within the whole range of possible modes and the existence of potential zones with high vibrations by means of changing the propeller speed from the full ahead speed to the full astern speed in 5 rpm intervals;

.3 automatic performance of the intermediate operations when the operation mode is changed, including fast passage of the speed ranges with high vibrations, interruption of blowing with augmentation of the ahead power, closing of the bleed-off valves, starting or speeding-up of the circulating pump of the main turbine condenser, opening of the cut-off valve in case of reduction in the ahead power or transfer to the manoeuvring mode;

.4 required system response to the cancellation of the last order;

.5 automatic actuation of the rotor turning-over device (if any) during short-duration stoppage of the turbine;

.6 functioning of the turbine emergency stop device;

.7 shuttting-off of the ahead and astern valves during the manoeuvre "full ahead" — "full astern" and vice versa, as well as change of the pressure at the inlet of the manoeuvring valves (momentary pressure drop) and water level in the steam boilers;

.8 compliance with the propeller speed in steady mode and the setting of the set-point device in the wheel house and ECR, and between the position of the manoeuvring valve lift indicator and the real lift;

.9 operation of the interlocking system precluding starting with the turning gear engaged, loading of an unready unit, as well as operation of the following alarms: "ineffective starting attempt", "rotor stoppage for more than 2 min", "unopened astern cut-off valve", "inoperative circulating pump", "unclosed bleed-off valves", "critical speed range", "inoperative blowing valves", "non-preheated turbine", "turbine is ready to start";

.10 operation of the systems and devices referred to under 12.5.2.1.12 – 12.5.2.1.15.

12.5.3.2 In the course of mooring and sea trials of the main steam turbines shall be checked the following:

.1 steady operation (with due account of 12.4.3.2) of the lubricating oil, gland-sealing steam pressure and main condenser collector (deaerator) level regulators and other parameters in the "slow astern speed", "full ahead speed" and "full astern speed" modes, as well as in case of fast alterations of mode from "full ahead" to "dead slow" and vice versa.

On board the prototype ships, the check shall be performed with the use of recording instruments;

.2 accuracy of the readings given by the indication systems for the parameters the necessity of which is prescribed by 4.2.10, 4.3.11, 4.4.6, Part XV “Automation” of the Rules for the Classification and Construction;

.3 operation of the alarm system in accordance with the requirements of 12.5.1.2 and 12.5.1.3;
operability of the automatic safety system in accordance with 12.4.3.1. Along with that, check of the operation of the alarm and safely systems shall be performed:

by vacuum — changing the steam pressure at ejectors;
by axial rotor displacement – simulating the movement of the measuring device;
by lubrication system — lowering the oil level in the lubrication system;
by vibration — simulating the operation of alarm through direct mechanical action on the measuring device;
by failure of the boilers — remotely cutting off the fuel supply to the boilers.

At the same time, it is necessary to check alternately the automatic starting of the stand-by oil pump and the automatic and/or remote starting (stopping) of auxiliary machinery supporting the main turbines from ECR.

12.5.4 Remote automated control systems of main gas turbines.

12.5.4.1 In the course of testing of the alarm, safely and remote automated control systems on the running gas turbine, it is necessary to check the effectiveness of interlocking system precluding the possibility of starting, false starting and motoring during:

.1 failure of main and stand-by power supply;
.2 turning gear engaged;
.3 operation of any protection device of the main gas turbine;
.4 non-conformity of the devices controlling fuel supply to the starting position;
.5 position of the throttle quadrant which does not conform to idle running;
.6 no pressure in the fuel supply and power supply systems of the automatic equipment;
.7 axial displacement of rotors (simulation by the measuring device shifting);
.8 malfunction of the alarm, safety and remote automated control systems.

12.5.4.2 In case of automated starting of the gas turbine ready for use, it is necessary to perform automatically operations for sequential starting, false starting, motoring, fuel system washing and turbine stoppage.

In so doing, it is necessary to check:

.1 issuance and execution of orders for remote switching-on and -off of machinery and devices being part of the unit;
.2 assignment and execution of a temporary program for any position of the gas turbine throttle quadrant within the range from the dead slow to full speed and the position corresponding to the "crush stop" mode;
.3 execution of the program for reversals and emergency shutdown of the gas turbine, release of signals to the control system for protection disablement;
.4 automatic changeover from the heavy oil to light oil when the power is reduced below the established level, heavy oil temperature drops below the rated one or "port" program is activated;
.5 steady operation of the system throughout the whole range of operating modes and existence of possible zones with high vibrations when the propeller speed is changed from the full ahead to full astern in 5 rpm intervals;
.6 conservatism of the actuator mechanisms in the event of long-duration lack of power supply and failure of the system;
.7 operational, local and automatic monitoring of the proper performance of the remote automated control system and automatic changeover to the stand-by units in the event of failure of the main units;
.8 operation of the alarm and safely systems which preclude, with the gas turbine running, engagement of the turning gear, starting of the serving pumps, reversing and activation of the "crush stop" mode at a load exceeding 0.5 the rated load, excess of the rotor speed above the rated speed by more than 15 %, as well as the alarm and protection for other parameters provided for by the systems.
12.5.4.3 In the course of the mooring and sea trials of the main gas turbine the following
shall be checked:

.1 agreement between the propeller speed in steady mode and the setting of the
set-point device in the wheel house and ECR, as well as the position of the running control
lever;

.2 accuracy of the indication instrument readings for the parameters specified in
Part XV "Automation" of the Rules for the Classification and Construction;

.3 steady operation of the automation regulating systems and remote control systems
in all modes;

.4 performance of the alarm and safely systems, their reliability and absence of false
operation for each monitored and protected parameter.

12.5.5 Remote automated control system of CPP, Voith-Schneider propellers and
azimuth thrusters.

12.5.5.1 For the remote automated control systems of the propulsion plants with CPP,
Voith-Schneider propellers and retractable steering propellers (with respect to the
requirements applied to these systems), during mooring and sea trials it is necessary to check:

.1 devices and functions of the remote automated control system listed
under 12.5.2 – 12.5.4 and related to the plants with CPP;

.2 blade turning-over velocity with the use of the remote automated control system for
the compliance with the requirements of the Rules for the Classification and Construction (with
the propeller being inoperative);

.3 device limiting the CPP blade turning-over velocity in the direction of pitch increase
in view of exclusion of the engine overloading under normal operation conditions;

.4 time of operation of the device for emergency shutdown of the engine, operate
setting of the engine overspeed device;

.5 limitation of the load on the engine when reaches the limiting value by means of
reducing the propeller pitch.

Check may be performed by simulating the performance parameters of the engine using
sufficiently reliable method;

.6 compliance with the set and real engine speed. For the systems provided with the
"Manoeuvres" program characterized by a specific combination of the propeller pitch and
engine speed, it is necessary to check compliance of these combinations with the
requirements of the technical documentation for each ship running;

.7 compliance with the zero pitch of the propeller and the position of the pitch set-point
device in the ECR and on the bridge;

.8 capability of ensuring 6 starts of the engine without replenishing of air receivers.
At the same time, it is necessary to determine the minimum pressure of the starting air which
makes the automated start of the engine possible;

.9 conservatism of the remote automated control system of the CPP (in the event of
loss of power supply to the pitch changing mechanism control system control the blades shall
remain in the position which they held immediately prior to the loss of pressure, with the
actuation of the relevant alarm);

.10 compliance with the readings given by the blade position indicators on the pitch
changing mechanism, in the ECR and on the bridge;

.11 alarm for the parameters specified by the technical documentation on the control system;

.12 alarm or interlocking from the ECR in the event of improper manoeuvre;

.13 alarm and blocking of clutch engagement when the CPP pitch is not equal to "0".

.14 pitch response test.

A full range of tests shall be carried out to get the pitch response and verify that it coincides
with the combinator curve of the propeller (relationship between the propeller pitch setting and
the propeller speed). The tests shall be carried out for at least three positions of the control
lever in ahead and astern directions (e.g., dead slow ahead/astern, half ahead/astern,
full ahead/astern) in normal and emergency operating conditions. Tests that are not affected by the control position may be carried out from one control position only. During the test, the list of the parameters established by the pitch control system manufacturer or integrator shall be recorded. The list shall be agreed with the Register and include at least the following parameters:

- position of the control handle;
- actual pitch indication (local, remote);
- rotational speed of the propeller;
- response time between the pitch change order (modification of the lever position) and the instant when the pitch and propeller speed have reached their final position;
- propelling thrust variation during the transfer of the control from one location to another one;
- test of the fail-to-safe characteristics.

A test of the fail-to-safe characteristics of the propeller pitch control system shall be carried out to demonstrate that failures in the pitch command and control or feedback signals are alarmed and do not cause any change of thrust. Such failures shall be clearly identified and included in the test procedure. Test procedure shall be prepared and submitted by the pitch control system manufacturer or integrator for agreement by the Register.

Test results shall demonstrate:

- that the propelling thrust is not significantly altered when transferring control from one location to another and in case of failures in the pitch command and control or feedback signals;
- that the pitch response times measured during the test do not exceed the maximum value to be defined by the pitch control system manufacturer or integrator.

12.5.6.1 In plants with two or more engines driving a common propeller shaft, it is necessary to check additionally:

- operation of the device to protect the engine remaining operative against overload. Along with that, it is necessary to check the simultaneous disengagement of the clutches between the propeller shaft and engine and automatic slowdown (reduction of the propeller pitch) to the load value safe for the engine remaining operative;
- accuracy of the automatic load distribution between the engines operating in parallel in static and dynamic modes;
- absence of the resonance zones for the engines operating in parallel;
- constant-error behaviour of the speed governors;
- dynamic tests when the CPP is reversed from the full speed ahead to full speed astern. The tests are conducted with the use of recording instruments.

12.5.6 Automation equipment of steam boilers.

12.5.6.1 In the course of the mooring trials of the boiler automation equipment it is necessary to check the boiler systems:

- feed water system. It is necessary to check the setting of the high and low level indicators in the boiler drum, minimum level indicator in the hot well, time delay to prevent false operation in a seaway, operation of the feed pumps in manual and automatic modes, setting of the water salimeters;
- fuel oil system. It is necessary to check operation and setting of the pressure gauges, fuel oil viscosity (at burner inlet) and level, fuel oil temperature in the service tank, changeover from the light oil to heavy oil (if provided), automatic devices for supply of fuel oil and combustion air;
- fuel oil heating (setting of the maximum and minimum limits of the thermostats);
- supply of combustion and atomization air. It is necessary to check the time setting for pre-ventilation of the boiler after stopping, regulation of air supply depending on the mode during firing-up and burning.

Moreover, it is necessary to check the capability of shutting off the burning installation from ECR and from a place situated outside the machinery space.
12.5.6.2 In the course of the mooring trials of the automatic burner and feeding systems (with confirmation of the obtained results also on the sea trials when operating their intended services), indication, alarm, protection and interlocking devices specified in Table 4.3.11, Part XV "Automation" of the Rules for the Classification and Construction shall be checked.

In so doing, when choosing and carrying out the operating modes of the boiler plant it is necessary to be guided by the requirements of Section 9.

12.5.6.3 The trials referred to in 12.4 and 12.5.6.1 shall be conducted in the following order:

1. check of the static and dynamic irregularities of the burning system together with the feed water system shall be combined with the check of the entire machinery installation under the appropriate modes of the ship running. Along with that, the steam pressure fluctuation range shall not cause the boiler safety valves, alarm and protection system to be actuated nor shall disturb normal operation of the steam consumers;

2. check of the alarm and protection to be activated in the event if the flame-jet cut-off shall be checked by action upon the photocell;

3. the alarm and protection for the air pressure before the boiler furnace shall be checked through simulation of the air pressure loss by closing down the dampers, easing off the pulse tube or in specific cases, subject to agreement with the Register, by switching off the fans; at the same time, it is necessary to check the automatic starting of the standby fan;

4. check of the alarm and protection for the water level drop shall be performed by blowing down the boiler with the feed pumps inoperative. Check of these system for the high level (in cases where they are mandatory) shall be performed by filling the boiler with water using feed pumps controlled manually. Along with that, at the same time it is necessary to check setting of the time relay preventing false operation of the protection device when the ship is in a seaway;

5. check of the operation of alarm for the feed water salinity and automatic operation of the by-pass valve (if any) shall be performed by direct supply of brakish feed water or by immersing the salt gauge into a vessel containing water of high salinity.

12.5.6.4 In case of auxiliary boilers, it is necessary to check the burning system when the boiler operates at all typical loads within the range 0 – 100 %, as well as during the parallel operation of the boilers. Along with that, particular emphasis shall be placed on the capability of the system to ensure normal operation of the boiler during transfers from full and intermediate load to zero load and back. The steam pressure fluctuation range shall not initiate actuation of the boiler safety valves, alarm or protection system nor shall disturb the normal operation of the essential steam consumers, especially those which are provided with the heating steam pressure regulators.

In case of composite boilers, it is necessary to check the operation of the automatic device (if any) to change over the exhaust gas using system to the fuel oil using system — by simulating the conditions under which the changeover is performed.

12.5.6.5 It is necessary to explore the possibility of unattended operation of the automated auxiliary boiler plant to feed the permanent consumers during the time cited under 12.4.4.

12.5.7 Automation equipment of electric power plant.

12.5.7.1 Prior to test of the electric power plant during the mooring trials it is necessary the pre-check separately all the systems of automation equipment of the electric power plant specified under 4.4, Part XV "Automation" of the Rules for the Classification and Construction and by the requirements under 12.4 and 12.5.1 of the Guidelines. To be checked during the test of the automation equipment:

1. operation algorithm of the automated prime movers of the generators in accordance with the RS-approved technical documentation;

2. remote and local starting and stop of the prime movers;

3. maintenance of the hot stand-by mode (if provided);

4. automatic starting of the standby unit in the event of overloading of the operating unit and removal thereof from parallel operation at reduced load (if provided);
.5 automatic sharing of load when the units operate in parallel (if provided);
.6 indication and alarm devices in accordance with the requirements of Table 4.4.6, Part XV "Automation" of the Rules for the Classification and Construction.

12.5.7.2 The machinery installation of the ship assigned an automation mark added to the character of classification shall be tested to determine its capability of being placed in service after de-energization.

The said test shall be carried out by stopping the generator prime movers with the running main machinery (on sea trials) and then by restoring the previous operating mode of the installation through an automatic starting from ECR the main and all auxiliary machinery needed to do this. No starting from the local stations shall be permitted for this purpose.

12.5.8 Automation equipment of bilge system.

12.5.8.1 It is necessary to check the liquid level, which initiates actuation of the alarm by filling the appropriate bilge wells with water, as well as the absence of false alarms when the ship is in a seaway.

12.5.8.2 It is necessary to check the automatic or remote starting of the bilge pumps. Along with that, it is necessary to monitor the operation of the alarm to indicate the pump operation, valve position and pressure in delivery main.

12.5.9 Remote automated or automatic control of valves of ship's service systems and machinery installation piping.

12.5.9.1 In the course of tests the following shall be checked:
.1 remote opening and closing of valves;
.2 automatic control of valves by means the appropriate shift of the operate setting;
.3 pressure value of feeding medium in pulse pipes and power pressure value on servos (also at the instant of starting);
.4 operation of "valve is open (closed)" alarm;
.5 required position of the actuating elements of the valves in the event of loss of power supply ("fail-safety");
.6 proper alarm on the mnemonics;
.7 proper functioning of the manual valve control, as well as local servo control.

12.5.10 Automation equipment of compressors.

12.5.10.1 In addition to the check of operation during the tests of the machinery installation, it is necessary to check:
.1 pressure at which the compressor is automatically started and shut down;
.2 operation of the alarm and protection systems for the air temperature, oil pressure and other parameters provided by the automation system depending on the compressor type;
.3 operation of the automatic blow-out and relief valves;
.4 proper functioning of the manual control.

12.5.11 Automated equipment of separators.

12.5.11.1 It is necessary to check the operability of the automated equipment of the lubricating oil and fuel oil separators with verification of alarm and protection system, provided depending on the separator type.

12.5.11.2 It is necessary to check the operation of alarm in the separator sludge tanks.

12.5.11.3 It is necessary to check the operation algorithm of the programmed system for the control of the separator discharge process.

12.5.12 Automated equipment of classed refrigerating plants.

12.5.12.1 In the course of tests it is necessary to check the operation algorithms of the alarm and protection systems provided depending on the plant type; in so doing, the requirements of Section 11 shall be taken into account.

12.5.13 Equipment of shipboard computer-based systems used for control and monitoring combined into a network forming a common integrated system.

12.5.13.1 Verification of a vision document and failure mode and effect analysis shall be performed in compliance with 7.10.7.1, Part XV "Automation" of the Rules for the Classification
Guidelines on Technical Supervision of Ships under Construction (Section 12)

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and Construction of Sea-Going Ships to implement cyber security measures preventing cyber threats to the integrated system.
12.6 ADDITIONAL INSTRUCTIONS ON TESTING OF DYNAMIC POSITIONING SYSTEMS (DP SYSTEMS)

12.6.1 Checking the proper operation of dynamic positioning systems (DP systems) components.
12.6.1.1 Position and heading sensors.
12.6.1.1.1 Differential global positioning system (DGPS):
   .1 demonstrate the operation of the GPS receivers;
   .2 demonstrate the operation of dual constellation receivers to utilize the Russian GLONASS satellites for position fixes;
   .3 verify the reception of differential correction data using more than one method for redundancy;
   .4 verify those headings on which some of the required GPS and differential antennae are blocked by ship structures or exhibit degraded data due to multipath reception off close by structures. Ensure that no headings exist at which all signals are lost;
   .5 verify correct telegram format and rate;
   .6 verify proper lightning protection has been provided for all antennas.
12.6.1.2 Acoustic position systems:
   .1 verify acoustic system accuracy for the type of base line used to manufacturer and/or customer specifications;
   .2 verify the location with respect to the ship installation reference point and vertical alignment of all hydrophones. Verify the mechanical operation and alignment repeatability of all hydrophone deployment systems;
   .3 verify set up and calibration procedures exist and are proven;
   .4 if redundant systems are installed, verify the independent operation each system. This is especially true for systems that use transponders as opposed to system using free running beacons. Additionally, verify that both systems can operate simultaneously without interfering with each other. If master/slave design then verify transfer;
   .5 verify operation of system to simultaneously track fixed and mobile targets;
   .6 verify water depth rating of transponders/beacons;
   .7 perform an operational and background noise survey of ship under various thruster configurations and power levels (this can be used to determine the worst case water depth capability of the acoustic position reference system as installed on a specific ship);
   .8 verify correct telegram format and rate.
12.6.1.3 Taut wire systems:
   .1 verify water depth rating of wire and clump weights;
   .2 verify proper operation of wire wench and tensioning systems and that they are suitable for the water depth rating of the system;
   .3 verify ease of operation to launch and recover taut wire and adjust system tension;
   .4 verify the location with respect to the ship installation reference point;
   .5 verify the proper polarity and scaling of the output tilt measurements;
   .6 verify correct telegram format and rate.
12.6.1.4 Radio/radar positioning system:
   .1 verify set up and calibration procedures exist and are proven;
   .2 verify heading limitations due to antenna blockage;
   .3 verify correct telegram format and rate;
   .4 verify proper lightning protection has been provided for all antennas.
12.6.1.5 Laser position systems (relative position):
   .1 verify set up and calibration procedures exist and are proven;
   .2 verify heading limitations due to line-of-sight blockage between sensor(s) and target(s);
   .3 verify system operation under manufacturer’s stated limiting environmental conditions;
   .4 verify correct telegram format and rate;
12.6.1.6 Riser angle systems:
.1 verify operation of both upper and lower electric riser angle sensors and data transmission especially if multiplexed through BOP control system;
.2 verify operation of acoustic riser angle sensors including orientation, polarity and latency of the received data by the DP system;
.3 verify correct telegram format.
12.6.1.7 Gyrocompasses, heading sensors engaging other physical principles:
.1 ensure proper mounting of compasses and/or heading sensors engaging other physical principles;
.2 verify correct telegram format and rate;
.3 verify heading reference data to all DP and peripheral equipment is received correctly.
12.6.1.2 Environmental sensors.
12.6.1.2.1 Wind sensors:
.1 ensure that sensors are located such that structural blockage is minimized. This especially true when a minimum number of sensors are use to obtain full 360° coverage with little or no overlap in coverage zones;
.2 verify accuracy of measured speed and azimuth data;
.3 verify that all wind velocity data is adjusted to a common plane, usually 10 m above sea surface, regardless of the vertical position of the sensors;
.4 verify correct telegram format and rate;
.5 verify proper lightning protection has been provided for all external sensors.
12.6.1.2.2 Vertical reference units:
.1 verify measurement of roll, pitch, heave, roll rate and pitch rate as applicable;
.2 ensure that sensors are located a close to the roll/pitch center of the ship to minimize lateral acceleration effects;
.3 verify that correct location parameters are entered in the sensor for correct compensation;
.4 verify correct telegram format and rate;
.5 verify the alignment of individual sensors with each well as to the ship.
12.6.1.3 The DP system propulsion plants/thrusters.
12.6.1.3.1 Controller functions:
.1 azimuth controller — proper operation of the azimuth control including rate and direction of the azimuth drive to be verified;
.2 pitch controller — proper operation of the pitch control device including rate of change of pitch and maximum pitch. Verify that the thruster delivers 100 % thrust at the 100 % pitch command to be verified. Test pitch limiting to avoid thruster overload if included;
.3 speed controller — proper operation of the shaft; speed control device to be verified. Verify that the thruster delivers 100 % thrust at the 100 % speed command. For fixed axis thrusters verify smooth and stable operation of direction change of rotation to reverse thrust output. Test speed limiting to avoid thruster overload if included;
.4 power controller — some systems use either pitch or speed control as appropriate in a closed loop control system that actually controls the input power level of the thruster. This type of control is superior to simple pitch or speed control in that it keeps the power consumed from spiking and adjusts in part for current inflow degradation. Verify the operation of the power control device. Verify that the thruster delivers 100 % thrust at the 100 % power command and that the controller protects against thruster overload.
12.6.1.3.2 Commands:
.1 verify proper operation of thruster assignment functions;
.2 verify automatic DP and/or joy stick/manual moment calculated azimuth and/or thrust commands are correctly received by the assigned thrusters;
.3 verify manual azimuth and/or thrust commands are received by the assigned thrusters.
12.6.1.3.3 Feedback: verify calibration of the following:
- azimuth angle feedback;
- pitch angle feedback;
- speed feedback;
- power feedback.

12.6.1.3.4 Thruster drive system operation:
.1 verify protective devices (setting) and equipment operation:
  - thruster start protection and operation;
  - thruster stop protection and operation;
  - thruster emergency stop protection and operation;
  - thruster drive system protection settings;
.2 verify time needed for thrusters restart.

12.6.1.4 Power systems.
12.6.1.4.1 For redundancy, a minimum of two skids shall be on line at all times and skids shall be added to or taken off line as the average total power requirement fluctuates. In order to maintain continuous power, some level of automatic power management system is desirable.

12.6.1.4.2 Main power:
.1 buss structure — verify proper indication and data from both closed and split buss operation. Also that power limit recognized and responds correctly to split buss operation;
.2 engine/generator — verify that proper engine and generator data is transmitted to the DP system;
.3 thruster supplies — verify that all thruster power data is transmitted to the DP system. Verify that start permissive logic is properly implemented and operational.

12.6.1.4.3 UPS power:
.1 redundancy — verify distribution of equipment between various UPS systems to minimize DP system degradation on loss of any one UPS;
.2 battery life — verify stated performance on battery operation. Typically 30 min;
.3 input power selection — verify that the UPS has multiple input power sources;
.4 bypass modes — verify that the UPS can be bypassed such that the output is fed directly from the input. This is an emergency mode of operation;
.5 verify key UPS alarms to DP.

12.6.1.4.4 Operational checks:
.1 closed/split buss operation — test the operation of the power plant in all closed and split bus combinations with all combinations of thrusters to ensure safe and stable operation;
.2 black out recovery — under normal DP operations, cause a black out of the main plant and determine the time to recover to full operational DP holding station. Note the time required to get each engine and thruster back on line and operating.

12.6.2 Coming on location trials.
12.6.2.1 These are ship specific trials used primarily to verify "good working order" of the DP system. For example:
.1 restart all operator stations pertaining to the DP and the thruster control systems;
.2 simultaneously reset and restart all three DP control computers and let them re-load from an operator station. Restart independent backup controller;
.3 restart both DGPS systems and let them settle. Check setup and verify all relevant reference stations enabled and active;
.4 restart both acoustic transceivers inside bilge keels and verify transducer shafts fully extended;
.5 enable sensors and make sure there are small differences between all three compasses and between the three vertical reference sensors;
.6 verify all thrusters "running" and "ready". DP systems in "lever" mode; test responses of each thruster individually using levers. Two engines running and on the switchboard, four on standby. All busties closed;
.7 set DP in "Joystick" mode and tested all thrusters responding correctly to small joystick deflections in all three axes (surge, sway and yaw);
.8 set DP in auto mode using two DGPS inputs and let settle for 30 min;
.9 perform "box" test, i.e., moving ship 30 m to starboard, then 30 m ahead, then 30 m to port and finally 30 m astern. All moves at low speed. Done at low, medium and high gain separately. Observe position plot correct and little or no overshoot at each new position. Send position plot to hard-copy color printer for filing purposes;
.10 inform engine room of power management test (power management system). Make a 50 m transversal move at a high speed setting (~ 3.5 knots) to observe levels and timing of the autostart of each standby generator in turn. Ultimately, all generators on the switchboard. Alternate use the joystick at its high gain setting;
.11 check that independent backup system reads parameters correctly, i.e., following the main system's inputs and outputs;
.12 test emergency transfer to the independent backup system. Observe "bumpless" transfer.
.13 transfer control back to main system;
.14 reset two of the three main DP controllers and observe no change in position, heading or thruster usage on one controller. Observe proper restart of controllers. Also verify auto-switch to "live" controller;
.15 test emergency stop of each thruster in turn by using panel mounted buttons. Restart thruster after each one;
.16 move into well-head position under DP control and verify with independent surveyor. Head set at predetermined desired stack heading based on oceanographic and meteorological statistical data from nautical "pilot" charts;
.17 deploy ROV carrying four transponders. Deploy transponders, each in turn, in a predetermined array based on depth and bathymetric data (if available);
.18 activate acoustic systems and calibrate the transponder array. Then enable in the DP system. Check both systems operational and satisfactory. Check DP system and positioning stability for a while using only acoustics as position reference;
.19 restore DP system to normal operational status and set warning and alarm limits for excursions according to safely calculations done for the site;
.20 log all activity and declare ship operational and ready.

12.6.3 Failure mode and effect analysis (FMEA).
12.6.3.1 Class 2 and 3 DP-systems, which correspond by their characteristics to marks DYNPOS-2 and DYNPOS-3 in the class notation shall be checked according to the FMEA provisions.
12.7 SURVEY OF MODU/FOP AUTOMATION EQUIPMENT

12.7.1 General.

12.7.1.1 All requirements of Section 12, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision apply to the MODU/FOP automation equipment subject to technical supervision of the Register according to the RS Nomenclature during manufacture, and the requirements of Section 12 of the Guidelines during installation and testing.

12.7.1.2 This Chapter contains additional requirements for survey of the MODU/FOP specific automation equipment during its testing after onboard installation.

The requirements for technical supervision of gas detection and alarm system are given in Section 4, and for ventilation system of enclosed spaces under overpressure, in Section 6.

12.7.2 Surveys.

12.7.2.1 Self-elevating MODU jacking remote (automated) control system.

12.7.2.1.1 During mooring and sea trials, the following shall be checked:

.1 remote and local control of electric motors for high-, medium- and low-pressure pumps of hydraulic power unit by starting and stopping them three times both from the main control station and local control stations;

.2 proper operation of limit switches by switching them as per control circuit;

.3 control relay circuits for three-position hydraulic switch electromagnets in all positions (support lowering, hull lift, hull lowering, support lift) by switching the appropriate limit switches;

.4 operability of remote and local control system separately for each leg and for all legs in all positions;

.5 concurrent operation of leg hoisting gears during the MODU lowering and lifting;

.6 actuation of alarms, indicators and safety arrangements in the following cases: maximum working fluid pressure in hydraulic cylinders; minimum working fluid pressure in control systems and catchers; open/closed position of catchers; vertical position of the catcher (when the catchers are set to outermost positions, the hoisting gear shall switch off);

loss of power supply;

.7 proper actuation of interlocking arrangements to prevent opening of catchers of moving yoke when the catchers of stationary yoke are in half-closed position;

.8 actuation of the MODU hull position indicator in the following cases: maximum heel, draught and trim (for semi-submersible MODU); minimum load on legs (for self-elevating MODU).

12.7.2.2 System for remote (automated) control of ballast system pumps and valves of submersible and semisubmersible MODU.

12.7.2.2.1 During mooring and sea trials, the following shall be checked:

.1 remote and local control of ballast pump electric motors by starting and stopping them three times both from the main control station and local control stations;

.2 remote opening/closing of valves by opening/closing them at least three times from the main control station and check for their actuation from local control stations;

.3 automatic control of valves operation by adjusting the actuation setting;

.4 actuation of alarms when valves are in opened/closed position;

.5 actuation of alarms at the maximum and minimum water levels in ballast compartments and tanks;

.6 operation of valve manual controls and servo-motor local controls.

12.7.2.3 Automated control of self-elevating MODU sea water supply system.

12.7.2.3.1 During mooring and sea trials, the following shall be checked:

.1 remote and local control of electric motors for sea water submersible pumps by starting and stopping them three times from the central control station, from the station mentioned in the detailed design and from local control stations;
.2 automatic starting of submersible pump electric motors at the minimum level in the sea water storage tank and automatic stopping when the tank is being filled;
.3 actuation of alarms and indicators in the following cases:
  minimum water pressure in the system;
  minimum level in the sea water storage tank.

12.7.2.4 Automatic control of air supply system for MODU riser tensioning device.

12.7.2.4.1 During mooring and sea trials, the following shall be checked:
  .1 remote and local control of compressor electric motors by starting and stopping them three times from the central and main control stations, from the station mentioned in the detailed design and from local control stations;
  .2 automatic starting of compressors at pressure drop in air receivers and their automatic stopping when the nominal working pressure is reached;
  .3 actuation of alarms and indicators on the maximum and minimum working pressure in air receivers.
13 LIFE-SAVING APPLIANCES

13.1 GENERAL

13.1.1 The provisions of this Section define the scope and methods of technical supervision of installation and testing of life-saving appliances listed in the Table 13.1.1 on board the ship under construction.

13.1.2 General provisions for the organization of the technical supervision are given in Section 1.

13.1.3 Technical documentation.

13.1.3.1 Installation and testing of life-saving appliances on board shall be performed under the Register technical supervision according to the RS-approved technical documentation.

13.1.4 Technical supervision of the Register.

13.1.4.1 Surveys during installation and testing of life-saving appliances shall be performed according to the examination and testing plan developed by the shipyard according to 13.2.1 based on Table 13.1.1, taking into account 13.3.

Table 13.1.1

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Item of technical supervision</th>
<th>Installation and mounting</th>
<th>Mooring trials</th>
<th>Sea trials</th>
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<td>launching appliances for rescue boats</td>
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<td>Lifejacket lights</td>
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<td>Line-throwing appliances</td>
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<td>Equipment of survival craft, rescue boats/fast rescue boats</td>
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<td>+</td>
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<td>Marine evacuation systems</td>
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<td>28</td>
<td>Symbols for use in accordance with SOLAS-74 as amended</td>
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<tr>
<td>29</td>
<td>Means of rescue</td>
<td>+</td>
<td>+</td>
<td></td>
</tr>
</tbody>
</table>

1 On cargo ships of 20,000 gross tonnage and above (refer to 13.4.1).
2 Equipment of survival craft, rescue boats/fast rescue boats, for which the RS certificates are required, are given in Appendix 1 to Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision.
13.1.5 Tests and checks specified in this Section are based on an assumption that the life-saving appliances have been tested at the firm (manufacturer) in compliance with the requirements of Section 13, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

13.1.6 At the initial survey of life-saving appliances during construction and testing to confirm the ship compliance with the requirements of SOLAS-74, as amended, also the requirements of Section 19 shall be met.
13.2 SURVEY PLANNING

13.2.1 Prior to commencement of survey of the life-saving appliances of the ship under construction, the RS Branch Office shall agree the examination and testing plan for life-saving appliances developed by the shipbuilder taking into account Table 13.1.1. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1 and with due regard to 13.3.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

13.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

13.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

13.2.4 Quality standards for installation and testing of the life-saving appliances shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

13.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
13.3 CHECKS AND TESTS

13.3.1 Launching appliances of lifeboats/rescue boats/fast rescue boats and liferafts.
13.3.1.1 General.
13.3.1.1.1 All metal structures of decks (and other hull elements) in way of the launching appliances, including deck strengthening thereunder, shall be accessible for examination during the tests.

No cementing of foundation, installation of planking or application of mastic, as well as lining of ceiling prior to completion of the tests shall be permitted.

13.3.1.2 Loaded tests.

13.3.1.2.1 The survival craft or rescue boat, loaded with its normal equipment or an equivalent mass and a distributed mass equivalent to that of the number of persons, each weighing 75 kg or 82.5 kg, as applicable, is permitted to accommodate, should be released by operation of the launching control on deck. The speed at which the survival craft or rescue boat is lowered into the water shall be not less than that obtained from the formula

\[ S = 0.4 + (0.02H) \]  

where \( S \) = speed of lowering, in m/s;

\( H \) = height from davit head to the waterline at the lightest seagoing condition, in m.

Thus, the maximum lowering speed established by the Administration shall not be exceeded.

13.3.1.3 Light loaded test.

13.3.1.3.1 The survival craft or rescue boat loaded with its normal equipment or an equivalent mass shall be released by operation of the launching control on deck to demonstrate that the lifeboat's mass is sufficient to overcome the frictional resistance of the winch, falls, blocks and associated gear. The lowering speed shall be as established by the Administration. A person shall then board the survival craft or rescue boat and perform a test of the launching operation from within the boat.

13.3.1.4 The requirements of 13.3.1.2 and 13.3.1.3 do not apply to free-fall lifeboats.

13.3.1.5 Loaded lowering test (brake test only).

13.3.1.5.1 The survival craft or rescue boat loaded with its normal equipment or an equivalent mass and a distributed mass equal to that of the number of persons, each weighing 75 kg or 82.5 kg, as applicable, is permitted to accommodate + 10% of the working load, shall be released by the operation of the launching controls on deck. When the craft has reached its maximum lowering speed, the brake shall be abruptly applied to demonstrate that the attachments of the davits and winches to the ship's structure are satisfactory. The maximum lowering speed established by the Administration shall not be exceeded.

13.3.1.5.2 If lowering of the lifeboat is controlled from within the lifeboat by means of a control wire paid off from an auxiliary drum on the winch, the following additional points shall receive particular consideration after installation of the davits and winches:

1. the mass on the control wire shall be sufficient to overcome the friction of the various pulleys on the control wire, when turning out the lifeboat from the stowed to the embarkation position;

2. it shall be possible to operate the winch brake from within the lifeboat;

3. the winch brake shall not be affected by the mass of the fully extended control wire;

4. there shall be sufficient length of control wire available at the lifeboat, during all stages of lowering; and

5. means shall be provided to retain the free end of the control wire in the lifeboat until the lifeboat is detached from the launching appliance by the operator.

13.3.1.5.3 If the winch brake is exposed to the weather, the lowering test shall be repeated with the braking surface wetted.
13.3.1.6 Recovery test.
13.3.1.6.1 It shall be demonstrated that the davit-launched lifeboat or rescue boat can be recovered to its stowage position by means of operating the hand gear and can be safely and properly secured.
13.3.1.6.2 For free-fall lifeboats it shall be demonstrated that the survival craft can be recovered to its stowage position and can be safely and properly secured.
13.3.1.6.3 Where davits are recovered by power, it shall be demonstrated that the power is automatically cut off before the davit arms come against the stops.
13.3.1.6.4 In the case of rescue boat launching appliances, it should be demonstrated that the fully equipped rescue boat when loaded with a mass equal to that of the number of persons it is approved to carry can be recovered by means of a winch at a rate of no less than 0,3 m/s.
13.3.1.6.5 It shall be demonstrated that the rescue boat can be recovered by means of the winch referred to in 13.3.1.6.4 using a hand gear.
13.3.1.6.6 The lower blocks of the boat tackle (long link of the suspension chains) shall be freely released when the boat reaches the water surface.
Ease of belaying the lower block of the boat tackle (eye or long link) to the boat hooks shall be checked when the boat is waterborne.
13.3.1.7 Adjustable ramp test.
13.3.1.7.1 It shall be demonstrated that adjustable ramps for free-fall launching may be adjusted satisfactorily with the free-fall lifeboat loaded to 1,2 times its related load.
13.3.2 Installation tests of liferaft launching appliances.
13.3.2.1 Static load test.
13.3.2.1.1 Each release hook shall be statically proof tested to 2,5 times the safe working load and be provided with an approved testing establishment certificate certifying that it has been so tested.
13.3.2.2 Operational test.
13.3.2.2.1 Each release hook shall be submitted to an operational test with a mass equivalent to the safe working load being applied. The release arrangements shall be demonstrated and checked with the liferaft loaded to ensure that the automatic release hook will not release while the load is still applied.
13.3.2.3 Marking.
13.3.2.3.1 Each release hook shall be checked to ensure it is permanently marked with:
- the manufacturer's name or the approved name of the release hook;
- the date of manufacture;
- the safe working load;
- the number of the test certificate required by 13.3.2.1.1; and
- clear, concise operating instructions.
13.3.2.4 Lowering test.
13.3.2.4.1 One liferaft ballasted to represent a 10 % overload or an equivalent mass shall be lowered from each launching appliance to establish the rate of lowering. The 10 % overload shall be 10 % of the mass of the liferaft assembly together with its equipment and full complement of persons calculated at 82,5 kg per person. It shall be jerked to ensure that the liferaft launching appliance, its fastenings and the supporting structures can withstand the associated loads.
13.3.2.5 Recording of lowering test.
13.3.2.5.1 The time shall be recorded for the sequence of preparing, loading and launching three liferafts. If so desired, persons may be used only in the preparing and loading operations and ballast substituted for the lowering and launching part of the test. This sequence test need not be carried out on every launching appliance on a ship.
However, at least one example of each launching appliance type and arrangement shall be so tested on each ship.
13.3.2.6 Towing strain test.
13.3.2.6.1 A moderate towing strain shall be put on the liferaft when waterborne to check that the release arrangements are satisfactory under this condition.
13.3.3 Procedure for checking the technical condition and operability of command broadcast apparatus.

13.3.3.1 The external examination shall comprise the examination of the main and remote microphone posts, remote loudspeakers. The microphone posts and commutators on the open deck shall be enclosed. Where the command broadcast apparatus is combined with the general purpose broadcasting unit intended for transmitting sound-recording programs and general radio broadcasting, the loudspeakers fitted in the ship's accommodations shall have volume controls.

13.3.3.2 Check of operability includes check of the following:

.1 the command broadcast apparatus. The communication of a wheelhouse with all posts shall be established selectively or circularly in any combination. The ability factor: the sound level of orders reproduction in interior spaces, as well as on open decks shall be 75 dB(A) and at least 20 dB(A) above the speech interference level (in cabins the above sound pressure levels shall be also provided during sea trials); the sound level of orders reproduction on the open decks shall be 80 dB(A) and at least 15 dB(A) above the speech interference level. Where the command broadcast apparatus is combined with the broadcasting unit intended for transmitting general radio broadcasting and sound-recording programs, the priority of the loudspeaking communication and command broadcast shall be checked;

.2 the opportunity to control the command broadcast apparatus from any command microphone post. The ability factor: all kinds of control (starting, switching off, switching of transmission lines, starting of forced broadcasting systems) shall be carried out remotely from any command microphone post. A visual alarm shall be activated when the command broadcast apparatus is started. The acoustic monitoring of an audio quality in each transmission line shall be carried out from the main command microphone post;

.3 the apparatus operation from an emergency transitional energy source, if any. The main (emergency) power source shall be switched off.
13.4 LIFEBOATS/RESCUE BOATS AND LIFERAFTS

13.4.1 Launch test.
   13.4.1.1 Except for free-fall lifeboats, it shall be demonstrated that the fully equipped
       lifeboat on cargo ships of 20 000 gross tons or more and rescue boat can be launched from a
       ship proceeding ahead at a speed of not less than 5 knots in calm water and on an even keel.
       There shall be no damage to the lifeboat or the rescue boat or their equipment as a result of
       this test.

13.4.2 Check of inscriptions and marking.
   13.4.2.1 Clear permanent inscriptions showing the port of registry and name of the ship, as
       well as the principal dimensions and capacity shall be marked externally on both sides of each
       lifeboat/rescue boat/fast rescue boat, as well as on each rigid liferaft and buoyancy apparatus bow.
       The lifeboat number and marking permitting to identify the ship, to which the lifeboat
       belongs, shall be made in such a way that it is visible from above.

   13.4.3 When stowing the liferafts, it is necessary to verify whether the number, capacity
       and location of the rafts comply with the RS-approved documentation, whether the Register
       certificates and firm's (manufacturer's) documents are available, whether the rafts are
       consistent with the documentation (by brands and marking) and their usable life, as well as
       technical condition (by external examination).

       Note. The rafts stowed on board ship shall have an usable life to next survey not less than
       9 months considering the maximum permissible period between surveys of 18 months since
       manufacture.

   13.4.4 When securing raft in the stowage positions the following shall be checked:
       availability and proper installation of the hydrostatic release unit (by the firm's (manufacturer's)
       documents), possibility of the raft free floating when the ship sinks.
13.5 LIFEBOYS AND LIFEJACKETS

13.5.1 It is necessary to check the number, arrangement and securing of lifebuoys on board ship according to the RS-approved documentation, availability of the Register certificates, as well as the technical condition and completeness of these.

Attention shall be given to proper arrangement and availability of the lifebuoys for immediate use.

13.5.2 The arrangements for quick release of the lifebuoys fitted with self-activated smoke signals and lights on the ship’s navigating bridge should be tested, using a dummy smoke signal, if necessary to demonstrate that the lifebuoys and their attachments will drop clear of the ship’s side when released.

13.5.3 Check of lifejackets.

13.5.3.1 Subject to check shall be all lifejackets including additional number of lifejackets to be provided for one watch crew and children, availability of the Register certificates and the firm’s (manufacturer’s) documents, their consistency with marking on the lifejackets, technical condition, completeness (availability of the whistle, search light and sea water battery, as well as the working life of the latter), availability of inscriptions on the lifejackets.

13.5.4 Self-igniting and light-and-smoke buoys of the lifebuoys.

13.5.4.1 It is necessary to check the number, marking (working life of the batteries), availability of the RS certificate, as well as the proper installation of their fastenings.
13.6 IMMERSION SUITS AND PERSONAL THERMAL PROTECTIVE AIDS

13.6.1 It is necessary to check the availability of the above items, compliance with the RS certificates submitted for them and their completeness. It is necessary to make sure that there are no visible damages and to examine their stowage positions in order to verify that they comply with the requirements of the manufacturer's instructions.
13.7 LINE-THROWING APPLIANCE

13.7.1 It is necessary to check the completeness of the line-throwing appliance, number of the projectiles and lines (including the working life), availability of the Register certificate and instructions for use of the appliance. Besides, it is necessary also to check the storage of the projectile, buoyant lines and pistol in a water-resistant casing (unless these items are stored in a watertight space).
13.8 ITEMS OF LIFEBOAT/RESCUE BOAT EQUIPMENT

13.8.1 The above items shall be checked for compliance with the RS-approved documentation and requirements of 4.4.8 for lifeboats and 5.1.2 for rescue boats of the International Life-Saving Appliance Code\(^1\). Subject to check shall be the availability and completeness, stowage of the items in the lifeboat and availability of the firm's (manufacturer's) documents, as well as for the items of lifeboat equipment as it stipulated by the RS Nomenclature, the availability of the relevant Register certificates.

\(^1\) Hereinafter referred to as "the LSA Code".
13.9 MARINE EVACUATION SYSTEMS

13.9.1 On the installation of a marine evacuation system on a ship, at least 50% of such systems shall be subjected to a harbour trial deployment. At least one of these systems should be deployed in association with at least two of the inflatable liferafts to establish that correct launching and subsequent retrieving, bowsing-in and inflation procedures have been correctly installed.

13.9.2 Subject to the above deployments being satisfactory, untried systems shall be similarly deployed within 12 months of the installation date.

13.9.3 For first of the above deployments, in association with the launching of the liferafts, a partial evacuation trial should be carried out to ensure that:

.1 the system does not interfere with the launching of other life-saving equipment fitted on board; and

.2 the system and associated liferafts are clear of all possible obstructions or dangers such as stabilizers or the ship's propellers.
13.10 SURVEY OF MODU/FOP LIFE-SAVING APPLIANCES

13.10.1 General.
13.10.1.1 Applicable requirements of Section 13, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and Section 13 of the Guidelines, as well as the applicable requirements of the LSA Code apply to the MODU/FOP life-saving appliances subject to technical supervision of the Register according to the RS Nomenclature during manufacture and installation.

13.10.1.2 This Chapter contains additional requirements to technical supervision during survey of the MODU/FOP specific life-saving appliances.

13.10.2 Surveys.
13.10.2.1 The scope and procedure for survey of lifeboats (capsules) during manufacture and testing at the manufacturer shall comply with 13.4, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision related to the lifeboats.

13.10.2.2 The scope and procedure for survey of launching appliances for the MODU/FOP survival craft during manufacture, bench tests at the manufacturer and during installation and testing on board MODU/FOP shall comply with Section 13, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision and the applicable requirements in Section 13 of the Guidelines, provided that after installation on board MODU these appliances will be subject to survey at the manufacturer during testing for compliance with the following requirements:

.1 the lowering speed under the load equal to \( P_{working} \) shall be not less than the value determined by the requirements in 6.1.2.8 of the LSA Code;

.2 launching appliances of rescue boats shall be capable of recovering the lifeboats at the minimal speed 0.3 m/s under the load equal to \( P_{working} \);

.3 measures shall be taken to prevent discharge of any liquids onto life-saving appliances during their launch and departure from MODU/FOP;

.4 all survival craft required for safe escape from MODU/FOP shall be launched with all people and outfit within maximum 10 min from output of escape signal.

13.10.2.3 When checking outfit of survival craft, the RS surveyor shall comply with the requirements in 4.1.5, 4.4.8 and 5.1.2 of the LSA Code and make sure that:

.1 each lifeboat shall carry a two-way VHF radiotelephone apparatus. In addition, at least two such apparatuses shall be available on each MODU/FOP, so stowed that they can be rapidly placed in any liferaft;

.2 each lifeboat shall carry a survival craft search and rescue locating device. In addition, at least two survival craft search and rescue locating devices shall be available on each MODU/FOP, so stowed that they can be rapidly placed in any liferaft.

13.10.2.4 During survey of arrangement of lifebuoys with lifelines, special consideration shall be given to length of lifelines which shall be equal to one and a half of distance between the place of stowage of buoy and water level (when MODU/FOP is afloat, this distance shall be measured at its minimum draught) or 30 m, whichever is greater.
14 SIGNAL MEANS

14.1 GENERAL

14.1.1 The provisions of the present Section shall apply in technical supervision of signal means under the RS Nomenclature during construction of ships.

14.1.2 The definitions and explanations on the general terminology are given in Part III "Signal Means" of the Rules for the Equipment of Sea-Going Ships.


14.1.4 Technical documentation.

14.1.4.1 Installation and testing of signal means on board the ship shall be performed under the Register technical supervision according to the RS-approved technical documentation.

14.1.5 Technical supervision of the Register.

14.1.5.1 Surveys during installation and testing of signal means shall be performed according to the examination and testing plan developed by the shipyard according to 14.2 based on Table 14.1.5.1, taking into account 14.3.

<table>
<thead>
<tr>
<th>Item of technical supervision</th>
<th>Inspection of compliance with the approved technical documentation</th>
<th>Inspection of documents confirming the Register supervision; brands</th>
<th>External examination, checking completeness</th>
<th>Inspection of mounting</th>
<th>Control measurements</th>
<th>Checking operability</th>
<th>Supervision during mooring trials</th>
<th>Supervision during sea trials</th>
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<tr>
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</table>

14.1.6 Tests and checks specified in this Section are based on an assumption that the signal means have been tested at the firm (manufacturer) in compliance with the requirements of Section 14, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

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1 Hereinafter referred to as "the Rules for the Equipment".
14.2 SURVEY PLANNING

14.2.1 Prior to commencement of survey of the signal means of the ship under construction, the RS Branch Office shall agree the examination and testing plan for items of technical supervision developed by the shipbuilder taking into account 14.3 and Table 14.1.5.1. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

14.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

14.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

14.2.4 Quality standards for installation and testing of the signal means shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

14.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
14.3 TECHNICAL SUPERVISION OF SIGNAL MEANS DURING CONSTRUCTION PERIOD

14.3.1 Technical supervision of signal means during construction period shall include the following:
.1 check of compliance of signal means with the RS-approved technical documentation for the ship construction;
.2 check of fitting of signal means on board ships;
.3 supervision during mooring and sea trials of ships;
.4 issue of the Register documents.

14.3.2 Check of compliance of signal means with the RS-approved technical documentation is carried out through the review of this documentation, passports, certificates and other documents, as well as by survey of signal means and conformity of their accompanying papers to the markings and brands assigned to signal means.

14.3.3 Check of fitting of signal means on board (refer to Appendix 1 to this Section) shall be carried out in way of external examination and control measurements with the purpose of determining the following:
.1 proper arrangement of the fixed signal means in the vertical and horizontal planes, over the ship’s breadth and also in relation to the centre longitudinal plane;
.2 proper mutual positioning of signal means;
.3 proper design of positioning and securing of signal means;
.4 absence of any ship structures or devices obstructing the proper operation of signal means;
.5 possibility of dismantling signal means and replacing with spare parts;
.6 proper positioning of outboard signal means;
.7 proper laying of electrical cables and protective earthing of signal means according to the requirements of Section 10;
.8 availability of protection from radio interference caused by electrical signal means;
.9 proper design of piping system conveying compressed air, steam or another media for actuation of the sound signal means;
.10 availability of devices conveying the media for the signal means and drainage of condensate;
.11 proper design of hoistiong devices for outboard signal means;
.12 proper construction and safely of devices and appliances for pyrotechnic signal means to be operated as well as storage lockers or boxes for them.

14.3.4 Surveys of signal means shall be carried out during mooring and sea trials of ships (refer to Appendix 2 to this Section) testing these means in operation with the purpose of determining the following:
.1 ready preparedness of signal means for operation;
.2 proper operation of visual and sound alarms of navigation lights;
.3 possibility of replacing fixed navigation lights with spare ones;
.4 availability of hoisting appliances for the navigation lights not fixed stationary;
.5 possibility of operation of navigation lights and flashing lights from the specified power sources;
.6 possibility of carrying of signal shapes on board required by the Rules for the Equipment.

14.3.5 In case of satisfactory results of mooring and sea trials and ultimate compliance of signal means with the requirements of the Rules for the Equipment, the RS surveyor shall duly issue the Register documents for the ship.
14.4 SURVEY OF MODU/FPU/FOP SIGNAL MEANS

14.4.1 Proper installation of signal means on board MODU/FOP shall be checked by visual examination and measurements. This check is aimed at checking if these signal means are arranged according to the diagram approved by the Register and comply with Part XVI "Signal Means" of the MODU/FOP Rules.

14.4.2 Proper installation of signal means on board FPU shall be checked by visual examination and control measurements; the check is performed to verify the proper arrangement of these signal means according to the diagram approved by the Register and their compliance with Part II "Signal Means" of the Rules for the Equipment of Floating Offshore Oil-and-Gas Product Units.
CHECK OF FITTING SIGNAL MEANS ON BOARD

1. Check of proper arrangement of the signal means fixed stationary in the vertical and horizontal planes, over the ship’s breadth and also in relation to the fore and aft centre plane.

1.1 Signal means shall be arranged in accordance with the drawing approved by the Register and in accordance with the requirements of Section 4, Part III “Signal Means” of the Rules for the Equipment.

Distance measurements shall be made with a long measure tape. Definition of the upper deck line for determining the light height shall be performed by the hose-type water level or by any other approved method. The proper arrangement of lights in the vertical plane shall be determined by an adjusting tool. As a basic way of controlling the arrangement of sector navigation lights, the method of mounting with the help of marks along the light axis line assigned on the lantern case shall be accepted. Coincidence of these marks with the conditional fore and aft centre line or parallel fore and aft centre lines in the position where the light is fitted shall ensure the required accuracy (refer to Fig. 1.1).

![Fig. 1.1](image)

Fitting of masthead light:
1 — centre line; 2 — marks on the lantern case centre line

1.2 Whistles shall be so fixed that the centre of the sound source is at the height of not less than 2.5 m above the uppermost deck extending from side to side and at least 0.5 m above the deckhouse and any other structures on this deck, which can obstruct the propagation of sound.

1.3 The bell shall be placed on the clear part of the forecastle deck, near the windlass or capstan and hung up in such a manner as to permit its free swinging through an angle of not less than 50° each way without touching any part of the structure or equipment of the ship.

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1 Check of proper arrangement of signal means may be also carried out using any other method approved by the Register.
1.4 The gong shall be placed as near the after end of the ship as possible and at such a place where nothing will intercept the propagation of the sound and be hung up so as to comply with the requirements of 1.3. A gong up to 5 kg in mass need not be fixed in a stationary position, but a special storage place shall be provided in the after part of the ship. The gong beetle shall be kept in a special pocket to be fitted close to the gong.

1.5 The ships shall be provided with proper devices (masts, stays with sufficient number of signal halyards) for hoisting the hoisting shapes. The signal shapes shall be stored near the navigation bridge or the devices for hoisting them to their regular positions.

1.6 For storing the pyrotechnic signal means, the ship shall be provided with special watertight metal lockers built into the deckhouse on the navigation bridge, or a metal box firmly secured on the bridge deck.

2. Check of proper mutual positioning of signal means.

2.1 The check shall be carried out in accordance with the drawing and requirements of Section 4, Part III "Signal Means" of the Rules for the Equipment.

3. Check of proper arrangement of side lights.

3.1 The side lights shall be protected by inboard shields with two transverse screens (fore and aft) perpendicular to the shield. Shields shall be of such a length that the distance from the outer length of the lantern axis or cylinder to the after edge of the transverse screen will be at least 0.9 m. The forward transverse screen shall be of such a breadth as to ensure that luminous intensity shall disappear within 3° ahead (refer to Fig. 3.1). The aft transverse screen shall be of such a breadth as to mask completely the light from being seen across the stern, but not to hinder showing its light to 22,5° abaft the beam. The height of the shield and of the screens shall not be less than that of the light case.

It is necessary that side lights placed on the horizontal shield or in recesses as well as the height of the fore screen ensure the vertical sector visibility required by the Rules for the Equipment. Inner surfaces of shields shall be painted matt black. The shields of the side lights shall be placed in such a position that their outer edge will not project beyond the line of the side of the ship.

![Fig. 3.1](image)

Fig. 3.1
Fitting navigation side light:
1 — screen; 2 — shield; 3 — filament of the lamp

4. Check to ascertain that there are no ship structures or hull fittings obstructing proper operation of signal means.

4.1 The masthead lights shall be placed above all other lights except for the manoeuvring light, and also above the obstructing superstructures so that each of them could be distinctly visible over the arcs of the horizon assigned to them. Horizontal shields of sufficient size

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1 Transverse screen need not be fitted where the light design ensures that the horizontal sectors of side lights are in accordance with the requirements of the Rules for the Equipment.
shall be installed under the masthead lights so as to prevent these lights from illuminating the navigation bridge and other decks. The shield length shall not decrease the vertical visibility sector.

The all-round lights, except for anchor ones, shall be so located as not to be obscured by masts, topmasts or superstructures within sectors of more than 6° (refer to Fig. 4.1).

In case of the all-round lights located near masts obscuring the visibility sector at more than 6°, platforms for fixing all-round lights shall be made distant from the masts with the help of long brackets or other appliances. It is necessary to make sure that there are no such structures or hull fittings obstructing propagation of the sound signal means sounding.

5. Check of possibilities of removing signal means and replacing them with spare parts, where necessary.

6. Check of proper positioning of hoist-type signal means.

6.1 Availability shall be checked of suitable devices for hoisting hoist-type lights to their regular positions and lowering them onto the deck. Such devices shall be of such structure as to ensure the correct stable position of lights when hoisted to their regular positions. In this case the visibility in horizontal and vertical sectors of lights shall be ensured.

6.2 Signal shapes shall be provided with suitable devices for fixing them to halyards on which they are hoisted, and for joining with other shapes. Folding shapes shall be fitted with the devices retaining them in open position and preventing the shapes from spontaneous folding. Devices for joining the shapes to each other (except the cones) shall provide for maintaining the proper distance between them, which is not to be less than 1.5 m for ships of 20 m and over in length and not less than 1 m for ships of less than 20 m in length. The cones shall be provided with devices for joining them directly to each other at their points or bases.

6.3 The trial hoisting of signal shapes to their regular positions shall be carried out.
7. Check of proper mounting of electrical cables and protective earthing of signal means.
   In this case the following shall be checked:
   .1 cable laying and its compliance with the drawings approved by the Register;
   .2 reliable securing, distance between securing devices, cable bending inner radius, cable marks and sections, no additional joints not specified by the drawing, cable lead-in;
   .3 switching on of navigation lights to the cable supply system by plug-and-socket conductor;
   .4 protection of the cable from damages at the outlet points in way of the deck and mast;
   .5 availability of protective earthing with the section suitable for the power supplying cable of shields, lights, plug-and-socket connectors.
8. Check of available protection from radio interference caused by electric signal means.
   8.1 In this case the following shall be checked:
      .1 availability of screening coatings on the cables laid in the spaces where the ship equipment of radio communication and radio navigation facilities is in-stalled, as well as on the upper decks and superstructures not separated from the aerial by a metal deck or bulkhead;
      .2 continuous screening, earthing of cable coatings and devices.
9. Check of proper design of piping system conveying compressed air, steam or another media for the sound signal means to be operated with the purpose of excluding their spontaneous sounding under the action of wind, snow, icing-up, etc.
10. Check of availability of devices ensuring supply of agent for sound signal means with no condensate.
11. Check of proper construction of appliances for hoisting portable signal means (refer to Section 6 of this Appendix).
12. Check of proper structure and safety of appliances and devices for operation of pyrotechnical signal means, as well as their storage locations.
   12.1 Availability on board shall be checked of special devices of sufficient size with a hole for the starting line to operate rocket parachute flares, which are permanently fixed on the bulwark or guard railings of the navigation bridge; also for the storing of the pyrotechnic signal means availability of special watertight metal lockers built into the deckhouse on the navigation bridge, or a metal box firmly secured on the bridge deck, shall be checked.
SURVEY OF SIGNAL MEANS DURING MOORING
AND SEA TRIALS OF SHIPS

1. Preparedness of electric signal means for ready operation.
   1.1 The navigation lights shall be fitted at their regular locations, supplied by two feeders and be at all times ready for use in accordance with their designation.
   1.2 The spare set of navigation lights shall be stored in a specially equipped light storage room or in special light lockers in assembled and good condition, and be ready for fitting and use as specified.
   1.3 During mooring trials, documents (certificates, form records, passports) for signal means of spare set confirming the Register technical supervision of their manufacture under RS Nomenclature shall be checked.
   1.4 Provision of ships with a spare set of lights and spare parts shall be as per the ship group (refer to 2.2.4 — 2.2.6, Part III "Signal Means" of the Rules for the Equipment).

2. Proper operation of visual-and-sound signals of navigation lights.
   2.1 Visual signals shall be tested with supplying devices of the shield and lights switched on.
   
   Depending upon the accepted design, the characteristics of proper operation are as follows: burning of signal lamps, actuation of blinker relay and absence of sound signal.
   2.2 With putting the switch (pressing the button) in the "control" position, sound alarms of the lights being tested shall start functioning simultaneously with visual signals.
   2.3 When simulating a damage in the light circuit by removing the lamp or by disconnecting the plug-and-socket connector, the acoustic and visual signals shall start functioning indicating the circuit failure.
   2.4 When simulating the failure of power supply of the navigation lights using the power circuit breaking, the sound signals shall be supplied with power and be supplied and operated from another power source.

3. Possibilities of replacing the stationary navigation lights with spare ones.
   3.1 Possibilities of replacing the stationary navigation lights with spare ones shall be tested by a random replacement of lights (trial replacement of basic side lights with spare ones is required where the spare lights are not stationarily fixed). The adequate horizontal and vertical sectors of visibility of spare lights as specified in the Rules for the Equipment shall be checked.

4. Survey in operation of hoisting devices for non-stationary navigation lights.
   4.1 Availability of suitable devices for hoisting and lowering navigations lights not fitted stationary shall be checked. Such devices shall be so constructed as to ensure the correct and stable positions of the lights when hoisted to their regular positions. The adequate horizontal and vertical sectors of visibility as specified in the Rules for the Equipment shall be checked.

5. Availability and possibilities of operation of basic and spare set of navigation lights and flashing lights and specified power supply sources.
   5.1 During mooring and sea trials of electric navigation lights and flashing lights the following shall be checked:
      .1 insulation resistance of each feeder with power supply sources switched off at the beginning and at the end of the trials;
      .2 cable switching in, as specified in the drawing of connections, availability of markings;
      .3 reliability of contact connections, protective and sealing coatings of cable ends, conformity of links of power safety fuse of prototype lamps;
.4 testing of the whole scheme in operation (burning of the lights from both power supply sources during the time sufficient to be convinced of the reliability of the lights in operation), operation of switches, alarms and all commutation devices;

.5 acoustic and visual alarms on the navigation light shield warning of any light failure. In this case acoustic alarms shall function automatically when switched on, warning of any navigation light failure. Power for acoustic alarms shall be supplied from a source or feeder other than the source or feeder supplying power for navigation light shield or accumulators;

.6 burning of spare navigation lights from the specified source of light. In case of power supply from accumulators, the discharge current, voltage dropping on all the feeders (for the prototype ship only) shall be checked;

.7 manoeuvring lights with manual and automatic actuation, where such actuation is specified. Stable operation of automatic controls, manoeuvring lights automatic cutting-off when changing-over the whistle mechanism to manual or automatic actuation shall also be checked;

.8 the daytime signaling lamp in operation when power supplied from the ship’s mains and from the emergency source of electrical power during at least 15 min. It shall be stored in the rudder or chart house and be at all times ready for use.

6. During mooring and sea trials of whistle electric mechanisms the following shall be checked:

.1 insulation resistance of cable and equipment scheme, cable switching in, as specified in the connection scheme, availability of markings, reliability of contact connections, availability of protective and sealing coatings of cable ends, protection of feeders, protective earthing of apparatus;

.2 operation of switches, alarms, commutation devices;

.3 operation of whistle electric mechanism with manual and automatic actuation under the specified programs. Duration of signals, intervals and full cycles in automatic actuation shall be measured;

.4 possibility of providing for manual actuation of signals with automatic cutting-off of the automatic controls at the moment of manual actuation;

.5 flashes sent simultaneously with whistle electric mechanism sounding;

.6 whistle electric mechanism cutting-off at the moment of manual actuation of manoeuvring light;

.7 operation of electric heating devices.
15 RADIO EQUIPMENT

15.1 GENERAL

15.1.1 The provisions of this Section shall apply during technical supervision of the radio equipment of ships listed in the RS Nomenclature.

15.1.2 The Section contains the requirements for technical supervision of the radio equipment in the course of ship construction.

15.1.3 General provisions of organization of technical supervision of ship construction are specified in Part I "General Regulations for Technical Supervision" and of technical documentation, in Part II "Technical Documentation" of the Rules for Technical Supervision.

15.1.4 Technical documentation.

15.1.4.1 Installation and testing of radio equipment on board the ship shall be performed under the Register technical supervision according to the RS-approved technical documentation.

15.1.5 Technical supervision of the Register.

15.1.5.1 Surveys during installation and testing of radio equipment shall be performed according to the examination and testing plan developed by the shipyard according to 15.2.1, taking into account 15.3 and 15.4.

15.1.6 Tests and checks specified in this Section are based on an assumption that the radio equipment has been tested at the firm (manufacturer) in compliance with the requirements of Section 15, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the RS surveyor in substantiated cases.
15.2 SURVEY PLANNING

15.2.1 Prior to commencement of survey of the radio equipment of the ship under construction, the RS Branch Office shall agree the examination and testing plan for radio equipment developed by the shipbuilder taking into account the RS Nomenclature and 15.3 and 15.4. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

15.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

15.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

15.2.4 Quality standards for installation and testing of the radio equipment shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

15.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
15.3 SURVEY DURING INSTALLATION AND CABLING

15.3.1 Installation and cabling of the radio equipment shall be carried out in compliance with the RS-approved technical documentation, the following shall be checked:

1. special spaces where the arrangement of the radio equipment is provided;
2. sources of power and cabling;
3. operational (high frequency) earthing;
4. arrangement and installation of the radio equipment.

15.3.2 In the course of surveys of spaces for the radio equipment and its installation the following shall be checked:

1. arrangement of the radio equipment, passages in the space, provision of doors, means of access and exits and also emergency ones;
2. main and auxiliary equipment, power and charging boards, to control stations are readily accessible;
3. radio equipment, power sources and auxiliary equipment are securely fastened by clamps, brackets or bolts;
4. lighting, ventilation and heating in spaces for the radio equipment and accumulator battery rooms.

15.3.3 In the course of surveys of the radio equipment cabling, the following shall be checked:

1. laying, fastening and passing of cables through watertight decks and bulkheads, provision of packing appliances;
2. proper cable brands and cross sections in compliance with the drawings;
3. proper disjunction, splicing, contact and protection terminals, connection, and jointing of cables;
4. compliance with the minimum internal bending radii of cables;
5. condition of external cable sheathings;
6. strength of soldering or squeezing of cable terminals to cable cores;
7. proper cable length available at the lead-in into the apparatus;
8. absence of coaxial cables in the same cable package, cable run, cable suspension, etc. with power and lighting cables;
9. insulation resistance of every laid cable disconnected at both ends from the radio equipment shall be not less than 20 MOhm irrespective of the cable length;
10. proper continuity screening of cables and aerial feeders and also special sheathings and pipe linings when used as means of mechanical protection or screens.

15.3.4 During surveys of operational (high frequency) earthing of the radio equipment within the interior of spaces, the following shall be checked:

1. reliability of electrical connection of copper busbar and aerial commutator (if any) to a metal bulkhead or deck electrically connected to the ship’s hull;
2. compliance of the cross sectional area of copper busbars and tappings leading to earthing terminals of transmitters with the copper busbar length run from the radio equipment to the place where connection with the bulkhead or deck is effected;

<table>
<thead>
<tr>
<th>Power of transmitter, in W</th>
<th>Busbar sectional area, in mm²</th>
</tr>
</thead>
<tbody>
<tr>
<td>Below 50</td>
<td>25</td>
</tr>
<tr>
<td>50 to 500</td>
<td>50</td>
</tr>
<tr>
<td>Above 500</td>
<td>100</td>
</tr>
</tbody>
</table>
.3 places of connections are thoroughly cleaned;
.4 reliable earthing of metal guards and leads-in aerials;
.5 reliable earthing of filter cases, screening cases and waveguides pipes, cases of various instruments, etc. The total resistance of all protecting connections of any earthing shall not exceed 0,02 Ohm.

15.3.5 In the course of surveys of leads-in and interior wiring of aerials, the following shall be checked:
.1 compliance of insulators with operational voltages of the transmitters;
.2 reliability of fastening of insulators and protective lead-in casings, inner painting of casings, ready accessibility of aerial lay-out;
.3 possibilities of removing the condensate from protection casings or inner cavities of hollow mast-type aerials;
.4 possibilities of easy and ready connection and disconnection of the leads-in of the transmitting aerials;
.5 reliability of fastening all the aerial and feeder devices;
.6 proper aerial commutation;
.7 insulation resistance which in relation to the ship's hull under normal climatic conditions shall be not less than 10 MOhm, and under excessive humidity — not less than 1 MOhm (for MF/HF aerials the recommended values: 50 MOhm and of 5 MOhm accordingly);
.8 provision of aerial and feeder screening devices, commutators and change-over switches;
.9 watertight leads-in of aerial and feeder devices;
.10 adequate distance of aerial from metal objects;
.11 protection from the mechanical damage likely to occur;
.12 necessary guarding against the possibility of accidental touching of the transmitting aerials;
.13 proper connection of wire aerials to down lead wire aerials.

15.3.6 Installation and connection of radio equipment shall be, as a rule, performed on the completion all the work including welding, insulation and finishing or spaces.

15.3.7 Upon completion of the fitting and installation of the total set of radio equipment, the following shall be checked:
.1 no mechanical damage and indents of the main and auxiliary radio equipment;
.2 clean contact surfaces;
.3 smooth functioning of all the controls;
.4 smooth and efficient operation of drop and sliding frames, removable panels, doors and their reliable securing;
.5 availability of measuring instrument or light indication for continuous monitoring of the ship's mains voltage, compliance of name plates on distribution boards with the kinds of the radio equipment connected thereto;
.6 adequate lighting of the controls of the radio communication facilities, working place of the radio operator;
.7 proper location of emergency lighting and switches, plug sockets, availability of markings designating the places where this equipment is fitted;
.8 proper mounting and easy use of marine clocks;
.9 proper arrangement of the furniture, equipment, spare parts and supplies;
.10 provision of a plate with the call sign of the ship, the ship station identity;
.11 noise level produced by external sources in the places where radio equipment is fitted.

15.3.8 During surveys of the radio equipment on the navigation bridge, its arrangement, convenience of maintenance, protection against harmful effects of water and extremes of temperature, sufficiency of illumination, safe distance to the magnetic compasses shall be checked.

15.3.9 The scope and procedure of surveys of the radio equipment, lighting, heating and ventilation arranged in the accumulator battery room are laid down in Sections 8 and 10.
15.3.10 The procedure of survey of the radio equipment distribution boards shall comply with Section 10.

15.3.11 The distribution board of the radio equipment shall be checked to ascertain the availability of switching and protective equipment, the compliance of their rated values with those of the voltage and current of the connected radio equipment.
15.4 SURVEY DURING MOORING AND SEA TRIALS

15.4.1 After its fitting and adjustment all radio equipment shall be subjected to mooring and sea trials under the programs approved by the Register. Main requirements for the contents and scope of the program are set forth in Section 18.

15.4.2 Mooring trials are carried out with the purpose of ascertaining the proper functioning of the radio equipment in conjunction with other apparatus.

15.4.3 In the course of testing the replacement of changeable components (fuses, signalling and lighting lamps) allowed without any repeating of the previous checks of the radio equipment unless the replacement requires its additional adjustment.

15.4.4 The list of documents to be submitted prior to trials, the procedure of trials, necessary conditions of their performance, and also the procedure of issuing the documents are specified in Section 18.

15.4.5 During mooring trials, the documentation and list of radio equipment shall be checked including:

.1 correspondence of the serial number of a product to that indicated in the RS certificate for a serial product, availability of the RS type approval for the product or another document required by the Administration, which confirms that the radio equipment fitted meets the requirements of Part IV “Radio Equipment” of the Rules for the Equipment and the appropriate IMO resolutions;

.2 availability on board of the valid ship station radio license issued by the Administration with the call-sign and MMSI, the date of license issue and its period of validity specified;

.3 availability on board of the contract for the shore-based maintenance by the firm possessing the RS Recognition Certificate (where the equipment operability is provided by the shore-based maintenance and repairs);

.4 inspection of tools, spare parts and testing equipment;

.5 availability on board of operating instructions for all the radio equipment;

.6 availability of service logs for the GMDSS radio equipment, in absence of these logs, the relevant equipment performance logs;

.7 correspondence of the list of the GMDSS equipment fitted on board to that specified in the RS-approved technical documentation (project) for the installation of such equipment;

.8 availability of reports on programming, mounting, and starting up and adjustment of the GMDSS equipment.

15.4.6 In addition to 15.3.2.1 – 15.3.2.4, examination of spaces where radio equipment is fitted includes checking of:

.1 availability of the clock, plans with procedures for ships' response to DSC distress signal, plates with the ship's name, its call sign, MMSI, the ship earth station identity of the recognized mobile satellite service, the radioteletype number fitted in a conspicuous place in the immediate vicinity of the controls of the communication facilities equipment;

.2 electric lighting of the spaces and radio installation controls;

.3 heating and ventilation.

15.4.7 Checking of the radio equipment functioning and operability includes the following:

.1 operational testing using the integrated control system (in so doing, operating instructions and recommendations of the equipment manufacturers shall be used);

.2 operational testing from the operator's work place;

.3 operational testing from the remote-control panels;

.4 checking of operability when supplied from the main, emergency and reserve sources of power, including the check of the transition signaling, absence of necessity of the manual restart and loss of the information stored in the radio equipment memory at transitions;

.5 checking of operability when supplied from accumulators or galvanic cells integrated in the radio equipment.
15.4.8 Visual examination in checking the radio equipment shall include the following:

1. visual examination of the outside of the shipboard communication facilities, earthing, screening of the equipment cables;
2. check of the condition of controls and alarms on the front panels of apparatus;
3. check of smooth running and precise fixing of controls;
4. internal examination of apparatus, where necessary, (condition of internal wiring, panels, connectors, etc. shall be checked);
5. check of aerials condition and high-frequency feeders. The construction and wiring shall be free of any mechanical damages. When examining whip aerials, attention shall be drawn to the condition of base insulators and painting quality;
6. check of reliability of connection of the precaution guards of the aerial leads-in to the ship's hull;
7. check the sag of the wire aerial (if any), which shall not exceed 6 % of the aerial length. The aerials horizontal separation from ship's metal parts shall be at least 1 m (for the MF/HF band) and 2 m (for the VHF band);
8. check of cleanliness of the surface of accumulator jars and racks for accumulator batteries (no rust is allowed), of the absence of oxides on clamp connections. The contacts of accumulator batteries shall be cleaned up.

15.4.9 Survey of radar transponder.

15.4.9.1 Where the RS-recognized service suppliers performing the tests of radar transponders are available in the area of the RS Branch Office activities, these suppliers shall be enlisted in checking the radar transponders.

15.4.9.2 Procedure for checking the technical condition and operability of radar transponders.

15.4.9.2.1 Checking of the radar transponder documents includes the check of the following:

1. keeping records on the technical condition of radar transponders in a service log or an equipment performance log;
2. the availability of a report-record on checking the radar transponder by the RS-recognized firm;
3. an entry in the product service log or the report-record on the date of the next replacement of the battery by the RS-recognized firm. The accumulators or galvanic cells used as the radar transponder power source shall have the shelf life of at least two years and be replaced when the storage time left is less than 12 months.

15.4.9.2.2 External examination includes the checks of the following:

1. the radar transponder location and the availability of the IMO symbol "Radar transponder", as well as its ready accessibility;
2. the case integrity, painting quality and absence of mechanical damages;
3. availability of protection of the radar transponder against an inadvertent operation;
4. availability and attachment of a buoyant lanyard suitable for use as a tether until the radar transponder is an integral part of a life-saving appliance;
5. availability and condition of a brief operating instruction on the radar transponder body;
6. availability of markings on the containers for storage of radar transponders or on the very transponders, which contain the entries on the date of the next replacement of the battery or on its expiry date;
7. availability of a pole or another means for installing the radar transponder in life-saving appliances at a height of at least 1 m above the sea level.
15.4.9.2.3 The check of the radar transponder operability comprises its check under self-testing conditions and also the check with the use of a 3 cm radar. To check the radar transponder operability, it is necessary:
.1 to force it into a test mode using the operating instruction marked on its outside;
.2 the ability factor of the radar transponder in the test mode: a visual and/or an audible alarm shall be activated depending on the design details of the specific type of the radar transponder. The alarm characteristics shall be defined in the technical description for the product;
.3 to switch off the radar transponder, using the operating instruction.

15.4.9.2.4 To check the radar transponder operability with the use of the ship’s 3 cm radar (the check may be ignored if the document on checking the radar transponder by a competent body possessing the RS Recognition Certificate, is available), it is necessary:
.1 to check the range, the distance between the transponder and the ship’s radar shall be 5 sea miles;
.2 the radar transponder may be checked on board ship if placed within the zone of the directional diagram of a radar aerial (e.g. on a bridge wing). In this case, the transponder shall be held vertically overhead during tests;
.3 to switch on the ship’s radar and radar transponder;
.4 the ability factor of the radar transponder: radar transponders replies as 12 points (arcs) shall be displayed on the radar display unit. If the number of points is not equal to 12, the range scale of the radar display unit shall be changed to the larger one to get all the 12 replies;
.5 to switch off the radar transponder and ship’s radar.

15.4.10 Survey of COSPAS-SARSAT emergency position indicating radio beacon (EPIRB-406).

15.4.10.1 After manufacture, COSPAS-SARSAT EPIRBs shall be subjected to an annual survey and shore-based maintenance (once in five years) in the RS-approved specialized firms.

Note. COSPAS-SARSAT is an international search and rescue system using polar orbitary satellite service for ships and aircraft in distress.

15.4.10.1.1 Procedure for checking the EPIRB-406 technical condition and operability. Checking of documents comprises the check of the following:
.1 availability and the period of validity of the documents on EPIRB-406 registration;
.2 an entry in the product service log or the report-record on the EPIRB last check by the RS-recognized firm. The EPIRB check with the measurement of main parameters shall be carried out by competent bodies, possessing the RS Recognition Certificate, at least once a year; the automatic releasing arrangements of free-floating satellite EPIRBs shall be checked at least once in two years;
.3 an entry in the product service log or the report-record on the date of the next replacement of the battery by the RS-recognized firm. The galvanic cells used as the EPIRB power source shall have the shelf life of at least two years and be replaced when the storage time left is less than 12 months.

15.4.10.1.2 External examination comprises the check of the following:
.1 the EPIRB-406 location and the availability of the IMO symbol “EPIRB”, as well as its ready accessibility;
.2 casing integrity, painting quality and absence of mechanical damages;
.3 availability of the EPIRB-406 protection against an inadvertent operation;
.4 availability and attachment of a buoyant lanyard suitable for use as a tether;
.5 availability and condition of a brief operating instruction on the EPIRB casing;
.6 availability of markings on the containers for EPIRB storage and on the EPIRB outside (on a nameplate), which contain the entries on the date of the next replacement of the battery or on its expiry date;
.7 availability of markings on the date of the next replacement or on the expiry date of the automatic releasing arrangement of free-floating EPIRB-406;
.8 availability of an identity code on the EPIRB-406 casing;
.9 availability of a serial number on the EPIRB-406 casing;
.10 availability of stripes of retroreflecting material on the EPIRB-406 casing.

15.4.10.1.3 The check of EPIRB-406 operability:
.1 check the EPIRB operability under self-testing conditions. Force it into a test mode using the operating instruction;
.2 the ability factor of the EPIRB in the test mode is a visual alarm (flashing of an indicating lamp). The flashing mode depends on the design details of the EPIRB specific type; the alarm characteristics shall be defined in the technical description for the product;
.3 following the above check, the EPIRB fitting on its bracket shall be examined assuring that the beacon is not on the air.

15.4.11 Survey of NAVTEX receiver. Procedure for checking the technical condition and operability of NAVTEX receiver:
.1 switch on the NAVTEX receiver. Self-testing conditions are activated automatically. The ability factor of the NAVTEX receiver shall be determined in compliance with an operating instruction;
.2 if the receiver has an integral loudspeaker, the latter shall be switched on for listening the receiver. The ability factor of the receiver: noise and signals heard in the loudspeaker;
.3 where a printer is available, its operability shall be checked under self-testing conditions. Select test conditions for the printer. The ability factor of the printer: the latter is printing a set of alphabetic characters;
.4 check the operability of a paper-moving device. Its ability factor: paper moving;
.5 check the functioning of a brightness control;
.6 check the list of selected stations. The list shall include at least one of the stations in each of the areas covered by the NAVTEX service messages. (The position of the stations and their operating schedule are given on the website of the Global Integrated Shipping Information System (GISIS) (gisis.imo.org));
.7 check the operability of software. Check the software using an operating instruction. The ability factor: a printout or an indication on a display of the check results;
.8 check the operability of an integral battery. Remove the paper from the printer. Tune the receiver to the reception of all stations. Following the receipt of messages and their retention in the NAVTEX receiver, power shall be turned off for 5 – 10 min. Insert the paper and turn on power. The ability factor: the message stored in the device memory shall be printed with the printer.

Note. International NAVTEX Service is the coordinated broadcast and automatic reception on 518 kHz of maritime safety information by means of narrow-band direct-printing telegraphy using the English language.


15.4.12.1 Checking of documents includes:
.1 check of documents in compliance with 15.4.5.1 (an intrinsically safe enclosure of equipment confirmed by the appropriate certificate of the competent laboratories shall be checked on oil tankers, ore/oil carriers, oil/bulk dry cargo carriers, gas carriers and chemical tankers);
.2 check of location of the two-way VHF radiotelephone apparatus and of the availability of the IMO symbol "Survival craft radio station".
15.4.12.2 External examination comprises the check of the following:
.1 the integrity of casing and gadgets for attaching the apparatus to clothes;
.2 availability of an operating instruction on the casing;
.3 painting condition (the product shall either be painted canary/orange or have a canary/orange marking stripe around it);
.4 availability of the dedicated primary battery for use in distress if the apparatus is intended for use with a power source to be replaced by user. Such primary battery shall have the storage period of at least two years, be designed so as to indicate that it was not used, and be painted or marked according to 15.4.12.2.3. The expiry date of the battery shall be indicated on its outside;
.5 if the apparatus is intended for use with a power source which is not replaced, the former shall be provided with the primary battery. In this case, the two-way VHF radiotelephone apparatus shall be de-signed so as to indicate that the battery was not used;
.6 availability of the expiry date of the primary battery on the outside of the apparatus;
.7 operation of a charging device if rechargeable batteries are used.
15.4.12.3 In order to check operability, it is necessary to:
.1 switch on the apparatus. The ability factor: light indication of switching-on;
.2 check the operability of a volume control. The ability factor: change of a loudness level;
.3 check the operability of a squelch control. The ability factor: sudden change of a noise level shall be heard with the change of a squelching level;
.4 check the operability of a channel selection switch, and the opportunity of quick selecting 16 channel. The ability factor: when switched on, the apparatus shall automatically tune in the 16 channel and the switching over of the alive apparatus to the 16th channel shall be possible with a single action pressing button "16";
.5 check the operability of the mode of the power level reduction (down to 1 W and below), and of the indication mode;
.6 check the operability of the VHF apparatus in the checking communication mode.
The apparatus shall ensure the operation on the 16 channel and, at least, on one additional channel. Switch on two radio stations on the 16 channel and establish communication within a ship in a simplex mode; select another channel on the radio stations to identify the channels inoperative in the receive and transmission modes. The power level reduction mode shall be used in the checking communication.

15.4.13 Survey of INMARSAT ship earth station. Procedure for checking the technical condition and operability of INMARSAT ship earth station.
15.4.13.1 Examine the station externally according to 15.4.8.


15.4.13.2 Check of the INMARSAT ship earth station (Standard C) operability includes check of the following:
.1 the station operability and the authenticity of the information received in the loopback mode of a communication line in transmitting the checking message which shall be prepared as follows: compose the message in a text field using an operating instruction; enter the address of a message recipient taking its own station as the called one and using the identity of the ship being surveyed, and enter it in an address book. Select the transmission mode "Routine" and transmit the message. The ability factor: the reception of the message transmitted in about 5 min. Check the authenticity of the information received by comparing the transmitted and received messages;
the station operability and the authenticity of the information received in the enhanced group calling (EGC) mode, which are checked by scanning the messages in an electronic log book according to the operating instruction. The next scheduled time of the NAVAREA messages transmission shall be selected (the schedule of transmissions is given, for example, in Inmarsat International SafetyNET Handbook; Admiralty List of Radio Signals, vol. 5; on the GISIS website (gisis.imo.org)). Program the EGC receiver in accordance with the operating instruction. The ability factor: the reception of NAVAREA messages. Scan the safety navigation messages received, which are available in the ezine, using the operating instruction;

.3 opportunity of transmitting a distress alert from the location generally used for conning, as well as from any other location intended for transmitting the distress alert;

.4 absence of necessity to manually repeatedly put the equipment in an operating mode and to retain the messages received and stored in the station memory at power supply broken off up to 60 s;

.5 the station operability with a reserve power source. In this case, a main (emergency) power source shall be switched off.

15.4.14 Survey of VHF radio installation. Procedure for checking the technical condition and operability of the VHF radio installation.

15.4.14.1 Examine the installation externally according to 15.4.8.

15.4.14.2 Check of the VHF radio installation operability:

.1 switch on the radio installation;

.2 check the correspondence of the DSC number entered with the number specified in a ship station radio license;

.3 check the input of position data in an automatic and a manual mode. The ability factor: the ship's latest position entered and the time of that positioning shall be displayed.

.4 check the time setting;

.5 check the set of channels and the urgent call mode on the 16/9 channels;

.6 check the scanning of channels;

.7 check the mode of transmitter power reducing;

.8 check the operation of a squelcher;

.9 check the change of display illumination;

.10 check the operability of a DSC encoder facility and DSC watchkeeping facility in the feedback loop "DSC controller – transceiver – DSC equipment – DSC controller" under self-testing conditions using an operating instruction;

.11 check the authenticity of the information received by controlling the VHF radio installation operability, while on air in the DSC mode, using the MENU in the "Test call" mode by means of a check session with the coast radio station from the list of the stations stored in the DSC controller or from the list of the stations in ITU List of Coast Stations and Special Service Stations, Admiralty List of Radio Signals.

15.4.15 Survey of MF/HF radio installation. Procedure for checking the technical condition and operability of MF/HF radio installation.

15.4.15.1 Examine the installation externally according to 15.4.8.

15.4.15.2 Check of radio installation operability:

.1 switch on the radio installation. When switched on, the radio station shall go to a receive mode;

.2 check the adjustment of the display illumination;

.3 check the operability of the following transmitter controls: the aerial attenuator switching-on, mode of emission/change of power level (in this case, the power level selected is controlled by the readings of a power level indicator), radio exchange mode setting in distress (on the frequency 2182 kHz). Check the aerial current by a current indicator (checking shall be carried out on the frequency 2182 kHz or the frequency specified in an operating instruction);
.4 carry out the internal examination of the DSC facility off the air using an operating instruction. The operability of the principal blocks of the radio installation shall be checked in this mode. The ability factor indication of the examination results on the display;

.5 check the range and the authenticity of the information received by means of a test call to the coast radio station (if the rules of the berth permit the use of MF/HF transmissions). In order to check the range and the authenticity of the information received in establishing communication in the HF band, select a coast radio station, located at a distance of 1000 miles and more from the ship;

.6 check the radio installation operability, range and the authenticity of the information received in the DSC, radiotelephony and narrow-band direct printing (for HF radio installation only) modes. In order to check the MF radio installation range and the authenticity of the information received, select a coast radio station, located at a distance of up to 100 sea miles from the ship, and originate a call on the DSC frequency in the MF band (2187,5 kHz). The information on the schedule of radio stations operation may be found, for example, in Admiralty List of Radio Signals. vol. 5, Sea Area A2;

.7 check the MF/HF radio installation operability from the reserve power source. Switch off the main (emergency) power source.

15.4.15.3 Check of radioteleprinter HF receiver operability for bringing in the information on navigational safety (if any being part of the MF/HF radio installation):

.1 check the operability, range and the authenticity of the information received of the radioteleprinter HF receiver for bringing in the information on navigation safely;

.2 check the operability of the receiver, signal processing unit, printing device and automatic frequency tuning device using a self-test system, if any, and an operating instruction;

.3 check the integrity of information on servicing areas and the types of messages stored in equipment when supply voltage is lost for a time period of 6 h;

.4 check the operability of the navigational information HF receiver during tuning in the maritime safety information with the use of an operating instruction, in accordance with the schedule of radio stations operation. The information on the schedule of radio stations operation of the system for transmitting the maritime safely information may be found, for example, on the GISIS website (gisis.imo.org). The broadcasts may be brought in with the ship's radioteleprinter HF receiver tuned to the system frequencies 4210; 6314; 8416,5; 12579; 16806,5; 19680,5; 22376 and 26100 kHz in accordance with the schedule of radio stations operation.

15.4.16 Survey of charging device and reserve source of supply. Procedure for checking the technical condition and operability of the charging device and reserve source of supply.

15.4.16.1 Examine externally according to 15.4.8.

15.4.16.2 Where accumulator batteries are maintenance-free, the date of their replacement shall be checked.

15.4.16.2.1 The equipment shall be located so that ready access for its examination and maintenance may be ensured, the equipment components (wiring and cabling inclusive) shall be arranged and laid so as to prevent their accidental damage.

15.4.16.2.2 The cases of all equipment shall have earthing terminals.

15.4.16.2.3 The information on a firm (manufacturer), serial number, the type of equipment shall be clearly indicated on the outside of equipment blocks.

15.4.16.2.4 To be checked are the following:

.1 reliability of accumulator batteries securing;

.2 cabling condition;

.3 condition of ventilation, heating and lighting in an accumulator battery room;

.4 availability of an operating instruction for accumulator batteries;

.5 availability of a warning on the door of the accumulator battery room;

.6 density and level of electrolyte in accumulator battery jars (cells);
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.7 availability of the sufficient quantity of electrolyte and distilled water, of an areometer, a measuring tube, an accumulator tester, other inventory needed for maintaining the accumulators; documents that the net capacity of accumulator batteries was checked in port within the last 12 months, using the high discharge method, by the competent body possessing the RS Recognition Certificate.

15.4.16.2.5 Check of operability:

.1 switch off the main (emergency) source of power supply;
.2 hook up the reserve source of power supply;
.3 check the operability of an audible and visual alarm system from the general conning position on changing over to the reserve source of power supply. Switch off the main source of power supply from the GMDSS radio equipment console. The ability factor: activation of the audible and visual alarm on changing over to the reserve source of power supply. Switch off the audible alarm and check that the visual alarm is still on (the visual alarm shall fade out only when the main source of power supply is hooked up);
.4 check that all the main equipment can be switched on and is in proper condition;
.5 check the accumulator battery voltage by its measurement in compliance with the operating instruction for this type of batteries;
.6 check the functioning of the charging device. Switch on the battery for discharging via an artificial load or test it using an accumulator tester, and switch on the charging device in an automatic mode after discharging. The factor of a state of operability: the charging device shall automatically be switched on for charging and the current during that period shall not change (but may change when the charging device is functioning in a buffer mode).

15.4.17 Survey of the ship security alert system. Procedure for checking the technical condition and operability of the ship security alert system.

15.4.17.1 Check the ship security alert system for completeness (in particular, the system compliance with the items specified in the RS Type Approval Certificate, which copy shall be provided with the system at the ship's delivery).

15.4.17.2 Check the correctness of mounting in accordance with the RS-approved technical design.

15.4.17.3 Check the correctness of programming the addressees of a report which shall be carried out and submitted to the RS surveyor by the specialist of the firm fitting the system in question.

If a shipowner fails to ensure the presence of the specialist, who mounted and programmed the equipment, during surveying the system, the RS attending surveyor shall be provided with a report compiled and signed by that specialist which shall contain the results of works on mounting the equipment, as well as the report addresses, stated by the Administration, programmed by that specialist on the completion of mounting.

15.4.17.4 Check the functioning of the ship security alert system by sending a test message. In this case, using any accessible communication channel, it shall be made sure that the test message has been delivered to the programmed address.

15.4.18 Survey during sea trials.

15.4.18.1 Sea trials are carried out to finally check the operability of radio equipment in the real-life environment.

15.4.18.2 In addition to the required in 15.4.9 – 15.4.17, the check during sea trials includes check of the following:

.1 opportunity of establishing communication with operating radio stations in all modes;
.2 interaction of navigational devices and arrangements with radio equipment;
.3 transition to doubling equipment if the main one fails;
.4 the audible and visual alarm of radio equipment.
15.4.18.3 The checks specified in all paras of this Section shall be applicable to a ship.

15.4.18.4 On ships of a series, the single types of radio equipment tests under running conditions may be replaced (if agreed with the RS Branch Office in charge of the technical supervision during the ship's construction) by the RS-approved simulation tests during the mooring trials (refer to Section 18).

15.4.18.5 All the equipment deficiencies revealed during the mooring and sea trials shall be eliminated prior to issuing the Register ship's documents.

15.4.19 Completion of ship's construction.

15.4.19.1 Following the ship's construction, the technical and operational documents shall be updated and the relevant service logs and certificates shall be completed.

15.4.19.2 Where necessary, spare parts and supplies shall be replenished up to the maximum recommended by the firm (manufacturer).
15.5 SURVEY OF MODU/FPU/FOP RADIO EQUIPMENT

15.5.1 During survey of the proper wiring of radio equipment, in addition to 15.3, the following shall be checked:

.1 proper arrangement of the MODU/FOP radio equipment according to Section 3, Part XVIII "Radio Equipment" of the MODU/FOP Rules, proper arrangement of the FPU radio equipment according to Section 3, Part III "Radio Equipment" of the Rules for the Equipment of Floating Offshore Oil-and-Gas Product Units;

.2 arrangement of the MODU/FOP transmitting and receiving antennas according to Section 4, Part XVIII "Radio Equipment" of the MODU/FOP Rules, arrangement of the FPU transmitting and receiving antennas according to Section 4, Part III "Radio Equipment" of the Rules for the Equipment of Floating Offshore Oil-and-Gas Product Units.
16 NAVIGATIONAL EQUIPMENT

16.1 GENERAL

16.1.1 The provisions of the present Section apply in the course of technical supervision of the navigational equipment of ships listed in the RS Nomenclature.

16.1.2 The Section contains the requirements for technical supervision of the navigational equipment during ship construction.


16.1.4 Technical documentation.

16.1.4.1 Installation and testing of navigational equipment on board the ship shall be performed under the Register technical supervision according to the RS-approved technical documentation.

16.1.5 Technical supervision of the Register.

16.1.5.1 Surveys during installation and testing of navigational equipment shall be performed according to the examination and testing plan developed by the shipyard according to 15.2.1, taking into account 15.3 and 15.4.

16.1.6 Tests and checks specified in this Section are based on an assumption that the navigational equipment have been tested at the firm (manufacturer) in compliance with the requirements of Section 16, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

In case some tests were not conducted at the firm (manufacturer) and it is confirmed by an entry in the RS certificate, then these tests shall be conducted.

Additional checks and tests may be assigned by the surveyor upon results of examination of the navigational equipment in substantiated cases.
16.2 SURVEY PLANNING

16.2.1 Prior to commencement of survey of the navigational equipment of the ship under construction, the RS Branch Office shall agree the examination and testing plan for navigational equipment developed by the shipbuilder taking into account the RS Nomenclature, as well as 16.3 and 16.4. The shipbuilder shall be informed about that at a kick off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

16.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

16.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

16.2.4 Quality standards for installation and testing of the navigational equipment shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

16.2.5 Any changes to the kick-off meeting records shall be agreed and documented.
16.3 SURVEY DURING INSTALLATION AND CABLING

16.3.1 Installation of the navigational equipment on board shall be carried out in compliance with the approved technical design documentation and the equipment manufacturer technical documentation. In this case the following items shall be checked:

.1 documents confirming the Register supervision at the firm (manufacturer) (prior to the installation of the navigational equipment);
.2 completeness, arrangement and securing of devices;
.3 easy access to devices;
.4 protection of the equipment from intrusion of any foreign objects inside and from any occasional mechanical damage;
.5 magnetic compass "safe distance" (for devices installed in the wheelhouse, refer to Appendices 4 and 5 to Part V "Navigational Equipment" of the Rules for the Equipment);
.6 quality of internal and external installation;
.7 quality of protection earthing of apparatus cases and cable net laying in accordance with Section 10;
.8 insulation resistance;
.9 compliance with the special requirements specified by the equipment design as well as with the requirements laid down in the RS-approved documentation;
.10 adjustment of the apparatus.
16.4 SURVEY DURING MOORING AND SEA TRIALS

16.4.1 After the completion of installation and adjustment work, all the navigational devices and appliances shall be made subject to mooring and sea trials under the programs approved by the Register and witnessed by a surveyor. The power supply to the navigational equipment shall be provided from the ship's mains.

16.4.2 Mooring trials shall be carried out with the purpose of ascertaining of proper functioning of the navigational equipment in cooperative operation with interfaced equipment. In the course of mooring trials, the following shall be carried out:

.1 check of serviceability of the equipment devices and systems;
.2 test of operation of the equipment operation control elements, alarm and interlocks systems;
.3 tests of equipment functioning in the rated regime;
.4 check of electric protection of apparatus in supply circuits from the ship's mains (if any) in accordance with the requirements of Section 10 "Electrical Equipment";
.5 check of serviceability after every three breaks in the power supply from the ship's mains during 60 s.

No breaking of software and no loss of essential data kept in the relevant data memory of the system shall occur;

.6 check of electromagnetic compatibility of all the installed equipment in simultaneous operation. The most critical modes of the work of the equipment (the highest power consumed, interference; highest sensitivity, etc.) shall be chosen.

16.4.3 In addition to the above stated in 16.4.2, during mooring trials the following items shall be checked.

16.4.3.1 Magnetic compasses and transmitting heading devices.

16.4.3.1.1 At surveys during mooring trials of magnetic compasses and transmitting heading devices, the following shall be checked:

.1 compass card is capable of free motioning in the conditions of inclination. The inclination of compass bowl at which the compass card retains horizontal position is not less than 10°, the free inclination of compass bowl with gimbal suspension is not less than 45°;
.2 card stagnation;
.3 serviceability of electric lighting from the main, emergency and self-contained (if any) sources of power;
.4 transmission of readings from the main unit to repeaters (if any). The divergence shall not exceed ±0,5°;
.5 error signals for mismatching in electric remote transmission system of dial readings (if any);
.6 two-way voice communication between the places where the standard compass is installed and the ship control station;
.7 operation of the device for the magnetic compass deviation compensation;
.8 operation in conjunction with other ship's devices (if any);
.9 independent serviceability of the magnetic compass irrelevant of any source of power;
.10 adjustment of the lightening for compass readings.

16.4.3.2 Receivers for a global navigation satellite systems or a terrestrial radionavigation systems.

16.4.3.2.1 At surveys during mooring trials of receivers for terrestrial radionavigation systems, the following shall be checked:

.1 adjustment and operation in different modes;
.2 operation of navigating, monitoring and signalling controls;
.3 arrangement of aerials, non-availability of interference;
.4 electrical protection of power supplying circuits;
.5 insulation appliances and aerials earthing;
.6 interface with other radio-and-navigational equipment;
.7 operation as per direct designation for determination of the ship's position by means of terrestrial radio navigation stations.

When signals from the terrestrial radio navigation stations in the area of mooring and sea trials are not available, check of radio navigation receivers shall be carried out by the ship crew members during the ship's operation with the subsequent submission of the results received.

16.4.3.2.2 At surveys during mooring trials of receivers for a global navigation satellite systems, the following shall be checked:

.1 such arrangement of radio navigation receivers aerials at which the reliable receipt of signals of the satellite constellation from any direction is provided;
.2 serviceability of aerial blocks after water influence;
.3 setting and operation in the standard and differential (if any) mode;
.4 time of acquiring signals and acquiring coordinates;
.5 accuracy of acquiring position in the static GPS mode and, for the combined receiver of the orbit global navigation satellite systems GPS and GLONASS: in the standard mode; in the differential mode;
.6 warning of loss of position or mode indication;
.7 frequency of position data update;
.8 operation in conjunction with other radio and navigational equipment.

Note. Where no differential updating signals from controlling stations of marine differential subsystem are available in the area of mooring and sea trials, the check of the differential mode of receivers shall be carried out during the ship's operation with the subsequent submission of the results received.

16.4.3.3 Electronic plotting aids (EPA), automatic tracking aids (ATA) or automatic radar plotting aids (ARPA).

16.4.3.3.1 At surveys during mooring trials of radars and radar plotting aids (EPA, ATA or ARPA), the following shall be checked:

.1 proper installation of the radar display unit and the antenna onboard;
.2 serviceability of the radar equipment;
.3 the radar shall be ready for operation within 4 min of being switched on (the "stand-by" position is provided after which the radar is set in the "switched-on" position within 15 s);
.4 scan centering and fixed range marks, coincidence of variable range marker and fixed marks;
.5 accuracy of target bearing with the help of an electronic bearing line;
.6 synchronal and cophasal rotation of the antenna and scan on the display screen, scan rate;
.7 operation of devices (if any) for anticlutter rain and anticlutter sea;
.8 possibility of orientation of the display relative to the centerline of the ship and the true meridian;
.9 functioning of the electronic plotting aids (EPA), auto tracking aids (ATA) or automatic radar plotting aids (ARPA);
.10 operation in conjunction with other navigational equipment.

16.4.3.4 Gyrocompasses.

16.4.3.4.1 At surveys during mooring trials of gyrocompasses, the following shall be checked:

.1 proper installation of the master compass and repeaters;
.2 settle time: normal and accelerated;
.3 steady state in alignment in the meridian and steady error of the master compass;
.4 error from one run-up to another shall not exceed ±1°;
.5 divergence in readings between the master and repeaters (shall not exceed 0,5°);
.6 operation of the course recorder;
7 main workstation console lighting control device ensuring the indication of readings of the master compass and repeaters;
8 operation in conjunction with other navigational equipment;
9 availability of a repeater at the emergency steering control station.

16.4.3.5 Echo sounders.
16.4.3.5.1 At surveys of echo sounders during mooring trials, the following shall be checked:
1 starting period of the echo sounder;
2 receiving and emitting surfaces with the help of a built-in control device (if any);
3 proper measuring the depth of water under the ship when in port (if allowed by the minimum depth under the vibrator);
4 coordination of depth information in the graphical form and the digital form;
5 actuation of alarm signals on approach to the dangerous and pre-set depths;
6 proper current and previously recorded information;
7 operation in conjunction with other navigational devices.

16.4.3.6 Relative and absolute logs.
16.4.3.6.1 At surveys of logs during mooring trials, the following shall be checked:
1 internal resistance of insulation of hydro-acoustic antenna to direct current (for absolute and relative hydroacoustic logs);
2 starting period of the log;
3 receiving and emitting channel with the help of a built-in control device (if any);
4 initial speed sensitivity of the log (with the help of slackening or tightening the mooring lines at the berth or when the ship is adrift at the anchorage);
5 coordination in readings of speed and distance repeaters and the log main unit;
6 watertight outboard bottom equipment penetrating the hull and convenient access for the replace-ment when the ship is afloat (where applicable);
7 convenience of input of permanent, linear and non-linear log corrections into the system (where applicable);
8 operation in conjunction with the ship equipment.

16.4.3.7 Shipborne automatic identification system (AIS).
16.4.3.7.1 At surveys of the shipborne automatic identification system (AIS) during mooring trials, the following shall be checked:
1 proper installation and mounting of the apparatus (refer to Appendix 7 to Part V "Nautical Equipment" of the Rules for the Equipment), including the power supply unit and the minimum display (if they are separate from the main unit);
2 proper installation and fastening of VHF antenna and antenna of GNSS receiver;
3 operation in conjunction with the navigation information sensors;
4 operation in conjunction with the equipment displaying graphical information;
5 operation in conjunction with the shipborne GNSS receiver;
6 operation in conjunction with the long range communication equipment (if any);
7 automatic switch on of the apparatus with the switch on of the ship's power supply and the 2 min starting period upon the switch on (this requirement is not applicable to the starting period for operating regime of the built-in GNSS receiver);
8 manual switch off of the apparatus when the ship is under repairs in port;
9 provision of processing of the data from the radionavigation system with the resolution within 0.0001 min in latitude and longitude WGS-84 coordinates;
10 automatic transfer to the built-in GNSS receiver in case of failure of the ship's (external) source of defining the position, and also appropriate indication from built-in means for the control of serviceability;
11 provision of alarm actuation and an indication of any alteration in the status of dynamic information sensors;
12 provision of displaying the necessary information on the minimum display.
16.4.3.8 Heading control system and ship's track control system.

16.4.3.8.1 At surveys of the heading control system and the ship's track control system during mooring trials, the following shall be checked:
   .1 proper installation of the system;
   .2 change-over of the modes of controls;
   .3 coordination of course and rudder indications;
   .4 rudder angle limitation;
   .5 signalling on the preset modes of control and actuation of alarms in case of failures of information sensors;
   .6 kind and amount of information displayed on the system control panel permanently and when required.

16.4.3.8.2 At surveys of the ship's track control system during mooring trials, the following shall be additionally checked:
   .1 monitoring of the ship's position received from the main radio navigation system with the data received from another independent system;
   .2 alarm actuation provided about approach to the pre-set point of the course change at wheel-over, at the moment of manoeuvre starting, and also when no confirmation of the alarm signal by the watch navigator is given;
   .3 alarm actuation in case of failure of the track control system as a whole and switch-over to another heading control mode.

16.4.3.9 Rate of turn indicators.

16.4.3.9.1 At surveys of the rate of turn indicators during mooring trials, the following shall be checked:
   .1 starting period of the equipment for operation;
   .2 check of modes of controls;
   .3 capability of operating independently of gyro-compass and radar;
   .4 operation with both the automatic and manual ship steering;
   .5 interface with other navigational equipment.

16.4.3.10 Sound reception system.

16.4.3.10.1 At surveys of the sound reception system during mooring trials, the following shall be checked:
   .1 proper installation of the receiving microphones, system loudspeakers, system display;
   .2 adjustment of audibility of incoming sound signals;
   .3 direction indicating period for an incoming sound (not more than 3 s).

16.4.3.11 Voyage data recorder (VDR).

16.4.3.11.1 At surveys of VDR during mooring trials, the following shall be checked:
   .1 proper installation and mounting of the VDR equipment and protective capsule with the final recording medium (the document confirming installation and check of the equipment by the organization recognized by the manufacturer shall be checked);
   .2 interfacing with the sensors of navigation and other operative information;
   .3 automatic switch-on of VDR when provided from the ship's power supply and automatic change-over to the emergency power supply in case of failure of the main power supply;
   .4 operation of VDR from its own accumulator batteries and continuing to record the bridge audio for a period of 2 h with its following automatic switch-off;
   .5 manual switch-off of VDR when the ship is under repairs in port;
   .6 starting period of VDR before the ship sails;
   .7 possibility of withdrawal the recorded information with no breaking up the protective capsule.
16.4.3.12 Electronic chart display and information system (ECDIS).

16.4.3.12.1 At surveys of the electronic chart display and information system (ECDIS) during mooring trials, the following shall be checked:

.1 proper connection of the equipment to the main and emergency power supply sources;
.2 interface of the equipment with GNSS receiver, gyrocompass, log, AIS, and, where appropriate, with the radar and ARPA;
.3 automatic checks of the equipment serviceability specified by the manufacturer and contained in the technical documentation;
.4 alarm signals of ECDIS or position determination system malfunction;
.5 correct coordinates received from the GNSS receiver,
.6 maintained serviceability in case of any interruption of the power supply for 45 s;
.7 accepting updates and preparing lists of updates. Capability of accepting updates to be entered manually.

16.4.3.13 Integrated navigation system (INS).

16.4.3.13.1 At surveys of the integrated navigation systems during mooring trials, the following shall be checked:

.1 arrangement of the system devices on the navigation bridge ensuring the monitoring of the navigational environment;
.2 operation in conjunction with the sensors of navigation information;
.3 influence of the system on the performance of the interfaced sensors of information;
.4 any impact of failures of some of the data processing units on the system serviceability;
.5 any impact of failures of some of the interfaced devices and appliances on the system operation;
.6 possibility of manual input of the data;
.7 alarm signals of failures of interfaced devices and systems, as well as in case of invalid data.

16.4.3.14 Combined ship control desks.

16.4.3.14.1 At surveys of the combined ship control desks during mooring trials, the following shall be checked:

.1 possibility for the operator to perform his duties both in the seating and in standing positions;
.2 accessibility to the internal structure and to protective means of power supply sources;
.3 symbols and inscriptions showing the purpose and the direction of the control devices;
.4 provision of continuous information or on call of the operator;
.5 audible and visual alarm indicating any failure of devices, machinery and appliances.

16.4.3.15 Unified timing system.

16.4.3.15.1 At surveys of the unified timing system during the mooring trials, the following shall be checked:

.1 proper installation of the system devices;
.2 main clock run shall not exceed 0.5 s during twenty-four-hour operation;
.3 variations of the main clock run during twenty-four-hour operation (not more than 0.1 s);
.4 corrections of the system run;
.5 transmission of current time to the controllable secondary clock;
.6 emergency (reserve) power supply to the system.

16.4.3.16 Bridge navigational watch alarm system (BNWAS).

16.4.3.16.1 At surveys of the BNWAS during mooring trials the following shall be checked:

.1 location of all devices for alarm acknowledgement and system reset to the initial state (means of activating the reset function) – easily accessible from the conning position, the workstation for navigating and manoeuvring, the workstation for monitoring and the bridge wings;
.2 location of means of a second stage audible alarm (the master and officer's cabins), the possibility of choosing by the officer of the watch (OW) the location for a second stage alarm actuation (in the back-up officer's location) and no possibility is available for cancellation of any audible alarm in the master's cabin from the bridge;

.3 location of means of a third stage audible alarm (in all the possible locations of crew members normally capable of taking corrective actions to steer the ship);

.4 visibility of flashing indication (first stage visual alarm) from any workstations on the bridge; variability of brilliance (although not to extinction);

.5 difference of audible alarm characteristic tone/ modulation from other signals (general alarm system, fire detection and fire alarm systems, etc.), the adequacy of the volume (on the bridge (first stage), in the officers' cabins (second stage), in all the spaces of officers' location (third stage));

.6 for ships which come under the provisions of SOLAS-74 (as amended): when activated in automatic mode, the BNWAS is always active (no matter whether the ship's heading or track control system is activated or not);

.7 whether the means of selecting the operational mode (on/off/auto) and the duration of the dormant period are securely protected against an unauthorized access (key, password);

.8 whether the BNWAS is powered from a battery (using the reserve source of electrical power of the GMDSS radio equipment is not allowed);

.9 if VDR is available: connection of the BNWAS to VDR;

.10 if the following equipment is forming part of the BNWAS: the system operability with additional reset facilities (motion sensor, etc.), other equipment on the bridge (radars, ECDIS, INS, etc.) capable of registering the OOW activity and activating a reset signal.

16.4.4 Sea trials shall be carried out with the purpose of final check of serviceability in the real operation conditions. At sea trials, the following items set forth below shall be checked in the scope laid down in 16.4.4.1 – 16.4.4.16.

16.4.4.1 Magnetic compasses and transmitting heading devices.

16.4.4.1.1 At surveys of magnetic compasses and transmitting heading devices during sea trials, the following shall be checked:

.1 compensation of deviation (availability of the Table with values of residual deviation);

.2 accuracy of indicating of the ship's course on permanent courses and circulation with corrections on cardinal and intercardinal points (alteration of a correction shall not exceed 1°);

.3 error of electric remote transmission of magnetic course readings to repeater devices (if any);

.4 proper electric remote transmission of the ship's true course readings to other shipboard devices;

.5 interchangeability of master and reserve compasses.

16.4.4.2 Satellite radio navigation system receivers.

16.4.4.2.1 At surveys of satellite radio navigation system receivers during sea trials, the following shall be checked:

.1 generating of new output data and synchronization of the GPS receiver in the dynamic regime, and in case of combined radio navigation receivers in the GPS and GLONASS systems with the ship's various speeds: in standard regime; in differential regime;

.2 warning on failures and indication status;

.3 influence of aerial position inclination on accuracy data in the conditions of rolling and pitching motions;

.4 serviceability of equipment when communication facilities, navigational and electrical devices applied onboard are in operation;

.5 providing operation of navigational equipment using output data of the satellite radio navigation system receiver.

16.4.4.3 Electronic plotting aids (EPA), automatic tracking aids (ATA) or automatic radar plotting aids (ARPA).
16.4.4.3.1 At surveys of radar and radar plotting aids (EPA, ATA, ARPA) during sea trials, the following shall be checked:
.1 serviceability of the radar and radar plotting aids in various regimes of the ship's motion (alteration of the ship's speed and course);
.2 errors of direction measurements with the help of an electronic bearing line;
.3 errors of range measurements with the help of an electronic variable range marker;
.4 matching variable range marker with fixed range rings;
.5 simultaneous operation of the radar and radio communication facilities;
.6 operation in the modes of a relative motion display and true motion display, and operation of automatic radar plotting aids simulating the effect on all tracked targets of an own ship manoeuvre (for ARPA);
.7 radar display of graphical and letter-digital data (about parameters of target motion and approach) of radar plotting aids (EPA, ATA or ARPA);
.8 operation of the radar in conjunction with the radio beacons and transponders;
.9 possibility of displaying information of ECDIS and ATS (where appropriate);
.10 continuous operation of the radar for 24 h (with switched-on high voltage for at least 12 h);
.11 range of detection of real targets on the sea surface;
.12 minimum range of detection ("blind area");
.13 transmission of data to the voyage data recorder (if any).
After the completion of the trials at the place where the radar station is installed the diagram containing dead sectors of vision and blind area of the radar shall be posted.

16.4.4.4 Gyrocompasses.
16.4.4.4.1 At surveys of gyrocompasses during sea trials, the following shall be checked:
.1 settle time in the conditions of rolling and pitching;
.2 accuracy of course indication at cardinal and intercardinal points, and circulation.
Alteration of a correction shall not exceed 1°;
.3 gyrocompass readings error in remote transfer to gyrocompass repeaters;
.4 availability of alarm on failures and recording thereof;
.5 transmission of the course data to other devices and systems.

16.4.4.5 Echo sounders.
16.4.4.5.1 At surveys of echo sounders during sea trials, the following shall be checked:
.1 steady operation, depth measuring with the help of the depth indicator and depth recorder at the ship's various cruising speeds. Checking for no interference. At the ship's full speed the depth recording shall be performed for at least every 10 min in each regime;
.2 steady echo sounder operation under rolling and pitching motion conditions (with the weather permitting);
.3 echo sounder operation when the seabed is of a sloping character;
.4 echo sounder operation when the ship is loaded or in ballast (if possible);
.5 possibility of echo sounder measuring and recording of minimum and maximum depths (if possible);
.6 alarm signal actuation on the ship's approach to the dangerous/pre-set depth;
.7 error of echo sounder measuring of shallow depths (using hand lot);
.8 echo sounder operation at the ship's circulation;
.9 echo sounder operation at the ship's slow speed astern;
.10 unambiguous indication of the data received from several transducers installed on board ship.

16.4.4.6 Relative and absolute logs.
16.4.4.6.1 At surveys of relative and absolute logs during sea trials, the following shall be checked:
.1 log errors of indicating speed and distance run in ship's various motion regimes (on the measuring line or by means of highly precise radio navigation systems);
log operation in rolling and pitching motion conditions (with the weather permitting);
minimum and maximum depths of the log operation (where appropriate);
automatic and forced selection and indication modes of speed through the water and speed over the ground measuring;
influence of the ship's static inclination and trim upon accuracy of hydro-acoustic log characteristics (where appropriate);
alarm signal actuation on log operation status under conditions of water aeration (where appropriate and the weather permitting);
log operation at the ship's circulation, speed astern, sway displacement under wind and current force, bow and stern thruster, pneumatic wash (used on icebreakers);
log easy taring (calibration), drawing up the table on residual errors (log corrections), additional service functions;
safe protrusion of log sensor from the bottom and in flush position to the bottom at the maximum speed, as well as its full replacement at the ship's maximum draught (with a sluice valve available for the log sensor).
Shipborne automatic identification system (AIS).

16.4.4.7 At surveys of the shipborne identification system (AIS) during sea trials, the following shall be checked:
apparatus is operational and ready for transfer of pre-planned position data in the independent regime not later than 2 min after switching on (this requirement is not applicable to GNSS receiver);
dynamic information transfer rate dependent on speed alteration;
dynamic information transfer rate dependent on course alteration;
operation in conjunction with the gyrocompass;
operation in conjunction with the log.

16.4.4.8 Heading control systems and the ship's track control systems.

16.4.4.8.1 At surveys of the heading control systems and the ship's track control systems during sea trials, the following shall be checked:
efficient operation of the systems using all kinds of controls during the whole of the sea trials;
accuracy of keeping the ship on a preset heading and/or track with recording of amplitudes of yaw at various heading angles to a seaway for at least 1 h, and after circulation, on each control channel at the ship's speed at least 6 knots and at sea force not more than 3 (the accuracy of keeping the ship shall be not less than 1°);
limitation of angles and number of the rudder activation in a seaway (the number of rudder activations shall not be more than those with the manual steering);
manual and automatic (if any) adjustment of the system in various navigating environment conditions, and also alteration of the ship's speed and loading;
monitoring of the ship's positions following along sequence of waypoints using the data of the independent positioning system;
ship's preset heading change in the automatic mode and change-over to a new preset track with the track steering;
ship's preset heading manual change from the master station and from remote stations (with and without change-over to manual steering);
alarm signals and data indication on the system control panel;
reliable change-over within 3 s from automatic heading control to track control and also to manual steering and vice-versa at any position of the rudder by a single easily accessible control.
16.4.4.9 Rate of turn indicators.
16.4.4.9.1 At surveys of the rate of turn indicators during sea trials, the following shall be checked:
   .1 operation starting period (not more than 4 min after switching-on);
   .2 clear indication of the direction and accuracy of angular speed at the ship's speed up to 10 knots;
   .3 possibility of application of the rate of turn both with automatic and manual ship steering;
   .4 efficiency of operation of the damping system under conditions of rolling and pitching motions.
16.4.4.10 Sound reception system.
16.4.4.10.1 At surveys of the sound reception system during sea trials, the following shall be checked:
   .1 efficient operation of the system in various weather conditions, the ship's speed and direction of incoming sound signals;
   .2 audibility of incoming sound signals inside the wheelhouse, the possibility of adjustment;
   .3 proper indication of the direction of incoming sound signals by means of the visual bearing of the sound source.
16.4.4.11 Voyage data recorder (VDR).
16.4.4.11.1 At surveys of VDR during sea trials, the following shall be checked:
   .1 automatic switch-on when supplied from the ship's power supply source and manual switch-off during the ship's long staying in port;
   .2 continuous recording and storage of information for 12 h;
   .3 recording of the bridge audio for a period of 2 h with no power supply from the ship's system and following automatic switch-off;
   .4 steady and reliable recorder operation under various navigational conditions of the ship;
   .5 actuation of alarm signals in case of an unauthorized access to recorder operation, and when a non-correctable error is detected during recording;
   .6 withdrawal of a copy of the recorded information with no breaking up of the protective capsule and no damage done to the records;
   .7 verification of identity and accuracy of the recorded data by means of comparison with the radar display screen photos and of generalized display of the navigational data.
16.4.4.12 Electronic chart display and information system (ECDIS).
16.4.4.12.1 At surveys of ECDIS during sea trials, the following shall be checked:
   .1 continuous operation of the apparatus on the ship under way;
   .2 possibility of superimposition (where appropriate) of the radar image and the ENC chart information and their matching;
   .3 correct voyage documenting within previous 12 h;
   .4 ship's route reckoned on the gyrocompass's and log's data;
   .5 superimposition of data received from the AIS and ARPA (where appropriate), and the ENC chart information;
   .6 adjustment of display brilliance in day and night conditions;
   .7 recording of the voyage data and impossibility of changing thereof;
   .8 automatic interchange of the ENC image when the own ship approaches the edge of the display at a determined distance;
   .9 automatic actuation of alarm signals when the ship approaches the turning point, pre-set line, border determined on the chart;
   .10 possibility of expanding (reducing) of the ENC chart scale.
16.4.4.13 Integrated navigation system (INS).
16.4.4.13.1 At surveys of INS during sea trials, the following shall be checked:
   .1 interaction of navigational devices and equipment involved in the system, as well as their operation in the independent mode;
   .2 transfer to duplicating equipment in case of failure of the main one;
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.3 quality of the ship's heading and pre-set track automatic steering (for system Categories B and C);
.4 continuous automatic monitoring of the main information coming to the system by means of comparing navigational data derived independently from two different sensors;
.5 actuation of sound (with the possibility of switching off) and visual alarm signals in case of failures of interfaced information sensors and data processing system;
.6 recording of actuation of alarm signals and confirmation of alarm signals accepted by the navigator;
.7 programmed protection of the system from logical errors of the navigator in the data input;
.8 completeness and quality of the navigational information displayed on the system generalized display.
16.4.4.14 Combined ship control desks.
16.4.4.14.1 At surveys of combined ship control desks during sea trials, the following shall be checked:
.1 use of the combined ship control desks as designated and ensuring the ship's safety of navigation;
.2 operation of controls, monitoring and indication as designated;
.3 arrangement of controls, indicating and monitoring instruments designated for immediate use in extreme circumstances important for the safely of navigation of the ship under way.
16.4.4.15 Unified timing system.
16.4.4.15.1 At surveys of the unified timing system during sea trials, the following shall be checked:
.1 reliable operation in the course of sea trials;
.2 main clock daily run (not more than 0.5 s) with variations within 0.1 s;
.3 corrections against the international accurate hour's service signals;
.4 operation of the secondary clock.
16.4.4.16 Bridge navigational watch alarm system (BNWAS).
16.4.4.16.1 At surveys of the BNWAS during sea trials BNWAS operability in all three modes shall be checked (on/off/ auto, when the system operates in automatic mode — refer to 16.4.3.16.6).
16.4.5 All paras of the present Section shall be checked on prototype ships.
On series ships some kinds of tests of navigational equipment carried out under way, in sea conditions, may be replaced by simulating tests approved by RHO during mooring trials (refer to Section 18).
All equipment defects found out in the course of mooring and sea trials shall be cleared prior to issuance the ship's documents by the Register.
16.5 SURVEY OF MODU/FOP NAVIGATIONAL EQUIPMENT

16.5.1 Ship's hydro meteorological complex. Check of installation shall be performed by external examination for compliance with the documentation approved by the Register and the requirements of Section 3, Part XIX "Navigational Equipment" of the MODU/FOP Rules. During testing, the operation of equipment for intended purpose shall be checked. Therewith, the parameters being recorded by the complex and those required by Table 2.2.1, Part XIX "Navigational Equipment" of the MODU/FOP Rules shall be compared.
17 ARRANGEMENTS FOR THE PREVENTION OF POLLUTION FROM SHIPS

17.1 GENERAL

17.1.1 The Section establishes the procedure of the Register technical supervision during the installation and testing of the PPS equipment and arrangements on board the ship.

17.1.2 General provisions for the organization of technical supervision during the installation and testing of the equipment and arrangements are set out in Part I "General Regulations for Technical Supervision"; those concerning technical documentation — in Part II "Technical Documentation" of the Rules for Technical Supervision.

17.1.3 Technical documentation.
17.1.3.1 Installation and testing of the PPS equipment and arrangements on board the ship shall be performed under the Register technical supervision according to the RS-approved technical documentation.

17.1.4 Technical supervision of the Register.
17.1.4.1 Surveys during installation and testing shall be performed according to the examination and testing plan developed by the shipyard according to 17.2.1, taking into account 17.3 – 17.6.

17.1.5 Tests and checks specified in this Section are based on an assumption that the PPS equipment and arrangements have been tested at the firm (manufacturer) in compliance with the requirements of Section 17, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.
17.2 SURVEY PLANNING

17.2.1 Prior to commencement of survey of the PPS equipment of the ship under construction, the RS Branch Office shall agree the examination and testing plan developed by the shipbuilder taking into account Table 17.2.1, as well as 17.3 – 17.6. The shipbuilder shall be informed about that at a kick-off meeting prior to commencement of construction according to 2.7.1.

The builder shall agree to undertake ad hoc investigations during construction as may be requested by RS where areas of concern arise and the builder to agree to keep RS advised of the progress of any investigation. Whenever an investigation is undertaken, the builder shall be requested, in principle, to agree to suspend relevant construction activities if warranted by the severity of the problem.

17.2.2 During approval and agreement of the examination and testing lists a note shall be taken of specific published Administration requirements and interpretations of statutory requirements.

17.2.3 The shipyard shall be requested to advise of any changes to the activities agreed at the kick off meeting and these shall be documented in the examination and testing plan. E.g. if the shipbuilder chooses to use or change sub-contractors, or to incorporate any modifications necessitated by changes in production or inspection methods, rules and regulations, structural modifications, or in the event where increased inspection requirements are deemed necessary as a result of a substantial non-conformance or otherwise.

17.2.4 Quality standards for installation and testing of the PPS equipment shall be reviewed and agreed during the kick-off meeting. The work shall be carried out in compliance with the RS rules and under the RS technical supervision.

17.2.5 Any changes to the kick-off meeting records shall be agreed and documented.

Table 17.2.1

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Items of technical supervision</th>
<th>Verification of technical documentation</th>
<th>Verification of Register certificates for materials and equipment, verification of brands</th>
<th>Verification of installation on ship</th>
<th>Hydraulic tests</th>
<th>Test in operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Equipment and arrangements for the prevention of pollution by oil:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>.1</td>
<td>segregated ballast tanks (reg. 18 of Annex I to MARPOL 73/78);</td>
<td>+</td>
<td>−</td>
<td>+</td>
<td>−</td>
<td>−</td>
</tr>
<tr>
<td>.2</td>
<td>slop tanks (reg. 29 of Annex I to MARPOL 73/78);</td>
<td>+</td>
<td>−</td>
<td>+</td>
<td>−</td>
<td>−</td>
</tr>
<tr>
<td>.3</td>
<td>cargo tanks of oil tankers (reg. 19 of Annex I to MARPOL 73/78);</td>
<td>+</td>
<td>−</td>
<td>+</td>
<td>−</td>
<td>−</td>
</tr>
<tr>
<td>.4</td>
<td>tanks for oil residues (reg. 12 of Annex I to MARPOL 73/78);</td>
<td>+</td>
<td>−</td>
<td>−</td>
<td>−</td>
<td>−</td>
</tr>
<tr>
<td>.5</td>
<td>crude oil washing system (reg. 33 of Annex I to MARPOL 73/78) where applicable;</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td></td>
<td>+</td>
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<tr>
<td>.7</td>
<td>15 ppm separators(^{1});</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td></td>
<td>+(^{2})</td>
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<tr>
<td>.8</td>
<td>15 ppm bilge alarms(^{1});</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td></td>
<td>+</td>
</tr>
<tr>
<td>.9</td>
<td>oil content meter intended for monitoring the discharge of oil- contaminated water from the cargo tank area of oil tankers(^{1});</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td></td>
<td>+(^{2})</td>
</tr>
<tr>
<td>.10</td>
<td>automatic discharge monitoring and control system for oil tankers;</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td></td>
<td>+</td>
</tr>
<tr>
<td>.11</td>
<td>oil/water interface detectors in slop tanks(^{1});</td>
<td>+</td>
<td>+</td>
<td>−</td>
<td></td>
<td>−</td>
</tr>
<tr>
<td>.12</td>
<td>oily water pumping, piping and discharge arrangements including those used for oil tanker cargo areas, oil residues and segregated ballast</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td></td>
<td>+</td>
</tr>
</tbody>
</table>
### Guidelines on Technical Supervision of Ships under Construction (Section 17)

<table>
<thead>
<tr>
<th>Nos.</th>
<th>Items of technical supervision</th>
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<th>Test in operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>.13</td>
<td>sludge incineration installations (incinerators)</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>.14</td>
<td>system of sludge preparation for incineration (mixing tanks, heating system, filters and homogenizing systems)</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>.15</td>
<td>oil fuel tank protection (reg. 12A of Annex I to MARPOL 73/78)</td>
<td>+</td>
<td>-</td>
<td>+</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>.16</td>
<td>pump room bottom protection, where applicable (reg. 22 of Annex I to MARPOL 73/78)</td>
<td>+</td>
<td>-</td>
<td>+</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

2 Equipment and arrangements for the prevention of pollution by sewage:

1. sewage treatment plants (1): + + + + +
2. sewage comminution and disinfection plants: + + + + +
3. holding tanks for the retention of sewage (reg. 9 of Annex IV to MARPOL 73/78): + - + + -
4. sewage disposal and discharge systems + + + + +

3 Equipment and arrangements for the prevention of pollution by garbage:

1. garbage incineration installations (incinerators) (1): + + + + (2) +
2. garbage processing devices: + + + - +
3. garbage receptacles + + + + -

4 Equipment and arrangements for the prevention of pollution by noxious liquid substances carried in bulk:

1. cargo tanks (reg. 2.6 of IBC Code (3)): + - + - -
2. ventilation equipment for removal of cargo residues (reg. 13.3 of Annex II to MARPOL 73/78): + + + - +
3. stripping system piping: + + + + +
4. underwater discharge outlet (reg. 6-10 of Annex II to MARPOL 73/78): + - + - +
5. cargo tank washing system: + + + + +
6. system for removal of residues of the noxious liquid substances: + + + + +

5 Equipment for the prevention of air pollution:

1. diesel engines complying with reg. 13 of Annex VI to MARPOL 73/78 and the requirements of NOx Technical Code (4): + + + - -
2. exhaust gas cleaning systems for reducing NOx emissions as marine diesel engine component: + + + + (2) +
3. exhaust gas cleaning systems in compliance with the Guidelines for Exhaust Gas Cleaning Systems (refer to IMO resolution MEPC.340(77) as amended) for reducing SOx emissions: + + + + (2) +
4. equipment for bunker oil sampling: + + + + (2) +
6 Ballast water management systems (IMO resolution MEPC.300(72), as amended) + + + + (2) +

(1) Availability of copy of the Type Test (Approval) Certificates drawn up in accordance with Appendix 2 to Section 17 of Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision shall be checked.
(2) Tightness tests of pipeline of above mentioned equipment in compliance with 17.5.
(3) International Code for the Construction and Equipment of Ships Carrying Dangerous Chemicals in Bulk, as amended.
(4) Technical Code on Control of Emission of Nitrogen Oxides from Marine Diesel Engines.
17.3 REGISTER TECHNICAL SUPERVISION

17.3.1 Prior to installation of the PPS equipment and arrangements it is necessary to make sure that all welding and assembling works on the seatings have been performed in accordance with the RS-approved technical documentation.

17.3.2 Installation on the seatings and securing of the equipment shall meet the requirements of the technical documentation approved by the Register.
17.4 SURVEYS AND TESTS ON BOARD SHIPS AFTER INSTALLATION
OF PPS EQUIPMENT AND ARRANGEMENTS

17.4.1 General.
17.4.1.1 The installation of the PPS equipment and arrangements shall be checked in accordance with the guidelines of the approved working drawings as well as the process documentation for installation. If the technical documentation contains special requirements for the installation of particular kinds of the PPS equipment and arrangements they shall be fulfilled.
17.4.1.2 The PPS equipment and arrangements having the RS documents confirming its supervision during the manufacture and bench tests at the manufacturer according to the RS Nomenclature shall be accepted for installation on board ship.

In case of onboard tests prescribed by the Register normative documents, such tests shall be carried out to the program agreed with the Register and prepared in accordance with the procedure specified in Part IV “Technical Supervision during Manufacture of Products” of the Rules for Technical Supervision.

17.4.2 Survey of tanks, PPS equipment and arrangements listed in Table 17.2.1.
17.4.2.1 During the survey of tanks the compliance of the arrangement, design and size (capacity) of the tanks with the requirements of the RS-approved design technical documentation shall be checked.
17.4.2.2 During the survey of the segregated ballast tanks of oil tankers it is necessary to check:
   .1 pipelines for the discharge of water ballast (reg. 30 of Annex I to MARPOL 73/78);
   .2 protective location of segregated ballast spaces (reg. 18.12 of Annex I to MARPOL),
   where applicable;
   .3 absence of connections to the cargo oil and fuel oil systems;
   .4 capacity of the segregated ballast tanks.
17.4.2.3 During the survey of the slop tanks of oil tankers the following shall be checked:
   .1 means for transferring the oily waters into a slop tank after cargo tank washing and, where applicable, pipelines for discharge of oily waters into the sea in compliance with reg. 34 of Annex I to MARPOL 73/78;
   .2 capacity of slop tanks (reg. 29 of Annex I to MARPOL 73/78);
   .3 position of inlets and outlets, baffles and weirs to avoid excessive turbulence (reg. 29.3 of Annex I to MARPOL 73/78).
17.4.2.4 During the survey of the cargo tanks of oil tankers the following shall be checked:
   .1 compliance of cargo tanks with the requirements of reg. 23 of Annex I to MARPOL 73/78;
   .2 protective location of cargo tanks (reg. 19 of Annex I to MARPOL 73/78).
17.4.2.5 During the survey of oil residue (sludge) and oily bilge water tanks the following shall be checked:
   .1 absence of direct pipeline connections to/from oil residue (sludge) tanks with side openings, excluding standard discharge connection required by reg. 13 of Annex I to MARPOL 73/78, as well as of the pipeline running to the incinerator service tank (where applicable);
   .2 there shall be no interconnections between the sludge tank discharge piping, piping for transfer of oil residues between oil residue (sludge) tanks and bilge-water piping other than possible common piping leading to the standard discharge connections. Also the piping shall have no connections to oily bilge water holding tanks, bilges of machinery spaces or 15 ppm separators;
   .3 oil residue (sludge) tanks may be fitted with drains, with manually operated self-closing valves and arrangements for subsequent visual monitoring of the settled water, that lead to an oily bilge water holding tank or bilge well, or an alternative arrangement, provided such arrangement does not connect directly to the bilge piping system;
.4 the oil residue (sludge) tank discharge piping and bilge water piping are equipped with non-return valves to prevent oil residues (sludge) from discharging to the bilge water piping, bilge water tank, bilges of machinery spaces and bilge water separator;
.5 equipment facilitating tanks cleaning and discharge of oil residues (sludge) to reception facilities: manholes of adequate size, heating systems (when heavy fuel oil is used), pump fit for transferring high viscosity oil sludge;
.6 heaters if the oily residues and oily bilge water holding tanks are in contact with a medium or spaces with a negative temperature, or heavy fuel oil is used on board;
.7 installation of light and sound alarms operating in case of 80 % filling of the tank.
17.4.2.6 Hydraulic tests of tanks shall be carried out in compliance with 2.5.
17.4.2.7 Structural arrangements for oil fuel tank protection and their location shall be checked for compliance with reg. 12A of Annex I to MARPOL 73/78 (including, if applicable reg. 12A.11).
17.4.2.8 Structural arrangements for cargo pump room bottom protection shall be checked for compliance with reg. 22 of Annex I to MARPOL 73/78 (if applicable).
17.4.3 Crude oil tank washing system for oil tankers.
17.4.3.1 During the survey the following shall be checked:
.1 completeness of the technical documentation approved by the Register;
.2 number and location of the tank washing machines;
.3 installation and support attachments of the tank washing machines, pipelines, pumps and drive units;
.4 rotation capability of the tank washing machines in accordance with Section 4 "Design criteria" of IMO resolution A.446(XI), as amended;
.5 readings of the indicators external to the tank to verify the rotational speed of the tank washing machines;
.6 possibility of isolating the steam heater (if any) for use when water washing, by double shut-off valves;
.7 possibility of isolating each tank washing machine by means of shut-off valves;
.8 possibility of blanking off the oil supply line to the machine and closing the tank opening when the machines need be removed;
.9 possibility of disconnecting effectively the washing system from the cargo oil system;
.10 availability of drain plugs to provide drainage of the piping;
.11 possibility of changing over the pumps in the event of any one pump out of order;
.12 availability of a relief device to prevent overpressure, which shall discharge into the suction side of the supply pump, or temperature sensors on the casings of centrifugal pumps;
.13 availability of pressure gauges and other instrumentation the connections of which shall be provided with isolating valves adjacent to the lines;
.14 proper storage and condition of approved flexible hoses for oil supply to the washing machines on combination carriers;
.15 that inert gas system is installed (refer to the applicable section of STORM Checklist (form 6.1.01)).
17.4.4 15 ppm bilge separators.
17.4.4.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 compliance of the related equipment with the technical documentation;
.3 availability of certificates confirming the Register supervision during the manufacture, Type Approval Certificate, as well as a copy of the Certificate of Type Approval for 15 ppm Bilge Separator (form 2.4.17.1/2.4.17.2);
.4 accessibility of the equipment items, ease of monitoring the instrument indications, possibility of replacing the filtering elements;
.5 availability and location of the sampling arrangements. The sampling arrangements shall be fitted on pipe sections running vertically as near the separator (filter) outlet as possible;
.6 availability of the thermometer pockets;
.7 proper installation of piping;
.8 availability of drip trays to collect possible leaks of oil residue the pipes of which shall be led into the holding tank;
.9 installation of the electrical equipment and automation facilities;
.10 availability of arrangements for draining the equipment;
.11 compliance with the requirements for installation specified in Section 6.1 of IMO resolution MEPC.107(49), as amended;
.12 availability of re-circulating facility installed after the 15 ppm bilge separator, 15 ppm bilge alarm and automatic stopping device for their inspection with the sea opening closed.

17.4.5 15 ppm bilge alarm.
17.4.5.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 availability of certificates confirming the Register technical supervision during the manufacture, Type Approval Certificate, as well as a copy of the Certificate of Type Approval for 15 ppm Bilge Alarm (form 2.4.11.1);
.3 availability of calibration report of the firm (manufacturer) or organization authorized by the manufacturer;
.4 installation and mounting of bilge alarms. Any electrical equipment which is part of the 15 ppm bilge alarm shall be based in a non-hazardous area, or shall be certified as safe for use in a hazardous area; self-recording devices for continuous recording of date, time, alarm status and the separator working condition;
.5 accessibility of the system components;
.6 availability of identification plates, rating plates, position indicators of the shut-off devices;
.7 installation of the electrical equipment and automation facilities;
.8 interlocks precluding discharge with the system switched off or in the event of any fault in the system;
.9 compliance with the requirements for installation specified in Section 6.2 of IMO resolution MEPC.107(49) as amended.

17.4.6 Automatic stopping device.
17.4.6.1 During survey the following shall be checked:
.1 installation of device;
.2 availability of shut-off valve location indicator.

17.4.7 Oil discharge monitoring and control system for oil tankers.
17.4.7.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 availability of certificates confirming the Register technical supervision during the manufacture, Type Approval Certificate and a copy of the Certificate of Type Approval for Oil Content Meters intended for monitoring the discharge of oil-contaminated water from the cargo tank areas of oil tankers (form 2.4.16.1);
.3 availability of record books of the equipment for the main system components;
.4 availability of the operating instruction and technical guidelines approved by the Register, which shall include technical description of the system, methods of operation and redundancy in the event of any fault or failure of the system;
.5 installation and mounting of the oil control meters of the discharge control devices, flow meters and compliance with the requirements of Part VI "Fire Protection" of the Rules for the Classification and Construction, in particular, observance of the regulation concerning passage of pipes and light conductors through the bulkheads;
.6 accessibility of the system components;
.7 availability and location of the sampling arrangements;
.8 availability of the identification plates, rating plates, position indicators of the shut-off devices;
.9 installation of the electrical equipment and automation facilities;
.10 compliance with the requirements for installation and survey of the system specified in Sections 10 and 11 of IMO resolution MEPC.108(49) as amended.

17.4.8 Oil/water interface detectors in slop tanks.
17.4.8.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 availability of certificates confirming the Register technical supervision during the manufacture, Type Approval Certificate, as well as the Certificate of Type Test for Oil/Water Interface (form 2.4.19);
.3 availability of a document issued by a competent organization which permits installation of the detector in dangerous spaces in accordance with Appendix 1 to Section 10;
.4 installation and securing;
.5 availability of data plates and marking (for permanently installed detectors);
.6 installation of electrical equipment including earthing jumpers (for permanently installed detectors).

17.4.8.2 Pipes of the detectors working on nonelectrical principles shall be tested in accordance with the RS-approved technical documentation.

17.4.9 Pumping, piping and discharge arrangements for oily waters, oil residues, segregated ballast.
17.4.9.1 The following pipelines shall be subjected to survey:
.1 discharge pipelines intended for the discharge of oily residues and oily waters to reception facilities with control of dimensions of flanges for standard discharge connections (reg. 13 in Annex I to MARPOL 73/78);
.2 pipelines for the discharge of oily mixtures to the sea from the cargo tank area;
.3 pipelines and arrangements for the discharge to the sea of the segregated ballast of oil tankers.

17.4.9.2 During survey of ships, including oil tankers, the following shall be checked:
.1 completeness of the technical documentation on the pipelines referred to in 17.4.9.1.1 and 17.4.9.1.2;
.2 availability and location of the pipelines referred to in 17.4.9.1.1 and 17.4.9.1.2, including dimensions of flanges for standard discharge connections (reg. 13 of Annex I to MARPOL 73/78), which shall ensure ease of connection of hose and fitting of blank flanges. The pipelines for the discharge of oily mixtures to sea shall be led to the open deck or to the ship’s side above the waterline in the deepest ballast condition;
.3 availability of an arrangement for manual starting and stopping of the discharge arrangements;
.4 availability and fitting-out of the discharge observation and remote cut-off position or availability of the effective communication system (such as telephone or radio system) between the observation position and the discharge control position.

17.4.9.3 When surveying oil tankers, in addition to checks under 17.4.9.2.1 – 17.4.9.2.4, the following shall be checked:
.1 location, installation of the pipelines and arrangements referred to in 17.4.9.1.3;
.2 installation of the system of pipelines for the emergency cargo transfer (if any) (reg. 23.11.2 of Annex I to MARPOL 73/78);
.3 availability of valves or other closing arrangements located at a point of connection with any cargo tank:
   in the pipelines which run through cargo tanks in the vicinity of the ship’s side or bottom (in accordance with reg. 23.11.1 of Annex I to MARPOL 73/78);
.4 possibility of draining the cargo pumps and pipelines through the use of stripping system (reg. 30.4 of Annex I to MARPOL 73/78);
.5 availability of a portable spool piece (if any) for emergency discharge of segregated ballast and of non-return valves (the Unified Interpretations to reg. 1.18 of Annex I to MARPOL 73/78);
.6 availability of reliable closing arrangements installed in the pipeline system to prevent the pipeline section between the sea-chest valve and inside shut-off valve from being filled with cargo (if applicable) (reg. 30.7 of Annex I to MARPOL 73/78);
.7 equipment for transfer of oil cargo between oil tankers at sea according to Ship to Ship Transfer Operations Plan (STS operations Plan) (reg. 41.1 of Annex I to MARPOL 73/78).

17.4.10 Sewage treatment plants.
17.4.10.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 availability of a copy of the Certificate of Type Test/Approval for Sewage Treatment Plants (form 2.4.13.1/2.4.13.2), Type Approval Certificate and a certificate confirming the Register technical supervision during the manufacture of the plant;
.3 consistency between the related equipment and the technical documentation;
.4 availability of valid documents and brands of the standard instruments put by a competent body;
.5 installation, assembly and securing of the equipment, associated pumps, arrangements, pipelines and fittings, automation, monitoring and control devices;
.6 availability of sampling arrangements. The plant shall be provided with a sampling arrangement located at the purified water outlet in accordance with the technical documentation approved by the Register;
.7 installation of the electrical equipment and automation facilities, earthing of the plant and electrical equipment insulation resistance.

17.4.10.2 Upon the finalization of the checks referred to in 17.4.10.1.1 – 17.4.10.1.7, it is necessary to conduct hydraulic tests of the plant in compliance with the requirements of 17.5.

The plant shall be tested by a test pressure equal to 1.5 times the water column pressure measured from the plant bottom to the lower toilet bowl not provided with a shut-off device in the discharge line, but not less than 25 kPa.

17.4.11 Sewage comminution and disinfection plants.
17.4.11.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 availability of a certificate confirming the Register technical supervision during the manufacture of the plant;
.3 compliance of the related equipment with the technical documentation;
.4 availability of valid documents and brands of the standard instruments put by a competent body;
.5 installation, assembly and securing of the equipment, associated pumps, arrangements, pipelines and fittings, automation, monitoring and control devices;
.6 installation of the electrical equipment and automation facilities, earthing of the plant and electrical equipment insulation resistance.

17.4.11.2 Upon the finalization of the checks referred to in 17.4.11.1.1 – 17.4.11.1.6, it is necessary to conduct hydraulic tests of the plant in compliance with the requirements of 17.5.

The plant shall be tested by a test pressure equal to 1.5 times the water column pressure measured from the plant bottom to the lower toilet bowl not provided with a shut-off device in the discharge line, but not less than 25 kPa.

17.4.12 Sewage holding tanks.
17.4.12.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation including the calculation of the total capacity of the holding tanks agreed with the shipowner, enabling retention of all sewage, having regard to the intended area of navigation, service conditions of the ship and number of persons on board, taken into consideration by the Register and agreed with the shipowner;
.2 compliance of the size and design of the tanks with the approved documentation and the location thereof;
.3 availability of manholes and their closing appliances;
.4 availability of the arrangements for flushing and steaming (if a steam system is available);
.5 availability of the arrangements for sediment resuspension (if contemplated by the technical documentation);
.6 availability and condition of the corrosion protection against effect of water;
.7 availability of the visual and acoustic alarm;
.8 availability of cofferdams separating the sewage holding tanks from the tanks used for drinking, washing water and for vegetable oil, as well as from accommodation, service (domestic) and cargo spaces intended for the carriage of food-stuff;
.9 availability of efficient means to indicate visually the amount of sewage holding tanks contents.

17.4.12.2 Upon the finalization of the checks referred to in 17.4.12.1.1 – 17.4.12.1.9, it is necessary to conduct hydraulic tests of the holding tanks in accordance with the requirements of 2.5. The holding tanks shall be tested by a test pressure equal to 1.5 times the water column pressure measured from the tank bottom to the lower toilet bowl not provided with a shut-off device in the discharge line, but not less than 25 kPa.

17.4.13 Sewage disposal and discharge systems.
17.4.13.1 During the survey, the following shall be checked:
.1 completeness of the technical and service documentation;
.2 availability, location and securing of the pumps (eductors) intended for sewage discharge;
.3 availability and location of the pipelines and fittings, including dimensions of flanges for standard discharge connections (reg. 10 of Annex IV to MARPOL 73/78), which shall ensure ease of connection of hoses for discharging sewage to reception facilities;
.4 availability of blank flanges to the discharge connections;
.5 availability of arrangements for manual starting and stopping of the pumps (eductors);
.6 availability and fitting-out of the discharge observation and remote cut-off position or availability of the effective communication system (such as telephone or radio system) between the observation position and the discharge control position;
.7 availability of arrangements providing discharge of untreated sewage water at the discharge rate approved by the Register and calculation in compliance with IMO resolution MEPC.157(55), as amended, if applicable.

17.4.14 Incinerators.
17.4.14.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 compliance of the related equipment with the technical documentation;
.3 availability of copies of the certificates confirming the Register technical supervision during the manufacture, Type Approval Certificate, as well as a copy of the Certificate of Type Approval for Shipboard Incinerators (form 2.4.12/2.4.12.1) and also brands and marking;
.4 satisfactory installation and securing of the equipment, associated machinery, system of sludge preparation for incineration, tanks, pumps, flame arresters, pipelines and fittings, automation, alarm and monitoring devices;
.5 condition of the incinerator interior and ash bin;
.6 tight closure of the charging hopper covers and availability of an interlock to make their simultaneous opening impossible;
.7 availability of plates with warning inscriptions with respect to the materials charged;
.8 proper installation of the pipelines and quick-closing valve of the service tank;
.9 availability of drip trays to collect possible fuel leaks, the pipelines of which shall be led into the holding tank;
.10 installation of the electrical equipment and automation facilities including connection of the ventilator power supply feeder to the emergency switchboard (if contemplated by the design);
.11 possibility of shutting off the burners from two positions one of which shall be located outside the space where the incinerator is installed;
.12 availability of automatic fire alarm and detection system;
.13 availability of a fire extinguishing system in compliance with Chapter II-2 of SOLAS-74.

17.4.15 Garbage comminuters and compactors.
17.4.15.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 compliance of the related equipment with the technical documentation;
.3 availability of a document confirming the RS technical supervision during the manufacture, and the marking;
.4 location and securing of the equipment, associated machinery, pumps, arrangements, pipelines and fittings, automation, control and monitoring devices;
.5 installation of a garbage chute (if appropriate) which shall run above the bulkhead deck and be fitted with covers capable of being locked;
.6 installation of the electrical equipment and automation facilities;
.7 ensuring comminution using comminuters to grind food wastes to a particle size no greater than 25 mm.

17.4.16 Garbage containers.
17.4.16.1 During the survey the following shall be checked:
.1 completeness of the technical and service documentation;
.2 compliance of location, design and size of garbage containers with the RS-approved technical design documentation;
.3 availability of distinctively marked garbage types in compliance with IMO resolution MEPC.295(71), as amended;
.4 availability of smooth inner surfaces with no openings in the walls and bottom;
.5 condition of the covers and their tight closing;
.6 availability of means for safe securing of garbage containers on board the ship.

17.4.17 Cargo tanks of ships intended for the carriage of noxious liquid substances in bulk.
17.4.17.1 During the survey the following shall be checked:
.1 completeness of the technical documentation pertaining to the tanks and their equipment;
.2 compliance of tank location, design and size with the requirements of the RS-approved technical design documentation, including protective location of cargo tanks (reg. 2.6 of IBC Code), where applicable.

17.4.18 Ventilation equipment for the removal of gaseous residues of the noxious liquid substances.
17.4.18.1 During the survey the following shall be checked:
.1 completeness of the technical documentation pertaining to the ventilation equipment;
.2 availability of certificates confirming the RS technical supervision during the manufacture of ventilation equipment;
.3 compliance of the location, design of the equipment with the requirements of the RS-approved design technical documentation;
.4 installation and securing of the equipment, accessibility for maintenance and inspection, proper installation of supply pipelines, installation of electrical equipment.

17.4.19 Tank washing system for ships carrying noxious liquid substances in bulk.
17.4.19.1 During the survey the following shall be checked:
.1 completeness of the technical documentation pertaining to the arrangements;
.2 compliance of the location, design of the equipment (including tank washing machines, washing water heating system) with the requirements of the approved design technical documentation. Any alterations shall be agreed upon with the Register;
.3 the required number and location of the tank openings for portable tank washing machines which shall comply with the approved diagrams.

17.4.20 Cargo and washing water discharge pipeline systems of ships carrying noxious liquid substances.

17.4.20.1 During the survey the following shall be checked:

.1 completeness of the technical documentation pertaining to the system;
.2 compliance of the location, design of the systems and its components with the RS-approved technical documentation;
.3 provision of pumps and pipelines with the required stripping quantity upon results of performance tests (Appendix 5 of Annex II to MARPOL 73/78);
.4 compliance of underwater discharge outlet size and location with the requirements (reg. 12.6 – 12.10 of Annex II to MARPOL 73/78);
.5 installation of electrical equipment and system automation devices.

17.4.21 Equipment for the prevention of air pollution.

17.4.21.1 Diesel engines, including those fitted with NO₅ reducing devices and complying with reg. 13 of Annex VI to MARPOL 73/78 and the requirements of the NO₅ Technical Code.

17.4.21.1.1 During the survey, the following shall be checked:

.1 completeness of technical documentation: approved Technical File of Marine Diesel Engine with NO₅ Reducing Device (if any);
.2 for engines equipped with NO₅ reducing devices, the check shall be performed in accordance with the procedure specified in the approved Technical File and may be performed using parameter check method in compliance with the requirements of 6.2 of the NO₅ Technical Code.

In cases where the engine has not been tested on the firm's (manufacturer's) test bed together with NO₅ reducing device due to impracticality of such testing, the check shall be performed in accordance with the procedure specified in 17.6.17.1.

17.4.21.2 Exhaust gas cleaning (EGC) systems for reducing SOₓ emissions (if any) in compliance with the requirements of the Guidelines for Exhaust Gas Cleaning Systems adopted by IMO resolution MEPC.340(77) as amended.

17.4.21.2.1 During the survey the following shall be checked:

.1 for EGC systems surveyed under Scheme A, availability of SOₓ Emission Compliance Certificate (Certificate of Unit Approval for Exhaust Gas Cleaning Systems (form 2.4.42)), Type Approval Certificate (CTO) and depending on the scheme of technical supervision C, C3 or MC;
.2 for EGC systems surveyed under Scheme B, availability of manufacturer's documents (MC) and CTO;
.3 availability of the approved documents prescribed by the Guidelines for Exhaust Gas Cleaning Systems adopted by IMO resolution MEPC.340(77), as amended;
.4 installation of EGC systems and sampling points has been carried out in accordance with the approved documentation.

17.4.21.3 Equipment for fuel oil sampling.

17.4.21.3.1 During the survey the following shall be checked:

.1 availability of approved documentation or Type Approval Certificate for the equipment for supplied fuel oil sampling;
.2 availability of an operating instruction for the equipment for supplied fuel oil sampling;
.3 availability of approved documentation for the fuel oil sampling points complying with the requirements of IMO circular MEPC.1/Circ.864/Rev.1;
.4 installation of the equipment for fuel oil sampling in accordance with the requirements imposed.
17.4.21.4 Requirements for carbon intensity of ships, to which the requirements for the Energy Efficiency Design Index (EEDI) and Energy Efficiency Existing Ship Index (EEXI) apply.  
During the survey, prior to sea trials, the following shall be checked:  
.1 availability of technical documentation agreed with the Register confirming the compliance of a ship with the technical requirements for carbon intensity (EEDI Technical File and, where applicable, EEXI Technical File), Report on Preliminary Verification of the Ship's Energy Efficiency Design Index (EEDI) (form 6.4.3);  
.2 compliance of the equipment installed and its parameters with the EEDI and EEXI Technical Files, as applicable. 

17.4.21.5 In case of installation of overridable shaft/engine power limitation (ShaPoLi/EPL) systems, which provide the possibility to override these limitations in the emergency cases (overridable system), availability of the approved ship's guidelines on ShaPoLi/EPL, installation and sealing of the equipment shall be checked in compliance with the 2021 Guidelines on the Shaft/Engine Power Limitation System to Comply with the EEXI Requirements and Use of a Power Reserve (IMO resolution MEPC.335(76) amended by IMO resolution MEPC.375(80)).

17.4.22 Cargo vapour collection and discharge system of oil tankers.  
17.4.22.1 During the survey the following shall be checked:  
.1 completeness of the technical documentation pertaining to the system;  
.2 compliance of the location, design of the equipment with the RS-approved technical documentation;  
.3 satisfactory installation of the following: piping of vapour collection system; means for condensate removal at low points on the piping system ends; shut-off valves of the vapour discharge manifolds;  
.4 compliance of the vapour removal flanges with the IMO requirements and industrial standards.

17.4.23 Ballast water management systems.  
17.4.23.1 During the survey the following shall be checked:  
.1 availability of the Type Approval Certificate of Ballast Water Management System (form 2.5.5-1) and the Type Approval Certificate;  
.2 availability of operating manual;  
.3 equipment installation in compliance with the RS-approved documentation;  
.4 compliance with the installation commissioning procedures in full scope in compliance with para 8.3.6 of the Code for Approval of Ballast Water Management Systems (BWMS Code) (IMO resolution MEPC.300(72)).
17.5 HYDRAULIC TESTS

17.5.1 The tightness tests of pipelines of the systems referred to in items 1.1 – 1.8, 1.10, 1.11, 2.4, 3.1, 4.3 – 4.6; 5.2 – 5.3 and 6 of Table 17.2.1, after their mounting on the ship, shall be conducted in compliance with 21.2.3, Part VIII "Systems and Piping" of the Rules for the Classification and Construction, provided that all works associated with the installation of the fittings and instruments have been completed prior to the tests.

17.5.2 The tightness tests of pipelines of sewage treatment plants or sewage comminuting and disinfecting system (refer to items 2.1 and 2.2 of Table 17.2.1), shall be carried out in compliance with 17.4.10.2 or 17.4.11.2 after their mounting on the ship. The test pressure used for the tests shall be maintained within 5 — 10 min, then it shall be reduced down to the working pressure and kept constant until the inspection is completed.

17.5.3 The equipment and arrangements shall be considered as passed the tests, if no leak or sweating in the welds, no water leaks in the flared pipe joints and in the coupling flanges of the fittings and instrumentation connections are detected.
17.6 FUNCTIONAL TEST

17.6.1 General.
17.6.1.1 Functional tests of the equipment and arrangements shall be carried out during mooring and/or sea trials of the ship according to program approved by the Register.
17.6.1.2 Tests shall be carried out using the standard equipment and instrumentation. Instruments used on the tests shall have documents of a competent body and/or brands certifying their periodic verifications if these instruments are subject to such verification.
17.6.1.3 Items the installation of which have been surveyed by the RS surveyor in accordance with 17.4 and with no remarks made thereon, which hinder such tests, shall be accepted for tests.
17.6.1.4 Ship's service systems, machinery, pumps, automatic equipment, electrical equipment, etc. operating directly or in association with the equipment and arrangements to be subjected to functional tests shall be tested in accordance with the provisions of the appropriate sections of the Guidelines.
17.6.1.5 During the tests it is necessary to check operation of the safety means which shall be set to a pressure not in excess of 1,1 the working pressure.
17.6.1.6 The general test procedure is set out in Section 18.
17.6.1.7 Where necessary, revision and check-out tests shall be carried out.

17.6.2 Tank washing system for oil tankers.
17.6.2.1 The system shall be tested with pure sea water.
17.6.2.2 During the tests the following shall be checked:
   .1 operation of the tank washing machines, including simultaneous action of the greatest number of the tank washing machines contemplated by the design;
   .2 operation of devices installed outside the cargo tanks indicating rotation and arc of rotation of each stationary washing machine;
   .3 operation of the double shut-off valves of the washing water heater if contemplated by the design;
   .4 capacity of the stripping system which shall exceed by 1,25 times the total capacity of all tank washing machines to be operated simultaneously during the tank bottom cleaning;
   .5 drainage of all cargo lines and pumps into the cargo or slop tanks or shore reception facilities through the use of stripping system via a special small diameter line to be connected to the ship's cargo system manifold valves;
   .6 operation of the indicators and instrumentation;
   .7 operation of the shut-off valves or other means enabling isolation of any tank not being stripped at that particular time;
   .8 operation of safety valves of the crude oil washing system pumps;
   .9 that the inert gas system was tested in compliance with the requirements of SOLAS-74/88/00.

17.6.3 15 ppm bilge separators.
17.6.3.1 Tests shall be carried out with a supply rate equal to the full throughput for which the equipment is designed.
17.6.3.2 Tests shall be performed using oily water taken directly from the engine room bilges (if applicable).
17.6.3.3 Prior to the test, the equipment shall be filled with pure sea water until it emerges from the sampling arrangement.
17.6.3.4 The tests shall proceed for 30 min in compliance with the bilge separator operating manual.
17.6.3.5 Operation of the sensors detecting the presence of oil in the oil collector and operation of the separator automatic draining valves shall be checked in compliance with the firm's (manufacturer's) instructions.
17.6.3.6 During the tests the following shall be checked:

1. leak-tightness of connections when the equipment is in operation;
2. operation in automatic control mode;
3. operation of pumping units and associated systems;
4. operation of automation, alarm and monitoring facilities;

Checks may be performed by creating extreme parameters directly at the system sensors.

17.6.4 15 ppm bilge alarm and automatic stopping devices.

17.6.4.1 Tests shall be performed together with the 15 ppm bilge separator. During tests, the following shall be checked:

1. zero setting of bilge alarm in compliance with 15 ppm bilge alarm operating manual;
2. continuous recording of date, time, alarm status and operating status of the 15 ppm bilge separator;
3. automatic actuation, when the oil content of discharge exceeds the set value, accompanied by visual and audible alarm with simultaneous switching-over of automatic stopping device to prevent discharge overboard and in case of 15 ppm bilge alarm failure, warming-up and deactivation. These checks may be conducted by creating extreme values in close vicinity to the system sensors.

17.6.5 Oil discharge monitoring and control systems for oil tankers.

17.6.5.1 Tests shall be carried out with water.

17.6.5.2 The system testing shall, at least, include the tests specified in Section 12 of IMO resolution MEPC.108(49), as amended.

17.6.6 Oil/water interface detectors in slop tanks.

17.6.6.1 The detector operation shall be checked when passing from oil to water and vice versa in compliance with the firm's (manufacturer's) instructions.

17.6.6.2 Check shall be performed with the use of a tank where the oil/water interface is clearly visible. The thickness of oil and water layers shall be, at least, sufficient for the detector to be completely submerged.

17.6.7 Pumping and discharge arrangements for oily waters and oil residues.

17.6.7.1 The tests shall be carried out with oily water or sea water.

17.6.7.2 When testing the discharge arrangements for oily water and oil residues to reception facilities the following shall be checked:

1. operation of the devices for manual starting and stopping of the discharge arrangements;
2. operation of the system for remote cut-off of the discharge arrangements from the discharge observation position or of the effective communication system (such as telephone or radio system) between the observation position and discharge control position;
3. operation of the visual and acoustic alarm giving a warning when the upper limiting level in the holding tanks is reached. The alarm shall be activated in case of 80 % filling of the holding tank.

17.6.7.3 When oil tankers are surveyed, operation of the systems, equipment and fittings specified in 17.4.8.3 is additionally checked.

17.6.8 Sewage treatment plants.

17.6.8.1 The plant shall be tested with water in compliance with the sewage treatment plant operating manual. During the test the following shall be checked:

1. free flow of the influent to the plant;
2. operation of the maserator to provide for comminution of the sewage particles (if forms a part of the plant set);
3. operation of the pumping and blower units;
4. operation of the level detectors situated in the plant chambers;
5. operation of the metering arrangements to supply coagulant solutions and disinfectants;
6. operation under manual and/or automatic control modes;
7. operation of the automation, monitoring and alarm facilities (simulation method may be accepted);
.8 operation of the electrical drives and auxiliary machinery (by external inspection);
.9 operation of the submersible pumps (if form part of the plant set);
.10 operation of the ventilation system of the space if the plant is installed in a separate space.

17.6.8.2 Then the sewage treatment plant shall be tested using the sewage formed under normal operating conditions in compliance with the sewage treatment plant operating manual. The plant treatment capacity shall be evaluated based on the following parameters:
- sewage sample transparency after treatment;
- content of activated sludge;
- aerated mixture oxygenation, etc.

Upon unsatisfactory results of the above mentioned check, the plant shall be tested with the sewage sampling and analysis performed by the recognized laboratory.

Conclusion of recognized laboratory shall be attached to the Register survey report.

17.6.9 Sewage comminution and disinfection plants.
17.6.9.1 The tests shall be carried out in accordance with 17.6.8.1, as applicable.

17.6.10 Sewage holding tanks.
17.6.10.1 Tests may be carried out with sea water.
17.6.10.2 During the tests the following shall be checked:
.1 free flow of the sewage influent;
.2 washing from the water fire main and steaming from the steam heating system;
.3 drainage by pump or eductor with discharge to the sea;
.4 operation of the visual and acoustic alarm giving a warning when the upper limiting level in the holding tanks is reached. The alarm shall be activated in case of 80 % filling of the holding tank;
.5 efficiency of means to indicate visually the amount of sewage holding tanks contents.

17.6.11 Sewage disposal and discharge systems.
17.6.11.1 The functional test shall be carried out together with tests referred to in 17.6.8 – 17.6.10, depending on the item actually fitted on board the ship.
17.6.11.2 During the test the following shall be checked:
.1 operation of devices for manual starting of the discharge arrangements;
.2 possibility of pumping out the sewage from the holding tanks to the reception facilities;
.3 operation of the system for remote cut-off of the discharge arrangements from the discharge observation position or of the effective communication system (such as telephone or radio system) between the observation position and discharge control position;
.4 devices providing discharge of untreated sewage with the RS-approved rate of discharge (where applicable) in compliance with IMO resolution MEPC.157(55), as amended.

17.6.12 Incinerators.
17.6.12.1 The test shall be conducted with wastes and oil residues specified in the documentation on the incinerator.
17.6.12.2 Water content of the oil wastes and/or sewage sludge (if the incinerator is intended to bum them) shall be not lower than that given in the documentation.
17.6.12.3 The tests shall be carried out in modes contemplated in the documentation on the incinerator. The sequence of the modes, time of operation in each mode, as well as the priority of tests shall be defined by a program approved by the Register.
17.6.12.4 The incinerator testing shall include the tests specified in Section 7.3 of Standard Specification for Shipboard Incinerators in IMO resolution MEPC.244(66), as amended.

During the tests the following shall be checked:
.1 operation of the space ventilation if the incinerator is located in a separate space;
.2 operation of the interlock of the charging hopper covers (if any) which shall make their simultaneous opening impossible when garbage is charged;
.3 operation of the interlock of the fuel burner when the burner is in the operating position and the combustion air is fed to the furnace;
.4 operation of the automatic device which cuts-off fuel supply to the burner within not more than 5 s in the following cases:
   loss of air flow to the furnace;
   flame failure in the torch;
   failure of electric power supply;
.5 operation under manual and automatic control modes;
.6 operation of the automation, alarm and monitoring facilities;
.7 fire protection of the incinerator spaces and/or waste stowage spaces shall meet the requirements in Annex 2 to IMO resolution MEPC.244(66), as amended;
.8 no spark ejection to the atmosphere from the exhaust gas system;
.9 operation of oil residue processing system designed for incineration (if the incinerator is intended for its burning).

17.6.13 Garbage processing devices.
17.6.13.1 During the test the following shall be checked:
   .1 operation of the space ventilation if the plant is located in a separate space;
   .2 operation of the garbage charging machinery;
   .3 operation of garbage comminers providing the required comminution of particles (not exceeding 25 mm in size);
   .4 operation of garbage compactors in compliance with the Operating Manual;
   .5 operation of the automation, alarm and monitoring systems.

17.6.14 Ventilation equipment for removal of the residues of noxious liquid substances.
17.6.14.1 The equipment shall be checked by an accessible method (e.g. by putting the equipment and air conduits into operation with simulation of the presence of the noxious liquid substances in the tanks or by testing the equipment and pipelines only for functional performance). The method of checking shall be agreed with the Register.
17.6.14.2 It shall be checked that removal of cargo residues from tank is performed by ventilation in compliance with Appendix 7 of Annex II to MARPOL 73/78 and approved Procedures and Arrangements Manual.
17.6.14.3 The effectiveness of tank ventilation shall be checked.
17.6.14.4 Operation of the ventilation system in way of the tank manholes when these are located in the space shall be checked.

17.6.15 Tank washing equipment.
17.6.15.1 The equipment may be checked by putting the equipment and pipelines into operation and by testing the tank washing machines for functional performance.

17.6.16 Cargo and washing water discharge systems of oil tankers carrying noxious liquid substances in bulk.
17.6.16.1 The cargo vapour discharge system shall be tested in compliance with Section 3, Appendix 5 of Annex II to MARPOL 73/78 to determine the system cleaning capacity according to regulation 12 of the above mentioned Annex. Compliance with the procedure for cargo tank stripping given in the approved Procedures and Arrangements Manual shall be verified.
17.6.16.2 When testing the system for washing water discharge through the underwater discharge outlet, operation of the system equipment and piping shall be tested. Tests shall be performed using the water free of noxious substances.
17.6.16.3 The equipment and pipelines forming part of the system shall be tested for functional performance.
17.6.16.4 During performance test of the system, its stripping ability shall be checked in compliance with reg. 12 of Annex II to MARPOL 73/78.
17.6.17 Equipment for the prevention of air pollution from ships.

17.6.17.1 Diesel engines complying with regulation 13 of Annex VI to MARPOL 73/78 and requirements of the NOx Technical Code.

The onboard confirmation tests of diesel engines to confirm that the engine continues to comply with the applicable NOx emission limit contained in regulation 13 of Annex VI to MARPOL 73/78 shall be conducted in accordance with the on board NOx verification procedures provided in the engines’ NOx Technical Files.

In cases where the engine has not been tested on the manufacturer’s test bed together with a NOx reducing device (refer to 17.4.20.1), the pre-certification of that engine and the NOx reducing device shall be performed. Where the selective catalytic reduction (SCR) system is used as NOx reducing device, the 2017 Guidelines Addressing Additional Aspects to the NOx Technical Code 2008 with Regard to Particular Requirements Related to Marine Diesel Engines Fitted with Selective Catalytic Reduction (SCR) Systems given in IMO resolution MEPC.291(71), as amended, shall be considered. However such onboard re-certification of engine fitted with NOx reducing device may be accepted for an individual engine or for an engine group represented by the parent engine only, but it shall not be accepted for an engine family certification.

17.6.17.2 Exhaust gas cleaning (EGC) systems for reducing SOx emissions are tested in compliance with the procedures specified in the approved EGCS Technical Manuals for Scheme A or B (ETM-A / ETM-B) and Onboard Monitoring Manual (OMM). During tests, continuous SOx emission monitoring system (if any), discharge water monitoring equipment, means for automatic recording and data processing are checked. For cleaning systems approved under Scheme B, functioning of the approved continuous SOx emission monitoring system is tested during operation of EGS system.

17.6.17.3 The operation of arrangements for engines change-over to low sulphur fuel oil (if any) is checked in accordance with the procedure for ship’s fuel-oil system preparation in a SOx emission control area.

17.6.17.4 Requirements for carbon intensity of ships.

For ships, to which the requirements for carbon intensity apply, the attained (actual) EEDI shall be verified at sea trials under the RS-approved programme in compliance with the IMO Guidelines (IMO resolution MEPC.365(79)). The attained (actual) EEXI shall be verified in compliance with the 2022 Guidelines on Survey and Certification of the Attained Energy Efficiency Existing Ship Index (EEXI) (IMO resolution MEPC.351(78)).

In case of ShaPoLi/EPL systems, which provide the possibility to override these limitations in the emergency cases (overridable system), the check in operation shall be carried out in compliance with the approved ship's guidelines on such systems and the 2021 Guidelines on the Shaft/Engine Power Limitation System to Comply with the EEXI Requirements and Use of a Power Reserve (IMO resolution MEPC.335(76) amended by IMO resolution MEPC.375(80)).

17.6.18 Instrumentation

17.6.18.1 When the systems and equipment referred to in 17.6.14 – 17.6.17 are subjected to tests in operation, operation of the instruments shall be checked simultaneously.

Documentation and/or brands of the instruments certifying that the mandatory periodical verifications have been performed by a competent body shall be checked.

17.6.19 Cargo vapour collection and discharge systems of oil tankers.

17.6.19.1 During the survey the following shall be checked:

.1 operation of the means for condensate removal at low points on the piping system ends;
.2 operation of shut-off valves of the vapour discharge manifolds;
.3 marking of the vapour discharge pipeline outputs.
17.6.20 Ballast water management systems.

17.6.20.1 After installation on board the ship performed in accordance with 17.4.23.1.4, the ballast water management systems shall be tested in compliance with IMO circular BWM.2/Circ.70/Rev.1. Upon results of acceptance tests performed in compliance with the requirements of the above-mentioned circular, a written report shall be submitted containing self-monitoring methods, results and information on self-monitoring parameters.
18 MOORING AND SEA TRIALS

18.1 GENERAL

18.1.1 The provisions of the present Section specify the procedure of technical supervision during mooring and sea trials of ships, machinery, arrangements, systems and equipment based under valid Rules for the Classification and Construction, Rules for the Equipment, as well as under the provisions of Part I "General Regulations for Technical Supervision" and of Part II "Technical Documentation" of the Rules for Technical Supervision.

For the purpose of defining the scope and methods of conducting trials, the provisions of appropriate sections of the Guidelines shall be followed accordingly.

18.1.2 The provisions of this Section shall be followed when considering programmes of mooring and sea trials when performing the trials, as well as when considering normative and technical documentation for trials of ships, machinery, arrangements, systems, equipment and outfit.

18.1.3 The Register technical supervision during trials of ships and equipment shall be carried out with the purpose of checking their compliance with the RS-approved (RS-agreed) technical documentation, rules and norms of the Register and also with the provisions of the international conventions applicable to a ship under construction.

18.1.4 The period of trials shall include the following stages of work:

.1 mooring trials;
.2 sea trials.

18.1.5 Preparation and trials shall be carried out by the shipyard. The results of this work, namely: entries in ship forms dealing with deslushing of the equipment, measurements tables of adjustment and alignment works shall be requested, where necessary, by the RS surveyor from the shipyard in advance of the commencement of mooring trials of relevant equipment.

The items of technical supervision shall be submitted for tests upon completion of all installation works and completion of main construction works, which are likely to affect the testing of the item.

The technical control body shall timely inform the RS surveyor of the readiness of the items of technical supervision for trials and of the date of their performance.

Surveys during trials of the item of technical supervision are carried out by the RS surveyor upon acceptance of the item by the technical control body.

18.1.6 Technical supervision of mooring and sea trials of ships, machinery, arrangements, equipment and outfit required by the relevant sections of the Guidelines shall be carried out by the surveyors of either the RS Branch Office supervising ship construction or another RS Branch Office as authorized by RHO.

18.1.7 Mooring and sea trials programme shall be developed, agreed and approved in compliance with the valid requirements of the Rules for the Classification and Construction, Rules for the Equipment, Rules for Technical Supervision and RS-approved technical documentation. The programme shall be approved by the Register in compliance with the provisions of Part II "Technical Documentation" of the Rules for Technical Supervision.

18.1.8 Mooring and sea trials shall be carried out under the mooring and sea trials programme approved by the Register; meanwhile, programmes for special purpose or design or type ships under construction in the countries where no RS Branch Offices available shall be considered by RHO; in all other cases, programmes shall be considered by the RS Branch Office.

18.1.9 In the programme for any kind of ship machinery, arrangements, systems and equipment the following technical requirements shall be indicated and necessary explanations, descriptions and methods shall be specified:

.1 conditions under which the tests shall be performed;
.2 scope of tests;
.3 duration of modes of operation;
Additional requirements for the contents of the programme for mooring and sea trials of internal combustion engines are given in Appendix 7 to Section 5, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision.

18.1.10 The programme for mooring and sea trials shall specify the technological requirements relative to integrated trials of machinery, arrangements, systems and equipment, relative to use of simulating and instrumental methods of checks, relative to use of special power sources, etc. In this case the possibility of using simulating methods of trials and special power sources shall be agreed with the Register upon submission of the relevant technical background.

When testing the shipboard equipment, which consists of a number of machinery, arrangements, systems and apparatus (for example, propulsion plant (PP))\(^1\), the programme shall specify simultaneous trials on preset modes of all machinery, systems, arrangements and apparatus contained in this system.

18.1.11 The programme for mooring and sea trials shall take into account the requirements of standards and technical documentation relative to delivery, and also the requirements of the firm's (manufacturer's) programmes for trials of the delivered equipment.

When there are methods available for trials agreed with the Register, the programme for mooring and sea trials shall contain references thereto.

The shipyard's documents issued upon the results of mooring and sea trials shall include measurements regulated by the relevant sections of the Guidelines, agreed standards, programs of firms (manufacturers), etc., as applicable.

18.1.12 Unless other terms of delivery are specified, the shipyard building the ship is responsible for safety during trials and safety of the ship itself.

The shipyard building the ship organizes performance of trials and conditions preventing any influence on trials results as well as ensures compliance with the requirements for safe navigation.

The shipyard constructing the ship shall provide for all necessary conditions for technical supervision by the RS surveyor in the course of mooring and sea trials in compliance with the requirements of the applicable RS rules and the Guidelines, and ensures the following:

| .1 | ship and shipyard communication facilities; |
| .2 | transport means. |

18.1.13 The equipment provided by the shipyard for use during the trials shall be operated in conformity with the technical operation regulations and maintenance instructions.

The RS surveyor is not entitled to operate the equipment himself/herself or interfere with the actions of the attending personnel. In case actions of the personnel may cause an accident or damage to the equipment, the RS surveyor is entitled to demand, via representatives of the technical control body, elimination of violations (up to the refusal to participate in the ongoing tests).

18.1.14 In the course of the trials any works disturbing the normal procedure of trials or being of any danger to participants shall be excluded. The equipment under trials, as well as the space around shall be clean and free of any obstacles; provision shall be made of proper illumination and ventilation of the spaces.

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\(^1\) This shall include main engines, shaftings and propellers with gears, bearings, and couplings, as well as auxiliary machinery, systems, arrangements, boilers, pressurized vessels, etc.
18.1.15 The items of technical supervision, which trials results do not meet the requirements of the applicable RS rules or the RS-approved documentation, shall be subjected to repeated trials after elimination of causes of unsatisfactory trials results.

18.1.16 Elimination of deficiencies and retesting shall be agreed upon with the RS surveyor. Retesting shall not affect further tests or interfere with there safely.

18.1.17 Measurements, which are taken by the technical control body and ascertain that the item of technical supervision is in good working order, shall be processed by the technical control body upon completion of the trials of the item of technical supervision and submitted to the RS surveyor.

In case of satisfactory results the RS surveyor signs the shipyard's document on completion of trials of the items of technical supervision, to which the tables of measurements are appended, where necessary.

18.1.18 An interruption in the trials of items of technical supervision under continuous modes shall be indicated in the test report, and a matter of continuation of the trials and the conditions of their performance (extension of time period and scope) shall be agreed upon with the RS surveyor, having regard to the causes of trials termination.

In case of the second forced interruption of the same continuous testing mode, the tests shall be terminated and the causes eliminated. Then repeated tests shall be conducted in full or extended scope, where necessary. The time for tests performance shall be agreed upon with the RS surveyor.

18.1.19 Trials of items of supervision shall be interrupted in the following cases:

.1 where faults or defects of items of supervision are found;
.2 where the item of supervision is in emergency condition;
.3 in case the meteorological conditions get worse and it interferes with further performance of the tests, distorts the test results, affects safety of first performance and safely of the ships.

Decision about suspension of the trials depending upon the causes shall be taken by the RS surveyor or shipyard (as agreed with the RS surveyor).

Irrespective of the person who has taken such a decision, the item of supervision is subject to re-testing the duration and scope of which shall be agreed with the RS surveyor.

18.1.20 In case of suspension of tests of the item of supervision at the RS surveyor’s request or on agreement with the RS surveyor, the report is drawn up wherein the causes of such suspension of tests, requirements for correction of the stated causes prior to re-testing and re-testing conditions shall be contained.

18.1.21 The ship may have such items of supervision installed on board, which have not been tested in full scope by the firm (manufacturer), provided that they shall be tested under special programme agreed with the Register, with subsequent tests under the programme of mooring and sea trials.

The above requirement applies to the prototype ships and to ships of a series.

18.1.22 The RS surveyor shall not participate in the ship commissioning work of the acceptance commission.
18.2 MOORING TRIALS

18.2.1 Mooring trials shall be carried out in order to check the following:

1. arrangement, completeness, quality of installation, adjustment and serviceability of the propulsion and auxiliary machinery, arrangements, systems, equipment and outfit as well as compliance of their parameters with the requirements of the RS-approved technical documentation;

2. readiness of the ship, its propulsion and auxiliary machinery, arrangements, systems and equipment for the sea trials.

18.2.2 Fulfilment of the requirements for certain items of technical supervision, on agreement with the RS Branch Office, may be transferred (in exceptional cases) to the period of the sea trials or some other time, provided these requirements do not interfere with the sea trials or affect the safety of ship navigation and people on board.

18.2.3 In case the ship is not ready for sea trials according to the RS Branch Office, the RS Branch Office, prior to sea trials, shall send a notification addressed to the shipyard which contains the objective justification for such opinion.
18.3 SEA TRIALS

18.3.1 Sea trials shall be conducted with the following purpose:
   .1 checking of basic parameters of ship main propulsion plant and their compliance with the specification characteristics;
   .2 checking of operation of the main propulsion plant in the ship's ahead and astern manoeuvring;
   .3 checking reversing properties of the main propulsion plant;
   .4 checking of serviceability of the main propulsion plant in the conditions approximate to the operating ones;
   .5 checking of serviceability of the deck machinery and arrangements;
   .6 comprehensive checking of the ship's automation equipment (if any) under the conditions approximate to the operating ones;
   .7 final tests of items of technical supervision, other than those subject to the inspection and subsequent check tests;
   .8 checking of serviceability of navigational, radio and electrical equipment under the conditions approximate to the operating ones;
   .9 measurements of torsional vibration of the "main engine – shafting – propeller" system, measurements of vibration;
   .10 for ships, to which the requirements for the Energy Efficiency Design Index (EEDI) apply, validation of the attained EEDI in compliance with the IMO Guidelines (IMO resolution MEPC.365(79));
   .11 confirmation of the possibility to assign the ship the Register class provided in the design to the ship according to its purpose, and the possibility to issue the Register documents.

18.3.2 In case the Register confirmation of the ship readiness for sea trials is required by port authorities to issue a sea trial permit, the Register may issue an appropriate confirmation, on the shipyard's written inquiry, in which preparation the following shall be considered:
   .1 confirmation shall be drawn up in an arbitrary form on the RS official letter form (using form 6.3.10 or form 3.1.11, or on the letter form upon agreement with the shipyard);
   .2 confirmation shall include the statement that in accordance with specific contract on technical supervision, all new construction surveys of the Register have been completed and, according to the Register, the ship may be considered ready for sea trials.

18.3.3 Prior to the commencement of sea trials the shipyard shall submit to the RS surveyor the following documentation:
   .1 programme of sea trials, including tests for validation of the attained EEDI (if applicable), approved by the Register;
   .2 technical documentation necessary for surveys and trials;
   .3 Stability Booklet and Damage Stability Booklet, developed as per results of inclination or light-weight check (for the ship of a series);
   .4 designed Stability Booklet and Damage Stability Booklet, inclination report (for the prototype ship).

18.3.4 Upon completion of sea trials or trials in the rate of speed with no ship's speed using simulation methods, the RS surveyor shall inform the shipyard of his comments pertaining the work that shall be done before the ship's documents may be issued by the Register.

18.3.5 Necessity of the additional sea trials shall be agreed with the RS surveyor and, generally, shall be determined by the following conditions:
   .1 where the parameters determining proper operation of the item of technical supervision can be received in the course of the additional sea trials only;
   .2 where, as a result of mooring and sea trials, the replacement of the whole item of supervision or some of its essential parts is required which serviceability may be confirmed only in the course of the additional sea trials;
.3 where it is impossible to attain the required rates by means of simulation, or where such means are not available.

18.3.6 Satisfactory results of the surveys performed under the List, no violation of the RS requirements upon results of the patrols, mooring and sea trials shall be the basis for drawing up the report (acts) on survey of the ship, on which basis the ship's documents are drawn up by the Register.
18.4 PARTICULARS OF TECHNICAL SUPERVISION OF TRIALS OF THE PROTOTYPE SHIPS

18.4.1 Trials of the prototype ship shall be carried out under the comprehensive programme including verification of characteristics and determination of parameters which may be used for ships of a series with no such verifications.

18.4.2 The comprehensive programme of trials of the prototype ship shall contain the following:

.1 measurements of torsional vibrations in the "engine – intermediate unit (shafting, reduction gear, couplings) – propeller system";
.2 measurements of vibration of machinery and equipment in accordance with Section 9, Part VII "Machinery Installations" of the Rules for the Classification and Construction;
.3 experience of inclination;
.4 checking operation of the propulsion plant with one main ICE with regard to provision of the ship speed at which the ship steering is maintained with failure of one turbocharger (as to emergency mode of the main engine refer to 2.5.1, Part IX "Machinery" of the Rules for the Classification and Construction;
.5 increase of duration of testing modes.

18.4.3 In case a list of arrangements to be made or recommended for use in the following ships of the series is elaborated upon completion of the prototype ship trials, such list shall be agreed upon with the Register.

18.4.4 Where necessary, having regard to the purpose of the ship and in case of using prototypes of materials, products, machinery and equipment, and in other justified cases, the Register documents shall specify operational tests under the RS-approved programme (refer also to 1.8, Part IV "Technical Supervision during Manufacture of Products" of the Rules for Technical Supervision).
18.5 TRIALS OF SHIP MACHINERY AND EQUIPMENT USING SIMULATION METHODS AND MEANS

18.5.1 Scope of application.
18.5.1.1 The provisions of this Chapter shall apply in trials of the ship's machinery and equipment using simulation methods and means permitting sea modes that shall be conducted in the shipyard water area or on the slip.
18.5.1.2 Simulation means or methods of trials suggested for the first time or not adequately verified in technical supervision practice, and also not complying with the requirements of this Chapter to the full extent shall be agreed with the Register in each particular case upon submission of the relevant technical background.
18.5.1.3 The provisions of this Chapter do not apply to the prototype ships and prototype specimens (prototype batches) of machinery, equipment and other products.

Note. Adjustment of simulating methods and means and comparison tests (refer to 18.5.3.13) may be conducted for the prototype ships of a series, unless it is further expressed otherwise.

18.5.1.4 Simulation tests shall be carried out both for separate kinds of ship machinery and equipment, and for the whole set of the ship's equipment.

18.5.2 Definitions and explanations.
18.5.2.1 Simulation tests are trials in sea modes/regimes (in the modes of full-scale conditions) in the water area of the shipyard or on the slip replacing the equivalent sea trials specified by the RS rules.

Simulation methods and means are methods and means permitting in the water area of shipyard or on the ship the conditions appropriate to the routine tests to be reproduced (to the maximum extent or to the sufficient extent recognized by the Register).

Routine tests are tests specified by the RS rules which are not simulating ones.

Comparison tests are checking of compliance of loadings and parameters of the ship's equipment operation received from the simulation tests with those of the same equipment received in the conditions of sea trials at the voyage on board the same ship.

18.5.3 General.
18.5.3.1 Expediency and methods of simulation tests shall be determined by the shipyard and designer.
18.5.3.2 Matters of tests not specified in this Chapter shall be settled in compliance with the provisions of relevant sections of the Guidelines.
18.5.3.3 In the course of simulation tests special arrangements, benches and proving grounds, appliances, apparatus, special devices and other means may be applied, and calculating methods and graphical diagrams are used as well.
18.5.3.4 Simulation methods and means shall be in conformity with standards agreed by the Register and RS-approved technical documentation.

Application of non-standard methods and means shall be agreed with the Register in each particular case upon submission of the relevant technical background.
18.5.3.5 Where necessary, a diving examination shall be performed with issuance of the adequate report.
18.5.3.6 Ship's preparation for trials including its placing in the shipyard water area or on the slip, manufacture, mounting (dismounting) of simulation arrangements, as well as appliances and equipment relevant thereto are subject to the shipyard responsibility, and not within the Register technical supervision.

Methods of simulation tests shall be approved by RHO or on its behalf by the RS Branch Office.
18.5.3.7 Simulation tests shall ensure verification of the ship's operation in the course of sea trials in the scope within the requirements of the RS rules and the provisions of appropriate sections of the Guidelines.

Where simulation methods and means ensure such conditions which more comprehensively reproduce features of real service than the routine tests, it is necessary that the test scope and modes shall be, as practicable and reasonable, extended as compared with those specified in this Part (for example, with the purpose of verifying designed parameters or specifications).

18.5.3.8 Simulation appliances, their securing means and influence caused by them (vibration, temperature, etc.) shall not have harmful influence upon the tested item or on the ship's structures. Where necessary, measures protecting from harmful influences shall be provided.

18.5.3.9 When carrying out simulation tests, parameters of the tested item shall be verified in the scope not less than that one specified for routine tests.

Where simulation tests are carried out not for the whole set of the ship's equipment or where in the course of these tests only some of their parameters are defined, the rest of the equipment (the remaining parameters) shall be verified by routine parameters.

The accuracy of the tests under way shall be not less than one assumed in routine tests and recognized by the Register as satisfactory.

18.5.3.10 Standard programmes (methods) of simulation tests are subject to the approval either by RHO or the RS Branch Office when authorized.

Programmes (methods) of a particular ship developed on the basis of the standard ones shall be agreed with the RS Branch Office (surveyor).

18.5.3.11 The Register, where necessary, may require routine tests that shall be carried out on board any ship under the approved programme irrespective of results of simulation tests.

18.5.3.12 Prior to the simulation tests comparison tests shall be carried out.

18.5.3.13 Comparison tests.

18.5.3.13.1 Comparison tests shall be carried out by the shipyard under the RS-approved programme (methods) supervised by the RS surveyor.

These tests consist of the tests using simulation methods and means as well as sea trials at the voyage conducted on board the same ship.

Comparison tests aim at verification of compliance of loadings and/or parameters of the ship's equipment operation received by simulation methods and means with the loadings and parameters of this equipment's operation received in the course of sea tests under real navigation conditions, as well as compliance with the requirements in 18.5.3.8.

18.5.3.13.2 The programme (methods) of comparison tests shall include the following:
- explanation part containing theoretical basis of assumed simulation method (drawings) of simulation arrangements and other appliances and their securing to tested items, schemes of proving grounds, information about the number of ships that shall be subject to comparison tests;
- provisions on checking of quality of mounting of simulation means, where necessary, indications on preliminary tests by simulation methods in the course of mooring modes;
- indications on the simulation stage of comparison tests including indications on control and measurements of parameters as well as concerning values of controlled parameters;
- indications on the stage of routine tests carried out for the comparison, including indications on control and measurements of parameters;
- indications on the comparison of the required convergence of parameters received at the stages of simulation and routine tests.

18.5.3.13.3 In the course of comparison tests special attention shall be drawn to the received values of compared parameters and the ship's equipment operation characteristic during two stages of the tests, also the extent of their convergence shall be analyzed.

The tests are considered satisfactory if the operation of the ship's equipment during the two stages of the tests is in compliance with the Register requirements, criteria and norms laid down in the RS-approved technical documentation and the compared results are, to the sufficient extent, convergent.
18.5.3.13.4 On the basis of results of the comparison tests the surveyor shall prepare the Report (form 6.3.29) where necessary data on the conducted tests are contained and make his conclusion about the possibilities of simulation tests on board ships of subsequent construction as a whole or some particular kinds of ship equipment. In lieu of issue of the Report, the shipyard document may be agreed upon.

18.5.3.13.5 Generally comparison tests shall be carried out at least on board two ships. Where results of the comparison are unsatisfactory though at one of the stages or the comparison of results show no required convergence, the comparison tests shall be considered unsatisfactory.

18.5.3.13.6 Results of comparison tests are not applicable to items of another type (type and size) or the same type but installed on board ships of other series, as well as on board ships of the same design but being constructed by different shipyards. The question of possible application of testing results to ships of various modifications of the same base design, which are under construction in the same shipyard shall be agreed with the Register in each particular case.

18.5.3.14 Simulation tests.

18.5.3.14.1 Simulation tests shall be carried out under the RS surveyor supervision under the programme (methods) prepared on the basis of comparison tests and approved by the Register.

18.5.3.14.2 Methods of simulation tests shall contain the following:

- general provisions;
- requirements for technical condition of the item submitted to tests;
- requirements for technical condition of simulation means and other supporting equipment;
- method indications on preparation for tests and their performance including the control and measurements of parameters which shall be attained with the help of simulation methods and means;
- diagrams of simulation arrangements and proving grounds;
- indications on control comparison tests and their frequency (refer to 18.5.3.16).

Note. The appropriate provision for control comparison tests and frequency shall be introduced in the ship's testing programme when updated.

18.5.3.14.3 Prior to simulation tests it is necessary to get assured that the ship's equipment has successfully undergone mooring trials, and nothing prevents from simulation tests.

The RS surveyor also shall inspect the following: availability of the document from the shipyard technical control body concerning the condition of simulation means;

availability of the RS-approved programmes (methods) of simulation tests or indications on simulation tests in the ship's approved programmes of mooring or sea trials and compliance with the requirements specified therein as to the preparation for tests.

18.5.3.14.4 In the course of simulation tests the RS-approved program (methods) and indications laid down in this Chapter as to the kind of the ship's equipment shall be followed.

Attention shall be drawn to the reliability of operation of simulation means. Adjustment and setting of simulation means not specified by the testing programme (methods) shall not be allowed.

18.5.3.15 Inspection and trial voyage.

18.5.3.15.1 Where routine tests are provided with the purpose of check of a part of the equipment and its separate modes (refer to 18.5.3.9), the inspection of the ship's equipment which has passed simulation tests shall be carried out and certified by the RS surveyor prior to the ship's voyage, and the control check of the equipment shall be exercised during its operation as per the direct designation.

18.5.3.15.2 In the course of simulation tests of the whole set of the ship's equipment inspection may be carried out and certified by the RS surveyor on completion of the simulation tests with the subsequent verification of the equipment operation during the ship's trial voyage.
In technically grounded cases (with the Register agreement) the ship’s trial voyage may be replaced by simulation tests of the ship's Register. In this event it is those simulation methods and means shall be used that have been applied for the verification of sea modes.

18.5.3.16 Check comparison tests.

18.5.3.16.1 On ships of serial production being tested by simulation methods check comparison tests shall be regularly carried out as specified in 18.5.3.13.1.

The tests shall be carried out on each fifth ship under the shipyard annual acceptance programme for up to 10 ships, and on each tenth ship under the manufacturer's annual acceptance programme 10 ships and over.

18.5.3.16.2 During the two stages of check comparison tests the RS surveyor shall carry out surveys and inspections in the scope not less than those specified for routine tests of ships of a series. Results of check comparison tests (refer to 18.5.3.13.3) shall be analyzed and compared with the results of the previous ship of the series, conclusion is drawn about the possibility of simulation tests on ships of subsequent production.

The requirements in 18.5.15 and 18.5.3.16.1 are reflected in the ship's testing programme.

18.5.4 Propulsion plants.

18.5.4.1 Indications as per tests.

18.5.4.1.1 Simulation tests of propulsion plants may be carried out on ships of all types and purposes (except for ships with air propulsion) in case when performances of the main engine on the mode of nominal (full) power and frequency of rotation may be reproduced with the immobile ship with the help of simulation means and methods.

18.5.4.1.2 Simulation tests of propulsion plants may be carried out with the help of simulation methods and means both with the ship afloat in the water area of the shipyard and on the slip.

18.5.4.1.3 Simulation arrangements shall ensure reproduction of the preset power and rotation frequency of the main engine on all modes of operation specified in the programme of simulation tests, and stable operation of the main engine on all modes.

18.5.4.1.4 Comparison tests of propulsion plants shall specify the following:

- simulation tests on loadings and parameters propulsion plants received in the course of sea trials of the prototype ship carried out under the Register-approved programmes;
- sea trials of the same ship at sea with maximally attained loadings of the main engine.

Results of comparison tests are considered satisfactory where parameters of propulsion plants under the loadings being similar, have sufficient convergence, and their operation is considered satisfactory.

18.5.4.1.5 The scope of surveys conducted by the RS surveyor in the course of simulation tests including the list of measured parameters, frequency and accuracy of measurements, methods and scopes of the control of technical condition and operation of propulsion plant, its auxiliary machinery, arrangements and systems, as well as the stern tube and shafting is similar to the scope of surveys in the course of routine tests which is indicated in appropriate chapters of this Section.

18.5.4.1.6 With the Register agreement the main engines may not be subject to mooring trials in compliance with the requirements of this Section unless their structural features and structural features of components involved in the propulsion plant require mooring trials prior to simulation ones; in this case, however, after completion of adjusting and setting works and until simulation tests the main engines shall be previously tested on the 100 % mode for 4 h at least (depending upon the main engine type and output).

18.5.4.1.7 In the course of simulation tests divergence from given values of power and rotation frequency is not to exceed: as to power – ±5 %, as to rotation frequency – ±3 %. On the mode of nominal and maximum loadings the power divergence is admitted in the reducing direction down to 5 % of the rating.

18.5.4.1.8 In the course of simulation tests of propulsion plant in the shipyard water area the ship's draught shall be constant on each testing mode.
The ship's inclination is admitted to be not more than 5° – for single-screw ships, 1° – for double-screw ships.

18.5.4.1.9 The ship shall be fitted with all necessary system of power supply (gas line, electric power supply, heating, lining and piping of cooling water, water supply to the ship's fire-extinguishing system), as well as technical service of tests shall be performed by the shipyard.

18.5.4.1.10 Upon the agreement with the RS surveyor, for receipt of the required data in the course of simulation tests it is admitted to adjust the simulation arrangement without stopping the propulsion plant, mode adjusting time is not taken into account.

18.5.4.1.11 In the course of simulation tests the load of main engines operating the fixed-pitch propellers shall change in propeller characteristics \( N_c = f(n) \), \( M_{tm} = f(n) \), and operating controllable pitch propellers and generators shall change in loading characteristics like as follows: \( N_c = f(H/D) \), \( N_c = f(M_{tm}) \) where \( n = \text{const rated power} \), \( N_c \) is a rated power; \( M_{tm} \) is nominal engine torque; \( n \) is engine shaft rotation frequency; \( H/D \) is controllable pitch propeller ratio.

Modes of engine loadings in this case shall comply with those indicated in Table 18.5.4.1.11 (refer also to the Appendix to Section 5).

<table>
<thead>
<tr>
<th>Mode No.</th>
<th>Engine torque, in % from nominal value</th>
<th>Rotor shaft rotation frequency, in % from nominal value</th>
<th>Duration of tests, in h</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>39</td>
<td>63</td>
<td>0,5</td>
</tr>
<tr>
<td>2</td>
<td>83</td>
<td>80</td>
<td>0,5</td>
</tr>
<tr>
<td>3</td>
<td>83</td>
<td>91</td>
<td>0,5</td>
</tr>
<tr>
<td>4</td>
<td>100</td>
<td>100</td>
<td>4,0</td>
</tr>
<tr>
<td>5</td>
<td>107</td>
<td>103</td>
<td>1,0</td>
</tr>
<tr>
<td>6</td>
<td>Speed astern</td>
<td>Complying with rated power of speed astern</td>
<td>0,5</td>
</tr>
<tr>
<td>7</td>
<td>–</td>
<td>Minimally stable</td>
<td>0,25</td>
</tr>
</tbody>
</table>

18.5.4.1.12 Upon completion of simulation tests, inspection of machinery, arrangements and systems shall be carried out. The scope of inspection and list of units subject to dismantling and examination shall be determined upon the RS surveyor agreement.

After completion of inspection and elimination of deficiencies revealed during the previous stages of tests and during the inspection the propulsion plant shall be checked in the course of check tests on the modes indicated in Table 18.5.4.1.12; in this case, generally, the operation of all components of the propulsion plant shall be checked in its operation as designated, however, where necessary, essential thermal parameters of the plant shall be controlled. Parameters of the propulsion plant in its 100 % power shall attain stable values.

<table>
<thead>
<tr>
<th>Mode No.</th>
<th>Rotor shaft rotation frequency, in % from nominal value</th>
<th>Duration of tests, in h</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>100 (full speed)</td>
<td>2,0</td>
</tr>
<tr>
<td>2</td>
<td>Speed astern</td>
<td>0,25</td>
</tr>
</tbody>
</table>

18.5.4.1.13 Check tests of the propulsion plant may be carried out both in the course of the ship's sea trials in open water (trial voyage) and with the help of simulation methods if they provide the check of reverses and also astern speed modes in accordance with Tables 18.5.4.1.11 and 18.5.4.1.12.

18.5.4.1.14 Check tests of propulsion plants, which simulation tests have been carried out on the slip, shall be conducted on the ship under way in open water or, when agreed with the surveyor, in mooring mode in the shipyard water area; in this case particular attention shall be drawn to the serviceability of sea-water pumps and ship systems servicing the propulsion plant.

18.5.4.1.15 Specified in 18.5.4.1.13 reverse verifications in the course of check tests using simulation methods are recognized as adequate in the event of reversing from the local control station or by means of the remote control.
Checking of reverses by means of the remote automatic control system shall be carried out with the ship under way.

18.5.4.2 Simulation methods and means of loading.

18.5.4.2.1 The place of testing, type of rudder-propeller system, ship’s aft draught, rotation power and frequency of the main engine are basic factors, which determine the choice of simulation methods. The following possibility shall be allowed for:

- reproduction of the given power and frequency of rotation with the preset characteristics of propeller, stern counter structure and aft draught changing range;
- mounting and dismantling of the loader on the slip or the ship afloat;
- accepting of the propeller thrust by the hull structure, mooring appliances, etc.;
- duration of operation with full loadings without any choking of engine cooling systems.

18.5.4.2.2 The following simulation methods and facilities of loading may be applied:

1. partially submerged propeller, if there is a possibility to vary deepening of the propeller axis of ships with insufficiently submerged propellers ( \( H < 0.6D_p \) ) afloat ( \( H \) is distance from the propeller axis up to the water surface, \( D_p \) is propeller diameter);

2. varied blade pitch of controllable pitch propeller— for ships with the controllable pitch propeller afloat when the propeller axis is deepened not less than 0.6\( D_p \);

3. supply of air to the propeller by means of air supplying arrangements of different design — for ships with deepened propeller axis not less than 0.6\( D_p \) afloat with not restricted power;

4. regulated volume of air suctioned to the water flow coming to the propeller — for ships afloat with ring propellers and deepened propeller axis not less than 0.6\( D_p \);

5. regulated restriction of ambient air to the propeller from the water surface — for ships afloat having insufficient deepening of the propeller axis (within 0.3 – 0.6\( D_p \)) and with main engine not more than 3680 kW;

6. loading arrangements reducing operated propeller disk area by means of blades tips excluded from operation — for ships with sufficiently deepened propeller axis (not less than 0.6\( D_p \)), free-positioned propeller of diameter not more than 3,5 m and main engine power not more than 2944 kW afloat;

7. hydrochamber distributing and regulating water flows coming to the engine and thrown by it — for ships of not more than 12 m long with propellers and water-jet propulsion installations of 220,8 kW on the slip;

8. hydroloaders fitted instead of the propeller and providing rated loadings affecting operated bearings, axial thrust and deformation of shafting — for ships with propeller power from 73,6 to 736 kW on the slip;

9. breaking bench connected to the propeller and providing rated loadings affecting shafting bearings, its deformation and axial thrust — for ships with propeller power not more than 73,6 kW on the slip;

10. other simulation methods and loading facilities, which may be admitted by the Register on special agreement.

18.5.5 Arrangements.

18.5.5.1 Rudder and steering gear.

18.5.5.1.1 In the course of simulation tests of rudder and steering gear the rudder blade or steering nozzle\(^1\) shall be subjected to loadings resulting in rudder torque on the rudder stock, equal to those occurring in the course of sea trials with different helm angles and the ship appropriate speeds.

\(^1\) Hereinafter referred to as “the rudder”.
18.5.5.1.2 Loadings on the rudder may be created by the following:
   .1 water jet thrown by the propeller;
   .2 special loading arrangements;
   .3 combined actions of the above stated factors.

18.5.5.1.3 In the course of simulation tests the indications specified in 3.4.3 shall be satisfied taking into account the information set forth below.

The main, auxiliary and emergency gears shall be subjected to tests when running ahead and astern. Where the rudder and steering gear is of such a design that the rudder torque at the rudder stock when run astern is more than ahead, the tests shall be carried out with the characteristics of the speed astern. Concerning the automatic pilot, refer to 18.5.6.3.6.

18.5.5.1.4 In the course of comparison tests of rudder and steering gear in accordance with 18.5.3.13 the rudder torque shall be measured directly at the rudder stock.

Measurement and comparison of the pressure in hydrocylinders for hydraulic (electrohydraulic) steering gears or the current intensity for electric gears may be allowed; in this case the varying character of the pressure and current intensity depending on helm angles and turning time at the stage of simulation tests shall be corresponding to the data proceeding in the course of routine tests.

Convergence of results (difference of parameters values at the stages of simulation and routine tests) shall not exceed the following:

As to oil pressure — 5 %, as to current intensity 10 %, as to turning time — 10 %.

18.5.5.1.5 Water jet tests shall be conducted by means of hydrodynamic forces applied to the rudder which are caused by the propeller in the main engine operating conditions, and in case of the controllable pitch propeller with the help of blades turning.

18.5.5.1.5.1 Prior to the tests of rudder and steering gear the main machinery, shafting and propellers shall be surveyed in the scope of sea trials.

18.5.5.1.5.2 The ship shall be positioned in the shipyard water area and reliably secured. Among the materials stated in 18.5.3.14.2 the scheme of the ship's position and calculations of its securing are available.

18.5.5.1.5.3 If under the testing conditions the rudder loading is not sufficient, it shall be increased up to that of the sea trials. With this purpose the rudder area may be increased by means of a temporary additional attachment placed thereon. The width of temporary attachment shall not exceed 0.25 width of the rudder blade, and the coefficient of the rudder compensation shall not exceed more than 25 – 30 %.

18.5.5.1.6 Tests with the help of loading arrangements may be carried out both on the ship afloat and on the slip. Loading arrangements shall provide the change of the rudder stock depending on the angle of helm turning by means of appropriate mechanical forces applied to the rudder.

Structure of loading arrangements shall exclude the possibility of rudder deformations in way of the applied forces equivalent to water pressure. The applied forces shall be distributed over the area, if possible.

18.5.5.1.7 Where loading arrangements in the form of hydraulic loaders are applied, and rudder forces are transferred by hydrocylinders piston rods, the pressure and, accordingly, the force to the rudder shall be adjusted by the hydraulic system relief valve in compliance with the conditions of tests or by any other way.

Pressure of the service liquid in hydraulic cylinders of the loading arrangement shall be determined by calculations for each of the testing conditions proceeding from the rudder stock designed moment when operated by the main and emergency gears. Calculations shall be introduced among the materials stated in 18.5.3.13.2. The pressure final value may be ascertained in the course of comparison tests.
18.5.5.1.8 In case of loading arrangement operated by the effect of cargoes determination of cargoes mass and rope-and-block system scheme shall be reproduced among the materials stated in 18.5.3.12. The final cargo mass may be ascertained in the course of comparison tests. Prior to the commencement of tests the shipyard shall submit the Report of Compliance of the Cargo Mass with the Indications of Testing Methods. Preference is given for application of monolithic cargoes.

Mild steel ropes shall be used for the arrangement. Beams, frames, shackles, swivels and other components of rope-and-block system shall be in conformity with each other and comply with the requirements of standards.

18.5.5.2 Anchor arrangements.

18.5.5.2.1 Simulation tests of anchor arrangements may be conducted on the anchor arrangements with the chain diameter not more than 50 mm having no remote control. Application of simulation tests to anchor arrangements with chain diameter equal to 50 mm and over, as well as those having remote control system shall be agreed with the Register in each particular case upon submission of the relevant technical background.

18.5.5.2.2 During simulation tests the indications specified in 3.5.4 shall be met allowing for the following factors set forth below.

18.5.5.2.3 With the help of methods and facilities of simulation the following factors occurring in routine tests shall be reproduced:

- stresses in the anchor chain;
- speeds including anchor chain paying out speeds when releasing the anchor;
- kinetic energy in the "anchor-anchor chain" system when releasing the anchor.

18.5.5.2.4 The kinetic energy ensuring the check of the band brake shall be reproduced with disconnected drive of anchor machinery from the sprocket by its maximum values corresponding to the condition when the anchor chain is released to the depth specified in 3.5.4.1 of the Guidelines and in motion with the speed specified in 6.3.3.3, Part IX "Machinery" of the Rules for the Classification and Construction.

18.5.5.2.5 During comparison tests of the anchor arrangements in accordance with 18.5.3.13 the comparison of stresses in the anchor chain at the stages of simulation and in routine tests shall be made by the way of correlation of current intensity of the electric drive and paying out speeds of the anchor chain. Convergence of results shall not exceed: as to the current intensity – 8 %, as to the speeds – 5 %. Determination of parameters by means of which the kinetic energy shall be correlated, shall be provided by the operator developing the comparison tests programme; the documents grounding that these parameters correlation ensure reproduction of the kinetic energy under the conditions of comparison tests shall be submitted to the Register.

18.5.5.2.6 Loading arrangements used for simulation tests shall provide the following operations:

- free release of anchors;
- haulage of anchors in succession;
- haulage of two anchors from a depth of not less than 45 m;
- breaking the anchor out the ground from a depth not less than 82.5 m;
- check of braking operation including automatic brakes of the drive (if available).

18.5.5.2.7 Where loaders are applied with chain sprockets and braking arrangements, as loading elements, the sprockets shall correspond to the anchor chain diameter, and the sprocket wrapping angle shall be not less than that required for the anchor machinery by the Rules for the Classification and Construction. The pull on the sprocket shall be adjusted and ensure anchor chain paying out speed up to 200 m/min.

Braking of sprocket by means of a brake shall be smooth and be adjusted so that the braking forces shall correspond to the mass of anchor chain and anchor overboard.

18.5.5.2.8 When constructing ships of large series productions with gross tonnage less than 100, not engage in international voyages, except for the ships for carriage of passengers or combustible or other hazardous cargoes, as well as towing boats simulation tests of anchor
arrangements specified in 18.5.5.2.9 and 18.5.5.2.10 may be applied with the Register special agreement. Such tests are possible provided if the Register has ascertained that anchor arrangements are manufactured with high quality, and this has been proved by routine tests of at least ten ships of the serial production.

18.5.5.2.9 Tests by means of hung over loads shall be carried out on the maximum depth of the shipyard water area, however not less than 10 m.

18.5.5.2.9.1 Tests under 3.5.4.1, 3.5.4.5 and 3.5.4.6 shall be carried out using anchors with loads attached thereto that compensate insufficient mass of anchor chains and anchors corresponding to the necessary depth of the place. For each operation not less than 8 – 10 anchor releases-and-haulages shall be carried out.

18.5.5.2.9.2 Average speed of chain paying out, m/min, shall be determined by the formula

\[
\gamma = 6nL/t \quad \text{(18.5.5.2.9.2-1)}
\]

where \( n \) = sprocket torque frequency of the anchor arrangement, in \( \text{min}^{-1} \); \( L \) = chain cable length passed for the sprocket's one turn-round which is determined by the formula

\[
L = 2d(4z + 1)10^{-3} \quad \text{(18.5.5.2.9.2-2)}
\]

where \( d \) = anchor chain diameter, in mm; \( z \) = number of cams in a sprocket.

18.5.5.2.9.3 In the course of tests, apart from that specified in 3.5.4, the hung over loads mass and also easy operation of all elements of the loading arrangement shall be controlled.

18.5.5.2.10 In the course of tests with the anchor chain tensed by the ship's running, stresses and speeds occurred in the units and elements of anchor arrangements, including anchor machinery, are aroused by the speed astern operated propeller. The loading shall be adjusted by varying of the rotation frequency of the propeller or by means the controllable pitch propeller. During tests of anchor arrangements on non-self-propelled ships towing boat or any other loading methods may be used.

18.5.5.2.10.1 Apart from the above stated in 3.5.4, it is necessary to be convinced of the following.

Anchor release shall be carried out at speed astern with subsequent anchor pay out at the full length and (after the anchor reliably grounded) with periodical braking by means of the anchor machinery brake. With clamped brake for 1 – 2 min the operation shall be maintained with the propeller. The last braking shall be performed with the clamped brake at the beginning of the last shot and with the stress of tensed chain corresponding to the mass of fully paid out anchor and chain free in water. Chains haulage shall be performed by the anchor machinery concurrently with the ship's running speed astern (the anchor is reliably moored aground) by means of forces corresponding to the mass anchors and anchor chains at the conditional depth of the ship's lying. Simulation of anchor breaking out of the ground shall be carried out at the largest speed of paying out at speed astern and with holdine for 3 – 5 s and subsequent transfer of speed to "stop".

18.5.5.2.10.2 The ship's speed (frequency of shaft rotation or position of blades of controllable pitch propeller) at which a loading is created equal to that one during routine tests shall be determined by means of comparison tests; in this case, amendments may be introduced allowing for current speed, wind direction and force.

18.5.6 Radio and navigational equipment.

18.5.6.1 In the course of simulation tests the appropriate provisions in Sections 15 and 16 for routine tests shall be followed and the requirements of this Chapter shall be complied with.

18.5.6.2 Preparation for tests and maintenance in the course of the tests shall be carried out by the manufacturer in compliance with the maintenance manual for the tested apparatus and approved methods of its testing, and in case of the RS-approved standard — in accordance with it.

18.5.6.3 Radio and navigational equipment may be tested at the special proving ground.
18.5.6.3.1 Proving grounds for tests of radar stations and gyrocompasses shall be recognized by the Register as satisfactory for these tests with issuance of the Recognition Certificate in accordance with Section 8, Part I "General Regulations for Technical Supervision" of the Rules for Technical Supervision.

For issuance of the Recognition Certificate the survey of proving ground shall be carried out including its compliance with the requirements, and comparison tests shall be conducted under the approved programme in accordance with 18.5.3.13.

18.5.6.3.2 The proving ground for testing the equipment with the help of simulation shall meet the following requirements:

.1 metal masses shall be at least 30 m distant from the ship;
.2 no industrial interference in the course of tests;
.3 the competent organization's permission for the transmitter to be operated in live air shall be available;
.4 correspondents for communication shall be designated within the designed ranges;
.5 navigational range and direction finding objects shall be fixed on the map of the proving ground by specialists of geodesic and hydrographic services;
.6 leading beacons of the proving ground, objects for the direction finding shall be visible from the position of taking bearings (upper bridge, navigation bridge wings); for proving ground reflecting objects their radar visibility shall be provided;
.7 ship shall be reliably and securely moored at the place of her lying; in the course of tests moorage of other floating craft at the tested ship is not admitted;
.8 with the purpose of higher quality of checking of radars and gyrocompasses as to their accuracy of determining of directions proving grounds shall have a few (six are recommended) reference points situate, as possible, in various directions at an interval about 60° and distant over 2 miles.

18.5.6.3.3 The proving ground's Recognition Certificate is subject to annual confirmation, and in this connection it shall be surveyed by the surveyor where the results of simulation and comparison tests which have been conducted under the RS technical supervision may be taken into account.

18.5.6.3.4 Dynamic pressure logs may be calibrated without arrival at the measuring line, and for this purpose devices ensuring dynamic pressure in the log sylphon apparatus similar to that existing in the ship's running with different speeds.

18.5.6.3.4.1 The device simulating the pressure in the sylphon apparatus shall ensure the log accurate adjustment in which residual corrections shall not exceed those admitted by the technical specifications for the log.

18.5.6.3.4.2 Upon results of comparison tests a table or diagram of changes of dynamic pressure in the sylphon apparatus depending on the ship's speed shall be prepared and agreed with the RS surveyor.

Two sets of devices shall be prepared one of which shall be used in simulation tests, and the other shall be a control one.

18.5.6.3.5 Echolots and navigational stations of horizontal sonar may be tested by means of instrumental method.

Acoustic parameters of vibrator transducer (of an aerial): sound pressure and sensitivity of the receiving path shall be measured with the help of hydrophones, oscillographs and other instrumentation devices; in this case, necessary precision and stability of readings shall be ensured.

18.5.6.3.5.1 In the course of comparison tests the RS surveyor shall compare acoustic parameters measured by means of instruments with those received during routine tests and with the norms of technical specifications which enables him to ascertain reliability of instrumental measurements and the hydroacoustic apparatus depth and range determined on the basis of those data.

18.5.6.3.5.2 In the course of simulation tests the surveyor shall check the identity of measurements of sound pressure with regard to fulfillment of the following conditions:
depth under the transducer shall be not less than 3 m;
no extraneous reflecting objects and noise sources shall be in the vicinity the area of acoustic measurements (distant 10 – 15 m);
measurements shall be made when the main engine is idle;
mooring method shall ensure easy installation of the measuring hydrophone;
fitting and fastening method for the hydrophone shall secure reliability and accuracy of its installation so that the hydrophone shall be fixed in a certain position relative to the transducer axis at a given distance from the latter;
measurement devices for instrumental testing shall be in proper working condition and calibrated prior to measurements in accordance with the Maintenance Manual;
cables connecting the devices shall be reliable screened;
measurements shall be conducted in all frequency bands, depth emitting ranges with narrow and broad directivity diagrams;
instrumental testing of hydroacoustic apparatus is required to be carried out in strict compliance with the requirements of testing methods and the maintenance manual of tested apparatus.  
18.5.6.3.6 The ship's heading or track control systems may be tested when the ship is not at sea but by means of simulation of the ship's running mode or by the instrumental method.  
18.5.6.3.6.1 The ship's running simulation shall be performed by means of the main engine full speed ahead thrust in conjunction with steering gear and gyrocompass operated.  
For testing of the ship's heading or track control systems the following conditions shall be met, the fulfillment of which shall be controlled by the RS surveyor:  
the ship's bows shall be moored at the hinged lug;  
the ship's stern shall be able to shift over the arc from the middle position to left and right as much as 35° – 45°;
availability of disturbing factors such as forces applied to the ship running it off the given course: tow boat operated, water jet caused by the propeller and ship, current, etc.  
18.5.6.3.6.2 Testing methods shall allow for all checking complex of the ship's heading or track control systems in the running conditions with the purpose of checking of parameters and defining of operating characteristics under all kinds of control: simple, tracking and automatic in accordance with indications in Section 16.  
18.5.6.3.6.3 Instrumental method for checking parameters of the ship's heading or track control systems in the automatic mode with idle main engines may be admitted by the Register in cases where rudder and steering gears and the ship's heading or track control systems showed full reliability on a number of ships of series production either in the course of routine tests or in service practice.  
18.5.7 Auxiliary machinery and equipment.  
18.5.7.1 In the course of simulation tests of the ship’s main propulsion installation in lieu of sea and control ones driven engines, auxiliary machinery, systems, boilers, vessels under pressure and equipment shall be checked like in routine tests.  
18.5.7.2 Parameters of operation of driven engines of auxiliary machinery, systems, boilers, vessels under pressure and other equipment shall be in compliance with those of bench tests and specified to the extent not less than in the course of routine tests in accordance with the indications of appropriate Sections.  
18.5.7.3 The ship's devices of automation, control, signals, communication and navigation which, prior to installation on board, have preceding undergone checking of serviceability and adjustment for working parameters on specially equipped test benches, under sea-going conditions they shall be checked within the scope agreed with the Register.  
Testing of serviceability and adjustment shall be carried out on bench tests under the conditions simulating the ship's ones to the extent recognized by the Register and sufficient in all parameters.  
18.5.7.4 Use of driven and auxiliary machinery, as well as any other equipment tested by simulation methods shall not require their additional adjustment.
18.6 MEASUREMENT OF VIBRATION ON BOARD SEA-GOING SHIPS

18.6.1 Vibration measurements of machinery and equipment shall be carried out in accordance with Section 9, Part VII "Machinery Installations" of the Rules for the Classification and Construction on board all prototype ships of a series constructed at the shipyard, on the first ship of modified design, on ships of single construction and subjected to conversion (taking into account particularities of conversion and as applicable to the equipment, which vibration may be influenced by the conversion performed).

18.6.1.1 Vibration measurements are carried out in the course of mooring trials (measurements of machinery vibration parameters (except for main engines) and shipboard equipment on their specification running regimes) and sea trials (measurements of the main engine vibrations, individual machinery and equipment, which specification power cannot be obtained during mooring trials) under the program approved by the Register. In well-grounded cases the measurements may be postponed until the first service voyages.

18.6.1.2 Vibration measurements of the main engines are carried out at specification running: slow, half and full ahead for ballast displacement.

18.6.2 Measurement of sanitary vibration level in ship's spaces shall be carried out in accordance with Section 18.3, Part XVII "Distinguishing Marks and Descriptive Notations in the Class Notation Specifying Structural and Operational Particulars of Ships" of the Rules for the Classification and Construction during sea trials on ships where the distinguishing mark COMF (V – 1 or 2, or 3) may be added to the design class notation.

18.6.2.1 During measurements the following conditions shall be met:
- ship moves with the constant speed and heading within rudder angle from port to starboard 2°;
- engine runs in the representative mode with the constant output power;
- sea force is not more than 3;
- propeller is completely submerged;
- water depth is not less than five times exceeds the ship's draught.

Any deviation from the specified conditions shall be recorded in the report on tests.

18.6.3 Effectiveness of arrangements elaborated and developed on the basis of vibration measurement results and aimed at reducing its to the allowable values shall be verified by control measurements.
18.7 GAS TRIALS

18.7.1 Gas trials shall be carried out for ships carrying liquefied gases and/or using gas as fuel.

18.7.2 Gas trials shall be performed for confirmation of:

.1 the parameters and correct operation of the equipment and machinery using gas fuel (natural gas, etc.);
.2 correct functioning of systems using gas in operation;
.3 correct functioning of the equipment and devices.

18.7.3 Prior to gas trials the shipyard shall submit:

.1 the confirmation that the ship is fully prepared for testing, the installation of equipment and machinery, cargo/ fuel containment system, cargo system, gas fuel system, emergency shut down (ESD) system, gas detection system and gas management system is completed;
.2 the programme for gas trials approved by the Register;
.3 the technical documentation necessary for surveys and trials.

18.7.4 Gas trials shall be carried out in the presence of the RS surveyor according to the programme submitted by the shipyard.

18.7.5 The programme for gas trials shall include, as a minimum, demonstration and verification of the equipment and machinery operation, functioning and operational characteristics of the cargo/ fuel containment system, cargo system, gas fuel system, ESD system and gas management system, including instrumentation, control, alarm and protection systems, during operation and cargo handling operations and/or bunkering including preparation of liquefied gas tanks and pipelines:

drying/ inerting;
gassing up;
cooldown;
liquid gas loading/ transfer to another tank/ discharging;
warm-up;
gas freeing;
aeration.

18.7.6 After completion of gas trials, the shipyard shall prepare the test results.
19 INITIAL SHIP SURVEYS ON COMPLETION OF CONSTRUCTION AND TRIALS WITH THE PURPOSE OF ISSUING CERTIFICATES REGULATED BY INTERNATIONAL CONVENTIONS AND CODES

19.1 The scope of initial survey of the ship on completion of construction with the purpose of confirmation of the ship compliance with international conventions and codes and issuing the relevant certificates is given in Part III "Survey of Ships in Compliance with International Conventions, Codes, Resolutions and Rules for the Equipment of Sea-Going Ships" of the Guidelines on Technical Supervision of Ships in Service.
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