RUSSIAN MARITIME REGISTER OF SHIPPING

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RULES
FOR THE CLASSIFICATION AND CONSTRUCTION OF SEA-GOING SHIPS

PART XI

ELECTRICAL EQUIPMENT

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RULES FOR THE CLASSIFICATION AND CONSTRUCTION OF SEA-GOING SHIPS

Rules for the Classification and Construction of Sea-Going Ships of Russian Maritime Register of Shipping (RS, the Register) have been approved in accordance with the established approval procedure and come into force on 1 January 2023.

The present edition of the Rules is based on the 2022 edition taking into account the amendments and additions developed immediately before publication.

The procedural requirements, unified requirements, unified interpretations and recommendations of the International Association of Classification Societies (IACS) and the relevant resolutions of the International Maritime Organization (IMO) have been taken into consideration.

The Rules are published in the following parts:

Part I "Classification";

Part II "Hull";

Part III "Equipment, Arrangements and Outfit";

Part IV "Stability";

Part V "Subdivision";

Part VI "Fire Protection";

Part VII "Machinery Installations";

Part VIII "Systems and Piping";

Part IX "Machinery";

Part X "Boilers, Heat Exchangers and Pressure Vessels";

Part XI "Electrical Equipment";

Part XII "Refrigerating Plants";

Part XIII "Materials";

Part XIV "Welding";

Part XV "Automation";

Part XVI "Structure and Strength of Fiber-Reinforced Plastic Ships";

Part XVII "Distinguishing Marks and Descriptive Notations in the Class Notation Specifying Structural and Operational Particulars of Ships";

Part XVIII "Additional Requirements for Structures of Container Ships and Ships, Dedicated Primarily to Carry their Load in Containers". The text of the Part is identical to IACS UR S11A "Longitudinal Strength Standard for Container Ships" (June 2015) and S34 "Functional Requirements on Load Cases for Strength Assessment of Container Ships by Finite Element Analysis" (May 2015);

Part XIX "Additional Requirements for Cargo Ships of Less Than 500 Gross Tonnage";

Part XX "Additional Requirements for Yachts";

Supplement to Rules and Guidelines of Russian Maritime Register of Shipping "IACS Procedural Requirements, Unified Requirements, Unified Interpretations and Recommendations".

REVISION HISTORY[1]
(purely editorial amendments are not included in the Revision History)

Amended paras/chapters/ sections	Information on amendments	Number and date of the Circular Letter	Entry-into-force date
Para 1.2.1	A new definition "Portable lighting fitting" has been introduced	315-23-1877c of 14.12.2022	01.01.2023
	New definition "Valve-regulated sealed type battery (sealed battery)" has been introduced	311-05-1958c of 18.07.2023	01.08.2023
Para 1.3.2.1.13	Requirement for survey of onboard lighting has been specified	315-23-1877c of 14.12.2022	01.01.2023
Para 1.3.3.1	Requirements for the list of electrical equipment subject to survey during manufacture have been specified	311-05-1941c of 26.05.2023	01.07.2023
Para 3.1.6	Requirements for accumulator battery charge have been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 4.3.1.19	Requirements for power supply of consumers from the main switchboard busbars of the main switchboard have been specified considering IMO resolution MSC.474 (102)	315-23-1647c of 18.10.2021	01.01.2024[2]
Para 5.5.11	Requirements for visual and audible alarm of steering gear control systems have been specified	315-22-1774c of 25.05.2022	01.07.2023
Para 5.5.12	Requirements for visual and audible alarm of steering gear control systems have been specified	315-22-1774c of 25.05.2022	01.07.2023

[1] Amendments and additions introduced at re-publication or by new versions based on circular letters or editorial amendments.
[2] Advance introduction while keeping the requirements which shall remain in effect before entry-into-force of amendments.

Amended paras/chapters/ sections	Information on amendments	Number and date of the Circular Letter	Entry-into-force date
Para 5.10.2	Requirements for supply of watertight doors have been specified considering IMO resolution MSC.474 (102)	315-23-1647c of 18.10.2021	01.01.2024[1]
Para 5.10.4	Requirements for IPX 8 protection of enclosures of electrical components of watertight doors situated below the bulkhead deck have been specified considering IMO resolution MSC.474 (102)	315-23-1647c of 18.10.2021	01.01.2024[1]
Para 6.1.8	New para with the requirements for the lighting fittings of domestic services has been introduced	315-23-1877c of 14.12.2022	01.01.2023
Para 6.2.4	Requirements for supply of local lighting fixtures and socket outlets have been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 6.3.1	Requirements for illumination of emergency lighting have been specified	311-05-1958c of 18.07.2023	01.08.2023
Chapter 7.10	The title of the chapter has been specified considering IMO resolution MSC.482 (103)	315-23-1647c of 18.10.2021	01.01.2024[1]
Paras 7.10.1 — 7.10.8	New para 7.10.1 determining applicability of the requirements of Chapter 7.10 has been introduced considering IMO resolution MSC.482 (103); existing paras 7.10.1 — 7.10.7 have been renumbered 7.10.2 — 7.10.8 accordingly	315-23-1647c of 18.10.2021	01.01.2024[1]
Para 7.10.6	Requirements for cargo hold water level alarm system have been specified	315-22-1891c of 08.02.2023	01.01.2024[1]
Para 7.10.8	Requirements for cargo hold water level alarm system components have been specified	315-22-1891c of 08.02.2023	01.01.2024[1]
Para 8.2.2	Requirements for time delay for generator overload have been specified	315-22-1896c of 15.02.2023	15.03.2023

[1] Advance introduction while keeping the requirements which shall remain in effect before entry-into-force of amendments.

Amended paras/chapters/ sections	Information on amendments	Number and date of the Circular Letter	Entry-into-force date
Para 10.6.1.2	Requirements for alternating current generators have been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 13.1.7	Requirements for sealed batteries have been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 13.2.1	Requirements for arrangement of sealed batteries have been specified	311-05-1958c of 18.07.2023	01.08.2023
Paras 14.1.2.1 — 14.1.2.10	New para 14.1.2.1 has been introduced containing requirements for terms Ics, Icu, Icw, Icm, etc.; existing paras 14.1.2.1 — 14.1.2.9 have been renumbered 14.1.2.2 — 14.1.2.10 accordingly	311-05-1958c of 18.07.2023	01.08.2023
Para 14.1.2.3	Requirements for nominal making capacity of electric switch apparatus intended for interrupting short-circuit currents have been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 14.1.2.7	Requirements for rated short-time withstand current for electric switch apparatus in circuits with selective action of protective devices have been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 16.8.9.4	Definition of cable transposition has been specified	311-05-1958c of 18.07.2023	01.08.2023
Para 17.1.1.9	Application of the requirements in Section 17 has been specified	315-22-1894c of 14.02.2023	01.03.2023
Para 17.3.1.1	Requirements for configuration of electric propulsion plants have been specified	315-22-1894c of 14.02.2023	01.03.2023
Chapter 17.16	New Chapter with the requirements for electric propulsion plants using accumulator batteries to supply the electrical equipment has been introduced	315-22-1894c of 14.02.2023	01.03.2023

Amended paras/chapters/ sections	Information on amendments	Number and date of the Circular Letter	Entry-into-force date
Sections 19 — 26	New Section 19 with the requirements for underwater power cables and electrical equipment of ships for which this type of power supply is used, as well as for electrical equipment for a voltage in excess of 15 kV has been introduced; existing Sections 19 — 25 (with paras and references thereto) have been renumbered 20 — 26 accordingly	315-23-1877c of 14.12.2022	01.01.2023

1 GENERAL

1.1 APPLICATION

1.1.1 The requirements of this Part of the Rules apply to electrical installations in ships subject to the Register survey, as well as to individual types of electrical equipment in accordance with 1.3.

1.2 DEFINITIONS AND EXPLANATIONS

1.2.1 Definitions and explanations relating to the general terminology of the Rules are given in Part I "Classification".

For the purpose of this Part of the Rules the following definitions and explanations have been adopted.

Emergency lighting is lighting of ship's spaces and zones by means of lighting fixtures fed from the emergency source of power or from the transitional emergency source of power.

Emergency source of electrical power is a source of electrical power intended to supply necessary ship's services in case of power failure on the main switchboard.

Emergency transitional source of electrical power is a source of electrical power intended to supply necessary ship's services from the moment of the power failure on the main switchboard busbars until the emergency generator is switched on to supply the emergency switchboard busbars.

Emergency switchboard is a switchboard intended to be supplied directly from the emergency or emergency transitional source of electrical power in case of failure of the main source of electrical power and to supply the emergency services.

Valve-regulated sealed type battery (sealed battery) is a sealed unattended accumulator battery with recombination of issued gases giving off no gases in operation outside the case.

Antistatic earthing is electrical connection to ensure grading of static electricity potentials of the structural parts of equipment and ship's hull due to their direct contact or through antistatic earthing conductors.

The antistatic earthing conductors are:

metal conductors connecting equipment subject to antistatic earthing, cable shields, piping, etc, to one another and/or to ship's hull or other equipment earthed;

layers of conductive substances applied onto equipment surfaces, such as: metal coatings, conductive plastics, compounds, mastics, antistatic paint coatings, etc.

Safety voltage is any voltage not dangerous to the personnel. This condition is considered to be satisfied if the windings of transformers, converters, and other devices to step down voltage are electrically separated and if the value of stepped-down voltage across these devices or sources of electrical power does not exceed:

50 V between poles for direct current;

50 V between phases or between phases and the ship's hull for alternating current.

Shaft generators are generators driven by the main machinery and supplying the ship's mains or separate consumers.

Galvanic intrinsic safety is such a state of the ship equipment and systems, under which the possibility of fire or explosion due to electric sparking in case of galvanic contact of the ship with a shore structure or another ship caused by electrochemical phenomena and stray currents in surrounding sea water and ground is excluded.

Main switchboard is a switchboard intended to be supplied directly from the main source of electrical power and to supply the ship services.

Earthing is electrical connection of a part of electrical equipment to be earthed to ship's hull.

Lightning protection zone is the area, within the limits of which the ship's space is protected against direct lightning strokes.

Uninterruptible power system (UPS) is combination of converters (rectifier-inverter), switches (bypass) and energy storage means, for example, batteries, constituting a power system for maintaining continuity of load power in case of input power failure.

Competent body is an organization possessing appropriate knowledge and experience in a specific area, which documents are recognized by the Register.

Ship's hull means all ship's metal parts, which have a reliable electrical connection to the outer metal shell plating. For ships with non-conducting hull, it is a special copper sheet with the area of not less than 0,5 m^2 and the thickness not less than 2 mm, which is fixed to the outside of the ship's shell plating at a level below the light load waterline and is used for earthing all the equipment installed on board the ship.

Air termination network is the upper part of the lightning protection device intended for the perception of atmospherics.

Non-essential services are services, the temporary disconnection of which does not impair the safety of navigation, the safety of human life and the safety of cargo on board.

Main electrical power plant is a space where the main source of electrical power is placed.

Main electrical power source is a source of electrical power intended to supply all electrical equipment and systems essential for maintaining the ship in normal operational and habitable condition, without resorting to the emergency source of electrical power.

Essential services are services normal operation whereof ensures safe navigation, safety of human life and safety of cargo on board ship; essential services are divided into primary and secondary services.

Primary essential services are the services, which need to be in continuous operation to maintain propulsion and steering of the ship. Such services are those listed in 1.3.2.1.

Secondary essential services are the services, which need not necessarily be in continuous operation to maintain propulsion and steering but which are necessary for maintaining the ship safety. These services shall be ready for the immediate activation. Such services are those listed in 1.3.2.2.

Down conductor is a conductor, which electrically connects the air termination network to the earth termination network.

Portable lighting fitting is a lighting fitting that, in standard use, may be easily moved without disconnecting from the supply network.

Special electrical spaces are spaces or locations intended expressly for electrical equipment and accessible only to operating personnel.

Not readily ignitable electrically insulating material is a material, which sustaines the tests specified in the Rules for Technical Supervision during Construction of Ships and Manu-facture of Materials and Products for Ships[1].

Electrical installation of low power is an electrical installation of a ship with the total power of supply sources up to 50 kW (kVA).

Electrostatic intrinsic safety is such a state of the ship equipment and systems, under which the possibility of fire or explosion due to static electricity discharges is excluded.

Electrical power plant with variable frequency main power source is an electrical power plant intended for operation in a set frequency range. The definition of an electrical power plant is given in 17.2.1.

[1] Hereinafter referred to as "the Rules TSDCS".

1.3 SCOPE OF SURVEYS

1.3.1 General.
General provisions applicable to the classification procedure, survey during ship's construction and manufacture of the equipment are stated in the General Regulations for the Classification and Other Activity and in Part I "Classification".
1.3.2 Survey of ship's electrical equipment.
Main and emergency sources of electrical power, power and lighting transformers and converters (both rotating and static), main and other switchboards, cable network, as well as electrical equipment, systems and arrangements listed in 1.3.2.1 — 1.3.2.4 are subject to survey on board the ship.
1.3.2.1 Primary essential services are:
.1 steering gear;
.2 pumps of hydraulic systems of CP-propellers;
.3 scavenging air blower, fuel oil supply pumps, fuel valve cooling pumps, lubricating oil pumps and cooling water pumps for main and auxiliary engines and turbines necessary for propulsion;
.4 forced draught fans, feed water pumps, water circulating pumps, vacuum pumps and condensate pumps for steam plants on steam turbine ships, and also for auxiliary boilers on ships where steam is used for equipment supplying primary essential services;
.5 oil burning installations for steam plants on steam turbine ships and for auxiliary boilers where steam is used for equipment supplying primary essential services;
.6 electrical equipment for azimuth thrusters which are the sole means for propulsion/steering with lubricating oil pumps, cooling water pumps;
.7 electrical equipment for electric propulsion plant and azimuth electric propulsion plant with lubricating oil pumps, cooling water pumps and forced draught systems;
.8 electric generators and associated power sources supplying the above equipment;
.9 hydraulic pumps supplying the above equipment;
.10 viscosity control equipment for heavy fuel oil;
.11 navigation lights, aids and signals;
.12 internal communication devices/systems;
.13 lighting (main lighting in accordance with to 6.1.1, emergency lighting in accordance with 9.3.1 and 20.1.2.1.1);
.14 control, monitoring, alarm and safety devices/systems for equipment to primary essential services;
.15 other primary essential services needed to ensure that the ship is used in compliance with its purpose and class notation.
1.3.2.2 Secondary essential services are:
.1 windlass;
.2 fuel oil transfer pumps and fuel oil treatment equipment;
.3 lubrication oil transfer pumps and lubrication oil treatment equipment;
.4 pre-heaters for heavy fuel oil;
.5 starting air and control air compressors;
.6 bilge, ballast and heeling pumps;
.7 fire pumps and other fire extinguishing medium pumps;
.8 ventilating fans for engine and boiler rooms;
.9 services considered necessary to maintain dangerous spaces in a safe condition, including services for hull earthing on oil tankers, lightning protection and services ensuring electrostatic and galvanic intrinsic safety;
.10 fire alarm systems;
.11 electrical equipment for watertight closing appliances;
.12 electric generators and associated power sources supplying the above equipment;

.13 hydraulic pumps supplying the above equipment;
.14 tunnel and azimuth thrusters;
.15 inert gas devices/systems in oil tankers;
.16 control, monitoring, alarm and safety devices/systems for cargo containment systems;
.17 electric drives for refrigerating plants, specified in 1.1, Part XII "Refrigerating Plants";
.18 control, monitoring, alarm and safety devices/systems for equipment to secondary essential services;
.19 other secondary essential services needed to ensure that the ship is used in compliance with its purpose and class notation.

1.3.2.3 Services for habitability are those services, which need to be in operation for maintaining the vessel's minimum comfort conditions for the crew and passengers. Examples of equipment for maintaining conditions of habitability are as follows:
.1 cooking;
.2 heating;
.3 domestic refrigeration;
.4 domestic ventilation;
.5 sanitary and fresh water;
.6 electric generators and associated power sources supplying equipment specified in 1.3.2.3.1 — 1.3.2.3.5.

1.3.2.4 Other electrical services are:
.1 electrical equipment of processing machinery of ships used for processing the living resources of the sea and not engaged in their catching (refer to 20.4.4.1);
.2 electrical equipment of fishing and processing machinery of fishing vessels (refer to 20.10.1.1).

1.3.2.5 Electrical equipment of domestic services, including that specified in 1.3.2.4, as well as permanently installed equipment not supplying primary and secondary essential services, shall be subject to survey on board the ship only in respect to the following:
.1 influence exerted by the operation of this equipment on the quality of electrical power produced by the shipboard electrical power plant;
.2 selection of the types and sections of cables and wires, as well as the methods of cable installation;
.3 insulation resistance, earthing and protective devices.

1.3.3 Survey during manufacture of electrical equipment.

1.3.3.1 The following kinds of electrical equipment intended for use in installations and systems listed in 1.3.2.1 and 1.3.2.2 are subject to survey during manufacture:
.1 electrical propulsion plant;
.2 generators;
.3 accumulators and batteries;
.4 uninterruptible power supply units (UPS);
.5 transformers and convertors;
.6 rotary converters;
.7 rotary amplifiers;
.8 static and semi-conductor convertors (rectifiers, inverters, frequency converters);
.9 switchboards and control and monitoring desks;
.10 electric drives for machinery referred to in 1.3.2.1 and 1.3.2.2;
.11 main and emergency lighting;
.12 control and monitoring devices;
.13 internal service communication;
.14 fire detection and fire alarm system and release indication on fire smothering system;
.15 cables and wires;

.16 heating and cooking appliances, stationary appliances.

1.3.3.2 The safe type electrical equipment shall be surveyed (with respect to its safety) by a competent authority whose documents are recognized by the Register, irrespective of whether or not this equipment is subject to survey according to the requirements of 1.3.3.1.

1.3.3.3 Scope of tests of electrical equipment after manufacture and requirements for tests are given in the Rules TSDCS.

1.4 TECHNICAL DOCUMENTATION

1.4.1 General provisions applicable to the procedure of approval of technical documentation are set forth in the General Regulations for the Classification and Other Activity. The scope of technical documentation on electrical equipment for the entire ship to be submitted to the Register for consideration is stated in 3.2, Part I "Classification".

1.4.2 Prior to starting the survey of the electrical equipment manufacture, the following documentation shall be submitted to the Register for consideration:

.1 description of the principle of operation and main characteristics;

.2 specification (list of items), which indicates all the components, instruments and materials used and their technical characteristics;

.3 general view drawing with sectional views;

.4 circuit diagram;

.5 programme of tests;

.6 results of rotor shaft (armature) calculation and drawing of fastening of poles, active iron core, commutator, etc., as well as welded joints of the spoke rib and the shaft, for electric machines with rated current in excess of 1000 A;

.7 busbar calculation of electrodynamic and thermal short circuit strength — for switchboards, if rated current of the generators operating separately or total current of the generators operating in parallel exceeds 1000 A;

.8 data concerning immunity to static or dynamic interference or method of electromagnetic compatibility testing;

.9 measures to be taken for interference suppression.

When necessary, the Register may require supplementary technical documentation and data on reliability to be submitted.

2 GENERAL REQUIREMENTS

2.1 OPERATING CONDITIONS

2.1.1 Influence of climatic conditions.

2.1.1.1 The rated ambient air and cooling water temperatures for electrical equipment shall be those specified in Table 2.1.1.1.

Table 2.1.1.1

Nos	Location of equipment	Ambient air and cooling water temperature, °C			
		Unrestricted service		Navigation outside the tropical zone	
		Air	Water	Air	Water
1	Machinery and special electrical spaces, galleys	+45 … +5	+32	+45 … +5	+25
2	Weather decks	+45 … –25	–	+40 … –25	–
3	Other spaces	+45 … +5	–	+45 … +5	–

N o t e . Electronic elements and devices designed for mounting in the switchboards, panels or casings shall be capable of reliable performance at an ambient air temperature up to 55 °C.
Temperature up to 70 °C shall not lead to failure of the elements, devices and systems.

2.1.1.2 Electrical equipment shall be capable of reliable performance at a relative air humidity of 75±3 % and a temperature of +45±2 °C or at a relative air humidity 80±3 % and a temperature of +40±2 °C, as well as at a relative humidity of 95±3 % and a temperature of +25±2 °C.

2.1.1.3 Where electrical equipment is installed within environmentally controlled spaces the ambient temperature, for which the equipment shall be suitable, may be reduced as against the value given in Table 2.1.1.1 and maintained at a value not less than +35 °C, provided:

.1 the equipment is not for use for emergency services and is located outside the machinery spaces;

.2 temperature control is achieved by at least two cooling units so arranged that in the event of loss of one cooling unit, the remaining unit is capable of satisfactorily maintaining the design temperature;

.3 the equipment installed in such spaces shall be able to work safely at temperature of +45 °C until the nominal working ambient temperature may be achieved; the cooling equipment shall be rated for +45 °C ambient temperature;

.4 audible and visual alarms shall be provided at a continually manned control station to indicate any malfunction of the cooling units.

2.1.2 Mechanical effects.

2.1.2.1 Electrical equipment shall be capable of reliable performance at vibrations with frequency of 2 to 80 Hz, i.e. with an amplitude of displacements of ±1 mm for frequency range of 2 to 13,2 Hz and an acceleration of ±0,7 g for frequency range of 13,2 to 80 Hz.

Electrical equipment located on the sources of vibrations (diesel engines, compressors, etc.) or in the steering gear room shall be capable of reliable performance at vibrations of 2 to 100 Hz, i.e. with an amplitude of displacement of ±1,6 mm for frequency range of 2 to 25 Hz and an acceleration of ±4,0 g for frequency range of 25 to 100 Hz.

Electrical equipment shall also be capable of reliable performance at shocks having an acceleration of ±5,0 g and at a frequency of 40 to 80 shocks per minute.

2.1.2.2 Electrical equipment shall be capable of reliable performance with the ship having continuous list up to 15° and trim up to 5°, as well as with the ship rolling up to 22,5° with period of rolling of 7 — 9 s and pitching up to 10°.

Emergency equipment shall also be capable of functioning reliably with the ship having continuous list up to 22,5° and trim up to 10°, or within the same limits of simultaneous list and trim.

In gas carriers and chemical tankers, the emergency electrical power sources shall be capable of reliable performance with the ship having list up to 30°.

2.1.2.3 Electrical equipment shall possess the relevant mechanical strength and shall be so located as to avoid the risk of mechanical damage (refer also to 2.7.4).

2.1.3 Permissible variations of supply parameters.

2.1.3.1 Electrical equipment shall be so designed that it remains operative in all cases, except as noted in 10.8.2, 14.1.4.2 — 14.1.4.3 at all variations from the supply voltage and frequency as specified in Table 2.1.3.1 (refer also to 3.1.2.2 and 16.8.3.3).

Table 2.1.3.1

Parameters	Variations from rated values		
	for long periods, %	for short periods	
		%	time, s
Voltage (a.c)	+6…–10	±20	1,5
Frequency (frequency range of an electrical power plant with variable frequency main power source)	±5	±10	5
Voltage (d.c.)	±10	5 10	cyclic variations ripple
Note. When the services are fed from accumulator battery: long-period voltage variation within + 30 to –25 % for the equipment fed from the accumulator battery connected to the charging unit; long period voltage variation within + 20 to –25 % for the equipment, which is not connected to the charging unit.			

2.1.3.2 On ships of restricted area of navigation **R3**, it is allowed (except for in machinery and devices of essential services) to use the electrical equipment (of general commercial type) not fully complying with the above requirements.

2.2 ELECTROMAGNETIC COMPATIBILITY

2.2.1 General.

2.2.1.1 The present requirements are applicable to electrical equipment to ensure electromagnetic compatibility on board.

2.2.1.2 Failure-free performance of the equipment shall be ensured under conditions of interference having the following parameters:

.1 static and variable (50 Hz) magnetic field in accordance with Table 2.2.1.2.1.

Table 2.2.1.2.1

Class of equipment	Intensity, A/m	
	static field	variable field (50 Hz)
1	100	100
2	400	400
3	1000	1000

Installation of equipment is permitted:

class 1 — at a distance of 2 m and more from a powerful field source (busbar, group transformer);

class 2 — at a distance of 1 m and more from a powerful field source;

class 3 — irrespective of the distance from field source of any kind;

.2 harmonic components of voltage in supply circuits in accordance with the higher harmonics diagram for ship mains to be found in Fig. 2.2.1.2.2 on a logarithmic scale;

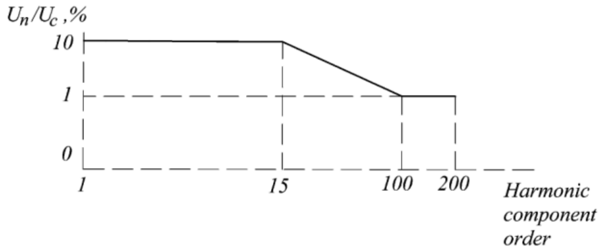

Fig. 2.2.1.2.2
Diagram of higher harmonic components for ship mains

.3 electrostatic discharges with a voltage amplitude of 8 kV;

.4 radio frequency electromagnetic fields within a range of 80 MHz — 6 GHz with a root-meansquare value of field intensity of 10 V/m;

.5 nanosecond voltage pulse with an amplitude of 2 kV for the power supply and of 1 kV for signalling and control cables with a duration of 5/50 ns;

.6 radio frequency interference in conductivity circuits within a range of 150 kHz to 80 MHz with a root-mean-square voltage of 3 V and 80 % modulation at a frequency of 1 kHz;

.7 microsecond voltage pulse with the duration of 1,2/50 μs in supply circuits with an amplitude of 1 kV when fed via the coupling decoupling device between each circuit and casing and of 0,5 kV when fed via the coupling decoupling device between the circuits.

2.2.1.3 The total harmonic distortion shall not exceed 8 % and shall be determined by the formula

$$K_u = \sqrt{\sum_{k=2}^{40}\left(\frac{U_{p,k}}{U_{p,1}}\right)^2} \cdot 100\ \%, \qquad (2.2.1.3\text{-}1)$$

where $U_{p,k}$ — mean square value of k harmonic subgroup voltage;
k — harmonic component order

$$U_{c,k} = \sqrt{U_k^2 + \sum_{h=-1}^{h=+1} U_{c,k+h}^2}, \mathrm{B}, \qquad (2.2.1.3\text{-}2)$$

where U_k — mean square voltage value of k harmonic component;
$U_{c,k}$ — mean square value of spectral component adjacent to k harmonic component;
h — spectral component order.

The value of K_u is specified for the complete electrical power system of a ship.

For circuits of electric propulsion plants not directly connected to ship's general consumers the total harmonic distortion shall not exceed 10 %.

Busbars with K_u > 10 % may be used for power supply to powerful sources of voltage curve harmonic components and to electrical equipment not sensitive to such harmonic components, provided that the busbars are connected to the main busbars through isolating devices (refer to 2.2.2.2).

When the specified value of the total harmonic distortion is exceeded, all electrical equipment shall be designed for such excess, which shall be supported by the documentation.

2.2.1.4 The intensity levels of radio interference from equipment in the power supply circuits shall not exceed the following values within the frequency bands given below:

for the equipment installed on open deck and navigation bridge:

10 – 150 kHz — 96 – 50 dBµV/m;

150 – 350 kHz — 60 –50 dBµV/m;

350 kHz – 30 MHz — 50 dBµV/m;

for the equipment installed in machinery and other enclosed spaces:

10 – 150 kHz — 120 – 69 dBµV/m;

150 – 500 kHz — 79 dBµV/m;

500 kHz – 30 MHz — 73 dBµV/m.

Artificial mains network and quasi-peak measuring receiver shall be used for measuring the intensity level of radio interference. The receiver bandwidth when measurements are taken within the frequency band from 10 to 150 kHz shall be 200 Hz and within the frequency band from 150 kHz to 30 MHz — 9 kHz.

2.2.1.5 On ships, for which the level of radio interference from power semiconductor converters cannot be limited in conformity with 2.2.1.4, the mains of automation, radio and navigational equipment shall be galvanically isolated from the mains of those converters so that at least 40 db are damped within the frequency range 0,01 — 30 MHz.

The power supply cables of equipment having the radio interference levels in excess of those stipulated by 2.2.1.4 shall be laid at least 0,2 m away from the cables of other equipment groups where the common cable run is longer than 1 m (refer to 2.2.2.8).

2.2.1.6 The levels of the radio interference electromagnetic field induced at a distance of 3 m from the equipment shall not exceed the following values within the frequency bands given below:

for the equipment installed on open deck and navigation bridge:

150 – 300 kHz — 80 – 52 dBµV/m;

300 kHz – 30 MHz — 52 – 34 dBµV/m;

30 – 2000 MHz — 54 dBµV/m, except for the band 156 — 165 MHz where the level shall be equal to 24 dBµV/m.

for the equipment installed in machinery and other enclosed spaces:

150 kHz – 30 MHz — 80 – 50 dBµV/m;

30 – 100 MHz — 60 – 54 dBµV/m, except for the band 156 — 165 MHz where the level shall be equal to 24 dBµV/m.

Quasi-peak measuring receiver shall be used to take measurements. The receiver bandwidth within the frequency band from 150 kHz to 30 MHz and from 156 to 165 MHz shall be 9 kHz and within the frequency band from 30 to 156 MHz and from 165 MHz to 1 GHz — 120 kHz.

2.2.2 Measures to ensure electromagnetic compatibility.

2.2.2.1 To ensure protection of radio equipment against electromagnetic interference, the requirements of Part IV "Radio Equipment" of the Rules for the Equipment of Sea-Going Ships[1] shall be considered.

2.2.2.2 For the purpose of dividing the power supply of the ship, rotary converters, special transformers and filters shall be used.

2.2.2.3 Power cable screens or metal armour shall be connected to the metal casing of relevant equipment and shall be earthed as frequently as possible, at each end as a minimum.

2.2.2.4 The screens of signal cables shall be earthed at one point on the side of the initial signal processing block. The cable shall have an external insulating sheath.

2.2.2.5 Continuous screening shall be ensured, and for this purpose cable screens shall be connected to equipment casings, and it shall also be ensured in cable branch boxes and cable distribution boxes, and in way of cable penetrations through bulkheads.

2.2.2.6 The earthing installed for the purpose of interference protection shall have an electric resistance not greater than 0,02 Ohm, minimum length possible, shall be resistant to vibration and corrosion, and shall be readily accessible for inspection.

2.2.2.7 Cable screens shall not be used as return conductors.

2.2.2.8 By the type of signals conveyed, ship cables are subdivided in groups as follows:

.1 coaxial cables of radio receivers and conveying video signals with the level of signals 0,1 μV to 500 μV;

.2 screened or coaxial cables conveying analogue or digital signals with a level 0,1 to 115 V;

.3 screened cables of telephone and radio broadcasting apparatus, control and signalling network with the level of signals 0,1 to 115 V;

.4 unscreened and located below the deck or screened and located above the deck cables of power and lighting network with the level of signals 10 to 1000 V;

.5 coaxial or screened cables of the transmitting aerials of radio transmitters, radar installations and echo sounders, power semiconductor converters with the level of signals 10 to 1000 V.

2.2.2.9 Cable of the same group may be laid in the same cable run provided interference-sensitive equipment is not influenced by the difference in the levels of signals conveyed. Where cable lengths laid in parallel are in excess of 1 m, the cables (cable runs) of different groups shall be laid at least 0,1 m apart and their intersections shall be effected at right angles. The radar installation and echo sounder cables mentioned in 2.2.2.8.5 shall either be double-screened or, if they are coaxial, laid inside a metal pipe. The outer screen shall be earthed, as well as the principal screen of the cable.

Where meeting the requirements for separate installation is not possible, cables of high degree of screening shall be used or cables shall be laid inside metal pipes or conduits.

Where the requirements of the equipment manufacturer regarding installation of cables connected to this equipment are available, these cables shall be laid in compliance with the requirements of the equipment manufacturer.

2.2.2.10 When electrical equipment is installed or cables are laid in the vicinity of magnetic compasses and to ensure protection against interference from other navigational equipment, the requirements of Part V "Navigational Equipment" of the RS Rules/E and Appendices 1 and 2, Section 16 of the Guidelines on Technical Supervision of Ships under Construction.

[1] Hereinafter referred to as "the RS Rules/E".

2.2.2.11 On all ships constructed from non-conductive materials, for which radio equipment is required by the Rules, all cables located within 9 m from the aerials shall be shielded or otherwise protected from radio interference, and all the equipment on board those ships shall be fitted with devices for radio interference suppression.

2.3 MATERIALS

2.3.1 Structural materials.

2.3.1.1 The structural parts of electrical equipment shall be fabricated of durable materials not containing asbestos, rated at least as having low flame-spread characteristics, resistant to sea air, oil and fuel vapour effects, or reliably protected against such effects.

For equipment installed or intended for use in dangerous spaces and zones, the structural parts of electrical equipment shall be fabricated of materials ensuring electrostatic and galvanic intrinsic safety.

2.3.1.2 Screws, nuts, hinges and similar items designed to fasten enclosures of the electrical equipment to be installed on weather decks or in spaces with increased humidity shall be made of corrosion-resistant materials or have effective corrosion-resistant covering.

2.3.1.3 All current-carrying parts of electrical equipment shall be of copper, copper alloys or other materials of equivalent qualities, with the exception of:

.1 rheostat elements, which shall be made of mechanically strong materials having high resistivity and capable of withstanding high temperatures;

.2 short-circuit rotor windings of asynchronous and synchronous motors, which may be made of aluminium or its alloys resistant to sea conditions;

.3 carbon brushes, cermet contacts and other similar parts when the properties specified so require;

.4 parts of electrical equipment directly connected to the ship's hull in case of hull-return singlewire system;

.5 aluminium windings of high-voltage transformers in compliance with 18.4.1.6.

2.3.2 Insulating materials.

2.3.2.1 Insulating materials of live parts shall not contain asbestos and shall have adequate dielectric strength and resistance to creepage currents, moisture and oil, as well as sufficient mechanical strength, or else be suitably protected.

The heating temperature of current-carrying parts and their connections shall not exceed the permissible heating temperature of the insulating materials at the rated load.

2.3.2.2 Non-flammable liquids may be used for cooling uninsulated parts of electrical equipment.

2.3.2.3 The insulating materials used for winding insulation in machines, apparatus and other equipment for essential services shall comply with the agreed standards.

The use of insulating materials not inferior to Class E is recommended.

2.3.2.4 Conductors used in electrical devices for internal connections shall have insulation made of materials rated at least as having low flame-spread characteristics and for apparatus with increased heating and also indicated in Section 15 — of non-combustible materials.

2.3.2.5 For insulation materials used for the manufacture of cables, refer to 16.3.

2.4 STRUCTURAL REQUIREMENTS AND PROTECTION OF ELECTRICAL EQUIPMENT

2.4.1 General.

2.4.1.1 Such parts as require replacement while in service shall be easily dismountable.

2.4.1.2 Where screw fastenings are employed, provision shall be made of exclude self-loosening of screws and nuts or, where dismantling and opening are a frequent occurrence, loss of same.

2.4.1.3 Gaskets used in components of electrical equipment (such as doors, covers, sight holes, packing glands, etc.) shall ensure adequate protection when in service.

The gaskets shall be secured to the covers or casings.

2.4.1.4 If the casings, panels and covers of electrical equipment, installed where unspecialized personnel has access to it, render lived parts inaccessible, they shall be opened with tools only.

2.4.1.5 Suitable water drainage arrangements shall be provided in electrical equipment where condensation is likely to occur. Channels shall be fitted inside the equipment to provide for condensate drainage from all equipment components. The windings and live parts shall be so arranged or protected that they are not exposed to the effects of such condensate as may accumulate inside the equipment.

2.4.1.6 Electrical equipment with forced ventilation, designed for installation in bottom parts of damp spaces, shall be provided with a ventilation system so as to avoid, as far as possible, suction of moisture and oil vapours inside the equipment.

2.4.1.7 Where measuring instruments with oil, steam or water supply are fitted in the control panel or desk, measures shall be taken to prevent these agents from making contact with the live parts in case of damage to the instruments or pipelines.

2.4.2 Insulation clearances.

Clearances between live parts at different potentials, or between live parts and earthed metal parts or outer enclosure, both in air and across the insulant surface shall be in conformity with the operating voltage and operating conditions of the installation, with the properties of the insulating materials used duly taken into account.

2.4.3 Internal wiring.

2.4.3.1 Stranded wires shall be used for internal wiring of electrical equipment throughout. Hookup wires shall be marked according to connection diagram.

2.4.3.2 For internal wiring of switchboards, control desks, other distribution and switching arrangements, etc., wires of not less than 1 mm^2 in cross-sectional area shall be used.

For systems of control, protection, measurement of different parameters, signalling and internal communication the use of wires having a cross-sectional area not less than 0,5 mm^2 is permitted.

For electronic and electrical devices for transformation and transmission of low-power signals wires not less than 0,2 mm^2 in cross-sectional area may be used.

2.4.3.3 Current-carrying parts shall be so attached that they will not have to sustain any additional mechanical stresses; such parts shall not be attached by screws fitted directly into insulating materials.

2.4.3.4 Stranded cores, cables and wires shall have their ends fitted out to suit the type of terminal used, or shall be provided with lugs.

2.4.3.5 Insulated wires shall be laid up and secured in such a manner that the method used for their attachment and arrangement does not lead to reduced insulation resistance and that they are not exposed to damage due to electrodynamic loads, vibrations or shocks.

2.4.3.6 Arrangements shall be made to ensure that the temperatures allowed for insulated wires under normal service conditions or for the duration of short-circuit current breaking are not exceeded.

2.4.3.7 Insulated wires shall be so connected to terminals or busbars that the wire insulation shall not be exposed to the overheating temperature under rated operating conditions.

2.4.4 Protection of electrical equipment.

2.4.4.1 Depending on location, the use shall be made of electrical equipment in appropriate protective enclosure, or other suitable measures shall be taken to protect the equipment from harmful effect of the environment and to protect the personnel from electric shock hazards.

2.4.4.2 The minimal degree of protection of electrical equipment installed in ship's spaces and zones shall be chosen from Table 2.4.4.2.

Table 2.4.4.2

Spaces, in which electrical equipment is installed		Type of electrical equipment: Electric machines, transformers	Switchboards, control gear, starters	Communication and signalling equipment, automation equipment, accessories (switchers, sockets, junction boxes)	Space heating and cooking appliances	Lighting fixtures
Spaces and zones, in which explosive mixtures of vapours, gases or dust with air are likely to occur		*Ex* (refer to 2.9, 20.2.4)		*Ex* (refer to 2.9, 20.2.4)		*Ex* (refer to 2.9, 20.2.4)
Dry spaces, dry accommodation spaces		IP20	IP20	IP20	IP20	IP20
Navigation bridge, radio room		IP22	IP22	IP22	IP22	IP22
Service spaces, steering gear rooms, refrigerating plant rooms (except for ammonia equipment), emergency diesel generator rooms, general purpose stores. Pantries, provision stores		IP22	IP22	IP22	IP22	IP22
Engine and boiler rooms	Above plating	IP22	IP22	IP44	IP22	IP22
	Below plating	IP44	–	IP44	IP44	IP44
	Control stations (dry)	IP22	IP22	IP22	IP22	IP22
	Enclosed separator rooms	IP44	IP44	IP44	IP44	IP44
	Premises and spaces protected by the fixed local application fire extinguishing systems[1]	IP44	IP44	IP44	IP44	IP44
Refrigerated spaces, galleys, laundries, bathrooms and showers		IP44	IP44	IP55	IP44	IP44
Catch processing spaces[2], shafting tunnels, cargo holds		IP55	IP55	IP55	IP55	IP55
Open decks		IP56	IP56	IP56	IP56	IP56

[1] The electrical equipment within adjacent areas not exposed to direct spray, upon agreement with the Register may have a lower degree of protection provided relevant measures of the electrical equipment protection are taken (e.g. installation of extra inlet ventilation openings, filters, baffles, etc).

[2] For the electrical equipment installed in the catch processing spaces an additional protection is recommended to enable sanitarization of the equipment with sea water.

N o t e . Where the enclosure of equipment does not guarantee the necessary protection, alternative methods of protection or alternative arrangement of equipment shall be applied to ensure the degree of protection stipulated by the Table.

2.5 PROTECTIVE EARTHING OF METAL PARTS, WHICH DO NOT CARRY CURRENT

Metal enclosures of electrical equipment operated at a voltage exceeding the safety level or having no double or reinforced insulation shall be fitted with an earth terminal marked with the symbol ⏚.

Provision shall be made for earthing inside and outside of the electrical equipment enclosure dependent on its purpose.

2.5.1 Parts to be earthed.

2.5.1.1 Metal parts of electrical equipment, which are likely to be touched under service conditions and which may become live in the event of damage to the insulation (except for those mentioned under 2.5.1.2), shall have a reliable electric contact with a component fitted with an earth terminal (refer also to 2.5.3).

2.5.1.2 Protection earthing is not required for:

.1 electrical equipment supplied with current at safety voltage;

.2 electrical equipment provided with double or reinforced insulation;

.3 metal parts of electrical equipment fastened in non-conducting material or passing therethrough and separated from the earthed and live parts in such a manner that under normal operating conditions these parts cannot become live or come in contact with earthed parts;

.4 bearing housings isolated to guard against circulating currents;

.5 lamp caps and fasteners for luminescent lamps, lamp shades, reflectors and guards supported on lamp holders or lighting fixtures constructed of, or shrouded in non-conducting material;

.6 cable clips, cleats, etc.;

.7 individual consumer — under voltage up to 250 V supplied through an isolation transformer.

2.5.1.3 The shields and metal armour of cables shall be earthed.

2.5.1.4 The secondary windings of all instrument transformers for current and voltage shall be earthed.

2.5.2 Earthing of aluminium structures in steel ships.

Superstructures of aluminium alloys fastened to the ship steel hull but insulated therefrom shall be earthed by at least two special wires, which will not start electrolytic corrosion at the points of their contact with the superstructure and the hull. The conductivity of each wire shall not be lower than the equivalent conductivity of a copper wire having a cross-sectional area of 16 mm^2. Such earthing connections shall be provided at different locations around superstructure perimeter, shall be accessible for inspection and protected from damage.

2.5.3 Earth terminals and conductors.

2.5.3.1 Bolts for fastening the earthing conductor to the ship's hull shall have a diameter not less than 6 mm. For cables and wires having a cross-sectional area of 2,5 mm^2 and 4 mm^2 it is permitted to use bolts (screws) 4 mm and 5 mm in diameter, respectively. Such bolts shall not be used for other purposes.

The bolts screwed into material (without nuts) shall be manufactured of brass or other corrosion resistant material.

Ship's hull in places of earthing conductor connections shall be cleaned to metal and properly protected against corrosion.

2.5.3.2 Fixed electrical equipment shall be earthed by means of external earthing conductors or an earthing core in the feeding cable.

When earthing is effected with a special core of the feeding cable, it shall be connected to the earthing device inside the enclosure of the electrical equipment.

Such earthing effected with external earthing conductors need not be provided in case the arrangement of equipment ensures a reliable electrical contact between the equipment enclosure and the metal ship's hull under all operating conditions.

For earthing effected with an external earthing conductors, the use shall be made of copper conductors, as well as conductors of any other corrosion-resistant metal provided the resistance of these conductors does not exceed that of the required copper conductor. The cross-sectional area of copper earthing conductor shall not be less than that specified in Table 2.5.3.2.

Table 2.5.3.2

Cross-sectional area of cable core connected to consumer, 2 mm^2	Cross-sectional area of earthing conductor of fixed electrical equipment, mm^2, min	
	solid	stranded
Up to 2,5	2,5	1,5
2,5 to 120	Half the cross-sectional area of cable core connected, but not less than 4	
Over 120	70	

In case earthing is effected with a special core, the cross-sectional area of this core shall be equal to the nominal area of the feeding cable core for cables, having a cross-sectional area up to 16 mm^2 and at least half the cross-sectional area of the feeding cable core, but not less than 16 mm^2 for cables having a cross-sectional area over 16 mm^2. Earthing resistance shall not exceed 0,4 Ohm.

2.5.3.3 Earthing of movable, loose and portable consumers shall be effected through and earthed jack in the socket outlet or other earthed contact device and a copper earthing core of the feeding flexible cable. The cross-sectional area of the earthing core shall not be less than the nominal cross-sectional area of the feeding flexible cable core for cables up to 16 mm^2 and at least half the cross-sectional area of the feeding flexible cable core, but not less than 16 mm^2, for cables over 16 mm^2.

2.5.3.4 Earthing of the fixed equipment shall be non-disconnectable.

2.5.3.5 Earthing of shields and metal armour of cables shall be effected in one of the following ways:

.1 using a copper earth wire of a cross-section not less than 1,5 mm^2 for cable conductors with a cross-sectional area up to 25 mm^2 and not less than 4 mm^2 for cable conductors with a cross-sectional area over 25 mm^2;

.2 by adequate attachment of the shields and metal armour to the hull;

.3 by means of cable gland rings provided these are characterized by corrosion resistance, good conductivity and elasticity.

Except for cables of end branches of circuit, which may be earthed at the supply end only, earthing can be effected at both cable ends. Cable shields and metal armour may be earthed in another approved way, provided these methods do not hamper the operation of equipment.

2.5.3.6 The external earthing conductors shall be accessible for inspection and protected against getting loose and mechanical damage.

2.6 LIGHTNING PROTECTION

2.6.1 General.

2.6.1.1 In ships provision shall be made for lightning protection devices covering the zone to be protected.

2.6.1.2 In ships, where consequential effects of lightning strokes may cause a fire or explosion, lightning protection earthing devices shall also be fitted to preclude consequential sparking.

2.6.1.3 Lightning protection device shall consist of an air termination, down conductor and earth termination. On metal masts no special lightning protection device need be fitted if provision is made for reliable electrical connection of the mast to the metal hull or earthing point.

2.6.2 Air termination network.

2.6.2.1 In metal ships the ship's vertical structures (masts, derrick posts, superstructures, etc.) may be used as air termination if provision is made for reliable electrical connection of these structures to the metal hull.

Additional air terminations shall be used only when ship's structural elements proper do not provide for reliable lightning protection.

2.6.2.2 If electrical equipment is installed on the top of the metal mast, provision shall be made for an air termination network, which is effectively earthed.

2.6.2.3 On each mast or top mast of non-conducting material an effectively earthed air termination shall be provided.

2.6.2.4 The air termination shall be made of a rod at least 12 mm in diameter. The rod may be of copper, copper alloys or steel protected against corrosion. For aluminium masts aluminium rods shall be used.

2.6.2.5 The air termination shall be fitted to the mast in such a manner that it projects at least 300 mm above the top of the mast or above any device fitted on its top.

2.6.3 Down conductor.

2.6.3.1 The down conductor shall be made of a rod, strip or multiwire cable having a cross-sectional area not less than 70 mm^2 for copper or its alloys and not less than 100 mm^2 for steel. Steel down conductors shall be protected against corrosion.

2.6.3.2 Down conductors shall run on the outer side of masts and superstructures with a minimum number of bends, which shall be gradual and have as large radius as possible.

2.6.3.3 Down conductors shall not run through dangerous spaces and zones.

2.6.3.4 In ships with non-metal hull the down conductor of the lightning protection device shall be laid separately throughout its length (including its connection to the earth termination network), without connecting to the busbars of the protective and operation earthing circuits.

2.6.4 Earth termination network.

2.6.4.1 In composite ships the metal stem or other metal structures immersed in water under any navigation condition may be used as earth termination.

2.6.4.2 Means shall be provided on board the ship to allow for connecting the ship's steel hull or the earth termination network to the shore-based lightning protection device earthing when the ship is in a dock or on a slipway.

2.6.4.3 Earthing of ships with non-conducting hulls shall be in accordance with 1.2 (refer to the definition "Ship's hull").

2.6.5 Connections in lightning protection device.

2.6.5.1 Connections between the air termination network, down conductor and earth termination network shall be welded or bolted with clamps.

2.6.5.2 The contacting surface area between the down conductor, air termination network and earth termination network shall not be less than 1000 mm^2.

The connecting clamps and connecting bolts shall be made of copper, copper alloys or steel protected against corrosion.

2.6.6 Lightning protection earthing devices.

2.6.6.1 Lightning protection earthing referred to in 2.6.1.2 shall be provided for isolated metal structures, flexible connections, pipes, screens of power and communication lines, pipeline entries into dangerous spaces.

2.6.6.2 All pipelines conveying petroleum products and other pipelines associated with dangerous spaces and zones and located on open decks or in spaces free from electromagnetic screening shall be earthed to the ship's hull at least at 10 m intervals throughout their length.

All pipelines, which are located on the upper deck where explosive gases may be present and which are not associated with dangerous spaces and zones, shall be earthed to the ship's hull at least at 30 m intervals throughout their length.

2.6.6.3 Metal parts near down conductors shall be earthed if they are not fixed to earthed structures and have no other metal connection to the ship's hull. In so doing, facilities or metal parts located at a distance of up to 200 mm from the down conductor shall be so connected to the down conductor that consequential sparking is excluded.

2.6.6.4 The joints of earthing elements shall be accessible for inspection and protected from mechanical damage.

2.7 ARRANGEMENT OF ELECTRICAL EQUIPMENT

2.7.1 Electrical equipment shall be installed in such a manner as to provide convenient access to controls and to all parts that require maintenance, inspection and replacement.

2.7.2 The horizontal-shaft electric machines shall be so installed that the shaft is positioned parallel to the centre line of the ship. Installation of machines with the shaft positioned in another direction is permitted only in those cases when the design of the machine ensures its normal operation under conditions specified in 2.1.2.2.

2.7.3 The air-cooled electrical equipment shall be so located that cooling air is not taken from bilges or other spaces wherein the air may be contaminated with substances having a harmful effect on insulation.

2.7.4 The electrical equipment placed in locations subject to vibration and shocks, which are heavier than those specified in 2.1.2.1 and which are impossible to eliminate, shall be so designed as to ensure its normal operation under these conditions or to mounted on relevant shock absorbers.

2.7.5 Electrical equipment shall be fixed in position in such a manner that the strength of decks, bulkheads and skin is not impaired as a result of this.

2.7.6 No electrical equipment shall be located in spaces wherein explosives are stored. Lighting of such spaces shall be provided with lighting fixtures fitted in adjacent flameproof spaces. If this is impracticable, the electrical equipment shall be of the design and type which prevent potential ignition and explosion.

2.7.7 When the enclosures of electrical equipment are made from different material than the structures on which they are installed, care shall be taken, if necessary, to prevent electrolytic corrosion.

2.8 SPECIAL ELECTRICAL SPACES

2.8.1 The doors of special electrical spaces shall be locked. These doors shall open on the outside.

In case the doors face corridors and passageways in accommodation and service spaces, it is permitted that these doors open on the inside on condition that protection guards and stops are provided. A warning notice shall be placed on the door. From the inside of the space the door shall open without a key.

2.8.2 Special electrical spaces shall not be adjacent to the tanks filled with flammable liquids. If this requirement is not feasible from the structural point of view, measures shall be taken eliminating the possibility of flammable liquid penetration into these spaces.

2.8.3 No exits, side scuttles of the opening type or other openings are permissible from special electrical spaces into dangerous spaces.

2.8.4 Handrails of non-conducting material shall be installed in special electrical spaces, in passageways and servicing areas when the open-type electrical equipment is used.

2.9 SAFE-TYPE ELECTRICAL EQUIPMENT

2.9.1 The requirements of the paragraph are applicable to all ships, in which enclosed or semienclosed spaces and zones explosive mixtures of vapours, gases or dust with air are likely to occur in dangerous concentrations.

The following spaces and zones fall under this category: paint lockers, lantern rooms (for oil lanterns), storerooms for cylinders with flammable gases, battery compartments and spaces, which contain tanks, machinery and pipes for flammable liquids having a flash point 60 °C and below.

Additional requirements for installation of electrical equipment in oil tankers are specified in 20.2; in ships intended for the carriage of motor vehicles with fuel in their taks — in 20.3; in ships intended for the carriage of dangerous goods — in 20.11.

2.9.2 Safe type of the equipment shall be confirmed by a certificate issued by a competent body. For simple electrical apparatus and components specified in 20.2.4.1.2 and 20.2.4.2.3, a certificate issued by a competent body as regards safety is not required. The manufacturer's confirmation of the product compliance with IEC 60079-11 and 60079-0 (or equivalent national standards) will be sufficient.

2.9.3 In dangerous spaces and zones, only safe type electrical equipment may be installed, the protection level of which corresponds to the category and group of the most dangerous gas mixture:

.1 paint lockers — sub-group IIB, temperature class T3 (refer also to 2.9.16);

.2 storerooms for cylinders with flammable gases — sub-group IIC, temperature class T2;

.3 battery compartments — sub-group IIC, temperature class T1;

.4 spaces which enclose tanks, machinery and piping for inflammable liquids having a flash point 60 °C and below — sub-group IIB, temperature class T3.

Depth-sounder oscillators and associated cables shall be installed in compliance with the requirements of 3.7.4 and 3.8.3, Part V "Navigational Equipment" of the RS Rules/E, and ventilator motors shall be installed in spaces adapted for the carriage of dangerous cargoes in compliance with 12.7.4, Part VIII "Systems and Piping".

2.9.4 In spaces where explosive mixture of dust or fibre with air may accumulate electrical equipment with the degree of protection not below IP65 shall be installed.

Electrical equipment of IP55 type may be permitted where the occurrence of explosive mixture of dust or fibre with air is temporary, resulting from the damage or infiltration from processing equipment in operation or ventilation cutoff.

Electrical equipment installed in these spaces shall have such protective enclosure that the temperature of its upper horizontal surfaces or those inclined more than 60° to the horizontal is, under conditions of continuous operation, by 75 °C below the smouldering point of dust accumulated in these spaces (the smouldering point shall be determined for a layer of dust 5 mm thick).

2.9.5 Lighting fixtures of safe type shall be so installed that a free space around them is not less than 100 mm, excluding the place of the fastenings.

2.9.6 Any equipment installed in dangerous spaces and zones, except for fire detectors, shall be provided with switches fitted at a safe position outside dangerous spaces and zones to disconnect all live conductors.

2.9.7 Fastening of electrical equipment directly to the walls of tanks intended for flammable liquids is not allowed. In any case, electrical equipment shall be fastened at a distance not less than 75 mm from the tank walls.

2.9.8 In enclosed and semi-enclosed spaces where an explosive mixture of gas or vapour with air is not likely to occur, but direct openings lead to dangerous spaces, electrical equipment of safe type shall be generally installed.

Installation of electrical equipment of non-safe type, is permitted if the following conditions are observed:

.1 operation of alarms (visual and audible) and automatic disconnection of power supply (in sound cases with time delay) to electrical equipment if the ventilation is shut off;

.2 interlocking to provide for possible connection of electrical equipment only after adequate ventilation of the space (at least 10 air changes).

2.9.9 In compartments/holds intended for carriage of flammable cargoes the electrical equipment, which is essential for the safety and control of the ship, shall have a possibility to be completely isolated and protected against unauthorised actuation. The equipment shall be isolated from locations outside the dangerous zones by removing special disconnectors, by switches with interlocking devices or other effective means.

If provision of such equipment is necessary for the safety and control of the ship, the equipment shall be of certified safe type: intrinsically safe (*Exia* or *Exib*), pressurised enclosure (*Exp*), flameproof (*Exd*), increased safety (*Exe*).

2.9.10 In explosion-dangerous spaces and zones only the cables serving the electrical equipment fitted in such spaces and zones in full compliance with the requirements of 2.9.11 may be laid. The through runs of cables may be permitted in the above spaces and zones provided the requirements of 2.9.11 — 2.9.15 are complied with. No connections of cables laid in dangerous zones are permitted.

2.9.11 Cables installed in dangerous spaces and zones shall have protective covering of one of the following types:

.1 metal armour or braid with additional insulation covering;

.2 lead sheath with additional mechanical protection;

.3 copper or stainless steel sheath (only for cables with mineral insulation).

2.9.12 Cables passing through dangerous spaces and zones shall be suitably protected against mechanical damage.

Penetrations of cables through decks and bulkheads shall be sealed to avoid ingress of flammable gases or vapours.

2.9.13 All shields and metal braids of cables of power circuits for electric motors and lighting systems, which pass through dangerous spaces and zones or supply the electrical equipment installed in these spaces, shall be earthed at both ends at least.

2.9.14 Cables of intrinsically safe circuits shall be laid separately from other cables and shall comply with the requirements of IEC 60079-14 and IEC 60079-25.

2.9.15 Cables of portable electrical equipment, except for cables of intrinsically safe circuits, shall not pass through dangerous spaces and zones.

2.9.16 **Additional requirements for electrical equipment installed in paint lockers.**

2.9.16.1 Electrical equipment shall be installed in paint lockers and in ventilation ducts serving such spaces only when it is essential for operational services.

Safe type equipment of the following type is acceptable: intrinsically safe (*Exi*), pressurized (*Exp*), flameproof (*Exd*), increased safety (*Exe*), special protection (*Exs*).

2.9.16.2 The minimum requirements for the safe type equipment are as follows: explosion group IIB, temperature class T3.

2.9.16.3 In paint lockers and spaces mentioned under 2.9.16.4, cables (through-runs or terminating cables) of armoured type or installed in metallic conduits shall be used.

2.9.16.4 In the areas on open deck within 1 m of inlet and exhaust ventilation openings or within 3 m of exhaust mechanical ventilation outlets, the following electrical equipment may be installed: safe type equipment permitted by 2.9.16.1, equipment of protection class (Exn), appliances, which do not generate arcs or sparks in service and which surface does not reach unacceptably high temperature under normal conditions.

2.9.16.5 Enclosed spaces giving access to the paint locker may be considered as non-hazardous, provided that:

.1 the door to the paint locker is a gastight door with self-closing devices without holding-back arrangements;
.2 the paint locker is provided with an acceptable, independent, natural ventilation system ventilated from a safe area;
.3 warning notices are fitted adjacent to the paint locker entrance stating that the store contains flammable liquids.

2.10 ANTISTATIC EARTHING

2.10.1 Antistatic earthing is a mandatory mean of ensuring electrostatic intrinsic safety for all types of ships having dangerous spaces and zones.

2.10.2 Equipment to be installed on board, in enclosed and semi-enclosed spaces and zones where explosive mixtures of vapours, gases or dust with air likely to occur (refer to 2.9.1), as well as any portable equipment to be brought and installed in such spaces shall be antistatically earthed.

2.10.3 Bonding straps shall be required for cargo tanks/process plant/piping systems which are not permanently connected to the hull of the ship, e.g.:

.1 independent cargo tanks;

.2 cargo tanks/piping systems which are electrically separated from the hull of the ship;

.3 pipe connections arranged for the removal of spool pieces;

.4 wafer-style valves with non-conductive (e.g PTFE) gaskets or seals.

2.10.4 The following equipment does not require use of the antistatic earthing conductors:

.1 fixed and portable electrical equipment shields and metal armour of cables earthed in accordance with 2.5;

.2 pipes and conduits for installation of cables earthed in accordance with 16.8.8;

.3 electrical equipment, automation equipment, radio equipment and navigational equipment earthed in accordance with 2.2.2;

.4 equipment and structures provided with lightning protection earthing in accordance with 2.6.6.

2.10.5 Arrangement and monitoring of antistatic earthing.

2.10.5.1 Where bonding straps are required, they shall be: clearly visible so that any shortcomings can be clearly detected; designed and sited so that they are protected against mechanical damage and that they are not affected by high resistivity contamination e.g. corrosive products or paint; easy to install and replace.

2.10.5.2 Bonding straps shall be connected to the non-metallic equipment, e.g. plastic pipes, in a manner defined by the manufacturer of the equipment. Design of the bonding straps being the component part of the equipment delivered to the ship shall meet the requirements of relevant Parts of the Rules or the standards approved by the Register.

2.10.5.3 Resistance of the antistatic earthing shall be monitored by portable instruments of any type with control d.c. voltage of not more than 10 V. The resistance value measured between the equipment, component, structure being monitored and ship's hull shall not exceed 10^6 Ohm with the area of contact between the measure electrode and the equipment surface being no more than 20 mm^2.

2.11 ARRANGEMENTS AND SYSTEMS FOR INSULATION RESISTANCE MONITORING

2.11.1 In each isolated ship power system with the nominal voltage above 50 V AC or above 110 V DC provision shall be made for an automatic continuous monitoring of insulation resistance of currentcarrying components relative to ship's hull. Measurements periodicity during the periodic monitoring shall not exceed 300 s.

2.11.2 In the networks with the voltage 1000 V and above monitoring of the insulation resistance shall be carried out only alive with the use of passive monitoring methods (for example, with the use of zerosequence current transformer).

2.11.3 Devices for insulation resistance monitoring in the networks with the voltage up to 1000 V shall:

be fitted with an indicator showing the insulation resistance value;

have visible and audible alarm at decrease of controlled value under the prescribed limit;

allow to perform smooth adjustment of alarm actuating setting value within the range from 100 to 5 kOhm. The current setting value shall be indicated;

have an operation speed sufficient for measuring insulation resistance value in the networks with the existing capacity level during the measurement cycle of the device which shall not exceed 30 s;

produce measuring current not exceeding 0,03A under all modes (including transient);

provide for the possibility of periodic intactness monitoring under operational conditions by means of earth leakage current through an active resistance equal to 80 % of resistance of the relevant setting actuating.

2.11.4 Location of devices for insulation resistance monitoring shall meet the requirements of 4.6.4.7.

3 MAIN ELECTRICAL POWER SOURCE

3.1 COMPOSITION AND CAPACITY OF MAIN ELECTRICAL POWER SOURCE

3.1.1 In every ship, a main electric power source shall be provided with a capacity sufficient to supply all the electrical equipment on board under conditions specified in 3.1.5. Such a source shall consist of two independently driven generators at least.

In ships of 300 gross tonnage and below (except for passenger ships), accumulator batteries may be the main power source.

3.1.2 The number and capacity of independently driven generators and electric converters, of which the main electrical power source is composed, shall be such that if any of them failed the rest would ensure:

.1 supply to electrical equipment essential for propulsion, steering and safety of the ship with the normal habitable conditions on board guaranteed;

.2 start of the most powerful electric motor with the greatest starting current. The motor start shall not involve a voltage and frequency drop in the mains that could result in a fall out of synchronism, stop of generator engine or disconnection of machinery and apparatus being in operation;

.3 supply to consumers necessary to start the propulsion plant (refer to 1.2.1, Part VII "Machinery Installation") when the ship is de-energized. For this purpose, emergency electrical power source may be used if its capacity proper or in association with the capacity of any other electrical power source would ensure a simultaneous supply of consumers listed under 9.3.1 — 9.3.3 or under 20.1.2.1 — 20.1.2.3 (refer also to 2.1.6, Part VII "Machinery Installations"), for this purpose their parallel operation may be provided.

3.1.3 Where the main electrical power source is needed to ensure propulsion and steering of the ship, provision shall be made that the power supply to the equipment essential for propulsion and steering and to ensure safety of the ship is maintained continuously or restored immediately in case of failure of any generator being in operation.

Along with that, in ships where electrical power is normally supplied by two or more generators running in parallel, provision shall be made for automatic switching-off of less essential consumers without any overloading of the remaining generators, with retention of power supply to consumers essential for propulsion, steering and to ensure safety of the ship.

In ships where electrical power is normally supplied by one generator, in case of its failure and deenergization of the main switchboard, provision shall be made for:

automatic starting of stand-by generator of sufficient capacity and its connection to busbars of the main switchboard within 45 s;

automatic re-starting, in the necessary sequence, of essential devices ensuring propulsion, steering and safety of the ship.

3.1.4 Instead of one independently driven generator as mentioned under 3.1.1, a generator driven by the main engine (shaft generator) may be used if it complies with 3.2.3 under conditions listed below:

.1 the shaft generator operates practically at a constant speed (in the set frequency range for an electrical power plant with variable frequency main power source) under different operating conditions of the ship;

.2 provision is made for actuation of the ship's propulsion plant in case of failure of any generator with an independent prime mover.

3.1.5 The number and power output of generators forming the main source of electrical power shall be determined with regard to the following operating conditions of the ship:

.1 running conditions;

.2 manoeuvring;

.3 in case of fire, hole in the ship's hull or other conditions affecting the safety of navigation, with the main sources of electrical power in operation;

.4 other operating conditions according to ship's purpose.

3.1.6 Where accumulator batteries are the main source of electrical power, their capacity shall be sufficient to satisfy the requirements of 3.1.2.1 for 8 h without recharging; provision shall be made for charging of accumulator batteries from the source of electrical power installed on board. For ships of restricted area of navigation **R3** with limited voyage duration, lack of access to the source of electrical power installed on board the ship to charge the accumulator batteries may be permitted, provided the voyage duration does not exceed 8 h.

For ships of restricted area of navigation **R3** with charging of accumulator battery of the main source between the voyages, the battery capacity may be reduced but not more than to triple energy consumption for the period of the longest design voyage.

3.2 GENERATOR SETS

3.2.1 General.

3.2.1.1 Engines designed for use as generator prime movers shall comply with the requirements set forth in Sections 2, 3 and 8, Part IX "Machinery", and, additionally, with the requirements of the Chapter.

3.2.1.2 Electric machine sets shall be designed for continuous duty, with regard to the power reduction during ship's service under conditions specified in 2.1.1.1.

3.2.1.3 Under short circuit in the ship's mains the generators shall provide for the value of the sustained short-circuit current sufficient for the operation of protective devices.

3.2.1.4 The voltage of generators shall be regulable within the range specified in 10.6 and 10.7 of this Part, and speed frequency shall be regulable within the range specified in 2.11.3, Part IX "Machinery".

3.2.2 Load sharing between sets running in parallel.

3.2.2.1 Alternating-current sets intended to run in parallel shall be provided with such a reactivevoltage drop compensating system that when the sets run in parallel the reactive load sharing between the generators does not differ from a value proportional to their output by more than 10 % of the rated reactive load of the largest generator involved or by not more than 25 % of the rated output of the smallest generator if this value is lower than the above one.

3.2.2.2 When the alternating-current sets run in parallel at 20 to 100 % of the total load, load sharing shall be within the limits specified in 2.11.3, Part IX "Machinery".

3.2.3 Shaft generator sets.

3.2.3.1 Where shaft generators are used for feeding the ship mains, automatic connection of one or more independently driven generators to the ship mains shall be provided, or an alarm shall be activated in the engine room or at the main machinery control room in case the network frequency is below the permissible value.

3.2.3.2 Shaft generators intended for supply of particular consumers may operate under parameters, which differ from those specified in 3.2.1.4.

3.2.3.3 Shaft generators and semiconductor transducers (inverters) supplying the ship mains shall not be damaged by short circuits at the main distribution board busbars. In this case, a steady short circuit current shall be ensured, sufficient for protection to be activated.

3.2.3.4 As a minimal requirement, shaft generators shall be designed for short periods of parallel running with other types of generator sets so that manual or automatic (if available) switch-over of the load is possible.

3.2.3.5 For shaft alternators, automatic devices shall be provided to preclude the current overload of their excitation system components when running at a speed below 90 % of the nominal speed during more than 5 s. In this case, a proportional voltage lowering across the generator terminals is permitted.

3.2.3.6 For each shaft generator, a de-excitation device shall be provided at the main distribution board, and measuring instruments as listed under 4.6.4.3.

3.2.3.7 When the shaft generator is connected into the ship mains, a visual warning signal shall be activated at the navigation bridge indicating that a change in the mode of main machinery operation might bring about a deviation in the ship main parameters beyond the limits stipulated by 10.6 and 10.7 of this Part and 2.11.3, Part IX "Machinery".

3.2.3.8 A generator with an independent prime mover may be used in shaft generators with semiconductor converters as a synchronous condenser. In such cases, a disengaging clutch shall be fitted between the generator and its prime mover.

3.2.4 Exhaust-heat turbogenerators.

3.2.4.1 Exhaust-heat turbogenerators supplying particular consumers may have performance characteristics different from those stated under 3.2.1.4.

3.2.4.2 The exhaust-heat turbogenerators used for feeding the ship mains shall be designed for parallel operation with generators having an independent prime mover. In this case, the distribution of load between the generator sets shall be in accordance with 3.2.2.

3.3 NUMBER AND CAPACITY OF TRANSFORMERS

3.3.1 In ships, where lighting and other circuits of essential services are powered through transformers, not less than two transformers shall be provided of such a capacity that in case of failure of the largest unit, the remaining transformers are capable of satisfying the complete need in electrical power under all operating conditions of the ship.

Where subdivided system of busbars is used, transformers shall be connected to different sections of the main switchboards.

In ships of less than 300 gross tonnage (other than passenger ships) of restricted areas of navigation **R2**, **R2-RSN**, **R2-RSN(4,5)**, **R3-RSN** and **R3**, with the electrical installation of low power installation of only one transformer is allowed.

3.4 POWER SUPPLY FROM AN EXTERNAL SOURCE OF ELECTRICAL POWER

3.4.1 If provision is made for ship's mains to be supplied from an external source of electrical power, an external supply switchboard shall be installed in the ship (refer also to 4.6.4.6).

For ships with the electrical installation of low power it is allowed that cables for supply of the ship's mains from an external source of electrical power shall be connected to the main switchboard directly.

3.4.2 At the external supply switchboard, the following facilities shall be provided:

.1 terminals for flexible cable connection;

.2 switch gear and protection devices for connecting and protection of permanently laid cable of the main distribution switchboard; where the cable length between the external supply switchboard and the main distribution switchboard is less than 10 m, no protection devices may be fitted;

.3 voltmeter or pilot lamps to indicate the presence of voltage from an external source across the terminals;

.4 device or facilities for connecting a device to control polarity and phase sequence;

.5 terminal for earthing a neutral wire from an external source;

.6 plate to indicate voltage, type of current and frequency;

.7 arrangement for mechanical fixation of the end of flexible cable connected to the switchboard and a hanger for the cable, which shall both be provided at the external supply switchboard or in its vicinity.

3.4.3 When supplying the ship's mains from an external source of power with the earthed neutral wire, the cross-sectional area of the wire shall be at least 1/2 of the cross-sectional area of the supply cable.

3.5 CONNECTION OF ELECTRICAL POWER SUPPLY UNITS

3.5.1 Where the electrical power supply units are not adapted for long operation in parallel to feed common busbars, it is necessary to use a connection circuit ensuring their switching-on for parallel operation for the duration of load transfer from one unit to another.

3.5.2 Direct current compound-wound generators designed for parallel operation shall have equalizing connections.

3.5.3 Where alternating-current generators are intended to operate in parallel, a synchronizer shall be installed in the main switchboard.

Where synchronizing is arranged to operate automatically, a standby manual synchronizer shall be provided by one operator.

3.5.4 Where several direct-current generators are installed, a magnetizing device shall be fitted in the main switchboard.

Such device may be also allowed for synchronous alternating-current generators if it is necessary for initial excitation.

3.5.5 Where the ship's and external sources of electrical power are not intended to operate in parallel to the common busbars of the ship's electrical installation, the system of connections shall be so interlocked, in this case, as to prevent their possible switching-on for parallel operation.

3.5.6 Where the main source of electrical power is necessary for propulsion of the ship, the main busbar shall be subdivided into at least two parts, which shall normally be connected by circuit breakers or other approved means (e.g. circuit breaker without release or disconnector). Bolted links between the main switchboard sections, by which the busbars can be split, are not acceptable.

So far as it is practicable, the connection of generating sets and other duplicated equipment shall be equally divided between the parts.

4 DISTRIBUTION OF ELECTRICAL POWER

4.1 DISTRIBUTION SYSTEMS

4.1.1 The following systems of electrical power distribution are acceptable:
.1 for alternating current up to and including 1000 V:
.1.1 three-phase three-wire insulated system;
.1.2 three-phase three-wire system with neutral earthed through high-value resistor or reactor (compensated-resistored neutral);
.2 additionally for current up to and including 500 V:
.2.1 three-phase four-wire insulated system;
.2.2 three-phase four-wire system with neutral earthed according to 4.1.1.1.2;
.2.3 single-phase two-wire insulated system;
.2.4 single-phase two-wire system with neutral earthed according to 4.1.1.1.2;
.2.5 single-phase single-wire system with hull return for voltage up to 50 V (in ships of less than 1600 gross tonnage), except stated in 6.8.4, provided that any possible current will not pass directly through any of the dangerous spaces;
.3 for direct current:
.3.1 two-wire insulated system;
.3.2 single-wire system with hull return for voltage up to 50 V (in ships of less than 1600 gross tonnage), except stated in 6.8.4, provided that any possible current will not pass directly through any of the dangerous spaces.

Where a hull return system is used, all final circuits shall be two-wire and the insulated return wire shall be earthed by connecting to the earthing busbar of the distribution board supplying the circuit, at the place accessible for inspection. In this case devices shall be provided for isolating the earthing busbars from the hull to test insulation condition.

In ships of 1600 gross tonnage and upwards the use of local earthed systems is accepted for supplying the following consumers (provided that any possible current will not pass directly through any of the dangerous spaces and zones):
.1 electrical (battery) starter systems of internal combustion engines;
.2 impressed-current cathodic protection systems;
.3 insulation resistance monitoring and measuring systems (refer to 4.6.4.7).

4.2 PERMISSIBLE VOLTAGE

4.2.1 Proceeding from the electrical power distribution system used, the permissible voltage across the terminals of power generating sets of electrical power sources with frequencies of 50 and 60 Hz shall be found under 4.1. Additional requirements for apparatus designed for a voltage in excess of 1000 V shall be found in Section 18.

4.2.2 Permissible voltage across the terminals of sources of electrical power and direct current sources shall not exceed the values below:

1500 V for systems with electrical power distribution for direct current complying with the requirements of Section 23;

500 V for power systems;

250 V for lighting and heating systems, and socket outlets.

4.2.3 Permissible voltage across the terminals of alternating-current consumers shall not exceed the values specified in Table 4.2.3.

Table 4.2.3

Nos	Consumers	Permissible voltage, V
1	Permanently installed power consumers, cooking and heating appliances permanently installed in spaces other than those specified in item 2	1000
2	Portable power consumers supplied from socket outlets fixed in position when used, heaters in cabins and passenger accommodation (refer to 15.2.5)	500
3	Lighting, signalling and internal communication, socket outlets for portable consumers with double or reinforced insulation or isolated electrically by isolating transformer	250
4	Socket outlets fitted in locations and spaces with increased humidity, and in extra humid spaces, and intended for supply of consumers having no double or reinforced insulation and not isolated electrically	50

4.2.4 Permissible voltage across the terminals of direct-current consumers shall not exceed the values specified in Table 4.2.4.

Table 4.2.4

Nos	Consumers	Permissible voltage, V
1	Permanently installed power consumers	500
2	Cooking, heating, etc. appliances	250
3	Lighting, socket outlets[1]	250

[1] In spaces with increased humidity and extra humid spaces, notices shall be provided at socket outlets with voltage exceeding the overrating voltage to notify of the use of consumers with double or reinforced insulation or those electrically isolated from overrating voltage.

4.3 POWER SUPPLY OF ESSENTIAL SERVICES

4.3.1 The following services shall be supplied by separate feeders from the main switchboard busbars:

.1 steering gear electric drives (refer also to 5.5.2);
.2 anchor gear electric drives (refer also to 4.3.3);
.3 fire pump electric drives;
.4 bilge pump electric drives;
.5 electric drives of sprinkler system compressors and pumps equipment to ensure operating of foam generators of high expansion foam system;
.6 refrigerating plant switchboard for cargo holds;
.7 electric drives of exciter sets of propulsion plant;
.8 section main-lighting switchboards;
.9 radio equipment switchboard;
.10 switchboard of navigational equipment;
.11 navigation light switchboard;
.12 section switchboards and distribution gear for supplying other essential services combined on the principle of uniformity of their functions;
.13 switchboards of integrated bridge control console (refer also to 4.5);
.14 switchboard of automatic fire detection system;
.15 electric drives of auxiliaries ensuring the operation of main machinery;
.16 switchboards of electric drives for cargo, mooring, boat and other gears, ventilation and heating appliances;
.17 control devices of controllable pitch propeller;
.18 charging facilities of starter accumulator batteries and batteries supplying essential consumers;
.19 for ships contracted for construction or conversion before 1 January 2024, ships, the keels of which are laid or which are at a similar stage of construction before 1 January 2024, and ships delivered before 1 January 2024, switchboards of electric drives for closure of watertight doors and devices holding fire doors in open position and closure of watertight and fire doors. For ships contracted for construction or conversion on or after 1 January 2024, ships, the keels of which are laid or which are at a similar stage of construction on or after 1 January 2024, and ships delivered on or after 1 January 2024, switchboards of devices holding fire doors in open position and switchboards of alarms for position and closure of fire doors;
.20 switchboard of refrigerating plant for the low pressure carbon dioxide extinguishing system;
.21 lighting switchboards for hangars and helicopter deck illumination.

It is permitted to supply services indicated in 4.3.1.4, 4.3.1.9 — 4.3.1.11, 4.3.1.14, 4.3.1.15, 4.3.1.17 — 4.3.1.19, from switchgear indicated in 4.3.1.12 or 4.3.1.13 by separate out-going feeders provided with adequate switching and protective devices.

4.3.2 In case one-purpose machinery with electric drives indicated in 4.3.1 is installed in double or greater number, except for specified in 4.3.1.1, 4.3.1.5 and 4.3.1.7 at least one of these drives shall be energized by a separate feeder from the main switchboard. Electric drives of the rest of such machinery are allowed to be supplied from section switchboards or special distribution devices intended for supply of essential services.

When the collecting busbars in the main switchboard are subdivided into sections having intersectional disconnecting devices, the electric drives, section switchboards, special distribution devices or boards installed in double or greater number or supplied by two feeders shall be connected to different sections of the main switchboard.

4.3.3 In cargo ships of restricted areas of navigation **R2**, **R2-RSN**, **R2-RSN(4,5)**, **R3-RSN** and **R3**, and in particular cases in ships of unrestricted service and ships of restricted area of navigation **R1**, the supply feeder of anchor gear may be connected to the distribution board of cargo winches or to another distribution board, on special approval of the Register, provided the boards are supplied directly from the main distribution board and adequate protection is available.

4.3.4 Final sub-circuits having a current rating in excess of 16 A shall supply not more than one consumer.

4.4 POWER SUPPLY OF ELECTRICAL (ELECTRONIC) AUTOMATION SYSTEMS

4.4.1 Power supply of electrical (electronic) automation systems shall satisfy the requirements of Part XV "Automation".

4.4.2 Power supply of automation devices necessary for starting and operating the emergency diesel generator shall be taken from a starter battery or another independent accumulator battery installed in the emergency diesel generator space.

4.5 POWER SUPPLY TO INTEGRATED BRIDGE CONTROL CONSOLE

4.5.1 When locating in the integrated bridge control console the electrical equipment, navigational equipment, radio equipment, electrical automatic and remote-control equipment for the main and auxiliary machinery, such equipment shall be supplied by separate feeders as required in this Chapter and other parts of the Rules.

It is allowed to feed the equipment specially listed in 4.3.1 from the switchboards of the integrated bridge control console, provided the requirements of 4.5.2 — 4.5.6 are met (refer to 9.4.3 as well).

4.5.2 The switchboards of the integrated bridge control console shall be fed from the main switchboard directly or through the transformers by two independent feeders connected to different sections of the main switchboard busbars, where busbars are subdivided.

When the emergency generator is provided on board the ship, the switchboards of the integrated bridge control console shall be supplied by one feeder from the main switchboard and by one feeder from the emergency switchboard.

4.5.3 In addition, the switchboards of the integrated bridge control console shall be independently supplied by a separate feeder from other source or sources of power, if necessary, basing on the requirements for the equipment fed from these switchboards.

4.5.4 The switchboard shall be provided with a change-over switch for feeders specified in 4.5.2.

If an automatic change-over switch is used, manual switching of feeders shall be also ensured. In this case, provision shall be made for necessary interlocking.

4.5.5 Each consumer specially listed in 4.3.1 fed from the switchboards of the integrated bridge control console shall be supplied by a separate feeder (refer also to 9.4.3).

4.5.6 In the integrated bridge, control console a light signalling device indicating the presence of voltage shall be fitted.

4.6 SWITCHBOARD AND SWITCHGEAR

4.6.1 Switchboard design and construction.

4.6.1.1 Frames, front panels and enclosures of main, emergency, section and distribution switchboards shall be constructed of metal or some other durable non-combustible material.

Where the aggregate capacity of generators intended for parallel operation exceeds 100 kW, barriers shall be installed between the generator sections and adjacent sections for protection against the effects of arcs.

4.6.1.2 Switchboards shall be of rigid construction capable of withstanding the mechanical stresses liable to occur under service conditions or as a result of short circuits.

4.6.1.3 Switchboards shall at least be protected from drip. This protection is not required if the switchboards shall be located in spaces where the conditions are such that no vertically falling drops of liquid can get into the switchboard (refer also to 4.6.6.2).

4.6.1.4 Switchboards intended to be installed in places accessible to unauthorized persons shall be provided with doors to be opened by means of a special key, the same for all the switchboards in the ship.

4.6.1.5 The design of switchboard doors shall be such that with the doors opened access is assured to all parts which require maintenance, and the live parts located on the doors shall be protected against inadvertent touching.

Opening panels and doors, which are used for mounting electrical control gear and measuring instruments, shall be securely earthed with at least one flexible connection.

4.6.1.6 Handrails shall be fitted to main, emergency and section switchboards and to control panels on their front sides. Switchboards accessible from the rear shall be provided with horizontal handrails fitted at the back.

The materials, which may be used for manufacture of handrails, are insulating material, wood or earthed metal pipes with insulating covering.

4.6.1.7 The generator panels of main switchboards shall be illuminated with lighting fixtures supplied on the generator side before the circuit breaker of the generator or not less than from two different busbar systems in case these systems are provided according to 3.5.6. When no such systems are provided, lighting fixtures may be supplied from the emergency switchboard.

4.6.1.8 The lighting of the front side of switchboard panels shall not interfere with instrument observation or produce a blinding effect.

4.6.1.9 The design of switchboards and control consoles not accessible from the rear shall be such that the access is ensured to all parts requiring maintenance.

Arrangements shall be provided for doors of switchboards to fix them in the open position.

Withdrawable blocks and instruments shall be fitted with devices to prevent their fall-out in the withdrawn position.

4.6.1.10 Each distribution device designed for voltage over the safe, with switchgear and protective devices and without a voltmeter, shall be furnished with a pilot lamp, which indicates the presence of voltage on busbars.

4.6.2 Busbars and uninsulated conductors.

4.6.2.1 The maximum permissible temperature for switchboard busbars and uninsulated conductors at the rated load and short-circuit current or at the permissible one-second short-circuit load for copper busbars shall be determined according to national standards.

4.6.2.2 Equalizer busbars shall be designed for at least 50 % of the rated current of the largest generator connected to the main switchboard.

4.6.2.3 Where the busbar is in contact with or close to insulated parts, its heat effects shall not cause under operating or short-circuit conditions a temperature rise in excess of that allowable for a given insulating material.

4.6.2.4 Busbars and uninsulated conductors in switchboards shall have adequate electrodynamic and thermal strength during short-circuit currents occurring at relevant points in the circuit.

Such electrodynamic loads as occur in busbars and uninsulated conductors due to short circuit may be as specified in the relevant national and international standards.

4.6.2.5 Insulators and other parts designed to support busbars and uninsulated conductors shall be capable of sustaining the loads due to short circuits.

4.6.2.6 The natural frequency of copper tier busbars shall be outside the ranges of 40 — 60 Hz and 90 — 110 Hz for rated frequency of 50 Hz, 50 — 70 Hz and 110 to 130 Hz for rated frequency of 60 Hz.

4.6.2.7 Busbars and uninsulated conductors of different polarity or of different phases shall be marked with distinguishing colours in accordance with IEC 60445:2017 or national standards.

4.6.2.8 Busbars shall be connected so as to prevent corrosion in way of connections.

4.6.2.9 Connection between switchboard busbars, arranged with a cable or flexible busbar conduit, shall be protected against a short circuit. Protection may be omitted if the length of such connection does not exceed 3 m and it is arranged with a cable or flexible busbar with double insulation of conductors.

4.6.3 Calculation of short-circuit currents and selection of electrical switch apparatus.

4.6.3.1 Short-circuit current shall be calculated on the basis of the standards or calculation methods approved by the Register.

4.6.3.2 In calculations of the maximum and minimum short-circuit currents a source of short-circuit current shall contain all generators including synchronous condensers, which may be connected in parallel, and all electric motors running simultaneously and able to produce current contribution to the short-circuit point[1]. Calculation is carried out at three-phase "metal" short-circuit.

Calculation of short-circuit currents shall be performed for all electric circuits where electrical equipment is installed which was selected and monitored with regard to permissible short-circuit current supplied directly from the busbars of the main switchboard, including busbars of switchboards for their testing for electrodynamic withstandability and heating while passing of short-circuit current.

These calculations shall be made at least for the following points:

on the generator side on the automatic circuit breaker terminals;

on the main switchboard busbars;

on the emergency switchboard busbars;

on the terminals of electric power consumers and busbars of the switchboards supplied directly from the main switchboard.

For evaluation of protective sensitiveness the calculation shall be made both of maximum and minimum short-circuit currents at the terminals of power consumers.

Calculation of short-circuit current in the circuit from the generator terminals up to the main switchboard busbars is made at the outputs of the generator automatic circuit breaker. Short-circuit current at the generator terminals is calculated with the availability of inner short-circuit protection of stator winding (for example, differential protection).

The results of short-circuit current calculation shall contain the list of all the electrical switch apparatus fitted and their parameters, as well as the maximum and minimum prospective short-circuit current at the points of their installation.

4.6.3.3 Requirements for short-circuit currents in systems with electrical power distribution for direct current are specified in 23.3.4.

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[1] Electrical motors supplied from semiconductor converters do not produce current contribution.

4.6.4 Electric switch apparatus and instrumentation.

4.6.4.1 Apparatus, measuring and indicating instruments used in connection with generators and other large essential installations shall be fitted on the switchboards associated with the appropriate generators and installations.

This requirement may be dispensed with in the case of generators where there is a central control console with switch gear and measurements for several generators.

4.6.4.2 One ammeter and one voltmeter shall be provided for each direct-current generator on the main and emergency switchboards.

4.6.4.3 The following instruments shall be provided for each alternating current generator on the main switchboard and for emergency generator on the emergency switchboard:

.1 an ammeter with a selector switch for current measurements in each phase;

.2 a voltmeter with a selector switch for measuring phase or line voltages;

.3 a frequency indicator (use of one double frequency indicator is permissible for generators operating in parallel with change-over to each generator);

.4 a wattmeter (for output upwards of 50 kVA);

.5 other instruments as required.

4.6.4.4 In ships having a low-power electrical installation, in which the generators are not expected to operate in parallel, one set of instruments as stipulated by 4.6.4.2 and 4.6.4.3 may be installed at the main and emergency switchboards, which would ensure a possibility of taking measurements at each generator installed.

4.6.4.5 Ammeters shall be installed in the circuits of essential consumers rated at 20 A and over. These ammeters may be installed on the main switchboard or at the control stations.

It is allowed to install ammeters with selector switches but not more than for six consumers.

4.6.4.6 In the main switchboard the feeder energized from the external power source shall be provided with:

.1 switchgear and protective devices;

.2 a voltmeter or a pilot lamp;

.3 means of protection against phase breaking.

4.6.4.7 A change-over arrangement or a separate device for each network of isolated systems for measuring and indicating insulation resistance shall be installed on the main and emergency switchboards.

In any case, the hull leakage current due to the operation of the measuring device shall not exceed 30 mA.

Provision shall be made for audible and visual alarms to warn of inadmissible decrease in the insulation resistance.

In ships with unattended machinery spaces this signalling shall be also provided at the ship's main machinery control room.

4.6.4.8 Measuring instruments shall have scales with a margin of divisions in excess of the rated values of quantities to be measured.

The upper scale limits of the instruments used shall not be less than:

.1 for voltmeters — 120 % of the rated voltage;

.2 for ammeters associated with generators not operating in parallel and with current consumers — 130 % of the rated current;

.3 for ammeters associated with parallel-operating generators — 130 % of the rated current for load-current scale and 15 % of the rated current for reverse-current scale (the latter refers only to direct- current generators);

.4 for wattmeters associated with generators not operating in parallel — 130 % of the rated output;

.5 for wattmeters associated with generators opera-ting in parallel — 130 % for power scale and 15 % for reverse power scale;

.6 for frequency indicator — ±10 % of the rated frequency.

4.6.4.9 Voltage, current and power ratings of electric power plant and generators shall be clearly indicated on the scales of electrical measuring instruments.

4.6.4.10 Wherever possible, switchgear shall be installed and connected to busbars in such a way that none of the movable elements and protective or control devices associated with switchgear are energized in the open position.

4.6.4.11 When switches with fuses are installed in outgoing circuits of switchboards, the fuses shall be positioned between the busbar and the switch.

4.6.4.12 Where switchboards are installed on a foundation at the floor level, the fuses shall be located not lower than 150 mm and not higher than 1800 mm from the floor level.

Live open parts of switchboards shall be located at a height of not less than 150 mm above the floor level.

4.6.4.13 Fuses shall be so installed in switchboards that they are easily accessible and the fuse link replacement is not dangerous for the operating personnel.

4.6.4.14 The fuses protecting the poles or phases of the same circuit shall be installed in a row, horizontally or vertically depending on the fuse design. The fuses in an a.c. circuit shall be positioned to follow the sequence of phases from left to right or from top to bottom.

In a d.c. circuit the positive-pole fuse shall be on the left, at top, or closer to reach.

4.6.4.15 The manual actuators of voltage regulators installed in main or emergency switchboards shall be positioned close to the measuring instruments associated with the respective generators.

4.6.4.16 The ammeters of direct current compound generators intended for operation in parallel shall be included in the hole circuit not connected to the common wire.

4.6.4.17 For connecting portable and semi-portable instruments, flexible-stranded conductors shall be used.

4.6.4.18 Switch electrical apparatus controls, panels and outgoing circuits on the switchboards shall have their designations marked. The apparatus switching positions shall be also indicated. Besides, markings shall be provided to indicate the rated currents of the installed safety devices and switches, settings of circuit breakers and electrothermal trips.

4.6.4.19 Each outgoing circuit in a switchboard shall be provided with an appropriate circuit breaker to disconnect all poles and phases. Switches or circuit breakers may be dispensed with in lighting branch boxes provided with a common switch and also in the circuits of instruments interlocking devices, alarms and local lighting of switchboards protected by fuses.

4.6.5 Light signals.

4.6.5.1 Light signals shall be of the colour specified in Table 4.6.5.1.

Table 4.6.5.1

Colour	General meaning	Type of signal	Condition of device
Red	Danger	Blinking	Alarm in dangerous conditions where immediate action is necessary
		Permanent	Alarm in dangerous conditions,detected, but not yet rectified
Yellow	Attention	Blinking	Abnormal conditions where immediate action is not required
		Permanent	Intermediate condition between abnormality and safety
			Abnormal condition already detected, but not yet rectified
Green	Safety	Blinking	Standby machinery is put into operation
		Permanent	Rated conditions of running and operation
Blue	Information	Permanent	Machinery and gear are ready to be started
			Voltage in mains. Everything is in order
White		Permanent	Signals switched on when necessary

Colour	General meaning	Type of signal	Condition of device
	General information		Notations relating to automatic control conditions
			Other auxiliary signals

4.6.5.2 The use of letters as light signals is acceptable on condition that letters clearly identify the condition of device.

4.6.6 Arrangement of distribution gear.

4.6.6.1 The switchboards shall be placed in locations where the possible concentration of gases, water vapours, dust and acid evaporations is eliminated.

4.6.6.2 If the switchboard having protective enclosure of IP10 type and below is located in a special space, cabinet or recess, then such spaces shall be made of non-combustible material or shall have a lining of such material.

4.6.6.3 Arrangement of pipelines and tanks near the switchboards shall conform to the requirements of 5.5, Part VIII "Systems and Piping".

4.6.6.4 The navigation lights switchboard shall be located in the wheelhouse where it is readily accessible and visible to the personnel on watch.

4.6.6.5 The main switchboard and generating sets shall be positioned in close proximity to each other, in the same engine room and within the boundaries of the same "A-60" class vertical and horizontal fire-resistant constructions. The enclosure situated within the main boundaries of machinery space, provided for the main machinery control room where the main switchboard is positioned, is not considered as separating the main switchboard from the generating sets.

Where essential services for steering and propulsion of ship are supplied from section switchboards these switchboards and any transformers, converters and similar equipment forming the essential part of the system supplying these services shall be also positioned in the same space as generating sets.

4.6.7 Access to switchboards.

4.6.7.1 In front of the main, emergency and other switchboards, a passageway shall be provided not less than 1000 mm wide for switchboards 3 m long and over. In front of the main and emergency switchboards, a passageway shall be provided not less than 800 mm wide for switchboards up to 3 m long and on ships of less than 500 gross tonnage, the passageway shall be at least 600 mm wide.

If withdrawable arrangements are provided in front of the main and emergency switchboards, the free space in the passageway shall be not less than 400 mm wide from the most protruding parts of this arrangement in completely withdrawn position.

In any case, if opening swing panels are located in front of the switchboard, the width of the passageway shall be sufficient for switchboard maintenance with the panel at a fully open position.

4.6.7.2 Behind the free standing main and emergency switchboards, it is necessary to provide a passageway not less than 600 mm wide. In case of passageway narrowing caused by location of hull framing (frames, stiffeners, etc.) behind the main or emergency switchboard, the width of passageway at the narrowing point may be reduced down to 500 mm.

In any case, if opening swing panels are located behind the switchboard, the width of the passageway shall be sufficient for switchboard maintenance with the panel at a fully open position.

Between the free standing switchboards with open live parts located in special electrical spaces a passageway shall not be less than 1000 mm wide.

4.6.7.3 The space behind the free standing switchboards with open live parts shall be enclosed and fitted with doors in accordance with 2.8.1.

4.6.7.4 For switchboards more than 3 m in length mentioned in 4.6.7.3 at least two doors shall be provided leading from the space where the switchboard is installed to the space behind the switchboard. These doors shall be as widely spaced as possible.

It is allowed that one of these doors shall lead to the adjacent space having at least another exit.

4.6.7.5 Passageways specified in 4.6.7.1 and 4.6.7.2 are measured from the most protruding parts of apparatus and structure of the switchboard to the protruding parts of equipment or hull structures.

5 ELECTRIC DRIVES FOR SHIPBOARD MECHANISMS AND EQUIPMENT

5.1 GENERAL

5.1.1 The control stations of the drives shall meet the relevant requirements of Part VII "Machinery Installations", while the power supply of electrical (electronic) automation systems shall meet the requirements specified in Part XV "Automation".

5.1.2 Electrically-driven mechanisms shall be provided with light signals to indicate switching-on of the electric drive.

5.1.3 Equipment provided with automatic, remote and local control shall be so designed that the automatic control is switched off as well as the remote control when the change-over to the local control occurs. The local control shall be independent both of the automatic and remote control.

5.2 INTERLOCKING OF MACHINERY OPERATION

5.2.1 The machinery provided with electric and manual drives shall be fitted with an interlocking device that will prevent simultaneous operation of the drives.

5.2.2 If the machinery is required to operate in a certain sequence, appropriate interlocking devices shall be used.

5.2.3 A device may be installed that will switch off the interlocking on condition that this device is protected from switching off the interlocking inadvertently. Informative inscription shall be placed in close proximity to this device that will indicate its application and forbid its use by unauthorized personnel.

Such a device is not permitted for machinery specified in 5.2.1.

5.2.4 Starting of the machinery, which electric motors or switchgear require additional ventilation in normal operation, shall be possible only with ventilation in action.

5.3 SAFETY ISOLATION DEVICES

5.3.1 Control systems of mechanisms, which operation under certain conditions may endanger human or ships safety, shall be provided with push-buttons or other safety isolation devices that will ensure disconnection of the electric drive from the power supply.

These push-buttons and/or other safety isolation devices shall be suitably protected against inadvertent actuation.

5.3.2 Push-buttons or other safety isolation devices shall be located near the control stations or in other places with a view to ensure safety of operation.

5.3.3 Electric drives of arrangements and machinery which require restriction of motion to prevent damage or break-down shall be provided with terminal switches to ensure reliable isolation of the electric motor.

5.4 SWITCHGEAR AND CONTROL GEAR

5.4.1 The switchgear in the circuits of electric drives, which in itself does not provide for short circuit protection shall withstand the short-circuit current that may flow at the point of its installation during the time required for operation of a special protection device.

5.4.2 Starting of the engine shall be possible only from the zero position of the control gear.

5.4.3 A discharge protection device shall be provided for the control gear that permits isolation of the shunt-field windings.

5.4.4 For directly started alternating-current electric motors, the requirements of 3.1.2.2 and 16.8.3.3 shall be taken into consideration.

5.4.5 For each electric motor rated at 0,5 kW and more and its control gear, provision shall be made for fitting a device to isolate the power supply. If the control gear is mounted on the main switchboard or on any other switchboard in the same compartment and its visibility is ensured from the place of installation of the electric motor, then for this purpose it is permitted to use a switch mounted on the switchboard.

If the requirements in respect of location of machine control gear stated above are not met, the following shall be provided:

.1 a device interlocking the switch on the switchboard in the "off" position; or

.2 an additional disconnecting switch near the electric motor; or

.3 fuses in each pole or phase of the control gear arranged in such a manner that they could be readily removed or replaced by the personnel.

5.5 ELECTRIC DRIVES AND CONTROL OF STEERING GEAR

5.5.1 In addition to the requirements of 6.2, Part IX "Machinery", 2.9, Part III "Equipment, Arrangements and Outfit" and 7.4.10, Part VII "Machinery Installations", steering gear shall comply with the requirements of this Part of the Rules.

5.5.2 Main electric or electro-hydraulic steering gear comprising one or more power units shall be supplied by two separate feeders laid directly from the main switchboard in two different runs (refer also to 16.8.4.12). One of these feeders may be supplied through the emergency switchboard.

When the collecting busbars in the main switchboard are subdivided, each feeder shall be supplied from different sections (refer also to 4.3.2).

In case the auxiliary electric or electro-hydraulic steering gear is provided according to 2.9, Part III "Equipment, Arrangements and Outfit", it may be supplied from the feeders of the main electric steering gear.

5.5.3 Each feeder shall be selected so as to supply all the electric motors, which are normally connected thereto and operate simultaneously.

5.5.4 If a change-over arrangement is provided to supply any electric motor or a combination of motors from one or the other feeders, such feeders shall be designed for operation under the most severe loads, and the change-over arrangement shall be installed in the steering gear compartment.

5.5.5 In case a steering gear power unit becomes inoperative, another unit required by 2.9.4, Part III "Equipment, Arrangements and Outfit" shall be actuated manually from the bridge control station. Provision may be made for an additional automatic actuation of the power unit.

5.5.6 In every ship provided with steering gear according to 2.9.6, Part III "Equipment, Arrangements and Outfit" in the event of failure of the main source of electric power of the steering gear power unit provision shall be made for automatic connection within 45 s to the emergency source of electrical power or another independent source located in the steering gear compartment and intended only for this purpose.

For ships of 10000 gross tonnage and over the power of this source shall be sufficient for continuous supply of the steering gear, associated control system and rudder angle indicators within at least 30 min and for all other ships, within at least 10 min.

5.5.7 The operating conditions for the electric motors of the drives for the active means of the ship's steering shall conform to the conditions prescribed for the entire gear, but the motors shall at least satisfy the short-term operating conditions during not less than 30 min.

5.5.8 The electric or electrohydraulic drive of a steering gear shall ensure:

.1 putting the rudder from hard over to hard over within the time and angle stated in 6.2.2, Part IX "Machinery";

.2 putting the rudder continuously from hard over to hard over during 30 min for each set at the maximum service speed ahead corresponding to the draught at which the rudder is fully immersed (refer also to 2.9.2 and 2.9.3, Part III "Equipment, Arrangements and Outfit");

.3 continuous operation during one hour at the maximum service speed ahead with putting the rudder over through an angle so as to ensure 350 puttings over per hour;

.4 possible stalling of the electric motor in "on" position for one minute from hot state (only for rudders fitted with the direct electric drive);

.5 sufficient strength of electric drive in the presence of mechanical forces arising at maximum speed astern.

It is recommended that a possibility shall be provided for putting the rudder over at the average speed astern.

5.5.9 Starting and stopping of the steering gear electric motors, other than electric motors of rudders with direct electric drive, shall be effected from the steering room and from the wheelhouse.

5.5.10 The starting devices shall ensure automatic restarting of electric motors as soon as the voltage is restored after a discontinuity in power supply.

5.5.11 For control systems required in 2.9.14, Part III "Equipment, Arrangements and Outfit", visual and audible alarm shall be initiated on the navigation bridge in case of:

.1 power supply failure of each power unit, the control system, as well as the earth faults;

.2 short circuit, broken connections, earth faults in command and feedback loops;

.3 data communication errors, computer hardware and software failures (if programmable electronic systems are used);

.4 low oil level in any tank of the hydraulic system;

.5 critical deviations between rudder order and response unless rudder's actual position reaching the set value position within acceptable time limits for feedback control systems (e.g., for the follow-up control system and autopilot). The alarm may be actuated with mechanic, hydraulic or electric failures.

Besides, means shall be provided to indicate operation of electric motors of the steering gear power units.

5.5.12 Failures, including those specified in 5.5.11, that can cause uncontrolled movement of the rudder blade shall be clearly identified. In case of the failures identification the rudder blade shall be fixed in the current position without manual intervention. For mechanical failures such as sticking valves and failure of static components (pipes, cylinders), the system response without manual intervention is not mandatory, and the operator can follow instructions on the steering gear control station on the navigation bridge in case of such failures.

Where hydraulic locking, caused by a single failure, may lead to loss of steering, an audible and visual alarm, which identifies the failed system, shall be provided on the navigation bridge.

5.5.13 The following visual and audible alarm shall be provided at the main machinery control room:

.1 loss of voltage, phase break-off;

.2 power supply circuit overload of each power unit;

.3 low oil level in any tank of the hydraulic system.

Besides, means shall be provided to indicate operation of electric motors of the steering gear power units.

5.5.14 The steering gear control systems specified in 2.9.13 and 2.9.14, Part III "Equipment, Arrangements and Outfit" shall be supplied by separate feeders laid in different runs from the power circuits of the steering gear in the steering gear compartment or directly from the busbars of the switchboard serving these power circuits.

5.5.15 In the steering gear compartment means shall be provided for disconnecting any bridge control system from the steering gear it serves.

5.5.16 Each remote control system specified in 2.9.13 and 2.9.14, Part III "Equipment, Arrangements and Outfit" shall have its own independent circuit, including all electrical components, for transmission of orders to the steering gear actuator and shall be so arranged that a mechanical or electrical failure in one of them will not render the other one inoperative. Wires, terminals and the components for duplicated steering gear control systems installed in units, control boxes, switchboards or bridge consoles, as well as circuits of common switching units of control systems, shall be separated as far as practicable or separated by means of a fire retardant plate.

5.5.17 In the case of double follow-up control, the amplifiers shall be electrically and mechanically separated. In the case of non-follow-up control and follow-up control, it shall be ensured that the follow-up amplifiers are protected selectively. Therewith, selectivity of protection devices actuation shall be ensured.

5.5.18 Where additional control systems are provided, their control circuits shall be designed for allpole disconnection.

5.5.19 Feed-back units and limit switches for the steering gear control systems shall be separated electrically and mechanically connected to the rudder stock or actuator separately.

5.5.20 Any of the most probable failures (loss of power or failure in feedback control systems) shall not result in the complete loss of steering capability.

5.5.21 The direction of rotation of the rudder wheel or the direction of motion of the control gear handle shall agree with the direction of putting the rudder over.

In the push-button control system, the push-buttons shall be arranged in such a manner that the switching on of the push-button located to the right causes the rudder blade to move rightward, while the button to the left its motion leftward.

5.6 ELECTRIC DRIVES OF ANCHOR AND MOORING MACHINERY

5.6.1 In addition to the requirements of 6.3 and 6.4, Part IX "Machinery", the drives of windlasses, anchor and mooring capstans and mooring winches shall comply with this Part of the Rules.

5.6.2 Electric drives of anchor and mooring machinery shall ensure possible stalling. Duration of stalling shall be limited by the activating time of overload protection or winding temperature protection, but not exceeding 30 s for anchor machinery and 15 s for mooring machinery.

5.6.3 In anchor and mooring capstans and mooring winches at the speed steps intended only for mooring operations provision shall be made for overload protection of the electric motor.

5.6.4 The supply of electric drives of anchor capstans shall be effected in conformity with 4.3.1 and 4.3.3.

5.7 ELECTRIC DRIVES OF PUMPS

5.7.1 The electric motors of fuel and oil transfer pumps and separators as well as of organic coolant circulation pumps shall be provided with remote disconnecting switches located outside the space wherein these pumps are placed and outside the machinery casings, but in close vicinity of the exits from these spaces.

5.7.2 The electric motors of the pumps transferring the liquids overboard through the drain holes above the lightest waterline at locations where lifeboats or liferafts are lowered shall be provided with disconnecting switches located near the control stations of the driving machinery for lowering the relevant boats or rafts.

5.7.3 The electric motors of emergency fire pumps and submersible bilge pumps shall be provided with remote starting devices located above the bulkhead deck (refer to 3.2.3.9, Part VI "Fire Protection").

A remote starting device shall be provided with a light signal indicating the "on" condition of the electric drive.

5.7.4 Disconnecting switches of electric drives specified in 5.7.1 shall be located in conspicuous positions covered with glass and provided with explanatory inscriptions. The disconnecting switches shall de-energize feeders of those electric drives.

5.7.5 Local starting of fire and bilge pumps shall be possible even in case of failure of their remote control circuits, including protection equipment (refer also to 6.6.8.3, Part VI "Fire Protection").

5.7.6 The electric motors of oily and sewage water transfer and discharge pumps shall be provided with remote cut-off arrangements located in the vicinity of discharge manifolds, provided no telephone or radio communication is available between the discharge observation position and discharge control position.

5.8 ELECTRIC DRIVES OF FANS

5.8.1 The electric motors of ventilation fans in machinery spaces shall be provided with at least two disconnecting switches, one of which shall be located outside these spaces and their casings, but in close vicinity of the exits from these spaces. It is recommended that these disconnecting switches be positioned together with similar switches referred to in 5.7.1.

5.8.2 The electric motors of ventilation fans of cargo holds and galley fans shall be provided with disconnecting switches at locations readily accessible from the main deck, but outside the machinery casings.

Electric motors of exhaust ventilation from galley ranges shall be provided with a disconnecting switch located inside the galley, regardless of the number of disconnecting switches.

5.8.3 The electric motors for general shipboard ventilation shall have at least two switches for remote disconnection of the motors, one of the switches being fitted in the wheelhouse and the other located at an easily accessible position outside the space being served. This position shall not be readily cut off in the event of a fire in the spaces served.

For ships with electrical installation of low power (other than passenger ships) it is permitted to use one disconnecting switch.

5.8.4 The electric motors of fans in the spaces protected by a smothering system shall be provided with a disconnecting switch operating automatically when fire extinguishing medium is discharged into the space. When such spaces are fitted with fire closing appliances that automatically block air access therein, the manual switching off the fans may be permitted; therewith, the disconnecting switches shall be located outside the above spaces.

5.8.5 The disconnecting switches of the electric motors of fans listed in 5.8.1 — 5.8.3 shall be so grouped on board the ship that all these electric motors could be stopped from not more than three positions. The disconnecting switches shall de-energize feeders of those electric motors of fans.

5.9 ELECTRIC DRIVES OF BOAT WINCHES

5.9.1 The electric drives of boat winches shall comply with the requirements of 6.20, Part II "Life-Saving Appliances" of the RS Rules/E.

5.9.2 The winch electric drive controls shall be provided with self-return to the "stop" position.

5.9.3 A switch in power circuit of the electric motor shall be installed near the boat winch control station.

5.10 ELECTRIC DRIVES OF WATERTIGHT AND FIRE DOORS

5.10.1 The electric drives of watertight doors shall meet the requirements of 7.12, Part III "Equipment, Arrangements and Outfit".

5.10.2 For ships contracted for construction or conversion before 1 January 2024, ships, the keels of which are laid or which are at a similar stage of construction before 1 January 2024, and ships delivered before 1 January 2024, power supply of electric drives and indicators of position and closure of the watertight doors shall be taken from the main, emergency and emergency intermediate sources of electrical power in accordance with 4.3.1, 9.3 and 20.1.2. For ships contracted for construction or conversion on or after 1 January 2024, ships, the keels of which are laid or which are at a similar stage of construction on or after 1 January 2024, and ships delivered on or after 1 January 2024, the electrical power required for power-operated sliding watertight doors shall be supplied from the emergency switchboard either directly or by a dedicated distribution board situated above the bulkhead deck. The associated control, indication and alarm circuits shall be supplied from the emergency switchboard either directly or by a dedicated distribution board situated above the bulkhead deck and be capable of being automatically supplied by the transitional source of emergency electrical power required by 9.3.4.3 in the event of failure of either the main or emergency source of electrical power.

5.10.3 As far as practicable, electrical equipment and components for watertight doors shall be situated above the bulkhead deck and outside dangerous areas and spaces.

5.10.4 Suitable protection from water penetration shall be provided for the enclosures of the following electrical equipment positioned perforce below the bulkhead deck:

.1 electric motors and control equipment circuits related thereto — IPX7;

.2 door position indicator sensors and circuit elements related thereto — IPX8;

.3 door movement audible alarm elements — IPX6.

For ships contracted for construction or conversion on or after 1 January 2024, ships, the keels of which are laid or which are at a similar stage of construction on or after 1 January 2024, and ships delivered on or after 1 January 2024, the water pressure IPX 8 shall be based on the pressure that may occur at the location of the component during flooding for a period of 36 h.

5.10.5 Electric power, control, indication and alarm circuits shall be protected against fault in such a way that a failure in one door circuit will not cause a failure in any other door circuit. Short circuits or other faults in the alarm or indicator circuits of a door shall not result in a damage in the electric power and control circuits. Arrangements shall be such that leakage of water into the electrical equipment located below the bulkhead deck will not cause the door to open.

5.10.6 A single failure in the power operating or control circuits of a sliding watertight door shall not result in a closed door opening. Availability of the power supply shall be continuously monitored in the immediate vicinity of each of the motors required by 7.12.5.7, Part III "Equipment, Arrangements, and Outfit". Loss of power supply in the power operating and control circuits shall activate an audible and visual alarm in the main machinery control room and at the navigation bridge.

5.10.7 The electric drives of devices for holding the fire doors in the open position (refer to 2.1.3.4, Part VI "Fire Protection") shall:

.1 be supplied from the main and emergency sources of electrical power;

.2 be remotely controlled from the wheelhouse for closing the doors individually, in groups or all doors simultaneously;

.3 automatically close all the doors simultaneously in case of the supply voltage loss;

.4 be so designed that any damage in the mechanism of closing any door could not render inoperative the systems of supply and operation of other doors.

5.11 ELECTRIC DRIVES FOR OIL BURNER UNITS OF BOILERS AND INCINERATORS

5.11.1 Electric drives for oil burner units of boilers and incinerators shall be provided with remote shut off devices located outside the spaces where they are installed (refer also to 5.3.8, Part X "Boilers, Heat Exchangers and Pressure Vessels" and 4.3.6, 4.10.3.4 and 6.2.3, Part XV "Automation").

5.11.2 Where the spaces in which the incinerators and boilers are installed are protected by aerosol fire-extinguishing system, the electric drives for oil burner units of boilers and incinerators shall be automatically shut off when the said system is activated.

5.12 ELECTRIC DRIVES OF DEWATERING ARRANGEMENTS OF FORWARD SPACES OF BULK CARRIERS

5.12.1 In addition to the requirements of 7.9.2 and 7.9.3, Part VIII "Systems and Piping", electric drives of dewatering arrangements of forward spaces of bulk carriers shall meet the requirements of this Part.

5.12.2 Positive indication shall be provided at the navigation bridge or other station complying with the requirements of 7.9.2, Part VIII "Systems and Piping" to show that the valve is fully open or closed.

5.12.3 The enclosures of electrical equipment for the dewatering system installed in any of the forward dry spaces shall provide protection to not lower than IPX8 standard for a water head equal to the height of the space in which the electrical equipment is installed for a time duration of at least 24 h.

6 LIGHTING

6.1 GENERAL

6.1.1 In all ship's spaces, places and zones where the illumination is essential for safety of navigation, control of machinery and gear, habitability and evacuation of passengers and crew, pilot embarkation and disembarkation stationary main lighting fixtures shall be provided, which are supplied from the main source of electrical power.

The list of spaces, places and zones where the emergency lighting fixtures shall be installed in addition to the main ones is given in 9.3.1.1 and 20.1.2.1.1.

6.1.2 Lighting fixtures installed in spaces and zones where mechanical damage is possible to the glass hoods shall be provided with protection gratings.

6.1.3 Lighting fixtures shall be installed in such a manner as to prevent heating of cables and adjacent materials up to a temperature exceeding the permissible level.

6.1.4 In spaces or spaces illuminated with luminescent lamps where visible rotating parts of machinery are located, all measures shall be taken to prevent stroboscopic effect.

6.1.5 External-illumination lighting fixtures shall be so installed that no light interference with ship's navigation could occur.

6.1.6 In spaces and zones illuminated with discharge lamps, which do not ensure continuity of burning at voltage variations according to 2.1.3, provision shall be also made for lighting fixtures with incandescent lamps.

6.1.7 Battery and other dangerous compartments shall be illuminated with lighting fixtures located in adjacent safe spaces through gastight windows, or with safe-type lighting fixtures located inside the compartment (refer also to 2.9).

6.1.8 Portable lighting fittings of domestic services are not included in the list of items of technical supervision.

6.2 POWER SUPPLY OF MAIN LIGHTING ELECTRIC CIRCUITS

6.2.1 The switchboards of the main lighting shall be supplied by separate feeders. The main lighting switchboards may supply the electric drives of non-essential services rated up to 0,25 kW and individual cabin heaters rated up to 10 A.

6.2.2 The protective devices of final lighting circuits shall be set to operate at a current rating not exceeding 16 A, the total load current of the consumers connected shall not exceed 80 % of the current setting of the protective device.

The number of lighting fixtures supplied by final lighting circuits shall not exceed that specified in Table 6.2.2. Cabin fans and other appliances may be supplied by final lighting circuits.

Table 6.2.2

Voltage, V	Maximum number of lighting fixtures
Up to 50	10
51 to 120	14
121 to 250	24

6.2.3 Lighting of corridors, machinery spaces, propeller shaft tunnels, boiler water-level indicators shall be supplied by not less than two independent feeders, with the lighting fixtures arranged in such a manner that, even in case of failure of either feeder, as uniform lighting as possible is ensured. These feeders shall be supplied from different distribution boards, which, in case of application of the lighting subdivided busbars in the main switchboard, shall be supplied from different busbar sections. One of the feeders may be that supplying from the emergency switchboard.

For cargo ships with the electrical installation of low power it is allowed that lighting of the above spaces, except for machinery spaces, be supplied by one feeder from the distribution board or from the main switchboard directly.

6.2.4 Local lighting fixtures, as well as socket outlets shall take power from the lighting switchboard by a separate feeder, other than that intended for supplying the common lighting fixtures.

6.2.5 If the ship is divided into main fire zones, then lighting of each zone shall be supplied by two feeders supplying the lighting circuits in other fire zones.

The lighting feeders shall be installed, as far as possible, in such a manner that a fire in one zone cannot damage the feeders supplying the lighting circuits in other zones.

In case of application of the lighting subdivided busbars in the main switchboard, these feeders shall be supplied from different busbar sections.

6.2.6 The main lighting circuits shall be arranged so that fire or any emergency in the spaces accommodating the main sources of power and/or main lighting transformers, if any, will not cause failure of the emergency lighting.

6.2.7 Permanently installed lighting fixtures in holds shall take power supply from a special switchboard. Apart from the switchgear and protective devices, this switchboard shall be provided with light signals to indicate switching-on of each individual lighting circuit.

For ships with low power electrical installations the lighting fixtures in holds may be supplied from the switchboard located in the wheelhouse; in this case, visual alarm is required on voltage availability in the power supply circuit of lighting fixtures in holds.

6.3 EMERGENCY LIGHTING

6.3.1 The illumination obtained from the emergency lighting fixtures in separate spaces, locations and zones listed in 9.3.1.1 and 20.1.2.1.1 shall at least be equal to 10 % of the general illumination obtained from the main lighting fixtures (refer to 6.7). It is permitted that the illumination from the emergency lighting fixtures in the machinery space is equal to 5 % of the main illumination if the socket outlets fed from the emergency lighting circuit are provided. The illumination shall be sufficient to easily find one's way to the means of escape (or shall be equal to 0,5 lx).

Where lighting fixtures with built-in accumulator batteries are used in the networks of emergency illumination, such fixtures shall provide the minimum illumination level 1 lx during 30 min on escape routes in case of power loss from the main and emergency source of electrical power except for places specified in 20.3.3.1.

6.3.2 To obtain the illumination required in 6.3.1, the emergency lighting fixtures with incandescent lamps may be combined with luminescent lamps.

6.3.3 The main lighting fixtures are permitted for use as emergency lighting fixtures if they may be also fed from the emergency sources of electrical power.

6.3.4 The emergency lighting circuit shall be so arranged that in case of a fire or other casualty in the spaces containing the emergency sources of electrical power and/or emergency lighting transformers the system of the main lighting will not fail.

6.3.5 For emergency lighting use could be made of the stationary lighting fixtures with built-in accumulators, automatic recharging from the main lighting circuit.

6.3.6 Emergency lighting fixtures or a combined lamp shall be marked in red in visible parts.

6.4 SWITCHES IN LIGHTING CIRCUITS

6.4.1 If in accordance with the requirements of these Rules switches shall be installed, two-pole switches shall be used.

In dry accommodation and service spaces it is allowed to use single-pole switches in circuits disconnecting individual lighting fixtures or groups of lighting fixtures rated at not more than 6 A and also in lighting fixture circuits designed for safety voltage.

6.4.2 For permanently installed external-illumination lighting fixtures, provision shall be made for switching off all the lighting fixtures from the wheelhouse or from any other permanently watched station on the upper deck.

6.4.3 The switches of lighting circuits of the fire extinction stations shall be located outside these spaces.

6.4.4 The lighting switches behind free-standing switchboards shall be installed near each access door behind the switchboard.

6.4.5 In emergency lighting circuits local switches shall not be used.

The use of local switches is permitted in circuits of such emergency lighting fixtures, which under normal conditions serve as the main lighting fixtures.

A switch shall be provided for emergency lighting in the wheelhouse.

Emergency lighting fixtures of embarkation stations, which under normal conditions serve as main lighting fixtures shall switch on automatically if the ship is de-energized.

6.5 GAS DISCHARGE LAMP INSTALLATIONS

6.5.1 Reactors and capacitors of gas discharge lamp installations shall be protected by securely earthed metal enclosures.

6.5.2 Capacitors of 0,5 μF and over shall be fitted with discharging devices. The discharging device shall be so designed that the voltage of the capacitor does not exceed 50 V in 1 min after disconnection from supply.

6.5.3 Reactors and transformers having a high inductive reactance shall be installed as close as possible to the lighting fixture they serve.

6.5.4 Gas discharge lamp installations supplied at over 250 V shall be provided with warning notices giving the voltage rating. All live parts of such installations shall be suitably protected.

6.6 SOCKET OUTLETS

6.6.1 Socket outlets for portable lighting fixtures shall be installed at least:
on deck near the windlass;
in the gyrocompass room;
in the radio equipment converter room;
in the steering gear compartment;
in the emergency generator set compartment;
in the machinery spaces; behind the main switchboard;
in special electrical spaces; in the propeller shaft tunnel;
in the wheelhouse;
in the radioroom;
in the vicinity of winches;
in the vicinity of the log and echo-sounder trunk or recess;
in spaces where centralized ventilation and air conditioning installations are located.

6.6.2 Socket outlets fed with different voltages shall be so designed as to prevent insertion of a plug intended for one voltage into a socket intended for higher voltage.

6.6.3 Socket outlets for portable lighting and other electric appliances installed on the open decks shall be mounted with their face looking downward.

6.6.4 Socket outlets shall not be fitted in machinery spaces below the plating, in enclosed fuel and oil separator rooms or where approved safety-type equipment is required.

6.7 ILLUMINATION

6.7.1 The illumination of particular spaces and zones shall not be below that specified in Table 6.7.1. This requirement is not applicable to ships provided with lighting circuits supplied at a voltage below 30 V.

The general lighting standards stated in Table 6.7.1 refer to a level of 800 mm above the deck (flooring) of the space, while the standards of general plus local lighting, to the level of working surfaces.

Table 6.7.1

Nos	Spaces and surfaces		Illumination, lux			
			Luminescent lighting		Incandescent lighting/LED lamps	
			general + local	general	general + local	general
1	Radio communication station	At the predetermined level above the deck	–	–	–	100
		Operator tables in radio communication station	–	–	200	–
2	Chartroom	At the predetermined level above the deck	–	100	–	50
		Chart tables	150	–	150	–
3	Wheelhouse	At the predetermined level above the deck	–	75	–	50
4	Machinery spaces, spaces for switchboards, manoeuvring and control stations and panels, spaces for automation facilities and gyrocompasses	At the predetermined level above the deck plating	–	75	–	75
		Surfaces of switchgear and control desks	200	100	150	75
		Main engine controls	150	100	150	75
		Passageways between boilers, machinery, ladders, platforms, etc.	–	75	–	30
		In front of boilers	100	75	75	75
5	Battery compartment	At the predetermined level above the deck	–	75	–	50
6	Propeller shaft tunnels, log, echo sounder trunks, chain lockers	At the predetermined level above the deck	–	50	–	20
		Surfaces of shaft bearings and connection flanges, etc.	75	–	50	–
7	Passageways on decks, gangways and lifeboat and liferaft positions	At the predetermined level above the deck	–	50	–	20
8	Overboard spaces in way of lifeboat and liferafts launching	Near the load waterline	–	–	–	5

6.8 NAVIGATION LIGHTS

6.8.1 The navigation lights switchboard shall supply by separate feeders the masthead lights, sidelights and sternlight, and in towing, pushing, fishing, pilot vessels, vessels restricted in ability to manoeuvre and air-cushion vehicles it shall supply also permanently mounted lights listed in Table 2.4.1, Part III "Signal Means" of the RS Rules/E, and additional masthead and stern lights listed in Table 5.2.1 of the said Part of the Rules.

6.8.2 The navigation lights switchboard shall be supplied by two feeders:

.1 one feeder from the main switchboard through the emergency switchboard;

.2 the second feeder from the nearest distribution board, which is not supplied from the emergency switchboard.

It is permitted to install the navigation lights control devices in the integrated bridge control console and taking the power in accordance with 4.5.2.

Where the main source of power of the ship is an accumulator battery and the main switchboard is installed in the wheelhouse, the navigation lights may be controlled directly from the main switchboard.

6.8.3 The power supply of navigation lights shall be of two-wire system with a double-pole switch for each circuit to be installed in the navigation light switchboard.

6.8.4 Each navigation light power supply circuit shall be provided with protection in both wires and with indication of the navigation light switching in compliance with the requirements of 4.1.4, Part III "Signal Means" of the RS Rules/E.

The indication device of the navigation light switching shall be so designed and installed that its failure does not cause the navigation light disconnection.

The voltage drop at the distribution board supplying navigation lights including the system of indicating the lights operation shall not exceed 5 % at rated voltage up to 30 V and 3 % at rated voltage above 30 V.

6.8.5 Independent of the navigation light switching indication referred to in 6.8.4, provision shall be made for visual and audible alarms operating automatically in case of:

.1 failure, including short circuit, of any navigation light with the switch in the "on" position;

.2 failure of power supply to navigation lights switchboard.

Alarms shall be supplied from a source or feeder other than that used for power supply to navigation light switchboard or from an accumulator battery.

6.8.6 Lamp holders and lamps used in navigation lights shall comply with the requirements of 3.1.7, Part III "Signal Means" of the RS Rules/E.

6.8.7 For navigation lights using light-emitting diodes (LEDs) in addition to the indication of navigation lights switching as required in 6.8.4 and the alarm as required in 6.8.5, provision shall be made for visual and audible alarms operating automatically in case luminous intensity of the light reduces below the level required in 3.1.7, Part III "Signal Means" of the RS Rules/E. In the absence of such alarms, it is permitted to use LEDs within their lifespan notified by the manufacturer.

6.8.8 All indicators on the navigation lights switchboard shall be dimmable, the brightness of a display, if fitted, shall be controllable.

6.8.9 Navigation lights switchboard shall support standard serial interfaces for data exchange with shipboard systems. For transferring alarms to external systems and receiving acknowledgements of alarms from external systems a bi-directional interface complying with IEC 61162 series shall be used.

Pre-programmed navigation lights group settings may also be provided.

6.9 LIGHTING AND ILLUMINATION MEANS OF HELIDECKS

6.9.1 General.

6.9.1.1 The lighting and illumination means for helidecks shall at least provide for the following:

indication of the perimeter (boundaries) of the helideck;

illumination of the landing area;

indication of the elevated structures within the landing area.

6.9.1.2 Lights used for this purpose shall be protected to not lower than level IP56 and shall function reliably under environmental effects mentioned in Section 2.

6.9.1.3 All lighting and illumination means as well as other electrical equipment within helicopter refuelling stations and hangars shall be of certified safe type and designed to not lower than the temperature class T3 and subgroup IIA.

6.9.1.4 In respect to their lighting characteristics and arrangement, the lights shall meet the requirements of ICAO (International Civil Aviation Organization) which shall be confirmed by the appropriate conclusion or by a Certificate of the Civil Aviation competent body.

6.9.1.5 The lighting and illumination means mentioned in this Chapter shall be fed by uninterruptible power supply.

6.9.2 Perimeter lights.

6.9.2.1 The lights shall be divided into two independent circuits and supplied in such a manner that when the power to any one circuit fails, 50 % of lights to indicate the perimeter remain functioning.

6.9.3 Illumination of the landing area.

6.9.3.1 The landing area and wind direction indicator shall be properly illuminated. For this purpose, floodlights may be used.

6.9.3.2 Helideck floodlights shall be located so as to avoid glare to pilots during take-off, landing and maneuvering.

6.9.4 Obstruction/warning lights.

6.9.4.1 To provide flight safety, all considerably elevated structures and items such as superstructure components, drill and production strings, etc. shall be marked by special obstruction/warning red lights.

6.9.4.2 Lights shall be divided into several independent circuits and supplied in such a manner that when power supply to one of the circuits fails, the basic part of the obsruction/warning lights remains functioning.

7 INTERNAL COMMUNICATION AND SIGNALLING

7.1 ELECTRIC ENGINE ROOM TELEGRAPHS

7.1.1 In addition to the requirements of this Chapter, the engine room telegraphs shall meet the requirements of 3.3.1, Part VII "Machinery Installations".

7.1.2 Engine room telegraphs shall be provided with visual alarm on voltage availability in the power supply circuit and audible alarm on loss of voltage in the power supply circuit.

7.1.3 Engine room telegraphs installed in the wheelhouse shall be provided with an illuminated dial of regulated illumination.

7.1.4 Engine room telegraphs shall be fed from the main switchboard or from the navigation equipment switchboard.

If the ship is provided with the integrated bridge control console the engine room telegraph may be fed from this control console.

7.1.5 The engine room telegraph transmitter shall be so installed in the wheelhouse that when orders are given out for ship's motion, the telegraph operating handle is shifted in the same direction with the ship. Vertical position of the handle shall correspond to the "stop" order.

7.1.6 Where engine room telegraphs and devices for remote control of the main engines and the controllable pitch propellers are installed on sloping desks of control panels, the handle in the "stop" position shall be perpendicular to the panel surface and be fixed precisely in this position.

7.1.7 Where two and more engine room telegraphs are located in close proximity to one another (on one deck), they shall ensure the transmission of an order from any telegraph and the reception of order by all of them simultaneously, without additional changing-over.

Change-over to telegraphs located on another deck or in another part of the ship shall be effected with the use of switches fitted on the navigation bridge.

7.1.8 Each engine room telegraph shall be provided with an audible signal arrangement that will ensure the operation of an audible signal on the bridge and transmission of orders and reception thereof in the engine room. In case of a wrong reply, the operation of the audible signal arrangement shall not stop (refer also to 3.3.1, Part VII "Machinery Installations").

7.2 INTERNAL SERVICE COMMUNICATION

7.2.1 The system of internal service communication (refer to the requirements below) shall provide a subscriber call and clear voice communication under the normal and emergency ship's operation conditions, as well as under specific noise conditions in places where the communication facilities are installed.

7.2.2 Sound-powered telephones, voice communication facilities, two-way loud-speaking communication facilities, automatic telephone systems or mobile phones of a local network may be used in the system of internal service communication.

7.2.3 The system of internal service communication shall provide voice communication between the wheelhouse and main service spaces and stations. In this case the separate two-way voice communication may be omitted if the communication facility provides at any time the call priority and communications between the wheelhouse and the following main service spaces and stations:

.1 main machinery control room;

.2 local control stations of the main machinery and propellers (for this purpose the two-way telephone communication between the wheelhouse and the main machinery control room with telephones connected in parallel and fitted at local control stations may be used);

.3 radioroom (may be omitted where communication may be established without hardware);

.4 steering gear compartment;

.5 space containing the emergency switchboard;

.6 forecastle and poop stations;

.7 gyrocompass room;

.8 fire smothering station (refer also to 3.1.3.2.6, Part VI "Fire Protection");

.9 space containing electric propulsion motors;

.10 cargo operations control station (in oil tankers);

.11 fire and rescue control station (in ships with distinguishing mark of provision with means for firefighting aboard other ships in the class notation);

.12 other spaces where equipment ensuring ship's safe navigation is installed.

7.2.4 Provision shall be made for communications between the main machinery control room or local control stations of the main machinery and propellers and the engineers' accommodations.

7.2.5 For the communication facilities specified in 7.2.3 and 7.2.4, in addition to sound-powered telephones, provision shall be made for power supply from the main source of electrical power and accumulator battery actuated automatically in case of failure of the main source of electrical power with a capacity sufficient to supply the communication facilities during the time specified in 9.3.1.3 or 20.1.2.1.4.

7.2.6 The communication facilities between the wheelhouse and the main machinery control room or local control stations of the main machinery and propellers shall include an additional audible and visual alarm to indicate the call both in the main machinery control room and the engine room.

7.2.7 A damage to, or disconnection of one communication facility shall not interfere with the functioning of other communication facilities.

7.3 SIGNALLING. GENERAL

7.3.1 The requirements cover the following systems signaling the equipment or ship's condition requiring attention of personnel or passengers, activating an audible and visual alarm:

.1 general alarm and fire alarm systems;
.2 fire detection and fire alarm system;
.3 release indication of fire smothering system;
.4 indication of closing of watertight and fire doors and also the doors indicated in 7.12;
.5 machinery alarm system;
.6 high level of bilge water alarm;
.7 cargo hold water level alarm on bulk carriers, passenger ships carrying 36 persons and more and single-hold cargo ships other than bulk carriers;
.8 engineer's alarm;
.9 personnel alarm, cargo control alarm and alarm of ultimate concentration of dangerously explosive and noxious gases;
.10 side port doors condition alarm;
.11 alarm on presence of people inside refrigerated holds: "Man in hold" alarm (for ships used for processing the living resources of the sea and not engaged in their catching);
.12 sewage holding tanks level alarm;
.13 release indication of fixed local application fire extinguishing system;
.15 bulkhead shaft glands, bearing and pump case temperature alarm system;
.15 maximum permissible cargo temperature alarm system;
.16 overpressure or under pressure in the cargo tanks alarm system;
.17 high- and limit-level alarms in cargo tanks.

7.3.2 An opportunity to functionally test each alarm system shall be provided.

Unless otherwise stated, all alarm systems shall be designed on the failsafe principle with provision for power supply failure alarm, alarm on contact-to-frame fault or circuit break, as well as the possibility of checking visual and audible alarms operability.

7.3.3 The control panel shall clearly distinguish between normal, alarm, acknowledged alarm, fault and silenced conditions. The system shall be arranged to automatically reset to the normal operating condition after alarm and fault conditions are cleared.

7.3.4 Audible alarms shall be heard and distinguishable in all the spaces and areas they intended for.

7.3.5 Audible alarms of an alarm system shall be given until their acceptance (acknowledgement) is confirmed, and the visual indication of each separate alarm shall remain until the fault has been corrected.

7.3.6 The sound frequency of audible alarm devices, excepting a bell, shall be within the range of 200 to 2500 Hz.

7.3.7 Where the visual alarm is applied, the colours specified in Table 4.6.5.1 shall be used unless otherwise stated.

7.3.8 The height of inscription text symbols for operating and alarm controls, unless they have been duplicated with symbols/a plate of an established pattern, shall be at least 7 mm, the width is 0,7 symbol height.

This requirement, excepting the visual alarms mentioned in 7.3.1, also applies to the texts of inscriptions above the controls in switchboards, control consoles, starting, protection and control equipment for electric drives of essential machinery listed in 1.3.2.1.5.

7.3.9 The texts of inscriptions above operating and alarm controls not mentioned in 7.3.8, as well as the texts of watch-keeping and other instructions used for the description of a working procedure, starting and control of an object shall have symbols of at least 3,5 mm high, the width is 0,7 symbol height.

7.3.10 Flashing alarms shall emit light within 50 % of the entire work cycle, the pulse frequency therewith shall be within the range of 0,5 to 1,5 Hz.

7.4 GENERAL ALARM SYSTEM

7.4.1 In addition to the requirements stated below, the general alarm system shall comply with the requirements of 2.1.3 and 6.22.1, Part II "Life-Saving Appliances" of the RS Rules/E.

7.4.2 Sound devices shall be installed in the following places:

in machinery spaces;

in public spaces, if their floor area is more than 150 m^2;

in corridors of accommodation, service and public spaces;

on open decks of passenger ships;

in working spaces.

7.4.3 General alarm system shall be supplied from the ship mains and the busbars of the emergency switchboard in conformity with 9.3.1.3 and 20.1.2.1.4.

General alarm system may be energized from the ship mains and from an independent accumulator battery if provision is made for an automatic changeover of general alarm circuits to the battery. In this case, no supply either from the emergency source or from an intermediate emergency source of electrical power is necessary.

7.4.4 The general alarm system shall be energized continuously, no matter if the accumulator battery is set in position for charging or discharging.

7.4.5 In case a separate accumulator battery is used for supply of the general alarm system, it may also energize other internal communication and signalling facilities if the battery capacity is sufficient for simultaneous supply of all consumers for at least 3 h and also if these facilities are so designed that a damage to one circuit will not interfere with operation of other circuits provided no longer supply time is required for those facilities.

7.4.6 In circuits supplying the general alarm system the protection only from short circuit shall be provided. Protective devices shall be fitted in both conductors of the feeder and also in circuits of each sound device.

Protection of several sound devices by one common protective device is permitted if in spaces where they are installed good audibility of other sound devices provided with independent protection is ensured.

7.4.7 General alarm sound devices shall be so located that a signal is clearly heard against the noise in the given space. Sound devices installed in spaces with high intensity of noise shall be fitted with luminous indicators.

The sound of general alarm devices shall differ in tone from the sounds of all other kinds of signalling. With the exception of bells, audible alarms shall have a sound frequency between 200 and 2500 Hz. Facilities may be provided for regulating the audible signal frequency within the above limits.

7.4.8 The general alarm system shall be actuated by means of a double-pole switch.

If the general alarm signal is not heard from the wheelhouse or from the station where it has been given, a pilot lamp shall be fitted after the switch to indicate that the general alarm system is activated.

The switches shall be provided with the inscriptions indicating their purpose.

7.4.9 No switching devices shall be incorporated into the circuits of the general alarm system other than the switch specified in 7.4.8. Where a power supply switch is installed on the general alarm system switchboard, provision shall be made for its interlocking in the "on" position or it shall be otherwise protected against access thereto of unauthorized persons.

It is permitted to use intermediate contactors controlled by the switch, but not more than one contactor in each loop.

7.4.10 Sound devices, switches and distribution devices of the general alarm system shall be provided with readily visible distinctive symbols.

7.4.11 The general alarm system shall consist of at least two loops controlled by one switch. Short circuit protection shall be provided at both poles of each loop of the general alarm system.

7.4.12 Sound devices connected to different loops of the general alarm system shall be fitted in large area spaces (machinery spaces, boiler rooms, fish-processing shops, etc.).

7.5 FIRE DETECTION AND FIRE ALARM SYSTEM

7.5.1 Fire detection and fire alarm systems used on ships shall be of the Register-approved type and, in addition to the requirements of this Chapter, meet the requirements of 4.1.1 and 4.2.1, Part VI "Fire Protection", the Code for Fire Safety Systems and the Code on Alerts and Indicators (refer to 1.2, Part VI "Fire Protection").

7.5.2 Application of fire detectors located in spaces where explosive vapours may accumulate or in a flow of air sucked out of these spaces is regulated by 2.9, 20.2 — 20.4.

7.5.3 There shall be not less than two sources of power supply for the electrical equipment used in the operation of the fixed fire detection and fire alarm system, one of which shall be an emergency source. The supply shall be provided by separate feeders reserved solely for that purpose. Such feeders shall run to an automatic change-over switch situated in or adjacent to the control panel for the fire detection system. Operation of the automatic changeover switch or failure of one of the power supplies shall not result in degradation of the fixed fire detection and fire alarm system. Where the fixed fire detection and fire alarm system would be degraded by the momentary loss of power, a source of stored energy having adequate capacity according to 9.3.7 shall be provided to ensure the continuous operation during changeover between power supplies.

The fixed fire detection and fire alarm system emergency power may be supplied by an accumulator battery or from the emergency switchboard. The emergency source of power shall be sufficient to maintain the operation of the fire detection and fire alarm system for the periods required under 9.3.1.5 or 20.1.2.1.5, as applicable. At the end of that period, it shall be capable of operating all connected visual and audible fire alarm signals for a period of at least 30 min. Where the system is supplied from accumulator batteries, they shall be located in or adjacent to the control panel for the fire detection system, or in another location suitable for use in an emergency. The rating of the battery charge unit shall be sufficient to maintain the normal output power supply to the fire detection system while recharging the batteries from a fully discharged condition. Where the emergency feeder for the electrical equipment used in the operation of the fixed fire detection and fire alarm system is supplied from the emergency switchboard, it shall run from this switchboard to the automatic changeover switch without passing through any other switchboard.

7.5.4 The smoke detection system based on air sampling (refer to 4.2.1.6, Part VI "Fire Protection") and the fans of this system shall be fed by separate feeders from the main and emergency sources or another independent source of electrical power.

7.5.5 Indicating units of the fire detection and fire alarm system, other than those indicated in 7.5.4, shall be designed in such a manner that:

.1 any signal or damage to one circuit does not influence normal operation of other circuits;

.2 a fire detection signal shall prevail over other signals fed to the indicating unit and to make it possible to determine the location of the space wherefrom this fire detection signal has arrived;

.3 contact-type fire detector circuits are normally closed; it is permitted to use detectors with normally open circuits if the contacts are hermetically sealed and permanent damage control of the circuits is effected;

.4 provision is made for monitoring its operation.

7.5.6 Indicating units of the fire detection and fire alarm system shall produce information specified in Table 7.5.6.

A visual signal of fire detection shall be executed in such a manner that is consists of two indicators (two lamps or a double filament), or a special device shall be provided to check the proper condition of signalling lamps. The colour of a light signal shall comply with the requirements of 4.6.5.

Visual signals shall be separate for each kind of information.

Signals intended to determine the location of the space or area wherefrom a pulse has arrived may be common with the signal of fire detection or damage.

Visual signals shall function from the moment a pulse is received till the moment the cause of their operation has been removed; the signal specified in item 1 of Table 7.5.6 shall function continuously irrespective of the nature of supply.

Table 7.5.6

Nos	Signalling of operating conditions and faults	Signal of using temperature fire detection and fire alarm system	Signal of using systems, in which air from protected spaces enters indicating units
1	Operation of device	Visual	Visual
2	Power supply from emergency source	Visual	Visual
3	Signals of fire and location of area or space where outbreak of fire is detected	Audible	Audible
		Visual	Visual
4	No draught in detection chamber	–	Visual
			Audible
5	No draught in pipelines	–	Visual
			Audible[1]
6	Disconnection in detector circuits	Visual	–
		Audible	
7	Location of faults in detector circuit	Visual	–
8	Off position of detector circuit[1]	Visual	–
9	Main power supply failure	Visual	Visual
		Audible	Audible

[1] Recommended.

7.5.7 The fire detection and fire alarm system shall meet the following requirements:

.1 the activation of any automatic detector or manually operated call point shall initiate a visual and audible signals at the control panel and indicating units. If the signals have not received attention within 2 min, an audible alarm shall be automatically sounded throughout the crew accommodation and service spaces, control stations and machinery spaces of category A. This alarm sounder need not be an integral part of the fire detection and fire alarm system;

.2 the control panel shall be located on the navigation bridge or in the continuously manned main machinery control room, and in the cargo control room, if any. One indicating unit shall be located on the navigation bridge if the control panel is located in the main fire control station;

.3 indicating units shall, as a minimum, denote the section in which an automatic detector has activated or manually operated call point has operated;

.4 clear information shall be displayed on or adjacent to each indicating unit about the spaces covered and the location of the sections.

7.5.8 Fire detection and fire alarm systems with a zone address identification capability shall be so arranged that:

.1 no loop shall pass through a space more than once to prevent its damage at more than one point by a fire. When this is not practical (e.g. for large spaces), the parts of the loop passing through the space for the second time shall be installed at the maximum possible distance from the other parts of the loop;

.2 means are provided to ensure that any fault (e.g. power break, short circuit, earth) occurring in the loop will not render the whole loop ineffective. It means that a fault occurring in the loop only renders ineffective a part of the loop not being larger than a section of a system without means of remotely identifying each detector (refer also to 2.2.6.5, Part VI "Fire Protection");

.3 all arrangements are made to enable the initial configuration of the system to be restored in the event of failure (electrical, electronic, informatic);

.4 the first initiated fire alarm will not prevent any other detector to initiate further fire alarms.

7.5.9 The fire detectors containing ionising radiation sources (radioactive isotopes) shall have a certificate confirming their radiation safety issued by a competent body.

7.5.10 Detectors shall meet the following requirements:

.1 automatic detectors shall be operated by heat, smoke or other products of combustion, flame, or any combination of these factors. The possibility of using automatic detectors operated by other factors indicative of incipient fires may be considered by the Register provided they are no less sensitive than the above detectors. Flame detectors shall only be used in addition to smoke and heat detectors;

.2 smoke detectors required according to 4.2.1.1, Part VI "Fire Protection" shall operate before the smoke density exceeds 12,5 % obscuration per metre, but not until the smoke density exceeds 2 % obscuration per metre. Smoke detectors fitted in machinery spaces of category A shall operate before the smoke density reaches 50 % obscuration per metre;

.3 heat detectors fitted in spaces with a normal air temperature shall operate within the temperature limits of 54 to 78 °C when the temperature is increased to those limits at a rate less than 1 °C per min. The Register may consider the possibility of using heat detectors with higher rates of temperature increase taking into account their sensitivity;

.4 the temperature of heat detectors activation in drying rooms and similar spaces, which are characterized by high temperatures, may be set up to 130 °C inclusive, and in saunas up to 140 °C inclusive;

.5 heat detectors shall reliably operate at a temperature at least by 5 °C in excess of the temperature at which the sensor is set;

.6 in machinery spaces of category A the detectors may be used which reveal a seat of fire on appearing temperature pulsation (heat-pulse detectors). They shall be set to a temperature pulse frequency of 1,9 to 2,3 Hz and above, and operate when an amplitude is exceeded by (2±0,5) °C whatever a space temperature may be;

.7 the type of all automatic detectors shall be so chosen that after the operation test they come back to normal operation without any components being replaced.

7.5.11 Sections and their cables shall meet the following requirements:

.1 automatic detectors and manually operated call points shall be grouped into sections;

.2 a section of automatic fire detectors which covers a control station, a service space or an accommodation space shall not cover a machinery space of category A and cargo spaces of ro-ro ships. In case the fire detection and fire alarm system is fitted with individually identifiable fire detectors, a loop covering sections of automatic fire detectors in accommodation spaces, service spaces and control stations shall not serve machinery spaces of category A and cargo spaces of ro-ro ships;

.3 where the fire detection and fire alarm system is not fitted with individually identifiable fire detectors, no section covering more than one deck within accommodation spaces, service spaces and control stations shall be permitted except the section serving an enclosed stairway. A number of enclosed spaces served by one section shall not exceed 50. In case the fire detection and fire alarm system is fitted with individually identifiable fire detectors, the sections may cover several decks and serve any number of enclosed spaces;

.4 cables of sections, including their feeding cables, being part of the system shall be so arranged as to avoid galleys, machinery spaces of category A, and other enclosed spaces of high fire risk except where it is necessary to provide fire detection or fire alarm in such spaces (refer to 16.8.1.8).

7.5.12 A fire detection and fire alarm system for periodically unattended machinery spaces of category A shall be so designed and the automatic detectors so positioned as to quickly detect the fire in any part of those spaces and under any normal operation conditions of machinery and variations of ventilation. Except in spaces of restricted height and where their use is especially appropriate, fire detection and fire alarm systems using only thermal detectors shall not be permitted. The fire detection and fire alarm system shall initiate audible and visual alarms, distinct from those of any other system not indicating fire, in sufficient number of places to ensure that the alarms are heard and observed on the navigation bridge and by a responsible engineer officer. When the navigation bridge is unmanned, the alarm shall sound in a continuously manned place.

7.5.13 A fire detection and fire alarm system for unattended machinery spaces of category A, as required in 4.2.3, Part VI "Fire Protection", shall meet the following requirements:

.1 an indicating unit shall be installed on the navigation bridge, in the fire control station or another accessible place protected against fire in a machinery space of category A;

.2 a visual alarm on the indicating unit shall indicate the location (zone) of fire;

.3 a fire alarm shall initiate visual and audible alarms distinct from those of any other system which shall be provided at the locations sufficient to be heard and observed by the watch officer on the navigation bridge and by the responsible engineer officer;

.4 in case of power supply failure or any fault in the system, the audible alarm shall be initiated in addition to the visual alarm;

.5 the type and arrangement of detectors shall ensure quick detection of fire and prevent misoperation under normal conditions of machinery space. Provision shall be made for detectors of at least two types operating by different factors of fire detection. In spaces of less than 2,5 m in height only the use of heat detectors is permitted;

.6 the arrangement of detector sections shall provide for the indication of fire location. An air movement due to machinery operation shall not affect the efficient operation of the fire detection and fire alarm system;

.7 detectors with controlled sensitivity shall have fixing arrangement and an indicator of the preset sensitivity;

.8 where provision is made for temporarily cutting off an individual detector or a section of detectors, this shall be clearly indicated. When a preset period of time expires, the switching-off detector or section of detectors shall automatically switch on;

.9 facilities shall be provided to release the fire alarm from the following locations:

.9.1 corridors having entrances to machinery spaces of category A;

.9.2 a wheelhouse;

.9.3 a control station in the machinery space.

7.6 RELEASE INDICATION OF FIRE SMOTHERING SYSTEM

7.6.1 The release indication system shall comply with the requirements of 3.8.3.8 and 4.3, Part VI "Fire Protection".

7.6.2 The release indication system shall be energized from two independent (main and emergency) sources of power. An accumulator battery having a capacity sufficient for feeding the system during 30 min may be used as an emergency source of power. Provision shall be made for automatic change-over of power supply for the release indication system to the emergency source in case of disappearance of voltage from the main source.

7.7 INDICATION OF CLOSING WATERTIGHT AND FIRE DOORS

7.7.1 Indication of closing watertight doors as required in 7.1.9, 7.1.11, 7.1.13, 7.12.2 and 7.12.4 — 7.12.6, Part III "Equipment, Arrangements and Outfit" shall meet the following requirements:

.1 for all ships at watertight door control stations and in the immediate vicinity, and on both sides of the internal doors for cargo ships the visual indicator system for door position shall be provided;

.2 the door position indicator system shall be of self-monitoring type and the means for testing of the indicator system shall be provided at the position where the indicators are fitted;

.3 all door types, including power-operated sliding watertight, shall be provided with an audible alarm, distinct from any other alarm in the area, which will sound whenever such a door is closed. For passenger ships the alarm shall sound for at least 5 s but not more than 10 s before the door begins to move and shall continue sounding until the door is completely closed. In the case of remote closure by hand operation, an alarm shall sound only while the door is actually moving. In passenger areas and areas of high ambient noise, the audible alarms shall be supplemented by visual signals at both sides of the door;

.4 all watertight doors, including sliding doors, operated by hydraulic door actuators, either a central hydraulic unit or independent for each door, shall be provided with a low fluid level alarm or low gas pressure alarm, as applicable or some other means of monitoring loss of stored energy in the hydraulic accumulators.

For ships contracted for construction before 01.07.2021 (in the absence of a contract, for ships, the keels of which are laid or which are at a similar stage of construction before 01.01.2022) or delivered before 01.07.2024, this alarm shall be both audible and visible and shall be located on the central operating console at the navigation bridge.

For ships contracted for construction on or after 01.07.2021 (in the absence of a contract, for ships, the keels of which are laid or which are at a similar stage of construction on or after 01.01.2022) or delivered on or after 01.07.2024, this alarm shall be both audible and visible and shall be located:

on the central operating console at the navigation bridge of passenger ships; and

at the navigation bridge of cargo ships;

.5 the power supply for indicator system of door position and for the alarm system shall be independent of the power supply for operating and closing the doors and shall be provided with a backup power supply from the emergency source of power (e.g. uninterruptible power supply).

For ships contracted for construction before 01.07.2021 (in the absence of a contract, for ships, the keels of which are laid or which are at a similar stage of construction before 01.01.2022) or delivered before 01.07.2024, in case of failure of the main power source audible and visual alarm shall be provided.

For ships contracted for construction on or after 01.07.2021 (in the absence of a contract, for ships, the keels of which are laid or which are at a similar stage of construction on or after 01.01.2022) or delivered on or after 01.07.2024, failure of the normal power supply of the required alarms shall be indicated by:

an audible and visual alarm at the central operating console at the navigation bridge of passenger ships; and

an audible and visual alarm at the navigation bridge of cargo ships.

7.7.2 Indication of position of fire doors as required in 2.2.3.3, 2.2.4 and 3.1.2.3, Part VI "Fire Protection" shall meet the following requirements:

.1 at the navigation bridge the visual indicator system for each door position shall be provided;

.2 remote-released sliding doors or power operated doors shall be equipped with an alarm that sounds for not less than 5 s but not more than 10 s before the door begins to move and shall continue sounding until the door is completely closed;

.3 the power supply for indicator system of door position and for the alarm system shall be independent of the power supply for operating and closing the doors and shall be provided with a backup power supply from the emergency source of power (e.g. uninterruptible power supply). In case of failure of the main power source audible and visual alarm shall be provided.

7.8 SOUND SIGNALS IN ENGINEERS' ACCOMMODATION SPACES

7.8.1 In the engineers' accommodation spaces the sound signalling system shall be provided for the emergency call of the engineer, which is actuated manually from the main engines control station in the engine room or from the main machinery control room, if any.

7.9 PERSONNEL ALARM

7.9.1 In ships where engineering watch is maintained by one person, or in ships with unattended machinery space, personnel alarm shall be provided, and in this case:

.1 the alarm system shall monitor safe and efficient condition of the machinery space personnel at least every 30 min;

.2 the alarm signal shall be transmitted to machinery spaces. If the signal is not acknowledged within 3 min, an appropriate signal shall be transmitted to navigation bridge and to accommodation, service and public spaces where machinery attending personnel might be staying;

.3 the alarm shall be put into operation by personnel attending machinery installation, when one person stays in the machinery space, and shall be disconnected after he leaves the space.

.4 the system shall also meet the requirements in 2.4.1.14, Part XV "Automation".

7.10 CARGO HOLD WATER LEVEL ALARM SYSTEM

For ships contracted for construction before 1 January 2024 or, in the absence of a contract, for ship designs requested for review before 1 January 2024.	*For ships contracted for construction on or after 1 January 2024 or, in the absence of a contract, for ship designs requested for review on or after 1 January 2024.*
7.10.1 The requirements of this Chapter apply to bulk carriers, passenger ships carrying 36 persons and more and single-hold cargo ships other than bulk carriers.	**7.10.1** The requirements of this Chapter apply to bulk carriers, passenger ships carrying 36 persons and more, single-hold cargo ships other than bulk carriers as well as multiple hold cargo ships other than bulk carriers and tankers constructed on or after 1 January 2024.
7.10.2 Unless otherwise specified in this Chapter, the cargo hold water level alarm system shall meet the requirements of 7.3 of this Part, as well as 3.4.11, Part V "Subdivision" and 7.9.9, Part VIII "Systems and Piping".	**7.10.2** Unless otherwise specified in this Chapter, the cargo hold water level alarm system shall meet the requirements of 7.3 of this Part, as well as 3.4.11, Part V "Subdivision" and 7.9.9, Part VIII "Systems and Piping".
7.10.3 The alarm system shall provide warning and emergency visual and audible alarms to indicate water level in cargo holds and for the ballast tanks and dry spaces, forward of the collision bulkhead — only emergency visual and audible alarms. The warning alarm shall be activated when the water reaches the lower level with the emergency alarm activated when the water reaches the upper level as mentioned in 7.9.9, Part VIII "Systems and Piping". It is allowed to use one sensor to initiate warning and emergency alarms. The error in the water level determination by detectors shall not exceed 100 mm. The warning and emergency audible alarms shall be dissimilar. The system shall provide clear identification of spaces from which the alarm has been released. The audible alarm shall be silenced from the alarm panel installed on the navigation bridge.	**7.10.3** The alarm system shall provide warning and emergency visual and audible alarms to indicate water level in cargo holds and for the ballast tanks and dry spaces, forward of the collision bulkhead — only emergency visual and audible alarms. The warning alarm shall be activated when the water reaches the lower level with the emergency alarm activated when the water reaches the upper level as mentioned in 7.9.9, Part VIII "Systems and Piping". It is allowed to use one sensor to initiate warning and emergency alarms. The error in the water level determination by detectors shall not exceed 100 mm. The warning and emergency audible alarms shall be dissimilar. The system shall provide clear identification of spaces from which the alarm has been released. The audible alarm shall be silenced from the alarm panel installed on the navigation bridge.
7.10.4 The alarm system shall be supplied by the main and emergency sources of electrical power. Instead of the emergency source of electrical power an independent, continuously charged from the shipboard charging facility, accumulator battery complying with the requirements for the emergency source of electrical power and capable of supplying the system during at least 18 h may be used. In the event of loss of the main or emergency power and of automatic changeover to the emergency power, an emergency warning alarm shall be released.	**7.10.4** The alarm system shall be supplied by the main and emergency sources of electrical power. Instead of the emergency source of electrical power an independent, continuously charged from the shipboard charging facility, accumulator battery complying with the requirements for the emergency source of electrical power and capable of supplying the system during at least 18 h may be used. In the event of loss of the main or emergency power and of automatic changeover to the emergency power, an emergency warning alarm shall be released.

For ships contracted for construction before 1 January 2024 or, in the absence of a contract, for ship designs requested for review before 1 January 2024.	*For ships contracted for construction on or after 1 January 2024 or, in the absence of a contract, for ship designs requested for review on or after 1 January 2024.*
7.10.5 The system shall be provided with self-monitoring capability. The alarm signal shall be activated when at least the following faults occur: short circuit, circuit break, contact-to-frame fault. For the computer-based systems, alarm shall be additionally provided to indicate the excess program execution time, central processor fault and input-output unit fault. The system shall provide a possibility of checking the visible and audible alarms.	**7.10.5** The system shall be provided with self-monitoring capability. The alarm signal shall be activated when at least the following faults occur: short circuit, circuit break, contact-to-frame fault. For the computer-based systems, alarm shall be additionally provided to indicate the excess program execution time, central processor fault and input-output unit fault. The system shall provide a possibility of checking the visible and audible alarms.
7.10.6 Provision shall be made in the system for disabling of the alarm in the events when the cargo holds and forepeak are used as water ballast tanks. In case where such ballast tanks are emptied, disabling shall be automatically released when the water level lowers below the level of the lowest detector fitted in the hold concerned.	**7.10.6** Bilge alarms may be used as cargo hold water level detectors provided that they meet the requirements set out in 7.10.1 — 7.10.5. Some cargoes require the bilge pumping system to be protected to prevent the spread of contaminated or potentially dangerous fluids. Where the cargo hold bilge well will be completely sealed when specific cargoes are carried, and the bilge well therefore may not be used for the entry of ingress water to the detector(s), a suitable alternative detection point or points shall be provided. If the bilge well is used for when specific cargoes are carried, the bilge well shall not be completely sealed in order to allow water ingress for activating the detectors. Provision shall be made in the system for disabling of the alarm in the events when the cargo holds and forepeak are used as water ballast tanks. In case where such ballast tanks are emptied, disabling shall be automatically released when the water level lowers below the level of the lowest detector fitted in the hold concerned.
7.10.7 The alarm system components fitted in cargo holds, ballast tanks and dry spaces shall be corrosion-resistant and protected to not lower than IP68 degree of protection and those fitted on open deck — to not lower than IP56 degree of protection.	**7.10.7** The alarm system components fitted in cargo holds, ballast tanks and dry spaces shall be corrosion-resistant and protected to not lower than IP68 degree of protection and those fitted on open deck — to not lower than IP56 degree of protection.

For ships contracted for construction before 1 January 2024 or, in the absence of a contract, for ship designs requested for review before 1 January 2024.	*For ships contracted for construction on or after 1 January 2024 or, in the absence of a contract, for ship designs requested for review on or after 1 January 2024.*
7.10.8 Where the alarm system components are fitted in holds intended for the carriage of dangerous goods as well as other goods causing formation of explosive mixtures in the holds, these components and their circuit shall be of intrinsically safe type and protected to not lower than (*Exi*) standard.	**7.10.8** Where the alarm system components are fitted in holds intended for the carriage of dangerous goods as well as other goods causing formation of explosive mixtures in the holds, these components and their circuit shall be intrinsically safe or explosion proof with appropriate apparatus group and temperature class which shall be determined depending on the cargo carried.

7.11 ALARM OF ULTIMATE CONCENTRATION OF DANGEROUSLY EXPLOSIVE AND NOXIOUS GASES

7.11.1 The alarm systems for ultimate concentration of dangerously explosive and noxious gases shall meet the requirements of 9.14.3 and 9.14.4, Part VIII "Systems and Piping", as well as of 7.2.7, Part XII "Refrigerating Plants".

7.11.2 The alarm systems for ultimate concentration of dangerously explosive and noxious gases shall initiate audible and visual alarms in the cargo control room, on the navigation bridge and at the analysing unit when the vapour concentration in a given space reaches a pre-set value, which shall not be higher than the equivalent of 30 % of the lower flammable limit.

7.11.3 The control panel shall be located in the cargo control room, on the navigation bridge, or in a gas safe continuously manned main machinery control room. Clear information shall be displayed on or adjacent to the control panel to allow the crew to readily determine the source of the alarm or fault condition.

7.11.4 An indicating unit shall be located on the navigation bridge if the control panel is located elsewhere.

7.11.5 The control panel shall have a button or switch to manually reset to normal operating condition after alarm and fault conditions are cleared.

7.11.6 Control panel and indicating unit alarm signals shall be distinct from fault condition signals.

7.11.7 Indicating units may have common alarms servicing multiple sampling points, provided that all sampling points within an alarm group are located in the same space.

7.11.8 Control panels shall have the capability to manually test audible and visual alarms.

7.11.9 Audible and visual alarms shall be initiated on the navigation bridge, at the control panel, and at all indicating units under the following conditions:

.1 upon detection of gas concentrations above the alarm setpoint in any monitored space;

.2 in a fault condition, such as power failure or short-circuit;

.3 low or no flow in any sampling pipe;

.4 tampering with the alarm setpoint; or

.5 failure of any self-test functions in computerized alarm systems.

7.11.10 Computerized systems shall have a self-test function to monitor power supply and volatile memory on start-up and repeated at least once every 24 h.

7.11.11 Audible alarms shall continue until their accepting (quitting) is acknowledged, and visual alarm shall remain in effect while an alarm condition is present.

7.11.12 Electrical components which would reasonably be expected to come into contact with sample gases shall be explosion-proof.

7.11.13 The gas detection equipment shall be so designed that it may readily be tested and calibrated.

7.12 INDICATION OF DOOR POSITION IN RO-RO PASSENGER SHIPS AND RO-RO CARGO SHIPS

7.12.1 Visual and audible alarms shall be installed on the navigation bridge and on each operating panel for closing/opening the doors specified in 7.4, 7.15, Part III "Equipment, Arrangements and Outfit" (visor outer bow doors, folding doors, inner bow doors, side shell and stern doors[1]) to provide separate indication of door closed and door fully locked.

The indication panel shall be provided with a lamp test function. The possibility for accidental or unauthorized turning off the indicator light shall be excluded.

7.12.2 The indicator system shall be designed on the fail safe principle and shall include the following:

.1 the indication panels installed on the navigation bridge and at doors' control station shall be provided with:

power supply failure alarm;

earth fault alarm or open-circuit alarm;

a lamp test;

separate indication for door closed, door not closed, door locked and door not locked;

.2 limit switches (door position sensors) closed when the door is closed (when more limit switches are provided for each door they may be connected in series);

.3 limit switches closed when securing arrangements are in place (when more limit switches are provided for each door they may be connected in series);

.4 circuits for the indication of door closed/not closed and for door locked/not locked shall be independent, but may be designed in one multicore cable;

.5 in case of position of limit switches (door position sensors), indication to show: not closed/not locked, securing device is not in place — as appropriate.

7.12.3 The indicator system shall indicate by visual and by audible alarms in the following cases:

.1 if the door is not fully closed, or not fully locked; or

.2 at least one securing device is open or a locking device is unsecured.

7.12.4 The indication panel on the navigation bridge shall be equipped with a mode selection switch "harbour/sea voyage", so arranged that audible alarm is given on the navigation bridge if the vessel leaves harbour with the doors not closed or with any of the securing devices not in the correct position.

7.12.5 The power supply for the indicator system shall be independent of the power supply for operating and closing the doors and shall be provided with a backup power supply from the emergency source of power or any other reliable source (e.g. uninterruptible power supply).

The sensors of the indicator system shall be protected from water, ice formation and mechanical damages, or they shall have respective design resistant to the action of the above factors.

7.12.6 For ro-ro passenger ships, besides the indicator system of door position, provision shall be made of a water leakage detection system with audible alarm and television surveillance, which shall be so arranged as to provide an indication to the navigation bridge and to the main machinery control room of any leakage through inner, side shell and stern doors.

For ro-ro cargo ships, it is permitted that television surveillance of water leakage through side shell and stern doors is provided from the navigation bridge only.

7.12.7 To control the bow door and the inner bow door position a television surveillance system shall be fitted with a monitor on the navigation bridge and in the main machinery control room. The system shall monitor the position of the doors and a sufficient

[1] Hereinafter referred to as "the doors".

number of their securing devices. Special consideration shall be given for the lighting and contrasting colour of objects under surveillance.

7.12.8 A drainage system (sumps) shall be arranged in the area between the bow door and the ramp, or where no ramp is fitted, between the bow door and inner door. The system shall be equipped with an audible and visual alarm functions to the navigation bridge for the high water level alarm in the sump or for water level in these areas exceeding 0,5 m, proceeding from the type of structure.

7.12.9 For ro-ro passenger ships engaged in international voyages, the special category spaces and cargo spaces, indicated in 1.5.4.3 and 1.5.9, Part VI "Fire Protection" (in the absence of continuous patrolling or other effective means of monitoring) shall be monitored by means of television surveillance, so that any movement of vehicles in adverse weather conditions or unauthorized access of passengers thereto, may be detected whilst the ship is moving.

7.13 RELEASE INDICATION OF FIXED LOCAL APPLICATION FIRE EXTINGUISHING SYSTEM

7.13.1 Release indication system shall comply with the requirements specified in 3.12, Part VI "Fire Protection".

7.13.2 The system shall be equipped with an audible and visual alarm functions regarding release of fire extinguishing system both in the protected space and in permanently manned stations. Where several fire extinguishing systems are installed the indication system shall clearly indicate the particular system activated.

7.14 TELEVISION SURVEILLANCE AND INDICATION SYSTEM

7.14.1 Television surveillance and indication systems shall comply with the requirements specified in 7.12.6, 7.12.7 and 7.12.9 of this Part and 7.15.5, Part III "Equipment, Arrangements and Outfit".

7.14.2 Generally, television surveillance and indication systems shall include the following:

.1 TV cameras;
.2 video displays;
.3 commutation switchboard;
.4 movement detectors;
.5 video recorders.

7.14.3 Television surveillance and indication system shall monitor respective areas and spaces and ensure video transmission to permanently attended control stations. Television surveillance and indication system shall give audible and visual signals when the condition of the monitored item/space is changed.

7.14.4 Television surveillance and indication system shall provide the following alarms:

.1 power failure;
.2 television surveillance and indication system failure;
.3 "TV camera — display" channel failure (short circuit, circuit break);
.4 TV camera(s) failure;
.5 movement detector failure;
.6 video recorder failure.

7.14.5 Television surveillance and indication systems may be of black-and-white or color type. The installation of this or that type depends on the required informative capacity of the system, parameters of the monitored item (location, lighting and other properties) and presumable targets (man, cargo, water and other purposes).

7.14.6 TV cameras transmitting video signals with a "signal/noise" (S/N) ratio not less than 50 dB shall be used in television surveillance and indication systems to minimize the noise on display.

7.14.7 Camera lens projection shall not be less than 480 television lines (tvl) (for color image) or not less than 570 tvl (for black-and-white image).

For digital cameras the lens resolution shall be not less than 1024×756 pixels.

7.14.8 Proceeding from their location TV cameras used in television surveillance and indication systems shall be protected to not lower than the following levels:

.1 IP22 — for those fitted in the internal service spaces;
.2 IP44 — for those fitted in machinery spaces;
.3 IP56 — for those fitted on ro-ro decks and exposed parts of the weather deck.

7.14.9 The installation of TV cameras shall be such that all dead zones are covered.

7.14.10 Within internal spaces, TV cameras shall be fitted in places with minimum temperature difference to reduce condensate formation on camera lens.

7.14.11 TV cameras fitted on the exposed part of the deck shall have a thermo-casing with a sun visor.

7.14.12 Where the lighting of monitored area is below TV camera sensitivity, the item (item area) shall be equipped at night-time with additional visible or infra-red lighting. Therewith, either camera lens shall be not swamped by the lights, or TV cameras with back light compensation (BLC) function shall be used. Where television surveillance and indication system of color type is used, infrared lighting is impermissible.

7.14.13 Displays with a capacity to operate around the clock over a long period of time with a static picture shall be used to display the data received from TV cameras. The display diagonal for multi-image shall be within 15" — 21" with a resolution not less than 800 tvl for black-and-white image (400 tvl for color image) or within 10" — 14" for full-screen image displays with a resolution not less than 600 tvl for black-and-white image (300 tvl for color image).

For LCD monitors, the resolution shall be at least 1280×960 pixels at a diagonal of 15" — 21" and at least 1024×756 pixels at a diagonal of 10" — 14".

7.14.14 Special type video recorders with a capacity to record over long periods of time or digital video data memory shall be used to record TV image.

7.14.15 The recording time for a 180 min videocassette shall not exceed 24 h with the use of special-type video recorder. The use of special-type video recorder with a longer recording time is only allowed if the recorder will automatically change over to real-time recording when alarm is activated by the movement detector.

7.14.16 Commutation switchboard shall provide priority display of areas where alarm has been activated.

7.15 SEWAGE HOLDING TANKS LEVEL ALARM

7.15.1 Alarm system shall comply with the requirements of Part IV "Ship's Equipment and Arrangements for the Prevention of Pollution by Sewage" of the Guidelines on the Application of Provisions of the International Convention MARPOL 73/78.

7.15.2 Alarm system shall be supplied from the main source of electrical power.

7.15.3 Alarm system shall ensure operation of audible and visual alarm at the stations with permanent watch in case the tank is filled up to 80 %.

7.16 BULKHEAD SHAFT-GLAND, BEARING AND PUMP CASE TEMPERATURE EXCESS ALARM

7.16.1 Bulkhead shaft gland, bearing and pump case temperature excess alarm shall comply with the requirements of 4.2.5, Part VII "Machinery Installations".

7.16.2 Alarm system shall be supplied from the main source of electrical power.

7.17 MAXIMUM PERMISSIBLE CARGO TEMPERATURE EXCESS ALARM

7.17.1 The maximum permissible cargo temperature excess alarm shall comply with the requirements of 9.6.6, Part VIII "Systems and Piping".
7.17.2 Alarm system shall be supplied from the main source of electrical power.

7.18 OVERPRESSURE OR UNDERPRESSURE IN THE CARGO TANKS ALARM SYSTEM

7.18.1 Overpressure or underpressure in the cargo tanks alarm system shall comply with the requirements of 9.7.12, Part VIII "Systems and Piping".

7.18.2 Alarm system shall be supplied from the main source of electrical power.

7.19 HIGH- AND LIMIT-LEVEL ALARMS IN CARGO TANKS

7.19.1 High- and limit-level alarms in cargo tanks shall comply with the requirements of 9.11.5, Part VIII "Systems and Piping".

7.19.2 Alarm system shall be supplied from the main source of the electrical power.

7.19.3 Alarm system shall produce sound and light signals on permanent watch posts when tanks are full at 95 % and 98 % correspondingly.

7.20 ALARM FOR THE FAILURE OF TOWING WINCH EMERGENCY RELEASE SYSTEM

7.20.1 Alarm shall comply with the requirements of 6.6.3, Part IX "Machinery".

7.20.2 Alarm and indicator means for the parameters connected with the operation of emergency release system shall be supplied from the main power source and shall have a backup power supply from an emergency or any other reliable power source (e.g. uninterruptible power supply).

8 PROTECTIVE DEVICES

8.1 GENERAL

8.1.1 Outgoing circuits of switchboards shall be protected against short circuits and overloads by means of devices installed at the inception of each circuit.

No overload protection is required for the switchboard power supply if the current consumers supplied from this switchboard have individual protective devices, and the power supply cable is selected on the basis of maximum working current.

8.1.2 Protective devices shall be so adapted to the characteristics of the equipment under protection that they operate under inadmissible overloads and short-circuit currents.

8.1.3 The electric protection system shall be discriminative with regard to both the overload currents and the short-circuit currents. Such protection system shall be designed so that its operation could not adversely affect the reliable functioning of ship's generating plant and the power supply of essential consumers. Short-circuit and overload protective devices shall not operate at starting currents of the electrical equipment under protection.

8.1.4 Overload protection shall be provided in:

.1 at least one phase or positive pole in a two-wire system;

.2 at least two phases in an insulated three-wire three-phase current system;

.3 all phases in a three-phase four-wire system.

8.1.5 Short-circuit protection shall be fitted in each insulated pole of a direct-current system or in each phase of an alternating current system.

Short-circuit current protective devices shall be set to operate at not less than 200 % of the rated current of the electrical equipment under protection. Operation of the protective devices may be without time delay or with a time delay necessary for the proper discrimination.

The short-circuit current protective device may be used for the protection of both the electrical equipment itself and its supply cable.

8.1.6 Where cables of reduced cross-sectional area are used in some lengths of power supply circuit, additional protection shall be provided for each of such cables unless the preceding protective device is capable of protecting the cable of reduced cross- sectional area.

8.1.7 Protective devices excluding the possibility of immediate repeated switching after operation of the protection shall not be used in supply circuits of the emergency switchboard, as well as in supply circuits of emergency consumers.

8.1.8 The design of the electronic and computer protection devices of generators and major services shall be such as to ensure easy identification and regulation of their operational settings.

Protection devices shall be equipped with the necessary apparatuses and instruction manuals shall be provided for checking their serviceability and the condition of the settings.

The protection devices of generators and important major services shall be tested once in 5 years to confirm the accuracy of their operation.

8.2 PROTECTION OF GENERATORS

8.2.1 Generators not intended for parallel operation shall be provided with means of protection against overloads and short circuits. Fuses may be used as protective devices for generators rated under 50 kW (kVA).

8.2.2 Generators intended for parallel operation shall be provided at least with the following means of protection:

.1 against overloads;

.2 against short circuits;

.3 against reverse current or reverse power;

.4 against under voltage.

It is necessary that the devices used for generator overload protection shall be provided with light and sound alarms to operate with a time delay of up to 15 min at the loads from 100 to 110 % of the rated current, and shall be capable of disconnecting the generator under protection after a time delay to suit the generator thermal time constant at the loads from 110 to 150 % of the rated current.

It is necessary that for a setting of the protection to operate at 150 % of the rated generator current the time delay shall not exceed 30 s for an alternating-current generator and 15 s for a direct-current generator. An overload exceeding 150 % of the rated current may be allowed where it is required by operating conditions and is admitted by the generator construction.

Overload protection settings and time delay shall be selected to suit the overload characteristics of the generator prime mover so that the prime mover is capable of developing the necessary output within the time delay period adopted. The protective devices used for generator overload protection shall not prevent the possibility of re-starting the generator immediately.

8.2.3 Automatic and selective disconnect of non-essential services shall be provided in the event of the generator overload. These services shedding may be carried out in one or several steps, depending on the generator overload capacity.

Therewith:

.1 the automatic disconnect is not allowed for primary essential services;

.2 the automatic disconnect is allowed for secondary essential services, provided disconnection will not prevent services required for safety being immediately available when the power supply is restored to normal operating conditions;

.3 the automatic disconnect is allowed for services needed for maintaining the minimum comfort habitability conditions for the crew and passengers on the ship.

Examples of such services are as follows:

cooking;

heating, domestic refrigeration;

domestic ventilation drives;

sanitary and fresh water, etc.

This requirement may be dispensed with in the case of electrical installations of low power.

8.2.4 Reverse-current and reverse-power protection of generators intended for parallel operation shall be selected to suit characteristics of generator prime mover. The respective protection settings shall be in accordance with those specified in Table 8.2.4.

Reverse-power protection for alternating-current generators may be replaced by a different, but not less effective, means of protection. With settings specified in the Table the protection of the types in question shall be activated in 10 s.

Reverse-current protection for direct-current generators shall be installed in the pole opposite to that, in which the equalizer lead is connected. Reverse-power or reverse-current protection shall still be capable of operation when the voltage applied is reduced by 50 % although reverse current or reverse power may have altered values.

Table 8.2.4

Kind of current	Limits of reverse-current or reverse-power protection settings related to generator prime mover	
	Turbine	Internal combustion engine
Alternating	2 — 6 % of rated output of generator, kW	8 — 15 % of rated output of generator, kW
Direct	2 — 6 % of rated current of generator, A	8 — 15 % of rated current of generator, A

Reverse-current and reverse-power protection shall permit trasfer of power fed from the ship's mains (as, for example, from cargo winches).

8.2.5 Undervoltage protection shall ensure the possibility of a reliable connection of generators to the busbars at a voltage of 85 % or more of rated voltage and shall exclude the possibility of generator-to-busbar connection at a voltage less than 35 % of rated voltage. Besides, it shall disconnect the generators in case of reduction of voltage across its terminals in the range from 70 to 35 % of the rated value.

Undervoltage protection shall operate with a time delay for disconnection of generators from busbars in case of reduction of voltage and shall operate without time delay at the attempt to make connection to the generator busbars before the minimum voltage specified above is reached.

8.2.6 Generators with the ratings of 1500 kVA and above shall be equipped with protective device or protective system, which shall open the circuit-breaker and shut down the generator in the event of a short circuit in the generator or in the supplying cable between the generator and its circuit-breaker. This requirement shall not apply to emergency generators.

8.2.7 If a turbine-driven direct-current generator is intended for operation in parallel, provision shall be made for tripping the circuit breaker of the generator when the automatic safety device of the turbine operates.

8.2.8 The current settings of protective devices with time delay shall be chosen in such a way that in any case a reliable interruption of short-circuit current is ensured after the prescribed time delay.

8.2.9 It is permitted to use safety devices in excitation systems of generators as protective devices for semiconductor elements.

8.3 PROTECTION OF ELECTRIC MOTORS

8.3.1 Outgoing feeders from switchboards supplying electric motors rated at over 0,5 kW shall be provided with means of protection against short-circuit currents and overloads, as well as with no voltage protection if the motor need not be automatically restarted.

It is admissible for overload and no-voltage protective devices to be installed in the motor starting apparatus.

8.3.2 The overload protective devices for continuously running motors shall disconnect the motor under protection when the load is in the range from 105 to 125 % of the rated current.

8.3.3 In supply circuits of fire pump electric drives the overload protective devices operating on the principle of electrothermal and temperature relays shall not be used.

The overload protective devices may be substituted by light and sound alarms.

8.4 STEERING GEAR PROTECTION

8.4.1 Only short-circuit current protection shall be provided for electric motors and control systems of electric or electrohydraulic steering gear.

Light and audible warning shall be provided of the motor overload or of any phase failure of the feeder supplying the motor.

8.4.2 Circuit breakers used to protect direct-current motors against short-circuit currents shall be set for release without time delay at currents not lower than 300 % and not higher than 400 % of the rated current of the motor under protection, while those used with alternating-current motors shall be set for release without time delay at currents not lower than 125 % of the peak starting current of the motor under protection.

In case fuses are used as protective devices the rated current for the fuse links shall be one grade of rating higher than it follows from the values specified for the electric motor starting currents.

8.4.3 For electric motors of the drives for the active means of the ship's steering short-circuit and overload protective devices shall be provided.

Overload protective devices of the above mentioned motors shall be fitted with light and sound alarms to warn of the motor overload and shall disconnect the electric motor over the load range specified in 8.3.2.

Short-circuit protection shall be in compliance with the requirements of 8.4.2.

8.4.4 For directly driven electric motors of steering gear, overload protection is permitted for locked rotor periods above 60 s with a setting of not less than twice the full load current of the motor protected.

Where such electric motors obtain their power supply via an electronic converter, e.g. for speed control, and which are limited to full load current are exempt from the requirement to provide overload protection. Alarm at electronic converter overload shall be provided with a setting equivalent to the highest permissible current for the normal operation of steering gear.

8.5 PROTECTION OF TRANSFORMERS

8.5.1 Short-circuit and overload protective devices shall be installed on the supply feeders of transformer primaries. If the supply feeder of the transformer primary is protected against short circuit currents only, then the supply feeder of the secondary shall be protected against overload.

Transformers rated up to 6,3 kVA may be protected by fuses only.

No overload protection or alarm is required for voltage transformers and supply transformers of the control circuits.

8.5.2 Where transformers are intended for parallel operation, it is necessary that switches shall be provided to disconnect their primaries and secondaries, but not necessarily at the same time.

If such transformers are fed from different main switchboard sections, which may be isolated in service, provision shall be made for an interlock to preclude their parallel operation in case of main switchboard sections isolation.

8.5.3 The switching-over of instrument current transformers shall be so arranged as to prevent the possibility of their secondary windings being on open circuit.

8.6 PROTECTION OF ACCUMULATOR BATTERIES

8.6.1 Means of protection against short-circuit currents shall be provided for accumulator batteries other than those, which are designed to start internal combustion engines.

8.6.2 Each battery charging system shall be provided with protection against battery discharge due to a drop or loss of the charger output voltage.

8.6.3 For accumulator batteries designed for starting internal combustion engines, it is recommended that disconnectors shall be fitted at the start of the circuit on the accumulator side to disconnect the batteries from services (the disconnector may be fitted in one pole).

8.7 PROTECTION OF PILOT LAMPS, VOLTMETERS, CAPACITORS AND VOLTAGE COILS

8.7.1 Pilot lamps, as well as measuring and recording instruments shall be provided with short circuit protection or short-circuit current limiting devices.

Pilot lamps may have no short-circuit protection of their own, nor short-circuit current limiting devices, provided that all the conditions specified below are met:

.1 the lamps are enclosed together with the device;

.2 the lamps are supplied from circuits inside the enclosure of the device;

.3 the protection of the circuit of the device is rated for current not exceeding 25 A;

.4 a fault in the lamp circuit is not liable to cause an interruption in the operation of an essential service.

Short-circuit protection or current limiting devices shall be located as close as practicable to the terminals of the device under protection on the supply side.

8.7.2 Radio interference suppression capacitators installed in the circuits of main and emergency switchboards, generators and essential electrical installations shall be protected against short-circuit currents.

Requirements for the protection of capacitators in the systems with electrical power distribution for direct current are specified in 23.4.3.

8.7.3 The voltage coils of apparatus and devices for control and protection shall be protected against short-circuit current, but they may have no protection of their own, provided that the conditions specified below are met:

.1 the coils are enclosed with the device, are under overall protection and belong to the control system of one device;

.2 the coils are supplied from a device circuit, the protection of which is rated for current not exceeding 25 A.

8.8 PROTECTION OF POWER SEMICONDUCTOR UNITS

8.8.1 Provision shall be made for protecting power semiconductor units from internal and external overvoltage.

8.8.2 Semiconductor element units shall be protected against short circuit. The overload protection of diodes and semiconductors shall be isolated from the overload protection of power circuits.

8.8.3 Where only one consumer is available, a common overload protection is permitted for diode and semiconductors units, and power circuits.

8.8.4 Additional requirements for the protection of semiconductor inverters of an electric drive supplied from d.c. distribution devices are specified in 23.4.3.2.

8.9 RESIDUAL-CURRENT DEVICES (RCD)

8.9.1 To protect personnel against current injury and to protect some kinds of electrical equipment against single-phase earth fault residual-current devices shall be used.

8.9.2 The residual-current devices shall be fitted in the supply circuits of socket outlets intended to feed the portable equipment and in the supply circuits of cabin's socket outlets as well as the socket outlets in public and other spaces with the voltage in excess of the safe one (50 V).

8.9.3 The residual-current devices shall be set to operate at zero sequence current within 10 — 30 mA.

8.9.4 For essential electrical equipment, installation of the residual-current devices is not permitted.

9 EMERGENCY ELECTRICAL INSTALLATIONS

9.1 GENERAL

9.1.1 In each self-propelled ship, an autonomous emergency source of electrical power shall be provided. Such source is not required for ships, in which the main sources of electrical power are accumulator batteries, on condition that at least one of the batteries installed satisfies the capacity and location requirements imposed upon the emergency source of electrical power.

9.1.2 A generator or an accumulator battery may be used as an emergency source of power.

9.1.3 The capacity of the emergency source of power shall be sufficient to supply simultaneously all those services that are essential for the safety of navigation in an emergency. In ships where electrical power is necessary for propulsion, the capacity of the emergency source of electrical power shall be sufficient to restore propulsion to the ship (in conjunction with other machinery, as appropriate) from a dead ship condition within 30 min after blackout.

9.1.4 The possibility shall be provided for functional testing of the complete emergency installation including testing of automatic starting arrangements of the diesel generator.

9.1.5 An indicator shall be mounted in the main machinery control room or on the main switchboard to show when the battery, which serves as an emergency source of electrical power, is being discharged.

9.1.6 The emergency sources of electrical power shall be provided only with short-circuit protection. If the emergency source of power is a generator, in the main machinery control room or in the main switchboard visual and audible alarms shall be fitted to warn of the generator overload.

9.2 SPACES OF EMERGENCY SOURCES OF ELECTRICAL POWER

9.2.1 The spaces of emergency sources of electrical power and of their transformers (if any), of emergency transitional sources of electrical power, emergency switchboard and distribution board of emergency lighting shall be located above the uppermost continuous deck, astern from forepeak bulkhead (collision bulkhead) and be easily accessible from the open deck. The above mentioned spaces in ships covered by the requirements of Part V "Subdivision" shall be located, as a minimum, at a height of 300 mm above the deepest (damage) waterline.

9.2.2 The arrangement of emergency sources of electrical power and pertinent transformers, if any, of transitional sources of electrical power, emergency switchboard and distribution board of emergency lighting with regard to the main sources of electrical power and pertinent transformers, and with regard to the main distribution board, shall be such that a fire or another emergency in the space of the main source of electrical power, of pertinent transformers, main distribution board or in any machinery space of category A would not hamper the supply, control and distribution of electrical power from the emergency source.

9.2.3 Spaces containing emergency sources of electrical power, pertinent transformers, transitional sources of electrical power, emergency switchboard and distribution board of emergency lighting shall not, where possible, be adjacent to machinery and boiler spaces or to spaces containing the main source of electrical power, pertinent transformers and main distribution board.

In case of adjacent arrangement, the decks and bulkheads separating these spaces shall be constructed in accordance with the requirements of Part VI "Fire Protection" relating to control stations.

9.2.4 Emergency switchboard shall be as close as possible to the emergency source of electrical power.

9.2.5 Where a generator serves as the emergency source of electrical power, the emergency switchboard shall be installed in the same space as the diesel generator except where such an arrangement would adversely affect the distribution board operation.

All starting arrangements, charging facilities and starter accumulator batteries of the emergency unit shall also be installed in this space, provided the requirements of 13.2 are complied with.

9.2.6 The emergency diesel generator space shall be provided with heating appliances to ensure the temperature in the space sufficient for starting, without fail, of the emergency generating set and ventilation in accordance with the requirements of 12.5.3, Part VIII "Systems and Piping".

9.2.7 Where the emergency source of electrical power is an accumulator battery, this battery and the emergency switchboard shall be installed in separate spaces.

The requirements for the battery compartments are given in 13.2.

9.3 EMERGENCY SOURCES OF ELECTRICAL POWER IN CARGO SHIPS

9.3.1 In cargo ships, the emergency sources of electrical power shall supply the following services:

.1 emergency lighting for:

all corridors, stairways and exits from service spaces as well as passenger lift cars and trunks;

machinery spaces, main generating stations;

all control stations, main and emergency switchboards;

emergency diesel generator space;

wheelhouse;

chartroom and radioroom;

stowage positions for emergency and fireman's outfit and also positions where manual fire alarms are fitted;

steering gear compartments;

positions at fire and sprinkler pumps, emergency bilge pump and starting positions of their motors;

cargo pump rooms;

helicopter hangars and landing areas;

gyrocompass space;

medical rooms;

.2 navigation lights, lights of "Vessel not under command" signal and other lights required by Part III "Signal Means" of the RS Rules/E;

.3 internal communication means and general alarm signals;

.4 radio equipment and navigational equipment according to the requirements of Part IV "Radio Equipment" and Part V "Navigational Equipment" of the RS Rules/E where the emergency source of power is a diesel generator;

.5 fire detection and alarm systems;

.6 daylight signalling lamps, sound signal means (whistles, gongs, etc.), manual calling and other signals required under emergency conditions;

.7 machinery and devices mentioned under 3.2.1.2, 3.4.7, 3.7.3.2.1 and 3.9.2, Part VI "Fire Protection";

.8 electric drives of watertight doors with their indicators and alarms;

.9 electric drives of devices holding fire doors;

.10 electric drive of the launching appliance for the lifeboat specified in 6.20.4.7, Part II "Life-Saving Appliances" of the RS Rules/E.

.11 other systems, the operation of which would be found necessary by the Register to ensure the safety of the ship and the persons on board.

In ships of unrestricted service and restricted area of navigation **Rl** of 300 and above gross tonnage, the emergency sources of electrical power shall ensure the supply of services listed above during 18 h.

Consumers mentioned under 9.3.1.3 — 9.3.1.6 may be supplied from their own batteries arranged as provided for in 9.2 and having a capacity sufficient to supply those consumers during 18 h.

For ships of gross tonnage 300 and above of restricted areas of navigation **R2**, **R2-RSN**, **R2-RSN(4,5)**, **R3-RSN** and **R3** the required period of 18 h may be reduced to 12 h.

For ships of less than 300 gross tonnage, the period of 18 h may be changed to 6 h in the case of unrestricted service and restricted area of navigation **R1** and to 3 h in the case of restricted areas of navigation **R2**, **R2-RSN**, **R2-RSN(4,5)**, **R3-RSN and R3**.

9.3.2 The emergency source of electrical power shall ensure, during 3 h, the emergency lighting of muster and embarkation stations for boarding life-saving appliances on deck and overboard according to 2.3.4 and 2.7.7, Part II "Life-Saving Appliances" of the RS Rules/E.

9.3.3 The supply of steering gear shall be effected from the emergency source of electrical power in accordance with 5.5.6.

9.3.4 Where a generator is used as the emergency source of electrical power, it shall be:

.1 driven by an internal combustion engine (refer to 2.2.5, Part IX "Machinery");

.2 automatically started upon failure of the electrical supply from the main source of electrical power monitored at the emergency switchboard busbars and automatically connected to the emergency switchboard, and consumers stipulated under 9.3.1 shall be automatically supplied by the emergency generator. The total time of starting and load take-over by the generator shall not exceed 45 s;

.3 in case the automatic start of emergency unit stipulated by 9.3.4.2 shall not take place within 45 s, an emergency transitional source of electrical power shall be provided, which shall start immediately on failure of the main source of electrical power.

9.3.5 Where an accumulator battery is used as the emergency source of electrical power, it shall:

.1 operate without recharging with voltage variations across the terminals within 12 % of rated voltage during the whole discharge period, where voltage variations across the terminals of accumulator battery connected to an electronic voltage converter are determined by the permissible range of voltage variation across the terminals of the converter;

.2 be automatically connected to emergency switchboard busbars in case of failure of the main source of electrical power and supply at least the consumers mentioned under 9.3.7 during the time stipulated by 9.3.1 excepting electric drives of fire doors with their indicators and alarms, which can be supplied during 30 min.

9.3.6 As transitional emergency source of electrical power stipulated by 9.3.4.3, an accumulator battery shall be used, which shall operate without recharging with voltage variations across the terminals within 12 % of rated voltage during the whole discharge period. Voltage variations across the terminals of accumulator battery connected to an electronic voltage converter are determined by the permissible range of voltage variation across the terminals of the converter, which shall not be above values specified in 2.1.3.1.

9.3.7 The capacity of the battery serving as the transitional source of electrical power shall be sufficient to supply, during 30 min, the following consumers:

.1 lighting and essential navigating lights according to 9.3.1.1, 9.3.1.2 and 9.3.2;

.2 all internal communications and announcing systems required in an emergency;

.3 general alarm system, fire detection and alarm system and warning system on starting a smothering fire-extinguishing system;

.4 daylight signalling lamps, sound signal means (whistles, gongs, etc.);

.5 command broadcast apparatus in accordance with item 11 of Table 2.3.4, Part IV "Radio Equipment" of the RS Rules/E;

.6 closing gear of watertight doors, their position indicators and signals warning of their closure;

.7 ship's security alarm system required by Part IV "Radio Equipment", as well as AIS installation and long-range identification and tracking system equipment, as required by Part V "Navigational Equipment" of the RS Rules/E.

Services listed under 9.3.7.2 — 9.3.7.7 may not be supplied from the transitional source if they have their own accumulator batteries, by which they are supplied during the required period of time.

9.3.8 For Class **INF2** and Class **INF3** ships, in accordance with the classification given in 7.3.2, Part VI "Fire Protection", regardless of the navigation area and tonnage of the ships, the emergency source of electrical power shall supply the services listed in 7.3.6 and 7.3.8, Part VI "Fire Protection" for a period of 36 h and 9.3.1 of this Part.

9.4 DISTRIBUTION OF ELECTRICAL POWER FROM EMERGENCY SOURCES

9.4.1 Under normal service conditions, emergency switchboard shall be supplied from the main distribution board. The supply feeder shall have an overload and short-circuit protection fitted at the main distribution board.

At the emergency switchboard, a switch shall be provided, which shall switch off automatically in the case of de-energizing the busbars of the main distribution board.

Where the main distribution board shall be supplied from the emergency switchboard, the automatic switch at the emergency switchboard shall be provided with short-circuit protection at least.

9.4.2 The emergency generator, during the stay of the ship in port, may be used to supply nonemergency consumers (refer also to 2.2.6, Part IX "Machinery"). In doing so, the following conditions shall be met:

provision is made for automatic disconnection of non-emergency consumers from the emergency switchboard to prevent overloading of the generator and to ensure the supply of emergency consumers;

damage of any control, protection and alarm circuits intended to maintain operation of the emergency generator during the stay of the ship in port, shall not affect the work of the main and emergency electrical power sources;

arrangements are provided to select the operating modes of emergency generators with a quick changeover to emergency mode being possible;

provision is made for instructions to be available onboard, for bringing all the controls (valves, switches, etc) in a position ensuring independent operation of the emergency generator when the ship is underway, and also containing information on the required oil fuel capacity, on the position of the operating mode switch (if any), on the position of ventilation closures, etc.

9.4.3 Consumers listed under 9.3.1 and 20.1.2 shall be supplied through separate feeders from the busbars of the emergency switchboard fitted up with relevant switch gear and protection. Supply of consumers mentioned under 9.3.1.2 — 9.3.1.6 and 20.1.2.1.2 — 20.1.2.1.6 may be effected from the main control console in the wheelhouse, which is supplied in conformity with 4.5.2.

9.4.4 Where a transitional source of power is available, consumers listed under 9.3.7 and 20.1.2.7 shall be supplied through a special distribution board on the feeders, of which no switches shall be fitted.

9.5 STARTING ARRANGEMENTS FOR EMERGENCY DIESEL GENERATORS

9.5.1 The following arrangements may be used as starting arrangements for emergency diesel generators:

.1 electric starter with its own accumulator battery and charging device;

.2 compressed air system with its own independent air receiver;

.3 hydraulic starting system;

.4 manual starting arrangements: starting handle for manual cranking, inertia starters, manually charged hydraulic accumulators or powder charge cartridges.

9.5.2 Each emergency generating set arranged to be automatically started shall be equipped with a starting device of an approved type with a stored energy capability of at least three consecutive starts. The source of stored energy shall be protected to preclude critical depletion by the automatic starting system, unless a second independent means of starting is provided. In addition, a second source of energy shall be provided for additional three starts within 30 minutes unless manual starting can be demonstrated to be effective.

9.5.3 Where automatic starting of the emergency diesel generator is not required, manual starting is permissible with the use of one of the starting arrangements specified in 9.5.1.4.

When manual starting is not practicable, the starting arrangements shall comply with the requirements of 9.5.2.

9.5.4 The starting arrangements of the accumulator batteries and the electric drives of the machinery ensuring the functioning of the compressed air or hydraulic systems of the emergency diesel generator starting shall be supplied from the emergency switchboard by separate feeders.

9.6 ALARM SYSTEM AND PROTECTION OF EMERGENCY DIESEL GENERATOR DRIVES

9.6.1 Emergency diesel generator drives having power of 220 kW and above shall be equipped with a protective device ensuring the shutdown of the engine in case of overspeed.

9.6.2 All protective devices that may influence the shutdown of emergency diesel generator drives, except for those preventing overspeed, shall be automatically overridden when the emergency diesel generator is in remote control or automatic mode during navigation. This requirement covers all emergency diesel generators regardless of their drives' output.

9.6.3 In addition to the remote fuel stop control, a local means of emergency shutdown of emergency diesel generator drives shall be provided.

9.6.4 For emergency diesel generator drives alarm system shall be activated at:

fuel oil leakage from high pressure pipes;

lubricating oil pressure below the minimum permissible value;

high temperature of cooling water or cooling air.

9.6.5 For drives having power of 220 kW and above, in addition, provision shall be made for alarm system activating at:

high lubricating oil temperature;

pressure or flow of cooling water below the minimum permissible value;

overspeed.

9.6.6 For drives having power of more than 2250 kW or with cylinder bore of more than 300 mm, in addition, provision shall be made for alarm system activating at excess of the oil mist concentration in crankcase.

9.6.7 Alarm system shall comply with the requirements given in 2.4.1, Part XV "Automation".

9.6.8 Grouped alarms shall be arranged on the navigation bridge.

9.6.9 Proceeding from the power of drives, local indication of the parameters listed in 9.6.4 — 9.6.6 shall be provided (within the same space as the emergency diesel generator) independent of the alarm and safety systems.

9.7 UNINTERRUPTIBLE POWER SYSTEM (UPS)

9.7.1 Uninterruptible power system (UPS), in addition to the requirements set forth below, shall comply with the requirements of IEC 62040-3:2011 and applicable requirements of national standards.

9.7.2 UPS shall be so designed as to comply with the applicable requirements of IEC 62040_-1:2017, IEC 62040-2:2016, IEC 62040-3:2011, IEC 62040-4:2013 and/or IEC 62040-5-3:2016.

9.7.3 UPS complying with these requirements may be used as emergency or transitional sources of electrical power as required by this Part.

9.7.4 UPS type selection shall be appropriate to power supply requirements of the connected load equipment.

9.7.5 UPS shall be provided with a bypass, which ensures power supply to connected load from the ship's mains if the inverter fails.

9.7.6 Each UPS shall be provided with audible and visual alarm to be given for:

.1 power supply failure to the connected load;

.2 earth fault;

.3 operation of battery protective device;

.4 when the battery is being discharged; and

.5 when the bypass is in operation for on-line UPS.

9.7.7 The requirements for location of the UPS shall be similar to the requirements for the location of the emergency or transitional source of electrical power.

9.7.8 UPS utilising sealed batteries may be located in any space other than the accommodation space, provided sufficient ventilation is ensured in compliance with the applicable requirements of IEC 62040-1:2017 and IEC 62040-3:2011.

9.7.9 UPS shall maintain rated voltage and frequency on the load side throughout the whole time necessary to supply the connected services.

9.7.10 On voltage recovery in the power supply circuit, the capacity of the UPS rectifier shall be sufficient to maintain rated voltage and frequency on the load side with simultaneous recharging the battery by the maximum possible charging current.

9.7.11 The accelerated (boost) charging of the UPS batteries by the maximum possible charging current shall be interlocked with the ventilation of the space where the UPS batteries are installed.

10 ELECTRICAL MACHINES

10.1 GENERAL

10.1.1 The materials of propulsion motors shafts, generators and slip coupling built into the shafting shall comply with the requirements of 3.7, Part XIII "Materials".

10.1.2 Alternating-current generators together with voltage correctors shall be capable to sustain, under steady short-circuit conditions, at least three-times the rated current within 2 s.

10.1.3 Electric propulsion generators and electric propulsion motors, or, where justified, also machines of different designation, shall have heating arrangements to maintain their temperature at least 3 °C above the ambient air temperature.

10.1.4 Generators built into the shafting of the main machinery shall have split stators and bearing shields if, due to the shaft arrangement, the stator displacement in the direction of the shaft from the rotor is not possible. Such generators shall have an air gap preventing mechanical contact of the rotor and stator under the most unfavourable service conditions.

10.1.5 Rotors and armatures of alternating and direct-current machines shall be capable of withstanding for 2 min, without damage and permanent set, the following increased speeds of rotation:

.1 generators, rotating converters and electric slip coupling and brakes: 120 % of the rated speed, but at least by 3 % more than the maximum speed transient process;

.2 series-wound motors: 120 % of the maximum permissible speed as indicated on the rating plate, but not less than 150 % of the rated speed;

.3 all motors other than mentioned above, 120 % of the maximum no-load speed.

10.1.6 Where a machine is so designed that after installation on board the ship its bottom portion is positioned below floor level, ventilation air intake shall not be through the bottom part of the machine.

10.1.7 Application of external cooling fans is not recommended for machines intended for installation on weather decks.

10.1.8 The power of electric motors supplied from an electrical power source, which does not comply with the requirements of 2.2.1.3, shall be calculated taking into account the additional heating due to the higher harmonic components.

10.1.9 Generators and generator systems, having the ship's propulsion machinery as their prime mover but not forming part of the ship's main source of electrical power may be used whilst the ship is at sea to supply electrical services required for normal operational and habitable conditions provided that:

.1 there are sufficient and adequately rated additional generators fitted, which constitute the main source of electrical power required by SOLAS, meeting the requirements of Section 3.

.2 constituting the main source of electrical power required by 3.1.3 and also upon the frequency variations exceeding ± 10 % of the limits specified below.

.3 within the declared operating range of the generators and/or generator systems the specified limits for the voltage variations and the frequency variations in 2.1.3.1 can be met; the total harmonic distortion does not exceed 5 %, for single harmonic — 3 %.

.4 the short circuit current of the generator and/or generator system is sufficient to trip the generator/generator system circuit-breaker taking into account the selectivity of the protective devices for the distribution system.

.5 where considered appropriate, load shedding arrangements are fitted to meet the requirements of 3.1.3.

.6 on ships having remote control of the ship's propulsion machinery from the navigating bridge means are provided, or procedures be in place, so as to ensure that supplies to essential services are maintained during manoeuvring conditions in order to avoid a blackout situation.

10.2 SLIP RINGS, COMMUTATORS AND BRUSHES

10.2.1 Direct-current machines for driving the propulsion plants and direct-current machines rated at 200 kW and over shall be provided with sight holes to enable observation of the commutator and brushes without removing the lids.

10.2.2 The permissible wear of commutator segments or slip rings shall be indicated on their sides. It shall be taken equal to at least 20 % of the commutator segment or slip ring height.

10.2.3 For armatures more than 1000 kg in mass provision shall be made to allow reconditioning of the commutator without removing the armature from the machine.

10.2.4 A flexible copper conductor shall be used for drawing current from brushes. Brush holder springs shall not be used for this purpose.

10.2.5 The position of brushes in direct-current machines shall be clearly and indelibly marked.

10.2.6 Commutator type machines shall be capable of operating practically without sparking at any load from zero to rated value. No sparking shall be possible at the specified overloads, reversals or startups, to such an extent as to cause damage to brushes or commutators.

10.3 BEARINGS

10.3.1 Bearings shall be so designed as to avoid the possibility of oil splashing or leaking along the shaft and coming into contact with the machine windings or live parts.

10.3.2 The casing of the sliding bearing shall be fitted with a hole for excessive lubricating oil drain and with a lid in the upper part of the casing. Oil level indicators shall be provided on machines rated at 100 kW or more.

10.3.3 Pressure lubrication system shall incorporate pressure indicators for oil entering the bearing.

10.3.4 In electric propulsion machinery, or machines of different designation, where so justified, provisions shall be made to prevent flow of shaft currents through sliding friction bearings.

10.3.5 Generators driven by belts or chains from the main machinery of the ship shall be so designed that the effect of the lateral forces is taken into account.

10.4 TEMPERATURE DETECTORS

10.4.1 Stators of alternating-current machines rated at over 5000 kW, or having a core length of more than 1 m, shall be provided with temperature detectors installed where the machine may be expected to develop the highest temperatures.

10.4.2 Embedded temperature detectors are recommended for electric motors with short-time or intermittent operating conditions.

10.4.3 It is recommended that overload protection for windlass-driving electric motors shall be by means of embedded temperature detectors so selected that the protection device will disconnect the motor when the temperature rise limit for the insulation employed is exceeded by more than 30 %.

The terminals of the detector shall be located so as to be easily accessible.

10.5 OVERCURRENT

10.5.1 Generators shall be so designed that after reaching the steady-state temperature corresponding to the rated load they shall be capable of sustaining overcurrent as specified in Table 10.5.1.

Table 10.5.1

Type of generator	Overcurrent, %	Duration of overload, s
A.c. with ratings not more than 1200 kVA	50	30
A.c. with ratings more than 1200 kVA	50	15
D.c.	50	15

10.5.2 Electric motors shall be so designed that they are capable of developing, without stopping or sudden rotation frequency changes, the increased torque specified in Table 10.5.2.

Table 10.5.2

Nos	Type of motor	Overload in torque, %	Duration of overload, s	Testing conditions
1	Synchronous motors, as well as squirrel-cage motors with starting current not less than 4,5 times the rated current	50	15	Frequency, voltage and excitation to be maintained at rated levels
2	Induction motors for continuous and intermittent duties	60	15	Frequency and voltage to be maintained at rated levels
3	Motors as specified in item 2, but for short-time and continuous duty with varying load	100	15	Frequency and voltage to be maintained at rated levels
4	Direct-current motors	50	15	Voltage to be maintained at rated level

10.5.3 For electric propulsion motors overload in torque and duration of overload are defined by the ship's designer taking into account changes in the main electric propulsion plant loads during maneuvering, sea passage, including navigation in difficult weather conditions etc.

10.6 ALTERNATING-CURRENT GENERATORS

10.6.1 General.

10.6.1.1 Each alternating-current generator shall have a separate, independent automatic voltage regulation system.

10.6.1.2 Alternating current generators with rated power not exceeding 1200 kVA shall possess sufficient excitation capacity to maintain the rated voltage with an accuracy of 10 % for 30 s at generator overcurrent equal to 150 % of the rated value and at a power factor 0,6. For generators with rated power above 1200 kVA, the duration of the above-stated overcurrent shall be 15 s.

10.6.1.3 Protection of alternating-current generators shall comply with the requirements of 8.2.

10.6.2 Voltage regulation systems.

10.6.2.1 Alternating-current generators shall have automatic voltage regulation systems ensuring that the voltage may be maintained within (2,5 % of the rated value (up to 3,5 % for emergency generators) at all load changes from no-load to rated load values at the rated power factor. The speed in this case shall be within the range specified in 2.11.3, Part IX "Machinery".

10.6.2.2 A sudden change in the balanced load of a generator running at rated speed and rated voltage, under given current and power-factor conditions, shall not cause a drop of voltage below 85 % or a rise above 120 % of the rated value. After the completion of transient processes, the generator voltage shall be restored within not more than 1,5 s with a deviation from the rated value being ±3 %. For emergency sets these values may be increased, respectively, to 5 s and ±4 % of the rated voltage.

Where no precise data are available on peak values of sudden load that may be connected additionally to the existing generator load, these may be taken equal to a load of 60 % of the rated current at a power factor of 0,4 or less, which is connected at idle speed and then disconnected. The speed in this case shall be within the range specified in 2.11.3, Part IX "Machinery".

10.6.2.3 For alternating-current generators the deviation from sine voltage shall not be more than 5 % of the harmonic component peak value.

10.7 DIRECT-CURRENT GENERATORS

10.7.1 General.

10.7.1.1 Compound-wound and shunt-wound direct-current generators shall be equipped with automatic voltage regulation systems.

10.7.1.2 Protection of direct-current generators shall comply with the requirements of 8.2.

10.7.2 Voltage regulations.

10.7.2.1 Voltage regulators of direct-current compound-wound generators shall enable reduction of no-load voltage, with the generator cold, by not less than 10 % below the rated generator voltage, taking into account the increased revolutions of the prime mover running at no load.

10.7.2.2 Manual voltage regulators shall be so designed that the voltage increases when their controls are rotated clockwise.

10.7.2.3 Voltage regulators of direct-current shunt-wound generators shall be so designed that, when the field current is removed, the field winding shall be closed to the discharge circuit.

10.7.2.4 Direct-current compound-wound generators shall have independent devices for voltage regulation within a tolerance of ±1 % for generators rated at up to 100 kW, or within ±0,5 % for generators of rating exceeding 100 kW. The above regulation limits shall be maintained with the generator cold and hot and at any load within the operating load range of generators.

10.7.2.5 Direct-current sets comprising compound-wound generators shall have such external characteristics that the voltage of a hot generator adjusted to the rated value with an accuracy of ±1 % at 20 % of the load does not vary at full load by more than ±1,5 % for generators rated at 50 kW or over, and by more than ±2,5 % for generators of lower output.

Voltage variations in a compound-wound gene-rator running at 20 to 100 % of the rated load shall not exceed the following limits:

.1 ±3 % for generators rated at 50 kW and more;

.2 ±4 % for generators rated over 15 kW but less than 50 kW;

.3 ±5 % for generators rated at 15 kW and less.

10.7.2.6 Direct-current sets comprising shunt-wound generators shall have such external generator characteristics and automatic voltage regulators that voltage is maintained to within ±2,5 % of the rated value at all load variations from zero to the rated load.

10.8 ELECTROMAGNETIC BRAKES

10.8.1 The brake shall operate when the brake operating coil becomes de-energized.
10.8.2 A 30 % voltage drop below the rated value shall not cause a hot brake to operate.
10.8.3 Electromagnetic brakes shall allow of manual release.
10.8.4 Electromagnetic brakes shall be fitted with at least two pressure springs.
10.8.5 The shunt windings of a compound-wound electromagnetic brake shall be capable of holding off the brake even when no current flows through the series winding.
10.8.6 The shunt windings of electromagnetic brakes shall be so constructed or protected that they can be safe from damage at overvoltages such as occur when they are being disconnected (refer also to 5.4.3).

10.9 ASYNSHRONOUS ELECTRIC MOTORS SUPPLIED FROM FREQUENCY CONVERTERS

10.9.1 Asynchronous electric motors supplied from frequency converters shall have output reserve in order to prevent overheat caused by the voltage curve harmonic distortion.

10.9.2 Stator winding of asynchronous electric motors less than 100 kW supplied from frequency converters shall be two-layer winding or single layer with equal length of conductors with F- or H-class reinforced insulation.

10.9.3 In order to reduce overvoltage in stator winding of asynchronous motors supplied from frequency converters with the pulse-width modulation (PWM) it is necessary to:

.1 apply star phase splicing of stator winding;

.2 optimum selection of impedance of the electric motor stator winding and cable between electric motor and frequency convertor;

.3 use control algorithm for frequency convertor limiting minimum pulse duration and pause between impulses.

11 TRANSFORMERS

11.1 GENERAL

11.1.1 The requirements of the Section apply to transformers listed in 3.3.
For additional requirements for transformers with voltages over 1000 V, refer to 18.4.
11.1.2 Dry-type transformers shall be used in ships.
11.1.3 Transformers shall have electrically separated windings for primary and secondary voltages.

11.2 OVERLOAD, VOLTAGE VARIATION AND OPERATION IN PARALLEL

11.2.1 Transformers shall be so designed as to be capable of withstanding 10 % overload for 1 h and 50 % overload for 5 min.

11.2.2 For single-phase and three-phase transformers used to supply the ship's mains, voltage variation at an active load between zero and rated load shall not exceed 5 % for transformers rated at up to 6,3 kVA per phase and 2,5 % for transformers of higher rating.

11.2.3 Transformers intended to operate in parallel shall have their winding connections grouped together, their transformation ratios shall be the same, and their short circuit voltages shall be such that the load on any transformer does not depart from the corresponding proportional part of power output of each transformer by more than 10 % of the rated current for a given transformer.

11.2.4 Nominal capacities of transformers for parallel work shall not differ from each other more than twice.

12 POWER SEMICONDUCTOR UNITS

12.1 GENERAL

12.1.1 In power semiconductor units use shall be made of semiconductor elements of silicone type.

12.1.2 To prevent condensation in semiconductor units having the dissipation power above 500 W, provision shall be made for heating so that their temperature is at least by 3 °C higher than that of the ambient air.

12.1.3 Power semiconductor units shall be provided with air cooling (natural or artificial).

12.1.4 For power semiconductor units with forced cooling, provision shall be made for the protection reducing or disconnecting the load in case of inadequate cooling.

The activation of protection shall be preceded by the activation of light and sound alarms for exceeding the maximum permissible temperature of cooling medium at the system outlet.

12.2 PERMISSIBLE PARAMETERS OF VOLTAGE DISTORTION

12.2.1 The total harmonic distortion in the ship mains depending upon the operation of the power semiconductor units shall not exceed the values specified in 2.2.1.3.

The voltage curve harmonic distortion factor shall be determined by the formula given in 2.2.1.3.

12.2.2 The factor of maximum relative deviation of instantaneous voltage value from the first harmonic component shall not exceed 30 %.

Factor K_{MD} shall be determined by the formula

$$K_{MD} = \frac{U_m - U_{1m}}{U_{1m}} \cdot 100\ \%, \tag{12.2.2}$$

where U_m = peak value of the ship mains voltage;
U_{1m} = peak value of the first harmonic component.

12.3 CONTROL AND SIGNALLING SYSTEMS

12.3.1 Semiconductor arrangements shall be provided with light signals for connection or disconnection of power circuits and control circuits.

12.3.2 The power section of semiconductor arrangements shall be electrically insulated from the control system.

12.3.3 The long-term current deviation in the parallel branches of semiconductor arrangements shall not exceed 10 % of average current value.

12.3.4 The operation of semiconductor arrangements shall not be hampered by the failure of particular gates. Where the load upon particular gates exceeds permissible values, it shall be reduced automatically.

When a gate fails, light and sound signals shall be activated.

12.4 MEASURING INSTRUMENTS

12.4.1 Semiconductor arrangements shall be fitted up with measuring instruments in accordance with their purpose.

12.4.2 In the scales of measuring instruments of semiconductor arrangements, maximum permissible parameter values shall be marked off. Where forced cooling is applied, the maximum permissible temperature shall be marked off clearly in the scale of the instrument for measuring the cooling air temperature.

13 ACCUMULATOR BATTERIES

13.1 GENERAL

13.1.1 Accumulator batteries shall be so constructed that the loss of capacity of a fully charged battery due to self-discharge after 28 days out of operation at a temperature of (25±5) °C does not exceed 30 % of rated capacity for acid batteries and 25 % for alkaline batteries.

13.1.2 Battery containers and closures for holes shall be so constructed and secured as to prevent spilling or splashing of the electrolyte when the container is inclined on any side to an angle of 40° from the vertical.

Closures shall be made from durable material resistant to electrolyte. Closure design shall be such as to avoid building up of excess gas pressure inside the battery.

13.1.3 The mastics used shall not change their properties or deteriorate at ambient temperature changes within –30 to +60 °C.

13.1.4 Materials used for fabrication of crates to house battery cells shall be resistant to electrolyte. Individual cells arranged within the crates shall be so secured that it is impossible for them to move relative to one another.

13.1.5 Where batteries are fitted for use for essential and emergency services a schedule of such batteries shall be compiled and maintained. The schedule, which shall be reviewed by the Register, shall include the following information regarding the battery:

type and manufacturer;
voltage and capacity;
location;
equipment and systems served;
maintenance/replacement cycle dates;
date of last maintenance or replacement;
for replacement batteries in storage, the date of permissible shelf life.

Details of the schedule shall be included in the ship's safety management system specified in Chapter IX of SOLAS 74.

13.1.6 Where batteries are replaced, they shall be of an equivalent performance type, which shall be reflected in appropriate instructions.

13.1.7 Where vented type battery shall replace sealed battery at its location, the requirements of the Rules relevant to the location and ventilation of the batteries shall be met.

13.2 ARRANGEMENT OF ACCUMULATOR BATTERIES

13.2.1 Batteries having a voltage in excess of the safety voltage, as well as batteries having a capacity over 2 kW computed from the maximum charging current and the rated voltage, shall be located in special battery compartments accessible from the deck, or in appropriate boxes installed on deck.

Batteries having a charge capacity of 0,2 kW up to 2 kW may be installed in boxes or cabinets located inside the ship's hull.

In ships with low-power electrical installation, except passenger ships, the above batteries may be installed in the machinery space in such a way that their upper section is at least above the margin line in case the ship is flooded.

Accumulator batteries intended for the electric starting of internal combustion engines except for emergency units may be installed in machinery spaces in special cabinets with sufficient ventilation.

Batteries having a charge capacity less than 0,2 kW and sealed batteries are allowed to be installed in any space, other than accommodation spaces, provided they are protected from the action of water and mechanical damage and do not harmfully affect the surrounding equipment.

13.2.2 The acid and alkaline batteries shall not be placed in one compartment or in one box. The vessels and instruments intended for the batteries with different electrolytes shall be placed separately.

13.2.3 The inside part of a battery compartment or cabinet, as well as all structural parts, which may be subjected to harmful effects of electrolyte or gas, shall be suitably protected.

13.2.4 Accumulator batteries and individual cells shall be properly fixed in position. In case they are installed on shelves in two or more rows, all the shelves shall have a clearance of at least 50 mm on the face and back side for air circulation, and the distance from the deck to the plugs in the upper row of cells shall not exceed 1500 mm.

13.2.5 Air circulation gaps shall be provided between accumulator batteries or separate elements. Such gaps shall be at least 15 mm or shall comply with the values specified in the technical documentation on accumulator batteries or elements.

13.2.6 Warning notices indicating the danger of explosion shall be provided on the doors leading to the battery compartment or nearby, as well as on the boxes containing the accumulators.

13.3 HEATING

13.3.1 The battery compartments and boxes wherein temperature in operation may fall down below +5 °C shall be heated. The heating is allowed to be effected by the heat produced in adjacent spaces, by water or steam generators installed inside the battery rooms, as well as by safe type electrical heating appliances with protection level in accordance with 2.9.3.3.

13.3.2 The heating system valves shall be located outside the battery compartments.

13.3.3 The shipboard air conditioning system shall not be used for heating the battery compartments.

13.4 VENTILATION

13.4.1 The battery compartments and boxes, except for unattended batteries not releasing gases during operation, shall have sufficient ventilation that will prevent accumulation of explosive air-gas mixture.

The ventilation system shall meet the requirements of 12.10, Part VIII "Systems and Piping".

13.4.2 The battery compartments equipped with mechanical ventilation shall be provided with devices that will prevent charging of accumulator batteries before ventilation has been switched on.

Charging cycle shall be automatically discontinued, shall the ventilators stop.

13.5 CHARGING OF ACCUMULATOR BATTERIES

13.5.1 Provision shall be made for charging facilities to charge the accumulator batteries of essential services within 8 h.

In case an additional battery is used substituting that being charged, the charging time may exceed 8 h.

13.5.2 The charging facilities shall have means for measuring the voltage across battery terminals and charging current, as well as discharging current for emergency sources of electrical power.

13.5.3 In ships equipped with portable accumulator-fed lanterns or with spare accumulator-fed navigation lanterns the facilities shall be provided for charging the accumulators of these lanterns.

13.6 INSTALLATION OF ELECTRICAL EQUIPMENT IN BATTERY COMPARTMENTS

13.6.1 Apart from safe type lighting fixtures, heating appliances and automatic detectors of fire detection system, as well as cables led to accumulators, lighting fixtures, heating appliances and automatic detectors of fire detection system, no other electrical equipment shall be installed in battery compartments.

Cables led to accumulator batteries, lighting fixtures, heating appliances and automatic detectors of fire detection system may run openly, provided they have metal armour or braid covered with non-metal sheath and this metal armour or braid is reliably earthed at both ends.

13.7 ELECTRICAL STARTERS FOR INTERNAL COMBUSTION ENGINES

13.7.1 Number of starter accumulator batteries.

13.7.1.1 In a ship equipped with electrically-started internal combustion engines, irrespective of the number of such engines, not less than two starter batteries shall be permanently installed for starting each of the main and auxiliary engines, or not less than two common batteries for starting all the engines. Moreover, provision shall be made for a permanent switching system that will ensure possible use of any battery for starting any of the engines in the group serviced by this battery. In this case parallel connection of the batteries is not allowed.

13.7.1.2 For ships of restricted area of navigation **R3** and also for ships of restricted area of navigation **R2** with the electrical installation of low power (other than passenger ships), it is permitted to have only one starter accumulator battery, provided that it may be used for starting all the engines.

13.7.2 Battery characteristics.

13.7.2.1 Each starter battery shall be designed to withstand the discharging current in starter duty that will correspond to the maximum current through the most powerful starting electric motor.

13.7.2.2 Capacity of each battery shall be sufficient for six starts of the engine in the ready-for- start condition, or in case of two or more engines, for not less than three starts of each engine. Total capacity of the batteries for starting main engines shall provide the required number of starts during 30 min.

13.7.2.3 In computing battery capacity, the duration of each start shall be considered not less than 5 s.

13.7.3 Charging facilities.

13.7.3.1 A starter battery charging facility shall be supplied by a separate feeder from the main switchboard even if the battery is charged from the appurtenant generator.

13.7.3.2 For ships of restricted area of navigation **R3** and also for ships of restricted area of navigation **R2** with the electrical installation of low power (other than passenger ships) the starter battery may be charged only from the appurtenant generator.

14 ELECTRICAL APPARATUS AND ACCESSORIES

14.1 ELECTRICAL APPARATUS

14.1.1 General.

14.1.1.1 The design of switchgear with renewable contacts shall be such that renewal of contacts shall be possible by means of standard tools, without dismantling the switchgear or its basic components.

14.1.1.2 All switches, circuit breakers and isolating switches, except those for cabins, shall be provided with mechanical or electrical contact-making position indicators located where the apparatus is actuated by the operator.

14.1.1.3 The positions of controller and master controller drums shall be rigidly locked by mechanical means, location in zero position being more rigid than elsewhere.

Controller and master-controlled drums shall be fitted with a scale and an indicator of position.

14.1.1.4 Machine control gear, except such as is used for smooth regulation, shall be so constructed that the end and intermediate fixed positions are easy to feel at various control stages while movement beyond the end positions shall be impossible.

14.1.2 Electrical switch apparatus and protective devices.

14.1.2.1 For the purposes of this Chapter, the terms Ics, Icu, Icw, Icm, etc. applicable to the switch apparatus comply with IEC 60947-2.

14.1.2.2 Electrical switch apparatus shall comply at least with the national standards and shall be so selected that:

under normal operation mode their rated voltages, currents and permissible temperatures are not exceeded;

they are capable of withstanding, without damage and heating above the limiting temperature, the prescribed overloads as specified for transient modes;

their characteristics under short-circuit current mode correspond to the prospective short-circuit current values at the outputs (terminals) of each switch apparatus at the design value of the power factor.

14.1.2.3 The nominal breaking capacity (Icn) of electrical switch apparatus designed to break short circuit currents shall be not less than:

maximum actual value of the periodic component of the prospective short-circuit current at the first half-cycle (Iac) for alternating current;

the prospective short-circuit current at the specified time constant of the direct current apparatus at the place of their installation at disconnection.

14.1.2.4 The nominal making capacity (I_{cm}) of electric switch apparatus, which may be incorporated in a shorted electric circuit, shall be not less than the peak prospective short-circuit current (I_p) at the place of their installation.

14.1.2.5 The electrodynamic strength current of electric switch apparatus not intended for interrupting short-circuit currents shall be not less than the peak prospective short-circuit current at the place of their installation.

14.1.2.6 Thermal strength of electric switch apparatus under short-circuit condition shall be consistent with the thermal action of periodic component of the prospective sort-circuit current (root-mean square (r.m.s.)) (I_{ac}) at the place of their installation during short-circuit specified by the selective action of protective devices.

N o t e . Thermal strength of electric switch apparatus is determined as the product of squared r.m.s. value of the periodic component prospective short-circuit current, kA, by the time, s, $I^2 \times t$ and shall be indicated in its technical specifications.

14.1.2.7 Rated short-time withstand current (Icw) for electric switch apparatus in circuits with selective action of protective devices shall be not less than the maximum r.m.s. periodic component of the prospective short circuit current at the first half-cycle ($Icw > Iac$).

14.1.2.8 The use of a circuit-breaker with inadequate rated service ultimate breaking capacity (I_{cs}) and rated ultimate making capacity (I_{cm}) corresponding to the prospective short-circuit current at the place of its installation is allowed, provided it is protected on the generator side by means of fuses and/or a circuitbreaker with at least necessary ratings for short-circuit currents, which is not used as a generator automatic switching device.

Such protective devices having only rated ultimate breaking capacity (I_{cu}) shall not be installed on the main and emergency switchboards and shall not be applied in the circuits of essential and emergency consumers. Their characteristics shall be such that:

.1 while breaking the maximum prospective short-circuit current, the circuit breaker on the load side be not damages to become unfit for further service;

.2 switching the circuit breaker on the prospective maximum current does not result in damage to the remaining part of the electrical installation; while it is allowed for the circuit breaker on the load side not to be immediately fit for further operation.

14.1.2.9 In electric circuits with a rated load current in excess of 320 A circuit breakers shall be fitted for overload protection. The use of circuit breakers is recommended at the current exceeding 200 A.

14.1.2.10 In direct current compound generator circuits where the generators are intended for parallel operation, circuit breakers shall have a pole for a common-wire mated mechanically with the other poles of the circuit breaker to switch it on before the other poles are connected to busbars and to switch it off after their disconnection.

14.1.3 Manually operated controls.

14.1.3.1 The direction of movement of manually operated controls of switchgear or machine control gear shall be such that clockwise rotation of a handle (lever) corresponds to closing of an apparatus, start-up of a motor, increased speed, increased voltage, and so forth.

Where lifting or lowering mechanisms are under control, clockwise rotation of a handle (handwheel) or shifting of a handle (lever) toward the operator shall correspond to lifting movement, and counterclockwise rotation or shifting away from the operator to lowering movement.

14.1.3.2 Switchgear push buttons shall be so designed that they cannot be actuated accidentally.

14.1.4 Motor-operated gear.

14.1.4.1 Actuators of switches and circuit breakers shall be so designed that in the event of loss of supply to the actuating motor the switch or circuit breaker contacts remain in closed or in open position only.

14.1.4.2 Electric motor actuators shall provide for reliable closing of the apparatus at all changes of the control voltage within 85 to 110 % of the rated value and in case of alternating current at frequency deviation (frequency range for an electrical power plant with variable frequency main power source) within ±5 % of the rated frequency.

14.1.4.3 A drop of control voltage down to 70 % of the rated value shall not result in opening the apparatus contacts, or reducing the pressure thereof.

14.1.4.4 The design of a motor-actuated switchgear shall embody a provision for manual operation.

14.1.5 Coils.

14.1.5.1 A conductor or a shoe shall be attached to a coil winding so as to avoid the mechanical stresses of the connection affecting the coil turns. The tapping of voltage coils shall be made from flexible stranded conductor, except where the contact terminals are secured directly to the coil frame.

14.1.5.2 The coils of electromagnetic apparatus shall bear notations giving particulars of their characteristics.

14.1.6 Resistor elements.

14.1.6.1 Resistor elements shall be easily replaceable, in sections or in total.

14.1.6.2 Resistors shall be so disposed and ventilated that they do not heat other devices beyond the permissible limits.

14.1.6.3 The joints between resistor elements or between these and terminals shall be effected by welding or by mechanical press-fitting where there is no need to provide for their dismantling. Soldering is admissible where there is no risk of temperature rise at the point of junction above the limits specified for the solder.

14.1.7 Fuses.

Fuse link housing shall be of totally enclosed type and allow no arc ejection to the outside, or sparking, or any other harmful effect upon the adjacent parts in case the fuse blows.

14.2 ELECTRICAL ACCESSORIES

14.2.1 General.

14.2.1.1 The enclosures of accessories and fittings shall be constructed from materials of adequate mechanical strength, which are corrosion-resistant or adequately protected from corrosion and at least flame-retardant. The enclosures of accessories and fittings designed for installation on weather decks, in refrigerated cargo spaces, fish processing shops, or other humid areas shall be made of brass, bronze, or equivalent alloy, or from plastics of suitable quality. If steel or aluminium alloys are used, anti-corrosive protection shall be provided.

It is inadvisable to use threaded connections or tight-fit mating of parts in accessories and fittings made of aluminium alloys.

14.2.1.2 Insulating parts, to which current-carrying components are fixed, shall be made of materials that do not evolve gases as would ignite from an electric spark at a temperature up to and including 500 °C.

14.2.1.3 The lighting fixtures designed to be mounted on or close to combustible materials shall be so constructed as not to get heated over 90 °C.

14.2.2 Lampholders.

14.2.2.1 The design of lampholders fitted with screw caps shall be such as to effectively prevent the lamps from getting loose in service.

14.2.2.2 No switches are allowed to be fitted in lampholders.

14.2.2.3 Each lighting lampholder shall be marked to indicate rated voltage and allowable current or load.

14.2.3 Plug and socket connector.

14.2.3.1 The pin jacks of socket outlets shall be so constructed as to ensure permanent pressure in contact with the plug pins.

14.2.3.2 Plugs with slotted pins are not allowed for use. The pins of plugs designed for currents in excess of 10 A shall be cylindrically shaped, solid or hollow.

14.2.3.3 Socket outlets and plugs for voltages exceeding the safety level shall have contacts for connecting the earth continuity conductors of the incoming cables from current consumers.

14.2.3.4 Socket outlets having protective enclosures shall be so constructed that the required degree of protection is ensured regardless of whether the plug is in or out of the socket outlet.

14.2.3.5 Socket outlets rated at over 16 A shall be provided with built-in switches. Provision shall be also made for interlocking such socket outlets to prevent the possibility of the plug being inserted or withdrawn when the socket switch is in the "closed" position.

14.2.3.6 Where socket outlets are not interlocked, the clearance between contacts in air or across the insulation surface shall be such that no short circuit is possible due to arcing over when the plug is withdrawn while carrying a load 50 % above the rated current at rated voltage.

14.2.3.7 Socket outlets and plugs shall be so designed that it is not possible to insert only one live contact pin into the socket outlet, or insert a live contact pin into the earthing contact. Besides, the design of the outlets intended for connecting the motors (gears), the direction of rotation (operation) of which depends on the change of the sequence of phases or poles connected, shall exclude the possibility of the sequence change. When the plug is inserted into the socket outlet, the earthing part of the plug shall make contact with the earthing part of the socket outlet before connecting the live pins.

14.2.3.8 In socket outlets, plugs and branched pin jacks, no fuses shall be fitted.

15 ELECTRICAL COOKING AND HEATING APPLIANCES

15.1 GENERAL

15.1.1 Only stationary-type electrical cooking and heating appliances are permitted for use.

15.1.2 Electrical cooking and heating appliances shall be supplied from the main switchboard or from distribution boards intended for this purpose.

15.1.3 The supporting structural parts of electrical cooking and heating appliances, as well as the internal surfaces of enclosures, shall be fabricated entirely from non-combustible materials.

15.1.4 In heated condition, permissible loss current shall not exceed 1 mA per 1 kW of rated power for a separately connected heating element or 10 mA for the appliance as a whole.

15.1.5 Electric cooking and heating appliances shall be so designed that the temperature of their components, which shall be handled by the personnel or which can be touched inadvertently, does not exceed the value indicated in Table 15.1.5.

Table 15.1.5

Nos	Item	Permissible temperatures, °C
1	Control handles and other parts to be handled during long periods of time	
	Metallic	55
	Non-metallic	65
2	Same, but where short-time contact is possible:	
	metallic	60
	non-metallic	70
3	Enclosures of electric space heating and cooking appliances at ambient temperature of 20 °C	80
4	Air coming out from electric space heating appliances into heated spaces	110

15.2 HEATING APPLIANCES

15.2.1 Electric heating appliances intended for space heating shall be of stationary type. These appliances shall be provided with devices for disconnection of the supply source when the temperature rise of the enclosure exceeds the permissible limit.

15.2.2 If built-in disconnecting devices are not provided in the heating and cooking appliances, such devices shall be installed in the rooms wherein these appliances are located.

Switches shall disconnect power supply at all poles or phases.

15.2.3 The enclosures of electric heating appliances shall be so constructed as to prevent the possibility of any objects being placed upon them.

15.2.4 Stationary heating appliances rated at 380 V and upwards and admitted for use in accordance with Table 4.2.3 shall be protected against access to live parts, except with the aid of special tools. The enclosures shall bear notices giving the voltage value.

15.2.5 Electric cooking appliances forming part of galley equipment shall be so constructed as to avoid the possibility of cooking utensils being brought into contact with live parts, and to prevent short circuits or damage to insulation due to liquid spilling or leakage.

15.2.6 Sauna shall be fitted with the temperature limiter, which shall cut off the electrical heater from the mains (at that, electrical heater control circuits shall also be de-energized), if the temperature in the area of 0,3 m from the ceiling exceeds 140 °C. In this area the electrical heater control devices (thermostats and temperature limiters) and associated cables withstanding a temperature not less than 170 °C may only be installed.

Electrical sauna heaters shall comply with the requirements of 2.1.5.1, Part VI "Fire Protection".

15.3 OIL, FUEL AND WATER HEATERS

15.3.1 In addition to the requirements of the Chapter, heaters shall meet the requirements of Section 6, Part X "Boilers, Heat Exchangers and Pressure Vessels".

15.3.2 Oil and fuel having a flash point above 60 °C may be heated by means of electric heaters, provided the requirements of 15.3.3 and 15.3.4 are fulfilled.

15.3.3 Electric heaters for pipelines shall be equipped with devices for temperature control, light signals for indication of operating conditions and also with light and sound signals for indication of fault conditions and inadmissible temperature rise.

15.3.4 Electric heaters for oil and fuel heating in tanks shall be equipped with devices for temperature control of the heated medium, low level indicators and manually disengaged devices for disconnection of power supply to the heaters in case of malfunction of devices for temperature control and if the upper temperature limit of the medium heated or the lowest permissible level are exceeded. An alarm system shall be provided in control posts of the heaters when means for disconnection of power supply to the heaters are activated.

15.3.5 To ensure protection against the heated medium ignition in case of malfunction of devices for temperature control the following shall be fulfilled:

.1 irrespective of device for temperature control, a means for disconnection of power supply to the heaters shall be provided that is activated at the temperature reaching the value of at least 15 °C lower than the flash point of the heated medium; or

.2 if programmable logic controller (PLC) is used in devices for temperature control of the heated medium, a means for disconnection of power supply to the heaters shall be provided that is activated in case of malfunction detected in devices for temperature control, such as: failure in temperature sensor, failure in communication line between temperature sensor and the controller, PLC power supply system failure or PLC failure.

For self-regulating heaters protection may be omitted.

15.4 SYSTEMS UTILISING HEATING CABLES

15.4.1 Systems utilising heating cables for removing ice and avoiding icing shall be provided for ship's arrangements, equipment and spaces intended for:
performing by the ship its purpose (descriptive notation in the class notation);
maintaining manoeuvrability;
maintaining stability;
safety of crew (rafts, boats, ladders, guard rails, etc.).
15.4.2 Heating capacity of such systems shall not be less than:
300 W/m^2 for the spaces of open decks, helidecks, ladders and gangways;
200 W/m^2 for superstructures;
50 W/m for guard rails with internal heating.
Lower values of heating capacity may be selected when confirmed as sufficient by calculations performed in compliance with IEC 62395-2:2013 or equivalent national standards.
15.4.3 In the systems utilising electrical heating cables, particular attention shall be paid upon the heat transfer between the cable and the equipment (space) to be heated to provide efficient heating.
15.4.4 The switchboard for the said systems shall be equipped with:
wattmeter or amperemeter to indicate the total load;
name plate indicating the rated load of each circuit and the switchboard as a whole;
residual-current device for each circuit;
load signal lamps for each circuit.
15.4.5 The heating cables shall be protected against overload exceeding 125 % of the rated current of the circuit. For cables of self-regulating type the overload protection may be omitted.
15.4.6 The use of heating cables for heating of pipelines carrying combustible media, as well as for pipelines and valves located in dangerous rooms and spaces, is only allowed when fitted with the appropriate type of explosion protection proved by a competent body certificate.

16 CABLES AND WIRES

16.1 GENERAL

16.1.1 The requirements of this Section do not apply to power cables designed for voltages above 1000 V.

16.1.2 Radio frequency, telephone cables and other special purpose cables of radio and navigational equipment are covered by the requirements of 16.8.4 — 16.8.8.

16.2 CABLE CONDUCTORS

16.2.1 Cables intended for supplying essential services shall have stranded conductors (refer also to 16.8.1.2). Table 16.2.1 specifies the minimum number of wires per conductor.

Table 16.2.1

Nominal cross-sectional area of conductor, mm^2	Minimum number of wires per conductor	
	circular non-tightened conductors	tightened sector and circular conductors
0,5 to 6	7	–
10 to 16	7	6
25 to 35	19	6
50 to 70	19	15
95	37	15
120 to 185	37	30
240 to 300	61	30
Note. The ratio between nominal diameters of any two wires in the mechanically tightened cable conductor shall not exceed 1:1,3, and for conductors formed geometrically, but not tightened, 1:1,8.		

16.2.2 Connections of separate wires of the conductor shall be displaced from one another by not less than 500 mm along the length of the conductor.

Such connections shall not impair the mechanical and electrical properties of the wire nor change the cross-sectional area of wires or the conductor as a whole.

16.2.3 Separate wires of rubber-insulated copper conductors shall be tinned or coated with suitable alloys.

Tinning or other anticorrosive coating of external stranding or of all wires of a rubber-insulated core may be dispensed with, if the manufacturer takes steps to guarantee that the rubber insulation does not affect adversely the metal of the conductor.

No tinning is required for conductors provided with other types of insulation.

16.3 INSULATING MATERIALS

16.3.1 For conductors of cables and wires, insulating materials specified in Table 16.3.1 may be used.

Table 16.3.1

Type of insulating compound	Abbreviated designation	Maximum rated temperature during normal operation, °C[1]
Thermoplastic		
Polyvinyl chloride or copolymer of vinyl chloride and vinyl acetate	PVC	70
Elastomeric or thermoset		
Ethylene-propylene rubber or similar (EPM or EPDM)	EPR	90
Hard grade ethylene prorylene rubber	HEPR	90
Cross-linked polyethylene	XLPE	90
Silicon rubber	S 95	95
Ethylene-propylene rubber or similar (EPM or EPDM) halogen-free	HF EPR	90
Hard grade halogen-free ethylene propylene rubber	HF HEPR	90
Halogen-free cross-linked polyetylene	HF XLPE	90
Halogen-free silicon rubber	HF S 95	95
Halogen-free cross-linked polyolefin	HF 90	90
[1] Wire temperature for calculating the permissible continuous load of cable.		

16.4 CABLE SHEATHING

16.4.1 Protective sheathing of cables and wires may be manufactured of non-metallic materials as specified in Table 16.4.1, lead, copper.

Table 16.4.1

Type of non-metallic solid sheathing compound	Abbreviated designation	Temperature limit of the cable, °C
Thermoplastic		
Polyvinyl chloride or copolymer of vinylchloride and vinyl-acetate	ST 1 ST 2	60 85
Halogen-free	SHF 1	85
Elastomeric or thermoset		
Polychloroprene rubber	SE 1	85
Chlorsulphonated polyethylene or chlorinated polyethylene rubber	SH	85
Halogen-free	SHF 2	85

16.4.2 Sheathing shall be of uniform thickness within allowable limits, throughout the manufacturing length of cable, and shall envelope the cable cores concentrically. The sheaths shall form an impervious covering in tight contact with the protected cores.

16.4.3 Lead cable sheaths shall be made of appropriate alloys specified by the national standards.

Pure lead sheaths may only be used when the lead sheath is covered with an additional protective envelope.

16.5 PROTECTIVE COVERINGS

16.5.1 Metal shielding braid shall be made of tinned copper wire or polymer-coated aluminium strip with drainage tinned copper wire. If plain copper wire is used, it shall be protected by suitable sheath. Non-shielding braids may be made of galvanized steel wires. The braid shall be uniform and its density shall be such that its mass is at least equal to 90 % of the mass of tube of equal diameter made of the same material and with a wall thickness equal to the braiding wire diameter.

16.5.2 Metal armour shall be made of annealed and galvanized steel wire or tape, wound helically, with a suitable pitch, over the cable sheath or an intermediate bedding over the sheath in such a way that a continuous cylindrical layer is formed to assure adequate protection and flexibility of the finished cable. On special demand, the armour may be made of non-magnetic metals, using the techniques described above.

16.5.3 Cable armour or braid made of steel tape or wire shall be effectively protected against corrosion.

16.5.4 Armour bedding shall be made of moisture-resistant materials.

16.6 MARKING

16.6.1 Rubber- or polyvinylchloride-insulated cables having a limiting temperature at core 60 °C shall be marked in such a manner as would enable their identification.

16.6.2 Cable cores shall be marked in such a manner as to assure adequate preservation of the markings.

In multi-core cables with cores arranged in several concentric layers at least two adjacent cores in each layer shall be marked with different colours.

16.6.3 Cables of fire resistant type shall be clearly marked.

16.7 HOOKUP WIRES

16.7.1 For internal wiring of distribution boards and electric devices, single-wire insulated conductors may be used (refer also to Table 16.3.1).

16.7.2 Non-insulated wires and busbars are permitted for use only for internal wiring of electrical devices. The external wiring with non-insulated wires or busbars is not allowed unless they are reliably guarded.

16.8 CABLING

16.8.1 General.

16.8.1.1 Use shall be made of flame-retarding or non-combustible cables and conductors with copper cores manufactured and tested in compliance with this Part of the Rules, national standards, as well as with the relevant requirements of IEC 60092-350:2020, 60092-352:2005, 60092-353:2016, 60092-354:2020, 60092-360:2014, 60092-370:2019, 60092-376:2017. Cables shall be tested for flame-retarding properties in compliance with the requirements of IEC: 60332-1-2:2004+AMD:2015 and 60332-3-22:2018.

Cables manufactured and tested in compliance with the standards other than those specified above shall be accepted provided they are in compliance with international or national standards and are of an equivalent or higher safety level than those.

Use of flexible or optical fibre cables used for special purposes may be allowed provided they are manufactured and tested according to the approved standards.

In this case, IEC 60331-23 for data transfer cables and IEC 60331-25 for optical fibre cables may be used.

As far as the fire resistance testing of cables is concerned, use shall be made of IEC 60331-1 for cables with outside diameter more than 20 mm and IEC 60331-21 or 60331-2 for other cables.

16.8.1.2 Cables and wires having stranded conductors shall be used, the cross-sectional area of the conductors being not less than:

.1 1,0 mm^2 for power, control and signalling circuits of essential services and for power circuits of other services;

.2 0,75 mm^2 for control and signalling circuits;

.3 0,5 mm^2 with the number of cores in the cable not less than four for instrumentation and internal communication circuits.

For power circuits supplying non-essential services, the use is permitted of cables with single-wire conductors having a cross-sectional area of 1,5 mm^2 and less.

In data transfer circuits high-frequency cables may be used with the core diameter of 0,4 — 0,8 mm considering mechanical strength of such cables in compliance with IEC 60092-370.

16.8.1.3 In circuits with heavy inductive and capacitive loads, the use shall be made of cables designed for working voltages approximately equal to twice the rated voltage of the circuit.

16.8.1.4 Maximum permissible temperature for the insulating material of the cable cores or wires shall be at least 10 °C higher than the maximum specified ambient temperature.

16.8.1.5 In locations affected by the action of petroleum products or other aggressive medium, the use shall be made of cables having a sheath resistant to such medium. Cables not having such properties may be installed in such locations only fitted in metallic pipes (refer to 16.8.8).

16.8.1.6 In locations where cables may be subjected to mechanical damage, the use shall be made of cables having an appropriate armour, while other types of cables in such locations shall be protected with special reliable covers or shall be installed in metallic pipes (refer to 16.8.8).

16.8.1.7 Cables supplying the electric drives of the sprinkler system and of the fire pump from the emergency source of electrical power and running through casings of machinery spaces of category A, galleys, drying rooms and other similar fire-hazardous spaces, shall be of fire-resisting type or protected from the action of flame.

The above requirements cover the remote-control cables of those devices as well.

16.8.1.8 Cables for services required for operations under fire conditions, including cables for their power supply (refer to 16.8.1.11) shall be routed clear of high fire risk spaces (refer to 16.8.1.9), and in addition to passenger ships, main vertical fire zones, except for cases, when the services themselves are installed in such spaces.

Where such installation of cables is necessary, the cables shall be of fire resistance type according to 16.8.1.1.

16.8.1.9 The high fire risk spaces include:

machinery spaces of category A;

spaces containing fuel treatment equipment and other highly flammable substances;

galleys and pantries containing cooking appliances;

laundries containing drying equipment;

accommodation spaces of high fire risk;

paint rooms, store rooms and similar spaces for storage of flammable liquids;

enclosed and semi-enclosed spaces requiring installation of safe-type electrical equipment.

16.8.1.10 Cables, distribution gear, switch apparatus and protective devices associated with these services shall be so designed or installed that the likelihood of the device failing in case of fire in any one such space or area is minimised.

16.8.1.11 Among the services required for operation under fire conditions are the following:

general alarm;

fire extinguishing systems;

fire detection and alarm systems;

warning alarm of fire extinguishing system release;

controls of fire doors with door-position indicators;

control of watertight doors with door-position indicators and warning alarm;

emergency lighting;

public address system;

low-location lighting;

remote emergency shutdown arrangements for systems, which operation may support the propagation of fire and/or explosion.

16.8.1.12 Use of fire resistant cables for devices listed in 16.8.1.11 is not mandatory provided that:

.1 fail safe functioning of devices is provided by, at least, two-loop or radial laying of cables spaced apart as far as practical so that if one loop or radial section fails, the rest sustain operability of the devices;

.2 the devices are provided with self-monitoring with such damages like a short circuit, an open-circuit fault, earth fault, or trouble-free functioning of these devices is ensured by duplicating cables laid in separate runs spaced apart as far as practical.

16.8.2 Choice of cables and wires for loads required.

16.8.2.1 Permissible continuous loads on single-core cables and wires with different insulation materials shall comply with the values specified in Table 16.8.2.1.

The current ratings given in the Table are applicable to the following cases of cable installation:

when installing not more than 6 cables in one bunch or in one row closely adhering to one another;

when installing cables in two rows, regardless of the number of cables in one row, on condition that a free space for air circulation is provided between each group or bunch of 6 cables.

When installing more than six cables in one bunch, which may be under rated current simultaneously or when no free space for air circulation between them is provided, the permissible current ratings for the given cross-sectional area shall be reduced by 15 % (factor 0,85).

16.8.2.2 Current ratings in amperes for cross-sectional areas given in Table 16.8.2.1 and also for any other cross-sectional areas shall be calculated from the formula

$$I = \alpha S^{0,625}, \tag{16.8.2.2}$$

where α = factor corresponding to the maximum permissible service temperature of the conductor obtained from Table 16.8.2.2;
S = nominal cross-sectional area of conductor.

Table 16.8.2.1

Current ratings in continuous service of single-core cables and wires with different insulation materials for ambient temperatures of +45 °C

Nominal cross-sectional area of conductor, mm²	Insulating material				
	Polyvinylchloride	Heat-resistant polyvinylchloride	Butyl rubber	Ethylene-propylene rubber of cross-linked polyethylene	Silicone rubber or mineral insulation
	Maximum permissible conductor operating temperature, °C				
	60	75	80	85	95
1	8	13	15	16	20
1,5	12	17	19	20	24
2,5	17	24	26	28	32
4	22	32	35	38	42
6	29	41	45	48	55
10	40	57	63	67	75
16	54	76	84	90	100
25	71	100	110	120	135
35	87	125	140	145	165
50	105	150	165	180	200
70	135	190	215	225	255
95	165	230	260	275	310
120	190	270	300	320	360
150	220	310	340	365	410
185	250	350	390	415	470
240	290	415	460	490	–
300	335	475	530	560	–

Table 16.8.2.2

Maximum permissible conductor operating temperature, °C	Factor α for nominal cross-sectional area *S*, mm²	
	≥2,5	<2,5
60	9,5	8
65	11	10
70	12	11,5
75	13,5	13
80	15	15
85	16	16
90	17	18
95	18	20

16.8.2.3 The permissible current ratings for double-, triple- and quadruple-core cables shall be determined by reducing the values given in Table 16.8.2.1 for the given cross-sectional area with the use of correction factors:

0,85 for double-core cables;

0,7 for triple- and quadruple-core cables.

16.8.2.4 The permissible current ratings for cables and wires in circuits of intermittent or shorttime service shall be determined by multiplying the current ratings for continuous service stated in Table 16.8.2.1 or chosen according to 16.8.2.2 by the correction factors given in Table 16.8.2.4.

16.8.2.5 The permissible current ratings given in Table 16.8.2.1 refer to the ambient temperature of +45 °C.

The correction factors for converting the permissible current ratings to be introduced depending on the ambient temperature are stated in Table 16.8.2.5.

Table 16.8.2.4

Correction factors for cables and wires with or without metal sheathing

Nominal crosssection of conductor, 2 mm²	Intermittent service, intermittence ratio, 40 %		Short-time service, 30 min		Short-time service, 60 min	
	Cable and wire					
	with metal sheathing	without metal sheathing	with metal sheathing	without metal sheathing	with metal sheathing	without metal sheathing
1	1,24	1,09	1,06	1,06	1,06	1,06
1,5	1,26	1,09	1,06	1,06	1,06	1,06
2,5	1,27	1,10	1,06	1,06	1,06	1,06
4	1,30	1,14	1,06	1,06	1,06	1,06
6	1,33	1,17	1,06	1,06	1,06	1,06
10	1,36	1,21	1,08	1,06	1,06	1,06
16	1,40	1,26	1,09	1,06	1,06	1,06
25	1,42	1,30	1,12	1,07	1,06	1,06
35	1,44	1,33	1,14	1,07	1,07	1,06
50	1,46	1,37	1,17	1,08	1,08	1,06
70	1,47	1,40	1,21	1,09	1,09	1,06
95	1,49	1,42	1,25	1,12	1,11	1,07
120	1,50	1,44	1,28	1,14	1,12	1,07
150	1,51	1,45	1,32	1,17	1,14	1,08
185	–	–	1,36	1,20	1,16	1,09
240	–	–	1,41	1,24	1,18	1,10
300	–	–	1,46	1,28	1,20	1,12

Table 16.8.2.5

Correction factors depending on ambient temperature

Maximum permissible conductor operating temperature, °C	Ambient temperature, °C										
	35	40	45	50	55	60	65	70	75	80	85
60	1,29	1,15	1,00	0,82	–	–	–	–	–	–	–
65	1,22	1,12	1,00	0,87	0,71	–	–	–	–	–	–
70	1,18	1,10	1,00	0,89	0,77	0,63	–	–	–	–	–
75	1,15	1,08	1,00	0.91	0,82	0,71	0,58	–	–	–	–
80	1,13	1,07	1,00	0,93	0,85	0,76	0,65	0,53	–	–	–
85	1,12	1,06	1,00	0,94	0,87	0,79	0,71	0,61	0,50	–	–
90	1,10	1,05	1,00	0,94	0,88	0,82	0,74	0,67	0,58	0,47	–
95	1,10	1,05	1,00	0,95	0,89	0,84	0,77	0,71	0,63	0,55	0,45

16.8.2.6 In choosing the cables for final branch circuits of lighting and cooking appliances correction factors or simultaneity factors are not applicable.

16.8.2.7 The cables shall be so designed that they could withstand maximum short-circuit current occurred in the circuit considering time and current ratings of the protective devices and peak value of the prospective short-circuit current of the first one-half period.

16.8.2.8 Cables installed in parallel and belonging to the same phase or pole shall be of the same type, be laid together and have the same cross-sectional area of at least 10 mm^2 and the same length.

16.8.3 Selection of cable cross-sectional areas for permissible voltage drop.

16.8.3.1 Voltage drop on the cable connecting the generators of the main switchboard or the emergency switchboard shall not exceed 1 %.

16.8.3.2 Voltage drop between busbars of the main or emergency switchboard and any points of the installation shall not exceed 6 % of the rated voltage under normal operating conditions; for consumers supplied from the accumulator battery with the rated voltage up to 50 V this value may be increased to 10 %.

For circuits of navigation lights, it may be required to limit the voltage drop by a lesser value in order to ensure necessary luminous intensity.

At short-term loads (e.g. when starting the electric motors) the greater voltage drop may be permitted if it does not cause disturbance of normal operation of the ship's electrical installation.

16.8.3.3 The cables used for feeding the directly-started alternating current electric motors shall be computed in such a manner that the voltage drop on motor terminals at starting is not over 25 % of the rated voltage.

16.8.4 Installation of cables.

16.8.4.1 Cables shall be installed in runs, which shall be, as far as possible, straight and accessible. The cable runs shall pass through locations where cables are not exposed to oil, fuel, water and excessive external heating.

Cable runs shall be installed not closer than 100 mm to sources of heat.

16.8.4.2 No cables shall be installed at a distance less than 50 mm from the double bottom and from the fuel and oil tanks.

Cable runs shall be installed at a distance not less than 20 mm from the shell plating, as well as from fireproof watertight and gastight bulkheads and decks.

16.8.4.3 For bunches of cables consisting of cable types, which have not been subjected to a bunch fire test, the following measures shall be taken during installation to limit the propagation of fire:

.1 fire-retarding divisions shall be used, B-0 class at least, (refer also to 2.1.2.5, Part VI "Fire Protection") where bunches enter the main and emergency switchboards, central control stations and consoles for the main propulsion plant and for important auxiliaries, as well as at each entry and exit point of cable runs in fully enclosed metal conduits (Fig. 16.8.4.3.1);

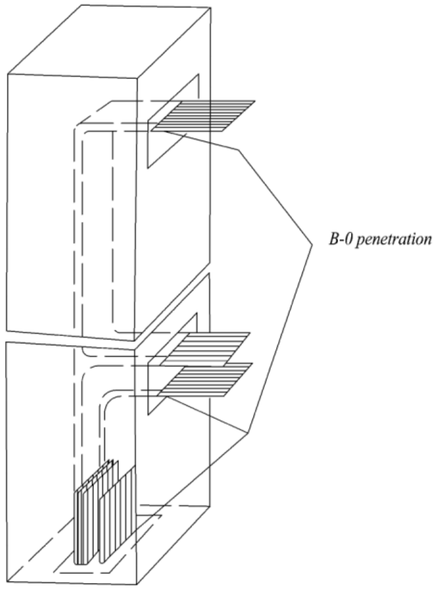

Fig. 16.8.4.3.1
Fully enclosed cable run protected with B-0 fire-retarding divisions

.2 in closed and semi-enclosed rooms and spaces, bunches installed in partly enclosed and open cable runs shall be protected by: flameproof coatings over the entire length of vertical cable runs and over a length of 1 m every 14 m apart on horizontal cable runs (Fig. 16.8.4.3.2-1); or

B-0 fire-retarding divisions at least at every second deck or every 6 mm apart for vertical cable runs and every 14 m apart for horizontal cable runs (Fig. 16.8.4.3.2-2). Fire-retarding divisions shall be made of steel plates at least 3 mm thick and having dimensions as shown in Fig. 16.8.4.3.2-2;

.3 bunches installed in cargo holds shall be protected by B-0 fire-retarding divisions at least at the entry and exit points of cable runs.

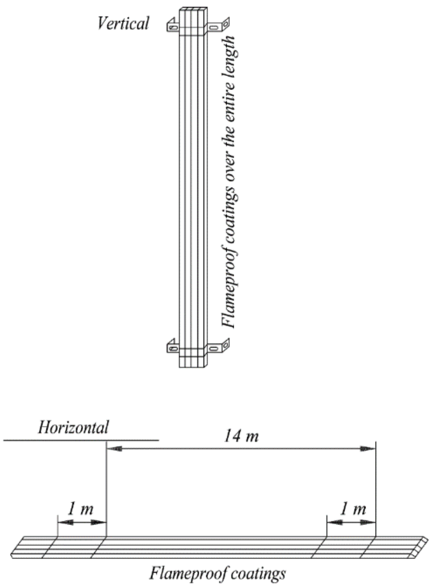

Fig.16.8.4.3.2-1
Cable runs protected with flameproof coatings

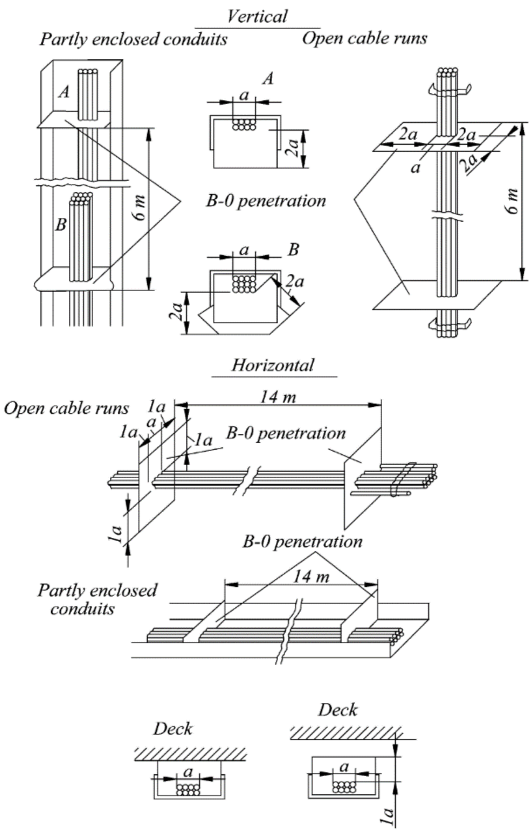

Fig. 16.8.4.3.2-2
Cable runs protected with B-0 fire-retarding divisions

16.8.4.4 Cables having external metallic sheaths may be installed on structures of light metal or be fastened in position by means of cable clips of light metal only in cases where reliable anticorrosive protection is provided.

16.8.4.5 In the holds of dry cargo ships intended for the carriage of dangerous cargoes, no through runs of cables shall, generally, be installed.

Where such cable-laying is necessary the requirements of 2.9 shall be fulfilled.

16.8.4.6 Cables installed in fishing vessels at locations subjected to the action of salt shall be adequately protected with casings or be provided with salt-resistant sheaths.

16.8.4.7 No cables are recommended to be installed under the flooring of machinery spaces. If such installation is required, cables shall be laid in metallic pipes or in closed conduits (refer to 16.8.8).

16.8.4.8 Cables installed across expansion joints in the hull structure shall be provided with expansion loops having a radius adequate for such joint. The inside diameter of a loop shall not be less than 12 outside diameters of the cables.

16.8.4.9 Installation of cables having insulation intended to withstand different permissible temperatures in the common cable runs shall be effected in such a manner that the cables are not heated above their permissible temperature.

16.8.4.10 Cables with different protective coverings the less hard of which may be damaged shall not be installed in one common pipe, one common duct or in other runs of not supported common laying.

16.8.4.11 Cores in multi-core cables shall not be used for supplying power and control currents to essential services not associated with one another.

Multi-core cables shall not be used simultaneously for safety voltage and service voltages exceeding the safety level.

16.8.4.12 When machinery is energized through two separate feeders, these feeders shall be installed in different runs as far apart as possible in horizontal and vertical directions.

16.8.4.13 When installing cables in ducts or other structures of combustible material, the ways of cable installation shall be protected from igniting by means of suitable fire protection, such as lining, coating or impregnation.

16.8.4.14 Cables shall not be embedded into thermal or acoustic insulation in case it is made of combustible materials. Cables shall be separated from such insulation by the lining of noncombustible materials or shall be installed at a distance at least 20 mm from it.

When cables are laid in thermal or acoustic insulation made of combustible materials, they shall be computed with relevant reduction in current rating.

16.8.4.15 Cables installed in refrigerated spaces shall be provided with protective sheath of metal, polychloroprene composition, or of any other material resistant to the exposure of the cooling agent.

If cables are provided with armour, this armour shall be adequately protected against corrosion.

16.8.4.16 Cables in refrigerated spaces shall be installed on perforated panels or bridges and fastened in position in such a manner that a free space is reserved between the cables and the walls of the room. Panels, bridges and cable clips shall be protected against corrosion.

If cables cross the thermal insulation of a refrigerated space, these cables shall run at right angles through an appropriate gland pocket on both ends.

16.8.4.17 When installing the cables, minimum internal bending radii shall be maintained in accordance with Table 16.8.4.17.

Minimum internal bending radii of high-frequency data transfer cables shall be at least 8 external diameters for unscreened and 10 external diameters for screened cables.

16.8.4.18 Cables and earthing conductors of equipment mounted on shock absorbers shall be installed in such a manner that they cannot be damaged in service.

16.8.4.19 Cables laid on the open deck of the ship and masts shall be resistant to sun radiation or protected against direct exposure to sun radiation.

Table 16.8.4.17

Type of cable		External diameter of cable, in mm	Minimum bending radius of cable
Insulation material of cable	Protective covering of cable		
Rubber or polyvinylchloride	Armoured with metal tape or wire	Any	10*d*
	Protected with metal sheath	Any	6*d*
	Lead alloy and armour	Any	6*d*
	Other sheaths	Up to 9,5	3*d*
		9,5 — 25,4	4*d*
		Over 25,4	6*d*
Varnished cambric	Any	Any	8*d*
Mineral insulation	Metal	Up to 7	2*d*
		7 — 12,7	3*d*
		Over 12,7	4*d*
Ethylene-propylene rubber or cross-linked polyethylene	Semiconducting and/or metal	25 and over	10*d*

16.8.5 Fastening of cables.

16.8.5.1 Cables shall be adequately fastened in position by means of clips, holders, hangers, etc., manufactured of metal or other non-combustible material.

The fastener surface shall be sufficiently wide and to have no sharp edges. The fasteners shall be selected in such a manner that the cables are securely fastened in position without damage to their protective coverings.

16.8.5.2 Distances between cable fastening points in case of horizontal installation shall not exceed the values given in Table 16.8.5.2.

When laying cable runs on cable ladders inside spaces the distance between cable fastening points may be enlarged up to 900 mm. Meanwhile, the distance between the supports of cable runs (ladder rung) shall not exceed 400 mm.

For vertical runs of cables these distances may be increased by 25 %.

Table 16.8.5.2

External diameter of cable, mm		Distance between fastening points for cables, mm		
over	up to	without armour	with armour	with mineral insulation
–	8	200	250	300
8	13	250	300	370
13	20	300	350	450
20	30	350	400	450
30	–	400	450	450

16.8.5.3 Cables shall be fastened in such a manner that mechanical strains in cables, if any, are not transmitted to their inlets or connections.

16.8.5.4 Cable runs and cables installed parallel to shell plating shall be fastened to ship's structures.

On watertight bulkheads and masts, cables shall be fastened on special supports (saddles, tray plates, chocks, etc.).

16.8.5.5 Cables running parallel to bulkhead subject to sweating shall be installed on bridges or on perforated panels in such a manner that free space is reserved between cables and bulkheads.

16.8.5.6 Cable runs shall be installed with a minimum number of crossings. The height of structures for crossing cable runs shall provide a distance between runs of not less than 5 mm. At places where cables cross each other and where it is impossible to leave an air gap, sheet rubber gaskets shall be applied.

16.8.5.7 For ships constructed from non-conducting materials it is permitted, due to the technology of hull construction from these materials, the properties of the materials used, etc., to accept the equivalents to the requirements for the installation, fastening and sealing of penetrations of cables and cable runs specified in the Rules for steel ships.

16.8.6 Cables penetrating decks and bulkheads.

16.8.6.1 Cable penetrations through watertight, gastight and fire-resisting bulkheads and decks shall be sealed.

Sealings where cables penetrate through the above bulkheads and decks shall not reduce their tightness; no force shall be transmitted to cables resulting from elastic deformations of ship's hull.

16.8.6.2 When installing the cable through nontight bulkheads or elements of ship's structure less than 6 mm thick, linings or bushings that will prevent damage to cables shall be provided.

When bulkheads or ship's structure is 6 mm or more thick, no linings or bushings are required, but the edges of holes shall be rounded.

16.8.6.3 Installation of cables over watertight decks shall be effected by one of the following methods:

.1 in metal pipes (shafts) protruding above the deck to a height of not less than 900 mm in locations where mechanical damage to cable is possible and to a height not less than that of the door sill in spaces where there is no risk of such damage;

.2 in common metal sockets or boxes with additional protection of cables by enclosures having the height specified in 16.8.6.3.1.

Cable boxes shall be packed with cable compound, while the pipes shall be provided with glands or be stuffed with cable compound.

16.8.6.4 Internal cross-section of each penetration shall be filled with cables to not more than 40 %. For module packing systems the extent of filling the penetration shall be determined in accordance with the approved design.

16.8.6.5 Cable penetrations shall be tested for tightness in accordance with the requirements of Appendix 1 to Section 4, Part IV "Technical Supervision during Manufacture of Products" of the Rules TSDCS.

16.8.7 Packing compounds.

16.8.7.1 To fill the cable boxes in watertight bulkheads and decks, the use shall be made of packing compounds having good adhesion to the inside surfaces of cable boxes and cable sheath that will withstand the action of water and oil products, will not shrink and lose its tightness in continuous service under conditions specified in 2.1.1 and 2.1.2.

16.8.7.2 Packings of cable penetrations through fire-resisting bulkheads shall withstand standard fire test specified for the given type of bulkhead in 2.1.2, Part VI "Fire Protection".

16.8.8 Installation of cables in pipes and conduits.

16.8.8.1 Metallic pipes and conduits wherein cables are installed shall be protected from corrosion on the inside and the outside surfaces. The inside surface of pipes and conduits shall be even and smooth. Ends of pipes and conduits shall be machined or protected in such a manner that no damage is caused to the cables when they are being pulled in.

Cables with lead sheaths not having any additional protective covering shall not be installed in pipes and conduits.

16.8.8.2 Pipe bending radius shall not be smaller than the permissible radius for cable of the largest diameter installed in this pipe (refer to 16.8.4.18).

16.8.8.3 The total cross-sectional areas of all cables measured on their outside diameters shall not exceed 40 % of the inside cross-sectional area of the pipe and the conduit.

16.8.8.4 The pipes and conduits shall be mechanically and electrically continuous and securely earthed if the earthing has not been already effected by the method itself of pipe and conduit installation.

16.8.8.5 The pipes and conduits shall be installed in such a manner that no water can accumulate therein. When required, ventilation holes shall be provided in the pipes and conduits, as far as possible, in the highest and lowest points, so that circulation of air is ensured and vapour condensation is prevented. Holes in pipes and conduits are permissible only at places where it will not enhance the danger of explosion or fire.

16.8.8.6 Cable pipes and conduits installed alongside ship's hull, which can be damaged due to deformation of ship's hull, shall be provided with compensation devices.

16.8.8.7 If in accordance with 16.8.1.1, the use is allowed of cables with combustible covering, these cables shall be installed in metallic pipes.

16.8.8.8 Cables installed in pipes and conduits vertically shall be fastened so that they are not damaged under tension due to gravity.

16.8.8.9 It is allowed to use cable trays/protective casings of the approved type made of reinforced and plain thermoplastic polymeric materials like polyvinylchloride (PVC) or fiber reinforced plastic (FPR).

The protective casing shall have round or other closed cross-section.

16.8.8.10 Cable trays/protective casings made of polymeric materials shall be supplemented by metallic fixing and straps such that in the event of a fire they, and the cables affixed, are prevented from falling and causing an injury to personnel and/or an obstruction to any escape route.

When cable trays/protective casings made of polymeric materials are used on open deck, they shall additionally be protected against UV radiation.

16.8.8.11 The load on the cable trays/protective casings made of polymeric materials shall be within the safe working load (SWL). The support spacing shall not be greater than the manufacturer's recommendation nor in excess of spacing at the SWL test.

In general, the spacing shall not exceed 2 m.

The selection and spacing of cable tray/protective casing supports shall take into account:

cable trays/protective casings' dimensions; mechanical and physical properties of their material; mass of cable trays/protective casings; loads due weight of cables, external forces, thrust forces and vibrations; maximum accelerations to which the system may be subjected; combination of loads.

16.8.8.12 The sum of the cables installed in cable trays/protective casings made of polymeric materials total cross-sectional area shall not exceed 40 % of the protective casing's internal cross-sectional area. This does not apply to a single cable in a protective casing.

16.8.9 Special precautions for single-core cables for a.c. wiring.

16.8.9.1 A.c. wiring shall not be carried out, as far as possible, in single-core cables. When, however, it is necessary to use single-core cables for circuits rated in excess of 20 A, the following precautions shall be observed:

.1 the cables shall be armoured with non-magnetic material;

.2 cables belonging to one circuit shall be placed in the same run or metal pipe and shall be as short as practicable. Each of such cables may be installed separately under a non-magnetic screen (in a pipe) earthed at one point and isolated from the screens of other cables and from the hull;

.3 cable clamps, unless they are made of non-magnetic material, shall include all the single-core cables of a circuit;

.4 the distance between the cables shall not be greater than one cable diameter.

16.8.9.2 Where single-core cables pass through bulkheads or decks, there shall be no magnetic material between cables belonging to the same circuit. The clearance between the cables and the magnetic material shall not be less than 50 mm.

16.8.9.3 When single-core cables having a current rating greater than 250 A are installed near steel structures, the clearance between the cables and the structure shall be at least 50 mm.

16.8.9.4 When single-core cables of a conductor cross-section of 185 mm2 or over are installed, a transposition (mutual position changing of cable line phases) of phases shall be effected at intervals not exceeding 15 m. Where cable length is below 30 m, no transposition is necessary.

16.8.9.5 Multicore cables with conductors in parallel shall be installed as single-core cables, and all the requirements for single-core cables apply in this case.

16.8.10 Connection and tapping of cables.

16.8.10.1 Ends of rubber-insulated cables to be introduced into machines, apparatus, switchgear and other equipment shall be provided with contact, protection and packing terminals that will ensure reliable electrical contact, will not permit moisture to penetrate inside the cable and will protect the insulation of cable cores from mechanical damage and effects of air and oil vapours.

At places of connection, rubber-insulated cable cores shall be provided with protective insulation against damage (wear, etc.).

16.8.10.2 Protective covering of a cable inserted into a device shall enter not less than 10 mm inside.

16.8.10.3 At places of tappings, connection of cables shall be effected in junction boxes by means of clamps.

16.8.10.4 If during the installation of cables it is necessary to make additional connections, these shall be effected in suitable junction boxes provided with clamps. The joint as a whole shall be protected from ambient conditions. Other methods of cable connection approved by the Register may be allowed.

16.9 BUSBAR CONDUITS ARRANGED OUTSIDE SWITCHBOARDS

16.9.1 Application.

16.9.1.1 The requirements of this Chapter apply to busbar conduits arranged outside switchboards instead of cables for supplying sections and/or switchboards and consumers. It is not recommended to install such conduits in hazardous areas, as well as on the exposed weather decks.

16.9.2. Busbar conduit system design.

Busbar conduit systems may consist of:

.1 electric conductors (busbar conduits), including neutral and earthing conductors and insulators;

.2 arrangements for busbar housing (ducts);

.3 connectors and tap-off units;

.4 deck and bulkhead penetrations;

.5 protection devices;

.6 bulkhead and deckhead fixing arrangements;

.7 separation units.

16.9.3 General requirements.

16.9.3.1 The safety standard and availability of the ship's mains designed to include busbar conduits shall be at least equivalent to those of the conventionally cabled ship's mains.

16.9.3.2 Busbar conduit systems shall comply with the relevant requirements of IEC 61439-1 and 61439-6 standards.

16.9.3.3 Busbar conduit systems, their elements and devices shall ensure reliable operation at the ambient temperatures from 0 up to 45 °C.

16.9.3.4 Busbar conduit systems shall be designed to comply with the following minimum degrees of protection:

dry spaces — IP 54;

wet spaces — IP 56.

The systems where condensation is possible shall be suitable for automatic draining.

16.9.3.5 The protection enclosures shall be sufficiently robust to withstand normal mechanical forces which may be expected on board ships.

16.9.3.6 The complete system shall comply with the fire test requirements as specified in IEC 60332-1-1 and 60332-1-2 standards.

Deck and bulkhead penetrations of busbar conduits shall not impair the mechanical, watertight and fire integrity of the decks or bulkheads through which they pass.

The internal arrangements of the ducts shall have the same fire integrity arrangements as the divisions which they pierce.

16.9.4 Special requirements.

16.9.4.1 Redundant essential consumers shall be supplied by separate busbar conduit systems. A failure in one system shall not impair the operation of the redundant one.

16.9.4.2 Where a system is arranged below the uppermost continuous deck, the ship's manoeuvrability as well as the safety of the crew and passengers shall not be impaired in the event of one more watertight compartment outside the engine room being flooded.

16.9.4.3 Busbars of main and emergency supply shall not be installed in a common duct.

16.9.4.4 System shall be fitted with means for separation to enable maintenance work and segregation of damaged parts. Where systems are led through fire sections, the separation units shall be installed on the supply side.

16.9.5 Protection devices.

16.9.5.1 The propagation of electric arcs along the busbars shall be prevented by arc barriers or other suitable means, such as, in the case of systems with uninsulated busbars, the use of current limiting circuit breakers.

17 ELECTRIC PROPULSION PLANTS

17.1 GENERAL

17.1.1 The requirements of this Section apply to all electric propulsion plants and their equipment, as well as to manufacture, installation and tests including:

.1 generators and their prime movers;

.2 switchboards;

.3 transformers/reactors;

.4 semiconductor frequency converters;

.5 electric propulsion motors;

.6 excitation arrangements (units);

.7 arrangements (units) of control systems of electric propulsion plants, monitoring systems (alarm system, indication and logging systems), as well as safety devices;

.8 power bus ducts and cable runs of production systems and power distribution in electric propulsion plants;

.9 accumulator batteries used to supply the electrical equipment.

17.1.2 The requirements of this Section do not apply to bow and aft thrusters being auxiliary arrangements for ship's steering.

17.1.3 If an electric propulsion plant is installed on board a ship, it shall comply with the requirements of this Section and applicable requirements of other Sections of this Part. At that, the distinguishing mark **EPP** shall be added to the class notation in compliance with the requirements of 2.2.12, Part I "Classification".

17.1.4 The electrical equipment of the electric propulsion plant shall meet the requirements of other sections and chapters of this Part unless otherwise specified in this Section.

17.1.5 In electric circuits of electric propulsion plants the voltage used shall not exceed those specified in 4.2 and Section 18.

17.1.6 It is recommended to provide electric heating in spaces enclosing electrical machines, switchboards and control panels.

17.1.7 Stationary lighting shall be provided underneath generators and motors of the electric propulsion plant.

17.1.8 Parts of electric propulsion machines (motors and generators) located under the floor shall have the degree of protection not below IP56.

Where they are installed in a dry compartment or protected against the ingress of water by a watertight foundation, and additionally, an alarm operating with the ingress of water in that compartment is provided, degree of protection IP23 may be allowed.

17.1.9 Provisions shall be made for arrangements preventing the generation and accumulation of moisture and condensate, in particular, while being idle for a long time, in casings of electric propulsion motors, generators, semiconductor frequency converters and other electric propulsion plant components. These arrangements may be electric heaters, air dryers, etc.

17.1.10 Electric propulsion plant shall be fitted with an arrangement for insulation resistance monitoring complying with the requirements of 2.11.

17.2 DEFINITIONS AND EXPLANATIONS

17.2.1 For the purpose of this Section the following definitions and explanations have been adopted.

Azimuth drive — drive which moves the propulsion unit around the vertical axis.

Main control station of the electric propulsion plant — control station of the main propulsion plant which is attended under seagoing condition.

Electric propulsion plant — set of equipment for distribution and conversion of electrical power into mechanical one in order to reproduce a predetermined torque by one or more propeller propulsions.

Double sensor — a sensor with two sensor elements in one housing.

Unified electric power plant — electric power plant united with the propulsion plant which ensures ship propulsion.

Local control station — control station located where a system intended for selection and input of reference values for semiconductor frequency converters or electric propulsion system external devices (units) control intended for semiconductor frequency converters which is independent from reference values for remote control system and any external are installed.

Podded drive — propulsion plant in which the electric propulsion motor is located in a dedicated, submerged unit (pod housing) of the ship.

Redundant sensor — two single sensors in separate housings to control the same parameter.

Electric propulsion system — coherent set of interrelated functional units implemented in electric power plant, interacting with a source of electric power to control the focus with the specified dynamic performance and set algorithms.

Electric power plant — complex of marine electrical equipment united by the process of production, distribution and conversion of electrical power into other forms of power (mechanical, thermal, light, chemical, etc).

17.3 CONFIGURATION OF ELECTRIC PROPULSION PLANTS

17.3.1 The electric propulsion plant supplied from and using a.c. electrical power includes the following devices:

.1 a.c. main generators or sets of accumulator batteries with their control devices — at least 2;

.2 main switchboard separated in two parts with a section circuit breaker or break switch;

.3 power transformers for a galvanic isolation or conversion of the main switchboard voltage to that of semiconductor frequency converter — one per each converter;

.4 power semiconductor frequency converters to supply the electric propulsion motor — at least 2;

.5 arrangements (units) of control or controller of electric propulsion plants — at least 2;

.6 electric propulsion motor — one or more.

17.3.2 For electrical propulsion plants with one electric propulsion motor, synchronous, asynchronous and electronically commutated main propulsion motors shall have two systems of stator windings supplied from the relevant semiconductor frequency converter. Each converter shall be designed for at least 50 % of the rated power of the electric propulsion plant. If the ship is equipped with several electric propulsion motors at the common shaft with the propeller of the main electric propulsion plant or with several main propulsion plants, the use of electric propulsion motors with one system of stator windings is permitted.

17.3.3 Propulsion d.c. motors shall be of the double-armature (double-commutator) type with each armature winding designed for at least 50 % of the rated power of the plant. Each armature winding shall be supplied from its independent converter. Any single failure in one converter shall not result in complete loss of power.

17.3.4 Provision shall be made for braking or locking devices as part of the shafting to prevent its free rotation with a switched-off propulsion motor (shaft) at any environmental conditions or during ship towing (refer also to 7.2.10, Part VII "Machinery Installations").

17.3.5 Electric propulsion system structure and control algorithm provided by some electric propulsion plants shall follow the one failure principle, i.e. if any component of the electric propulsion plant fails, a ship shall be underway at least at the partial power.

17.3.6 Provision shall be made for a warning alarm at all active control stations when any failure occurs in the electric propulsion plant.

17.3.7 For all auxiliary machinery and essential services, provision shall be made for local control stations to which control is transferred if the remote automated control system of the electric propulsion plant fails.

17.3.8 Configuration of electric propulsion plant supplied with and using d.c. electric power is specified in в 23.8.1.

17.4 EXCITATION SYSTEMS

17.4.1 General.

17.4.1.1 Every excitation system shall be supplied by a separate feeder. The obtainable current and voltage of the excitation system, as well as source of power shall fully comply with the requirements for all electric propulsion plant modes including manoeuvring, overcurrent and short circuit, as well as the capsizing moment conditions.

17.4.1.2 Power supply of excitation systems shall be protected against short circuits only. The activation of an electromagnetic release at short circuit shall be supplemented with an alarm at control stations.

17.4.1.3 If the built-in short-circuit monitoring device of the excitation system trips, the respective circuit breaker of the generator or propulsion motor shall also trip.

17.4.1.4 If the excitation system is fitted with independent safety devices against underfrequency and over-voltage or U/f-functions, they shall be adjusted in such a way that the system protection reacts first.

17.4.1.5 Excitation circuits shall be provided with means for suppressing voltage rise when an excitation switch is opened (field suppression system).

17.4.1.6 Means (filters, etc.) shall be provided to limit harmonic distortions and reduce a power factor.

17.4.2 Generator excitation.

17.4.2.1 Excitation systems shall be supplied from the generator, the generator shall be self-excited. The voltage built up shall be done without the aid of external sources of electrical power.

17.4.2.2 External source of electrical power may be used for exciter control circuits, as well as for initial excitation, provided it is redundant.

The external source of power shall be supplied from the main and emergency switchboards and, additionally, from the standby accumulator battery. At least two external sources of power for all electric propulsion plant generators shall be provided.

17.4.3 Electric propulsion motor excitation.

17.4.3.1 The exciter shall be supplied directly from the same main switchboard section supplying the stator winding.

17.4.3.2 Excitation systems and automatic control systems shall protect electric propulsion motors from overspeeding in the event of the propeller breaking down or working clear of water.

17.5 ELECTROMAGNETIC COMPATIBILITY (EMC)

17.5.1 The electric propulsion plant shall operate without malfunctions and failures being exposed to electromagnetic interference, and comply with the requirements of 2.2.

17.5.2 Equipment producing transient voltage, frequency and current variations shall not cause malfunctions and failures of other equipment on board, neither by conduction, induction or radiation.

17.5.3 If a total harmonic distortion value of 10 % is exceeded when operating the propulsion plant, the appropriate filtering and interference-free operation of any consumers shall be ensured.

17.6 PRIME MOVERS OF ELECTRIC PROPULSION PLANT GENERATORS

17.6.1 Permissible speed deviations.

17.6.1.1 If electric propulsion plant generators are also used for supplying the ship network, frequency deviations with the relevant load variations shall meet the requirements specified in 2.11.3, Part IX "Machinery".

17.6.1.2 Where the speed control of the propeller requires speed variation of prime movers of the electric propulsion plant generators, the governors shall be provided with means for local control as well as for remote control.

17.6.1.3 The prime movers rated power and overload capacity of the Unified Electric power plant generators shall be adequate to supply the power needed in the range of the operating conditions of the electrical equipment, as well as the electric propulsion plant load variations due to manoeuvring, at sea, including severe weather conditions.

17.6.2 Parallel operation.

17.6.2.1 In case of parallel operation of generators, the control system used shall ensure stable proportional distribution of loads over the entire output range of the prime movers as specified in 3.2.2.

17.6.2.2 In case the unified electric power plant generators (shaft generators) are used simultaneously for power supply and the electric propulsion plants containing reversible semiconductor frequency converters adapted to recover the power at braking of the electric propulsion motor and to retard the speed of the electric propulsion motor in reverse, the power plant control system ыshall ensure transmitting data on consumed active power from generators to define switching threshold of baking resistors shall be provided.

17.6.3 Reverse power.

17.6.3.1 When the propulsion motor is braking or reversing in emergency from full ahead running to full speed astern, the prime movers of an independent electric propulsion plant shall be capable of absorbing a proportion of the recuperated energy without tripping due to overspeed or reverse power.

17.6.3.2 To absorb a proportion of the recuperated energy and to retard the speed of the electric propulsion motor of an independent electric propulsion plant, braking resistors may be used ensuring the necessary limits on the prime movers and the electric propulsion plant generators speed. The amount of recuperated work shall be limited by DMS controllers.

17.7 ELECTRIC PROPULSION PLANT GENERATORS

17.7.1 General.

17.7.1.1 Generators (shaft generators) operating with semiconductor converters shall be designed for the expected harmonics of the system. While designing the electric power plant and selecting the generators' rated power, a sufficient output reserve shall be provided to prevent the generator temperature rise, compared with the sinusoidal load.

17.7.1.2 Stator windings of generators with rated power output above 500 kVA shall be provided with temperature sensors.

17.7.1.3 Electric propulsion plant generators shall be fitted with cooling air cleaning filters opencircuit and closed-circuit ventilation. For alternating current brushless generators with closed-circuit ventilation the cooling air cleaning filters are not mandatory. Ventilation ducts shall be arranged so as to prevent water ingress into the machine.

17.7.1.4 Electric propulsion plant generators may be used for supplying auxiliary electrical machinery and services provided voltage and frequency are stable under all conditions, including manoeuvring, in compliance with the requirements of 2.1.3.

17.7.1.5 No circuit breakers shall be fitted in excitation circuits of generators except those which remove excitation of machinery at short circuits or damages in the main current circuit.

17.7.1.6 Means of protection of generators shall comply with the requirements specified in 8.2.

17.7.1.7 For ice class ships and icebreakers, electric propulsion plant generators' rated power shall be selected taking into account the minimum required power delivered to the propeller shaft determined in accordance with 2.1.1.2, Part VII "Machinery Installations".

17.7.2 Generator bearings and lubrication.

17.7.2.1 Sliding bearing shells shall be easily replaceable. Provision shall be made for checking the bearing lubrication. Adequate lubrication shall be provided even at the maximum potential trim. Provision shall be made for relevant seals to prevent oil ingress inside the generator.

17.7.2.2 In case of bearings with forced lubrication (under pressure), the following alarms, as a minimum, shall be provided at the electric propulsion plant control stations:

.1 failure of lubricating system (no flow of lubricating oil, failure of lubrication pump, loss of pressure in the lubrication pipe, etc.);

.2 maximum temperature of each bearing.

17.7.2.3 Generators shall be fitted with backup (emergency) devices for bearings lubrication which, in the event of malfunction or failure of the main (working) lubricating system, provide adequate lubrication until the machine full stop.

17.7.2.4 To avoid damage to bearings, provision shall be made to ensure that no currents can flow between the bearing and the shaft.

17.7.3 Generators cooling.

17.7.3.1 In addition to thermometers, temperature sensors of cooling air shall be provided which shall initiate an alarm with the excess of a permissible temperature.

17.7.3.2 For machines with a closed circuit cooling and heat exchanger, the flow of primary and secondary coolants shall be monitored. An alarm shall be initiated with the flow failure.

17.7.3.3 Leakage-water and condensed moisture shall be kept away from the machine windings. Provision shall be made for an alarm to monitor leakage.

17.8 ELECTRIC PROPULSION PLANT SWITCHBOARDS

17.8.1 Electric propulsion plant switchboards shall meet the requirements of 4.6 and 18.6.

17.8.2 Electric propulsion plant system shall be fitted with an arrangement for insulation resistance monitoring (refer to 2.11).

17.8.3 Switches for routine switching in de-energized circuits of the electric propulsion plant shall be provided with an interlocking device to prevent their tripping under voltage, or false switching.

17.9 ELECTRIC PROPULSION PLANT POWER TRANSFORMERS

17.9.1 General.
17.9.1.1 Transformers and reactors shall meet the requirements of Section 11 and 18.4.
17.9.1.2 Provision shall be made for at least two independent power transformers for the electric propulsion plant. Only transformers with separate windings shall be used.
17.9.1.3 The winding temperatures of transformers used in electric propulsion plants shall be monitored with a sensor and indicator system.
17.9.1.4 For current measurements on the primary side in each phase supplying the electric propulsion plant transformer, ammeters shall be provided on the main switchboard.
17.9.1.5 Each electric propulsion plant transformer shall have overcurrent and short circuit protection on the primary and secondary side.
For protection on the secondary side, electric propulsion plant semiconductor converter may be used.
17.9.2 Liquid cooled electric propulsion plant transformers.
17.9.2.1 Windings of liquid cooled transformers shall be completely covered by liquid, even for inclinations up to and including 22,5°.
17.9.2.2 Transformers shall be provided with the necessary collecting and accumulating arrangements for coolant leaks.
Fire detectors and fire-fighting equipment shall be installed in the vicinity of the transformer. The firefighting equipment may be manually operated.
17.9.2.3 Transformers shall be fitted with protection against gassing of coolant.
17.9.2.4 The coolant temperature shall be monitored with a sensor system. A pre-alarm shall be actuated before the maximum permissible temperature is attained. When the maximum permissible temperature limit is reached, a separate sensor shall activate protection which switches off the transformer.
17.9.2.5 The coolant level shall be monitored by two sensors, one of them shall actuate an alarm and the other set up to the maximum permissible level shall switch off the transformer.
17.9.3 Air cooled electric propulsion plant transformers.
17.9.3.1 The operation of fans for transformers cooling, as well as the cooling air temperature shall be monitored with a sensor system.
An alarm shall be given at the excess of temperature or fan failure.
17.9.3.2 Where a closed circuit cooling air system with an air cooler is used, in addition to the requirements of 17.9.3.1, the following shall be monitored:
.1 the minimum flow of primary and secondary coolants (air and water);
.2 heat exchanger leakage to be alarmed.
The heat exchanger shall be so installed that water leakages and condensed moisture are kept away from the windings.

17.10 ELECTRIC PROPULSION PLANT SEMICONDUCTOR CONVERTERS

17.10.1 General.

17.10.1.1 Converters shall meet the requirements of Section 12.

17.10.1.2 At least two entirely independent separate semiconductor converters shall be provided to feed separate winding systems of electric propulsion plant (or separate electric propulsion plants).

17.10.1.3 Each converter shall be provided with a separate unit or a control system.

17.10.1.4 There shall be provided two galvanically isolated speed sensors for each unit or device of control system. Common housing of both sensors is permitted.

17.10.1.5 If the converter feeds a permanently excited electric propulsion motor of direct of alternative current (including those of permanent magnet), a switch disconnector shall be fitted in the "motor – converter" line which opens automatically in case of an inverter or rectifier fault. Devices shall be provided for such faults diagnosis.

17.10.1.6 Electric propulsion plant converters shall be designed for the nominal torque of the drive (nominal torque at a propeller shaft). Short-term overloads and speed variations (dips) resulting from overloads or the load throwing off at propeller emergence shall not lead to the activation of converter protection.

17.10.1.7 The recuperated energy may be received to the unified electric power plant at retarding the speed of the electric propulsion motor in reverse via the reversible semiconductor frequency converters to ensure the quality parameters (refer to 2.1.3) for the ship's power consumers. The excess of the recuperated energy shall be absorbed by "braking resistors".

17.10.1.8 Reactive power may be compensated by means of reversible semiconductor frequency converters. Thus, the control unit shall receive a signal from control system of the electrical power plant to comply with the current value of the reactive power being generated by the power consumers of the unified electric power plant.

17.10.1.9 The cabinets for semiconductor converters shall meet the requirements of 4.6 and Section 18.

17.10.1.10 The design of the cabinets for semiconductor converters shall provide for the quick exchange of power components of the built-in equipment. This may be achieved by use of modular design for power circuit, its components, control, protection and data display units.

17.10.1.11 Requirements for semiconductor converters of the electric propulsion plant in the systems with electrical power distribution for direct current are specified in в 23.8.2.

17.10.2 Cooling of semiconductor converters.

17.10.2.1 If converters are fitted with a forced-cooling system, means for its monitoring shall be provided. In case of a failure of the cooling system, measures shall be taken to prevent the overheat and failure of the converter.

17.10.2.2 The cooling system shall be provided with an alarm system. The alarm signal shall be generated by the reducing of a coolant flow or by high temperature of semiconductors.

17.10.2.3 Single failures in the converter cooling system shall not result in tripping all converters of the ship's electric propulsion plant.

17.10.3 Protection of semiconductor converters.

17.10.3.1 Operational overvoltages in a supply system of converters shall be limited by suitable devices to prevent breakdown of the components of the semiconductor frequency converters power circuit.

17.10.3.2 A suitable control system shall ensure that the rated current of semiconductor elements cannot be exceeded under all normal and most severe conditions.

17.10.3.3 Power circuit and the converter components shall be protected against damage and failure due to direct short-circuit at the terminals. Protection by fuses against short-circuit currents is permitted. The relevant feedbacks of the converter shall control (limit) the current in such away, that no components are damaged when the converter is switched on to a blocked motor.

17.11 PROTECTION ARRANGEMENTS FOR HARMONIC FILTERS

17.11.1 A harmonic filter maintaining harmonic distantion levels within acceptable limit shall be arranged as a three phase unit with individual protection of each phase on the main switchboard busbars at any step of propulsion.

17.11.2 Each individual filter circuits shall be protected against overcurrents and short-circuit currents. The fuses in filter circuits shall be monitored. Any fuse burnout shall be alarmed.

17.11.3 When designing and using line filters, their layout shall be designed for any conceivable line constellations. In particular, self-resonance shall be excluded under any load conditions and operating generators constellations.

17.11.4 In case of several parallel filter circuits, the current symmetry shall be monitored. An unsymmetrical current distribution in the individual filter circuits and the failure of the filter shall be alarmed.

17.11.5 Consideration shall be given to additional protection for the individual capacitor element (e.g. relief valve or overpressure disconnector) in order to protect against damage from rupturing. This consideration shall take into account the type of capacitors used.

17.11.6 Additional requirements for protection arrangements for harmonic filters in systems with electrical power distribution for direct current are specified in 23.8.3.

17.12 ELECTRIC PROPULSION MOTORS

17.12.1 General.

17.12.1.1 Stator windings of a.c. motors and interpole, mainpole and compensation windings of d.c. motors of electric machines with a capacity above 500 kW, shall be provided with temperature sensors.

17.12.1.2 Regarding the design and lubrication of electric propulsion motor bearings, the requirements of 17.7.2 shall be met.

17.12.2 Electric propulsion motors cooling.

17.12.2.1 The cooling system shall ensure sufficient cooling under all load and speed conditions.

17.12.2.2 Electric propulsion motors shall be fitted with built-in temperature sensors which shall give an alarm signal with the excess of a permissible temperature.

17.12.2.3 For machines with a closed circuit cooling system and a heat exchanger, the flow of primary and secondary coolants shall be monitored.

17.12.2.4 Provision shall be made to alarm leakage. The heat exchanger shall be installed so that water leakages and condensed moisture are kept away from the windings.

17.12.2.5 If the cooling system of the propulsion motor fails, the emergency operation mode to ensure ship's manoeuvring under heavy navigating conditions shall be provided. Interventions by an operator for opening of emergency air flaps are permitted.

17.12.2.6 Air-cooled electric propulsion motors shall be fitted with air intake filters and at least two forced draught fans (groups of fans), ensuring emergency operation required in 17.12.2.5 in case of failure of either fan. For electric propulsion plant with one electric propulsion motor, supply of each electric drive of forced draught fans from different switchboards or from different sections of the main switchboard shall be provided. Where several electric propulsion motors are installed in the electric propulsion plant, electric drives of fans (group of fans) of any separate electric propulsion motor may be supplied from one switchboard or from one section of the main switchboard. At that, electric drives of fans (groups of fans) of different electric propulsion motors shall be supplied from different switchboards of from different sections of the main switchboard. A visual signal indicating fans operation and an alarm on their shutdown shall be provided.

17.12.2.7 A liquid cooling system for multi-armature machines shall be independent for each armature.

17.12.3 Protection of electric propulsion motor.

17.12.3.1 Over-current protection in the main and excitation circuits shall be set sufficiently high so that there is no possibility of its operating due to the over-currents caused by ship's maneuvering, operation in heavy seas or in broken ice.

17.12.3.2 Short-circuit and overcurrent protection may be provided by the converter. Different electric propulsion motor designs (d.c. synchronous, induction and permanent-magnet excitation motors) shall be taken into consideration.

Additional requirements for the protection of electric propulsion motor in the systems with electrical power distribution for direct current are specified in 23.8.4.

17.12.3.3 For electric propulsion d.c. motors provision shall be made for an independent overspeed (runaway) protection device as required in 2.11, Part IX "Machinery".

The electric propulsion motor shall be capable to withstand overspeed up to the limit reached in accordance with the characteristics of the overspeed protection device at its specified operational setting.

17.12.3.4 The motor shall be capable to withstand a sudden short-circuit currents at its terminals under nominal load without damage.

Steady state short-circuit current of a permanent excited motor shall not cause thermal damages of the motor and the current carrying components (e.g. slip rings, cables, feeders or busducts).

17.13 SPECIAL REQUIREMENTS FOR PODDED AZIMUTH THRUSTER DRIVES AND STEERABLE PROPELLER DRIVES

17.13.1 General.

17.13.1.1 If the space, where an electrical machine and other equipment are located, is inaccessible during operation and associated with special environmental conditions (high temperature, humidity, etc.), special measures shall be taken like use of highly reliable materials and components, adequate number of sensors, as well as special means for protection of components against flooding and damages.

17.13.1.2 The components, e.g. controls, sensors, slip rings, cable connections and auxiliary drives shall withstand undamaged the strength of vibration, of at least 4*g* from 3 to 100 Hz.

17.13.2 Sensors.

17.13.2.1 Sensors which can be changed only during dry docking shall be fitted with two sensor elements in the same housing with separate data transmission channels.

17.13.3 Bearings.

17.13.3.1 Oil filling levels in bearing housings shall be monitored during operation and standstill. Any oil leakage shall activate an alarm.

This applies to circulated lubrication systems as well. These systems shall additionally be equipped with lubricating oil flow monitoring. A flow level monitoring alarm shall be independent from the electric propulsion motor control system.

17.13.3.2 The temperature of shaft bearings shall be monitored by an alarm and protection system. The alarm shall be carried out in two steps: alarm and engine stop. The protection system shall be independent from the temperature indication system for shaft bearings, and the alarm system.

17.13.4 Bilges in a pod housing.

The water level in pod bilges and associated spaces shall be monitored with level sensors. In addition to high level sensors in bilges operating for an alarm system, independent sensors to monitor a high emergency level shall be provided which prevent false operations and automatically stop the propulsion.

17.13.5 Fire detection system.

An effective fire detection system with the adequate number of sensors of the relevant type shall be provided. The general requirements for such systems are specified in 7.5.

17.13.6 Accessible spaces (in a pod housing).

Sufficient illumination and ventilation shall be provided for accessible spaces of the pod housing where regular maintenance work and equipment inspection are carried out.

17.13.7 Protection of the propulsion motor.

17.13.7.1 Motors of more than 1 MW and all permanent excited motors shall be provided with protection against internal faults that also monitors the connections between the semiconductor converter and the motor. The power supply to the defective equipment shall be interrupted with an appropriate time delay and an alarm shall be given.

17.13.7.2 Humidity shall be monitored for motors with closed air cooling systems. The excess of the permissible humidity level shall be alarmed.

17.13.8 Motor supply lines.

17.13.8.1 Cables operated at high temperature limits shall be installed separate from other cables. If required, splitters shall be provided to prevent contacts between cable sheaths.

17.13.8.2 IP protection for all terminals, cable glands and busbar connections shall be equal to motor protection, however, at least IP44. These requirements also apply to control cables.

17.13.9 Slip rings.

17.13.9.1 Where data from feedback sensors, controlled variable sensors, etc. are transmitted via a data bus of slip rings, the busbar shall be duplicated. Failure of each single busbar shall be alarmed.

17.13.9.2 Slip rings unit fitted with external forced cooling system shall be capable of operation without a cooling system for a certain period of time. The cooling system failure shall be alarmed.

17.13.10 Azimuth podded drive and Azimuth steerable propeller drive.

17.13.10.1 Azimuth drive shall meet the requirements for steering gear in accordance with the requirements of 5.5.

17.13.10.2 The single failure localization principle shall be ensured for all electrical and hydraulic components. Safe operation of the ship shall be ensured independently of the rudder angle and ship's speed at any time a failure occurs. The designer shall develop and submit for approval the "Failure Mode and Effects Analysis" (FMEA).

17.13.10.3 The position of the azimuth drive shall be mechanically indicated on a scale at the drive location (steering compartment).

17.13.10.4 At least two independent electric drives shall be provided for each azimuthal unit for turn, whereby one drive shall be supplied from the main switchboard and the other, from the emergency switchboard.

17.13.10.5 Azimuth electric drives shall be protected against overcurrent (by converter, if applicable) and short circuit. They shall be able to supply 160 % of the torque necessary for the rated speed of movement in accordance with the requirements of 7.2.3, Part VII "Machinery Installations".

Azimuth drives with different design, e.g. hydraulic, shall also be able to fulfill the above requirements.

17.13.10.6 The thrust azimuth angle shall be limited to ±35°. At low propulsion power rating and thus low ship's speed or crash-stop maneuver these limits may be disabled with the control system.

17.13.10.7 The thrust azimuth angle shall be limited related to the steps of the set ship's speed that the safety of the ship is not endangered (due to excessive thrust while turning). The limitation (interlock) shall be provided redundantly and independently of the control of the azimuth angle (pod turning).

17.13.10.8 Reaching or exceeding the permissible limitations of the azimuth angle shall be alarmed. After triggering the limitation, it shall be possible to move the azimuth drive back to the permitted angles of the drive turn without manual reset.

17.13.10.9 The operation and indication equipment of the azimuth drive shall be arranged in such a way that the set direction of the propeller thrust or the direction of the ship's moving is clearly indicated. It shall be clear to the operator whether the direction of the ship's moving or the direction of the propeller thrust of the electric propulsion plant was chosen.

17.13.10.10 The local control station for azimuthal unit shall be equipped with the following:

.1 ammeters for each supply system of each load component;
.2 azimuth angle (turn angle) indicators for each drive;
.3 power supply system readiness for operation indicators for each drive;
.4 power supply system disturbance indicators for each drive;

and provide for the following:

.5 power limitation (from converter);
.6 control from main machinery control room;
.7 control from the navigation bridge;
.8 control from local control station;
.9 running indication for the associated propulsion drive.

The local control station can be activated locally at any time and shall have the highest priority.

17.14 ELECTRIC PROPULSION PLANTS CONTROL SYSTEMS

17.14.1 Powerplant control systems.

17.14.1.1 For power supply systems of electric propulsion plants with generators operating in parallel, the automated powerplant control system shall be provided which will ensure adequate power generation being consistent with the needs of specific operational modes of the electric propulsion plant, in transit/maneuver including. Automatic load based disconnection of generators in maneuver mode is not permitted.

17.14.1.2 In case of under-frequency on main switchboard busbars, overcurrent or overload and reverse power, the propulsion power shall be automatically limited (to prevent de-energizing of main switchboard busbars).

17.14.1.3 If generators are running in parallel and one of them is tripping by protection system, the automated power plant control system shall automatically reduce the electric propulsion plant load to protect the remaining generators against unacceptable overloads and ensure their operation at permissible loads. The same requirement applies to the main switchboard busbars tiebreakers.

17.14.1.4 Tripping of the main switchboard busbars tiebreaker shall not lead to any malfunction of the system. It is not necessary that the power plant control system remains in the automatic mode if the power supply system is split.

Any loss of the control system automatic functions shall be alarmed.

17.14.1.5 Electric power plant control system shall ensure transfer of information to electric propulsion system as regards the current value of active capacity consumption from generators to restrict the power recuperated to the unified electric power system and determination of on threshold of "braking resistors".

17.14.1.6 Electric power plant control system shall ensure transfer of information to electric propulsion system as regards the current value of reactive capacity consumption being generated by the power consumers of the unified electric power plant.

17.14.2 Location of the electric propulsion plant control stations.

17.14.2.1 Electric propulsion plant control stations may be located at any convenient place according to the ship's purpose.

Where control stations are arranged outside the machinery space, i.e. on the bridge or in other locations, control stations in the machinery space or main machinery control room shall be provided as well.

17.14.2.2 The local control station has a priority and shall be located in the vicinity of the drive or semiconductor converters. Changes of electric propulsion plant modes generated at this station shall be displayed by the system indicating a preset and executed commands.

17.14.2.3 Where several control stations are available, a control stations switch in the control station having a priority shall be provided. Such switch shall provide switching of any, but only one control station (central and wing stations on the navigation bridge are considered as one control station).

17.14.2.4 Each control station shall have an emergency stop device independent of the control system and the active (in "on" condition) control station.

17.14.3 Main and local control stations.

17.14.3.1 At least two mutually independent main and local control stations shall be provided for electric propulsion plant.

17.14.3.2 In case of damage, malfunctioning or loss of power supply of the main station control system, a local control station of the electric propulsion plant converters shall be provided.

17.14.3.3 The bridge shall be fitted with control systems such that the steering (azimuth thrust change) control system can operate independently of the speed and electric propulsion plant electric propulsion motor reverse control system.

17.14.3.4 All electric propulsion plant alarms shall be acknowledged at the local control station. Alarms which do not require any further intervention of the personnel can be acknowledged at the main control station (on the navigation bridge) with the mandatory follow-up acknowledgement at the local control station.

17.14.3.5 Restart of the electric propulsion plant shall be possible from both (main and local) control stations, depending on which one has been preselected. After the main switchboard de-energizing it shall be possible to restart the electric propulsion plant at the main control station.

17.14.3.6 If the electric propulsion plant is controlled from a panel or desk with the use of electric, pneumatic or hydraulic drive, the failure of them shall not result in electric propulsion plant tripping, and each control station at the panel or desk shall be immediately ready for manual operation.

17.14.3.7 Mechanically linked control stations installed in the wheelhouse (on the navigation bridge) for their synchronous operation may be permitted.

17.14.3.8 The remote control system of the electric propulsion plant shall be so designed that no time delay is needed for the personnel to move a control handle at a control station to a new position.

17.14.3.9 The electric propulsion plant control system shall be provided with an interlock to prevent the electric propulsion plant activation with a shaft turning gear engaged.

17.14.3.10 Each control station shall have a visual indication on the control system being alive.

17.14.4 Measuring, indicating and monitoring equipment.

17.14.4.1 Failures in measuring, monitoring and indicating equipment shall not result in failure of the electric propulsion plant control system, e.g. failure of the actual value (speed) sensor or of the reference speed value sensor shall not cause an excessive increase of propeller speed.

17.14.4.2 The local (active) control station shall be equipped with the following:

.1 ammeter for each power supply line of each load component (stator current of each winding, etc.), and also in the excitation circuit (for adjustable-excitation systems);

.2 voltmeters for each power supply line of each load component, and also for power supply of the excitation system (for adjustable-excitation systems);

.3 speed indicator for each shaft;

.4 "Powerplant ready for electric propulsion plant operation" indicator;

.5 "Powerplant disturbed" indicator;

.6 "Electric propulsion plant power limited" (from converter) indicator;

.7 "Control from the main machinery control room" indicator;

.8 "Control from the navigation bridge" indicator;

.9 "Control from the local control station" indicator.

17.14.4.3 The main control station (on navigation bridge) shall be equipped with the following:

.1 revolution indicator for each shaft;

.2 each shaft power meter;

.3 "Powerplant ready for switching on" (additional generators) indicator;

.4 "Power plant ready for electric propulsion plant operation" indicator;

.5 "Power plant disturbed" indicator;

.6 "Electric propulsion plant power limited" indicator;

.7 "Request to reduce power" indicator — if not automatically controlled or "override" button pushed (cancellation of the plant automated control);

.8 "Control from the main machinery control room" indicator;

.9 "Control from the navigation bridge" indicator;

.10 " Control from the local control station" indicator;

.11 indication of the generators operating at the electric propulsion plant;

.12 indication of power reserve (recommended).

17.14.4.4 When two or more control stations are provided for change of speed and angle of turn of CPP blades, both speed change and angle of turn of CPP blades indicators shall be provided at each control station.

17.14.4.5 The main machinery control room shall be equipped with the following:

.1 speed indicator for each shaft;

.2 each shaft power meter;

.3 "Power plant ready for switching on" (additional generators) indicator;

.4 "Power plant ready for electric propulsion plant operation" indicator;

.5 "Power plant disturbed" indicator;

.6 "Electric propulsion plant power limited" indicator;

.7 "Request to reduce power" indicator — if not automatically controlled or "override" button pushed (cancellation of the plant automated control);

.8 "Control from the main machinery control room" indicator;

.9 "Control from the local control station" indicator;

.10 "Control from the navigation bridge" indicator;

.11 indication of the generators operating at the electric propulsion plant.

The list of parameters controlled by the alarm system is given in Tables 17.14.4.5-1 and 17.14.4.5-2.

17.14.5 Fail-safety of electric propulsion plant control systems.

17.14.5.1 Electric propulsion plant control systems with the use of processors shall comply with the requirements of Section 7, Part XV "Automation".

Table 17.14.4.5-1

List of monitored parameters of the electric propulsion plant with AC synchronous, permanent excited and induction electric propulsion motors

Monitored parameter	Limiting value, Max/Min	Local measuring instrument	Alarm, display in the main machinery control room	Load reduction	Automatic "Stop"	Main control station (bridge), group alarm
Electric propulsion motor:						
Lubrication system	Malfunction	Inspection glass	×	×	×	×
Bearing temperature	Max	Thermometer	×			×
Stator winding temperature	Max		×	×		×
Slip rings (synchronous electric propulsion motor)	Malfunction (electric arc)	Inspection hatch	×			×
Water/air cooling system	Malfunction		×			×
Cooling air temperature at the inlet	Max	Thermometer	×			×
Coolant	Leakage		×			×
Speed	Max		×		×	×
Voltage regulation (synchronous electric propulsion motor)	Failure		×		×	×
Insulation resistance for stator and feeder	Min		×			×
Insulation resistance for excitation system and feeder (synchronous electric propulsion motor)	Min		×			×
Transformers:						
Winding temperature	Max		×	×		×
Coolant	Leakage		×	×		×
Cooling system	Malfunction		×			×
Converters:						
Mains	Malfunction		×		Start	×
Cooling system	Malfunction		×	×		×
Power units temperature	Max		× Max1		× Max2	×

Monitored parameter	Limiting value, Max/Min	Local measuring instrument	Alarm, display in the main machinery control room	Load reduction	Automatic "Stop"	Main control station (bridge), group alarm
Cooling agent flow	Min		×			×
Coolant	Leakage		×			×
Preliminary alarm						×
Accident, failure			×		×	×
Rotor speed and position sensor (synchronous electric propulsion motor)	Malfunction		×			×
Emergency stop (Converter switched off)			×		×	×
Semiconductor fuse	Malfunction		×		×	×
Semiconductor temperature	Max		×	Reduction		×
Voltage (direct current link)	Max		×		×	×
Current (direct current link)	Max		×		×	×
Current at the converter outlet	Max		×		×	×
Electric propulsion plant main, shipboard electrical system:						
Harmonic trap	Accident, damage		×			×

Table 17.14.4.5-2

List of monitored parameters of the electric propulsion plant with d.c. electric propulsion motors

Monitored parameter	Limiting value, max/min	Local measuring instrument	Alarm, display in the main machinery control room	Load reduction	Automatic "Stop"	Main control station (bridge), group alarm
Electric propulsion motor:						
Lubrication system	Malfunction	Inspection glass	×	×	×	×
Bearing temperature	Max	Thermometer	×			×
Main pole temperature	Max		×	×		×
Auxiliary pole/compensating winding temperature	Max		×	×		×
Water/air cooling system	Malfunction		×			×
Cooling air temperature at the inlet	Max	Thermometer	×			×
Coolant	Leakage		×			×
Speed	Max		×		×	×
Commutator/brushes	Malfunction (electric arc)	Inspection hatch	×			×
Armature current	Max		×		×	×
Insulation resistance for armature circuit and feeder	Min (earth fault)		×			×
Transformers:						
Winding temperature	Max		×	×		×
Coolant	Leakage		×			×
Cooling system	Malfunction		×			×
Converters:						
Mains	Malfunction		×		Restart	×
Cooling system	Malfunction		×	×		×
Power units temperature	Max		× Max1		× Max2	×
Cooling agent flow (direct cooling)	Min		×			×
Coolant	Leakage		×			×
Preliminary alarm						×
Accident, failure			×		×	×
Armature speed sensor	Malfunction		×			×
Emergency stop (Converter switched off)			×		×	×
Semiconductor fuse	Malfunction		×		×	×

Monitored parameter	Limiting value, max/min	Local measuring instrument	Alarm, display in the main machinery control room	Load reductio n	Automatic "Stop"	Main control station (bridge), group alarm
Electric propulsion plant main, shipboard electrical system:						
Harmonic trap	Accident, damage		×			×

17.14.5.2 The loss of power or malfunctioning of any other control and monitoring systems shall not result in loss of propulsion and electric propulsion plant control, ship's steering or azimuth drive.

17.14.5.3 Electric propulsion plant, azimuth drives and their control systems shall have self-check system and an alarm system to detect failures quickly.

17.14.5.4 The most probable failures, e.g. loss of power, wire failure or cable and wire short circuits, etc. shall result in the least critical of all possible new conditions of the ship (fail to safety).

17.14.6 Power supply of electric propulsion plant control systems.

17.14.6.1 Power supply of the remote control system of electric propulsion plant shall be carried out in accordance with 3.1.2, Part XV "Automation".

17.14.6.2 Arrangements (units) of control or controllers of each electric propulsion motor or semiconductor frequency converter shall be supplied by separate circuits. Malfunction in the supply circuit of one of such control units shall not cause loss of power supply to the remaining operative units.

17.15 ELECTRIC COUPLINGS

17.15.1 General.

17.15.1.1 Electric couplings shall be designed so that they may be dismantled without the disassembly of a driving motor or reduction gear. The design and location of couplings shall ensure free access for their maintenance, brush replacement and air gap measurements without dismantling the couplings.

17.15.1.2 Enclosures and end shields shall be made of steel or material of equivalent strength (refer also to 10.1.1).

17.15.1.3 The rotating parts of couplings, as well as their windings shall be designed and secured so that they cannot be damaged in the event of a sudden stop. Electric couplings shall not cause axial forces. Balance ratio of electric couplings shall meet the requirements of 4.1.2, Part IX "Machinery".

17.15.1.4 The maximum torque under excitation forcing conditions shall not exceed the twofold rated torque of the coupling.

The requirements of this Chapter also apply to electric couplings fitted in other systems.

17.15.2 Protection and interlocking.

The design of the coupling connection system or the interlock used shall be such that the coupling excitation during the main propulsion engine starting and reversing is prevented.

Where several driving motors operate on a common transmission, in order to prevent the simultaneous start of driving motors rotating in opposite directions, the interlock in the coupling excitation system shall be used.

17.15.3 Electric couplings excitation.

Excitation windings of electric couplings shall be protected against overvoltage.

The excitation circuit of electric couplings shall include:

.1 a two-pole switch;

.2 a magnetic field discharging device;

.3 short-circuit protection.

17.16 ELECTRIC PROPULSION PLANTS USING ACCUMULATOR BATTERIES TO SUPPLY ELECTRICAL EQUIPMENT

17.16.1 If an electric propulsion plant meets the requirements of this Chapter, the descriptive notation **Battery system** shall be added to the character of classification.

17.16.2 The requirements of this Chapter apply to:

.1 ships in which the accumulator batteries are the only source of electrical power for electric propulsion plant equipment;

.2 ships in which the accumulator batteries are one of the sources of electrical power for electric propulsion plant equipment;

.3 ships with operation mode when the electrical equipment of electric propulsion plant is supplied only from accumulator batteries and, at that, there is another source of electrical power in stand-by mode.

17.16.3 In addition to the requirements of this Chapter, accumulator batteries used to supply the electrical equipment of electric propulsion plants shall meet the requirements of Sections 13 and 26.

17.16.4 If a ship is fitted with an emergency source of electrical power required in accordance with 9.1.1, it shall be independent of accumulator battery used to supply the electrical equipment of electric propulsion plant.

17.16.5 To assign additional descriptive notation **Battery system** to a ship in the class notation, the following technical documentation (Ag — for agreement, FI — for information) shall be submitted:

.1 calculation of the capacity of accumulator batteries designed to supply the electrical equipment of electric propulsion plants (Ag);

.2 analysis of failures regarding supply of electrical equipment and operating capacity of electric propulsion plants (Ag);

.3 information on noxious substances that are contained or may be evolved when using accumulator batteries (FI);

.4 list of alarms directly related to accumulator batteries and associated shipboard systems, if any (Ag);

.5 substantiation of fire extinguishing system choice (Ag);

.6 operation manual for accumulator batteries and their control systems (FI);

.7 risk analysis (Ag) (when lithium accumulator batteries are used) containing the following risks of:

thermal runaway;

internal short circuit;

external short circuit;

failure of sensors (voltage, temperature, gas sensor, etc.);

increase of impedance (of accumulator battery elements, connecting members, etc.);

loss of cooling;

leakages (electrolyte, cooling system);

failure of accumulator battery control system (faults when controlling the circuit breakers, overloads, overdischarge, etc.);

external penetration (fire, fluid leak, water for fire fighting, etc.)

17.16.6 The compartment for accumulator batteries used to supply the electrical equipment of electric propulsion plant shall be equipped with ventilation system complying with the requirements of 13.4 and 26.10.1.

17.16.7 In normal operating conditions sea water shall not penetrate the compartment for accumulator batteries.

Piping systems that are not used in operation of accumulator batteries shall not be located in the compartment of accumulator batteries. The specified location may be admitted if the following minimum conditions are met:

compartment for accumulator batteries is equipped with the means of effective fluid leakage detection;

pipes are welded inside accumulator compartment;

no flammable liquids are conveyed through the piping;

only pipes of Class III in accordance with 1.3.2, Part VIII "Systems and Piping" are admitted.

17.16.8 Arrangement of accumulator batteries shall meet 13.2 and 26.10.

17.16.9 Cabinets where accumulator batteries are arranged shall have hatches for access to the accumulator batteries preventing penetration of foreign objects on the elements of accumulator batteries, connecting members and cooling systems, if installed.

17.16.10 In case the compartment for accumulator batteries are considered as hazardous zone in accordance with international standards of series IEC 60079, this compartment shall be covered with antistatic coatings.

Compartments where lithium accumulator batteries are arranged may not be covered with antistatic coatings provided it has been confirmed by the risk analysis required in accordance with 17.16.5.7.

17.16.11 A possibility for access to the compartment of accumulator batteries shall be provided to carry out general maintenance and safe repair of elements of accumulator batteries.

17.16.12 Accumulator batteries shall be cooled by ventilation of the compartment where they are arranged or by direct cooling by means of special circuit of the cooling system.

If direct cooling is provided, the following alarms shall be provided where necessary:

high temperature of cooling air for accumulator batteries with mechanical ventilation;

flow reduction of the primary and secondary cooling agent of accumulator batteries having closed-circuit cooling system with heat exchanger.

As an alternative to air temperature and cooling agent flow of accumulator batteries, the control of supply discontinuity for ventilator electrical drive may be applied.

17.16.13 Protection degree of accumulator batteries shall be provided depending on the place of their arrangement. Minimum necessary protection degree shall be:

IP 2X for accumulator batteries with voltage of less than 1500 V;

IP 32 for accumulator batteries with voltage of 1500 V and above.

17.16.14 Lithium accumulator batteries.

17.16.14.1 Lithium accumulator batteries shall be charged and discharged by means of control system which provides:

.1 monitoring over condition of accumulator battery on the level of at least of modules, units and subunits at least by voltage, temperature and, if necessary, monitoring over current flow and detection of current leakage;

.2 assessment of potential necessity to connect or disconnect the unit or subunit of batteries by determining if the unit or subunit is in critical condition in case of a request from power control system or any other connected control system;

.3 control of correct connection and disconnection of units and subunits of accumulator batteries;

.4 optimization of battery service life and power accessibility by means of monitoring and control over charging condition and serviceability of accumulator battery, cell control, units and subunits balance as well as monitoring and control of accumulator battery maintenance system.

17.16.15 Compliance of the fire extinguishing system with the battery type shall be confirmed in the document specified in 17.16.5.5.

18 ADDITIONAL REQUIREMENTS FOR ELECTRICAL EQUIPMENT DESIGNED FOR A VOLTAGE IN EXCESS OF 1000 V UP TO 15 KV

18.1 GENERAL

18.1.1 The requirements apply to three-phase a.c. systems with the rated voltage in excess of 1 kV where the rated voltage means the voltage between phases.

Unless otherwise specified in this Section, the requirements for design and installation for low-voltage equipment (up to 1000 V) given in this Part also apply to high-voltage equipment.

18.1.2 Electrical equipment for a voltage over 1000 V shall not be housed in the same casing (enclosure) with low-voltage equipment unless the relevant segregation is provided or appropriate measures ensuring safe access for low-voltage equipment maintenance are taken.

18.1.3 Insulating materials used for electrical equipment shall ensure the insulation resistance of 1500 ohms per 1 V rated voltage, but at least 2 megohms during the unit operation.

18.1.4 For monitoring of insulation status the systems for each feeder insulation monitoring shall be used. Such systems shall show direction to the damaged area and have visible and audible alarm at decreasing of the monitored value below the specified level. It is recommended to complete feeder monitoring systems with portable devices for search of insulation fault location.

18.1.5 At the entrance to special electrical spaces, a warning notice shall be provided indicating the voltage. Enclosures of electrical equipment installed outside special electrical spaces shall be provided with warning notices indicating the voltage.

18.2 SYSTEM DESIGN

18.2.1 Distribution design.

18.2.1.1 The following power distribution systems may be used for three-phase a.c. current high-voltage plants:

insulated three-wire system;

three-wire system with the neutral earthed to the ship's hull through a high-capacity resistor or reactor;

four-wire system with the deadly earthed neutral.

18.2.1.2 Configuration of network for ensuring uninterruptible power supply.

The main switchboard design shall provide for the possibility of its separation into, as a minimum, two independent parts by means of a circuit breaker or disconnector.

Each part of sections shall be connected to, as a minimum, one generator.

Where two independent main switchboards interconnected by cable jumpers are provided, circuit breakers shall be fitted at its both sides. All the duplicated electrical drives shall be supplied from different main switchboards or its split sections.

18.2.1.3 Systems with earthed neutral.

18.2.1.3.1 Neutral points of generators running in parallel may be connected to a common bus before an earthing resistor or reactor fitted in a switchboard or immediately at the generators.

18.2.1.3.2 In case of an earth fault, the leakage current shall not exceed the rated current of the largest generator or the total rated current of a relevant main switchboard section and shall not be less than the triple minimum current required for earth-fault protection activation.

18.2.1.3.3 When the system is energized, at least one neutral earthing point shall be closed. The electrical equipment in systems with a deadly earthed neutral connected to the hull through a high capacity resistor or reactor shall bear without damage the single plase-to-earth fault current during the time needed for protection device activation.

18.2.1.4 Neutral opening.

In the neutral wire of each generator, provision shall be made for a disconnector, which may cut out the neutral from earthing for insulation resistance measurements and generator maintenance.

18.2.1.5.1 All earthing impedances of neutral points shall be connected to the hull. The connection to the hull shall be so arranged that any circulating currents in the earth connections do not interfere with radio, radar, intercommunication and control equipment circuits.

18.2.1.5.2 It is allowed to connect all resistors or reactors to the common earthing busbar, which shall be connected to the ship's hull at least at two points.

18.2.1.6 Divided systems.

18.2.1.6.1 Neutral connections to the hull shall be provided for each split group of main switchboard sections in divided systems with an earthed neutral.

18.2.2 Degrees of enclosures protection.

18.2.2.1 General requirements.

Each part of electrical equipment shall have shielded enclosures corresponding to its location and effecting environmental conditions. The requirements of IEC 60092-201:2019 may be considered as minimum.

18.2.2.2 Electrical machines.

A degree of protection by enclosure for electrical machines shall be at least IP23. The degree of protection of machines lead boxes shall not be less than IP44.

Motors installed in spaces accessible to unqualified personnel shall have the degree of protection of at least IP4X to prevent touching of live and rotating parts.

18.2.2.3 Transformers.

A degree of protection by enclosure for transformers shall be at least IP23.

Transformers installed in spaces accessible to unqualified personnel shall have the degree of protection of at least IP4X.

The requirements of 18.7.1 apply to transformers having no enclosure.

18.2.2.4 Switchgear, control panels and converters.

A degree of metal enclosures protection for switchgear, control panels, static converter cabinets shall be at least IP32. Panels installed in spaces accessible to unqualified personnel shall have the degree of protection of at least IP4X.

18.2.3 Insulation distances.

18.2.3.1 Air clearances.

Air clearances between live parts with different potentials or between live parts and earthed metal parts or the casing shall not be less than specified in Table 18.2.3.1.

Table 18.2.3.1

Nominal voltage, kV	Minimum air clearance, mm
3 (3,3)	55
6 (6,6)	75
10 (11)	120
15	160

Minimum clearances for intermediate values of working voltages are assumed as for the next larger value of a standard voltage.

Selecting lesser clearance, special high-voltage impulse tests shall be made to confirm admissibility of such an option.

18.2.3.2 Creepage distances.

Creepage distances between live parts with different potentials and between live parts and the hull shall be selected on the basis of national and international standards with due regard to the rated voltage of the system, insulation material and dynamic overvoltage due to transient processes.

18.2.4 Protective devices.

18.2.4.1 Faults on the generator side.

In addition to the types of protection specified in 8.2, generators shall be provided with protection devices against an interphase fault in the cables connecting the generator and main switchboard, and against turn-to-turn faults inside the generator.

When this protection device is activated, the generator shall be shut off from the main switchboard and its excitations shall automatically be removed.

In distribution systems with deadly earthed neutral, the earth fault of a generator phase shall also result in the activation of protection.

18.2.4.2 Faults to earth.

18.2.4.2.1 An audible and visual alarm shall be activated in a system at any earth faults.

18.2.4.2.2 Protection automatically disconnecting a faulted circuit at earth faults shall be activated in low-impedance (deadly-earthed) systems.

18.2.4.2.3 In high-impedance earthed systems (systems with a neutral earthed through a high-resistance resistor), where the feeders outgoing from the main switchboard cannot be disconnected at an earth fault, the insulation of electrical equipment supplied from these feeders shall be designed for the line voltage of the system.

Notes: 1. The systems to be classified as effectively earthed (low impedance) if a coefficient of earthing is below 0,8, and ineffectively earthed (high impedance), 0,8 and over.

2. The efficient of earthing means a ratio between a voltage "phase — earth" in a healthy, i.e. intact phase and a line ("phase — phase") voltage.

18.2.4.3 Power transformers.

Power transformers shall be protected against a short circuit and overloading with circuit breakers.

Where the transformers are intended for running in parallel, the activation of protection on the primary side shall cause their automatic disconnection on the secondary side as well.

18.2.4.4 Voltage transformers for control systems and instruments.

Transformers intended for supply of control circuits and instruments shall be protected against overloading and short circuits on the secondary side.

18.2.4.5 Fuses.

Protective fuses shall be used for short-circuit protection.

No fuses for overload protection are allowed.

18.2.4.6 Low-voltage systems.

Low-voltage distribution systems (up to 1000 V) supplied from high-voltage transformers (systems) shall be protected against overvoltages associated with the ingress of a high voltage on the secondary (low voltage) side. This may be achieved by:

earthing of the low voltage system;

appropriate neutral voltage limiters;

earthed screen between the primary and secondary windings of the transformer.

18.2.4.7 Protective earthing.

Metal enclosures of electrical equipment shall be earthed by external flexible copper conductors having a cross-sectional area designed for a single-phase short-circuit current, but not less than 16 mm^2. Earthing wires shall be marked.

Earthing conductors may be connected by welding or by bolts of at least 10 mm in diameter.

18.3 ELECTRICAL MACHINES

18.3.1 Stator windings of generators.

Generator stator windings shall have accessible both phase and neutral ends to ensure the installation of the differential protection.

18.3.2 Temperature detectors.

Electrical machines shall be fitted with built-in temperature detectors in their stator windings to actuate an audible and visual alarm whenever the temperature exceeds the permissible limit.

For built-in temperature detectors, means shall be provided to protect measurement circuits against overvoltage.

18.3.3 Tests.

In addition to the tests required for all electrical machines, high-frequency testing voltage tests, in accordance with IEC 60034-15, of individual phase windings (coils) of the machine shall be provided to demonstrate a satisfactory level of resistance to turn-to-turn faults caused by step-fronted switching surges.

18.3.4 Design.

18.3.4.1 A machine casing, bearing shields, guards of air intakes and outlets shall be made of steel alloys. Aluminium alloys for the above parts are not allowed.

18.3.4.2 A draining arrangement readily accessible for maintenance shall be provided in the lower part of a machine casing for removal of condensate.

Vertically-designed motors shall be fitted on their top with a rigidly secured canopy preventing the ingress of water and foreign objects inside the machine. A lower end shield shall be shaped so as to prevent accumulation of water in way of a bearing.

18.3.4.3 Lead boxes of machines shall be dimensioned so as to ensure:

necessary insulation distances between current-carrying parts and the casing;

a sufficient space for arrangement of connecting cable terminations and windings ends.

An individual terminal box shall be provided for instrument current transformers, heating anticondensation elements, temperature detectors, etc.

18.3.4.4 The leads of stator winding phases shall enter a separate terminal box, which is different from the ones for lower voltages, through a sealing gasket.

A separate terminal box may be provided for neutral leads.

Terminals for earthing cable cores shall be provided inside terminal boxes. In this case, a reliable electrical connection between a machine casing and box body shall be ensured.

18.3.4.5 Motors having the rated power 2000 kW and over shall be fitted with differential protection devices. For this purpose, a separate lead box shall be provided on a motor casing, located on the opposite side from the main box, in which a sufficient space for three current transformers and leads of neutral winding ends shall be provided.

In case of the impossibility, due to the small size of the engine room, to mount the above-mentioned lead box on the opposite side from the main box, the said box may be mounted at any convenient place on the motor casing.

18.3.4.6 Bearings temperature of motors with power of 1000 kW and over shall be monitored by local indicators (devices). Temperature detectors for remote control shall also be provided for each bearing.

18.3.4.7 In order to prevent the harmful effect of bearing currents, the bearing on the side opposite to a drive shall be electrically isolated from a casing. The possibility of measuring insulation resistance of an isolated bearing without its disassembly shall be provided.

18.3.4.8 The design of plain bearings shall provide:

.1 local indicators of the lube oil level;

.2 separate pump with a local pipeline, tank, cooler, filter and flow-rate indicator when forced circulating lubrication is used;

.3 potential fitting of instruments for vibration control, including pertinent cable lines, as well as of instruments for bearing wear measurements;
.4 potential use of the motor starting interlock when lubrication fails.

18.4 POWER TRANSFORMERS

18.4.1 General.

18.4.1.1 Dry-type transformers shall meet the requirements of IEC 60076-11:2018.

Dry-transformers in use shall have earthed screens between high and low voltage windings.

Liquid-cooled transformers shall meet the requirements of applicable parts of IEC 60076.

Oil-immersed transformers shall, as a minimum, be provided with the following alarms and protections:

"minimum liquid level" — alarm and automatic trip or load reduction;

"maximum liquid temperature" — alarm and automatic trip or load reduction;

"high gas pressure in enclosure" — automatic trip.

18.4.1.2 Transformers located in spaces accessible to unqualified personnel shall have a degree of protection provided by enclosure of at least IP4X.

18.4.1.3 Where the low-voltage side of transformer has an insulated neutral point, a spark fuse shall be inserted between the neutral point of each transformer and ship's hull.

The fuse shall be rated for not more than 80 % of the minimum test voltage of services fed through the given transformer.

18.4.1.4 The equipment for monitoring the condition of insulation on the lower-voltage side of the unit or for detecting locations of this insulation damages may be connected to the fuse in parallel. This equipment shall not interfere with the reliable operation of the fuse.

18.4.1.5 Effective means (e.g. heating) shall be provided to prevent condensation and moisture accumulation inside the transformers when de-energized.

18.4.1.6 Use of aluminium as material for the transformer windings is permitted provided the following conditions are met:

.1 provision is made for protection of the windings and their outlets from the corrosion in the conditions of the open sea;

.2 provision is made for protection from galvanic corrosion at the joints of the windings with current carrying parts made from other materials;

.3 joints indicated in 18.4.1.6.2 are accessible for inspection and protected from loosening.

18.5 CABLES

18.5.1 General.

18.5.1.1 Cables shall be constructed in accordance with the requirements of IEC 60092-353:2016 and 60092-354:2020 or other equivalent standards.

18.5.1.2 For three-phase cable systems, triple-core cables with multiwire cores shall be used. The cross-sectional area of the cable conductor for power circuits shall be at least 10 mm^2.

18.6 SWITCHGEAR AND CONTROLGEAR ASSEMBLIES

18.6.1 General.
Switchgear and controlgear assemblies shall be constructed according to IEC 62271-200:2011 and the following additional requirements.
18.6.2 Construction.
18.6.2.1 Mechanical construction.
18.6.2.1.1 Switchgear shall be of the metal-enclosed type in accordance with the requirements of IEC 62271-200:2011, or of the insulation-enclosed type in accordance with the requirements of IEC 62271-201:2014, or in accordance with the requirements of national standards.
18.6.2.1.1.1 Switchboards shall be locked with a special key other than for lower-voltage switchboards and switchgear. Opening of doors and withdrawal of separate part shall be possible only after disconnection of the panel or switchboard from the electric network.
18.6.2.1.1.2 Passageways for a switchboard and electrical equipment inspection at least 800 mm wide and 1000 mm wide between the bulkhead and switchboard, and between parallel switchboard sections respectively, shall be provided along the switchboards. Where intended for maintenance, their width shall be increased up to 1000 mm and 1200 mm respectively.
The specified width of these passageways is required irrespective of the applied means of protection against contact, like doors, net or insulated guardrails.
The doors, continuous bulkheads and net screens shall be at least 1800 mm high.
The perforated bulkheads or net screens shall ensure a degree of protection not below IP2X.
Insulated guardrails shall be provided on the front side of all main and emergency switchboards. Where the access is required behind these switchboards for their operation or technical maintenance, insulated guardrails shall be installed on the back side of these switchboards.
18.6.2.1.1.3 Live parts of electrical installation shall be located at a distance specified in Table 18.6.2.1.1.3 away from protection guards.

Table 18.6.2.1.1.3

Nominal voltage, kV	Minimum height of passageway, mm	Minimum distances of live electrical parts from various protection guards, mm		
		solid doors and continuous	bulkheads net doors and screens	insulated guardrails
3 (3,3)	2500	100	180	600
6 (6,6)	2500	120	200	600
10 (11)	2500	150	220	700
15	2500	160	240	800

18.6.2.2 Locking facilities.
Withdrawable circuit breakers used in switchboards shall be provided with mechanical locking facilities in both service and disconnected positions. For maintenance purposes, key locking of withdrawable circuit breakers and other equipment and fixed disconnectors shall be provided.
Withdrawable circuit breakers shall be located in the service position so that there is no relative motion between fixed and moving portions.
18.6.2.3 Shutters.
The fixed current-carrying contacts of withdrawable circuit breakers shall be automatically covered by insulating shutters when the circuit breaker is drawn out. Insulating shutters for incoming and outgoing circuits may be done by using colours or labels.

18.6.2.4 Earthing and interphase fault devices.

In order to ensure the safe maintenance of high-voltage switchgear, an adequate number of devices for forced busbar fault and earthing for busbars and outgoing feeders shall be provided.

18.6.2.5 Internal arc classification (IAC).

Switchgears and controlgear assembles shall be classified according to internal arc classification.

Where switchgear is accessible by authorized personnel only Accessibility Type A is sufficient. Accessibility Type B is required if accessible by non-authorized personnel (refer to IEC-62271-200:2011, Annex AA; AA2.2).

Installation and arrangement of the switchgear and contourgear shall comply with their IAC and arrangement (F — Front side; L — Lateral side; R — Rear side).

18.6.3 Auxiliary supply system.

18.6.3.1 Source of supply.

Where a separate auxiliary electrical or other source of power is required for operation of circuit breakers and other switches, and also for protection devices, in addition to such a main source, a stand-by one, which an energy supply shall be sufficient for at least two operations of all the components, shall be provided.

However, the circuit breaker releases activated due to overload, short-circuit or undervoltage shall be independent of any electrical sources of power.

The requirements does not preclude using the releases activated by an operating voltage, provided that the control of tripping circuits and their supply system integrity (continuity) will be ensured, i.e. if the integrity of the circuits is broken or their supply system is faulty (fails), an alarm will be activated.

18.6.3.2 Number of supply sources.

At least one independent stand-by source of power supply for split main switchboards (refer to 18.2.1.1) for operation of circuit breakers and other switches, in addition to their own supply sources each fed from its own busbar system, shall be provided. Where necessary, an emergency source of electrical power intended for activation of the machinery installation from fully de-energized or dead ship condition may be used for this purpose.

18.6.4 High-voltage tests.

Every main and other switchboards shall be tested by a high voltage of standard frequency. The test procedure and voltage values shall meet the requirements of an appropriate national standard or IEC 62271-200:2011.

18.7 INSTALLATION

18.7.1 Electrical equipment.

18.7.1.1 Where high-voltage equipment is not contained but a special room forms the enclosure of the equipment, the access doors shall be so interlocked that they cannot be opened until the supply is isolated and the equipment earthed down.

At the entrance of the rooms or spaces where high-voltage equipment is installed, caution notes shall be placed, which indicate danger of high-voltage. The relevant free space shall be provided in the vicinity of high-voltage equipment to prevent significant potential hazard to the service personnel during the technical maintenance. In addition, the distance between the switchboard and the above ceiling/deck shall meet the requirements of internal arc classification in compliance with IEC-62271-200:2011.

18.7.1.2 Electrical equipment shall be in special electrical spaces and shall have a degree of protection at least IP23 (refer also to 18.6).

When justified, the equipment may be installed outside the above spaces provided its degree of protection is the last IP44 and access to current-carrying parts of the equipment will only be possible when the voltage is off and special tools are used.

18.7.1.3 A diagram of connections and a drawing of electrical equipment arrangement shall be available in the special electrical space.

18.7.2 Cables.

18.7.2.1 Cable run laying.

Cables shall not run through accommodation spaces. However, when required due to technological reasons, such laying is allowed in special enclosed transit systems (structures).

18.7.2.2 Segregation.

High-voltage cables shall be segregated from cables for voltage below 1000 V. In particular, they shall not be run in the same cable bunch, nor in the same ducts or pipes with cables for a voltage 1000 V and below.

Where high-voltage cables of different voltage ratings are installed on the same cable tray, the insulation distances between the cables shall not be less than those specified for a high-voltage cable according to 18.2.3.1.

18.7.2.3 Installation of cables.

High-voltage cables shall be laid in earthed metallic pipes or metallic ducts, or to be protected by earthed metallic enclosures.

Open installation of cables (on carrying pressed panels) is allowed if they have a continuous metallic armour, which shall be reliable and repeatedly earthed.

18.7.2.4 Cable terminations.

Terminations in all conductors of high-voltage cables shall be effectively covered with a suitable insulating material. In terminal boxes, if conductors are not insulated, phases shall be separated from earth and from each other by other by durable barriers of a suitable insulating material.

High-voltage cables, having a conductive layer between phases to control the electric field within the insulation, shall have terminations, which provide electric stress control.

Terminations shall be of the type compatible with the insulation and jacket material of the cable and to be provided with means for earthing all metallic shielding components (metallic tapes, wires, etc.).

18.7.2.5 Marking.

High-voltage cables shall be readily identifiable by suitable marking.

18.7.2.6 Tests after installation.

Before putting into service of a new high — voltage cable network or after its updating (repair or additional cables installation), each cable and its accessories (terminations, earthing ends, etc.) shall be tested by a high voltage.

Tests shall be carried out after an installation resistance measurement.

For the cables of a rated voltage ((U_o/U) above 1,8/3 kV (U_m = 3,6 kV) testing of electric strength of insulation shall be performed by a.c. testing voltage in compliance with the manufacturer's recommendations as follows:

a) during 5 min by phase-to-phase voltage of the system being applied between the cable core and a metal screen/braiding;

b) during 24 h by nominal voltage of the system.

Or by the d.c voltage being equal to $4U_o$ during 15 min.

For cables with nominal frequency (U_o/U) below 1,8/3 kV (U_m = 3,6 kV) testing of the electrical strength of insulation is made by d.c. voltage equal to $4U_o$ during 15 min.

where:

U_o is rated a.c. voltage of rated frequency for which the cable is intended applicable between the phase wires and earthing and a metal screen;

U is rated a.c. voltage of rated frequency for which the cable was intended applicable between the phase wires;

U_m is maximum voltage value in the high voltage system when the equipment capable for operation.

Upon testing, the cable cores shall be grounded for the certain period of time sufficient for removal of the obtained electric charge.

Then the repeated measurement of cable insulation resistance shall be made.

19 ADDITIONAL REQUIREMENTS FOR ELECTRICAL EQUIPMENT FOR A VOLTAGE OF 15 TO 220 KV

19.1 GENERAL

19.1.1 Application.

These requirements apply to three-phase alternating current systems with rated voltages from 15 kV to 220 kV, where rated voltage means the voltage between phases.

Requirements for design and installation of low voltage electrical equipment (up to 1000 V) set out in this part also apply to high voltage electrical equipment, unless specified otherwise in this Section.

19.1.2 Rated voltage of the system.

19.1.2.1 Rated voltages in electrical power distribution systems shall not exceed the values specified in Table 19.1.2.1.

Table 19.1.2.1

Rated interphase voltage, in kV	Rated frequency, in Hz
15	50 (60)
20	50 (60)
35	50 (60)
110	50 (60)
150	50 (60)
220	50 (60)

19.1.3 Dividing of high voltage and low voltage equipment.

19.1.3.1 Electrical equipment for voltages in excess of 1000 V shall not be installed in the same housings (enclosures) as low voltage equipment unless suitable separation is provided or suitable measures are taken to ensure safe access for the maintenance of the low voltage equipment.

19.1.3.2 Insulating materials for electrical equipment shall ensure the insulation resistance appropriate for the operating conditions of the equipment during the plant's continuous service.

19.1.3.3 Warning notices indicating the voltage value shall be provided at the entrance of special electrical spaces. Warning notices shall also be provided for enclosures of electrical equipment installed outside special electrical spaces.

19.2 SYSTEM DESIGN

19.2.1 Distribution systems.

The following systems of electrical power distribution are permitted for high voltage three-phase alternating current installations:

three-wire insulated system;

a three-wire system with the neutral point connected to the ship hull via a high-value resistor or reactor;

three-wire system with effectively earthed neutral;

three-wire system with a dead earthed neutral.

Two-wire system of electrical power distribution is permitted for high voltage direct current installations.

19.2.1.1 Configuration of 15 — 35 kV network for ensuring uninterruptible power supply.

The main switchboard design for distribution boards of 15, 20, 35 kV shall provide for the possibility of its separation into, as a minimum, two independent parts by means of a circuit breaker or disconnector.

Each part of sections shall be connected to, as a minimum, one electric power source of the appropriate voltage.

Where two independent main switchboards interconnected by cable jumpers are provided, circuit breakers shall be fitted at its both sides. All the duplicated electrical drives shall be supplied from different main switchboards or split sections of the main switchboard.

19.2.1.2 Configuration of 35 — 220 kV network for ensuring uninterruptible power supply.

For integrated gas-insulated switchgear (GIS), in general, the same circuits are used as for open switchgear of the appropriate voltage except where deviations in the circuits are caused by a process necessity, higher reliability, etc.

In GIS (gas-insulated switchgear) the main elements of the circuit, including the apparatus (switches, disconnectors, earthing switches, measuring instruments, etc.) and collecting busbars shall be enclosed in a gas-tight aluminium alloy enclosures, which constitute a complete assembly unit-modules. The individual hardware modules (units) shall be connected to each other by gas-tight flange connections. A set of the specified modules representing a complete circuit chain is called a cell. The switchgear (GIS) is assembled from cells and individual modules.

The following circuits specified in Appendix 1 to this Section shall be used to organize the 110 kV switchgear:

unit (line — transformer) with disconnectors (refer to Fig. 1 (diagram 110-1));

unit (line — transformer) with switcher (refer to Fig. 2 (diagram 110-3N));

two units with switchers and non-automatic jumper at the line side (refer to Fig. 3 (diagram 110-4N));

bridge with switchers in the line circuits and repair jumper at the line side (refer to Fig. 4 (diagram 110-5N));

bridge with switchers in the transformer circuits and repair jumper at the transformer side (refer to Fig. 5 (diagram 110-5AN));

entry — termination (refer to Fig. 6 (diagram 110-6));

triangle (refer to Fig. 7 (diagram 110-6N));

quadrangle (refer to Fig. 8 (diagram 110-7));

hexagon (refer to Fig. 9 (diagram 110-8));

one operating busbar sectioned by the switcher (refer to Fig. 10 (diagram 110-9));

one operating busbar sectioned by the transformer number, with connecting the transformers to bus sections via the switcher junction (refer to Fig. 11 (diagram 110-9N));

two operating busbars (refer to Fig. 12 (diagram 110-13));

The following curcuits shall be used to organize the 220 kV switchgear (refer to Appendix 1):

unit (line — transformer) with disconnectors (refer to Fig. 13 (diagram 220-1));

unit (line — transformer) with switcher (refer to Fig. 14 (diagram 220-3N));

two units with switchers and non-automatic jumper at the line side (refer to Fig. 15 (diagram 220-4N));

bridge with switchers in the line circuits and repair jumper at the line side (refer to Fig. 16 (diagram 220-5N));

bridge with switchers in the transformer circuits and repair jumper at the transformer side (refer to Fig. 17 (diagram 220-5AN));

entry — termination (refer to Fig. 18 (diagram 220-6));

triangle (refer to Fig. 19 (diagram 220-6N));

quadrangle (refer to Fig. 20 (diagram 220-7));

hexagon (refer to Fig. 21 (diagram 220-8));

one operating busbar sectioned by the switcher (refer to Fig. 22 (diagram 220-9));

one operating busbar sectioned by the transformer number, with connecting the transformers to bus sections via the switcher junction (refer to Fig. 23 (diagram 220-9N));

two operating busbars (refer to Fig. 24 (diagram 220-13));

transformer busbar with one-and-a-half line connection (refer to Fig. 25 (diagram 220-16));

one-and-a-half breaker circuit (refer to Fig. 26 (diagram 20-17)).

High speed earthing switches shall be provided at GIS line entries.

GIS shall be connected to transformers by cables or closed gas-insulated current leads to avoid overhead entries.

The need for an excess-voltage suppressor in GIS circuits is determined by overvoltage calculations during design.

19.2.1.3 Neutral earthing systems.

It is recommended to make a 20 kV network with neutral earthed through a resistor. In this case, a step-down transformer with a "star — star" winding connection with a resistor in the neutral of the 20 kV winding is used or a special "star — delta" transformer connected to the 20 kV switchgear busbars with a grounding resistor in the"star" neutral is used.

To ensure the selectivity of the operation of the relay protection, the resistance of the earthing resistor shall be such that the single-phase fault current in the 20 kV network is at least 1000 A.

It is permitted to perform 20, 35 kV switchgear circuit with neutral earthing through an arc suppression reactor.

19.2.1.4 Systems with earthed neutral.

19.2.1.4.1 Shall be provided with deadly earthed neutrals:

.1 110 — 150 kV transformers with on-load tap changers (OLTC) with 35 kV neutral insulation level (50 Hz neutral test voltage is equal to 85 kV);

.2 transformers with generating sources on the low- or medium-voltage side, irrespective of the neutral insulation class. Part of the neutrals of such transformers may be ungrounded if, during maintenance or emergency modes, it is not possible to separate them for operation with a network section without transformers with earthed neutrals, or if disconnection of the transformers with insulated neutral points during earth faults before disconnection of the transformers with earthed neutral points is ensured.

At that, neutrals with incomplete insulation shall be protected by suitable surge arresters/surge suppressors.

19.2.1.4.2 Neutral winding protection for 110 kV and 150 kV transformers shall be provided by a valve arrester: RVS35 + RVS15 or RVM35 + RVM15 for 110 kV transformers and RVS 60 (2RVS20 + RVS15) or 2RVM35 (four components) for 150 kV transformers.

Valve-type arresters for neutral line protection shall be located immediately at the transformers.

19.2.1.4.3 When the system is energized, at least one neutral earthing point shall be closed.

The electrical equipment in systems with a deadly earthed neutral connected to the hull through a high capacity resistor or reactor shall bear without damage the single phase-to-earth fault current during the time needed for protection device activation.

19.2.1.5 Neutral opening.

If a transformer with an incomplete neutral-point insulation is being switched on or off, its neutral shall be earthed during the operation. All new power transformers with a neutral insulation level in accordance with IEC 60076-3 shall provide for operation with both insulated and earthed neutral, for which a ZON-110 (transformer neutral earthing switch) and an arrester shall be installed in their neutral points.

19.2.2 Degrees of enclosures protection.

19.2.2.1 Each part of electrical equipment shall have shielded enclosures corresponding to its location and effecting environmental conditions. The requirements of IEC 60092-201 may be considered as minimum.

19.2.2.3 A protection degree of transformer enclosures shall be at least IP23.

Transformers installed in spaces accessible to unqualified personnel shall have the degree of protection of at least IP4X.

The requirements of 18.7.1 apply to transformers having no enclosure.

19.2.2.4 A degree of metal enclosures protection for switchgear, control panels, static converter cabinets shall be at least IP32. Panels installed in spaces accessible to unqualified personnel shall have the degree of protection of at least IP4X.

19.2.3 Insulation clearances.

19.2.3.1 Air clearances.

The air clearance between live parts with different potentials or between live parts and earthed metal parts or the casing shall be not less than that specified in Table 19.2.3.1.

Table 19.2.3.1

Rated interphase voltage, in kV	Minimum air clearance, in mm
15	160
20	180
35	290
110	700
150	1100
220	1700

Minimum clearances for intermediate values of working voltages are assumed as for the next larger value of a standard voltage.

If selecting lesser clearance, special high-voltage impulse tests shall be conducted to confirm admissibility of such an option.

19.2.3.2 Creepage clearances.

Creepage clearances between live parts with different potentials and between live parts and the hull shall be selected on the basis of national and international standards.

19.2.4 Protection devices.

19.2.4.1 Faults to earth.

19.2.4.1.1 An audible and visual alarm shall be activated in a system (on control panels) at any earth faults.

19.2.4.1.2 Protection automatically disconnecting a faulted circuit at earth faults shall be activated in low-impedance (deadly-earthed) systems.

19.2.4.1.3 In high-impedance earthed systems (systems with neutral earthed through a high-capacity resistor), where the feeders outgoing from the main switchboard cannot be disconnected at an earth fault, the insulation of electrical equipment supplied from these feeders shall be designed for the line voltage of the system.

N o t e s : 1. The systems to be classified as effectively earthed (low impedance) if a coefficient of earthing is below 0,8, and ineffectively earthed (high impedance), 0,8 and over.

2. The efficient of earthing means a ratio between a voltage "phase — earth" in a healthy, i.e. intact phase and a line ("phase — phase") voltage.

19.2.4.2 Power transformers.

Power transformers shall be protected against a short circuit and overloading with automatic electrical switching devices (breakers).

Where the transformers are intended for running in parallel, the activation of protection on the primary side shall cause their automatic disconnection on the secondary side as well.

19.2.4.3 Voltage transformers for control systems and instruments.

Transformers intended for supply of control circuits and instruments shall be protected against overloading and short circuits on the secondary side.

19.2.4.4 Fuses.

Protective fuses shall be used for short-circuit protection. No fuses for overload protection are permitted.

19.2.4.5 Low-voltage systems.

Low-voltage distribution systems (up to 1000 V) supplied from high-voltage transformers (systems) shall be protected against overvoltages associated with the ingress of a high voltage on the secondary (low voltage) side.

This may be achieved by:

earthing of the low voltage system;

appropriate neutral voltage limiters;

earthed screen between the primary and secondary windings of the transformer.

19.2.4.6 Protective earthing.

Metal enclosures of electrical equipment shall be earthed with external flexible copper conductors having a cross-section designed for a single-phase short-circuit current, but not less than 16 mm^2. Earthing wires shall be marked.

Earthing conductors may be joined by welding or with bolts not less than 10 mm in diameter.

19.3 POWER TRANSFORMERS

19.3.1 General requirements.

19.3.1.1 Dry-type transformers shall meet the requirements of IEC 60076-11.

Dry-transformers in use shall have earthed screens between high and low voltage windings.

Liquid-cooled transformers shall meet the requirements of IEC 60076-1.

Oil-immersed transformers shall, as a minimum, be provided with the following alarms and protections:

"Minimum liquid level" — alarm and automatic trip;

"Maximum liquid temperature" — alarm and automatic trip or load reduction;

"High gas pressure in enclosure" — automatic trip.

19.3.1.2 Transformers located in spaces accessible to unqualified personnel shall have a degree of protection provided by enclosure of at least IP4X.

19.3.1.3 To protect transformer equipment against lightning overvoltages, arresters are installed on the high-voltage side as well as on the 6 — 10 kV side. The number of 35 — 220 kV arrester sets and their location are selected in accordance with the requirements of national standards, the level of test voltages of the equipment to be protected, based on the diagrams of electrical connections adopted for the design period, the number of cable lines and transformers (auto-transformers).

19.3.1.4 The neutral earthing mode of 110 — 150 kV high-voltage windings is selected taking into account the neutral insulation class, ensuring the earthing coefficient within permissible limits, permissible single-phase short-circuit currents in accordance with the equipment selection conditions, and the operation of relay protection and emergency automation.

19.3.1.5 Permanent neutral earthing shall be provided for all 220 kV auto-transformers and windings. 110 kV T winding neutrals which may be isolated from earth during operation shall be protected by surge arresters of the non-linear arrester or arrester-110 type with a limiting level coordinated with the isolation level of the neutral point to be protected.

19.3.1.6 In order to reduce single-phase short-circuit currents, the neutral point of a 220 kV auto-transformer may be earthed through low-resistance current-limiting resistors or reactors.

19.3.1.7 Provision shall be made for effective measures (e.g., heating) to prevent moisture condensation and accumulation inside the transformers when deenergized.

19.4 CABLES

19.4.1 General requirements.

Cables shall be constructed in accordance with the requirements of IEC 60840 and 62067 or other equivalent national standards.

19.4.1.1 For three-phase cable systems, triple-core cables with multiwire cores shall be used.

19.4.2 Requirements for underwater cables.

19.4.2.1 Conducting cores shall be class 1 or class 2, made of uncoated or metal-coated annealed copper in accordance with IEC 60228. All conductive cores require measures to achieve longitudinal watertightness.

19.4.2.2 The insulation of cables with voltages of 15 — 220 kV shall be made of cross-linked polyethylene or ethylene propylene rubber with a normal operating temperature not exceeding 90 °C.

19.4.2.3 The rated insulation thickness of cables shall comply with the requirements of IEC 60502-2, IEC 62067, IEC 60840 or shall be specified by the manufacturer.

19.4.2.4 The shielding of the individual wires of single-core and triple-core cables shall consist of a conductor core and an insulation shield.

19.4.2.5 The conductive core shield shall be non-metallic and shall consist of an extruded semi-conductive compound, which may be applied to the semi-conductive tape. The extruded semi-conductive compound shall have adhesion to the insulation.

19.4.2.6 The insulation screen shall consist of a non-metallic semi-conductive layer in combination with a metallic screen.

19.4.2.7 For optimal resistance to mechanical stresses during cable laying, the semi-conductive shields of underwater cables shall be adhesively bonded.

19.4.2.8 A layer of semi-conductive tape or semi-conductive compound may be applied separately to each wire or bundle of wires.

19.4.2.9 Metal shielding shall be applied to individual wires or to a bundle of wires and shall consist of one or more tapes, a braid, or a concentric layer of wire, or a combination of wire and tape(s), or a metal sheath.

19.4.2.10 Armour of power cables shall be made of round or flat wire; the wire shall be of galvanized or stainless steel, copper, tinned copper or other corrosion-resistant metal alloy. When selecting the armouring material, the possibility of corrosion shall be taken into account, not only for mechanical safety reasons, but also for electrical safety reasons.

19.4.2.11 The outer covering of cables shall be of textile origin or made as an extruded layer.

19.4.3 Requirements for the laying of underwater marine cables with a voltage of 15 kV — 220 kV when connecting fixed offshore platform consumers from external power supply sources.

19.4.3.1 The laying of underwater marine power cable lines in areas of regular ship moorings is not permissible.

19.4.3.2 Depending on the specific conditions of the site design, design solutions may include options for laying the cable directly on the bottom of the water body (both with and without cable protection by means of pipe work, rip-rap, etc.), with cable burial in the ground, using additional armouring.

The cable laying option and depth of cable laying shall be determined by the project taking into account data on depth, speed and way of water movement at the transition point, prevailing winds, bottom profile and chemical composition of the bottom, chemical composition of water. The minimum depth of burial in coastal areas and shallow water shall be at least 1 m.

19.4.3.3 Cable lines shall be laid on the bottom so that in uneven areas they are not suspended; sharp projections shall be eliminated. Banks, rock ridges and other underwater obstacles in the route shall be avoided or trenches or passages shall be provided in them.

19.4.3.4 Newly constructed underwater cable lines shall be laid at a distance of at least 1,25 m from existing cable lines, but not less than 20 m. This distance may be reduced with appropriate justification during the project documentation development.

19.4.3.5 The horizontal distance from cables buried in the bottom of water bodies to pipelines (oil and gas pipelines, etc.) shall be determined by the project, depending on the type of dredging carried out when laying pipelines and cables, and shall be at least 50 m. This distance may be reduced to 15 m by agreement with the organizations in charge of the cable lines and pipelines.

19.4.3.6 On shores without improved embankments at the point of underwater cable crossing, a reserve of at least 30 m in length shall be provided for offshore laying, which shall be laid in a figure-eight fake pattern. Improved embankment cables shall be laid in pipes. Cable wells shall be provided at the cable exit point. The upper pipe end shall enter the onshore well and the lower end shall be at least 1 m deep from the lowest water level. On shore sections, the pipes shall be firmly sealed.

19.4.3.7 In areas where cables come ashore and are exposed to shore scouring, measures shall be taken to prevent exposure of cables during ice drifts and floods by strengthening the shores (patching, berms, piles, sheet piles, slabs, etc.).

19.4.3.8 Crossing of underwater marine cables with each on subsea sections is prohibited.

19.4.3.9 Justification for the choice of cable line technology is determined by the project and shall be justified both in terms of safe construction technology and in terms of the least manmade impact on the ecosystem of the water body.

19.4.3.10 Cable lines shall be so constructed that dangerous mechanical stresses and damage are avoided during installation and operation, to ensure which:

cables shall be laid with a length allowance sufficient to compensate for possible ground movements and thermal deformations of the cables and the structures through which they are laid; Laying cable allowance in the form of rings (coils) is prohibited;

it is necessary to provide a cable length margin for re-terminating or replacing the cable sleeves;

cables laid horizontally or vertically on structures, walls and ceilings shall be rigidly fixed at the end points, directly at the sleeves, on both sides of the bends, and on straight sections as designed, but at least every 1 m (this distance may vary by agreement with the manufacturer);

110 — 220 kV cable lines may not be co-located in cable structures with cable lines below 110 kV with the exception of 0,4 kV cables for technological needs;

it is not permitted to lay 110 — 220 kV cable lines together with heating pipelines and other utility lines.

19.4.3.11 When laying cable lines, the three phase cables shall be laid in parallel and arranged in a triangle or in the same plane. Other layouts are possible and shall be justified and agreed upon with the cable manufacturer.

19.4.3.12 Individual cables (not connected in a triangle) shall be laid in such a way that there are no closed metal loops of magnetic materials around each cable. In this respect, the use of magnetic materials for banding, fastening or other products (brackets, clamps, sleeves, shields) covering the cable in a closed circuit is prohibited. Routing individual cables inside pipes made of magnetic materials (e.g. steel or cast iron) is prohibited. Cable labels shall be attached with capron, plastic strands or non-magnetic metal wires (e.g. made of stainless steel or copper).

19.4.3.13 During installation, cables shall not be subjected to mechanical stress beyond the cable design limits, including stretching, bending, torsion and crushing.

19.4.3.14 The protection of underwater cable lines may include the following means and combination thereof: additional armour, burial, protection without burial, including pipe work, mats and rip-rap.

19.4.3.15 Recommendations for running cables through walls and deck. In addition to the general requirements for the arrangement of cable routes, the following shall be taken into account:

integrity: the passageways shall meet the fire and watertightness requirements of the wall or deck;

thermal insulation: cable sections shall not be mounted in thermal protection or covered with thermal insulation, but they may pass through such insulation;

mechanical passageway supports: with the exception of the cable suspension system, the passageways shall be so designed that they do not accommodate forces resulting from movements, vibrations or temperature fluctuations of the offshore installation.

19.4.4 Selection of cable according to loads, selection of cross-sectional area for permissible voltage drop.

19.4.4.1 Calculation of the current rating of the cable shall be carried out in accordance with IEC 60287-1-1. The type of electric current to be transmitted (direct current, alternating current), the climatic conditions for cable laying and the nature of the ground shall be taken into account.

Calculation shall be carried out using the values of maximum permissible conductor temperature, conductor resistance, losses and thermal specific resistance. Next, the rated current load derived from the calculation is compared with the rated current load of the consumer/installation to be designed and a conclusion is made as to the suitability of the selected cable, or the need to recalculate based on the ratio:

$$I_{\text{length nom.calc.}} > I_{\text{length nom.inst.}},$$

where $I_{\text{length nom.calc.}}$ — rated current load for the cable line, obtained from the calculation of IEC 60287-1-1;

$I_{\text{length.nom.inst.}}$ — the rated current load of the consumer/installation being designed.

The calculation shall be adjusted subject to the conditions specified in 19.4.4.2 and 19.4.4.3.

For the calculation, the voltage deviation at the consumer/receiving unit shall not exceed 10 % of the standardized voltage level of the electrical consumer according to IEC 60038. The necessity of reducing the voltage deviation shall be substantiated by technological conditions as well as by national standards.

19.4.4.2 Calculation of losses due to eddy currents in metal sheaths of single-core cables laid in the same plane in two parallel three-phase networks shall be carried out in accordance with IEC 60287-1-2. This calculation is necessary for estimating the reduction of the current capacity for circuits laid in parallel. The type of cable sheathing, phase rotation, and geometric parameters of the cable line route shall be taken into account.

19.4.4.3 Calculation of current distribution between phase conductors of single-core cables arranged in parallel and losses due to circulating currents shall be carried out in accordance with IEC 60287-1-3. The type of cable sheathing, phase rotation, and geometric parameters of the cable line route shall be taken into account.

19.4.4.4 Calculation of ambient thermal resistances for different cable laying options (thermal resistance between single core and sheath, thermal resistance between sheath and armour, thermal resistance of outer protective covering) shall be performed in accordance with IEC 60287-2-1 and IEC 60287-2-2. The specified data shall be used to calculate the current capacity of the cable in accordance with the requirements of 19.4.4.1.

19.4.4.5 Reference operating conditions, deviations from these conditions and cable selection shall be carried out in accordance with the requirements given in IEC 60287-3-1.

19.4.4.6 Calculation of cables for cyclic and fault tolerance shall be carried out in accordance with IEC 60853-1 and IEC 60853-2. In carrying out this calculation, the ability of cable of the selected size to withstand potential short-circuit currents and earth faults of an appropriate duration is checked.

19.4.4.7 Calculation of thermally permissible short-circuit currents with respect to nonadiabatic/adiabatic heating and short-circuit temperature shall be carried out in accordance with IEC 60949. Once the calculation is completed, the maximum permissible core temperature for the cable insulation type in question is compared with the calculated core temperature based on the condition:

$$\theta_{f.calc.} < \theta_{f.max},$$

where $\theta_{f.calc.}$ – final temperature of the conductor during a steady-state short-circuit, °C;

$\theta_{f.max}$ – maximum permissible temperature of the conductive core during a steady-state short-circuit for a given cable type, °C.

19.4.4.8 Calculation of the economic cross-section of the cable and its selection in accordance with economic criteria shall be made in accordance with IEC 60287-3-2. The specified calculation and selection are carried out after calculation of the rated current load of the cable, the voltage drop in accordance with 19.4.4.1 and verification of the cable thermal and dynamic resistance in accordance with 19.4.4.6 in order to clarify the economic component of the design decisions.

19.5 SWITCHGEAR AND CONTROLGEAR ASSEMBLIES

19.5.1 General requirements.

Switchgear and controlgear shall be constructed in accordance with the requirements of IEC 60298. 110 — 220 kV GIS shall be manufactured in compliance with IEC 62271-203 and the following additional requirements.

19.5.2 Design.

19.5.2.1 Mechanical design.

Distribution boards shall be made of metal and be of closed type — in accordance with IEC 60298, or shall be made of insulating materials and be of closed type — in accordance with IEC 60466 or in compliance with the requirements of national standards.

19.5.2.1.1 Switchboards shall be locked with a special key other than those for low-voltage switchboards and switchgear. Opening of doors or drawing separate components out shall be possible only after disconnection of the panel or switchboard from the electrical power supply.

19.5.2.1.2 Passageways shall be provided along the switchboards for the switchboard (up to 35 kV inclusive) and electrical equipment inspection. Their width shall be at least 1000 mm between the bulkhead and switchboard, and at least 1200 mm between the parallel sections of the switchboard. Where such passageways are intended for maintenance, their width shall be increased up to 1200 mm and 1500 mm respectively.

The specified width of those passageways is required regardless of the type of contact protection means used like doors, guard nets and insulating rails.

Doors, continuous bulkheads and net screens shall be at least 1800 mm high.

Perforated bulkheads or net screens shall ensure the degree of protection not below IP2X.

Insulated handrails shall be fitted on the front side of the switchboards. Insulated handrails shall be fitted to the rear of such shields if it is necessary to access the rear of such shields for operation or maintenance.

Arrangement of the gas-insulated switchgear shall be symmetrical, i.e. all three phases of the same cell shall be adjacent to each other, with the possibility to extend the GIS in both directions to two cells, unless the design specification provides otherwise.

The width of the gangway along the cell poles (sufficient on the cell front side) for the transport of gas-handling, test equipment and dismantled switchgear components shall be at least 3 m for 110 kV GIS and 4 m — for GIS of 220 kV and above. Space shall be provided in the GIS room to accommodate the high-voltage test installation, dismantling and technological work on the equipment.

19.5.2.1.3 Live parts of the electrical installation shall be spaced from protective guards at a distance not less than that specified in Table 19.5.2.1.3.

Table 19.5.2.1.3

Rated voltage, in kV	Minimum height of the passageway	Minimum distance of live electrical parts from different types of safety barriers, in mm		
		Solid doors and partitions	Mesh doors and partitions	Insulating handrails
15	2500	160	240	800
20	2500	210	280	900
35	2500	320	390	1000
110	2500	730	800	1500
150	2500	1130	1200	1800
220	2500	1730	1800	2000

19.5.2.2 Interlocking devices.

Automatic withdrawable circuit breakers used in switchboards must be provided with a device for locking them both in the service and retracted positions. Locking keys and lockable disconnectors shall be provided to ensure safe maintenance of withdrawable switches and other apparatus.

The withdrawable circuit breakers shall be fixed in the operating position so that relative movements between the movable and fixed parts are avoided.

19.5.2.3 Shutters.

The fixed current-carrying contacts of withdrawable circuit breakers shall be automatically covered by insulating shutters when the circuit breaker is drawn out.

19.5.2.4 Earthing and interphase fault devices.

In order to ensure the safe maintenance of high-voltage switchgear, an adequate number of devices for forced busbar fault and earthing for busbars and outgoing feeders shall be provided.

The device shall be rated for the maximum short-circuit current.

19.5.3 Auxiliary supply system for switchgear.

19.5.3.1 Source of supply.

Where a separate auxiliary electrical or other source of power is required for operation of circuit breakers and other switches, and also for protection devices, in addition to the main source, a stand-by source with sufficient power supply for at least two operations of all the components shall be provided.

However, the circuit breaker releases activated due to overload, short-circuit or undervoltage shall be independent of any sources of electrical power.

This requirement does not preclude using shunt releases (releases activated by an operating voltage), provided that the control of tripping circuits and their supply system integrity (continuity) will be ensured, i.e. if the integrity of the circuits is broken or their supply system is faulty (fails), an alarm will be activated.

19.5.4 High-voltage tests.

Every main and other switchboards shall be tested by a high voltage of standard frequency. The test procedure and voltage values shall meet the requirements of an appropriate national standard or IEC 60298 and IEC 62271-203.

19.6 METAL SHEATHED 110 — 220 KV INTEGRATED GAS-INSULATED SWITCHGEAR (GIS)

19.6.1 General requirements.

Metal-sheathed 110 — 220 kV gas-insulated switchgear (GIS) shall be manufactured in accordance with IEC 62271-203 and the following additional requirements.

19.6.2 Design.

19.6.2.1 GIS shall be so designed as to ensure the safety of personnel during standard operation as well as during emergencies and repair work, including maintenance of switchgear, earthing of connected cables, identification of cable faults, voltage tests of connected cables or other apparatus and removal of dangerous electrostatic charges, and checking the phase sequence after installation or extension.

19.6.2.2 The unit design shall ensure that the agreed permissible foundation shifts and mechanical or thermal influences do not affect the equipment parameters. Compensators for mechanical displacements and expansions are placed where necessary to ensure GIS mechanical flexibility. All components with the same rating and design that may need to be replaced shall be interchangeable.

19.6.2.3 GIS shall be divided into compartments in such a way that normal operating conditions are met and measures are taken to limit the arc impact on the internal cavities. For this purpose, partitions shall be used, the design of which shall meet the following requirements:

the partitions used to separate GIS compartments shall be gas-tight to prevent contamination from penetrating into the adjacent compartment;

the partitions shall be made of a material with such insulating and mechanical properties as to ensure their proper functioning during the entire GIS service life;

the partitions shall retain their dielectric properties under operating voltage when they are contaminated by electronegative gas decomposition products from switching operations.

19.6.2.4 GIS partitions (insulators) shall be calculated:

for the pressure difference when vacuuming gas from a compartment (element) on one side of the bulkhead at normal operating pressure on the other side of the bulkhead;

for excessive pressure on one side of the bulkhead at normal operating pressure on the other side during the electrical testing of circuit equipment;

for non-symmetrical partitions to the worst pressure direction;

for additional loads and vibrations;

for the serviceability of the component, when servicing is carried out with a pressurized partition.

19.6.2.5 GIS components to be installed in enclosures shall comply with the requirements of the relevant standards.

Due to small dimensions, extended service life and maintenance intervals, GIS components shall be designed with fitted devices that allow for in-service monitoring of the equipment and ensure increased operational reliability:

trigger counters in switchgear;

conductivity current monitoring sensors in gas-insulated surge arresters;

in metering transformers, the execution of a separate winding for electricity metering.

GIS components shall be equipped with auxiliary means (heating, ventilation, protective measures, etc.) to ensure normal operation of the equipment over the entire range of actual operating conditions.

Switchgear connection and disconnection controls and emergency network termination controls must be located at a height of between 0,4 m and 1,8 m above the service level.

19.6.2.6 Cable connections.

GIS components that remain connected to the cable shall be able to withstand the test voltages specified in the relevant standards for cables of the same rated voltage.

During the testing of cable electric strength, neighbouring GIS parts shall be disconnected and earthed to prevent GIS live parts from being affected by disruptive discharges in the cable. For this purpose, a process isolator (disconnector) shall be installed in GIS cable connection.

An entry for cable diagnostics and testing with DC and AC voltages shall be provided on the cable sheath or on GIS for each phase (IEC 62271-209).

When 35 — 220 kV GIS or cable lines and cable inserts are used, surge arresters shall be used to protect them against lightning surges. The choice of location and parameters for the surge arrester is determined on the basis of the calculations made in the design documentation.

19.6.2.7 Direct connections between GIS and transformer shall be made in accordance with IEC 62271-211. A process isolator (disconnector) shall be installed at the transformer inlet to enable preventive testing of transformers in GIS gas-insulated current lead.

19.6.2.8 "Electronegative gas — air" ("air — gas") entries shall comply with the climatic version specified for the operating conditions.

19.6.2.9 In the design of current leads for intra-substation connections, the shells, current carrying parts, contact assemblies, bulkheads and support insulators used in the main GIS components shall be primarily used. The design of the current leads shall comply with all test standards applicable to GIS — IEC 62271-203.

19.6.2.10 Insulating devices.

In order to arrange the possibility of GIS testing with overvoltage rated for transformer connection and entries, it shall be possible to provide an isolating gap from the mating equipment. For overhead entries it may be sufficient to disconnect the conductor from the outer (overhead) side.

For checking the electrical resistance of GIS main supply circuit, it shall be possible to access the main supply circuit without having to dismantle the GIS components.

19.6.2.11 Corrosion protection.

The choice of GIS materials and protective coatings shall be determined by the operating conditions, standards of the Unified system of corrosion and ageing protection (USCAP) and specified in the operating instructions.

All bolted or screwed connections of the sheath shall remain easily dismantled. The continuity of the earthing circuits shall be guaranteed taking into account the corrosion of bolted and screwed connections.

The number of earthing points and GIS grounding scheme shall be such as to preclude any occurrence of electrochemical corrosion of current lead metal where they intersect the overlaps.

19.6.2.12 GIS gas system.

Controlled pressure system in GIS shall not be used where the gas volume is automatically fed from an external compressed gas source or from an internal gas source.

Autonomous pressure system and closed pressure system shall be used in GIS. Means shall be provided to enable safe and convenient make-up of gas systems when the equipment is in operation. The use of external gas make-up pipes is not permissible.

Stand-alone gas pressure systems.

The recommended leakage rate of a single GIS compartment to atmosphere and between compartments for autonomous pressure system is not more than 0,5 % per year.

Closed pressure systems.

In a closed pressure system, a gas leakage rate of 0,1 % per year is assumed to fulfil the expected lifetime requirement.

Pressure coordination is specified in IEC 62271-203. The manufacturer shall select the minimum permissible electronegative gas pressure for the insulation and switching capacity P_{me} and the pressure for the pressure drop alarm activating.

Depressurizing.

For safety reasons and limitation of the consequences for GIS, a pressure relief device shall be installed in each compartment, except for high volume compartments where the overpressure is self-limiting to values which do not exceed the type test pressure.

Pressurization devices (valves with opening and closing pressures and devices for relieving pressure without reclosing the relief hole, diaphragms and frangible discs) shall have a deflector to direct the release and ensure that there is no hazard to the operator's work where it may be encountered.

19.6.2.13 Enclosure design.

The enclosures shall be designed in accordance with the requirements of PB 03-576-03 "Regulations for the Construction and Safe Operation of Pressure Vessels".

The enclosure shall be capable of withstanding the normal and transient pressures to which it is subjected in operation, as well as the possible effects of internal arcing overlap.

Measures shall be provided to reduce the effects of internal arcing on GIS equipment and to minimize the time interval of the power failure. The arc shall not penetrate into neighbouring gas compartments. The effects of an internal arc shall be localized within the same compartment where the arc occurred.

Recommended protection criteria in accordance with IEC 62271-203 for different arc durations according to the protection system configuration are given in Table 19.6.2.13.1.

Table 19.6.2.13.1

Rated short-circuit current	Degree of protection	Current duration	Status criteria
≤ 40 kA (actual value)	1	0,2 s	No external effects other than the operation of pressure relief devices
	2	≤ 0,5 s	No fragmentation (allow for burning)
≥ 40 kA (actual value)	1	0,1 s	No external effects other than the operation of pressure relief devices
	2	≤ 0,3 s	No fragmentation (allow for burning)

19.6.2.14 Interlocking.

Self-contained and closed pressure systems filled with compressed gas for insulation and/or operation and having a minimum operating pressure for insulation and/or operation greater than 0,2 MPa (absolute pressure) shall be fitted with pressure (or density) monitoring devices for continuous or at least periodic monitoring as part of the maintenance programme, taking account of the requirements of the relevant standards.

For GIS components and control equipment with a minimum operating pressure not exceeding 0,2 MPa (absolute pressure), such means shall be subject to agreement between the manufacturer and the consumer.

The gas density or temperature-compensated gas pressure in each compartment shall be continuously monitored. The indicator-type control device shall provide at least two pressure or density settings (pressure/density alarm and minimum functional pressure or density).

Gas monitoring devices shall be accessible for inspection and replacement when high voltage equipment is in operation.

For the main circuits, the following interlocking devices, which are used for creating insulation gaps and earthing, are mandatory:

interlocks to prevent switching on — for apparatus installed in the main circuit, which are used to provide an isolation gap during maintenance work;

interlocks to prevent tripping — for the earthing switches.

GIS interlocking components (intermediate disconnector/earthing switch interlock relays, disconnector/earthing switch contactors) made by the manufacturer shall have additional status interlock contacts to collect discrete signals about the status of these components to the feeder controllers.

Interlocking relays with normally closed contacts shall be provided in GIS interlocking circuits to implement additional interlocking conditions (software interlocks in feeder controllers).

Earthing switches with a short-circuit making capacity smaller than the nominal peak of the short-circuit withstand current shall be mechanically interlocked with the corresponding disconnectors so that when the main current-carrying circuit is high, it is not possible to switch on earthing circuit on and when the earthing circuit is switched on, it is not possible to switch on the main current-carrying circuit.

Quick-release earthing switches shall have an interlock to prevent switching on when there is voltage on the main current-carrying circuit and a mechanical interlock for the drive in the disconnected and switched-on positions.

Load-break switches with a short-circuit making capacity less than the nominal peak withstand short-circuit current or with a breaking capacity less than the nominal operating current and disconnectors shall be interlocked with the corresponding switch to prevent the load-break switch or disconnector from tripping or opening if the switch is not tripped.

19.6.2.15 During GIS operation, the level of noise generated by the equipment shall not exceed the value specified by the manufacturer.

19.6.2.16 Earthing of GIS and control equipment.

The enclosures of GIS components and auxiliary equipment shall be fitted with a reliable earthing terminal with a clamp screw or bolt for connection to an earthing conductor.

Metal sheath parts connected to the earthing system may be regarded as an earthing conductor.

It is permitted to earth the GIS in accordance with the manufacturer's instructions.

Provision shall be made for earthing all parts of the main live circuits to ensure the safety of maintenance personnel during repair work.

Earthing switches installed on collecting busbars and outgoing lines shall have a short-circuit making capability and a short-circuit making capacity.

In addition, after opening the enclosure for the period of repair work, it shall be possible to connect portable earthing switches to those parts of the circuit which were previously earthed through earthing switches.

The enclosures and all metal parts that are not part of the main or auxiliary circuit must be earthed. For continuity of the chain, the connections between the enclosures, frame and other metal parts may be made by bolting or welding.

In case of phase-by-phase GIS design, loop circuits connecting the three phase enclosures shall be installed to ensure the flow of induced currents. Each of these loop circuits shall, as far as possible, be directly connected to a common earthing system by means of a conductor capable of carrying short-circuit current.

19.6.2.17 Degrees of protection.

Degrees of protection in accordance with IEC 60529 shall be determined for the control equipment permitting external penetration and for the enclosures (cabinets) of the corresponding control circuits and/or auxiliary low-voltage circuits and control drives of all high voltage switchgear, control equipment and switchgear.

19.6.2.18 Electromagnetic compatibility.

For the main circuit of the switchgear in normal operation without switching operations, the emission level is checked by measuring the radio interference voltage, if applicable. The test procedure for the radio interference test shall be in accordance with IEC 60060-1.

Electromagnetic compatibility requirements apply to interfaces and inputs of auxiliary circuits, control circuits, auxiliary assemblies that have electronic components, the effect of interference on which can lead to incorrect functioning. The limit values for radio interference tests shall not exceed the limit values specified in the standards for the particular type of electrical equipment.

19.6.2.19 Position indicators.

In switchgear, if the contacts are invisible, a clear and reliable indication of the position of the main circuit contacts must be provided, which is mechanically connected to these contacts. Possibility of easy monitoring of the position indicator during maintenance work on the equipment shall be provided.

The colors and markings of the positions of the signalling device in the disconnected, activated or, where provided, earthed position shall comply with IEC 62271-203.

The disconnector or earthing switch disconnected position can be detected if one of the following conditions is fulfilled:

the insulating gap is visible;

the position of the movable contact, ensuring the insulating distance or gap, is indicated by a visual indicator device.

19.6.3 Requirements to electrical insulation strength.

The insulation of GIS main circuits, control circuits, auxiliary circuits must comply with the requirements of the IEC 60071-1.

The rated test voltages of the GIS main circuits must comply with IEC 60071-1.

The insulation of the GIS control and auxiliary circuits with respect to earth shall withstand a short-term (one-minute) alternating voltage test in accordance with IEC 60071-1.

The leakage path of the external insulation of "electronegative gas — air" ("air — gas") entries shall comply with at least II* contamination degree in accordance with IEC/TS 60815-1 and IEC 60694.

19.6.4 Requirements for through-current short-circuit resistance.

GIS shall withstand the effects of rated short-time currents and rated peak currents (thermal and electrodynamic withstand currents) under short-circuit conditions without damage preventing its further proper operation. The value of the electrodynamic withstand current i_d shall be at least 2,5It.

GIS earthing circuits shall be resistant to the effects of through short circuit currents for their duration.

19.6.5 Heating requirements for normal operation and short-circuits.

GIS heat dissipation, during continuous normal operation, shall meet the requirements of IEC 60694.

The temperature of the GIS enclosure parts under normal operating conditions, accessible to touch, shall not exceed 70 °C, those not accessible to touch must not exceed 80 °C.

Permissible temperature rise above the temperature of the GIS secondary circuits shall comply with IEC 60694.

19.6.6 Requirements for gases.

The manufacturer shall specify the type, required quality, quantity and density of the gas (gas mixture) used in the GIS components and the control equipment, and shall give the consumer the necessary instructions for gas renewal and maintenance of the required quantity and quality.

The manufacturer shall specify the requirements for new and used gas applied in the GIS. New gas to be used in GIS shall comply with IEC 60376. When using new electronegative gas, IEC 62271-203 recommendations in case of pre-commissioning of equipment and IEC 60376 recommendations for monitoring gas properties and maintenance of GIS during operation shall be applied.

Mixtures of gases such as ultra-pure nitrogen and carbon tetrafluoride may be used as insulating and arc quenching media in GIS components.

Methods of preparing mixtures, filling the equipment with mixtures and maintaining the composition of mixtures during operation shall comply with the instructions of the equipment manufacturer.

19.6.7 Tests.

GIS shall be subject to prototype testing of products as well as product testing during steady-state production at the installation site. As agreed between the manufacturer and the customer, the test item may be GIS in assembly or parts whereof.

The prototype tests are carried out on equipment after the production technology has been mastered and when the design, materials and production technology and technical characteristics have been altered. The tests shall be carried out on each GIS when it leaves the manufacturer's and also in order to verify the stability of GIS technical characteristics during their serial production.

These tests shall be carried out in compliance with IEC 62271-203.

The on-site tests are carried out after the GIS has been installed at the facility. The scope and procedure of the on-site tests shall be agreed with the customer.

19.7 CURRENT LEADS FOR A VOLTAGE OF 6 — 220 KV

19.7.1 General.

19.7.1.1 For voltages of 6 — 35 kV inclusive, cast (solid) insulated or shielded current leads shall be used; for voltages of 110 — 220 kV, gas-insulated current leads shall be used.

19.7.1.2 Requirements for contact joints, metal coatings, types, thicknesses and quality requirements for coatings shall be in accordance with IEC 60999-1 and IEC 60999-2.

19.7.2 Cast (solid) insulated current leads 6 — 35 kV.

19.7.2.1 The degree of protection provided by the current lead enclosure is IP44 for indoor conductors. The current lead is naturally cooled.

19.7.2.2 Copper, aluminium or aluminium alloys shall be used for busbars, flanges and busbar compensators of current leads. Special compounds, e.g. epoxy resins, shall be used for insulation.

19.7.2.3 Permanent terminations of current leads made of copper and copper alloy shall be made by soldering with copper-phosphorus solder with silver additive.

19.7.2.4 Design.

19.7.2.4.1 The current lead shall consist of differently configured sections. The set and location of the current lead components is determined by the assembly drawing of the route designed for the specific site.

19.7.2.4.2 The current lead section shall consist of a copper or aluminium busbar, covered with a layer of rigid insulation with a thickness depending on the value of the rated voltage. The ends of the sections shall be provided with pins with holes for bolting the sections together and to the electrical equipment. Section length shall not exceed 10 m.

19.7.2.4.3 For equipment to be built into the current lead (disconnectors, voltage and current transformers, overvoltage limiters), enclosures of the appropriate type shall be provided.

19.7.2.4.4 The connection between the sections along the entire length of the line shall be split (bolted) by means of special couplings with thermal expansion joints, which shall be installed along the current lead at intervals of not more than 10 m. Joints without thermal expansion joints can be filled at the installation site with the same compound as the busbar.

19.7.2.4.5 The connections between the current leads and the outlets of the electrical apparatus shall be made demountable, using busbar compensators and (at the customer's request) protective sheaths.

19.7.2.4.6 The configuration of the sections shall ensure that the current lead can be laid in any spatial position taking into account the configuration of the route.

19.7.2.4.7 The design of the current lead shall allow for a vertical run of up to 10 m.

19.7.2.4.8 The fastening components of the current lead shall ensure that the conductor is securely fastened to the supporting structure and that it can move within ±20 mm in case of temperature variations in the busbars.

19.7.2.5 Electrical parameter requirements.

19.7.2.5.1 Requirements for insulation strength according to IEC 60071-1 for apparatus with normal insulation.

19.7.2.5.2 Partial discharge intensity in the current lead insulation of level "a" as per IEC 60071-1 shall not exceed 5 pC for the voltage of $1{,}05 \cdot U_m \cdot \sqrt{3}$ or 10 pC for the voltage of $1{,}5 \cdot U_m \cdot \sqrt{3}$.

19.7.2.5.3 Continuous heating temperature of the current lead components at the rated current must not exceed:

for copper or aluminium busbars and contact connections: +90 °C in accordance with IEC 60694;

for the outer surface of the current lead insulation layer: +70 °C.

19.7.2.5.4 The current lead shall be resistant to the electrodynamic and thermal effects of short-circuit currents, the parameters of which do not exceed the specified values:

the current of electrodynamic resistance i_d or its multiplicity K_d in relation to the rated current amplitude;

the current of electrodynamic resistance $I_т$ or its multiplicity $K_т$ in relation to the rated current;

thermal resistance current flow time $t_к$, 1 and 3 s.

19.7.2.5.5 The ratio $i_д \geq 1{,}8\sqrt{2}\,I_т$ shall be observed between the Id and It values.

19.7.2.5.6 Each section of the current lead shall have a grounding conductor terminal (clamp) made in accordance with IEC 60947-4-1 and IEC 60417-DB-12M. The earthing bolt shall be of at least 10 mm in diameter.

19.7.3 Gas-insulated current leads 110 — 220 kV.

19.7.3.1 With respect to the phase conductor arrangement, the current leads shall be either three-phase (with three phases in a common enclosure) or single-phase (with the phases placed in separate enclosures).

19.7.3.2 In terms of the termination design, the current leads shall be of the following types:

with "air — electronegative gas" entry;

with "electronegative gas — air" entry;

with "electronegative gas — electronegative gas" entry.

19.7.3.3 Gas-insulated current leads shall be designed for fault-free operation under both normal conditions and under short-circuit, overvoltage and standardized overload conditions.

19.7.3.4 Requirements for electrical insulation strength.

19.7.3.4.1 Standardized test voltages of the GIS main circuits shall comply with Table 19.7.3.4.1.

Table 19.7.3.4.1

Voltage class	Test voltage, in kV				
	full lightning impulse		switching impulse	short-term alternating voltage	
	relative to the ground	between phases for GICL*	relative to the ground	relative to the ground	between phases for GICL
110	450	450	–	230	230
150	650	650	–	300	300
220	900	900	–	440	440
* Gas-insulated current lead with all three phases housed in the same enclosure.					

19.7.3.4.2 The insulation of GICL control and auxiliary circuits in relation to earth shall withstand a test short-term (one-minute) alternating voltage of 2,0 kV applied alternately between live and earthed parts and between live parts of different circuits.

19.7.3.4.3 The partial discharge intensity in the GICL insulation shall not exceed the value of 10 — 11 C when an alternating current voltage equal to $1{,}1U_{w.v.}/\sqrt{3}$ is applied in accordance with IEC 60071-1.

19.7.3.5 Requirements for through-current short-circuit resistance.

19.7.3.5.1 GICL shall withstand the effects of rated short-time currents and rated peak currents under short-circuit conditions without damage preventing its further proper operation. The value of the electrodynamic resistance i_d shall be at least $2{,}5I_t$.

19.7.3.5.2 The rated current flowing time of 1s, 2s or 3s is specified in the GICL documentation.

19.7.3.5.3 GICL earthing circuits shall be resistant to the effects of through short circuit currents for their duration equal to 1 s.

19.7.3.6 Heating requirements for normal operation and short-circuits.

19.7.3.6.1 The temperature of the GICL enclosure parts under normal operating conditions, accessible to touch, shall not exceed 70 °C. The temperature of the GICL enclosure parts not accessible to touch under standard operating conditions, shall not exceed 80 °C.

19.7.3.6.2 Permissible temperature rise above the temperature of the GICL secondary circuits shall comply with the IEC 60999-1 and IEC 60999-2. The permissible temperature limits for contact heating of live parts during the passage of fault currents shall not exceed the permissible values in accordance with IEC 60999-1 and IEC 60999-2.

19.7.3.7 Design.

19.7.3.7.1 All sheaths of the individual sections and components of the current lead shall be electrically connected and earthed.

19.7.3.7.2 The connection of individual sections and/or pivoting sections shall be carried out with bolts.

19.7.3.7.3 Compensation devices shall be provided to compensate for dimensional variations in current leads due to temperature fluctuations, as well as dimensional deviations during manufacture and installation.

19.7.3.7.4 The GICL design shall allow for the use of sectionalizing and termination devices in the form of "air — insulated gas", "cable — insulated gas", "insulated gas — insulated gas" entries, as well as the use of rotating elements along with the line sections of the current lead to provide the necessary routing.

19.7.3.7.5 Entry of "cable — insulated gas/electronegative gas" type for connecting power cable and GICL shall comply with the recommendation of IEC 62271-305.

19.7.3.7.6 The GICL sheathing shall be resistant to burning through inward arc over time (in accordance with IEC 61640):

at arc currents of 40 kA and above — from 0,1 s to 0,3 s;

at arc currents under 40 kA — 0,2 s to 0,5 s.

The specific time at which the GICL heath shall be resistant to burning through at internal arc overlap is determined by the manufacturer on the test basis.

19.7.3.7.7 Each sealed section of the current lead shall be equipped with protection against excessive pressure build-up of electronegative gas.

19.7.3.7.8 Each pressurized section of the current lead shall be fitted with an electronegative gas density gauge and electronegative gas filling and venting valves. Density sensors shall be so designed that their operation can be verified without purging gas from the compartment.

19.7.3.7.9 The electronegative gas density (pressure) gauges shall have settings for an alarm and interlock output:

the electronegative gas density (pressure) at which the refilling of electronegative gas is required;

the minimum density (pressure) of electronegative gas at which the conductor shall be taken out of service (disconnected by the circuit-breakers on both sides).

19.7.3.7.10 Components for the control and signalling circuits of the current lead shall be housed in cabinets.

The cabinets shall be fitted with outputs for centralized control circuits.

Protection degree of the cabinets against contact with or proximity to lived parts, contact with moving parts inside the enclosure, ingress of solid foreign bodies and water in accordance with IEC 60529 shall be specified in the company (manufacturer) technical documentation.

19.7.3.7.11 The earthing circuits of the enclosure and the main GICL circuit elements, as well as the method of their attachment, shall be selected in accordance with the requirements of IEC 60947-4-1 and IEC 60417-DB-12M.

19.7.3.8 Requirements for testing.

GICL shall be subjected to qualification, acceptance, type and commissioning tests on site. As agreed between the manufacturer and the customer, the test item may be GISL in assembly or parts whereof.

19.8 DRY CURRENT-LIMITIMG REACTORS

19.8.1 Basic parameters.
19.8.1.1 The reactor voltage classes shall comply with the IEC 60071-1, IEC 60071-2.
19.8.1.2 Rated current and rated inductive reactance of single reactors at 50 Hz shall be taken from Table 19.8.1.2.1. Rated current and rated inductive impedance of twin reactors at 50 Hz shall be taken from Table 19.8.1.2.2.

Table 19.8.1.2.1

Rated current, in A	250	400	630	1000	1600	2500	4000
Rated inductive impedance, in Ohm	1,00	0,35	0,25	0,14	0,14	0,14	0,10
	1,40	0,45	0,40	0,22	0,20	0,20	0,18
	2,00	–	0,56	0,28	0,25	0,25	–
	2,50	–	0,70	0,35	0,35	0,35	–
	–	–	1,00	0,45	0,56	–	–
	–	–	1,60	0,56	–	–	–
	–	–	2,00	0,70	–	–	–
	–	–	–	1,00	–	–	–

Table 19.8.1.2.2

Rated current, in A	2 x 630	2 x 1000	2 x 1600	2 x 2500
Nominal inductive impedance, in Ohm	0,25	0,14	0,14	0,14
	0,40	0,22	0,20	0,20
	0,56	0,28	0,25	0,25
	–	0,35	0,35	0,35
	–	0,45	–	–
	–	0,56	–	–

At 60 Hz, the rated current values shall be in accordance with Tables 19.8.1.2.1 and 19.8.1.2.2 and the rated inductive reactance value — in accordance with 19.8.1.2.1 and 19.8.1.2.2 multiplied by a factor of 1,2.
19.8.1.3 Reactors shall be made with vertical, stepped or horizontal phase arrangement.
19.8.1.4 Reactors shall be manufactured with natural air or forced air cooling.
19.8.2 Design requirements.
19.8.2.1 Reactor outputs shall comply with the requirements of IEC 60999-1 and IEC 60999-2.
19.8.2.2. The angle between the reactor leads shall be 0°, 90° or 180°. The specific value is set in accordance with consumer's requirements.
The identical terminals of the beginning, middle and end of the winding of vertically and staggered phases shall be placed on the same vertical line. The tolerance for the angles between the leads shall not exceed ±10°.
Reactors with alternatively arranged contact leads as well as twin reactors with different angles between lower and middle or middle and upper leads can be manufactured by agreement between the consumer and the manufacturer.

19.9 3 — 220 KV SURGE ARRESTERS

19.9.1 Basic electrical characteristics.

19.9.1.1 The residual voltages of the arrester shall be specified by the manufacturer in the technical documents for the particular types of arrester at 30/60 μs, 8/20 μs and 1/10 μs current pulses with the maximum pulse values given in Table 19.9.1.1.

Table 19.9.1.1

Rated maximum values of current pulses through the arrester

Arrester class by capacity	Rated discharge current, in A	Maximum current values, in A, at pulses, in μs		
		30/60	8/20	1/10
1	5000	125, 250, 500	2500, 5000, 10000	5000
	10000	125, 250, 500	5000, 10000, 20000	10000
2	10000	250, 500, 1000	5000, 10000, 20000	10000
3	10000	500, 1000, 2000	5000, 10000, 20000	10000
4	10000	500, 1000, 2000	5000, 10000, 20000	10000
	20000	500, 1000, 2000	10000, 20000, 40000	20000
5	20000	500, 1000, 2000	10000, 20000, 40000	20000

N o t e . A pulse means a unipolar wave of voltage or current rising without noticeable oscillation at high speed to a maximum value and decreasing, usually at a slower speed, to zero with little, if any, transition to the opposite polarity. The parameters specifying voltage or current pulses are polarity, maximum value (amplitude), conditional edge length and conditional pulse duration:

.1 conditional pulse edge time (duration) T1: time expressed in microseconds and determined by multiplying by 1,25 the time in microseconds required to increase the maximum (amplitude) value of the pulse from 10 % to 90 %;

.2 conditional pulse duration T2: the time, expressed in microseconds, between the conditional start of the pulse and the moment when the voltage or current decreases to half of the maximum value;

.3 pulse shape indication: a combination of two numbers in microseconds, the first indicating the rising edge and the second the duration of the pulse. This combination shall be recorded as T 1/T2 (the "/" sign has no mathematical meaning)

19.9.1.2 The manufacturer shall specify the value of the classification current and the corresponding minimum classification voltage of the arrester:

.1 classification current of the arrester I_{cl}: the amplitude value (the higher amplitude value of the two polarities if the current is asymmetrical) of the active component of the power frequency current, which is used to determine the classification voltage of the arrester and is rated by the manufacturer;

.2 classification voltage of the arrester U_{cl}: the maximum (amplitude) value of the power frequency voltage divided by 2, which shall be applied to the arrester to obtain the classification current. The classification voltage of a multi-element arrester is defined as the sum of the classification voltages of the individual elements.

19.9.1.3 The arrester shall withstand without damage 18 rectangular current pulses of 2000 μs with a maximum value (amplitude) equal to the current carrying capacity specified by the manufacturer.

19.9.1.4 The arrester shall withstand without damage 20 pulses of rated discharge current and 2 pulses of high current with an amplitude:

.1 65000 A — for arresters of capacity class 1 and rated discharge current of 5000 and 10000 A;

.2 100000 A — or arresters of capacity class 2 — 5 and nominal discharge current of 10000 and 20000 A.

19.9.1.5 Arresters shall withstand a combination of operating and simulated operational tests, which shall not result in damage or loss of thermal stability:

.1 for arresters of capacity class 1 and rated discharge current 5000 and 10000 A — 20 pulses of rated discharge current and 2 pulses of high current with an amplitude of 65000 A;

.2 for arresters of capacity classes 2 to 5 and rated discharge currents 10000 and 20000 A — 20 pulses of rated discharge current, 2 pulses of high current with an amplitude of 100000 A and 2 pulses of current carrying capacity.

19.9.2 Requirements for external insulation.

19.9.2.1 Leakage path length of the external insulation of the arrester operating under conditions corresponding to pollution degree I shall be at least 1,8 cm/kV of the highest operating voltage of the network, while for pollution degrees II, III, IV — at least 2,0; 2,5 and 3,1 cm/kV respectively.

19.9.2.2 Insulation of arresters made with organic (polymer) materials shall be traction-erosion-resistant.

19.9.2.3 Insulation of the limiter enclosure shall withstand the lightning pulse, switching pulse, one-minute power frequency voltage tests.

19.9.2.4 Lightning pulse voltage test shall be carried out for all types of arresters. The maximum value of the test pulse voltage shall not be less than the residual voltage at the limiter at rated discharge current multiplied by 1,3.

19.9.3 Design requirements.

19.9.3.1 The arresters shall be tight.

19.9.3.2 The design of the plastic-insulated arrester shall be resistant to moisture penetration.

19.9.3.3 Arresters shall have contact terminals for connection to current-carrying and earthing wires. The input terminals shall be suitable for the connecting of copper or aluminium cables and busbars, including stranded wires.

19.9.3.4 All metal parts of the arresters shall be protected against corrosion. The sealing material for tightening shall be ozone-resistant.

19.9.3.5 In case of multi-column arrester design, the manufacturer shall specify the maximum permissible irregularity in the distribution of currents over the columns.

19.9.3.6 If the arrester has an insulating base, it shall withstand the bending moment and climatic tests without any damage capable of affecting its proper functioning.

19.9.3.7 Arresters shall be explosion-proof. The manufacturer shall specify the maximum effective value of the steady-state high and low (800 A) short-circuit current of the internal fault, which the arrester shall withstand without hazardous explosive failure.

19.9.3.8 Arresters with the maximum continuous permissible operating voltage of 73 kV or higher shall have no partial discharge level at $1{,}05 \cdot U_{ct}$ above 10 pC.

19.9.3.9 Arresters with the maximum continuous permissible operating voltage of 73 kV and above shall have a radio interference level at $1{,}05 \cdot U_{ct}$ and at all lower voltages not exceeding 2,500 μV.

19.10 ENTRIES AND BUSHINGS FOR 110 - 220 KV

19.10.1 The voltage classes of the entries and their corresponding maximum working voltages ($U_{w.v.}$) shall be selected from a range of standard values according to IEC 60137.

19.10.2 Overall and mounting dimensions, connection dimensions and nominal weight of the entries shall be in accordance with the design documentation approved in accordance with the established procedure.

19.10.3 Entries shall have:

the metering lead for measuring the dissipation factor (tgδ) and capacitance (C) or a special lead at the bushings with a measuring capacitor for connecting a voltage measuring device under operating conditions and for measuring the dissipation factor and capacitance. These outputs can be used to measure partial discharge intensity and also to connect an input insulation monitoring device;

built-in or remote compensators to compensate for temperature variations in oil volume, ensuring that the oil pressure in the inlet is within the specification limits for the design temperature range. Inlets with overpressure shall be provided with an oil pressure gauge in the inlet;

inlets without overpressure having integrated expansion joints;

entry lifting attachments located on the coupling sleeve.

19.10.4 The entry design shall allow for the installation of current transformers below the supporting flange at the distances specified in the agreed dimensional drawings of the entries.

19.10.5 The insulation resistance of the measuring lead shall be at least 1500 Mohm, the capacitance with respect to earth (C_e) shall not exceed 10000 pF and the dissipation factor (tgδz) at power frequency shall not be greater than 0,05.

19.10.6 The measuring lead shall withstand a test voltage of 2 kV of power frequency for 1 min without breakdown and overlap.

19.10.7 The temperature of the metal parts of the entries in contact with the insulating material, when the rated current is flowing, shall not exceed:

105 °C — for BMI entries (class A);

120 °C — for entries with solid RIP or RIN insulation (class E);

130 °C — for gas insulation (class B).

The maximum temperature rise of the contact parts for connection to external conductors shall not exceed 65 °C. Inlets used as part of apparatus, e.g. switchgear, shall comply with the requirements to thermal mode of the appropriate apparatus.

19.10.8 The entry design shall be tight and moisture-proof.

19.10.9 The supporting flange of the entries shall be sealed.

19.10.10 The polymeric outer insulation of the entries shall be made of moulded silicon-organic compositions of RTV-2 type or similar, providing tracking-erosion resistance and resistance to ignition.

19.10.11 Entries designed to replace previously produced entries shall be interchangeable in terms of connection and installation dimensions. The specifics of replacing a particular type of entry shall be specified in the operating instructions for the relevant entry points.

19.10.12 The current-carrying resistance of entries for oil circuit-breakers at DC at 20 °C shall not exceed 70 μOhm.

19.11 LAYOUT (MOUNTING)

19.11.1 Electrical equipment.

19.11.1.1 Where high voltage equipment without containment is installed in a special space actually serving as its containment, the space doors shall be so locked that they cannot be opened unless the voltage is disconnected and the conductive parts of the equipment are earthed.

Warning notices shall be provided at entrances to spaces or areas where high voltage equipment is located to warn against dangerous high voltages.

19.11.1.2 In justified cases, the equipment may be installed outside special electrical spaces provided its enclosure degree of protection is at least IP44 and current-carrying parts are accessible only when de-energized or using special tools.

19.11.1.3 The diagram of connections and electrical equipment arrangement drawing shall be available in the special electrical space.

19.11.2 Cables.

19.11.2.1 Cable route laying.

Cables shall not run through accommodation spaces.

19.11.2.2 Separation.

High-voltage cables shall be laid separately from cables for voltages below 1000 V. In particular, high voltage cables shall not be laid in the same routes or in the same ducts or pipes, or in the same conduits.

If high voltage cables of different rated voltages are laid in the same routes, the insulation distances between the cables shall not be less than those set for the higher voltage cable, as indicated in 19.2.3.1.

19.11.2.3 Cable installation.

High-voltage cables in three-phase version shall be laid in metal conduits or in metal ducts, or they shall be protected by metal sheaths.

Open cabling (on load-bearing pressed panels) is permitted if they have continuous metal armouring which shall be reliably (repeatedly) earthed.

19.11.2.4 Cable terminations.

The terminations of all high-voltage cables shall be made of suitable insulating material. In junction boxes, if the cable wires are not insulated, the phases shall be separated from the hull and each other by means of solid partitions made of suitable insulating material. High-voltage cables having a conductive layer between the phases for monitoring the electric field strength of the cable insulation shall have leads intended for such monitoring.

The insulation material of the leads shall be compatible with the cable sheathing and sheath material, and the leads shall be fitted with earthing devices for all metal shielding components of the cable (metal strips, wires, etc.).

When terminating power cables, the appropriate sleeve design and grade for the operating and ambient conditions shall be used. Termination sleeves on cable lines shall be so designed that they protect the cables against the penetration of moisture and other harmful substances from the environment and that the sleeves withstand the test voltages for cable lines and comply with the requirements of the technical documentation.

Installation of cable fittings shall be carried out by personnel specially trained and authorized by the cable fitting manufacturer, under the supervision of the firms (manufacturers) and the technical supervision of the operating company. The use of couplings from different firms (manufacturers) shall be agreed with the cable manufacturer and the operator.

19.11.2.5 High voltage cable fittings.

The number and types of cable fittings to be used shall be defined in the cable line project documentation. The fittings shall have the highest possible degree of factory-assembled availability to minimize the influence of human element during assembly and the likelihood of damage to the sleeve structure during assembly and transport.

When selecting cable fittings for cable lines of 35, 110 kV and above, the following requirements shall be met:

pre-qualified cable fittings tested for reliability according to IEC 60840 and IEC 62067 shall be used;

end fittings (terminations and gas-insulated entries) shall be demountable, preferably with an outer insulator of fiber-reinforced materials, designed to avoid the use of liquid dielectric media and feeder fittings (except as specified in the design documentation), and shall allow removal of the insulator for preventive maintenance and shall be adjusted for the installation of cables with optical fibers integrated in the cable shield. Composite insulators for outdoor end sleeves shall be used with different creepage path lengths, depending on the degree of atmospheric contamination at the site;

fittings shall be used that are designed to protect against mechanical damage, water and dust ingress;

end fittings with special adapters for periodic monitoring of partial discharge levels by means of mobile measuring units shall be used, and such fittings shall be designed to allow installation of fixed partial discharge sensors and measurement of currents in cable shields;

for the installation and fixing of terminations, it is recommended to use corrosion-resistant steel structures with factory-applied hot-dip galvanization or thermodiffusion galvanization;

the service life of the cable harness shall be at least 30 years.

The following cable fittings for 1 — 35 kV cable lines shall be used:

fittings based on heat-shrinkable antitreking, non-combustible, flame-retardant tubes and products;

cold shrinkage cable fittings and those based on prefabricated elastomeric elements.

19.11.2.6 Marking.

High-voltage cables shall be fitted with easily readable identification marking.

19.11.2.7 Testing upon the installation completion.

All cables and their components (terminations, earth leads, etc.) shall be subjected to a high voltage test before commissioning a new high-voltage cable system or after modification (repair or installation of additional cables).

The tests shall be carried out following the measurement of the insulation resistance.

For 15 — 220 kV power cable lines, the following tests shall be carried out to confirm the quality and proper installation of the cables and to determine the technical characteristics of the cables:

a.c. voltage, sinusoidal waveform and frequency in the range of 20 — 300 Hz, test voltage level in accordance with Table 19.11.2.7, or rated operating line voltage for 24 h without load;

Table 19.11.2.7

Value of alternating test voltage for 35 — 220 kV cable lines with XLPE insulation

Rated voltage, kV	Test voltage level, kV	
	commissioning	under service conditions
35 — 47 (IEC 60840:2017)	52 kV	52 kV irrespective of service life
47,1 — 69 (IEC 60840:2017)	72 kV	72 kV irrespective of service life
69,1 — 115 (IEC 60840:2017)	128 kV	128 kV irrespective of service life
115,1 — 138 (IEC 60840:2017)	152 kV	132 kV irrespective of service life
138,1 — 161 (IEC 60840:2017)	174 kV	150 kV irrespective of service life
161,1 — 220 (IEC 62067:2011)	180 kV	180 for cables with a service life of up to 5 years; 152 for cables with a service life of more than 5 years

determination of cable core integrity and phasing of cable cores and cable shields is carried out in operation after assembly, installation of sleeves or disconnection of cable cores has been completed;

determination of cable core resistance;

determination of the electrical operating capacity of cables;

measurement of current distribution over single-core cables and shields;

checking the earthing device (measuring the earthing resistance);

testing of cable sheaths with d.c. voltage;

measurement of partial discharge characteristics;

thermovision inspection of terminations and cable entries in GIS (for 110 — 220 kV cable lines);

measurement of the dissipation factor;

checking the integrity of the fiber optic cables (at the customer's request, this check can also be carried out immediately after laying the construction cable lengths, before installation of the coupling and termination sleeves).

Electrical tests of cable lines after laying are carried out upon completion of the cable installation.

APPENDIX 1 (RECOMMENDED)

Electrical circuit schematic diagrams of 110 — 220 kV switchgear. Standard solutions:

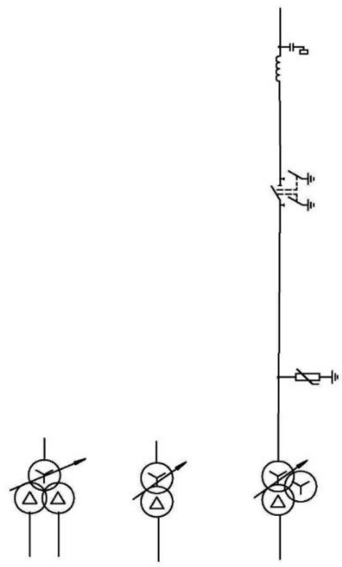

Fig. 1
unit (line — transformer) with disconnectors (diagram 110-1)

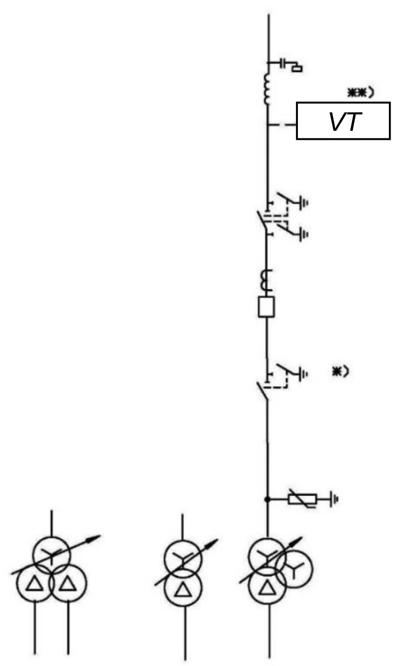

Fig. 2
unit (line — transformer) with switcher (diagram 110-3N):

1. the disconnector marked with *) is provided in case of supply on the MV side;
2. the voltage transformer marked with**) shall be installed with appropriate justification

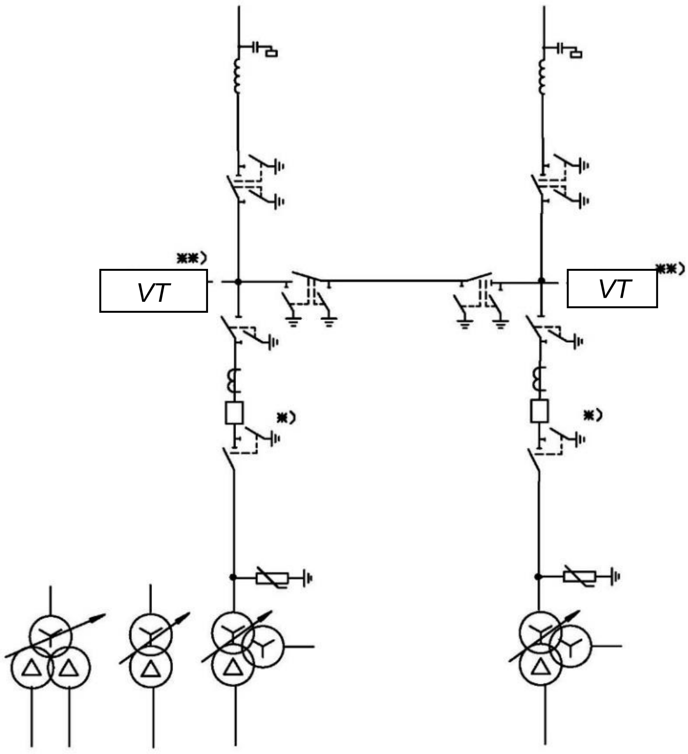

Fig. 3
Two units with switchers and non-automatic jumper at the line side (diagram 110-4N):
1. the disconnectors marked with *) are provided in case of supply on the MV side;
2. the voltage transformers marked with**) shall be installed with appropriate substantiation

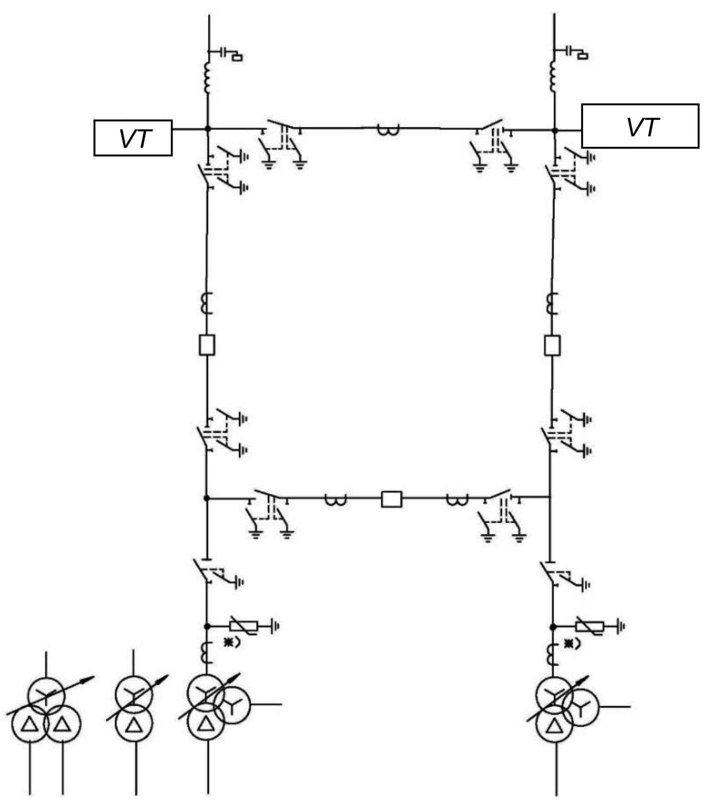

Fig. 4
Bridge with switchers in the line circuits and repair jumper at the line side (diagram 110-5N):
1. the voltage transformers marked with*) shall be installed with appropriate justification

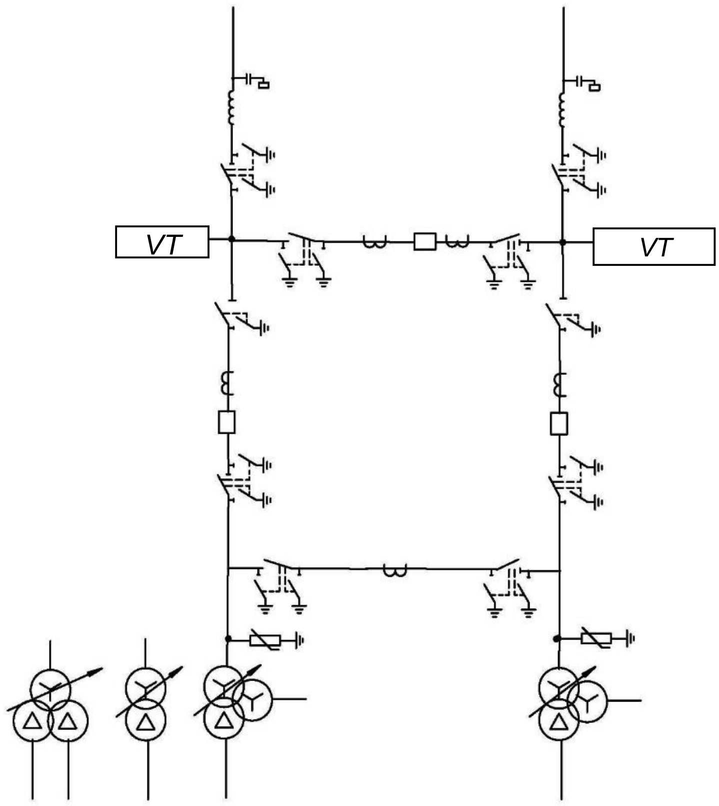

Fig. 5
Bridge with switchers in the transformer circuits and repair jumper at the transformer side (diagram 110-5AN)

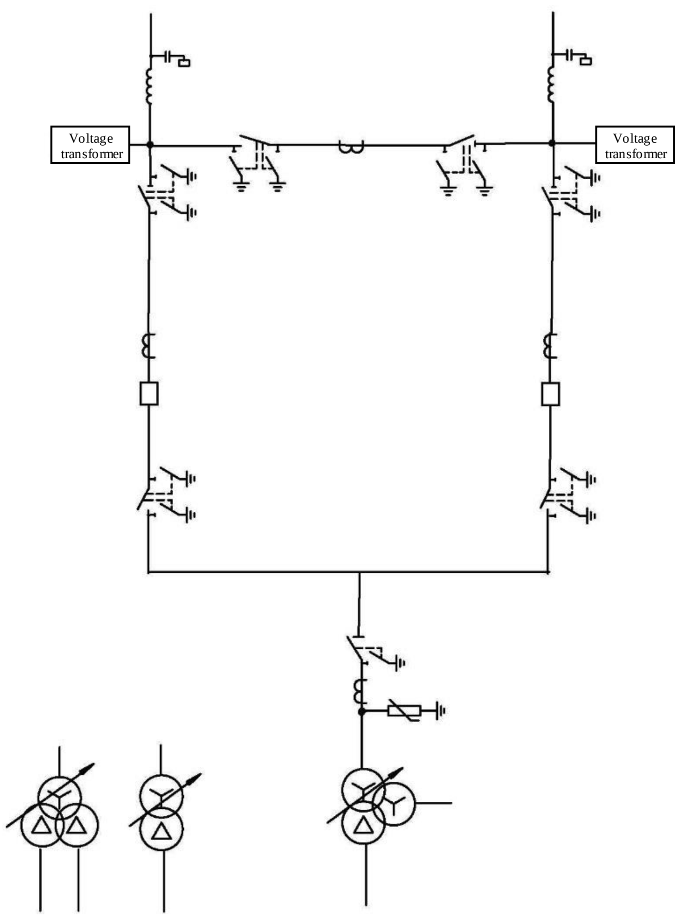

Fig. 6
Entry — outlet (diagram 110-6)

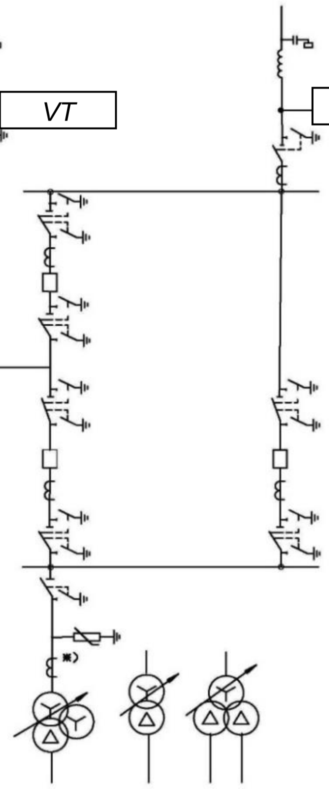

Fig. 7
Triangle (diagram 110-6N):
1. the voltage transformers marked with*) shall be installed with appropriate justification

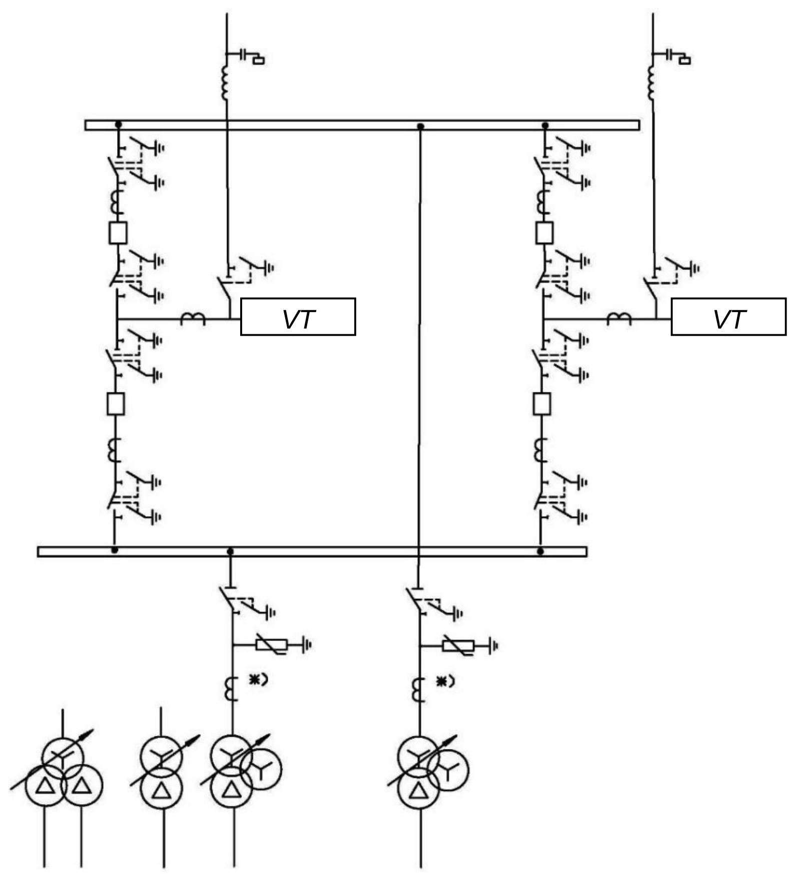

Fig. 8
Quadrangle (diagram 110-7):
1. the voltage transformers marked with*) shall be installed with appropriate justification

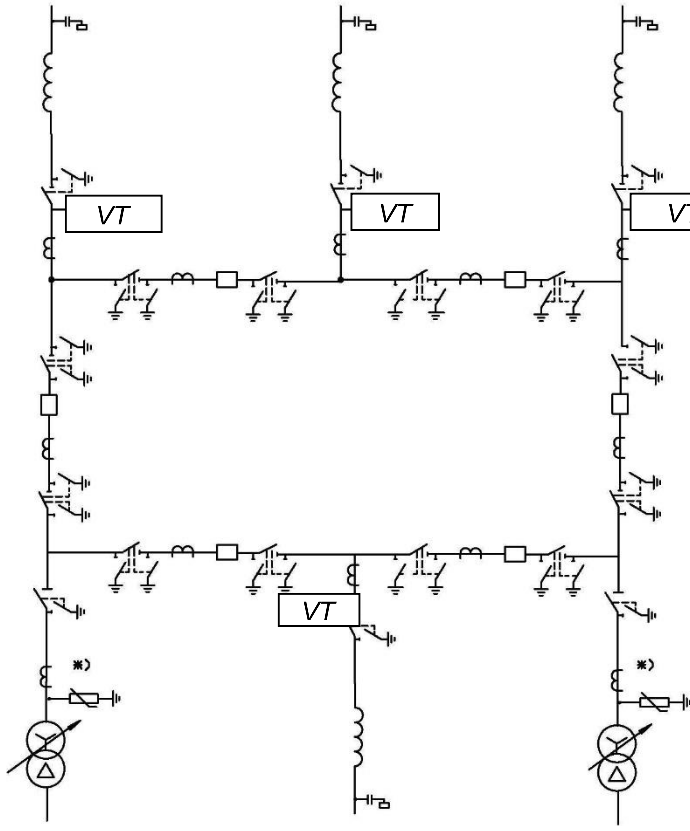

Fig. 9
Hexagon (diagram 110-8):
1. the voltage transformers marked with*) shall be installed with appropriate substantiation

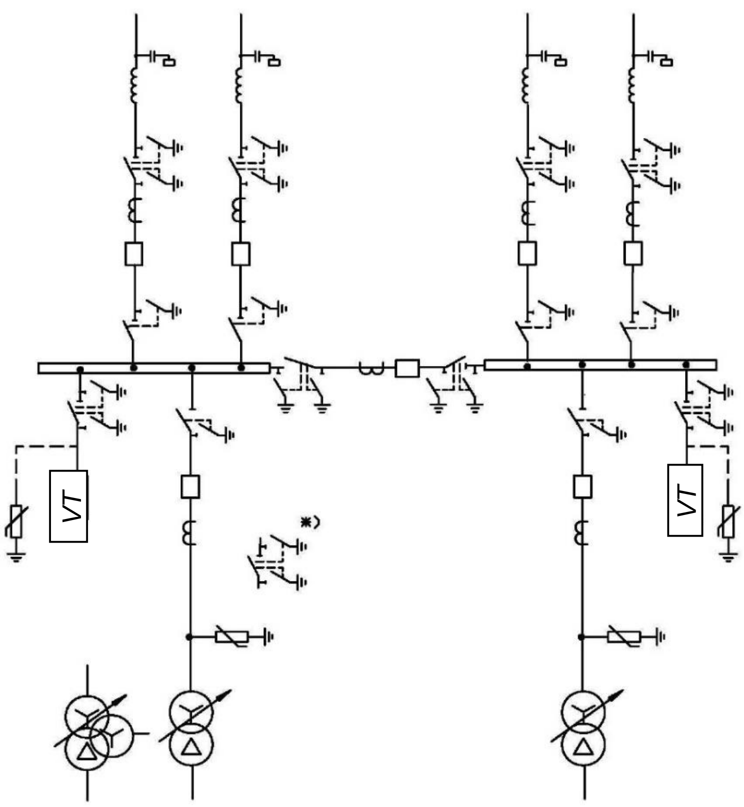

Fig. 10
One operating busbar sectioned by the switcher (diagram 110-9):
1. disconnectors marked with *) are installed with three-winding transformers or autotransformers in transformer circuits;
2. the need for surge arresters on busbars is indicated in the specific design

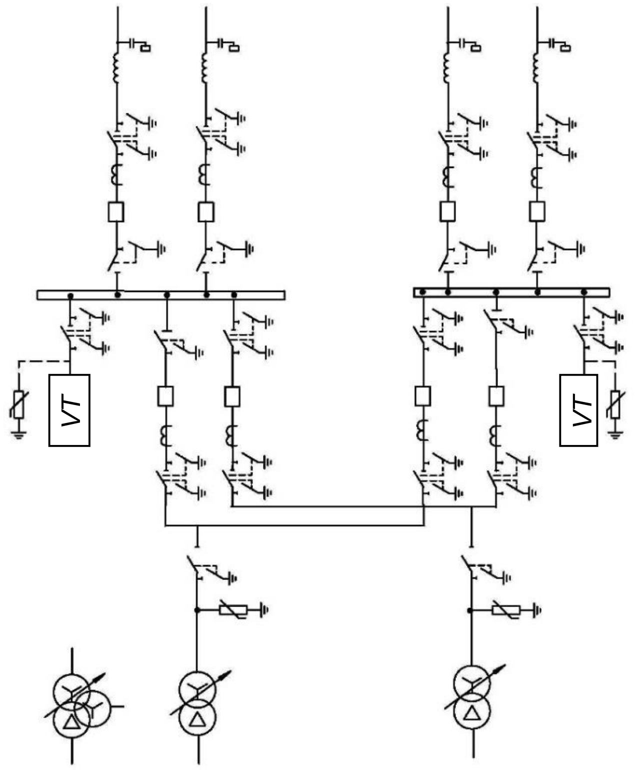

Fig. 11
One operating busbar sectioned by the transformer number, with connecting the transformers to bus sections via the switcher junction (diagram 110-9N):

1. the need for surge arresters on busbars is indicated in the specific design.

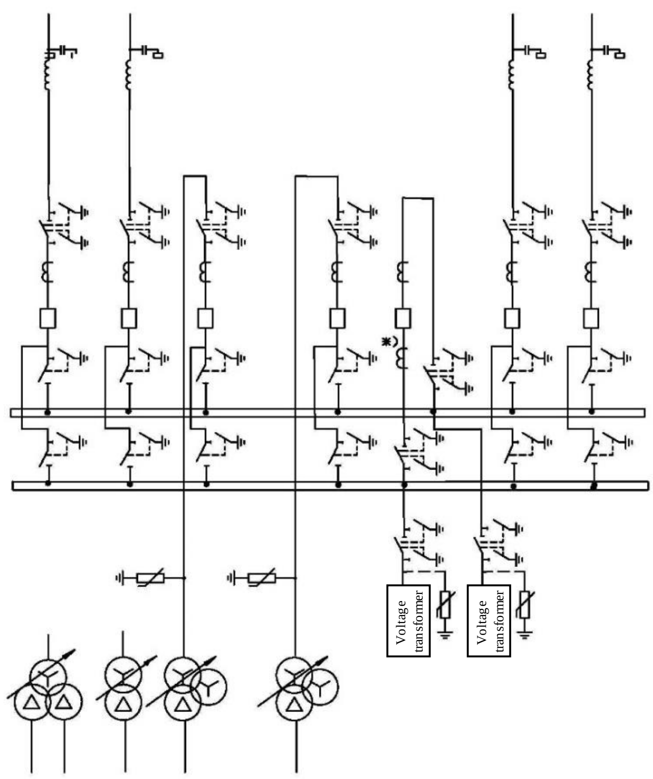

Fig. 12
Two operating busbars (circuit 110-13):

1. the voltage transformers marked with*) shall be installed with appropriate justification;
2. the need for surge arresters on busbars is indicated in the specific design

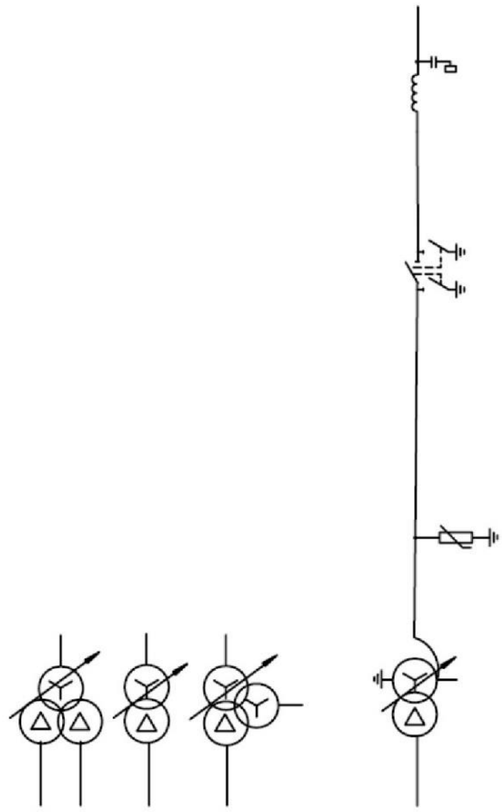

Fig. 13
Unit (line — transformer) with disconnectors (diagram 220-1)

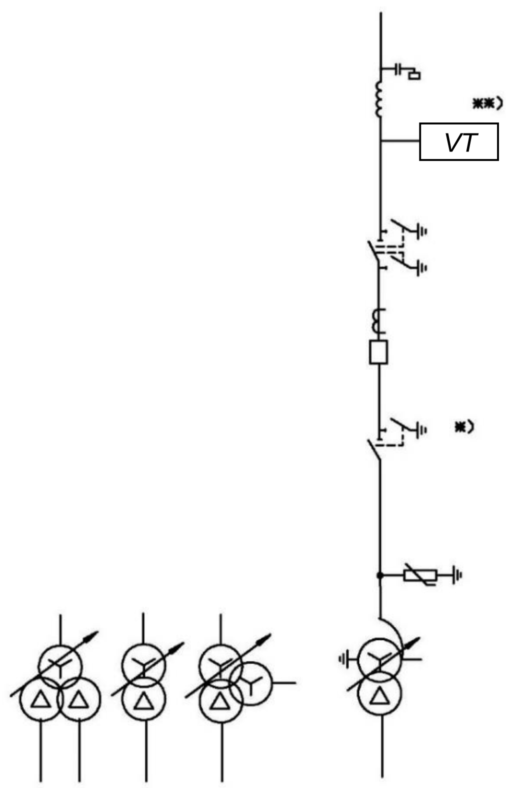

Fig. 14
Unit (line — transformer) with switcher (diagram 220-3N):

1. the disconnector marked with *) is provided in case of supply on the MV side;
2. the voltage transformer marked with**) shall be installed with appropriate justification

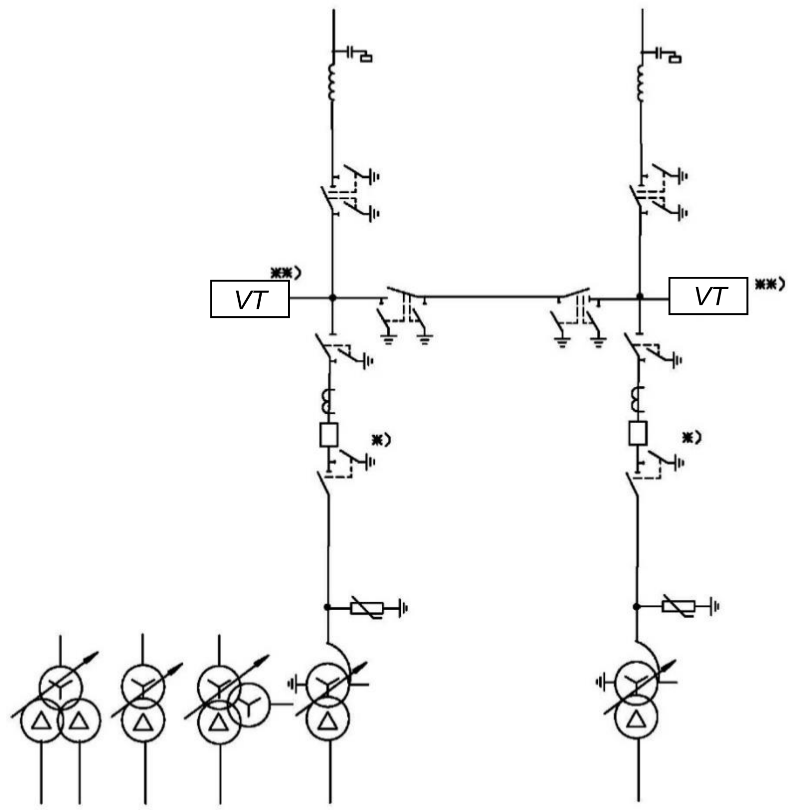

Fig. 15
Two units with switchers and non-automatic jumper at the line side (diagram 220-4N):
1. the disconnectors marked with *) are provided in case of supply on the MV side;
2. the voltage transformers marked with**) shall be installed with appropriate justification

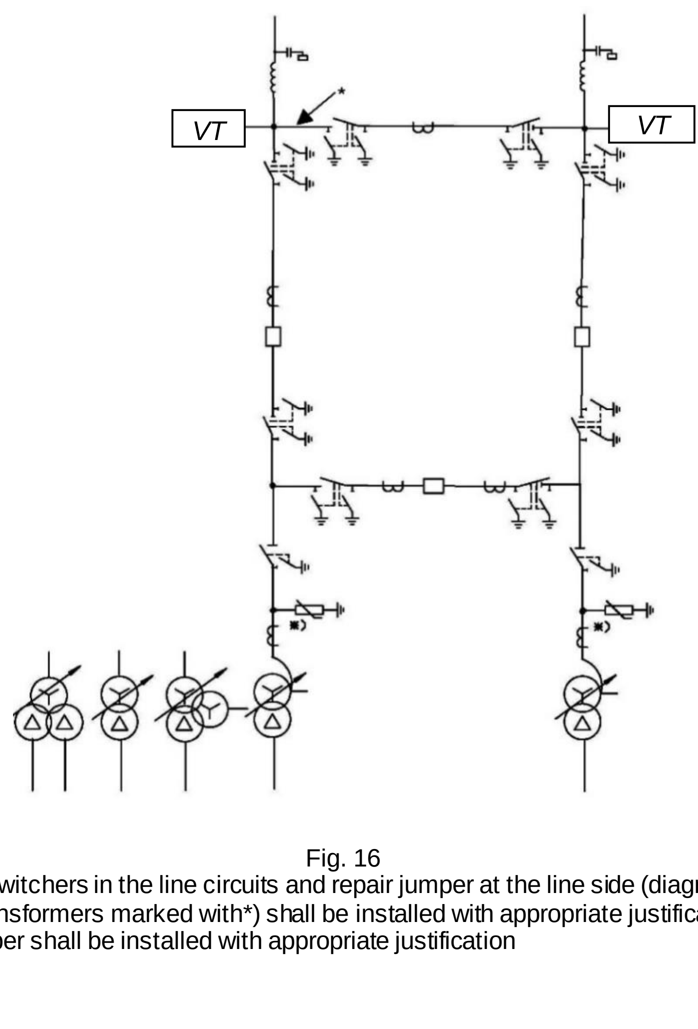

Fig. 16
Bridge with switchers in the line circuits and repair jumper at the line side (diagram 220-3N)
1. The voltage transformers marked with*) shall be installed with appropriate justification;
2. * — repair jumper shall be installed with appropriate justification

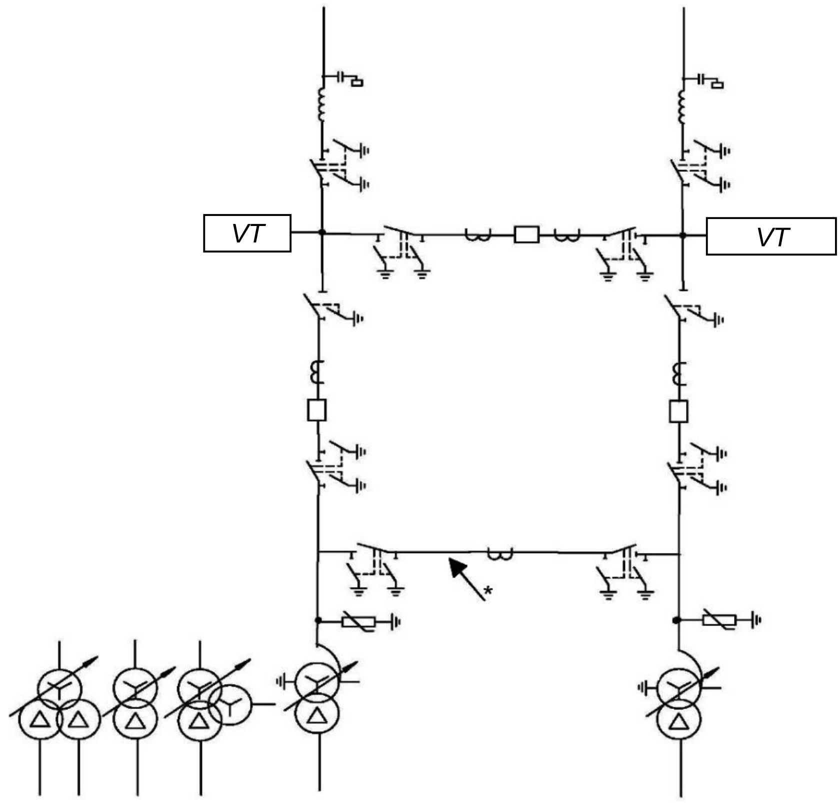

Fig. 17
Bridge with switchers in the transformer circuits and repair jumper at the transformer side (diagram 220-5AN):
1. * — repair jumper shall be installed with appropriate justification

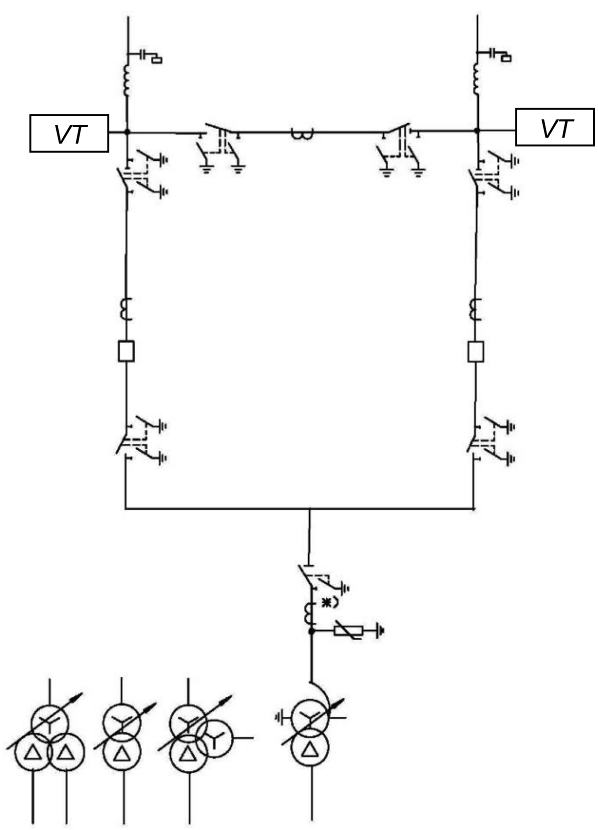

Fig. 18
Entry — outlet (diagram 220-6):
1. the voltage transformers marked with*) shall be installed with appropriate justification

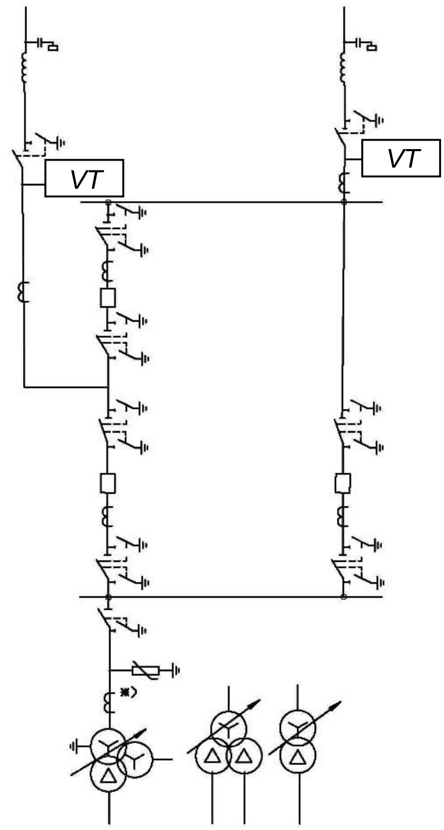

Fig. 19
Triangle (diagram 220-6N):

1. the voltage transformers marked with*) shall be installed with appropriate justification

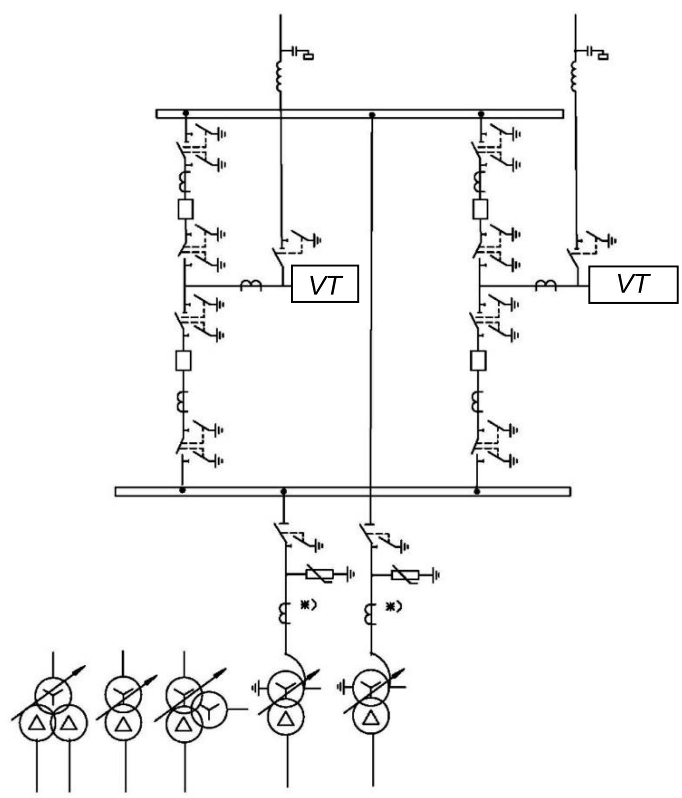

Fig. 20
Quadrangle (diagram 220-7):

1. the voltage transformers marked with*) shall be installed with appropriate justification

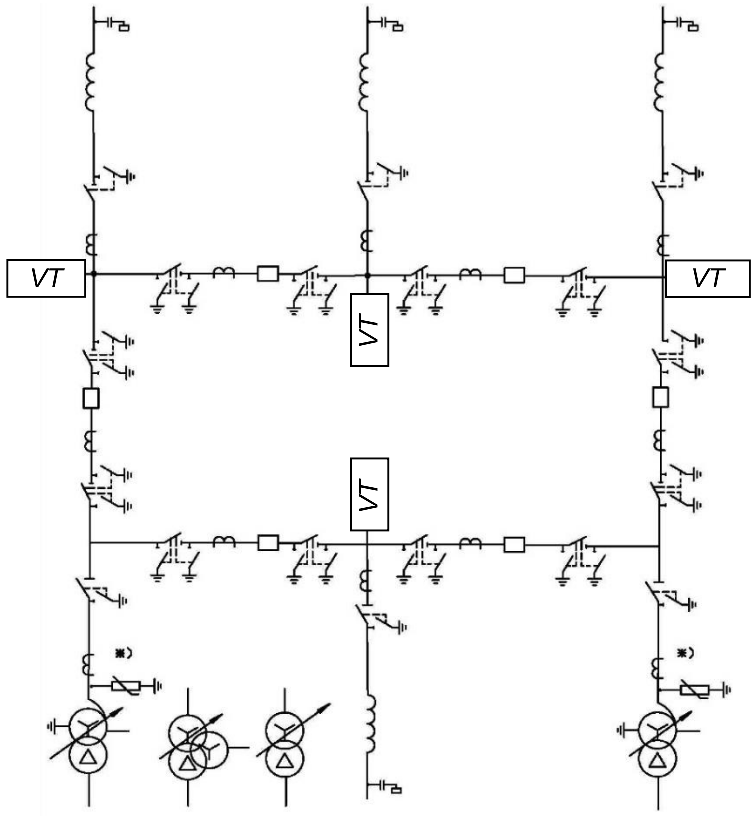

Fig. 21
Hexagon (diagram 220-8):
1. the voltage transformers marked with*) shall be installed with appropriate justification

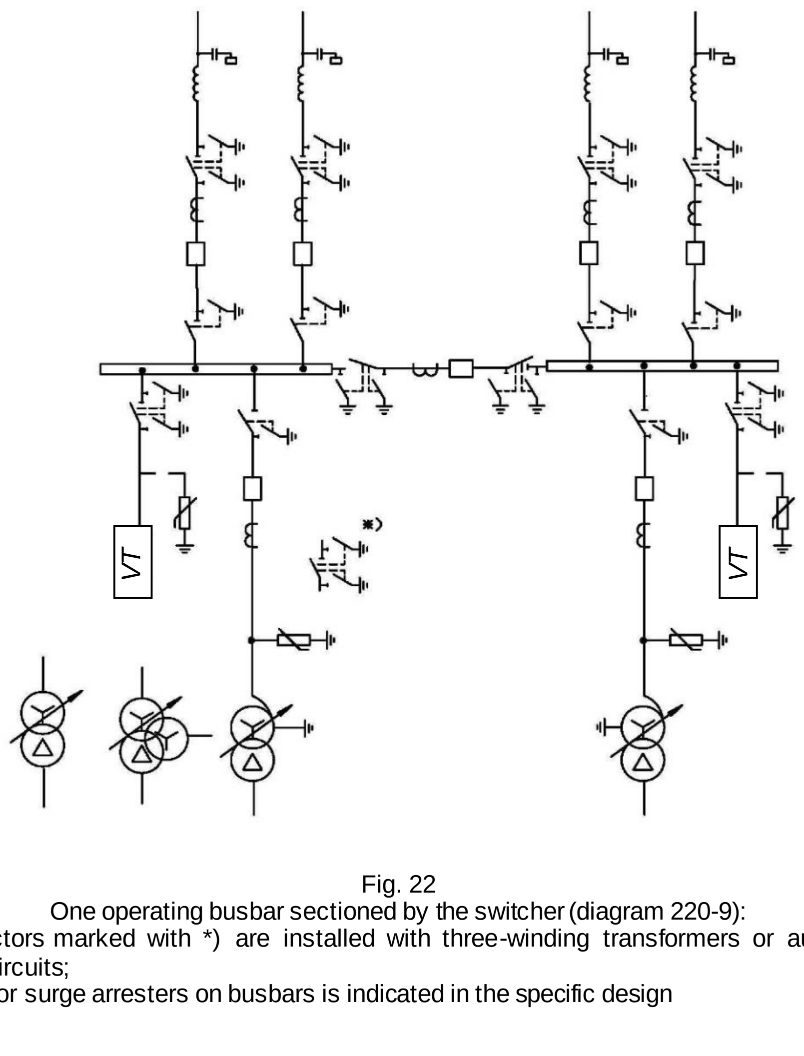

Fig. 22
One operating busbar sectioned by the switcher (diagram 220-9):
1. disconnectors marked with *) are installed with three-winding transformers or autotransformers in transformer circuits;
2. the need for surge arresters on busbars is indicated in the specific design

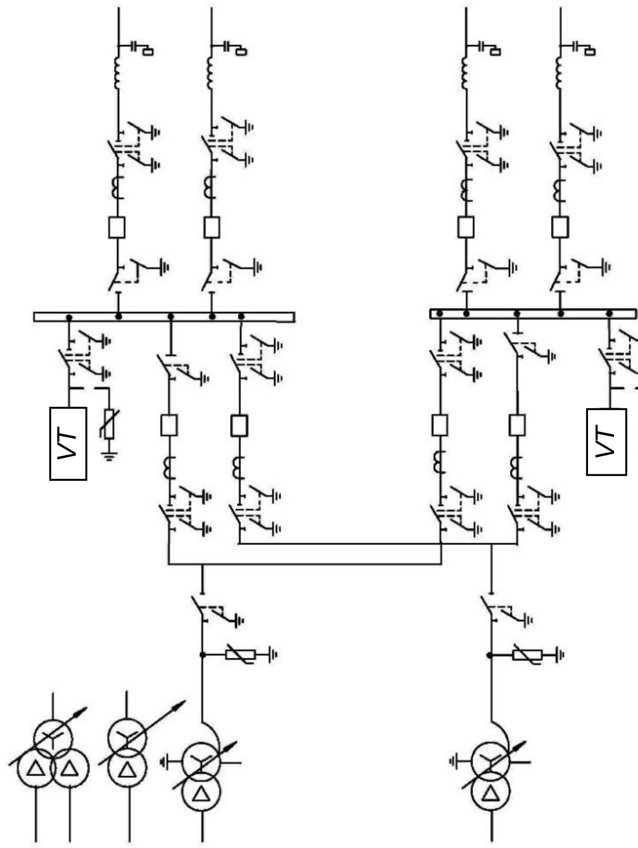

Fig. 23
One operating busbar sectioned by the transformer number, with connecting the transformers to bus sections via the switcher junction (circuit 220-9N):
1. the need for surge arresters on busbars is indicated in the specific design

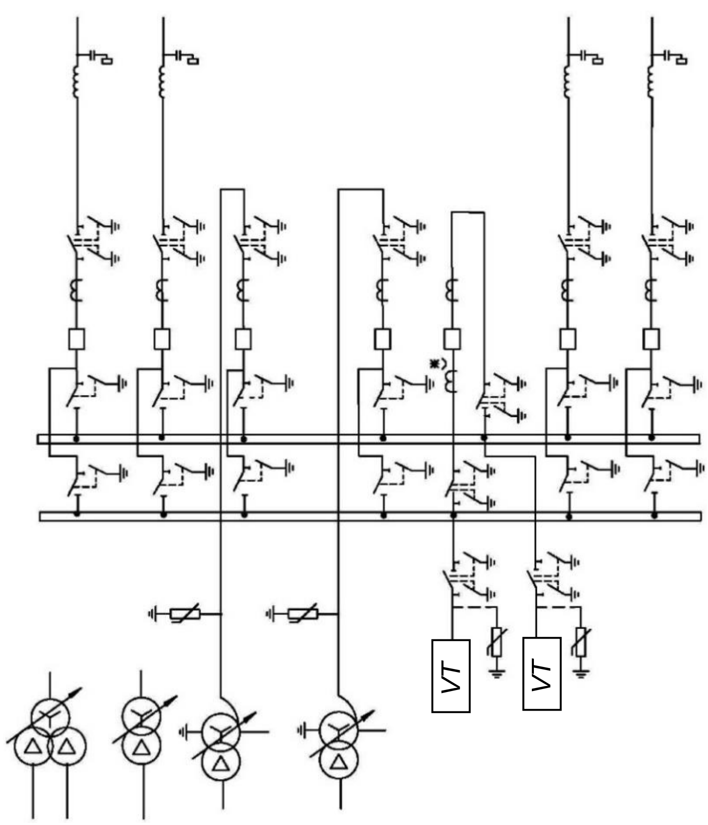

Fig. 24
Two operating busbars (diagram 220-13):
1. the voltage transformers marked with*) shall be installed with appropriate substantiation;
2. the need for surge arresters on busbars is indicated in the specific design

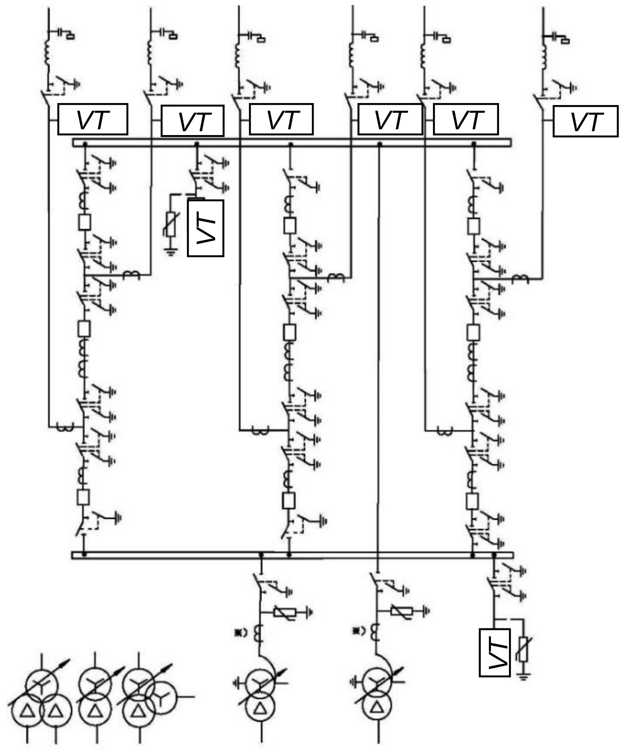

Fig. 25
Transformer busbar with one-and-a-half line connection (diagram 220-16)

1. the voltage transformers marked with*) shall be installed with appropriate justification;
2. the need for surge arresters on busbars is indicated in the specific design

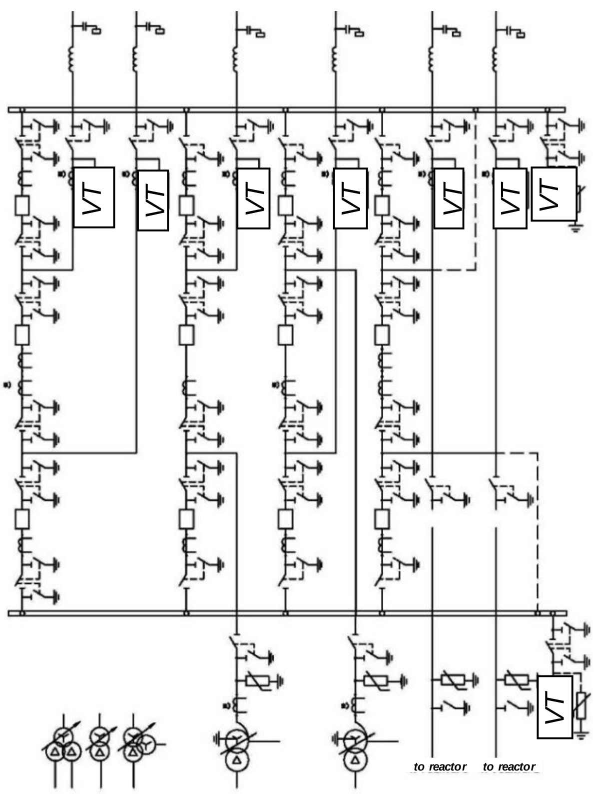

Fig. 26
One-and-a-half circuit (diagram 220-17):

1. the solid line shows the connection of the reactors to the lines and the dotted line — directly to the busbars;
2. the voltage transformers marked with*) shall be installed with appropriate justification;
3. the need for surge arresters on busbars is specified in the specific design

20 REQUIREMENTS FOR ELECTRICAL EQUIPMENT PROCEEDING FROM SHIP PURPOSE[1]

20.1 PASSENGER SHIPS

20.1.1 Supply and signalling.

20.1.1.1 Electric drives of sea-water pumps, air compressors and control-and-signalling devices of automatic sprinkler systems shall be supplied directly from the main and the emergency switchboards through separate feeders. The feeders shall be connected to an automatic switch fitted near the pump of the sprinkler system. Normally, the switch shall be connected to the feeder from the main distribution board, and in case of supply failure it shall automatically switch over to the supply feeder from the emergency switchboard. At the main and the emergency switchboards, the switches of the feeders shall be clearly marked off and shall be permanently in the "on" position. No other switches shall be fitted to these feeders.

20.1.1.2 Supply cables of sea-water pumps, air compressors and control-and-signalling devices of automatic sprinkler systems shall not run through machinery casings, galleys and other enclosed spaces of high fire hazard, except where the above devices and machinery are installed in the spaces in question.

20.1.1.3 In saloons, in way of stairs, passages and ladders to the boat deck, the lighting fixtures shall be supplied through two independent feeders at least (refer also to 6.2.3).

20.1.1.4 The supply systems of essential ship gear shall be so designed that a fire in one of the main vertical fire zone would not damage the above service supply systems in another main vertical fire zone. These requirements may be considered satisfied where the main and emergency supply feeders of the services running through any such zone are as distant from each other as possible both vertically and horizontally.

20.1.1.5 General alarm system shall consist of two independent groups: one for passengers and the other for the crew.

A special alarm, operated from the navigation bridge or fire control station, shall be fitted to summon the crew. The alarm may be part of the ship's general alarm system the requirements for which are specified in 7.4.

In passenger ships with a low-power electrical plant or with a number of passengers less than 36, one group of general alarms is permitted.

20.1.1.6 A fixed fire detection and fire alarm system shall meet the following additional requirements:

.1 be capable of remotely and individually identifying each detector and manually operated call point;

.2 one section of automatic and manual detectors shall not be located in more than one main vertical zone;

.3 when the system is required to sound a local audible alarm within the cabins where the detectors are located, means to silence the local audible alarms from the control panel shall not be permitted.

20.1.2 Supply from emergency sources of electrical power.

20.1.2.1 In passenger ships of unrestricted service and of restricted area of navigation **R1**, the emergency sources of electrical power shall simultaneously supply, during 36 h, the following services:

.1 emergency lighting for:

muster and embarkation stations for boarding life-saving appliances and spaces overboard where lifesaving appliances are launched according to 2.3.4 and 2.7.7, Part II "Life-Saving Appliances" of the RS Rules/E;

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[1] The present requirements are additions and amendments to the relevant requirements of Sections 1 — 18.

indicators of exits to the boat deck and notice-plates at the life-saving appliances;
exits from the spaces where a large number of passengers, special personnel or crew members can gather simultaneously;
alleyways, stairways and exits to the open deck in all accommodation and service spaces as well as passenger lift cars;
machinery spaces and generator rooms with their local control stations;
all control stations as well as main and emergency switchboards;
emergency diesel generator space;
wheelhouse;
chartroom and radioroom;
stowage positions for emergency and fireman's outfit and positions where manual fire alarms are fitted; steering gear compartments;
positions of attendance upon emergency fire and bilge pump, sprinkler pump and starting positions of their motors;
helicopter hangars and landing areas;
gyrocompass space;
medical space.

.2 navigation lanterns, lanterns of "Vessel not under command" signal and other lanterns required by Part III "Signal Means" of the RS Rules/E;

.3 radio equipment and navigational equipment according to the requirements of Parts IV "Radio Equipment" and V "Navigational Equipment" of the RS Rules/E;

.4 internal communication, announcing and general alarm systems;

.5 fire detection and alarm systems, fire door control devices and indicators showing the position of fire doors specified in 2.2.3.3, Part VI "Fire Protection";

.6 sound signal means (whistle, gong, etc.), daylight signalling lamps, manual summoning signals and other signals as required under emergency conditions;

.7 one of the fire pumps, a pump of the automatic sprinkler system, an electric-driven pump of the pressure water-spraying system referred to in 3.4.7, Part VI "Fire Protection", as well as electrical equipment used to ensure operation of the high expansion foam fire extinguishing systems referred to in 3.7.3, Part VI "Fire Protection";

.8 emergency bilge pump and equipment essential for operation of remote-controlled bilge valves;

.9 services listed in 7.3.6 and 7.3.8, Part VI "Fire Protection" for Class **INF2** and **INF3** ships in accordance with classification given in 7.3.2, Part VI "Fire Protection", regardless of area of navigation and tonnage of the ship;

.10 other systems, which operation will be considered by the Register to be vital for ensuring the safety of the ship and persons on board.

The services indicated in 20.1.2.1.3 — 20.1.2.1.6 may be fed from its own accumulator batteries located according to 9.2 and having a capacity sufficient for their supply for a period of 36 h.

For ships of restricted areas of navigation **R2**, **R2-RSN**, **R2-RSN(4,5)**, **R3-RSN** and **R3**, the period of 36 h may be reduced to 12 h.

20.1.2.2 Emergency sources of electrical power shall ensure the supply of steering gear in accordance with 5.5.6.

20.1.2.3 Emergency sources of electrical power shall supply, for a period of 30 min, the following services:

.1 electrical drives of watertight doors together with their indicators and warning signals. Sequential operation of the doors may be permitted providing all doors can be closed in 60 s;

.2 electric drives of passenger lifts. Passenger lifts may be operated sequentially;

.3 supplementary lighting shall be provided in all cabins to clearly indicate the exit. Such lighting may be connected to an emergency source of power or have a self-contained source of electrical power in each cabin.

20.1.2.4 Where a generator serves as the emergency source of electrical power, it shall be:

.1 driven by an internal combustion engine (refer to 2.2.5, Part IX "Machinery");

.2 automatically started in case of supply failure, and automatically switched over to the busbars of the emergency switchboard; services listed under 20.1.2.7 shall be automatically supplied from the emergency generator. The total time for starting and carrying the board by the generator shall not exceed 45 s;

.3 for an emergency, a transitional source of electrical power shall be provided, which shall be activated immediately upon de-energizing.

20.1.2.5 Where an accumulator battery serves as the emergency source of electrical power, it shall:

.1 operate without recharging and with voltage across its terminals within 12 % of rated voltage during the whole discharge period, where voltage variations across the terminals of accumulator battery connected to an electronic voltage converter are determined by the permissible range of voltage variation across the terminals of the converter;

.2 be automatically connected to the busbars of the emergency switchboard in case of supply failure and supply at least the services listed under 20.1.2.7 during the time stipulated by 20.1.2.1.

20.1.2.6 For the emergency transitional source of electrical power required by 20.1.2.4.3, an accumulator battery shall be used, which shall operate without recharging and with voltage across its terminals within 12 % of rated voltage during the whole discharge period. Voltage variations across the terminals of accumulator battery connected to an electronic voltage converter are determined by the permissible range of voltage variation across the terminals of the converter, which shall not be above values specified in 2.1.3.1.

20.1.2.7 The capacity of the battery serving as transitional source of electrical power shall be sufficient for supplying the services listed below during 30 min:

.1 lighting and necessary navigation lights according to 20.1.2.1.1 and 20.1.2.1.2;

.2 internal communication and announcing systems required in an emergency;

.3 general alarm system, fire detection and alarm systems, control devices of fire doors and indicators showing the position of fire doors specified in 2.2.3.3, Part VI "Fire Protection";

.4 daylight signalling lamps, sound signal means (whistles, gongs, etc.) and other types of signals required under emergency conditions;

.5 arrangements for closing watertight doors, their position indicators and signals warning of their closing.

Sequential closing is permitted;

.6 ship's security alarm system and AIS installation required by Part IV "Radio Equipment" and Part V "Navigational Equipment" of the RS Rules/E.

Services listed under 20.1.2.7.2 — 20.1.2.7.6 may be supplied from their own accumulator batteries, which shall ensure their supply during the time necessary.

20.1.3 Electrically powered low-location lighting (refer to 8.5.5, Part III "Equipment, Arrangements and Outfit").

20.1.3.1 The low-location lighting system shall be connected to the busbars of the emergency switchboard so as to be powered by the main source of electrical power under normal circumstances and also by the emergency source of electrical power when the latter is in operation.

The low-location lighting system shall function at all times.

20.1.3.2 Where an accumulator battery is the emergency source of electrical power, its capacity shall be sufficient for powering the low-location lighting system for at least 60 min.

20.1.3.3 The additional emergency lighting required by 20.3.3 may be accepted to form partly or wholly the low-location lighting system, provided that such system complies with the requirements of 20.1.3.

20.1.3.4 The electrically powered low-location lighting system shall ensure the following minimum standards of luminance:

.1 for luminous surface of the planar source — 10 cd/m^2, the light band being not less than 15 mm in width;

.2 for the point source — 35 mcd in the directions of approach and viewing, along with that: the direction of viewing for the sources located on a horizontal plane, i.e. on the deck, shall be within a cone with an angle of 60°, the axis of which is inclined at 30° to the source installation plane (refer to Fig. 20.1.3.4.2-1);

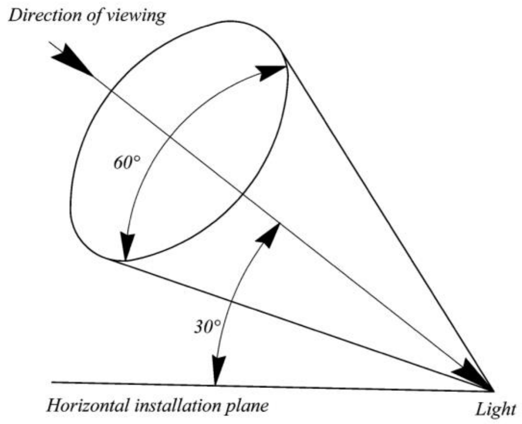


Fig. 20.1.3.4.2-1

the direction of viewing for the sources located on a vertical plane, i.e. on the bulkheads (e.g. for marking of the door handles) shall be within a cone with an angle of 60°, the axis of which is perpendicular to the source installation plane (refer to Fig. 20.1.3.4.2-2);

spacing between sources shall be not more than 300 mm.

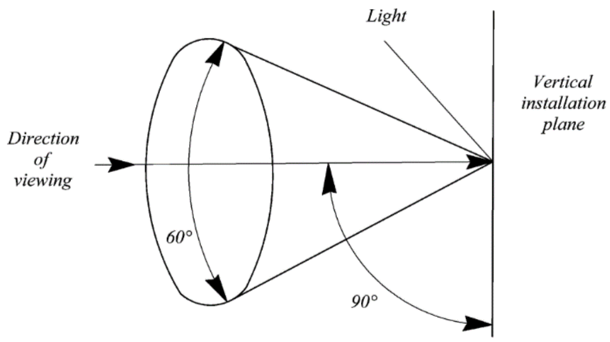


Fig. 20.1.3.4.2-2

20.1.3.5 Power supply of the LLL system shall be such that a failure of any single light or fire in one fire zone or on one deck do not result in lighting and escape route marking in another fire zone being ineffective.

20.1.3.6 Failure or damage, other than short circuit, of any single light, shall not result in loss of visible delineation of the escape route at a length of more than 1 m.

20.1.3.7 The electrical equipment (lights) shall be provided with a minimum degree of ingress protection of IP55.

20.1.4 Additional requirements for passenger ships having a safety centre.

20.1.4.1 Internal communication shall comply with the requirements of 2.2.8.3 and 2.2.8.5, Part VI "Fire Protection".

20.1.4.2 General alarm shall comply with the requirements of 2.2.8.6.4, Part VI "Fire Protection".

20.1.4.3 Indication of closing watertight and fire doors shall comply with the requirements of 2.2.8.6.3, Part VI "Fire Protection".

20.1.4.4 Flooding detection system shall comply with the requirements of 2.2.8.6.8, Part VI "Fire Protection".

20.1.4.5 Indication of closing doors on passenger ro-ro ships shall meet the requirements of 2.2.8.6.7, Part VI "Fire Protection".

20.1.5 Additional requirements for passenger ships having length, as defined in 1.2.1 of the Load Line Rules for Sea-Going Ships[1], of 120 m or more or having three of more main vertical zones.

20.1.5.1 Steering systems and steering-control systems shall comply with the requirements of 2.2.6.7.2 and 2.2.6.8, Part VI "Fire Protection".

20.1.5.2 Lighting of safety areas shall comply with the requirements of 2.2.6.13.7, Part VI "Fire Protection".

20.1.5.3 Lighting along escape routes, at assembly stations and at embarkation stations of life-saving appliances, shall comply with the requirements of 2.2.7.4.2, Part VI "Fire Protection".

20.1.5.4 Internal communication shall additionally comply with the requirements of 2.2.6.7.6, 2.2.6.8 and 2.2.7.4.4, Part VI "Fire Protection".

20.1.5.5 Flooding detection system shall comply with the requirements of 2.2.6.7.7 and 2.2.6.8, Part VI "Fire Protection".

[1] Hereinafter referred to as "the RS Rules/LL".

20.2 OIL TANKERS AND OIL RECOVERY SHIPS

20.2.1 General.

The requirements of the Chapter cover the electrical equipment of oil tankers and oil recovery ships intended for the carriage of petroleum products having a flash point 60 °C and below and petroleum products having a flash point 60 °C and above, which require heating up to a temperature less than 15 °C below the flash point.

The electrical equipment of oil tankers (>60 °C), oil recovery ships (>60 °C) and bilge water removing ships (>60 °C) is covered by the requirements of 20.2.3.2.3.2, 20.2.5 and 20.2.6.2 (refer also to 9.6.5, Part VIII "Systems and Piping").

The requirements of this Chapter specify the boundaries of dangerous zones, the division of ship's spaces and areas into zones, the installation of electrical equipment in hazardous spaces and areas in compliance with IEC 60092-502:1999 "Electrical Installations in Ships — Tankers — Special Features".

20.2.2 Distribution of electrical power.

For distribution of electrical power on board the ship, only the following systems may be used:

.1 two-wire insulated system for direct current;

.2 two-wire insulated system for single-phase alternating current;

.3 three-wire insulated system for three-phase alternating current (also for voltage above 1000 but not in excess of 11000 V a.c.);

.4 three-wire system with neutral earthed through a high-value resistor for voltages above 1000 but not in excess of 11000 V a.c., provided that any possible resulting current does not flow directly through any dangerous spaces and areas.

20.2.3 Dangerous zones, spaces and areas.

20.2.3.1 Classification of dangerous zones.

Zone 0, in which an explosive gas/air mixture is continuously present or present for long periods.

Zone 1, in which an explosive gas/air mixture is likely to occur in normal operation.

Zone 2, in which an explosive gas/air mixture is not likely to occur, and if it occurs it will only exist for a short time.

20.2.3.2 Division of spaces and areas into zones.

20.2.3.2.1 *Zone 0:*

.1 internal areas of cargo compartments and tanks, cargo piping and transfer systems of recovered oil;

.2 open areas lying at a height up to 1 m from oil-covered water surface (for ships operating in the oil spill).

20.2.3.2.2 *Zone 1:*

.1 cofferdams and segregated ballast tanks adjoining cargo tanks as well as the forepeak, if served by a system connected to ballast tanks installed in the cargo area;

.2 enclosed or semi-enclosed spaces containing cargo pumps or cargo piping, provided the latter is not all-welded;

.3 enclosed and semi-enclosed spaces above the deck of cargo compartments and tanks, which have their bulkheads above or level with the bulkheads of the cargo compartments and tanks;

.4 enclosed and semi-enclosed spaces immediately above cargo pump rooms and also above vertical cofferdams adjoining cargo compartments and tanks unless separated by a gastight deck and provided with mechanical ventilation;

.5 areas and spaces other than cofferdams adjoining cargo compartments and tanks and located below cargo compartment and tank top;

.6 areas and semi-enclosed spaces on the open deck within 3 m of any outlets other than ventilation outlets, cargo tank manholes and hatches, pump rooms and cofferdams adjoining cargo tanks, of cargo valves and cargo piping flanges, as well as areas on open deck within 3 m of cargo vapour outlet (small volumes) and of the pump room ventilation outlets mentioned in 9.7.4 and 12.4.6, Part VIII "Systems and Piping";

.7 areas on open deck, or semi-enclosed spaces on open deck in the vicinity of any cargo gas outlet arranged according to 9.7.11, Part VIII "Systems and Piping", equipped with high-speed devices to ensure the passage of large volumes of gas or vapour mixture at the rate of 30 m/s at least during cargo loading and ballasting or during discharging, within a vertical cylinder of unlimited height and 6 m radius centred upon the center of the outlet, and within a hemisphere of 6 m radius below the outlet;

.8 areas on open deck, or semi-enclosed spaces on open deck, within 1,5 m of cargo pump room entrances, cargo pump room ventilation inlet, openings into cofferdams or other zone 1 spaces;

.9 areas on open deck within spillage coamings and trays surrounding cargo manifold valves and 3 m beyond these, up to a height of 2,4 m above the deck;

.10 areas on the open deck above cargo compartments and tanks where the structures limit natural ventilation, over the full breadth of the ship and 3 m fore and aft of their boundary bulkheads up to a height of 2,4 m above the deck as well as enclosed and semi-enclosed spaces within this area. For ships operating in the oil spill, this area is extended to cover the whole length of the ship;

.11 storage spaces for cargo hoses and equipment for collecting spilt oil (oil collectors);

.12 enclosed and semi-enclosed spaces having direct access or other openings into one of the above areas and spaces;

.13 spaces and areas above cofferdams adjoining cargo compartments and tanks, which are not divided by oil- and gastight bulkheads and decks, not adequately ventilated and entered from an upper deck.

20.2.3.2.3 *Zone 2:*

.1 areas above zone 1 over the full breadth and length of the ship to a height of 6 above the deepest load waterline (for ships operating in the oil spill);

.2 internal areas of cargo compartments and tanks, slop tanks, cargo piping, transfer systems of recovered petroleum products having a flash point >60 °C and their ventilation systems;

.3 areas on open deck or semi-enclosed spaces 4 m beyond the cylinder and 4 m beyond the sphere with the radius of 6 m defined in 20.2.3.2.2.7;

.4 areas or spaces within 2 m of the areas defined in 20.2.3.2.2.6.

.5 areas on the open deck above cargo compartments and tanks where unlimited natural ventilation is provided, over the full breadth of the ship and 3 m fore and aft of their boundary bulkheads up to a height of 2,4 m above the deck around enclosed and semi-enclosed spaces of area 1.

20.2.3.2.4 Spaces and areas not included in zones 0, 1 and 2 are considered safe.

20.2.3.3 Enclosed spaces having direct access to or other openings into areas listed under 20.2.3.2.2.10 and 20.2.3.2.3.5 are not regarded as dangerous if provision is made for two self-closing gastight doors forming an air lock and, additionally, for mechanical supply ventilation with air suction from locations outside dangerous zones.

20.2.3.4 In the case of ships operating in the oil spill, entrances, ventilation openings (both for suction and discharge) and other openings of safe spaces such as accommodation, service spaces and machinery spaces, control stations and wheelhouse, which have no gastight closures, shall not be located more than 6 m below the deepest waterline and, under all circumstances, shall be outside dangerous zones.

Entrances to safe spaces lying more than 6 m below the deepest waterline or within dangerous zones shall be provided with air locks. In such spaces, openings more than 6 m below the waterline shall bear gastight closures when operating in the oil spill.

20.2.4 Electrical equipment in hazardous areas.

20.2.4.1 Only the following electrical equipment may be considered for zone 0 spaces:

.1 certified intrinsically-safe apparatus of category (ia);

.2 simple electrical apparatus and components (for example, thermocouples, photocells, strain gauges, junction boxes, switching devices, included in intrinsically-safe circuits of category (ia), not capable of storing or generating electrical power or energy for ignition of explosive mixture even in case of disconnection, short circuit or earth fault in the intrinsically-safe circuit, as well as complying with IEC 60079-14.

20.2.4.2 Only the following electrical equipment may be considered for zone 1 spaces:

.1 any type that may be considered for zone 0;

.2 certified intrinsically-safe apparatus of category (ib);

.3 simple electrical apparatus and components (for example, thermocouples, photocells, strain gauges, junction boxes, switching devices, included in intrinsically-safe circuits of category (ib), not capable of storing or generating electrical power or energy for ignition of explosive mixture at normal operating conditions, as well as complying with IEC 60079-14;

.4 certified flameproof type (d);

.5 certified pressurized type (p). In this case automatic shutdown is required when values of overpressure fall below minimum prescribed values;

.6 certified increased safety type (e). In this case the electric motors with voltage of 3kV and above require an addition protection such as air purging prior to the start to reduce the risk of spark striking in the air gap;

.7 with compound sealing (m);

.8 special explosion protection (s);

.9 echo sounder transducers and their cables in compliance with the requirements of Part V "Navigational Equipment" of the RS Rules/E, cables of an impressed current cathodic protection system, housed within corrosion-resistant steel pipes with gastight connections up to the upper deck and not located adjacent to a cargo tank bulkhead (refer also to 16.8.4.2);

.10 through runs of cables.

20.2.4.3 The electric motors driving the arrangements located in pump rooms shall be installed in adjacent flameproof spaces (refer also to 4.2.5, Part VII "Machinery Installations"). The electric motors shall be fitted with remote shut-down devices located outside the spaces where the motors are installed and above the cargo tank deck (refer also to 9.4.4, Part VIII "Systems and Piping").

20.2.4.4 Lighting in pump rooms shall be interlocked with ventilation of these spaces in such a way as to ensure the possibility of the lighting switching on with ventilation in operation only. Failure of the ventilation system shall not result in the lighting switching off. Emergency lighting, if fitted, shall not be interlocked with ventilation.

20.2.4.5 Only the following electrical equipment may be considered for zone 2 spaces:

.1 any type that may be considered for zone 1;

.2 tested specially, for example type (n) protection;

.3 the type which ensures the absence of sparks and arcs and of "hot spots" during its normal operation.

20.2.5 Portable electrical equipment used for collecting spilt oil.

20.2.5.1 Portable equipment for collecting and transfer of oil shall be of safe type.

20.2.5.2 Distribution boards and socket outlets for supplying portable oil-collecting and transfer equipment on deck shall be permanently fitted in such a way that a cable connected to them would not pass through door coamings or other closed openings serving as a boundary of dangerous spaces and zones.

The design of such distribution devices and socket outlets shall provide for an interlock that would rule out the possibility of the portable electrical equipment being connected to them when energized and ensure protection from short-circuit currents and overvoltage in each phase.

20.2.5.3 Flexible cables for connection of portable electrical equipment used for collecting spilt oil shall have a metallic braid (screen) covered by an external proof sheathing of an oil-resistant material.

20.2.6 Installation of cables.

20.2.6.1 On the decks of oil tankers and oil recovery ships, cables shall run on flying bridges in suitable conduits (grooves). Single cables may be laid in pipes. Where the flying bridges are within zone 1, cables complying with the requirements of 2.9.11 shall only be installed.

20.2.6.2 When cables are installed in conduits (grooves), the following requirements shall be met:

.1 cables in conduits (grooves) shall be loosely laid in rows on separators of non-metallic materials; in this case, the possibility of lateral displacement of the row (cable) shall be excluded. It is permitted to use methods of fixed pipeless installation of cables (in cable hangers, under clips), which shall be approved by the Register from the viewpoint of the design features; in case of fixed installation cables shall be laid not more than in two rows;

.2 cables shall not be in contact with metal parts of the conduit (groove);

.3 cables shall not be subjected to constant or variable tensions due to deformation of the ship's hull and shall be protected from this deformation, especially in way of detachable or sliding connections between the gangway or platform and superstructures. In way of detachable or sliding connections of the gangway or platform provision shall be made for expansion loops having the inside radius of not less than 10 diameters of the thickest cable;

.4 cables shall be protected from direct exposure to solar radiation, sea waves, oil products carried on board the ship and from mechanical damage;

.5 cables shall be separated from sources of heat by a distance specified in 16.8.4.1;

.6 cables runs on the passageway platform or in pipes inside spaces within zone 1, as well as expansion loops shall not be located below 300 mm from the cargo tank deck;

.7 metal sheaths or armours of cables shall be earthed at both ends. For final subcircuits earthing of the metal sheath may be effected only at the supply end.

20.2.6.3 In systems with voltages specified in 20.2.2.1.4, only cables having copper screens with additional insulation covering may be used. The cross-sectional area of a screen shall be at least the cross-sectional area of a conductor.

20.2.7 Integrated cargo and ballast systems.

20.2.7.1 These requirements are applicable to integrated cargo and ballast systems on tankers, irrespective of the size or type of the tanker.

Within the scope of these requirements, integrated cargo and ballast system means any integrated hydraulic and/or electric system used to drive both cargo and ballast pumps (including active control and safety systems and excluding passive components, e.g. piping).

20.2.7.2 Measures shall be taken to prevent cargo and ballast pumps becoming inoperative simultaneously due to a single failure in the integrated cargo and ballast system, including its control and safety systems.

20.2.7.3 The emergency stop circuits of the cargo and ballast pumps shall be independent from the circuits for the control systems. A single failure in the control system circuits or the emergency stop circuits shall not render the integrated cargo and/or ballast system inoperative.

20.2.7.4 Manual emergency stops of the cargo pumps shall be arranged in a way that they are not cause the stop of the power pack making ballast pumps inoperable.

20.2.7.5 The control systems shall be provided with a duplicate power supply from the main switchboard. The failure of any power supply shall provide audible and visible alarm activation at each pump control location.

20.2.7.6 In the event of failure of the automatic or remote control systems, a secondary means of control shall be made available for the operation of the integrated cargo and ballast system. This can be achieved by manual overriding and/or redundant arrangements within the control systems.

20.3 SHIPS INTENDED FOR CARRIAGE OF MOTOR VEHICLES WITH FUEL IN THEIR TANKS INCLUDING COMPRESSED HYDROGEN OR NATIONAL GAS FOR THEIR PROPULSION

20.3.1 General.

20.3.1.1 The requirements of this Chapter are applicable to electrical equipment of holds and other spaces and areas intended for the carriage of motor vehicles with fuel in their tanks necessary for their propulsion.

20.3.1.2 The holds and spaces specified in 20.3.1.1 belong to the category of dangerous spaces and zones.

20.3.1.3 Cables shall be protected against mechanical damage. Cables installed horizontally shall be positioned at a distance not less than 450 mm above the continuous deck or platform preventing a free propagation of gases in the downward direction. The sealings where cables penetrate bulkheads and deck shall be gastight.

20.3.1.4 Electrical equipment installed in ventilation ducts shall be of the following safe types: increased safety (*Exe*) or with flameproof enclosure (*Exd*) and be able to operate in the explosive gas environment and comply with IIC (compressed hydrogen) or IIA (compressed natural gas) gas mixture.

20.3.1.5 The lighting system in holds and spaces specified in 20.3.1.1 shall be arranged at least in two groups, each supplied separately from an independent circuit.

20.3.2 Installation of electrical equipment in holds and spaces intended for carriage of motor vehicles with fuel in their tanks in passenger ships and ferries.

20.3.2.1 In holds and compartments, in spaces located at a height of more than 450 mm above the cargo deck or platform preventing free penetration of gases downwards, it is allowed to install electrical equipment:

with the degree of protection at least IP55 provided the ventilation system ensures at least 10 air changes per hour;

specially designed for use in zone 2.

20.3.2.2 In holds and spaces above the bulkhead deck, in zones less than 450 mm above the deck or platform preventing, a free propagation of gases in the downward direction, electrical equipment installed shall be of the following safe types: intrinsically safe (*Exi*), with pressurized enclosure (*Exp*), with flameproof enclosure (*Exd*) or increased safety (*Exe*).

20.3.2.3 In holds and spaces below the bulkhead deck all the electrical equipment shall be of the following safe types: intrinsically safe (*Exi*), with pressurized enclosure (*Exp*), with flameproof enclosure (*Exd*) or increased safety (*Exe*).

20.3.3 Special requirements for passenger ships having ro-ro cargo spaces.

20.3.3.1 In passenger ships with roll-on/roll-off cargo spaces or special-category spaces as mentioned under 1.5, Part VI "Fire Protection", apart from emergency lighting required by 20.1.2.1.1, additional emergency lighting shall be provided in all public spaces and corridors, that shall serve for 3 hrs at least under any heel of the ship and when all other electrical power sources fail.

This lighting shall make the escape routes clearly visible (or ensure an illumination intensity of 0,5 lx). Any damage to a lighting fixture shall be clearly visible.

20.3.3.2 As electrical power sources for this additional lighting, accumulator batteries shall serve fitted in lighting fixtures, continuously recharged from the emergency switchboard and replaced within the period established by the manufacturer with regard to their service conditions.

20.3.3.3 In each corridor of crew spaces, in crew recreation rooms and in each space where the crew members generally work, a hand lamp (lantern) shall be provided supplied from an accumulator unless additional emergency lighting stipulated by 20.3.3.1 and 20.3.3.2 is installed in the space.

20.3.4 Installation of electrical equipment in holds and spaces intended for carriage of motor vehicles with fuel in their tanks in cargo ships.

20.3.4.1 In holds and compartments, in spaces located at a height of more than 450 mm above the cargo deck or platform preventing free penetration of gases downwards, it is allowed to install electrical equipment: with the degree of protection at least IP55 provided the ventilation system ensures at least 10 air changes per hour;

specially designed for use in zone 2.

20.3.4.2 In holds, spaces and zones less than 450 mm above the cargo deck or platform preventing a free propagation of gases in the downward direction, electrical equipment installed shall be of the following safe types: intrinsically safe (*Exi*), with pressurized enclosure (*Exp*), with flameproof enclosure (*Exd*) or increased safety (*Exe*).

20.4 SPECIAL PURPOSE SHIPS

20.4.1 Supply of essential services.
In special purpose ships carrying more than 60 persons, the power supply of essential services shall comply with 20.1.1.4.
20.4.2 Emergency sources of electrical power.
20.4.2.1 In special purpose ships carrying not more than 60 persons, the emergency source of electrical power shall comply with 9.3.
Ships having a length above 50 m shall additionally comply with 20.1.2.3.1.
20.4.2.2 In ships carrying more than 60 persons, the emergency source of electrical power shall comply with 20.1.2.
20.4.3 Electrical equipment in storerooms for explosives.
20.4.3.1 Except for lighting fixtures in glass hoods and protection gratings and cables in gastight pipes, no electrical equipment shall be installed in storerooms for explosives specified in 2.1.5.3, Part VI "Fire Protection".
20.4.3.2 Switches of lighting circuits shall be fitted outside storerooms for explosives and shall be provided with light signals to indicate the presence of voltage in the lighting fixtures.
20.4.3.3 In storerooms for explosives, the devices for connection of portable electrical equipment to the ship's mains shall be provided with nameplates indicating the rated electrical parameters and shall have a protective enclosure not below IP56 type.
20.4.3.4 Storerooms for explosives shall be fitted with automatic heat detectors operating at temperatures rising above 40 °C (refer to 6.2.2.17, Part VI "Fire Protection").
20.4.4 Ships used for processing the living resources of the sea and not engaged in their catching.
20.4.4.1 Survey of electrical equipment.
In addition to the requirements of 1.3.2, the electrical equipment of processing machinery (catch processing) is subject to survey on board the ship (refer also to 1.3.2.4.1).
20.4.4.2 Survey during manufacture of electrical equipment.
The electrical equipment of processing machinery specified in 20.4.4.1 is subject to survey during manufacture in addition to that listed in 1.3.3.1. Use of electrical equipment not fully complying with the requirements of Sections 1 — 18 is permitted.
20.4.4.3 Structural requirements and protection of electrical equipment of processing machinery and refrigerating plants.
20.4.4.3.1 The electrical equipment installed in catch processing spaces shall be resistant to seawater and fish processing products influence or shall be adequately protected against it.
20.4.4.3.2 The electric motors of the processing refrigerating compressors, fans of the refrigerated holds and freezing apparatus and, in well-grounded cases, the electrical equipment of other processing machinery shall be provided with heating arrangements to maintain a temperature which is at least by 3 °C higher than the ambient temperature.
20.4.4.3.3 Distribution gear and start, control and protection devices of electrical equipment specified in 20.4.4.3.1 shall be installed in special electrical spaces.
20.4.4.3.4 Cables installed in spaces subjected to prolonged influence of salt and other products of fish processing shall be provided with sheaths resistant to such influence or be adequately protected.
20.4.4.4 Composition and capacity of main electrical power source.
20.4.4.4.1 Determination of the composition and capacity of the main source of electrical power shall determined with regard to the following operating conditions of the ship:
running conditions;
manoeuvring;
in case of fire, hole in the ship's hull or other conditions affecting the safety of navigation, with the main source of electrical power in operation;

processing.

20.4.4.4.2 The capacity of generators composing the main electrical power source shall be such that if any of them fail, the rest will ensure power supply of electrical equipment under conditions specified in 20.4.4.4.1, as well as minimal habitable conditions to persons on board.

20.4.4.5 Distribution of electrical power.

20.4.4.5.1 Where the main electrical power source incorporates shaft generators not intended for operation in parallel with the independently driven generators, the machinery and systems ensuring propulsion, manoeuvrability and safety of navigation shall be supplied from the busbars of independently driven generators, while the electrical equipment of processing refrigerating plant and machinery shall be supplied from the busbars of shaft generators.

20.4.4.5.2 The electric drives of processing refrigerating compressors shall be supplied by separate feeders from the busbars of the main switchboard. It is admissible for these drives to be fed from a separate switchboard supplied by two feeders connected to different sections of the main switchboard.

20.4.4.5.3 Electrical circuit for supplying switchboards of the processing machinery (catch processing) shall be separated electrically (galvanically) from the ship's mains.

20.4.4.5.4 If provision is made for electrical power transmission to other ships, a power transmission switchboard separated electrically (galvanically) from the ship's mains shall be installed.

20.4.4.5.5 Where portable tools and movable mechanization facilities not permanently installed are supplied from a circuit of more than 50 V, a safety isolation device in combination with a separating transformer shall be used for each consumer. Such device shall interrupt power supply if the hull leakage current exceeds 30 mA.

20.4.4.6 Lighting.

20.4.4.6.1 Catch processing spaces and refrigerating machinery rooms shall be illuminated by stationary lighting fixtures, which shall be supplied and arranged in accordance with 6.2.3.

20.4.4.6.2 Fish storage holds shall be illuminated with stationary lighting fixtures, which shall be supplied in accordance with 6.2.7.

20.4.4.7 Signalling.

A "Man-in-Hold" signal push-button shall be located inside the refrigerated holds at each exit to actuate signal at the wheelhouse or another permanent attended space.

20.4.4.8 Emergency electrical installations.

20.4.4.8.1 The emergency source of electrical power shall comply with the requirements of 9.3.

20.4.4.8.2 In addition to the requirements of 9.3.1.1, the emergency source of electrical power shall supply the emergency lighting for the catch processing spaces and the exits therefrom as well as for the deck in way of fishing machinery.

20.4.4.8.3 Where a generator is used as the emergency source of electrical power, an emergency transitional source of electrical power (accumulator battery) shall be provided, the capacity of which shall be sufficient to supply the consumers specified in 9.3.7 and 20.4.4.8.2 during 30 min.

20.5 CONTAINER SHIPS

20.5.1 General.

The requirements of the Chapter are applicable to the electrical equipment of ships intended for the carriage of thermal containers.

20.5.2 Supply and distribution of electrical power.

20.5.2.1 As the rated power of electrical equipment of thermal containers their prescribed power shall be taken. The consumed power of the electrical equipment of thermal container shall not exceed 15 kW (18,75 kVA) under rated operating conditions.

20.5.2.2 The overload protective device of sources of electrical power prescribed in 8.2.3 shall ensure disconnection of thermal containers from the main switchboard in the last turn (refer also to 21.2.1).

20.5.2.3 The electrical circuit supplying the equipment of thermal containers shall be separated from the ship's mains by transformers with separate windings, fed from the main switchboard.

20.5.2.4 The electrical installations of thermal containers shall be fed from special distribution gear energized by separate feeders.

20.5.2.5 Socket outlets installed in cargo holds or on open decks in areas of stowage of thermal containers shall be supplied by separate outgoing feeders from the special distribution gear (switchboards) specified in 20.5.2.4 and 20.5.3.3.

20.5.2.6 The electrical circuit of socket outlets intended for supply of the electrical installations of thermal containers shall be rated for 220/380 V voltage at 3-phase alternating current, 50 Hz in frequency, or for 240/440 V voltage at 3-phase alternating current, 60 Hz in frequency.

20.5.2.7 For each isolated network of sockets monitoring of insulation resistance shall be provided (refer to 2.11).

20.5.3 Distribution gear and transformers.

20.5.3.1 The distribution gear (switchboards) of thermal containers, electrical converters, if any, and transformers with separate windings shall be installed in special electrical spaces.

20.5.3.2 The secondary winding of transformers with separate windings shall have an isolated zero point.

20.5.3.3 Each distribution gear (switchboard) shall be equipped with appliances, which ensure:

.1 visual signalling to indicate the presence of voltage;

.2 connection and disconnection of each outgoing feeder supplying the socket outlets;

.3 short-circuit protection at the outgoing feeders supplying the socket outlets;

.4 measuring of insulation resistance with visible and audible alarm at the main machinery control room at decreasing of the controlled value below the specified level.

20.5.4 Socket outlets.

20.5.4.1 In holds containing thermal containers it is allowed to install socket outlets used only for power supply of containers with the degree of protection not less than IP55 type, and on open decks — IP56 type.

When the electrical systems of remote control over temperature, humidity, ventilation and other characteristics of thermal containers are used, it is permitted to install additional socket outlets for connection of these control devices in holds or on decks.

20.5.4.2 Socket outlets for power supply of the electrical equipment of thermal containers shall, in addition to requirements of 6.6, be fitted with an isolating switch interlocked so that the plug cannot be inserted or withdrawn while the switch is in the "on" position. A nameplate indicating the voltage shall also be fitted.

20.5.4.3 The electrical installation of thermal containers shall be supplied from the ship's mains at the direct sequence of phases *A(R), B(S), C(T)* according to the scheme given in Fig. 20.5.4.3.

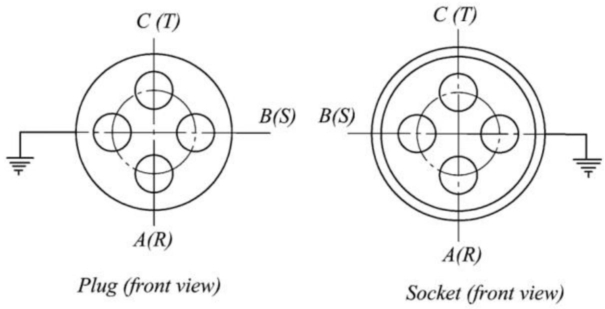


Fig. 20.5.4.3

20.5.4.4 Socket outlets intended for supply of the electrical installations of thermal containers shall be rated at the following currents:

63 A for voltage of 220 V, 50 Hz or 240 V, 60 Hz;

32 A for voltage of 380 V, 50 Hz or 440 V, 60 Hz.

20.5.4.5 Socket outlets shall be designed so as to prevent connection of plugs rated for one voltage to socket outlets rated for another voltage.

20.5.4.6 Design and dimensions of plugs and sockets shall correspond to international standards.

20.5.5 Protection earthing.

The receptacle intended for connection of the earthing conductor in the flexible cable of the thermal container shall be grounded through the earthing conductor in the supply feeder, where the distribution gear (switchboard) is installed for supply of socket outlets of thermal containers.

20.6 CATAMARANS

20.6.1 In each hull of the ship at least one generator being a part of the main source of electrical power shall be provided.

20.6.2 In each hull of the ship, a main distribution board shall be installed. One of the boards may be installed above the bulkhead deck.

20.6.3 The busbars supplying the ship hulls shall be sectioned.

20.6.4 The emergency services of each hull shall be supplied from the emergency source of electrical power through separate feeders.

20.6.5 The disconnecting switches of electrical equipment specified in 5.7.1, 5.7.2, 5.8.1, 5.8.2 and 5.8.3 shall be grouped separately for each hull.

20.7 FLOATING CRANES AND CRANE SHIPS

20.7.1 Where systems similar to those mentioned in Section 17 are used for crane machinery of floating cranes and crane ships, the requirements of this Section being also applicable to the electric drives of crane machinery, such systems fall, so far as practicable, under the relevant requirements of this Chapter.

20.7.2 For self-driven floating cranes, the capacity of the main source of electrical power shall be sufficient for the selective operation of the crane both underway and during cargo-handling operations.

20.7.3 Accumulator rooms, accumulator boxes and spaces containing emergency sources of electrical power may be located below the bulkhead deck, provided all the requirements of 9.2 and 13.2 are satisfied.

20.7.4 To produce sound signals during cargo-handling operations, a sound-signal means shall be fitted on the crane, activated from the operator's cabin.

20.8 FLOATING DOCKS

20.8.1 General.

The requirements of this Chapter cover the electrical equipment of steel floating docks in addition to the relevant requirements set forth in Sections 1 — 18.

20.8.2 Survey of electrical equipment.

20.8.2.1 In addition to requirements of 1.3.2.1, the following kinds of equipment, systems and devices are subject to survey on board the floating dock:

.1 electric drives and their systems of control and monitoring of the mechanisms ensuring submersion and emersion of the dock;

.2 earthing of the docked ship.

20.8.2.2 All kinds of electrical equipment used in steel floating docks and listed under 1.3.3.1 and 20.8.2.1 are subject to survey during manufacture. For machinery and gear of non-autonomous docks, it is permitted to use the electrical equipment not fully complying with the requirements of Sections 1 — 18.

20.8.3 Protective enclosures of electrical equipment.

Protective enclosures of the electrical equipment shall be in compliance with Table 2.4.4.2 considering that dry compartments of the dock wing walls refer to the spaces of increased humidity, and dry compartments of pontoons, tunnels in pontoons and other similar spaces refer to the extra humid category.

20.8.4 Earthing.

20.8.4.1 Each docked ship shall be earthed to the dock hull through at least two special flexible cable connectors having a cross-sectional area not less than 70 mm^2 each, and devices for connection thereof to the dock hull shall be provided at the dock.

20.8.4.2 To connect the dock hull to the shore earthing system, it is necessary to provide at least two flexible copper cables, having a cross-sectional area not less than 70 mm^2 each, and also a device for connection of these cables to the dock hull.

No metal earthing of the dock hull is allowed if a system of cathodic protection from corrosion is applied, and circuits of the dock are electrically separated from the shore circuits.

20.8.4.3 All sections of the dock hull, pontoons, wing walls and similar structures shall be electrically connected by reliable means.

20.8.5 Number and output of sources of electrical power.

20.8.5.1 Main sources of electrical power for docks may be as follows:

.1 for autonomous docks — intrinsic generators;

.2 for non-autonomous docks — shore electrical power system.

20.8.5.2 At least two generators and, in addition, a shore electrical power system, if necessary, shall be provided as main sources of electrical power on autonomous docks.

For non-autonomous docks it is allowed to use only a shore electrical power system.

20.8.5.3 The power of main generators of autonomous docks or the power available from a shore electrical power system shall be sufficient to ensure the following operating conditions of the dock:

submersion of the dock;

docking of the ship;

emersion of the dock;

emergency condition;

other conditions in accordance with the dock's purpose.

20.8.5.4 The power of main generators of the autonomous dock shall be such that in case of failure of any generator the rest of the generators ensure safe submersion and emersion of the dock and also docking and undocking of ships.

20.8.6 Distribution of electrical power.

20.8.6.1 The following systems of electrical power distribution are allowed for use in docks in addition to those specified in 4.1.1:

.1 three-phase four-wire alternating current system with earthed neutral wire;

.2 one-wire system, both alternating and direct current, with dock's hull return only for welding circuit (refer also to 20.8.4), and also for devices of monitoring and measurement of insulation resistance.

20.8.6.2 In addition to 4.3.1 the following consumers shall be supplied by separate feeders from the main switchboard busbars energized directly by the generators proper or through the transformer, or by the shore electrical power system:

.1 system of monitoring, signalling and control of the dock submersion and emersion;

.2 switchboards for electric drives of the ballast system sluice valves associated with safe operation of the dock;

.3 switchboards for supply of welding outfit;

.4 switchboards for supply of the docked ship.

20.8.6.3 Essential consumers and electric drives of machinery situated at the wing wall where no source of electrical power is installed shall be supplied from the switchboard located therein. This switchboard shall be considered as a separate part of the main switchboard and shall be fed from the main switchboard by two feeders. The cross-section of each feeder shall be sufficient for supply of the wing wall essential consumers in case of failure of one feeder. The supply feeders shall run between wing walls in different spaces if it is permitted by the dock design.

In separate cases, installation of both feeders in one space may be allowed.

20.8.6.4 Signal marker lights may be supplied from lighting switchboards.

20.8.6.5 In case of high-voltage electrical power supply of the non-autonomous dock from the shore electrical power system, in addition to the high-voltage feeder a device shall be fitted for connection of the low-voltage supply feeder. This device shall be designed for continuous transmission of electrical energy required at the idle dock when no repairs are carried out. In this case, provision shall be made for continuous supply of at least one electric drive of maximum capacity fire pump when fully loaded and also for supply of all electric motors of sluice valve drives and lighting of main spaces.

When high-voltage electrical power is supplied to the non-autonomous dock by two independent feeders, a low-voltage supply feeder need not be provided.

20.8.6.6 When the dock is supplied from the shore low-voltage electrical power system, it is required to provide two feeders and two devices for reception of electrical power, one of them supplying the consumers specified in 20.8.6.2 and the other — at least the consumers referred to in 20.8.6.5.

20.8.6.7 Arrangement and design of devices for connection of cables used for power supply from the shore electrical power system shall be such as to ensure:

.1 installation of cables at an adequate distance from one another to prevent simultaneous damage of high-voltage and low-voltage feeders;

.2 absence of mechanical stresses in cables during submersion and emersion of the dock;

.3 prevention of transmission of mechanical stresses to the terminals intended for connection of cables or wires.

It is recommended that the devices for reception of electrical power from the shore electrical power system shall be located on different wing walls of the dock.

20.8.6.8 A bright and clear warning inscription indicating the voltage shall be made on the hull in a prominent position or on the door of the external supply switchboard.

20.8.6.9 The maximum permissible level of the short-circuit power shall be determined for each dock, which may be supplied from the shore electrical power system. This level shall be marked on the warning inscription of the external supply switchboard.

20.8.6.10 The docked ships shall be fed from the stationary supply switchboards installed in the dock.

20.8.6.11 Each supply switchboard of the docked ship shall be fitted with:

.1 switchgear and protective devices, terminals or plug and socket connectors for flexible cables connected to the docked ship. All the terminals of the switchboard shall bear a mark indicating a phase or pole;

.2 a pilot lamp indicating the presence of voltage across switchboard terminals;

.3 a nameplate indicating the nominal voltage, nature of current, its permissible value and frequency.

20.8.6.12 At the supply switchboard of the docked ship provision shall be made for the device for fastening the ends of the flexible cable feeding the docked ship.

20.8.6.13 Cross-sectional area of the flexible supply cable of the docked ship shall be chosen for rated current of the protection setting fitted in the outgoing feeders of the supply switchboard of the docked ships.

20.8.7 Transformers.

In floating docks one transformer of adequate power may be used for supply of the lighting circuit and circuits of essential consumers. In this case, it is recommended to provide for possible reserve supply of these consumers from the transformer intended for feeding the docked ships.

20.8.8 Lighting.

In addition to provisions of 6.6.1, socket outlets for portable lighting fixtures shall be installed at least:

in dry compartments of wing walls where equipment and outfit for the system of submersion and emersion of the dock is located;

in spaces of safety deck where the equipment for the system of submersion and emersion of the dock is located;

in the space where the central control console of the dock submersion and emersion is located;

in the area of location of the mooring machinery electric drives.

20.8.9 Service telephone communication.

20.8.9.1 In the absence of other types of voice communication provision shall be made for telephones of the ship's control group, which ensure clear two-way communication between the following spaces:

main machinery control room — warping capstans;

main machinery control room — emergency diesel-generators space;

main machinery control room — main switchboard space;

main machinery control room — main diesel generator space;

main machinery control room — high-voltage transformer space;

main machinery control room — spaces of location of hand drives for sluice valves of the dock submersion and emersion system;

main machinery control room — fire-extinguishing station.

Besides, two-way independent voice communication shall be provided between the main machinery control room and machinery space.

20.8.9.2 In docks provision shall be made for connection of at least one telephone set to the shore telephone system.

20.8.10 General alarm system.

General alarm system shall be actuated from the main machinery control room and from the space intended for the personnel on watch, if such a space is provided.

20.8.11 Installation of cables.

20.8.11.1 If the pontoon deck is illuminated with lighting fixtures of submersible type and if the cables used are not light, they shall run to the lighting fixtures in water- and gastight pipes.

The pipes and their packings shall be selected with regard to operation under pressure not less than the permissible pressure of submersible lighting fixtures.

20.8.11.2 On special agreement with the Register, cables may be installed on tray plates (saddles) welded directly to the dock plating.

20.8.12 Distribution of electrical power and cabling with the use of one-wire system.

20.8.12.1 Relevant terminals of sources and consumers of electrical power shall be reliably connected to the dock hull. This connection shall not be made in pipelines, tanks and cylinders containing compressed gases, petrol and oil.

20.8.12.2 For direct-current circuit the insulated wire shall be connected to the positive poles and terminals of sources and consumers of electrical power.

Instruments, switchgear and protective devices shall be set to the positive pole.

20.8.12.3 Conductors used for connection of terminals of the electrical equipment and the dock hull shall be equal in cross-sectional area to the conductors isolated from the hull.

20.8.12.4 Points of connection of conductors to the steel hull of the dock shall be situated in areas and positions readily accessible for control and maintenance of contacts.

These points shall be located on structures, which are reliably joined by welding to the dock hull.

20.8.12.5 Working earthing conductors shall be joined in such a manner that reliable electrical connection to the hull is ensured.

It is recommended to use high-power busbars, which are connected to the dock hull in several points.

20.8.12.6 Regardless of the system of electrical power distribution used for welding circuit, the welding station in the docked ship shall be supplied by two-wire system from the welding circuit of the dock.

Hull return system of the docked ship is not permitted.

20.8.12.7 When carrying out welding operations on the hull of the docked ship, a cable with a potential opposite to that of the electrode shall be connected to the hull as close to the part being welded as possible.

20.8.13 Busbar conduits.

20.8.13.1 The application of busbar conduits is allowed for floating docks. The degree of protection of busbar conduits depending on the place of installation shall comply with the requirements of 2.4.4.2.

20.8.13.2 Busbar conduits shall be designed for adequate load and shall withstand, along with insulators and holders, mechanical stresses resulting from short-circuit current directly at busbars.

20.8.13.3 At alternating current exceeding 1500 A, provision shall be made for reduction of the current loss in busbar holders, fixtures, insulators and structures which results from the influence of magnetic fields.

20.8.13.4 All protective devices and switchgear connected immediately to the busbar conduit shall be installed in places accessible for inspection and repair.

Cables and busbars connecting the protection devices and the busbar conduit shall not be more than 2 m in length.

20.8.13.5 Busbar conduits with the degree of protection IP20 and below shall be installed at a height not less than 2,5 m above the floor level.

20.8.13.6 Warning inscriptions indicating the voltage shall be made on the protective enclosure of the busbar conduit at 3 to 5 m intervals throughout the whole length.

20.8.14 Emergency electrical installations.

20.8.14.1 Each floating dock shall be provided with an emergency source of electrical power ensuring power supply of all the necessary consumers for not less than 3 h.

20.8.14.2 Emergency source of electrical power shall ensure supply of consumers as per 9.3.1, which are installed on board the dock, and also supply of the following consumers:

.1 electrical drives essential for sluice valves of the system of the dock submersion and emersion (at least 2 closings and openings of the sluice valves);

.2 indication and control circuits of the system of the dock submersion and emersion;

.3 command service communication.

20.8.14.3 If the emergency source of electrical power is a diesel generator with an automatic starting system, provision shall be made for local starting of the diesel generator.

20.8.14.4 The emergency diesel generator space shall be located above the margin line of the dock and be easily accessible from the open deck.

20.8.14.5 All the emergency consumers shall be supplied from the emergency switchboard.

In well-grounded cases, the emergency diesel generator and emergency switchboard may be installed in different spaces, and also one section of the main switchboard may be used as an emergency switchboard, provided the main switchboard is located above the level of the margin line of the dock.

20.8.15 Electric drives of submersion and emersion system of the dock.

20.8.15.1 Electric drives for sluice valves of the submersion and emersion system shall not hinder manual opening and closing of sluice valves. Interlocking device shall be also provided to prevent the electric drive from operation in case of sluice valve change-over to manual control.

20.8.15.2 Electric drives for sluice valves shall be fitted with local and remote-controlled (in the main machinery control room, etc.) indicators of sluice valve limit positions. For electric drives of sluice valves intended for water distribution in the pontoon compartments it is also recommended to provide for devices indicating the extent to which the sluice valve is open.

20.8.15.3 For sluice valves intended for water distribution in the pontoon compartments it is recommended to provide for separate control of each sluice valve, as well as for group control of port and starboard sluice valves.

20.8.15.4 Control circuit for electric drives of the drain (ballast) pump shall provide for local and remote control from the main control station with indication of the pump operation or control of electric motor load on the ammeter.

20.8.16 Connection of electrical power supply sources.

When generators of the autonomous dock or transformers of the shore power supply are connected directly to the distribution busbar conduit, and the main switchboard is not installed, provision shall be made for a common control desk fitted with control gear for circuit breakers of generators or transformers and with instruments and devices of control, signalling and protective systems.

These instruments and devices are listed in 4.6.

20.8.17 High-voltage electrical installation of the dock.

20.8.17.1 High-voltage electrical installation of the dock shall comply with the requirements of national standards and rules applicable to the shore electrical installations.

20.8.17.2 High-voltage electrical installation of the dock shall be located in separate special electrical spaces.

20.9 BERTH-CONNECTED SHIPS

20.9.1 For berth-connected ships, the following sources may be used as main sources of electrical power:

generators;

shore electrical power system.

20.9.2 On independent berth-connected ships, provision shall be made for at least two generators as main sources of electrical power.

In addition, the ship mains may be supplied from the shore electrical power system.

Berth-connected ships that are not independent may be supplied from the shore electrical-power system only.

20.9.3 On independent berth-connected ships, the power of generators of the main power source or the power supplied by the shore electrical power system shall be sufficient for the operation of services in accordance with the ship purpose, in case of fire, hull leakage or other circumstances adversely affecting the safety of the berth-connected ship while the main source of electrical power is in operation.

20.9.4 The main generator power of an independent berth-connected ship shall be sufficient to ensure operation in accordance with 20.9.3 in the case of failure of any of the generators.

20.9.5 In floating hotels and hostels, power supply and signalling functions of essential systems and gear shall be effected in conformity with 20.1.1.1 — 20.1.1.4.

The side, bow and stern lights may be supplied from lighting switchboards.

20.9.6 Each floating hotel or hostel shall be provided with an independent emergency source of electrical power to ensure the operation of services in accordance with 20.1.2.1 during 12 h, as well as the operation of services in accordance with 20.1.2.3 during 30 min.

20.9.7 As regards the automatic starting of the emergency source of electrical power and provision of an emergency transitional source in floating hotels and hostels, the requirements of 20.1.2.4 — 20.1.2.7 shall be complied with.

20.9.8 For continuously crewed berth-connected ships, emergency source of electrical power capable of supplying consumers for 3 h in accordance with the requirements of 9.3.7 shall be installed.

20.10 FISHING VESSELS

20.10.1 Survey of vessel's electrical equipment.

20.10.1.1 In addition to the requirements of 1.3.2 the following kinds of equipment, systems and devices are subject to survey on board the ship (refer also to 1.3.2.4.2):

.1 electrical equipment of fishing machinery;

.2 electrical equipment of processing machinery (catch processing).

20.10.2 Structural requirements and protection of electrical equipment of fishing and processing machinery.

20.10.2.1 The electrical equipment installed in catch processing spaces shall be resistant to sea water and fish processing products influence or shall be adequately protected against it.

20.10.2.2 Electrical equipment distribution gear and start-protection devices specified in 20.10.2.1 shall be installed in spaces separated from catch processing spaces.

20.10.2.3 Cables installed in spaces subjected to prolonged influence of salt and other products of fish processing shall be provided with sheaths resistant to such influence or be adequately protected.

20.10.2.4 The separate spaces for refrigerating plants and storerooms for cylinders containing Group II refrigerant in accordance with 2.2.1, Part XII "Refrigerating Plants" shall be considered as dangerous spaces. Electrical equipment installed in separate spaces for refrigerating plants that remains in operation after an emergency shutdown provided for in 21.2.4, and electrical equipment installed in storerooms for cylinders shall be of certified safe type with protection level not lower than IIA T1.

20.10.3 Composition and capacity of main electrical power source.

20.10.3.1 The composition and capacity of the main source of electrical power shall be determined with regard to the following operating conditions of the vessel:

.1 running conditions;

.2 manoeuvring;

.3 in case of fire, hole in the ship's hull or other conditions affecting the safety of navigation, with the main source of electrical power in operation;

.4 fishing.

20.10.3.2 The power of generators composing the main electrical power source shall be such that if any of them fail, the rest will ensure power supply of electrical equipment essential for propulsion, steering and safety of the ship under conditions specified in 20.10.3.1 as well as normal habitable conditions on board, excluding the power required in fishing activities, processing and preservation of the catch.

In vessels of less than 500 gross tonnage the power necessary to ensure normal habitable conditions on board may be neglected.

20.10.4 Distribution of electrical power.

20.10.4.1 Where the main electrical power source incorporates shaft generators not intended for parallel operation with the independently driven generators, the machinery and systems ensuring propulsion, manoeuvrability and safety of navigation shall be supplied from the busbars of independently driven generators, while the electrical equipment of fishing and processing machinery shall be supplied from the busbars of shaft generators.

20.10.4.2 The electric drives of refrigerating compressors shall be supplied by separate feeders from the busbars of the main switchboard. It is admissible for the electric drives of refrigerating compressors to be fed from a separate switchboard supplied by two feeders connected to different sections of the main switchboard.

20.10.4.3 Where portable tools and movable mechanization facilities not permanently installed, are supplied from a circuit of more than 50 V, a safety isolation device in combination with a separating transformer shall be used for each consumer.

Such device shall interrupt power supply if the hull leakage current exceeds 30 mA.

20.10.5 Lighting.

20.10.5.1 Catch processing spaces and refrigerating machinery rooms shall be illuminated by stationary lighting fixtures, which shall be supplied and arranged in compliance with 6.2.3.

20.10.5.2 Fish storage holds shall be illuminated by stationary lighting fixtures, which shall be supplied in accordance with 6.2.7.

20.10.6 Signalling.

A "Man-in-hold" signal push-button shall be located inside the refrigerated holds at each exit to actuate signal at the wheelhouse or another permanently attended space.

20.10.7 Emergency electrical installations.

20.10.7.1 Emergency sources of electrical power shall supply the following consumers:

.1 emergency lighting for:

.1.1 muster and embarkation stations for boarding life-saving appliances and spaces overboard where life-saving appliances are launched;

.1.2 all alleyways, stairways and exits;

.1.3 control stations;

.1.4 machinery spaces, generator rooms, steering gear compartment, space containing the emergency source of electrical power as well as spaces for main and emergency switchboards;

.1.5 catch processing spaces and the exits therefrom as well as the deck areas where the fishing machinery is installed;

.2 navigation lights, lights of "Vessel not under command" signal and other lights required by Part III "Signal Means" of the RS Rules/E;

.3 internal communication and announcing equipment, fire detecting system, general alarm system, daylight signalling lamps, sound signal means;

.4 emergency fire pump, if any;

.5 radio equipment and navigational equipment according to the requirements of Part IV "Radio Equipment" and Part V "Navigational Equipment" of the RS Rules/E.

20.10.7.2 The spaces of emergency sources of electrical power and of their transformers (if any), of emergency transitional sources of electrical power, emergency switchboard and distribution board of emergency lighting on ships not covered by the requirements of Part V "Subdivision" may be located below the uppermost continuous deck, but, in any case, above the freeboard deck.

20.10.7.3 Emergency sources of electrical power shall ensure supply of consumers specified in 20.10.7.1 for a period of 6 h. In case of ships intended for fishing in the polar waters the supply period shall be increased to 8 h.

20.11 SHIPS CARRYING DANGEROUS GOODS

20.11.1 General.

20.11.1.1 The requirements of this Chapter, in addition to the requirements of 7.2, Part VI "Fire Protection", apply to the electrical equipment of ships and cargo spaces intended for the carriage of dangerous goods in compliance with IEC 60092-506:2003.

20.11.2 Dangerous zones, spaces and areas.

20.11.2.1 Classification of dangerous zones.

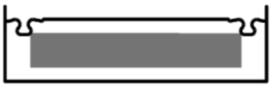
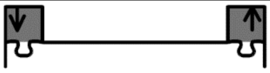
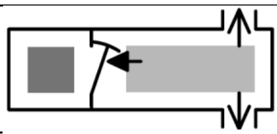
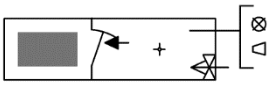
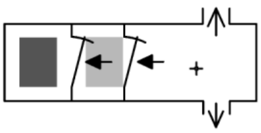
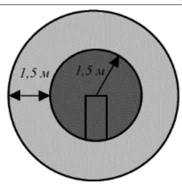
Zone 1, in which an explosive gas/air mixture is likely to occur in normal operation.

Zone 2, in which an explosive gas/air mixture is not likely to occur, and if it occurs, it will only exist for a short time.

Typical examples of arrangement of the dangerous zones are given in Table 20.11.2.1.

Table 20.11.2.1

Dangerous zones for dangerous goods

Subparagraphs	Typical examples	Comments
20.11.2.2 20.11.2.3.1 20.11.2.4.1.1 20.11.2.5.1.1		
20.11.2.3.2 20.11.2.4.1.2 20.11.2.5.1.2		
20.11.2.4.1.4 20.11.2.5.1.4		
20.11.2.4.2.1 20.11.2.5.2.1		natural ventilation
		space under overpressure, visual and audible alarm in control stations to be actuated when pressure drops
20.11.2.4.2.1 20.11.2.5.2.1 — only for fore room		natural ventilation
20.11.2.4.1.3 20.11.2.5.1.3 20.11.2.4.2.2 20.11.2.5.2.2		

 — gastight self-closing door

\+ — non-dangerous space

 — dangerous zone 1

 — dangerous zone 2

20.11.2.2 For packaged dangerous goods, Class 1, except of subclass 1.4S, the dangerous zones encompass the following spaces and areas classified as *Zone 1*:

.1 enclosed spaces of cargo compartments/holds as well as open or enclosed ro-ro cargo spaces;

.2 integral storerooms for the ship's stock of explosives.

20.11.2.3 For dangerous goods carried in bulk, Class 4.1, 4.2, 9 and MHB (Materials Hazardous in Bulk) capable of producing explosive dust/air mixtures, the dangerous zones encompass the following spaces and areas classified as *Zone 1*:

.1 enclosed spaces of cargo compartments/holds;

.2 air ducts of ventilation systems for spaces of cargo compartments/holds specified in 20.11.2.3.1.

20.11.2.4 For dangerous goods carried in bulk, Class 4.3, capable of producing explosive gaseous mixture, the dangerous zones encompass the following spaces and areas:

20.11.2.4.1 *Zone 1*:

.1 enclosed spaces of cargo compartments/holds;

.2 air ducts of ventilation systems for spaces of cargo compartments/holds specified in 20.11.2.4.1.1;

.3 areas on open deck or semi-enclosed spaces on open deck within 1,5 m of any ventilation outlets of cargo compartments/holds specified in 20.11.2.4.1.1;

.4 enclosed or semi-enclosed spaces having direct access to or other openings into spaces and areas specified in 20.11.2.4.1.1 and 20.11.2.4.1.2, unless appropriate measures are taken to prevent the explosive mixture from penetration into these spaces;

.5 air ducts of ventilation systems, pipelines of bilge systems, etc. where open ends of this piping directly face dangerous zone 1.

20.11.2.4.2 *Zone 2*:

.1 enclosed or semi-enclosed spaces with natural ventilation, having direct access to or other openings into spaces and areas specified in 20.11.2.4.1.1 and 20.11.2.4.1.2 and separated from these spaces by gastight self-closing doors as well as directly within air lock, if any;

.2 areas within 1,5 m of areas and spaces on open deck specified in 20.11.2.4.1.3;

.3 closed spaces (e.g. pipe tunnels, pump rooms with bilges, etc.) with piping specified in 20.11.2.4.1.5 along with their flanges, valves, pumps, etc. except cases when special methods of pressure buildup approved by the Register are used in those spaces.

20.11.2.5 For packaged dangerous goods, Class 2.1 and also Classes 3, 6.1 and 8 (liquids with $T_{flash} \leq 23\,°C$), the dangerous zones encompass the following spaces and areas.

20.11.2.5.1 *Zone 1*:

.1 enclosed spaces of cargo compartments/holds;

.2 air ducts of ventilation systems for spaces of cargo compartments/holds specified in 20.11.2.5.1.1;

.3 areas on open deck or semi-enclosed spaces on open deck within 1,5 m of any ventilation outlets of cargo compartments/tanks specified in 20.11.2.5.1.1;

.4 enclosed or semi-enclosed spaces having direct access to or other openings into one of the above areas specified in 20.11.2.5.1.1 and 20.11.2.5.1.2, unless appropriate measure are taken to prevent the explosive mixture from penetration into these spaces;

.5 air ducts of ventilation systems, pipelines of bilge systems, etc. where open ends of this piping directly face dangerous zone 1.

20.11.2.5.2 *Zone 2*:

.1 enclosed or semi-enclosed spaces with natural ventilation having direct access to or other openings into spaces specified in 20.11.2.5.1.1, 20.11.2.5.1.2 and separated from these spaces by gastight self-closing doors, as well as directly within air lock, if any;

.2 areas within 1,5 m of areas or spaces on open deck specified in 20.11.2.5.1.3;

.3 enclosed spaces (e.g. pipe tunnels, pump rooms with bilges, etc.) containing pipes specified in 20.11.2.5.1.5 along with their flanges, valves, pumps, etc. Except for the cases where forced ventilation with 6-time air change is used in those spaces.

20.11.3 Installation of electrical equipment in dangerous spaces and zones.

20.11.3.1 Electrical equipment installed in spaces and areas where only explosive dust is likely to occur due to bulk cargoes, shall comply with the following minimum requirements, unless otherwise specified (refer to Table 20.11.3.2):

.1 protection level IP55 and the maximum surface temperature of 200 °C or,

.2 certified safe type with temperature class T3 and protection level IP55.

20.11.3.2 Electrical equipment installed in areas where only explosive gas atmosphere is likely to occur shall be of certified safe type and comply with the following minimum requirements, unless otherwise specified (refer to Table 20.11.3.2):

Table 20.11.3.2

Requirements for electrical equipment depending on specific solid bulk cargoes

Dangerous goods	IMO class	Dominant risk[1]	Protection against explosive dust	Protection against explosive gas atmosphere	
				Subgroup A	Temperature class
Aluminium dross	4.3	Hydrogen	–	IIC	T2
Aluminium ferrocilicon powder	4.3	Hydrogen	–	IIC	T2
Aluminium cilicon powder, uncoated	4.3	Hydrogen	–	IIC	T2
Ammonium nitrate fertilizers:		Refer to footnote[2]			
type A	5.1		–	–	–
type B	9		–	–	–
Coal	MHB	Dust, methane	IP55	IIA	T4
Direct-reduced iron	MHB	Hydrogen	–	IIC	T2
Ferrophosphorus (no briquettes)	MHB	Hydrogen	–	IIC	T1
Ferrocilicon	4.3	Hydrogen	–	IIC	T1
Iron oxide, spent. Sponge iron, spent	4.2	Dust	IP55	IIA	T2
Seed cake, expelled	4.2	Hexane	–	IIA	T3
Silicomanganese	MHB	Hydrogen	–	IIC	T1
Sulfur	4.1	Inherent	IP55	–	T4
Zinc slag	4.3	Hydrogen	–	IIC	T2

[1] This column relates to the possible evolution of substances, which may affect the installations of electrical equipment and cables.

[2] Provision shall be made to disconnect all electric circuits terminating within cargo spaces in accordance with the provisions of 2.9.9.

.1 temperature class T3;

.2 sub-group of equipment IIB.

The certified safe-type electrical equipment shall be at least with protection suitable for operation in *Zone 1*.

20.11.3.3 Electrical equipment installed in spaces and areas where only solid bulk cargoes and MHB (Materials Hazardous in Bulk) are carried shall comply with the requirements of 20.11.3.1, 20.11.3.2 and the minimum requirements of Table 20.11.3.2.

20.11.3.4 Electrical equipment installed in spaces and areas where explosive gas atmosphere and dust are likely to occur shall comply with the requirements of 20.11.3.1 and 20.11.3.2.

20.11.3.5 Electrical equipment installed in spaces and areas where dangerous goods of Class 1, except for Class 1.4S, are likely to be carried, shall comply with the following requirements:

.1 protection level IP65;

.2 the maximum surface temperature — 100 °C.

20.11.3.6 Electrical equipment installed in dangerous zone of category 2 shall be:

.1 of type suitable for use in adjacent spaces in accordance with 20.11.3.1 — 20.11.3.5; or

.2 of special design for protection class "n" and appropriate temperature class, sub-group and protection level in accordance with 20.11.3.1 — 20.11.3.5; or

.3 of such design that does not generate arcs or sparks in service and which surfaces do not reach unacceptable high temperatures under normal conditions.

Where the spaces certified for zone 2 is protected with redundant mechanical ventilation capable of starting automatically electrical equipment not certified for zone 2 may be installed provided its automatically disconnected following loss of ventilation. In addition to the above, the manned stations shall be provided with audible and visual alarms activated at the failure in the ventilation system.

For primary essential services such as bilge and ballast ones, the electrical equipment shall be with the certified safe-type electrical equipment with protection suitable for operation in dangerous zone of category 2.

20.11.3.7 Portable electrical equipment shall, in general, have its own independent source of electrical power (except for intrinsically safe electric circuits) and be of certified safe type with protection suitable for operation in *Zone 1*.

Where in the spaces belonging to dangerous zone of category 2 of the reserved forced ventilation system of with automatic switching on, the installation of non-certified for this category electrical equipment provided its automatic switching off and interlocking of switching on during failure of ventilation. In addition to the above, the manned stations shall be provided with audible and visual alarms activated at the failure in the ventilation system.

For primary essential services such as bilge and ballast ones, the electrical equipment shall be with the certified safe-type electrical equipment with protection suitable for operation in dangerous zone of category 2.

20.12 VESSELS OF DREDGING FLEET

20.12.1 General.

Requirements of this Chapter cover electrical equipment of vessel of dredging fleet (refer to 8.1.2 of the RS Rules/LL) with descriptive notation **Dredger**, or **Hopper barge**, or **Hopper dredger** in addition to the applicable requirements of Sections 1 — 18 of this Part.

20.12.2 Survey of electrical equipment.

20.12.2.1 In addition to the requirements of 1.3.2.1 of this Part, the following equipment, systems and devices are subject to survey on board the vessel of dredging fleet (refer to 8.1.2 of the RS Rules/LL):

.1 electric drives of cargo discharge system and their control system;

.2 electric drives and their systems of the emergency control systems for closing the dredging valves.

20.12.3 Draught gauges.

An accurate draught indicator of the vessel of dredging fleet (refer to 8.1.2 of the RS Rules/LL), capable of showing the corresponding position of the draught, shall be fitted at the navigation bridge. This draught indicator shall also be capable of providing a record of draught as a function of time.

21 REQUIREMENTS FOR ELECTRICAL EQUIPMENT OF REFRIGERATING PLANTS

21.1 GENERAL

21.1.1 The requirements of the Section cover the electrical equipment of classed refrigerating plants. The requirements of 21.2.3, 21.2.4, 21.3.1 and 21.4 apply to unclassed refrigerating plants as we

21.2 POWER SUPPLY AND SWITCHING

21.2.1 The electric drives of refrigerating plants shall be powered through separate feeders from the switchboard of the refrigerating plant.

The electric drives of refrigerating compressors may be supplied directly from the main switchboard. The refrigerating fans may be supplied from the switchboard of the refrigerating plant or other switchboard energized directly from the main switchboard.

For each method of power supply, it is necessary to provide that in case of generator overload the refrigerating plant electric drives are disconnected in the last turn.

The emergency ventilation system shall be supplied through a separate feeder from the switchboard energized from the main switchboard or directly from the main switchboard.

21.2.2 Power supply of electric drives of thermal containers shall comply with the requirements of 20.5.2.

21.2.3 When using the refrigerants of Group II according to Table 2.2.1, Part XII "Refrigerating Plants", a device shall be provided for emergency remote disconnection of the refrigerating plant switchboard operated from the following locations:

.1 from the permanent control post of the refrigerating plant in the refrigerating machinery room;

.2 from a location outside the space that may be contaminated with the refrigerant of Group II in case of breakdown in the refrigerating machinery room;

.3 outside, near every exit from the refrigerating machinery room.

The apparatus for emergency remote disconnection shall be installed in such a manner that it cannot be actuated inadvertently.

21.2.4 The apparatus for emergency remote disconnection of the switchboard of the refrigerating plant working with Group II refrigerant shall simultaneously switch off the electric drives of refrigerating compressors if they are fed from the main switchboard (refer to 21.2.1), main lighting of the refrigerating machinery compartment and switch on the emergency ventilation, water screens and reserve lighting.

Additionally, near the device for emergency remote disconnection of the refrigerating plant switchboard at locations stated in 21.2.3.1 and 21.2.3.2, devices shall be installed for remote starting in any sequence of emergency ventilation, water screens, and reserve lighting, without disconnection of the refrigerating plant switchboard.

Emergency remote disconnection of the lighting is not required when safe type lighting fixtures are used in the main and emergency lighting circuits. At that, reserve lighting may not be fitted.

21.2.5 It is recommended that the electrical heating appliances for hatches and doors to refrigerated spaces and freezing chambers shall be supplied at safety voltage.

21.3 VENTILATION

21.3.1 If the refrigerant of Group II is used, the exhaust fan electric motors of the emergency ventilation in the refrigerating machinery rooms, installed in the exhaust ducts, shall be of safe type.

21.3.2 The electric motors of fans located in the stream of air coming from the refrigerated cargo spaces shall have a degree of protection not below IP55.

21.4 LIGHTING

21.4.1 If the refrigerant of Group II is used, safe-type reserve lighting fixtures shall be installed in the refrigerating machinery room in addition to the main lighting fixtures in accordance with the requirements of 2.9.3, 2.9.11 and 2.9.13. The reserve lighting fixtures shall be powered separately from the electrical equipment and main lighting fixtures installed in the refrigerating machinery room.

22 SPARE PARTS

22.1 Every ship shall be provided with spare parts in the amount sufficient for repairing when essential services fail at any situation, an accident at sea inclusive, in order to ensure movement, control and safety of a ship and people on board.

22.2 Specifying a required minimum of spare parts, the recommendations of manufacturers of specific kinds of equipment shall be followed.

23 SPECIAL REQUIREMENTS FOR ELECTRICAL EQUIPMENT OF SHIP'S ELECTRIC POWER SYSTEM WITH ELECTRICAL POWER DISTRIBUTION FOR DIRECT CURRENT

23.1 GENERAL

23.1.1 These requirements shall apply to the ship electric power d.c. distribution systems with voltage up to 1500 V measured between the pole terminals.

23.1.2 For the ship electric power d.c. distribution system the use of auxiliary sources and items of alternative three-phase current complying with the applicable sections of this Part of the Rules is permitted.

23.1.3 Both direct current generator and rectifier supplied from the alternating current generator may be the sources of d.c. electrical power.

23.1.4 In addition to the system for insulation resistance monitoring specified in 2.11, the portable devices for search of insulation fault location shall be applied.

23.2 CONNECTION SYSTEMS OF ELECTRIC POWER SUPPLY UNITS

23.2.1 In addition to the requirement to subdivide the d.c. main busbar into two parts, specified in 3.5.6, it is allowed to use two independent main switchboards interconnected by cable jumpers or bus cables. Automatic switches shall be provided on both ends of the cable jumper or bus cable. In this case, connection of generators and duplicated consumers shall be symmetrically distributed between the main switchboards, where practicable.

23.3 ELECTRICAL POWER DISTRIBUTION

23.3.1 Distribution systems and permissible voltage.

23.3.1.1 In the ship electric power d.c. distribution systems and the unified electric power d.c. distribution plants only the application of two-wire insulated system of electrical power distribution is allowed.

23.3.1.2 The permissible d.c. voltage at the terminals of electric power sources shall not exceed 1500 V.

23.3.1.3 At least two voltmeters shall be provided for d.c. main switchboard. In case d.c. main switchboards are divided, each part shall be fitted with a voltmeter.

23.3.1.4 One ammeter and one voltmeter shall be provided for each rectifier supplying d.c. busbars.

23.3.2 Power supply of essential consumers.

23.3.2.1 Essential consumers may be supplied from the d.c. power distribution box via the converter or from the separate a.c. distribution box supplied from the a.c. generators complying with the requirements of 3.1 and 3.2.

23.3.3 Distribution box arrangement.

23.3.3.1 D.c. main switchboard, generator sets and rectifiers shall be located in close vicinity to each other, as stated in 4.6.6.5.

23.3.4. Calculation of short-circuit currents.

23.3.4.1 In the calculation of maximum and minimum short-circuit currents, a short-circuit source, in addition to those specified in 4.6.3.2, shall contain all other devices (special electromechanical and electrical condenser-type power storages, for example, a.c.-d.c. (d.c.-a.c.) motor generators, filters with capacitors of large total capacity) operating simultaneously and able to produce current contribution to the short-circuit point. Calculation for d.c. distribution gear shall be made for a solid short-circuit fault between conductors of opposite polarity.

Short-circuit currents shall be calculated for all circuits, in accordance with 4.6.3.2, including fuses, automatic circuit breakers, and other electrical equipment, as well as for points on the busbars of a d.c. switchboard.

23.3.4.2 Since the circuits contain short-circuit currents of capacitors and capacitor banks, a short circuit process may be accompanied by resonant currents resulting from power exchange between capacitators and inductive elements in these circuits. Therefore, it is recommended to use software and computer simulation of relevant systems or their equivalent fragments in short-circuit current calculation.

Short-circuit current calculation shall be performed in a circuit from rectifier's output terminals to main switchboard's busbars, at outputs of an automatic circuit breaker, and directly on main switchboard's busbars. In the latter case current contribution of all main circuits shall be calculated.

23.3.4.3 Results of short-circuit calculation for individual circuits shall contain the list of selected electrical switching devices, fuses, and their ratings, including, for selective circuit breakers, permissible thermal withstand values I^2t.

To confirm feasibility of a protective function by the selected equipment, the list shall contain design values of maximum and minimum short-circuit currents, as well as on-site design values I^2t of protective devices, for a corresponding time equal to a trip setting.

Protection of the equipment against short-circuit currents with protective devices shall be assessed by comparison of the rated thermal withstand value I^2t to the relevant design thermal withstand value for a short-circuit current flowing during the time equal to the trip setting of the switch.

23.3.4.4 To calculate short-circuit currents in ship's power systems with complete or partial distribution of power for direct current, a procedure described in Appendix 1 to this Section is recommended.

23.4 PROTECTION DEVICES

23.4.1 Faults on the d.c. generator side.

23.4.1.1 When the protection specified in 8.2.6 is activated, the generator shall be shut off from the main switchboard and its excitation shall automatically be removed.

23.4.2 Faults on the rectifier side.

23.4.2.1 The rectifiers shall be fitted with protection devices against the pole-to-pole fault in the cable or bus cable connecting the rectifier and the main switchboard.

23.4.2.2 Residual current devices shall be applied to control earthing of the poles in equipment and feeders of direct current system,

23.4.2.3 An audible and visual alarm shall be activated in the system at any earth faults.

23.4.3 Protection of capacitors.

23.4.3.1 Capacitive power storages (capacitors and capacitor banks) of d.c. distribution gear shall be fitted with quick-response short-circuit current protection per each section and a slower one at the storage input/output.

23.4.3.2 D.c. link capacitors of semiconductor inverters of the electric drive powered from d.c. distribution gear shall be locked with diodes, when possible, to remove or reduce the contribution with discharging current and the one generated by an electrical machine in case of shirt-circuit in a source.

When it is not possible, connection to a distribution device shall be ensured via protective elements of quicker response.

23.5 ELECTRICAL MACHINES

23.5.1 D.c. generators and electric motors of nominal rated power 1000 kW and above shall be fitted with differential protection devices. For this purpose, a separate lead box shall be provided on a motor casing, located on the opposite side from the main box the slots for the sensors of differential protection shall be provided.

23.5.2 A.c. generators and built-in rectifiers may be provided with common cooling system.

23.6 A.C. POWER SUPPLY CONSUMER TRANSFORMERS

23.6.1 Transformers fed from the converters and used as power source shall comply with the rate parameter of permissible stress rate while feeding from the pulse sources.

23.7 ELECTRICAL POWER CONVERTERS

23.7.1 Heat transfer from power semiconductor elements of converters for d.c. distribution may be performed both by the air cooling system and liquid air coolers.
23.7.2 The rectifiers intended for the parallel operation shall be capable of equal load distribution including short-term load.
23.7.3 The voltage at the uncontrolled rectifier output may be maintained by the excitation system of the generator to be used as power source for the rectifier.
23.7.4 The rectifiers of d.c. power sources shall contain a device for overshoot suppression and reception of excess power at the rectifier outlet connected to d.c. distribution qew.
23.7.5 As the rectifiers of d.c. electrical power source, the active controlled rectifiers constructed by the power source principle with the possibility to stabilize the output voltage and the additional function of reactive power compensation at the input may be applied.
23.7.6 In d.c. input circuit the inverters of the main propulsion plant shall be fitted with a device for overvoltage limitation and reception of surplus power from the electric drive in the regeneration mode.
23.7.7 In the output circuits of inverters the filters shall be installed to limit the stress rate up to the permissible level and to protect the coil insulation of the electric machine or transformer connected to the inverter.

23.8 ELECTRIC PROPULSION PLANTS

23.8.1 The electric propulsion plant supplied from and using a.c. electrical power includes the following devices:

.1 a.c. (or d.c.) main generators with their control devices — at least 2;

.2 a semiconductor converter-rectifier (may be built in the generator case, and is not used in case of power supply from a d.c. generator), either controlled or uncontrolled one, one per generator

.2 main switchboard separated in two parts with a section circuit breaker or break switch;

.4 storages compensating for power deficiency or excess;

.5 semiconductor converters — inverters of an electric propulsion plant for a.c. supply to stator windings of propulsion motors (or d.c. converters for d.c. supply to propulsion motor armature windings) — at least 2;

.6 arrangements (units) of control or controller of electric propulsion plants — at least 2;

.7 electric propulsion motor — one or more. For electric propulsion plants with one propulsion motor, it is necessary to provide two systems of stator windings, each powered from its own semiconductor inverter, or two armature windings, each powered from its own d.c. voltage converter.

23.8.2 At least two, totally independent, stand-alone semiconductor frequency converters (or, respectively, two inverters powered from the d.c. switchboard or two d.c. voltage converters) to power individual winding systems of the propulsion motor (or separate motors) shall be provided for the electric propulsion plant.

If the converter feeds a permanently excited electric propulsion motor of direct or alternating current (including those excited from permanent magnet), a quick-response protection device, for example, a switch disconnector, shall be fitted in the "converter – motor" line, which, in response to a signal from the diagnostic device, shall open automatically in case of failure of a rectifier, an inverter of a semiconductor frequency converter, or short-circuit at the inverter input supplied from the d.c. switchboard.

23.8.3 Circuits of each individual filter maintaining harmonic distortion levels within acceptable limits shall be protected against over-currents and short-circuit currents. When designing power filters, the possibility of integrating into the circuits of additional elements to reduce current contribution from capacitors and their variability in short-circuit conditions of external circuits.

Integrity of fuses in filter circuits shall be monitored. In case of any fuse burnout, an alarm warning system shall be activated.

23.8.4 Short-circuit and overload protection of the motor may be provided by an inverter or a power regulator connected to the d.c. switchboard.

Difference in designs of propulsion electrical machines (synchronous motor, permanent-magnet d.c. motor, asynchronous motor, switch reluctance motor or d.c. motor) shall be taken into account.

APPENDIX 1 (RECOMMENDED)

PROCEDURE FOR CALCULATING SHORT-CIRCUIT CURRENTS IN SHIP'S ELECTRIC POWER SYSTEMS WITH ELECTRICAL POWER DISTRIBUTION FOR DIRECT CURRENT

INTRODUCTION

This procedure is applicable to ship's power systems (SPS) with full or partial electrical power distribution for direct current. The procedure may be applied to ships of various purposes carrying autonomous and united power systems with d.c. power sources and a.c and d.c. power users.

The procedure contains general provisions on calculation of the short-circuit surge current in ship's power systems with d.c. distribution, to assess the electrodynamic resistance of the protective switching equipment and d.c. busbars.

ABBREVIATIONS

AB — accumulator battery
AR — active rectifier
AI — autonomous inverter
VTG — valve-type generator
AT — azimuth thruster
VPP — variable pitch propeller
VTSG — valve-type synchronous generator
FPP — fixed pitch propeller
GS — generator set
ME — main engine
PM — propulsion motor
EPP — electrical propulsion plant
DGS — diesel-generator set
UPS — unified power system
UPP — unified power plant
CB — capacitor bank
SC — short circuit
UR — uncontrolled rectifier
DM — driving motor
AVCS — automatic voltage control system
SG — synchronous generator
EPS — electric propulsion system
SEPP — ship's electric power plant
CR — controlled rectifier
EMF — electromotive force
PP — propulsion plant
PS — power system

1 GENERAL

The procedure provides for a simplified analytical calculation of short-circuit surge current in ship's electric power systems (PS) with partial or full electrical power distribution for direct current.

Three-phase synchronous generators shall be used as power sources.

Ship's a.c electrical power users may be supplied either directly from a.c. generators or d.c. switchboards via inverters.

Ship's d.c. electric power users are powered from d.c. switchboards connected via rectifiers to generators.

In case of full electric power distribution for direct current all ship's power users are supplied from the d.c. mains via semiconductor inverters or directly from the d.c main switchboard.

In case of partial d.c. power distribution, some ship's users are powered from the a.c main switchboard directly connected to d.c. generators, others are powered from a d.c. switchboard connected to the a.c. main switchboard via rectifiers and transformers.

The calculation goal is to check the protective switching equipment and d.c. busbars for electrodynamic resistance.

Two-pole solid SC in a d.c. mains has been assumed as design short circuit.

The procedure is applied to calculation of SC currents in autonomous and unified PS. In unified PS, main generator sets (GS) feed power to both ship's general power users and ship's electric propulsion system (EPS).

Calculation of short-circuit currents shall be made for the heaviest operation mode of the PS as regards short-circuit conditions.

To check the protection equipment of sources and sectional equipment, a SC point shall be selected so that the intensity of SC current flowing via the protection equipment or current lead reaches the maximum possible value.

Electrodynamic resistance of the equipment and current leads is determined by the maximum permissible SC current value.

Heat resistance is determined by the heat impact of SC current within the protection operation time. This procedure does not provide the calculation of the heat impact of SC current.

Calculation of electrodynamic resistance of the equipment and current leads shall consider the surge current from discharge of capacitors of rectifiers and inverters installed on the d.c. side.

The heat impact of SC current is calculated not taking into account automatic voltage regulation systems of valve-type synchronous generators (VTSG).

SC currents shall be calculated in sequence, by analyzing main current diagrams, determination of SC point contribution sources, preparation of a design circuit, selection of reference SC points, substantiation and selection of design operation modes of PS and contribution sources, preparation of a design equivalent circuit, calculation of SC currents from each contribution source and calculation of total SC current.

2 POWER SYSTEM MAIN CURRENT DIAGRAMS

2.1 Schematic diagram of the power system with partial electrical power distribution for direct current.

Ship's PS may be divided into systems with either partial or full electric power distribution for direct current.

In case of partial distribution of the d.c. power, some ship's users are supplied directly from synchronous a.c generators, others — via the a.c. mains by means of rectifiers and inverters.

In PS with partial distribution of the d.c. power, power sources, generator sets (GS), run at the constant speed and generate the d.c. power of the rated voltage and frequency.

These systems have local areas with d.c. power distribution. D.c. switchboards are supplied via rectifiers and power transformers. Most often, triple-wound voltage transformers with two output windings shifted by 30 el. deg. are used for power supply of the d.c. switchboard. An uncontrolled bridge semiconductor rectifier is connected to each secondary winding. Such connection of the uncontrolled rectifier enhances the power quality in the ship's a.c. mains and reduces a voltage non-sinusoidality ratio.

Ship's general power users receive power supply from a.c. main switchboard. A ship's powerful variable-frequency electric drive is supplied from the d.c. main switchboard via semiconductor autonomous inverters (AI).

PS with partial distribution of d.c. power are typically used with composite propulsive systems.

In composite propulsive systems, a propeller is driven simultaneously by the main heat engine (ME) and the propulsion motor (PM). Either fixed or variable pitch propeller (FPP, VPP) may be used as a ME. Diesel-generator sets (DGS) are used as GS. Either diesel or gas turbine serve as a driving motor.

D.c. main switchboards may supply ship's powerful variable-frequency electric drives, including thrusters. In the course of ship service, PM or ME may operate the propeller in either autonomous or joint mode. A typical schematic diagram of PS with partial distribution of d.c. power and composite propulsive system is shown in Fig. 2.1.

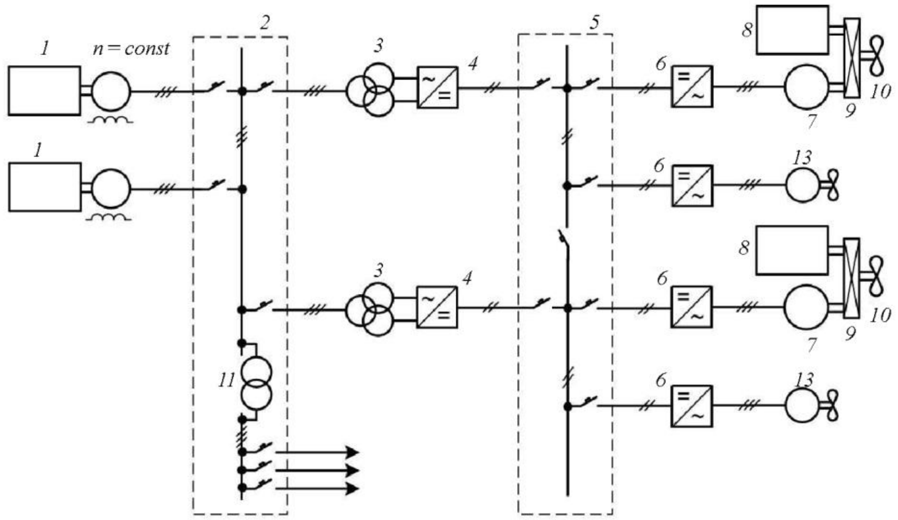


Fig. 2.1
A typical schematic diagram of PS with partial distribution of d.c. power and composite propulsive system:
1 — diesel-generator sets; *2* — a.c. main switchboard; *3* — three-winding transformers; *4* — semiconductor rectifiers;
5 — d.c. main switchboard; *6* — semiconductor inverters; *7* — propulsion motor; *8* — main engine; *9* — reduction gearbox; *10* — propeller; *11* — stepdown transformer; *12* — ship's general power users; *13* — thruster

The schematic diagram of PS with partial distribution of d.c. power as shown in Fig. 2.1-1 comprises diesel-generator sets *1* running at a constant speed. The a.c. main switchboard *2* is supplied directly from DGS *1*. The d.c. main switchboard *5* is powered from the a.c. main switchboard *2* via three-winding transformers *3* and twelve-pulse bridge rectifiers *4*.

D.s. main switchboard *5* feeds propulsion motors (PM) *7* and thruster motors *13*. Ship's a.c. power users are supplied directly from the a.c. main switchboard *2* by means of the stepdown power transformer *11*.

2.2 Schematic diagram of the power systems with full electrical power distribution for direct current.

In PS with full distribution of the generated d.c. power, all the power generated by GS is fed via semiconductor rectifiers to the d.c. main switchboard. GS run at a variable speed or have several speed settings. These systems are used on fully electrical ships or on ships equipped with a powerful electric drive.

Depending on the ship's purpose and architecture, PS may employ one or two d.c. main switchboards arranged at some distance from each other. The switchboards are interconnected with bus ducts or a cable. They may be installed in an engine or motor room.

Synchronous generators excited from electromagnets or permanent magnets are used as electric generators. Bridge circuits serve as semiconductor rectifiers. Uncontrolled diode rectifiers, controlled thyristor rectifiers and active transistor rectifiers may be used.

AI most frequently assembled in a bridge circuit on transistors are used as inverters.

EPS with two electrical propulsion plants (EPP) are operated on single-shaft and twin-shaft ships. Propellers with direct torque transfer from PM or azimuth thrusters may serve as propulsors.

Fig. 2.2-1 shows a schematic diagram of PS with full distribution of the generated d.c. power with two EPP, low-speed PM and direct torque transfer to propeller.

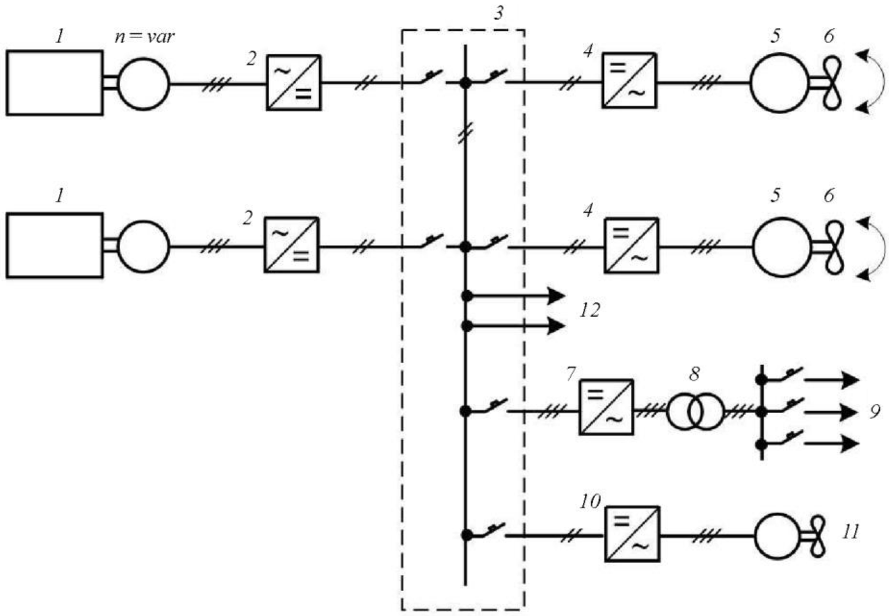


Fig. 2.2-1
Schematic diagram of PS with full distribution of the generated d.c. power and an electric propulsion system with direct torque transfer to propeller:
1 — diesel-generator sets; *2* — semiconductor rectifiers; *3* — d.c. main switchboard; *4* — EPP semiconductor inverters; *5* — propulsion motor; *6* — propeller; *7* — semiconductor inverter of ship's general power users; *8* — stepdown main transformer; *9* — ship's general a.c. power users; *10* — semiconductor inverter of a thruster; *11* — thruster; *12* — ship's general d.c. power users

According to this diagram, GS *1* run at a variable speed and generate the d.c. power fed via semiconductor rectifiers *2* to the d. c. main switchboard *3*. The main switchboard *3* supplies the EPP semiconductor inverters *4*.

D.c. PM *5* are supplied from the inverter *4* and set the propeller *6* into motion. PM *5* are of reversible configuration and allow switching from motor to generator operation mode during the EPP operation.

Thruster *11* and ship's general power users *9* are supplied from the d.c. main switchboard *3* via autonomous inverters *7*, *10* and stepdown main transformers *8*.

According to this diagram, PM *5* may run at braking in generator mode with power recuperation to the ship's d.c. mains and to prime movers. PM *5* is of reversible configuration.

In PS, ship's d.c. power users *12* can be connected to, and supplied directly from the d.c. main switchboard *3*.

This diagram may be used for construction of PS on the basis of reversible shaft generator units capable of running both in motor and generator operation modes. There is no principal difference in the diagram configuration of PS with reversible shaft generator units and composite propulsive systems.

Fig. 2.2-2 shows a schematic diagram of PS with full distribution of the generated d.c. power with single-shaft EPS and two low-speed PM *5* connected in tandem with direct torque transfer to propeller *6*. Two three-phase PM in this diagram of EPS may be substituted with two and more three-phase units.

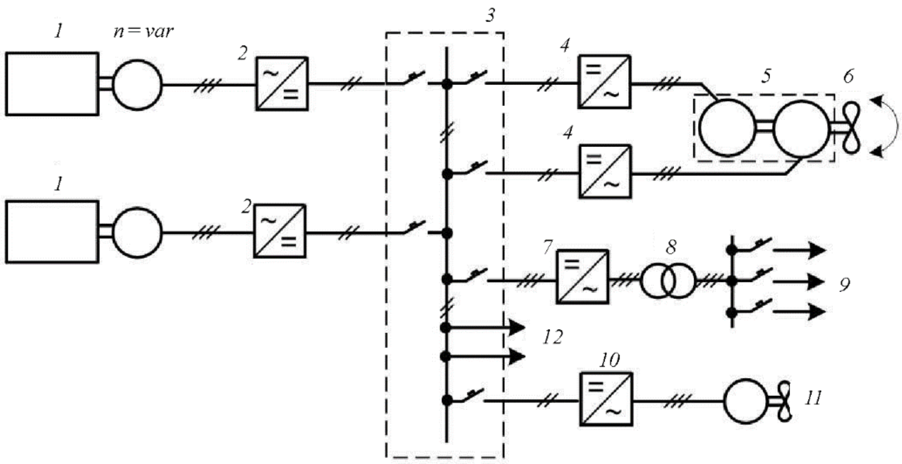


Fig. 2.2-2
Schematic diagram of PS with full distribution of the generated d.c. power and a single-shaft electric propulsion system with direct torque transfer to propeller:
1 — diesel-generator sets; *2* — semiconductor rectifiers; *3* — d.c. main switchboard; *4* — EPP semiconductor inverters; *5* — propulsion motor; *6* — propeller; *7* — semiconductor inverter of ship's general power users; *8* — stepdown main transformer; *9* — ship's general a.c. power users; *10* — semiconductor inverter of a thruster; *11* — thruster; *12* — ship's general d.c. power users

Fig. 2.2-3 shows a schematic diagram of PS with full distribution of the generated d.c. power with two EPP and mechanical azimuth thrusters (AT).

Difference of this PS from the previous one is that AT *6* with PM *5* installed in the ship hull perform as propulsors.

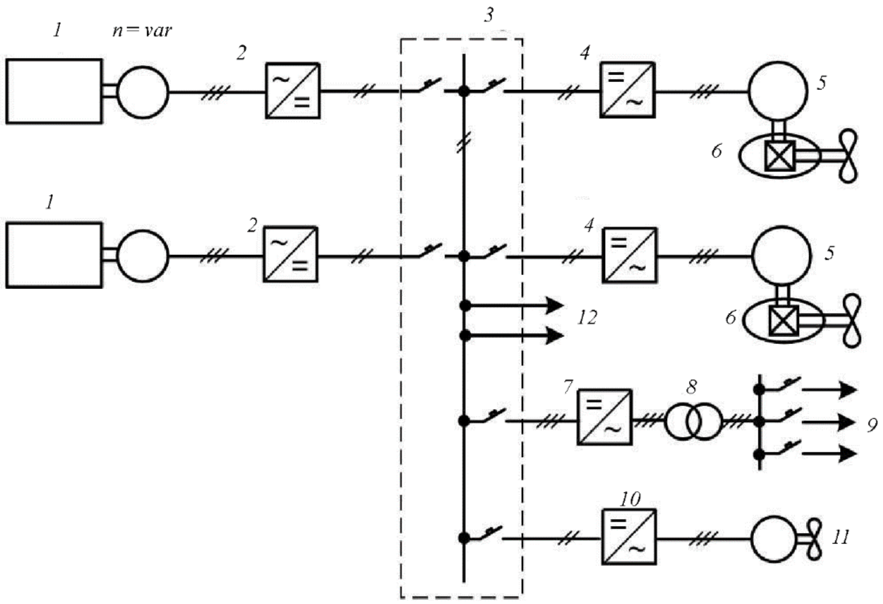


Fig. 2.2-3
Schematic diagram of PS with full distribution of the generated d.c. power with two EPP and mechanical AT:
1 — diesel-generator sets; *2* — semiconductor rectifiers; *3* — d.c. main switchboard; *4* — EPP semiconductor inverters; *5* — propulsion motor; *6* — azimuth thrusters; *7* — semiconductor inverter of ship's general power users;
8 — stepdown main transformer; *9* — ship's general a.c. power users; *10* — semiconductor inverter of a thruster; *11* — thruster; *12* — ship's general d.c. power users

Braking and reversing of the ship in this case are performed by turning AT *6*, and switching PM *5* over to generator operation mode with the ship braking, is excluded in this case.

PM *5* has a medium-speed configuration and is installed in the ship hull.

Figure 2.2-4 shows a schematic diagram of PS with full distribution of the generated d.c. power with two EPP and electrical AT *6*. PM *5* are arranged inside the ATpod.

With PM *5* arranged inside AT *6*, electrical machines shall have a low-speed configuration.

In these EPS, PM *5* may run in generator mode when, under the impact of oncoming seawater flows as the ship brakes, AT *6* switches over to hydraulic turbine operation mode.

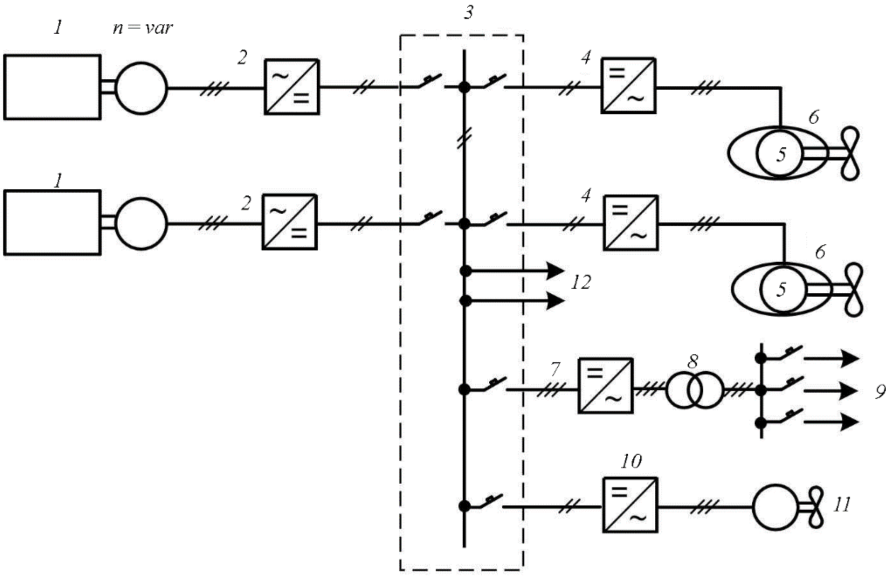


Fig. 2.2-4
Schematic diagram of PS with full distribution of the generated d.c. power with two EPP and electrical azimuth thrusters:
1 — diesel-generator sets; 2 — semiconductor rectifiers; 3 — d.c. main switchboard; 4 — EPP semiconductor inverters; 5 — propulsion motor; 6 — azimuth thrusters; 7 — semiconductor inverter of ship's general power users;
8 — stepdown power transformer; 9 — ship's general a.c. power users; 10 — semiconductor inverter of a thruster; 11 — thruster; 12 — ship's general d.c. power users.

3 CONTRIBUTION SOURCES TO THE SHORT-CIRCUIT POINT

Contribution sources to a short-circuit (SC) point in PS with electrical power distribution for direct current may be as follows:

valve-type a.c. generators;

ship's powerful variable-frequency electric drive, including a propulsion electrical drive or a thruster drive;

ship's general uncontrolled electrical drive, including a.c. or d.c. ones;

static power storages, including capacitor banks or accumulator batteries.

3.1. Valve-type generators.

Main sources of electrical power on a ship are generator sets (GS). GS consist of a driving motor (DM) and an electric generator.

A diesel or a turbine may be used as DM. The motor type does have any influence on the surge SC current amount. A PS speed determines an electric generator's design and number of poles. As SC develops, no PM speed dip occurs at the first moment.

Three-phase synchronous generators excited from electromagnets and having salient poles are most frequently used as electrical generators. Synchronous generators (SG) excited from permanent magnets have also been used recently. Ships of smaller displacement are fitted with SG with two and more three- phase windings.

In addition to SG, the valve-type generator (VTG) comprises a semiconductor rectifier. In most cases rectifiers are configured basing on a bridge circuit. Either in-series or parallel connection of two and more bridge rectifiers is possible.

Semiconductor rectifiers may be assembled on the basis of:

diodes — uncontrolled rectifiers (UR);

thyristors — controlled rectifiers (CR) with amplitude-phase control;
transistors — fulled controlled or active rectifiers (AR).
Transformers may be provided at the UR or CR input, a choke — at the AR input.
Standard schematic diagrams of semiconductor rectifiers are shown in Fig. 3.1-1.

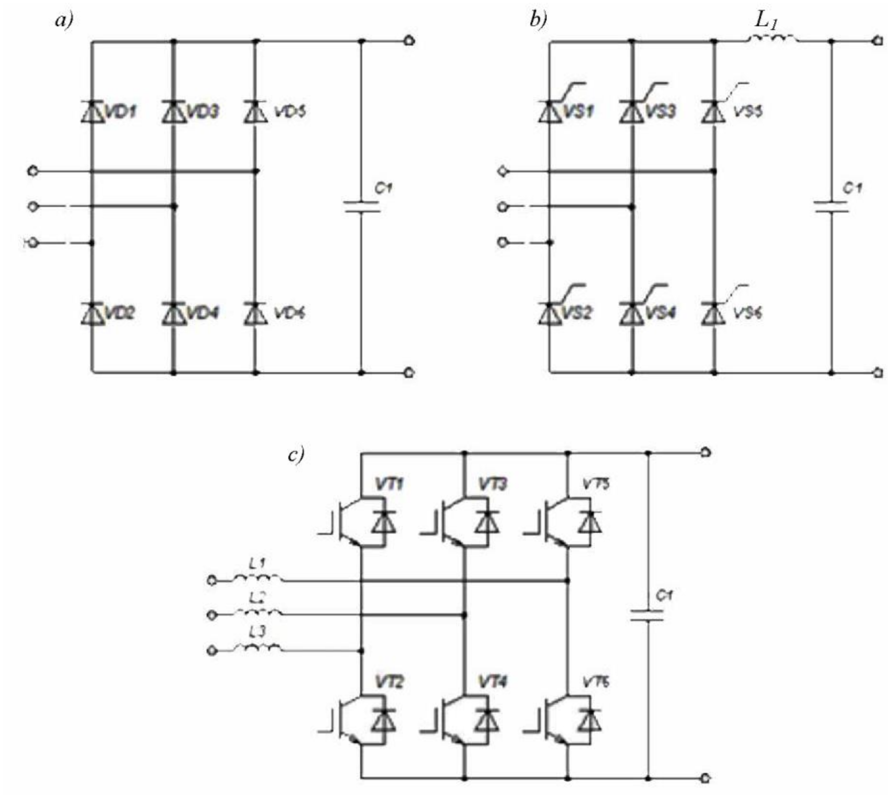


Fig. 3.1-1
Schematic diagrams of semiconductor rectifiers:
a — uncontrolled rectifier; *b* — controlled rectifier; *c* — active rectifier

When applying an uncontrolled rectifier (UR), an electromagnet-excited SG is used as a generator. The constant voltage at the rectifier input and in the d.c. mains of PS is ensured by means of the automatic voltage control system (AVCS) acting on the SG excitation winding.

When a controlled rectifier (CR) is used, SG excited from electromagnets or permanent magnets may be included in VTG. The constant voltage in the d.c. mains of PS is ensured due to combined action of AVCS of the synchronous generator and pulse-phase control system of the CR. When active rectifiers are used as part of VTG, the constant voltage in the d.c. mains of PS is ensured by the rectifier's AVCS.

Standard schematic diagrams of valve-type generators based on uncontrolled rectifiers are shown in Fig. 3.1-2.

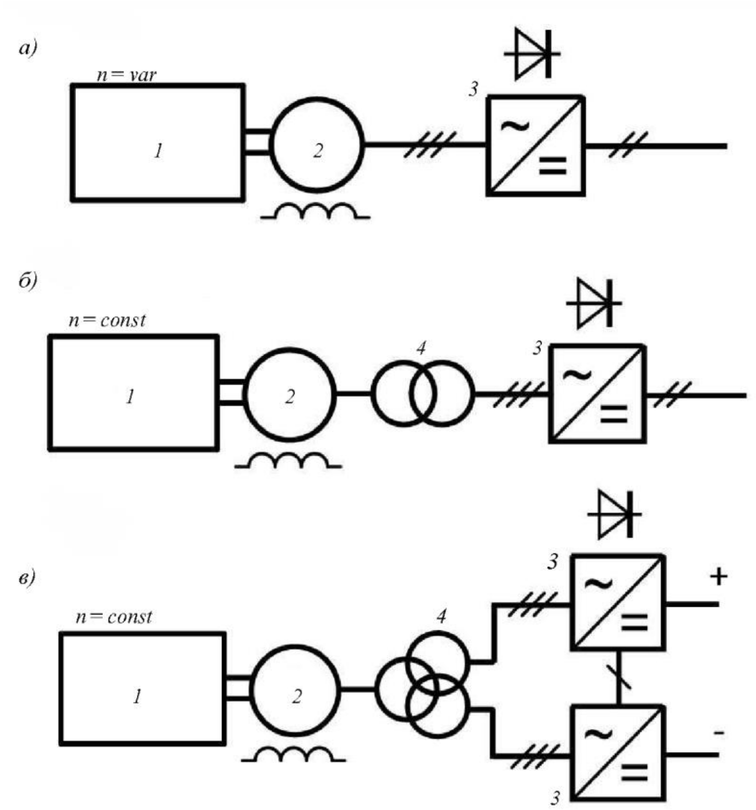


Fig. 3.1-2
Schematic diagrams of valve-type generators based on uncontrolled rectifiers:
a — VTG with six-pulse UR; *b* — VTG with six-pulse UR and two-winding transformer;
c — VTG with twelve-pulse UR and three-winding transformer:
1 — driving motor; *2* — electromagnet-excited synchronous generator; *3* — bridge rectifier; *4* — transformer

Fig. 3.1-2, *a* shows a schematic diagram of VTG with six-pulse UR. This VTG may operate both at constant and variable speeds. The constant voltage in the d.c. mains of PS is ensured with AVCS of the synchronous generator.

Fig. 3.1-2, *b* shows a schematic diagram of VTG with six-pulse UR and two-winding step-up transformer. The voltage is controlled as described above, due to combined action of the generator's AVCS.

Fig. 3.1-2, *c* shows a schematic diagram of VTG with twelve-pulse UR and three-winding transformer. These VTG are used in PS with partial distribution of d.c. power. In this case GS operates at a constant speed, and SG is connected to the a.c. main switchboard, which feeds d.c. main switchboard via the three- winding transformer and twelve-pulse UR.

Standard schematic diagrams of valve-type generators based on controlled rectifiers (CR) are shown in Fig. 3.1-3.

Figure 3.1-3, *a* shows a schematic diagram of VTG with six-pulse CR and electromagnet-driven SG. The constant voltage in the d.c. mains of PS is ensured by the combined action of the synchronous generator's AVCS and CR.

Fig. 3.1-3, *b* shows a schematic diagram of VTG with six-pulse CR and SC excited from permanent magnets. The constant voltage in the d.c. mains of PS is ensured by the synchronous generator's AVCS.

A standard schematic diagram of the valve-type generator based on an active rectifier is shown in Fig. 3.1-4.

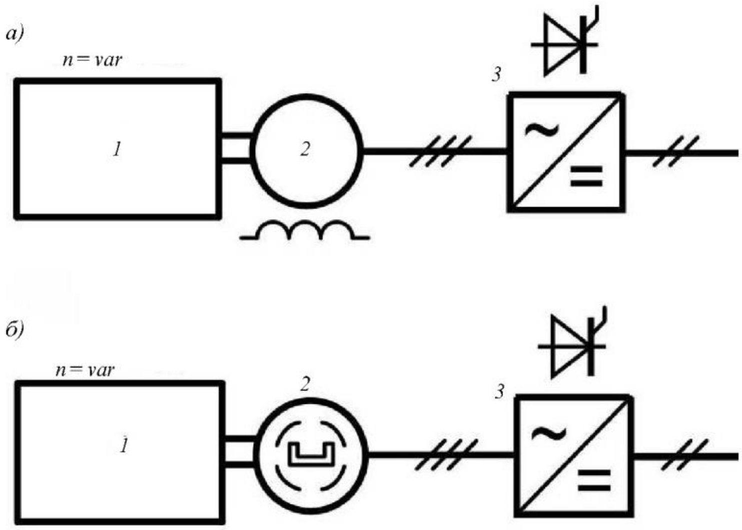


Fig. 3.1-3
Schematic diagrams of valve-type generators based on controlled rectifiers:
a — VTG with six-pulse CR and electromagnet-driven SG; *b* — VTG with six-pulse CR and permanent-driven SG
1 — driving motor; *2* — synchronous generator; *3* — six-pulse bridge rectifier

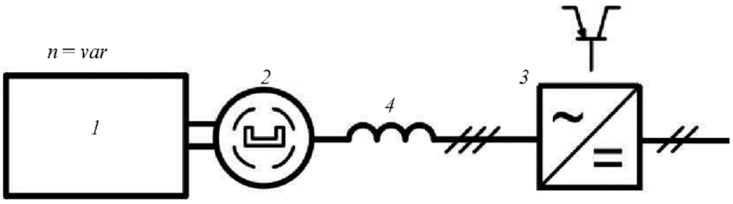


Fig. 3.1-4
Standard schematic diagram of the valve-type generator based on an active rectifier:
1 — driving motor; *2* — synchronous generator excited from permanent magnets; *3* — six-pulse bridge active rectifier; *4* — choke

In the VTG circuit, use of AR allows to maintain the voltage in the d.c. mains, starting from the SG rated voltage and higher.

3.2 Electric propulsion plants.

Contribution sources to a SC point in PS with electrical power distribution for direct current may be motors with variable-frequency electric drive, which, first of all, include PM of electric propulsion systems and thrusters.

EPP consist of autonomous semiconductor inverters, PM and propulsors.

A schematic circuit of the autonomous semiconductor inverter used in EPP is shown in Fig. 3.2-1.

The inverter consists of two three-phase bridges connected back-to-back, assembled on transistors and diodes. A semiconductor diode is back-to-back connected in parallel with each transistor. As a result, the inverter becomes reversible, and, in case of short circuit in the d.c. mains, the PM switches over to generator mode and contributes to the SC point with the current flowing via an uncontrolled bridge rectifier assembled on diodes.

At the AI voltage input, capacitor banks are installed to serve as another source of SC point contribution in the d.c. mains.

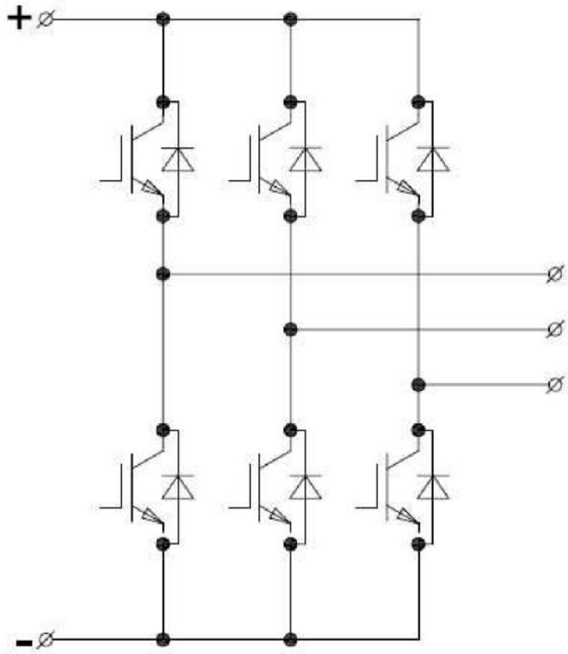


Fig. 3.2-1
Autonomous inverter

Propellers and azimuth thrusters may serve as propulsors in the EPP. As propellers in EPS, fixed-pitch propellers are most frequently used. Propellers are driven by low- or medium-speed PM. In the latter case PM is connected to the shafting via a reduction gearbox.

A standard schematic diagram of an EPP with direct torque transfer to the propeller is shown in Fig. 3.2-2.

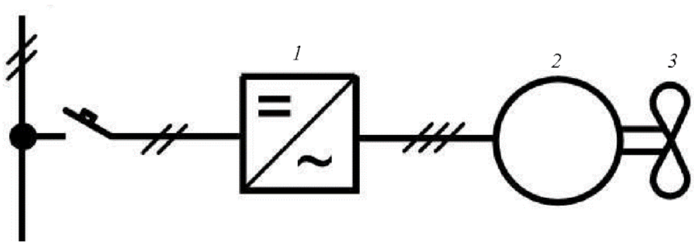


Fig. 3.2-2
A schematic diagram of the EPP with direct torque transfer to the propeller:
1 — semiconductor inverter; *2* — propulsion motor; *3* – fixed-pitch propeller

Asynchronous and synchronous motors excited from electromagnets or permanent magnets may be used in PM.

In the diagram shown in Fig. 3.2-2, the PM is reversible and may switch over to generator operation mode when the ship brakes.

In case of a single-shaft EPS, two PM may connected in tandem, or two-armature PM with two and more thee-phase windings may be used.

Fig. 3.2-3 shows a standard schematic diagram of the EPP with a composite propulsive system. According to this schematic diagram, PM *2* is medium-speed and designed for partial power output of the propulsive system.

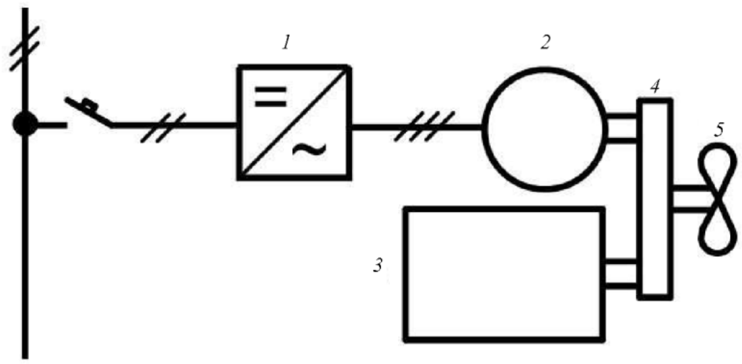


Fig. 3.2-3
Schematic diagram of the auxiliary EPP with a composite propulsive system
1 – semiconductor inverter; *2* – propulsion motor; *3* – main engine; *4* – gearbox; *5* – propeller;

In full speed mode, PM *2* and main engine (ME) *3* run jointly to operate propeller *5*, thus ensuring the maximum speed of the ship.

In economic speed mode, ME *3* drives both propeller *5* and PM *2*, which runs in generator mode and generates electric power fed to ship's general power users.

In low speed mode, PM *2* is powered from GS and ensures the ship's motion on its own. PM *3* is not involved in operation and disconnects from the reduction gearbox with a clutch.

Multi-purpose shaft-generator units are configured according to the same diagram, where the shaft generator may run both in generator mode and in propulsion motor mode.

Standard diagrams of the EPP with azimuth thrusters are shown in Fig. 3.2-4.

In the schematic diagram shown in Fig. 3.2-4, *a* PM *2* is medium-speed and arranged in the ship hull. Generator mode of PM *2* is possible for a short period of time only in case of short-circuit. The propeller's operation in hydraulic turbine mode in these units is excluded.

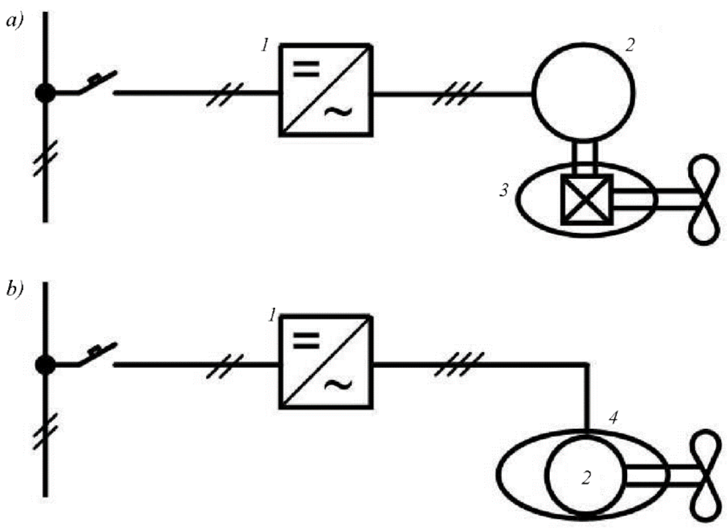


Fig. 3.2-4
Schematic diagrams of EPP with azimuth thrusters:
a — EPP with mechanical AT; *b* — EPP with electrical AT:
1 — semiconductor inverter; *2* — propulsion motor; *3* — mechanical AT; *4* — electrical AT

In the EPP shown in Fig. 3.2-4, *b* PM *2* is low-speed and installed in the AT *4* case. Generator mode of PM *2* is possible both in case of short-circuit and in hydraulic turbine mode of the propeller.

Asynchronous and synchronous electrical machines excited from electromagnets or permanent magnets have found application as PM in EPS with AT.

Number of poles in synchronous PM depends on the speed. Generally, PM is three-phase, less frequently a PM has two and more three-phase windings.

3.3 Ship's general power users.

3.3.1. Ship's general a.c. power users.

Ship's general a.c. power users may serve as contribution sources to a SC point in PS with the electrical power distribution for direct current , while being supplied from either d.c. or a.c. switchboard.

The uncontrolled asynchronous electric drive is most frequently used on ships as a ship's general a.c. power user. If short-circuit develops, asynchronous machines switch over to generator mode of operation. Ship's statical load is not involved in contribution to a SC point.

In PS with partial distribution of d.c. power, ship's a.c. power users are supplied from the a.c. main switchboard, and in case of short-circuit on the d.c. main switchboard, their contribution current is added to that of the generators and flows to the SC point via the transformer and semiconductor rectifier.

The diagram of connection of the ship's general a.c.load to the a.c. main switchboard in PS with partial d.c. power distribution is shown in Fig. 3.3.1-1.

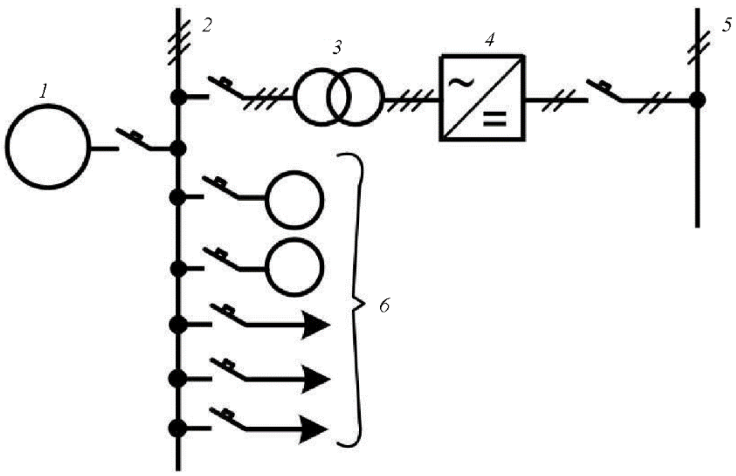


Fig. 3.3.1-1
Diagram of connection of the ship's general a.c. load with partial d.c. power distribution:
1 — generator; *2* — a.c. main switchboard; *3* — main stepdown transformer of EPP; *4* — semiconductor inverter; *5* — d.c. switchboard; *6* — ship's general a.c. load

When calculating the SC current in PS with electrical power distribution for direct current, a ship's asynchronous drive may be reasonably substituted with an equivalent electric motor. Ship's statical load is not involved in contribution to a SC point.

The connection diagram of the equivalent electric motor in PS with partial d.c. power distribution is shown in Fig. 3.3.1-2.

In PS with full distribution of the d.c. power, ship's a.c. power users are supplied from the secondary a.c. switchboard. In its turn, the a.c. switchboard is connected to the d.c. main switchboard with a two-winding stepdown transformer and an autonomous voltage inverter (AI).

The voltage AI is reversible and is assembled according to the diagram shown in Fig. 3.2-1. Therefore, when a short circuit occurs in the d.c. mains, contribution may be provided by asynchronous motors, which at the moment short circuit run in generator mode for a short time.

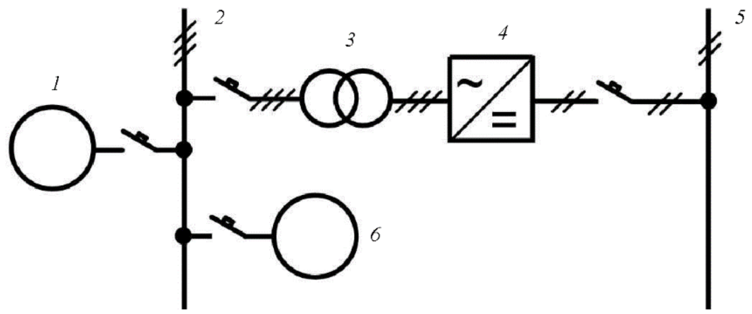


Fig. 3.3.1-2
Connection diagram of the equivalent motor in PS with partial d.c. power distribution:
1 — generator; *2* — a.c. main switchboard; *3* — main stepdown transformer of EPP; *4* — semiconductor inverter; *5* — d.c. switchboard; *6* — equivalent electric motor

The diagram of connection of the ship's general a.c. load to the d.c. main switchboard in PS with full d.c. power distribution is shown in Fig. 3.3.1-3.

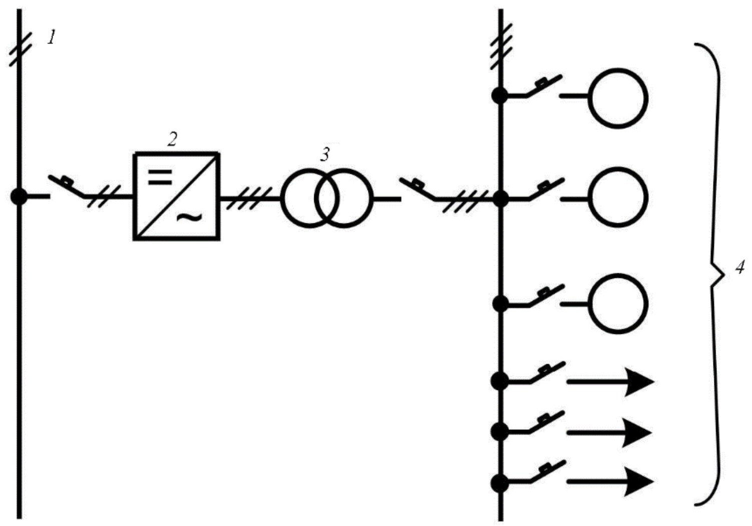


Fig. 3.3.1-3
Diagram of connection of the ship's a.c. load in PS with full d.c. power distribution:
1 — d.c. main switchboard; *2* — autonomous inverter; *3* — stepdown power transformer; *4* — general ship's load

When calculating the SC current in PS with electrical power distribution for direct current, a ship's asynchronous drive may be reasonably substituted with an equivalent electric motor. Ship's statical load is not involved in contribution to a SC point.

The connection diagram of the equivalent electric motor in PS with full distribution of d.c. power is shown in Fig. 3.3.1-4.

3.3.2. Ship's general d.c. power users.

A contribution source of a SC point may be a d.c. electric drive connected to the main switchboard or the d.c. switchboard.

A d.c. drive is connected to the d.c. mains via a starter or a semiconductor d.c.-d.c. converter.

Fig. 3.3.2 shows a diagram of connection of a d.c. electric drive to the d.c. main switchboard.

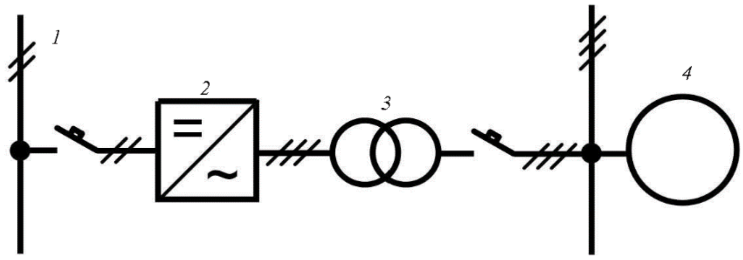


Fig. 3.3.1-4
Connection diagram of the equivalent motor in PS with full d.c. power distribution:
1 — d.c. main switchboard; *2* — autonomous inverter; *3* — stepdown power transformer;
4 — equivalent electric motor of ship's general load

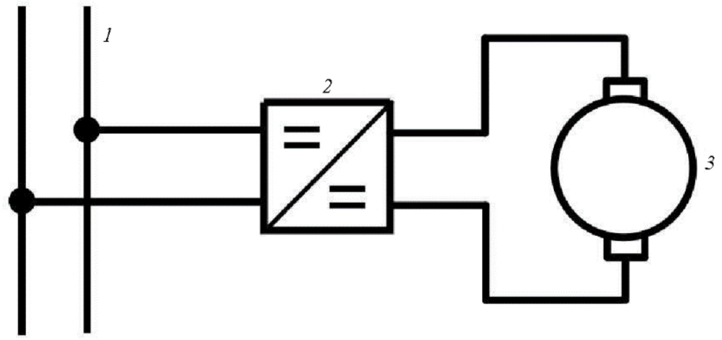


Fig. 3.3.2
Connection diagram of a d.c. electric drive to the d.c. main switchboard:
1 — d.c. main switchboard; *2* — semiconductor d.c.-d.c. converter; *3* — d.c. electric motor

3.4 Capacitor banks.

In PS with the electrical power distribution for direct current, the contribution current to a SC point may be generated by capacitor banks.

Capacitor banks may be installed at the rectifiers output, inverters input, or connected directly to d.c. busbars of the main switchboard or a switchboard.

The connection diagram of capacitor banks in the d.c. mains of PS is shown in Fig. 3.4.

When calculating the SC current in PS with eletrical power distribution for direct current, a contribution current to a SC point from each unit of capacitor banks shall be calculated separately.

In case of short-circuits in any d.c. busbar circuits, surge short-currents of other generators may be significantly impacted by discharging currents of capacitors if there are common circuits for the surge current and discharging current of capacitors.

Capacities of capacitors mounted at inputs of inverters and being part of AI are significant, reaching 1 mF per 1 MW of the inverter power. If the resistance of bus segments where capacitor discharging currents are flowing is low, values of discharging currents may reach hundreds of kiloamperes at the minimum current buildup time.

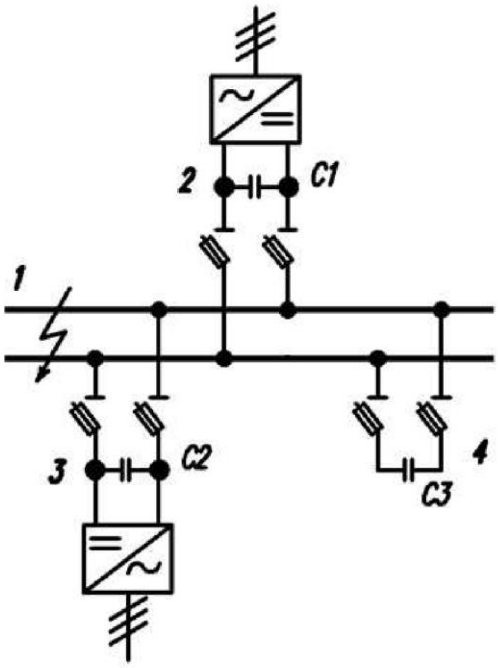


Fig. 3.4
Connection diagram of capacitor banks in the PS d.c. mains:
1 — d.c. main switchboard; *2* — semiconductor rectifier with capacitor banks at its output;
3 — autonomous inverter with capacitor banks at its input; *4* — individual capacitor banks

3.5 Accumulator batteries.

In PS with distribution of the d.c. power, accumulator batteries may be used for storing the electrical power. Accumulator batteries may be connected to d.c. busbars of the main switchboard either directly or via a d.c.-d.c. converter.

When a short-circuit occurs in the d.c. mains, accumulator batteries may function as sources contributing to a SC point.

The diagram of direct connection of accumulator batteries in the d.c. mains of ps to the d.c. main switchboard is shown in Fig. 3.5-1.

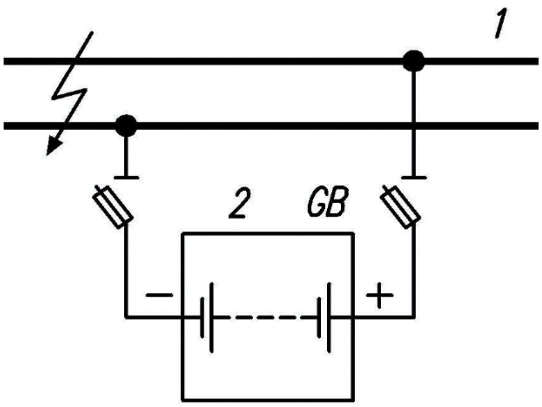


Fig. 3.5-1
Connection diagram of accumulator batteries in the d.c. mains of PS:
1 — d.c. main switchboard; *2* — accumulator batteries

The diagram of connection of accumulator batteries in the d.c. mains of PS to the d.c. main switchboard via semiconductor d.c.-d.c. converters is shown in Fig. 3.5-2.

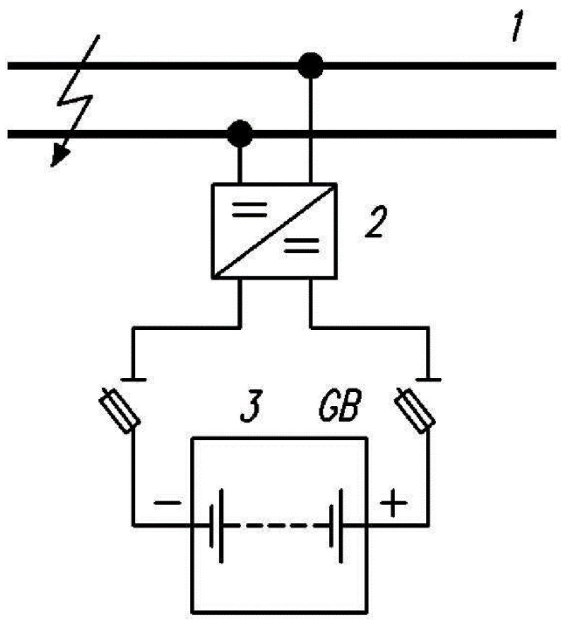


Fig. 3.5-2
The connection diagram of accumulator batteries in the d.c. mains of PS via semiconductor d.c.-d.c. converters:
1 — d.c. main switchboard; *2* — semiconductor d.c.-d.c. converter; *3* — accumulator batteries

Schematic circuits of d.c.-d.c. converters are quite diverse. In the PS diagrams in question, these converters are reversible and allow both charging AB and AB operation as a power source to the ship's mains. Therefore, all switchboards connected to the d.c. main switchboard are considered to contribute to a SC point.

When calculating the SC current in PS with electrical power distribution for direct current, a contribution current to a SC point from all accumulator batteries provided in the mains and connected to the main switchboard or a d.c. switchboard shall be calculated separately.

4 SELECTION OF DESIGN OPERATION MODE OF POWER SYSTEM AND CONTRIBUTION SOURCES TO A SHORT-CIRCUIT POINT

4.1 Selection of power system and electric power system design operation mode.

PS with partial and full power distribution are described with a great variety of operation modes. Intensity of SC currents is considerably dependent on the operation mode. Therefore, the operation mode, in which as many as possible sources contributing to a SC point operate, shall be selected.

When selecting an operation mode of the ship's electric power plant (SEPP), a mode with maximum number of GS running in parallel shall be selected.

In the calculation all electric propulsion plants and all thrusters are assumed to be operating unless specified otherwise in the design and operational documentation.

The equivalent electric motor's power is calculated for the most heavily loaded operation mode of SEPP.

4.2 Selection of operation mode of contribution sources to a short-circuit point.

The electrical machine speed influences the inductive reactances of an armature winding. As the GS speed drops, so does the frequency of the generated current, with reactances decreasing proportionally. Alongside with that the SG voltage and power may drop, also impacting the SC current intensity. Therefore SC currents from generators shall be calculated at the rated and minimum GS speed.

SC currents from PM shall be calculated at the rated speed when the electromotive force (EMF) of the electrical machine is maximum. Similarly, currents contributing to a SC point from motors of thrusters and any other powerful variable-frequency electric drive shall be calculated at the rated speed.

SC currents from reversible VTG or PM in composite propulsive systems shall be calculated for the electrical machine running in generator mode at the rated and minimum operational speed.

Units of capacitor banks and accumulator batteries shall be considered fully charged for the purpose of calculation.

5 POWER SYSTEM DESIGN CIRCUITS

5.1 General requirements for the power system design circuit.

Design circuits shall be prepared on the basis of PS circuit diagrams.

The circuit shall comprise the entire set of the generators and power converters, d.c. and a.c. users operating in the mode under consideration. Static power storages such as accumulator batteries and capacitor banks may be omitted in the circuit.

The circuit shall include the switchgear and protection equipment, current leads, individual large motors comparable with power supply sources and connected to d.c. switchboard, main transformers, ship's asynchronous load as an equivalent motor connected to the a.c. switchboard.

The following technical data of PS elements required for calculation of SC currents shall be included in the circuit:

types, rated power, currents, and voltages of generators;

types, rated power of propulsion motors;

types, rated power of thruster motors;

types, rated power, and voltages of transformers;

types, rated power, currents and operation time of the switchgear and protection equipment;

types, rated power, currents, and voltages of semiconductor rectifiers and inverters;

cross-section, number of cores and length of current leads;

voltages and currents of equivalent d.c. and a.c. motors;

types, voltages and currents of individual heavy-duty motors.

5.2 Design circuit of a power system with full electrical power distribution for direct current.

Fig. 5.2 shows the design circuit for PS with full distribution of the generated d.c. power. The design circuit is prepared in accordance with the above-considered circuit diagram.

The design circuit 5.2 shows generators *1*, semiconductor rectifiers *2*, d.c. main switchboard *3*, EPP semiconductor inverters *4*, semiconductor inverter of ship's general power users *5*, semiconductor inverter of a thruster *6*, stepdown power transformer *7*, propulsion motors *8*, thruster motor *9*, ship's general a.c. power users *10*.

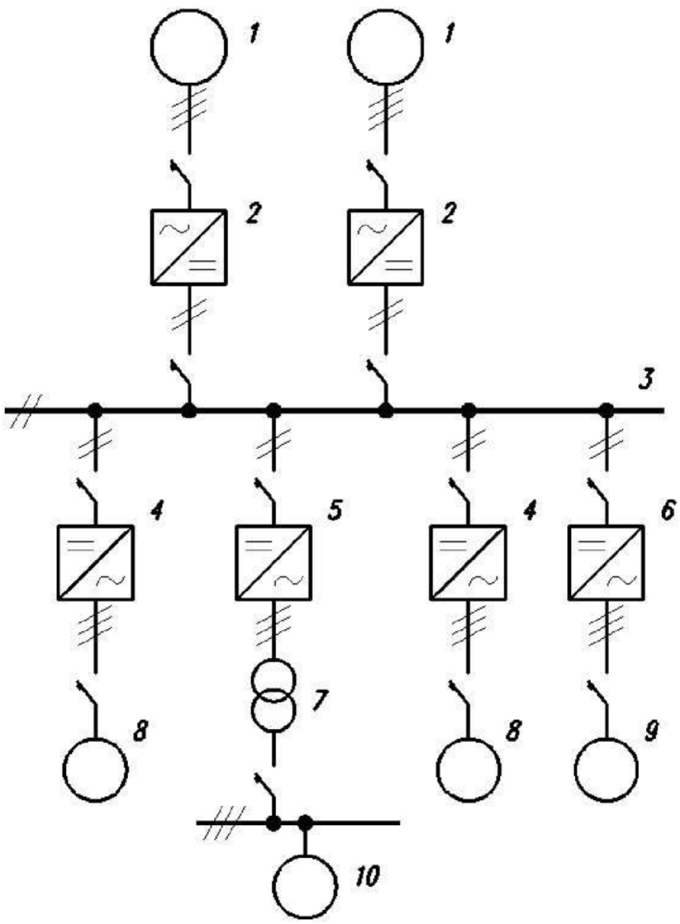


Fig. 5.2
Design circuit of PS with full distribution of the generated d.c. power:
1 — generators, *2* — semiconductor rectifiers; *3* — d.c. main switchboard; *4* — EPP semiconductor inverters;
5 — semiconductor inverter of ship's general power users; *6* — semiconductor inverter of a thruster;
7 — stepdown power transformer; *8* — propulsion motors; *9* — thruster motor;
10 — ship's general a.c. power users

5.3 Design circuit of a PS with partial electrical power distribution for direct current.

Fig. 5.3 shows the design circuit for PS with partial distribution of the d.c. power. The design circuit is prepared in accordance with the above-considered circuit diagram.

Design circuit 5.3 shows generators *1*, a.c. main switchboard *2*, EPP three-winding main transformer *3*, stepdown power transformer of ship's general power users *4*, twelve-pulse semiconductor rectifiers *5*, equivalent motor *6*, d.c. switchboard, semiconductor inverters of a thruster *8*, EPP semiconductor inverters *9*, propulsion motors *10*, thruster motors *11*.

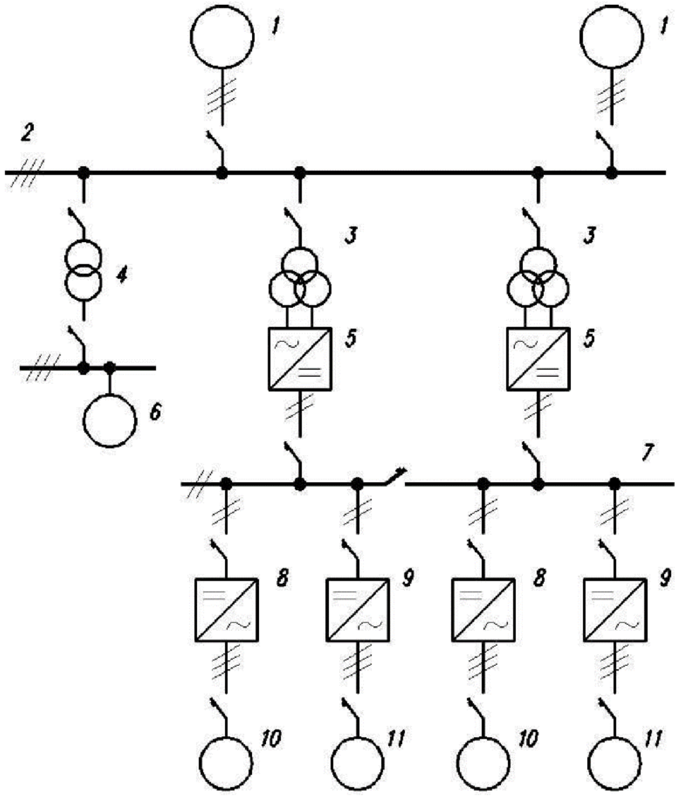


Fig. 5.3
Design circuit of PS with partial distribution of the generated d.c. power:
1 — generators; *2* — a.c. main switchboard; *3* — EPP three-winding power transformer; *4* — stepdown power transformer; *5* — semiconductor rectifiers; *6* — equivalent motor; *7* — d.c. switchboard; *8* — semiconductor inverters of a thruster; *9* — EPP semiconductor inverters; *10* — propulsion motors; *11* — thruster motors

6 SELECTION OF SHORT-CIRCUIT DESIGN POINTS

6.1 Short circuit design points in power systems with full electrical power distribution for direct current.

Design points shall be selected after preparation of the PS design circuit.

To check the protection equipment of power sources and section equipment, a SC point shall be selected so that the intensity of SC current flowing via the protection equipment or current lead reaches the maximum possible value.

To check the protection equipment, a SC point shall be assumed on outputs of the tested equipment. Fig. 6.1 shows an example selection of SC design points for PS with full distribution of the generated d.c. power.

Point *K1* is found on d.c. main switchboard busbars *3*. Short-circuit current calculation at this point is required for checking the busbars for thermal and dynamic resistance.

Depending on location of this short-circuit point, currents from sources contributing to the short-circuit place are added up. Contribution sources are generators *1*, propulsion motors *8*, thruster motors *9*, ship's load in terms of equivalent motor *10*.

Point *K2* is found from the side of generator *1* at the output of semiconductor rectifier *2*.

The SC current at this point is calculated to select the switchgear and protection equipment and determine the contribution current of SC current at *K1* point.

In the diagram under consideration, the switchgear and protection equipment may be installed at the rectifier *2* input and at the d.c. switchboard input *3*. An automatic circuit breaker (or safety fuses) at the rectifier *2* input are required to protect rectifier *2* and the outgoing line if no protection is provided in the rectifier.

In case of any internal damages in the semiconductor converter, short-circuit at its input or output, an automatic circuit breaker shall initiate a protective cutoff and prevent failure of the rectifier *2* or its complete destruction under internal damage.

The rectifier output may be fitted with a capacitor bank that will ensure additional contribution to the SC current at *K1* point. At the input of d.c. switchboard *3*, a d.c. automatic circuit breaker or a fusedisconnecting switch may be used as switchgear and protection device.

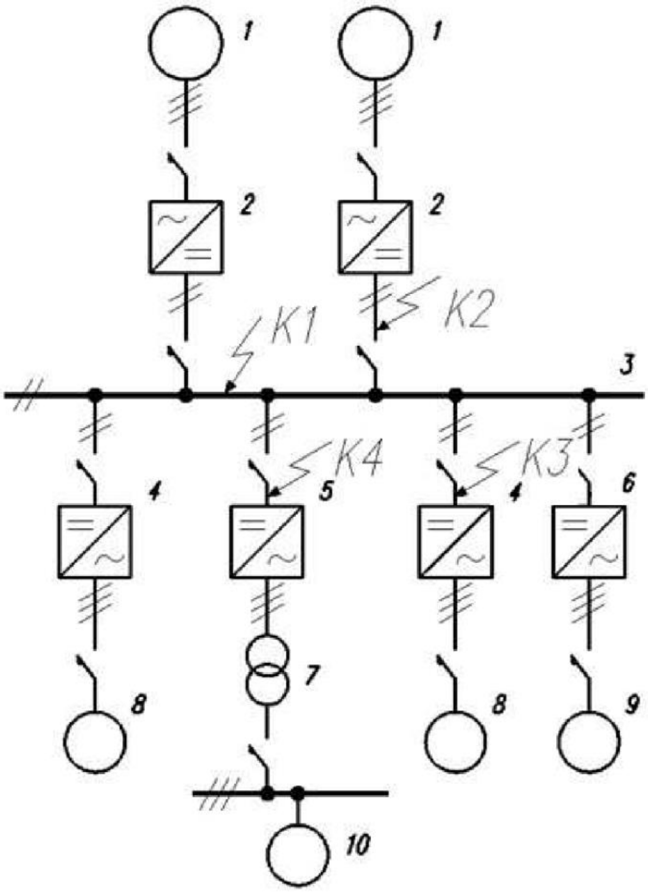


Fig. 6.1
SC design points in PS with full distribution of the generated d.c. power:
1 — generators, *2* — semiconductor rectifiers; *3* — d.c. main switchboard; *4* — EPP semiconductor inverters; *5* — semiconductor inverter of ship's general power users; *6* — semiconductor inverter of a thruster; *7* — main stepdown transformer; *8* — propulsion motors; *9* — thruster motor; *10* — equivalent motor

Point *K3* is found at inverter *4* input feeding the propulsion motor *8* or the thruster motor *9*.

Two SC currents converge in this point: the one from the propulsion motor (thruster motor) that has switched over to generator mode, and the other from d.c. main switchboard *3*.

In the first case the contribution current from the motor flows to the SC point, in the second case the total SC current flows to the SC point from the d.c. system.

It should be noted that a high capacity capacitor is provided at the inverter input *4*, *6*. If short-circuit develops at the busbars of the switchboard or at a different location, capacitors will discharge to the SC point. This current shall be taken into account in selection of the switchgear and protection equipment and calculation of the busbar's dynamic resistance. Generally, this feeder in the d.c. switchboard is protected with a fuse-disconnecting switch.

Point *K4* is found at the input of the inverter that supplies, via the a.c. switchboard, ship's general power users *10*. Two short-circuit currents converge at this point: from equivalent motor *10* of a.c. switchboard and from d.c. main switchboard *3*.

In the first case the contribution current from the equivalent motor *10* flows to the SC point, in the second case the total SC current flows to the SC point from the d.c. system.

It should be noted that a capacitor bank is provided at the inverter input *5*. In case of short-circuit, the current from the capacitor bank will also flow to the SC point.

If stepdown power transformer *7* is provided at the output of inverter *5*, it has a limiting action, which shall be taken into account in short-circuit current calculation.

6.2 Short circuit design points in power systems with partial electrical power distribution for direct current.

Fig. 6.2 shows an example selection of SC design points for PS with partial distribution of the generated d.c. power.

Point *K1* is found on d.c. switchboard busbars *7*. Short-circuit current calculation at this point is required for checking the busbars for thermal and dynamic resistance.

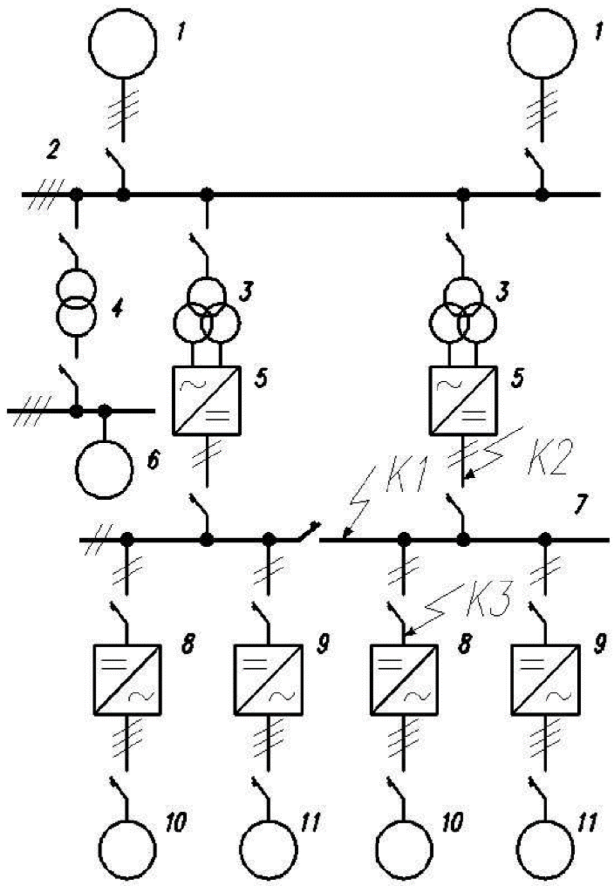


Fig. 6.2.
SC design points in PS with partial distribution of the generated d.c. power:
1 — generators; *2* — a.c. main switchboard; *3* — EPP power transformer; *4* — stepdown power transformer; *5* — semiconductor rectifiers; *6* — equivalent motor; *7* — d.c. switchboard; *8* — semiconductor inverters of a thruster; *9* — EPP semiconductor inverters; *10* — propulsion motors; *11* — thruster motors

Depending on location of this short-circuit point, currents from sources contributing to the short-circuit place are added up. Contribution sources are generators *1*, propulsion motors *10*, thruster motors *11*, ship's general load in terms of an equivalent motor *6*.

Point *K2* is located on the side of the a.c. distribution system at the output of the semiconductor rectifier *5*. The SC current at *K2* point is calculated to select the switchgear and protection equipment and determine the contribution current of SC at *K1* point. Since in the case under consideration the rectifier *5* is supplied from the power transformer, the short-circuit current is calculated for conditions of short-circuit at the secondary winding of the transformer *3*. Other calculations for this point are similar to those described for the circuit considered in 6.1.

Point *K3* is located at the inverter *9* input supplying the propulsion motor (thruster motor). Two short circuit currents converge at this point: the propulsion motor or thruster motor that has switched over to generator mode, and from d.c. main switchboard *7*.

In the first case the SC contribution current from the propulsion motor flows to point *K1*, in the second case, the total SC current flows to the SC point from the d.c. system. Other calculations for this point are similar to those described in 6.1 for the PS circuit above with full distribution of the d.c. power.

7 EQUIVALENT CIRCUITS OF POWER SYSTEMS

7.1 General requirements for preparation of power system equivalent circuits.

On the basis of the design circuit prepared for selected design modes and design SC points, an equivalent circuit for each SC point is prepared.

For this purpose circuit elements and power sources are substituted with resistances and electromotive forces (EMF) expressed in named units: resistors — in milliohms, currents — in kiloamperes, electromotive forces — in volts. Resistance values shall be assumed at an operating temperature.

Each accumulator battery group shall be substituted with equivalent EMF and impedance of the accumulator battery group, considering resistances of connections between elements and contact connections.

Each armature of a d.c. electrical machine shall be substituted with equivalent EMF and dummy resistance.

D.c. motors of auxiliary mechanisms are assumed as one equivalent power supply source with equivalent EMF and dummy resistance.

A.c. circuit elements (generators, transformers, motors, reactors, segments of cable runs and extended busbars) are substituted with active and inductive resistances.

Magnetically connected areas of the system are substituted with equivalent electrically connected circuits. Resistances of automatic circuit breakers and switching and protective equipment, as well as resistances of the units installed in one or two phases (for example, of a current transformer) shall not be included in the circuit.

It is allowed to neglect relatively low resistances: of automatic circuit breakers, generator cables of 10 — 15 m long, bus arrangement of boards, transient resistance of contacts.

Synchronous generators, synchronous and asynchronous motors in the equivalent circuits are taken into account with their EMF, active and inductive resistances. Parameters of generators and synchronous motors shall be assumed from their specifications. Parameters of asynchronous motors of various types and average parameters of equivalent asynchronous motors may be taken from Appendix 3 of OST5.6181-81 industrial standard.

When preparing an equivalent circuit, in-series resistances of elements of individual circuits (cables, busbars, equipment, transient resistances, resistances of contacts, etc.)

expressed in named units shall be substituted with total ones. Active and inductive resistances are added separately.

If there are transformers in the circuit, their substitute resistances shall be reduced to the same voltage level assumed as a base. Resistances of all circuit elements installed on another voltage levels, as well as currents, EMF, and voltages of these elements shall be levelled to the base.

7.2 Equivalent circuit of power system with full generated power distribution for direct current. Synchronous generators are used as power sources in PS, an asynchronous motor is used as an equivalent motor and a thruster motor. Synchronous or asynchronous motors may be used as propulsion motors.

Fig. 7.2-1 shows an example design equivalent circuit of PS with full distribution of the generated d.c. power, with asynchronous propulsion motors.

The PS comprises two synchronous generators *1*, equivalent asynchronous motor *2*, asynchronous propulsion motor *3*, thruster motor *4*.

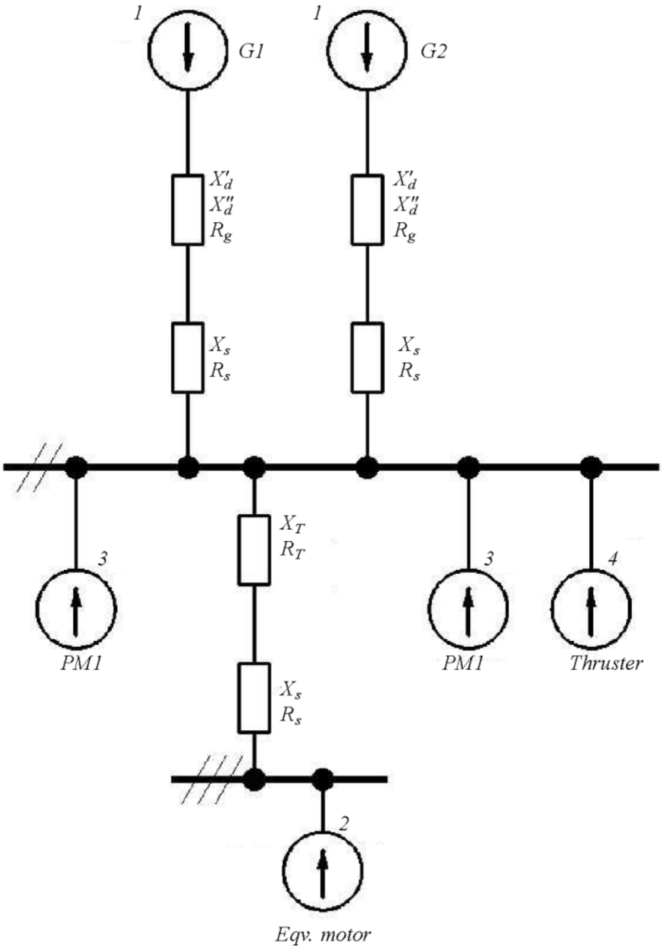


Fig. 7.2-1
Design equivalent circuit of a PS with full distribution of the generated d.c. power, with asynchronous propulsion motors:
1 — synchronous generators; *2* — equivalent asynchronous motor; *3* — asynchronous propulsion motor; *4* — asynchronous motor of a thruster

Fig. 7.2-2 shows an example design equivalent circuit of PS with full distribution of the generated d.c. power, with synchronous propulsion motors.

This circuit is different from the one in Fig. 7.2-1 in that a synchronous motor is used as PM.

Since, according to 2.5.4 of the standard OST5.6181-81, calculation of the synchronous motor's SC current is substituted with calculation of the SC current from a similar synchronous generator, resistances of a synchronous machine and a cable run are added to the PS circuit.

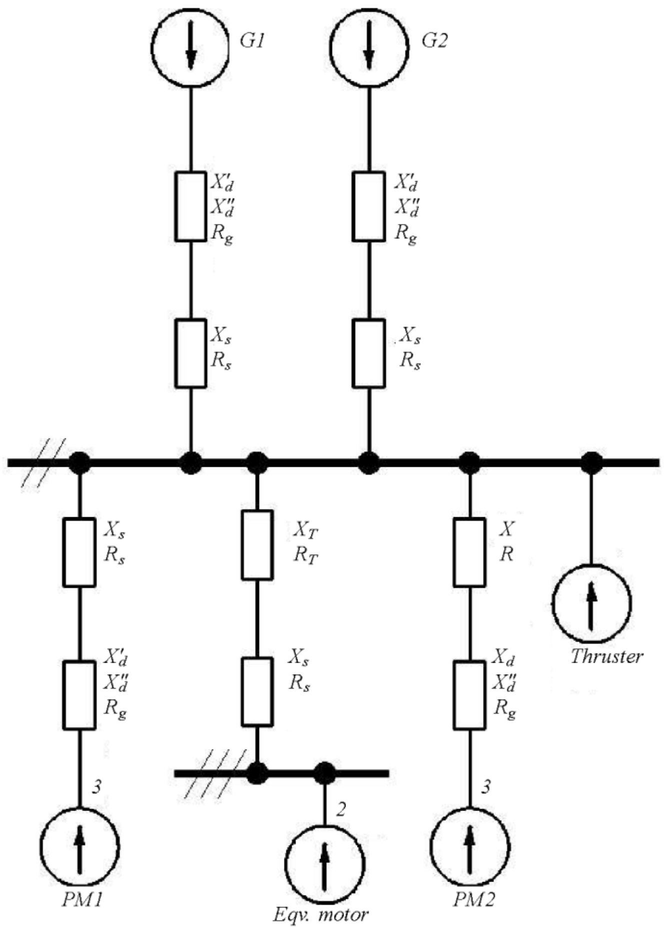


Fig. 7.2-2
Design equivalent circuit of PS with full distribution of the generated D.C. power, with synchronous propulsion motors:
1 — synchronous generators; *2* — equivalent asynchronous motor; *3* — synchronous propulsion motors;
4 — asynchronous motor of a thruster

7.3 Equivalent circuit of power system with partial generated power distribution for direct current.

Fig. 7.3-1 shows an example design equivalent circuit of a PS with partial distribution of the generated d.c. power, with asynchronous propulsion motors.

Fig. 7.3-2 shows an example design equivalent circuit of PS with partial distribution of the generated d.c. power, with synchronous propulsion motors. These circuits are regulated by the requirements set for the previous circuits with full distribution of the d.c. power.

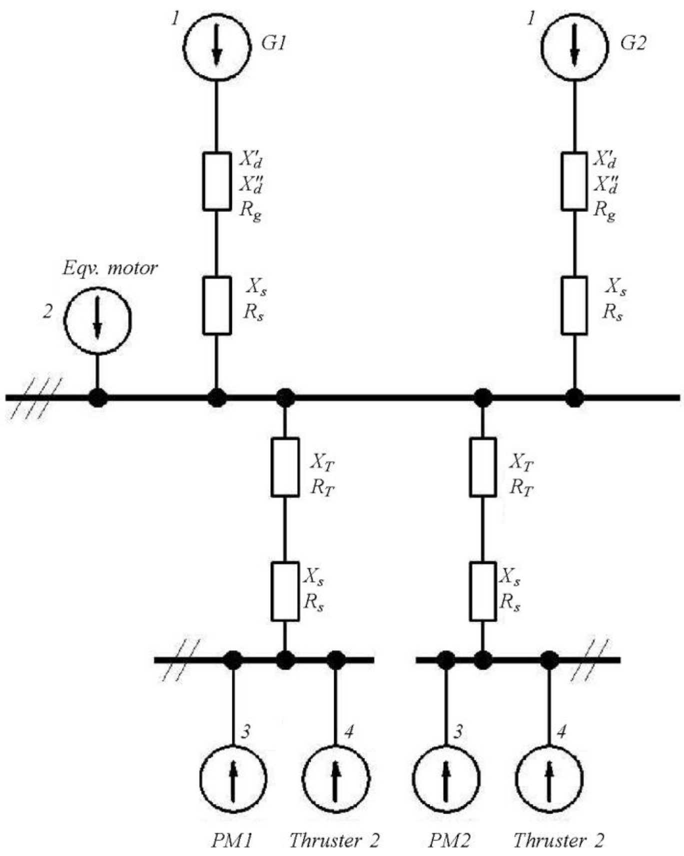


Fig. 7.3-1
Design equivalent circuit of PS with partial distribution of the generated d.c. power,
with asynchronous propulsion motors:
1 — synchronous generators; *2* — equivalent asynchronous motor; *3* — asynchronous propulsion motors;
4 — asynchronous motor of thrusters

7.4 Simplification of power system equivalent circuits.

7.4.1 After equivalent circuits are ready, they shall be simplified. To simplify a circuit, the following principles may be used:

.1 if a SC point is in the node where several branches converge, the circuit may be divided into parts (individual branches), with a short-circuit preserved at the end of each branch. In this case currents are calculated for each branch individually. The rated power of a generator or a group of generators in this branch shall be assumed as base power. The current at a SC point (circuit) is equal to a sum of currents of individual branches;

.2 if the circuit is fully symmetrical with respect to a SC point (similar sources, similar resistances, etc.), or a part of it is symmetrical with respect to an intermediate point, it may be summed along the axis of symmetry. In this case the power of sources or motors is equal to the sum of their powers, whereas resistances shall be added in parallel;

.3 substitution of in-parallel or in-series resistances with an equivalent one;

.4 substitution of two or more power supply sources with an equivalent one;

.5 parameters of all circuit elements involved in conversion shall be expressed in the same units.

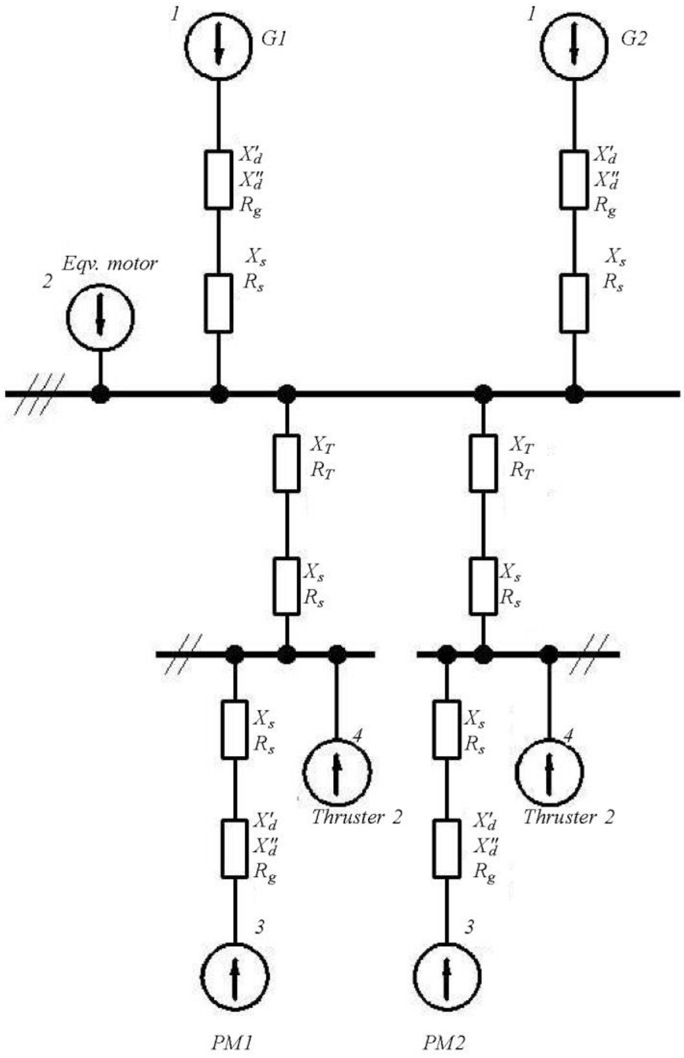


Fig. 7.3-2
Design equivalent circuit of PS with partial distribution of the generated d.c. power,
with synchronous propulsion motors:
1 — synchronous generators; *2* — equivalent asynchronous motor; *3* — synchronous propulsion motors;
4 — asynchronous motor of thrusters

8 CALCULATION OF SHORT CIRCUIT CURRENTS IN POWER SYSTEMS WITH ELECTRICAL POWER DISTRIBUTION FOR DIRECT CURRENT

8.1 General provisions of calculation of short-circuit currents in power system with electrical power distribution for direct current.

The following procedure is recommended for calculation of short-circuit currents in PS with d.c. power distribution:

.1 analysis of the PS main current diagrams;

.2 determination of power supply sources and sources contributing to SC points.

Power supply sources are:

generator sets;

propulsion motors supplied from the d.c. board via semiconductor inverters;

a.c. motors supplied from the d.c. board via inverters;
a.c. motors supplied from the a.c. board;
capacitors installed in the d.c. mains;
accumulator batteries.

.3 substantiation and selection of the PS design operation mode before a short-circuit occurs when generator sets and powerful motors in short-circuit conditions will generate the maximum current;

.4 preparation of design circuits specifying all power supply sources and SC point contribution sources.

.5 substantiation and selection of design SC points.

.6 preparation of PS equivalent circuits.

.7 determination of parameters of all power supply and contribution sources making up design circuits.

.8 calculation of SC current for each design point.

The calculation diagram of short-circuit currents in the PS d.c. mains is graphically shown in Fig. 8.1.1.

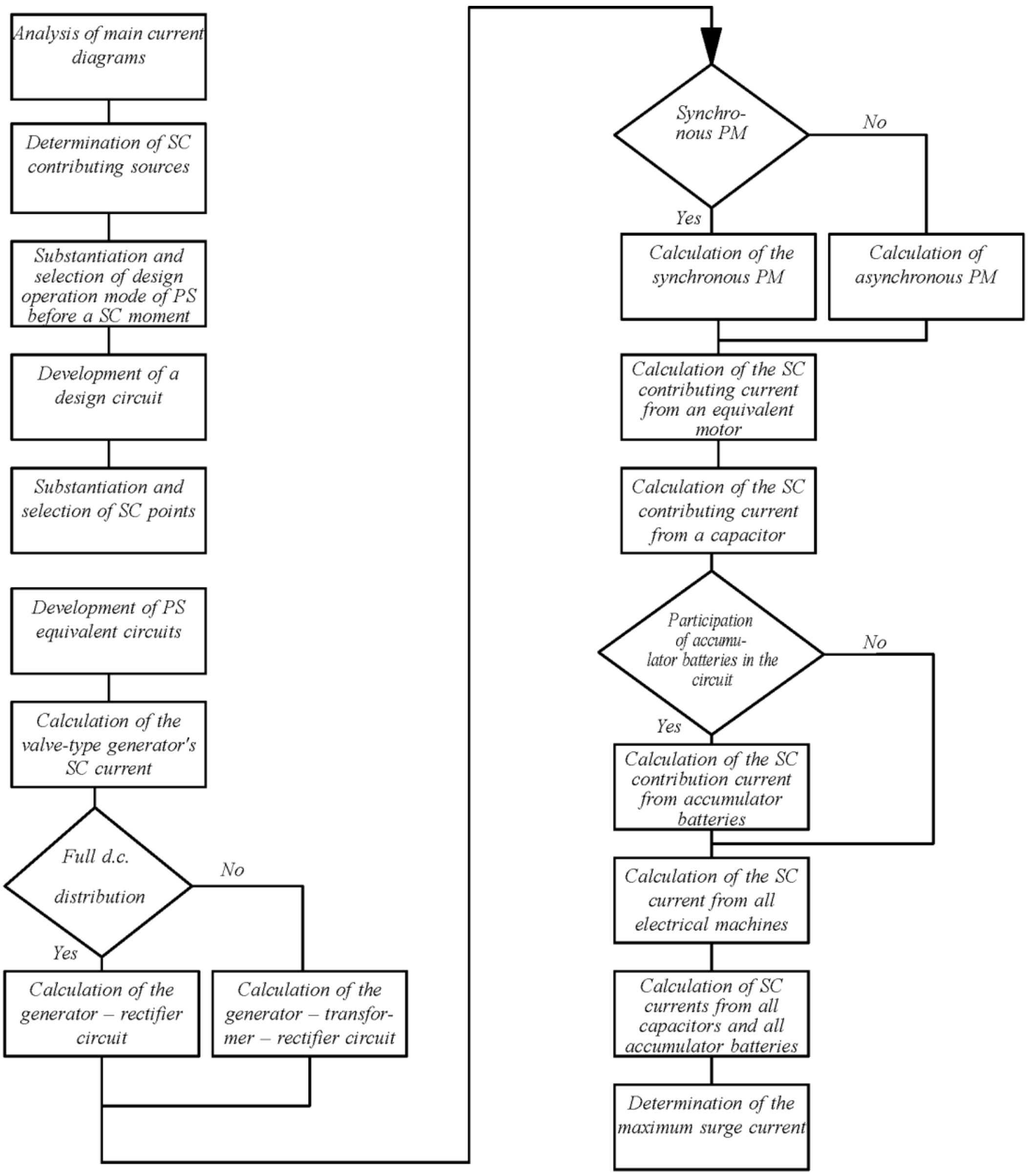


Fig. 8.1.1.
Calculation algorithm of short-circuit currents in PS with d.c. power distribution

8.2 Calculation of SC currents from generators.

8.2.1 Calculation of the short-circuit current in PS with partial power distribution for direct current. Power supply sources in PS with power distribution for direct current are valve-type generators consisting of an electric generator and a semiconductor rectifier.

In PS with partial distribution of d.c. power, the generator is connected to the a.c. main switchboard, that feeds power to the d.c. switchboard via the transformer and rectifier. The number of generators and the number of rectifiers may differ.

If a three-phase bridge rectifier is short-circuited, its supplying transformer becomes shorted via valves for the time of the short-circuit. Therefore, the SC current at rectifier outputs may be calculated in the similar way as for a symmetrical SC at secondary outputs of transformers.

Calculation of the rectifier's short-circuit shall consider the power ratio of the rectifier (its supplying transformer) and the main power supply source (a synchronous generator).

If the rectifier power is less than 1/25 of the synchronous generator's (generators') power, the maximum SC current at rectifier outputs is determined by the formula

$$I_{KTR} = \frac{100 \cdot \sqrt{2} \cdot P_{surg}}{e_s} \cdot I_r \cdot 10^{-3} \quad (8.2.1\text{-}1)$$

or by the formula

$$I_{KTR} = \sqrt{2/3} \cdot \frac{U_r \cdot P_{surg}}{\sqrt{x_{tr}^2 + r_{tr}^2}}, \quad (8.2.1\text{-}2)$$

where U_r — rated voltage of the secondary transformer winding, V;
I_r — rated current of the secondary transformer winding, A;
e_s — short-circuit voltage of the transformer, %;
r_{tr}, x_{tr} — active and inductive resistances of the transformer as reduced to the secondary winding, mOhm;
$P_{surg} = (1 + e^{-r_{tr}\pi/x_{tr}}))$ —surge factor that determines a relative value of the SC current aperiodic component.

Transformer resistance is determined by the formula

$$r_{tr} = \frac{\Delta P_s \cdot U_r^2}{S_r^2} \cdot 10^3; \quad (8.2.1\text{-}3)$$

$$x_{tr} = 10 \cdot \sqrt{e_s^2 - (\Delta P_s / 10 \cdot S_r)} \cdot (U_r^2 / S_r) \cdot 10^3, \quad (8.2.1\text{-}4)$$

where S_r — rated power of the transformer, kVA;
U_r — rated voltage of the secondary transformer winding, kV;
ΔP_s — short-circuit losses, W.

Transformer parameters required for the calculation are derived from rated data.

Formula (8.2.1-1) may be used for calculation of the SC current of a single-phase bridge rectifier supplied from a single-phase transformer.

Steady-state value of the SC current is found by Formulae (8.2.1-1) and (8.2.1-2) at $P_{surg} = l$.

If the rectifier power is more than 1/25 of the synchronous generator's (generators') power, parameters of the latter shall be considered in calculation of the maximum SC current.

PS parameters required for the calculation should be reduced to the same basic terms.

Basic terms shall be assumed as follows:

base power

$$S_b = S_{G1} + S_{G2} + \ldots + S_{GN}, \quad (8.2.1\text{-}5)$$

where $S_{G1} - S_{GN}$, — rated powers of synchronous generators feeding the SC point, kVA;

base voltage equaling the rated voltage of generators

$$I_b = I_{vg}; \quad (8.2.1\text{-}6)$$

base current

$$I_b = S_b/(\sqrt{3} \cdot U_b \,); \tag{8.2.1-7}$$

base resistance

$$Z_b = U_b/(\sqrt{3} \cdot I_b). \tag{8.2.1-8}$$

Resulting design resistance upstream of a SC point shall be reduced to basic terms by the formula

$$Z_b^* = Z_d/Z_b, \tag{8.2.1-9}$$

where Z_d — design resistance upstream of a SC point, mOhm;
Z_b — base resistance, mOhm;
Z_b^* — design resistance upstream of a SC point, p. u.

To calculate the maximum SC current of the rectifier, a design equivalent circuit shall be prepared where all elements (generators, equipment, cable run segments, transformer) shall be substituted with active and inductive resistances. All resistances of the design circuit shall be determined in terms of named units (refer to Fig. 8.2.1-1).

In calculation of the maximum SC current, it is recommended to neglect resistances of switchgear, busbars and transient resistances of contacts.

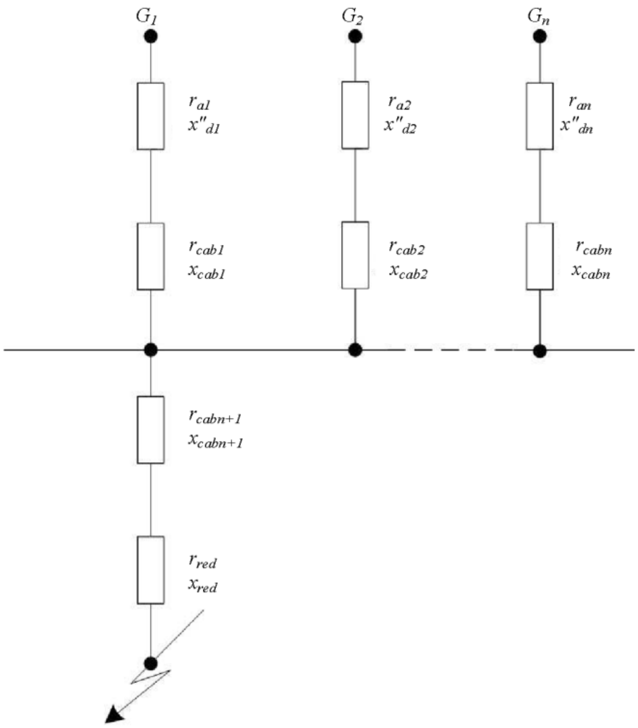


Fig. 8.2.1-1
The equivalent circuit for calculation of the SC current for generators in PS with partial d.c. power distribution: $G_1 - G_n$ — synchronous generators; $r_{a1} - r_{an}$ — active resistance of the generator stator winding phase at 348 K (75 °C), mOhm; $x''_{d1} - x''_{dn}$ — sub-transient inductive resistance of the generator along a longitudinal axis, mOhm; $r_{cab} - r_{cab+1}, x_{cab} - x_{cab+1}$ — active and inductive resistances of a.c cable segments, mOhm; r_{red}, x_{red} — active and inductive resistances of the transformer and circuit segment from rectifier leads to a SC point, as reduced to the primary winding's voltage, mOhm.

Active and inductive resistances of cable runs are derived from the formulae

$$r_{cab} = r_{sr} \cdot L_c/n;$$
$$x_{cab} = x_{sr} \cdot L_c/n, \tag{8.2.1-10}$$

where r_{sr}, x_{sr} — active and inductive resistances of 1 m cable line as derived from look-up tables;
L_c — cable segment length, m;
n — number of parallel cables.

The equivalent circuit for calculation of the SC current for generators in PS with partial d.c. power distribution is shown in Fig. 8.2.1-1.

Active and inductive resistances of the transformer and circuit segment from rectifier leads to a SC point, as reduced to the primary winding's voltage, shall be determined by the formulae

$$r_{red} = (r_{tr} + r_{s=}) \cdot (U_1/U_2)^2;$$
$$x_{red} = (x_{tr} + x_{s=}) \cdot (U_1/U_2)^2, \tag{8.2.1-11}$$

where U_1 and U_2 — rated voltage of the primary and secondary transformer windings, V;
r_{tr}, x_s — active and inductive resistances of the transformer derived from Formulae 8.2.1-3 and 8.2.1-4, mOhm;
$r_{s=}, i$ — active and inductive resistances of circuit elements in the segment from rectifier leads to a SC point, from the d.c. side, in one pole (if a choke is provided, 1/2 of its resistance shall be added to the design equivalent circuit), mOhm.

In each branch of the design equivalent circuit, active and inductive resistances are summed separately. As a result, the design circuit takes the form shown in Fig. 8.2.1-2.

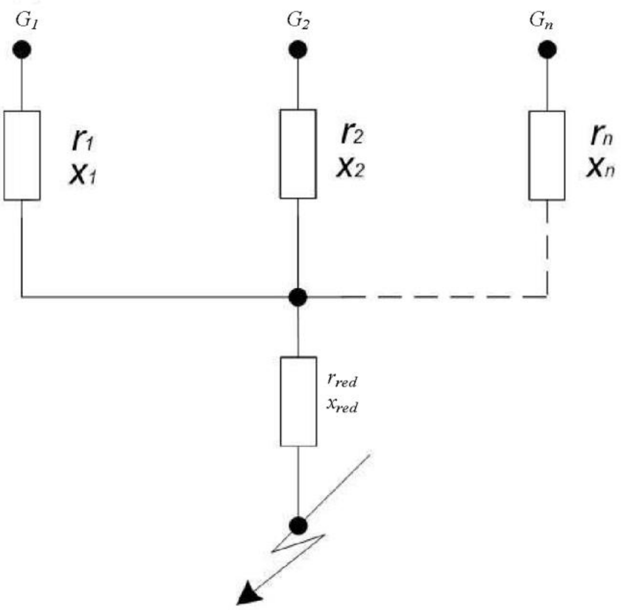


Fig. 8.2.1-2.
Design equivalent circuit of a separate segment

$$r_1 = r_{a_1} + r_{cab_1};$$

$$x_1 = x''_{d_1} + x_{cab_1};$$

$$r_n = r_{a_n} + r_{cab_n}; \quad (8.2.1\text{-}12)$$

$$x_n = x''_{d_n} + x_{cab_n};$$

$$r_к = r_{cab_{n+1}} + r_{red};$$

$$x_к = x_{cab_{n+1}} + x_{red}.$$

The design circuit (Fig. 8.2.1-2) transforms into the similar equivalent circuit by substitution of inparallel segments with an equivalent one (Fig. 8.2.1-3).

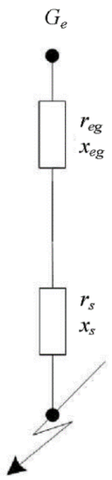


Fig. 8.2.1-3
Similar equivalent circuit of in-parallel segments

For two parallel generators, equivalent resistances are calculated by the formulae

$$r_{eg} = \frac{r_1 \cdot x_2^2 + r_2 \cdot x_1^2}{(x_1 + x_2)^2}; \quad (8.2.1\text{-}13)$$

$$x_{eg} = \frac{x_1 \cdot x_2}{x_1 + x_2}. \quad (8.2.1\text{-}14)$$

If there are more than two generators operating in parallel, the equivalent inductive resistance is determined by the formula

$$1/x_{eg} = 1/x_1 + 1/x_2 + \ldots + 1/x_n. \quad (8.2.1\text{-}15)$$

The active equivalent resistance in this case is determined by Formula (8.2.1-13), where the equivalent resistance x_{eg1} of two circuits is determined first, then x_{eg2} — the resistance of the new circuit, x_{eg1} and one of those remaining, etc.

The circuit (Fig. 8.2.1-3) transforms into the similar circuit by substitution of in-series segments with similar ones (Fig. 8.2.1-4).

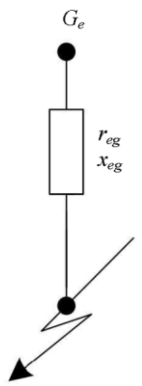


Fig. 8.2.1-4
Similar equivalent circuit of in-series segments

$$r_e = r_{eg} + r_s;$$
$$x_e = x_{eg} + x_s. \qquad (8.2.1\text{-}16)$$

Design resistance upstream of a SC point is determined.

$$Z_d = \sqrt{x_e^2 + r_e^2}\ . \qquad (8.2.1\text{-}17)$$

Design resistance upstream of a SC point in p. u. is determined by Formula (8.2.1-9).
Maximum SC current is determined by the formula

$$I_{KTR} = \frac{\sqrt{2}\cdot E_d^{"}}{Z_d^*}\cdot(\gamma + P_{surg} - 1)\cdot\frac{U_1}{U_2}\cdot I_b, \qquad (8.2.1\text{-}18)$$

where $E_d^{"}$ — initial value of sub-transient EMF, which, in calculation, is recommended to be assumed $E_d^{"} = U_b = 1{,}0$ p.u;

γ — attenuation factor of a SC current's periodic component for the time the maximum current is reached. For 400 Hz mains $\gamma = 1$, for 50 Hz mains it shall be derived from the curve in Fig. 8.2.1-5 as function of Z_d^* and the time constant of the SC sub-transient current's periodic component $T_d^{"}$ at the moment of time *t* = 0,01 s.

For a single generator operating, or for generators of same type operating in-parallel, $T_{de}^{"}$ is assumed to be equal to $T_d^{"}$ of one generator; for generators of different types operating in-parallel $T_{de}^{"}$ is assumed to be equal to $T_{de}^{"}$ with the higher value;

P_{surg} — surge factor derived from the curve in Fig. 8.2.1-6 as function of resistance ratio x_e/r_e, determined by Formula (8.2.1-16).

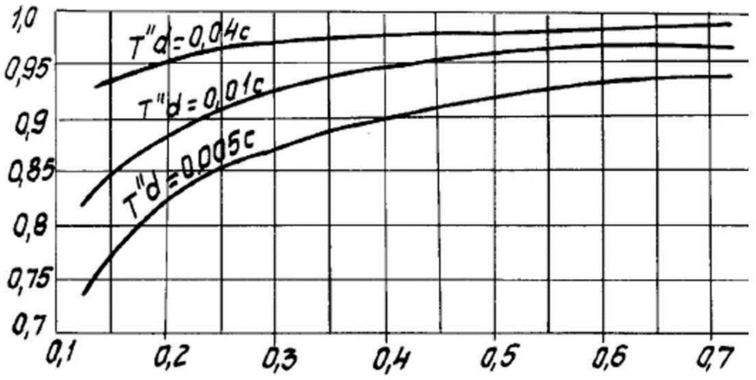


Fig. 8.2.1-5
Curves of the attenuation factor of a SC current periodic component versus Z_d^* and time constant of the SC sub-transient current's periodic component $T_d^{"}$: design resistance values upstream of a SC point Z_d^* at the *X*-axis; attenuation factor values γ at the *Y*-axis.

8.2.2 Calculation of the short-circuit current in PS with full electrical power distribution for direct current.

In PS with full distribution of the d.c. power, each generator is connected to its own rectifier.

If a three-phase bridge rectifier supplied directly from a synchronous generator is short-circuited, the SC current at rectifier outputs is calculated by the same method as in case of a symmetrical SC at generator leads, considering active and reactive resistances of the generator — rectifier cable line.

To calculate from rated values of the generator, the following values shall be determined:

S_{Gr} — full rated power of the generator, kVA;

U_r — rated voltage, V;

I_r — rated current of the generator, kA;

f — rated frequency of the generator, Hz;

r_G — active resistance of the stator winding, p. u.;

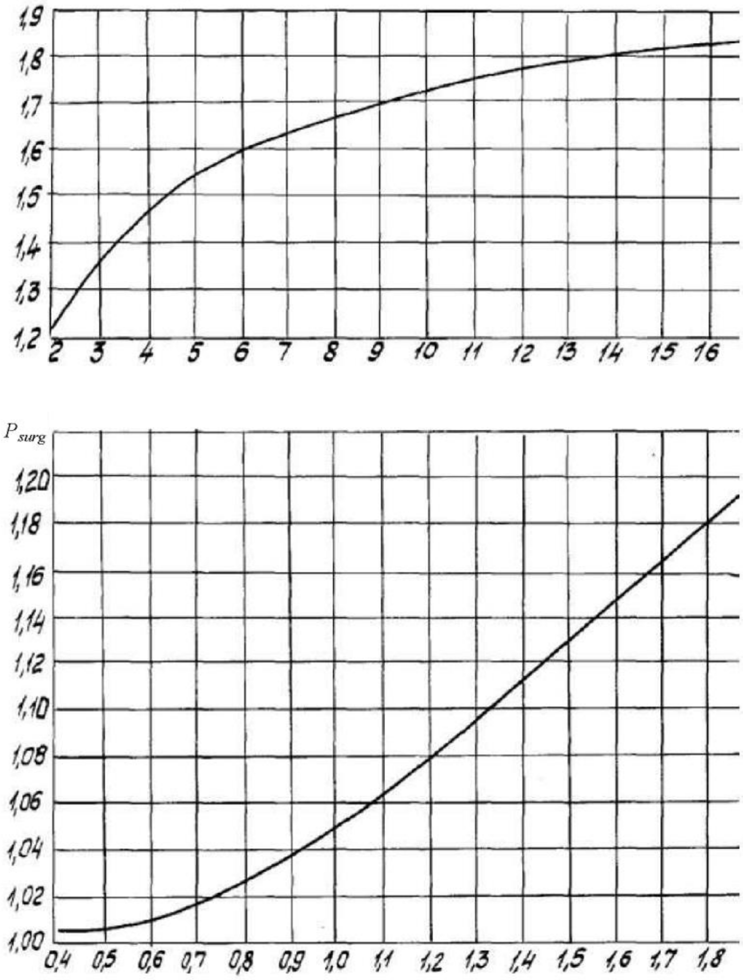


Fig. 8.2.1-6
Surge factor P_{surg} versus ratios x/r in the SC circuit:
values P_{surg} — at the *X*-axis; ratios x/r — at the *Y*-axis

$x_d^{"}$ — sub-transient inductive resistance along a longitudinal axis, p. u.;
x_d' — transient inductive resistance along a longitudinal axis, p. u.;
$T_d^{"}$ — sub-transient time constant along a longitudinal axis, s;
cosφ — power factor.

The equivalent circuit for calculation of the SC current for generators in PS with full d.c. power distribution is shown in Fig. 8.2.2.

Parameters required for the calculation shall be reduced to the same basic terms.

Basic terms shall be assumed as follows:

base power equal to the base power of generators $S_b = S_{GN}$;

base voltage equal to the rated voltage of generators $U_b = U_N$;

base current

$$I_b = S_b/(\sqrt{3} \cdot U_b); \qquad (8.2.2\text{-}1)$$

base resistance

$$Z_b = U_b/(\sqrt{3} \cdot I_b). \qquad (8.2.2\text{-}2)$$

Resulting design resistances upstream of a SC point shall be reduced to basic terms by the formula

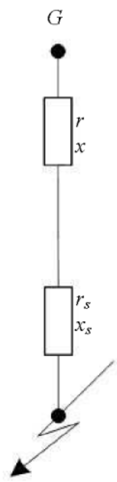


Fig. 8.2.2
The equivalent circuit for calculation of the SC current for generators in PS with full d.c. power distribution

$$Z_b^* = Z_d / Z_b, \quad (8.2.2\text{-}3)$$

where Z_d — design resistance upstream of a SC point, mOhm;
Z_b — base resistance, mOhm;
Z_b^* — design resistance upstream of a SC point, p. u.

To calculate the maximum SC current of the rectifier, a design equivalent circuit (Fig. 8.2.2) shall be prepared where all elements shall be substituted with active and inductive resistances. All resistances of the design circuit shall be determined in terms of named units.

Active and inductive resistances of cable runs are derived from the formulae

$$r_{cab} = r_{sr} \cdot L_c / n;$$
$$x_{cab} = x_{sr} \cdot L_c / n, \quad (8.2.2\text{-}4)$$

where r_{sr}, x_{sr} — active and inductive resistances of 1 m cable line as derived from look-up tables (Appendix 4 to OST5.6181-81 standard);
L_c — cable segment length, m;
n — number of parallel cables.

Active and inductive resistances of the generator shall be taken from the rated data of the machine whereas internal resistance of the rectifier as the short-circuit occurs may be neglected.

Then the sub-transient and transient EMF of the generator shall be determined in terms of p. u.

$$E_0'' = U_0 + I_0 \cdot x_d'' \cdot \sin\varphi_0; \quad (8.2.2\text{-}5)$$

$$E_0' = U_0 + I_0 \cdot x_d' \cdot \sin\varphi_0, \quad (8.2.2\text{-}6)$$

where $U_0, I_0, \sin\varphi_0$ — voltage and current of the generator in terms of p. u. and displacement angle between them under previous SC conditions.

After that, design impedance in the generator circuit, and impedances for transient and steady-state processes shall be determined.

$$Z_d^{"} = \sqrt{(r + r_{cab})^2 + (x_d'' + x_{cab})^2}; \tag{8.2.2-7}$$

$$Z_d' = \sqrt{(r + r_{cab})^2 + (x_d' + x_{cab})^2}. \tag{8.2.2-8}$$

Initial value of the sub-transient current I_0'', p. u., is equal to

$$I_0'' = E_0''/Z_p'' \tag{8.2.2-9}$$

Initial value of the transient current I_0', p. u., is equal to

$$I_0' = E_0'/Z_p'. \tag{8.2.2-10}$$

Then a periodic component of the SC current, p. u. is determined

$$I_t = (I_0'' - I_0') \cdot e^{(-t/T_d'')} + I_0'. \tag{8.2.2-11}$$

The value of time t in this case is directly dependent on generator frequency f, as the expression $t = 1/2f$, that is for the 50 Hz frequency the value of time is $t = 0{,}01\ s$.
Surge current of SC i_{ug}, kA, is equal to

$$i_{ug} = \sqrt{2}\,(I_t - I_0'' \cdot \gamma_a) \cdot I_b, \tag{8.2.2-12}$$

where γ_a — aperiodic component factor derived from curve $\gamma_a = f\,(x/r)$, given in the standard OST5P.6181-81 (Appendix 10), which is found as a function of the RATIO $(x_d' + x)/(r_g + r)$.

8.3 Calculation of the short-circuit current from the electrical propulsion plant.

8.3.1 Calculation of the short-circuit current from the electrical propulsion plant with synchronous PM.

The SC current from the electrical propulsion plant with synchronous PM is calculated similarly to the short-circuit current of the synchronous generator (8.2.2 of this Procedure).

Sub-transient EMF E_0'', and transient EMF E_0' for a motor running with overexcitation (with lead power factor) is determined by the same formulae as EMF of the generator working for the active and inductive load.

8.3.2 Calculation of the short-circuit current from the electrical propulsion plant with asynchronous PM.

The contribution current from asynchronous PM shall be taken into account for the first three periods of the SC current.

To calculate from rated data of the asynchronous motor, the following values shall be estimated:

P_{mr} — rated power, kW;
I_{mr} — rated current, kA;
r_{sm} — active resistance of the stator winding, p. u.;
x_m' — transient inductive resistance of the stator winding, p. u.;
x_m — inductive resistance of the stator winding, p. u.;

μ — magnetic coupling ratio of rotor and stator windings;
T_r — time constant of the rotor winding, s;
T_r' — transient time constant of the rotor winding, s.

Initial value of the SC current's periodic component is determined:

$$I_{0m}' = \frac{U_c}{Z_{pm}'} \cdot \mu, \tag{8.3.2-1}$$

where U_c — voltage across the motor feeder before SC is assumed to be equal to 1 when calculating in motor's p. u., and 0,95 when calculating in generator's p. u.

Then, the SC current's periodic component (effective value) for moment of time t is determined by the formula

$$I_{tm} = I_{0m}' \cdot e^{(-t/T_{re}')}, \tag{8.3.2-2}$$

where T_{re}' — time constant of transient process attenuation.

For SC across motor terminals $T_{re}' = T_r'$.
In case of short-circuit in the d.c. mains, resistance of the cable line from the motor to the inverter shall be taken into account:

$$T_{re}' = T_r' \cdot \frac{(x_m' + x_{cab}) \cdot (x_m + x_{cab}) + (r_{sm} + r_{cab})^2}{(x_m + x_{cab})^2 + (r_{sm} + r_{cab})^2}, \tag{8.3.2-3}$$

Values of e^{-x} are given in the standard OST5P.6181-81 (Appendix 11).
The total SC current from the motor (amplitude value) for the moment of time t may be determined by the formula

$$i_{tm\max} = \sqrt{2} \cdot \left(I_{tm} + \frac{U_c}{Z_{pm}'}\right) \cdot e^{(-t/T_{se}')}, \tag{8.3.2-4}$$

where T_{se}' — time constant of attenuation of the SC current's aperiodic component is determined by the formula

$$T_{se}' = \frac{(x_m' + x_{cab})}{(\omega \cdot (r_{sm} + r_{cab}}, \tag{8.3.2-5}$$

where ω — pulsation, $\omega = 2 \cdot \pi \cdot f$.

The surge current is determined as the total current value before moment $t = T/2$ by the formula

$$i_{surg.m} = \sqrt{2} \cdot (I_{tm} + \frac{U_c}{Z_{pm}'} \cdot \gamma_a) \cdot I_{mr}, \tag{8.3.2-6}$$

where γ_a — aperiodic component factor derived from curve $\gamma_a = f(x/r)$, given in OST 5P.6181-81 (Appendix 10), which is found as a function of the ratio $(x_m' + x_{cab})/(r_{sm} + r_{cab})$.

8.4 Calculation of the short-circuit current from ship's general power users.
8.4.1 Calculation of the short-circuit current from ship's general power users in PS with partial electrical power distribution for direct current.

In PS with partial distribution of the d.c. power, all ship's general power users are fed from a.c. main switchboard. D.c. switchboard supplies a variable-frequency electric drive: electrical propulsion plants and thruster drive.

Ship's general power users powered from the a.c. board have negligible influence on the contribution to the SC current on d.c. switchboard busbars, due to the fact that the total power of such users is considerably lower than the generator power.

The d.c. distribution network is supplied from rectifiers connected to power transformers.

The contribution current to the d.c. network is calculated for short-circuit conditions on the secondary winding of the power transformer. Calculation is done using Formulae (8.2.1-1 — 8.2.1-13).

8.4.2. Calculation of the short-circuit current from ship's general power users in PS with full electrical power distribution for direct current.

8.4.2.1 Calculation of the SC current from ship's general a.c. power users in PS with full electrical power distribution for direct current.

In PS with full distribution of the d.c. power, ship's general power users may receive power both from an a.c switchboard or directly from a.c. main switchboard. The most powerful users receive power from the a.c. main switchboard via inverters.

The current from asynchronous motors is calculated by Formulae (8.3.2-1 — 8.3.2-6), from synchronous motors — by Formulae (8.2.2-1 — 8.2.2-12).

Ship's general users of lower power are supplied from the a.c. switchboard. This switchboard is supplied from the d.c. main switchboard via the inverter and power transformer. The inverter and power transformer are reversible elements of the circuit and lead the current in reverse direction. If short-circuit occurs on d.c. main switchboard busbars, asynchronous motors connected to a.c. switchboard busbars and expressed in terms of an equivalent motor, generate the contribution current to the SC point.

Alongside that, the estimated power of the equivalent motor is much (by an order) lower than that of generators and propulsion motors. Therefore, in calculation of contribution currents on d.c. switchboard busbars, this source of contribution may be neglected.

If the equivalent motor's power is comparable to that of the EPP, the contribution current to the SC point from this source shall be taken into account. A factor limiting the SC current passage via the transformer is its power-to-size ratio. If the equivalent motor's power is lower than the transformer's power-to-size ratio, the contribution current to the SC point shall be calculated on the basis of the equivalent motor's power.

The contribution current from the equivalent asynchronous motor on busbars is calculated by the formula

$$i_{surg} = 7{,}8 \cdot I_r, \tag{8.4.2.1-1}$$

where I_r — rated current of the equivalent asynchronous motor.

From the input side of the stepdown transformer, with account of the transformation ratio, the contribution current is equal to

$$i_{surgt} = i_{surg} \cdot K_t, \tag{8.4.2.1-2}$$

where K_t — transformation ratio.

If the equivalent motor's power exceeds the transformer's power-to-size ratio, the current is calculated by the formula

$$I_t = U_1/(\sqrt{3} \cdot Z_d), \tag{8.4.2.1-3}$$

where Z_d — design resistance upstream of the SC point;

U_1 — voltage across the primary winding of the transformer.

8.4.2.2 Calculation of the SC current from ship's general d.c. power users in PS with full distribution of d.c. power.

When d.c. motors of the power comparable with that of generators are connected to the d.c. main switchboard, the contribution current to the SC point from this source of current shall be calculated.

The contribution current from d.c. motors connected directly to the d.c. switchboard is calculated as follows.

.1 Analytical calculation method for maximum short-circuit current from d.c. motors.

Analytical calculation of maximum short-circuit current from d.c. motors is calculated by expressions and in accordance with the sequence given below:

$$\alpha = \frac{0{,}44 \cdot U_{er} \cdot E_r}{p \cdot U_r \cdot F_r \cdot W_t / \alpha_p}; \qquad (8.4.2.2.1\text{-}1)$$

$$\beta = \frac{R_a \cdot I_r + K_c \cdot e_r \cdot K_\beta (P/\alpha)}{U_r} \qquad (8.4.2.2.1\text{-}2)$$

$$\gamma = \frac{F_q + b_k \cdot AS_r \pm 2(W_s/a_s) \cdot I_r}{2(W_t/a_p) \cdot I_e 0}, \qquad (8.4.2.2.1\text{-}3)$$

where α — coefficient, 1/s;
β, γ — coefficient, p. u.;
$K_c =$ 1— for machines without a compensating winding;
$K_c =$ 0,8 — for machines with a compensating winding.
U_{er} — rated voltage of an independent excitation winding at no-load and at the rated voltage, V;
E_r — rated EMF of the machine, V;
p — number of pairs of poles;
U_r — rated voltage, V;
F_r — rated effective current of the machine to pole, Wb;
W_t — number of turns of an independent (parallel) excitation winding to pole;
a_p — number of parallel paths of an independent (parallel) excitation winding;
R_a — active resistance of an armature circuit at T = 348K (75 ºC), Ohm;
I_r — rated current of an armature, A;
e_r — reactive EMF of a short-circuited section of an armature winding, V;
K_β — brush coverage ratio;
F_q — magnetizing force of a quadrature-axis armature reaction indesign conditions (to a pair of poles);
b_k — busbar of a switching zone, cm;
AS_r — rated linear load of an armature, A/cm;
W_s — number of coils of a series excitation winding to pole;
a_s — number of parallel paths of a series excitation winding;
I_{e0} — current of an independent (parallel) excitation winding at no-load and at the rated voltage, A.

In the numerator of Formula (8.4.2.2.1-3), a "minus" is put before a summand $2(W_s/a_s)$ if a motor with a back-to-back series winding is calculated, and a "plus" sign is put if a motor with a cumulative excitation winding is calculated.

Coefficients are determined:

$$C = 3{,}82 \cdot p \cdot n_r; \qquad (8.4.2.2.1\text{-}4)$$

$$A = \alpha + C \cdot (\beta + 0{,}11 \cdot \gamma); \qquad (8.4.2.2.1\text{-}5)$$

$$B = \alpha \cdot C \cdot (\beta + \gamma), \quad (8.4.2.2.1\text{-}6)$$

where A и C — coefficients, 1/s;
B — coefficient, 1/ s [2].

Attenuation decrements are determined:

$$P_a = A/2 + \sqrt{(A/2)^2 - B}; \quad (8.4.2.2.1\text{-}7)$$

$$P_b = A/2 - \sqrt{(A/2)^2 - B}. \quad (8.4.2.2.1\text{-}8)$$

Design transient i'_s and steady-state $i'_{s\,st}$ SC currents are determined:

$$i'_s = C/(P_a - P_b). \quad (8.4.2.2.1\text{-}9)$$

For machines with independent excitation, the steady-state SC current is determined by the formula

$$i'_{s\,st} = 1/(\beta + \gamma). \quad (8.4.2.2.1\text{-}10)$$

For machines with parallel excitation, the steady-state SC current is equal to zero.

The time for the SC current to reach the maximum is determined at independent excitation

$$t_m = \frac{1}{P_a - P_b} \cdot \ln \frac{P_a \cdot i'_s}{P_b(i'_s - i'_{s\,st})} = \frac{2{,}3}{P_a - P_b} \cdot \lg \frac{P_a \cdot i'_s}{P_b(i'_s - i'_{s\,st})}; \quad (8.4.2.2.1\text{-}11)$$

at parallel excitation

$$t_m = \frac{1}{P_a - P_b} \cdot \ln \frac{P_a}{P_b} = \frac{2{,}3}{P_a - P_b} \cdot \lg \frac{P_a}{P_b}. \quad (8.4.2.2.1\text{-}12)$$

Maximum design SC current at leads of the machine that has run idle before the SC moment is determined:

at independent excitation

$$i_{sm} = i_{s\,st} - i'_s e^{-P_b \cdot t_m} + (i'_s - i'_{s\,st}) e^{-P_b \cdot t_m}; \quad (8.4.2.2.1\text{-}13)$$

at parallel excitation

$$i_{sm} = i'_s (e^{-P_b \cdot t_m} - e^{-P_a \cdot t_m}), \quad (8.4.2.2.1\text{-}14)$$

where i_{sm} — maximum SC current, p. u.

Maximum SC current at motor leads that has operated under rated conditions before SC is determined by the formulae

$$I_{smm} = (i_{sm} - 1) I_r \cdot 10^{-3}, \quad (8.4.2.2.1\text{-}15)$$

where I_{kmm} — maximum SC current at motor leads, kA.

.2 Simplified analytical calculation method for maximum short-circuit current from direct-current motors.

The maximum SC current of the motor with the main parallel excitation, which has run idle before the SC moment is determined by the formula

$$i_{sm} = \frac{C}{10^{-3}} J. \tag{8.4.2.2.2-1}$$

Auxiliary value *J* is determined from design curves in Fig. 8.4.2.2.2 as function of coefficients *A* and *B*.

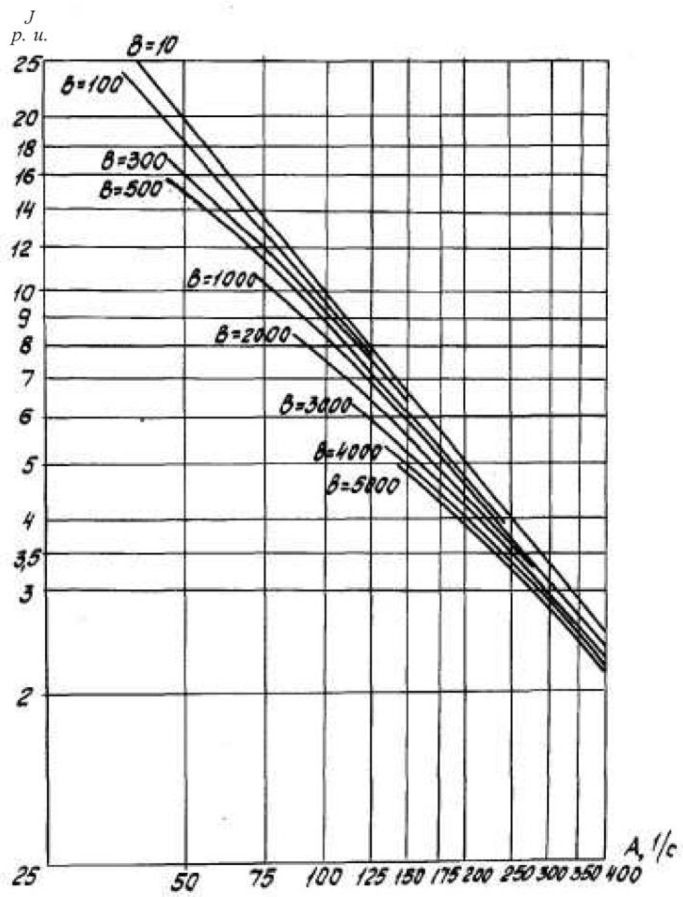


Fig. 8.4.2.2.2
Auxiliary value *J* as function of coefficients *A* and *B*

Coefficients *A*, *B* and *C* are determined by Formulae (8.4.2.2.1-4 — 8.4.2.2.1-6).

The maximum SC current of the motor in terms of named units is determined by the Formula (8.4.2.2.2-1).

In accordance with the simplified procedure of short-circuit current calculation, the maximum SC current for machines with independent excitation at their rated voltage not more than 400 — 500 V shall be determined.

The contribution current to the SC current from large-sized motors of the power comparable to that of main power supply sources shall be calculated similarly to calculation of the maximum short-circuit current by the analytical procedure described in this Chapter above.

The contribution current from motors of auxiliary mechanisms, with account of resistances of cable runs, is determined by the formula

$$I_{sam\,\max} = 5 \sum_1^n I_{am\,n}, \tag{8.4.2.2.2-2}$$

where n — number of motors running in the conditions under calculation;
$I_{am\,n}$ — rated current of the n-th motor running in design mode, kA;
$I_{am\,n}$ and n shall be taken from the load chart.

The contribution current from motors of auxiliary mechanisms is taken into account only in calculation of maximum SC currents.

8.5 Calculation of the short-circuit current from capacitor banks.

In PS with d.c. power distribution, capacitor banks may be installed at the output of rectifiers, input of inverters, or connected directly to the d.c. busbars of the main switchboard.

The connection diagram of capacitor banks in the PS d.c. mains is shown in Fig. 3.4.

In of case of SC on d.c. busbars or outgoing feeders, surge SC currents of other contribution sources are considerably influenced by discharging currents of capacitors.

Capacities of capacitors mounted at inputs of inverters and being part of autonomous inverters are significant, reaching 10 mF per 1 MW of the inverter power. If the resistance of circuit segments through which capacitor discharging currents are flowing is low, values of discharging currents may reach hundreds of kiloamperes.

Connecting plates of a charged capacitor to any resistor R will enable flowing of the capacitor's discharging current due to the voltage across the capacitor. With the capacitor discharging, electrons from one side of the plate (if they are in excess) will be flowing over to the other one (if they are in deficiency) until the potentials of plates are equalized, that is, the voltage across the capacitor becomes equal to zero.

Voltage variation during discharging of the capacitor is shown in Fig. 8.5.

The discharging current of the capacitor is proportional to the voltage across the capacitor, and its variation with the time is similar to voltage variation.

At the starting moment of discharging, the voltage across the capacitor is maximum, and the discharging current is maximum, therefore, discharging is quick. As the voltage drops, the discharging current drops as well, and charges' exchange between plates becomes slower.

The time of capacitor discharging process depends on the circuit resistance and capacitor capacity, with the growth of both resistance and capacity increasing the discharging time. As the resistance grows, the discharging current becomes lower, carryover of charges from one plate to another becomes slower. As the capacitor capacity increases, the charge on the plates increases as well.

Discharging of a capacitor having capacity C and charged to potential difference via resistance R, which is an external resistance of the discharge circuit or internal leakage resistance of the capacitor takes place according to the formula:

$$U_t = U_0 e^{-t/T}. \tag{8.5-1}$$

Instantaneous value of the discharging current

$$i_t = \frac{U_0}{R} e^{-t/T}, \tag{8.5-2}$$

where U_t — voltage between capacitor plates in seconds, after discharging has begun, V;
i_t — current in the capacitor circuit existing in t seconds after discharging has begun;
T — moment of time from the moment of charging beginning under consideration, s;
U_0 — voltage of the source that charges the capacitor, V;
C — capacitor capacity, F;
R — resistance of the discharge circuit, Ohm;
T — rc time, in s ($T = RC$);
$e = 2{,}718$.

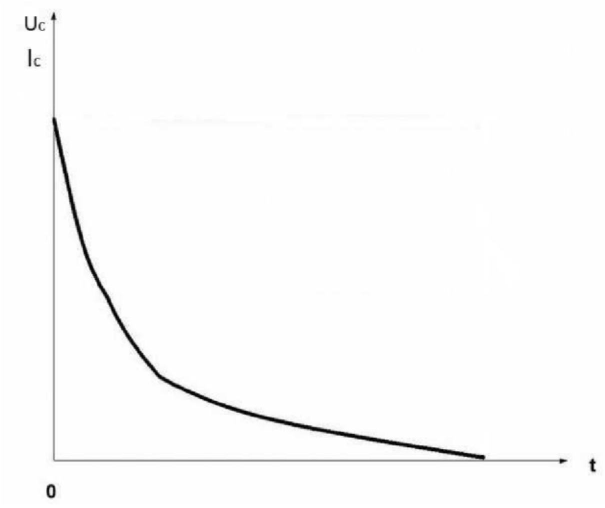


Fig. 8.5
Voltage and current curve across the capacitor during discharging

Capacitor charging and discharging processes are usually considered as a function of the circuit's r_c time *RC*. The r_c time actually indicates the time period, in s, after which the voltage of the capacitor being discharged becomes $e = 2{,}718$ times lower than the voltage under consideration.

When the capacitor is charging, the rc time indicates the time, in s, during which the voltage across plates increases by 63 % of the difference between the available voltage and the charging current source's voltage.

Since charging and discharging to full values of final voltages lasts indefinitely long, often it is more convenient to consider the charging mode finished as the voltage across plates reaches 99 % of the charging voltage (or 1 % of the initial voltage value in discharged condition).

8.6 Calculation of short-circuit currents from accumulator batteries.

In PS with distribution of the d.c. power, accumulator batteries may be used for storing the electrical power. On smaller ships they may be used for power supply of the electric propulsion system, and their power may be comparable with that of generator sets.

Calculation of the maximum short-circuit current from accumulator batteries is described below.

EMF of accumulator battery groups and internal impedance of one accumulator battery (in short circuit conditions) are determined during calculation. $E_{a.s}$ and $R_{a.s}$ are assumed from specifications.

If there are n accumulator batteries in the group, EMF ($E_{a.gr}$) and impedance ($R_{a.gr}$) of the accumulator battery group are determined by the formulae:

$$E_{a.gr} = E_{a.s} \cdot n; \quad (8.6\text{-}1)$$

$$R_{a.gr} = R_{a.s} \cdot n. \quad (8.6\text{-}2)$$

Calculation of impedance of the accumulator battery group shall consider resistances of connections between elements and contact connections.

Maximum SC current across leads of accumulator battery groups is determined by the formula

$$I_{sma.gr} = E_{a.gr}/R_{a.gr}. \quad (8.6\text{-}3)$$

Maximum SC current of the accumulator battery group for a remote SC point is determined by the formula

$$I_{sma.gr} = E_{a.gr}/(R_{a_{gr}} + R_c), \tag{8.6-4}$$

where R_c — resistance of a circuit comprising resistances of cables, equipment, and etc., from leads of the accumulator battery group to a SC point.

Resistances R_c of these elements of the design circuit are determined by the formulae:
resistances of cable runs, R_{cab}, mOhm, are determined by the formula

$$R_{cab} = 2 \cdot r_{surg} \cdot l_{cab}, \tag{8.6-5}$$

where r_{sr} — resistance of a 1 m cable run containing *m* parallel cables of S cross-section in one pole, MOhm, to be determined from Table 1 of informative Appendix 7 of standard OST5P.6126-77;
l_{cab} — length of a cable line in one pole, m;

resistance of busbars, R_b, mOhm, is determined by the formula

$$R_b = 2 \cdot r_{bsr} \cdot l_b, \tag{8.6-6}$$

where r_{bsr} — resistance of 1 m of busbars in one pole, mOhm/m, to be determined from reference Appendix 8 of standard OST5P.6126-77, depending on cross-sections of busbars;
l_b — busbar length in one pole, m.

Transient resistance of contacts, resistances of the switchgear and protection equipment and shunts are determined from Table 4 of reference Appendix 7 and reference Appendices 9-14 of OST5P.6126-77.

Determination of time dependence of the accumulator battery group's short-circuit current.

Variation of the accumulator battery group's SC current as function of the time is determined by the formula

$$I_{sa.gr} = \frac{E_{a.gr}}{R_{a.gr} + R_s}\,(1 - e^{-t/T_s}), \tag{8.6-7}$$

where T_s — the time constant of the SC circuit, which is found by the formula

$$T_s = \frac{L_{a.gr} + L_s}{R_{a.gr} + R_s}, \tag{8.6-8}$$

where $L_{a.gr}$ — inductance of the accumulator battery group, H;
L_s — inductance of the SC circuit from accumulator battery group leads to the SC point, H;
$R_{a.gr}$ — resistance of the accumulator battery group, mOhm;
R_s — resistance of the SC circuit from accumulator battery group leads to the SC point, mOhm;

Specific inductance of cable runs with limited number of cables (from two to twenty) and arranged in a cassette, as is shown in Fig. 8.6-1, is determined from the curves in Fig. 8.6-2 — 8.6-4.

When cables of other cross-sections and grades are used, the specific inductance for cable runs with the number of cables from 2 to 20 is calculated following the analytical procedure, by the formulae:

$$L'_2 = (1 - 4\ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}9)$$

$$L'_4 = (-0{,}193 - 2\ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}10)$$

$$L'_6 = (-0{,}183 - 1{,}32\ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}11)$$

$$L''_8 = (-0{,}184 - \ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}12)$$

$$L'_{10} = (-0{,}16 - 0{,}8\ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}13)$$

$$L'_{12} = (-0{,}135 - 0{,}66\ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}14)$$

$$L'_{16} = (-0{,}124 - 0{,}5\ln\frac{r}{d})10^{-7};\qquad(8.6\text{-}15)$$

$$L'_{20} = (-0{,}103 - 0{,}4\ln\frac{r}{d})10^{-7},\qquad(8.6\text{-}16)$$

where $L'_2 - L'_{20}$ — specific inductance of cable runs, H/m;
r — radius of a cable conductor, mm;
d — centre-to-centre spacing between adjacent cables, mm,

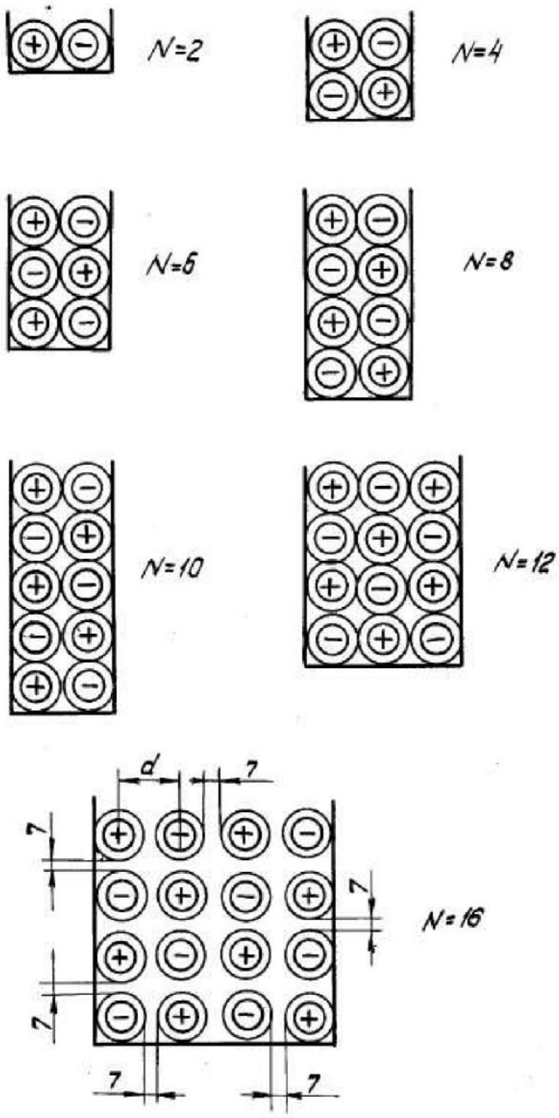


Fig. 8.6-1
Cable runs for the number of cables in a cassette from 2 to 16

When cables are laid in a cassette without vents, d — diameter of an insulated cable, mm.
Inductance of the cable run of l length is determined by the formula

$$L'_{\mathrm{c}} = L' \cdot l; \tag{8.6-17}$$

The actual value of the SC current for accumulator batteries as power sources is assumed to be equal to the maximum SC current value.

8.7 Calculation of the total short-circuit current.

After the current contributing to SC points from sources is calculated, the resultant current at each selected point shall be determined.

The sources contributing to short-circuit points that have been reviewed above, have different characteristics, different active and inductive resistances and time constants.

The build-up time of the surge SC current from electrical machines, capacitors and accumulator batteries differs. It should be noted that capacitor banks, if there is no inductance in the discharging current, provide the maximum discharging current (assumed to be the surge current from discharging of capacitor batteries) at the moment of time, approaching zero ($t = 0$). If inductance is present, the moment when the maximum surge current occurs is shifted to the right on the time scale.

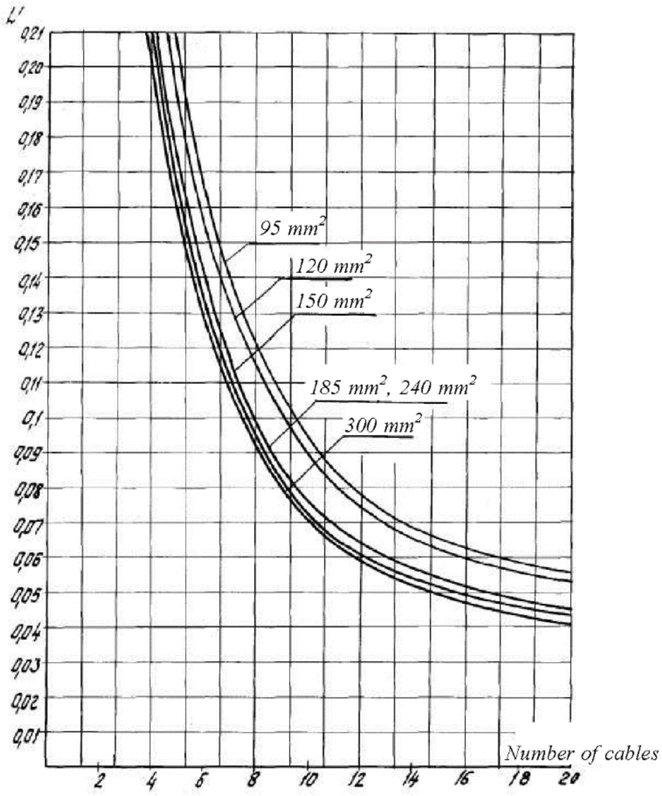


Fig. 8.6-2
Curves to determine the specific inductance of the cable run as function of the number of cables and cross-section of a conductor of cable of type "SHP", H/m • 10^{-6}

The discharging current of accumulator batteries depends only on the internal resistance and discharge circuit's resistance. The maximum value is reached at the moment of time, approaching zero ($t = 0$).

Electrical machines represented by generators and motors generate the surge current at the moment of time t other than zero. The value of time t in this case is directly dependent on generator frequency f, as the expression $t = 1/2f$, that is for the 50 Hz frequency the value of time is $t = 0{,}01\ s$.

For the d.c. distribution circuits under consideration, the generator's operating frequency may be other than 50 Hz. Propulsion motors and thruster motors at the moment of short-circuit occurrence may operate at a random frequency determined by the control law of a variable-frequency drive. Equivalent asynchronous motors run at the rated frequency (50 Hz).

To determine the maximum surge current at a SC point, the maximum sum of currents from sources contributing to a SC point at a random moment of time shall be determined.

To determine the maximum surge SC current, contribution sources shall be divided into two groups:

sources that provide the maximum surge current at the moment of time $t = 0\ s$;

sources that provide the maximum surge current at the moment of time other than $t = 0\ s$;

The first group of sources may include capacitor banks and accumulator batteries, the second group — all generators and motors.

The surge current from capacitor banks and accumulator batteries at the moment of time approaching zero ($t_0 = 0\,s$) will be equal to the sum of currents from all batteries to a SC point:

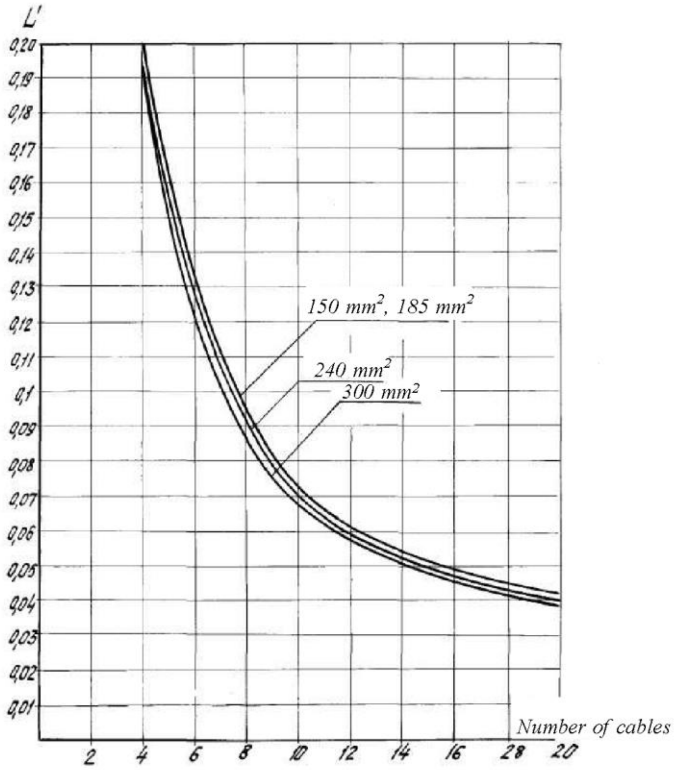


Fig. 8.6-3
Curves to determine the specific inductance of the cable run as function of the number of cables and cross-section of a conductor of cable of type "НРШМ", H/m • 10^–6

$$I_{udb_{t0}} = I_{c1} + I_{c2} + \ldots I_{cn} + I_{\mathrm{ac}}. \tag{8.7-1}$$

The surge currents from capacitor banks and accumulator batteries at the moment of time $t_1 = 1/2f$ are summed again, using the expressions in 8.5 and 8.6.

$$I_{udb_{t1}} = I_{c1_{t1}} + I_{c2_{t1}} + \ldots I_{cn_{t1}} + I_{\mathrm{as}_{t1}}, \tag{8.7-2}$$

where $t_1 = 1/2f$;
f — generator frequency, Hz.

Surge currents from generators and motors at the moment of time $t = 1/2f$, are summed to give the sum of currents from all electrical machines to a SC current.

$$I_{\mathrm{udem}_{t1}} = I_{g1} + I_{g2} + \cdots I_{gn} + I_{m1} + I_{m2} + \cdots I_{mn}, \tag{8.7-3}$$

where $t_1 = 1/2f$;
f — frequency, Hz.

The total surge current from capacitor banks and accumulator batteries as calculated by Formula (8.7.2), and from generators and motors at the moment of time t=1/2*i*, as calculated by Formula (8.7.3) are summed:

$$I_{ud_{t1}} = I_{udb_{t1}} + I_{udem_{t1}} \tag{8.7-4}$$

From the resulting values of the surge SC current from capacitor banks and accumulator batteries at the moment of time approaching zero $I_{udemb_{t0}}$, as calculated by Formula (8.7-1), and the total surge current from capacitor banks and accumulator batteries and from generators and motors at the moment of time $t = 1/2f I_{ud_{t1}}$, as calculated by Formula (8.7-4), the highest value is selected.

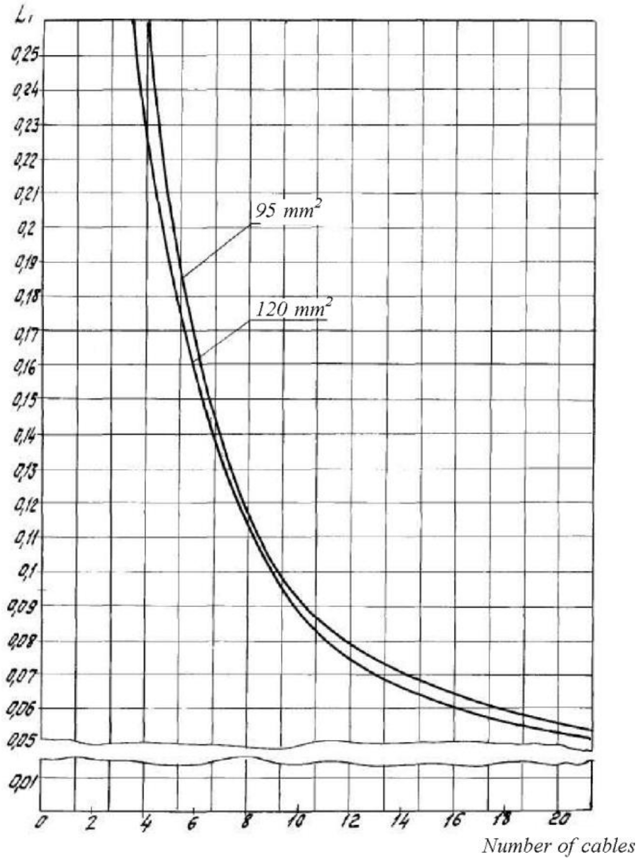


Fig. 8.6-4
Curves to determine the specific inductance of the cable run as function of the number of cables and cross-section of a conductor of cable of types "SBM-60", "SBM-100" and "SPHG-60", H/m • 10^{-6}

The maximum value of the design SC current is used in the check of the switchgear and protection equipment and busbars for electrodynamic resistance.

9 TERMS AND DEFINITIONS

Electric plant is a set of the electrical equipment connected to each other that fulfils a certain function, for example, generation, conversion, transmission, distribution, storage or consumption of electrical power.

Electrical equipment is a set of electrical products used for generation, conversion, transmission, distribution, storage or consumption of electrical power.

Short-circuit is a connection between phases or between phases and ground as a result of damaged phase insulation, which is abnormal for normal operation conditions of a system.

Short-circuit current is the current flowing in a system in short-circuit conditions.

Electrodynamic resistance to the short-circuit current is the ability of electric plants to withstand the action of the surge short-circuit current.

Thermal resistance to the short-circuit current is the ability of electric plants to withstand the heat action of the surge short-circuit current for a certain period of time in set operation conditions.

Initial short-circuit current is a periodic component of the short-circuit current at the moment of short-circuit occurrence is specified as an actual (effective) value.

Steady-state short-circuit current is the current that flows after a transient process caused by short-circuit is finished. To be specified as an actual (effective) value.

Rated short-circuit current is a surge short-circuit current, the dynamic action of which shall be withdrawn by an electric plant without any damages impairing its serviceability

Synchronous machine is a commutatorless a.c. machine, where, in steady-state mode, the ratio of the rotor speed and current frequency in the circuit connected to the armature winding does not depend on the load within the range of permissible loads.

Asynchronous machine is a commutatorless a.c. machine, where the ratio of the rotor speed and current frequency in the circuit connected to the machine depends on loads.

Valve-type a.c. machine is a commutatorless a.c. machine, the armature winding of which is connected to external circuits via a valve-type is a switching device and where the ratio of the rotor speed and current frequency in the circuit connected to the machine depends on the load and may be changed by changing the phase position of control pulses fed to valves.

Zero-phase-sequence impedance of a synchronous (asynchronous) machine (Zero-phase-sequence impedance) is a ratio of the fundamental harmonic of zero-phase-sequence voltage in the armature winding (primary winding) of a synchronous (asynchronous) machine to the zero-phase-sequence current of the same frequency in the same winding.

Synchronous inductive resistance along the longitudinal axis of a synchronous machine (Synchronous inductive resistance along the longitudinal axis) is a ratio of the steady-state value of the EMF's fundamental harmonic, which is induced in the armature winding of a synchronous machine as a total magnetic flux caused by a current component in this winding along the longitudinal axis, to this current component at a synchronous speed

Synchronous inductive resistance along a transverse axis of a synchronous machine (Synchronous inductive resistance along a transverse axis) is a ratio of the steady-state value of the EMF's fundamental harmonic, which is induced in the armature winding of a synchronous machine as a total magnetic flux caused by a current component in this winding along a transverse axis, to this current component at a synchronous speed.

Transient inductive resistance of the armature winding along the longitudinal axis of a synchronous machine (Transient inductive resistance along the longitudinal axis) is a ratio of the initial value of the EMF's fundamental harmonic, which is induced in the armature winding of a synchronous machine as a total magnetic flux caused by a current component in this winding along the longitudinal axis, to the initial value of this current component at its sudden change, in absence of damping circuits, in the presence of a closed excitation winding along the longitudinal axis, and at a synchronous speed

Transient inductive resistance of the armature winding along a transverse axis of a synchronous machine (Transient inductive resistance along a transverse axis) is a ratio of the initial value of the EMF's fundamental harmonic, which is induced in the armature winding of a synchronous machine by total magnetic flux caused by a current component in this winding along the transverse axis, to the initial value of this current component at its sudden change, in absence of circuits, in the presence of a closed excitation winding along the transverse axis, and at a synchronous speed

Sub-transient inductive resistance of the armature winding along the longitudinal axis of a synchronous machine (Sub-transient inductive resistance along the longitudinal axis) is a ratio of the initial value of the EMF's fundamental harmonic, which is induced in the armature winding of a synchronous machine by total magnetic flux caused by a current component in this winding along the longitudinal axis, to the initial value of this current component at its sudden change, in the presence of damping circuits along the longitudinal axis, and at a synchronous speed

Sub-transient inductive resistance of the armature winding along the transverse axis of a synchronous machine (Sub-transient inductive resistance along the transverse axis) is a ratio of the initial value of the EMF's fundamental harmonic, which is induced in the armature winding of a synchronous machine by total magnetic flux caused by a current component in this winding along the transverse axis, to the initial value of this current component at its sudden change, in the presence of damping circuits along the transverse axis, and at a synchronous speed

Positive-phase-sequence active resistance of the armature winding of a synchronous machine (Positive-phase-sequence active resistance) is a ratio of a part of the in-phase component of the voltage's fundamental harmonic in the synchronous machine's armature winding, which corresponds to fundamental and incremental losses in this winding caused by the fundamental harmonic of the positive-phase-sequence current therein, to the same current harmonic at the rated speed.

Negative phase-sequence active resistance of the armature winding of a synchronous machine (Negative phase-sequence active resistance) is a ratio of the in-phase component of the fundamental harmonic of the negative phase-sequence armature voltage caused by the armature's sinusoidal current of the negative phase-sequence and rated frequency, to the same current at the rated speed of a synchronous machine.

Zero-phase-sequence inductive resistance of a synchronous (asynchronous) machine (Zero-phase-sequence inductive resistance) is a ratio of the fundamental harmonic's idle component of zero-phase-sequence voltage in the armature winding (primary winding) to the zero-phase-sequence current of the same frequency in the winding of a synchronous (asynchronous) machine.

Zero phase-sequence active resistance of the armature winding of a synchronous machine (Zero-phase-sequence active resistance) is a ratio of the fundamental harmonic's in-phase component of the zero-phase-sequence armature voltage of a synchronous machine caused by the fundamental harmonic of the zero-phase-sequence armature current and rated frequency, to the same current harmonic at the rated speed of a synchronous machine.

Steady-state short-circuit current of a synchronous generator (Steady-state short-circuit current) is the current that has settled upon short-circuit in the armature winding of an excited synchronous generator rotating at a synchronous speed.

Surge short-circuit current of a synchronous machine (Surge short-circuit current) is the maximum value of the current in the armature winding of a synchronous machine within the first half-cycle after its short-circuit, when the aperiodic component is maximum.

Aperiodic component of the short-circuit current of a synchronous machine (Aperiodic component of the short-circuit current) is a component of the short-circuit current in the synchronous machine's armature winding, which is caused by the presence of winding inductances.

Transient short-circuit current of a synchronous machine (Transient short-circuit current) is a periodic short-circuit current of the synchronous machine's armature winding, which is equal to the sum of its steady-state value and transient component caused by reaction of an excitation winding.

Sub-transient short-circuit current of a synchronous machine (Sub-transient short-circuit current) is a periodic short-circuit current of the synchronous machine's armature winding, which is equal to the sum of the transient current and a sub-transient component caused by the reaction of damping circuits.

Time constant of the aperiodic component of a synchronous machine (Time constant of the aperiodic component) is an electromagnetic time constant determined by an arithmetical average of parameters of the synchronous machine's armature winding along the longitudinal and transverse axes of its magnet system, accounting for reactions of other windings.

Transient time constant of a synchronous machine along a longitudinal axis with a short-circuited armature winding is an electromagnetic time constant determined by excitation winding parameters, with account of reaction of the synchronous machine's armature winding along the longitudinal axis.

Transient time constant of a synchronous machine along the transverse axis with a short-circuited armature winding is an electromagnetic time constant determined by excitation winding parameters along the transverse axis (if any), accounting for reaction of the synchronous machine's armature winding along the transverse axis

Transient time constant a synchronous machine along the longitudinal axis with an open-circuit armature winding is an electromagnetic time constant determined by excitation winding parameters of a synchronous machine along the longitudinal axis.

Transient time constant of a synchronous machine along the transverse axis with an open-circuit armature winding is an electromagnetic time constant determined by excitation winding parameters of a synchronous machine along the transverse axis.

Sub-transient time constant of a synchronous machine along the longitudinal axis with a short-circuited armature winding is an electromagnetic time constant determined by damping circuits parameters along the longitudinal axis, with account of reaction of the synchronous machine's armature winding and excitation winding.

Sub-transient time constant of a synchronous machine along the transverse axis with a short-circuited armature winding is an electromagnetic time constant determined by damping circuits parameters along the transverse axis, accounting for the reaction of the armature winding and excitation winding along the transverse axis of a synchronous machine.

24 SPECIAL REQUIREMENTS FOR VALVE-TYPE GENERATOR SETS

24.1 GENERAL

24.1.1 Unless otherwise specified in this Section, drive movers of valve-type generator sets shall comply with the requirements of Part IX "Machinery", generators and semiconductor converters — with the requirements of this Part and control system – with Part XV "Automation".

The manufacturer shall take into consideration the nature of physical processes in the equipment being part of valve-type generator sets and shall ensure its compatibility and system integration.

24.1.2 Alternating and direct current valve-type generator sets may be used as the main electrical power source. As an emergency electrical power source, the valve-type generator sets may be used only in the ship electric power system with electrical power distribution for direct current.

24.1.3 In addition to the list given in 1.4.2, prior to survey of electrical equipment during the manufacture, the calculations shall be submitted to the Register for consideration to confirm the absence of mechanical resonance across the operating speed variation range of the valve-type generator set from the minimum to the maximum values, or else the near resonance frequencies shall be excluded from the rotational speed control law.

24.2 DEFINITIONS AND EXPLANATIONS

24.2.1 The following definitions and explanations have been adopted in this Section.

Valve-type generator means an equipment system consisting of rotating electric engine, semiconductor converter and control system intended for generation of electrical power as part of the ship electric power system.

Alternating current valve-type generator means the valve-type generator consisting of a rotating electric engine, semiconductor converter (or inverter) and control system intended for generation of alternating electrical power.

Direct current valve-type generator means the valve-type generator consisting of a rotating electric engine, semiconductor converter (or inverter) and control system intended for generation of direct current electrical power.

Valve-type generator set means a unit consisting of the valve-type generator and prime (drive) heat mover.

Voltage regulator of semiconductor converter means a device being a part of the semiconductor converter of the alternating or direct current valve-type generator set intended for voltage control.

Voltage frequency regulator of semiconductor converter means a device being a part of the semiconductor converter of the alternating current valve-type generator set intended for output voltage frequency control.

24.3 DRIVE (PRIME) MOVERS

24.3.1 Internal combustion engine, steam turbine, gas-turbine engine or other source of mechanical energy, accepted for application on board the ships by these Rules, may be used as a prime mover in the valve-type generator set.

24.4 GENERATORS

24.4.1 Synchronous generator with electromagnetic excitation, synchronous generator with permanent magnets, asynchronous generator, direct current commutator-type generator or other type of electric machines, accepted for application on board the ships by these Rules, may be used as an electrical generator in the valve-type generator set.

24.4.2 A generator being a part of the valve-type generator set shall be calculated for the estimated level of higher harmonic components induced by operation for the semiconductor converter. When calculating the rated power of the generator of the valve-type generator set, the sufficient output reserve shall be provided to prevent the generator temperature rise, compared with sinusoidal load.

24.4.3 As regards the valve-type generator set based on the synchronous generators with permanent magnets not capable of field suppression the measures shall be provided for rapid deceleration of the generator shaft in case of inner short circuits in the generator or semiconductor converter, or other additional measures for field suppression or emergency localization shall be provided.

24.5 SEMICONDUCTOR CONVERTERS

24.5.1 Semiconductor rectifiers, inverters, frequency converters, d.c. converters may be used as a semiconductor converter in the valve-type generator set.

24.5.2 Where necessary, the valve-type generator set shall contain the required devices (noise limiters) limiting the distortion level of the generating voltage curve to ensure compliance with the requirements of 2.2.1.3.

24.5.3 When a mains-controlled semiconductor converter is used in the alternating current valve-type generator set, the measures shall be provided for ensuring its reactive power necessary for commutation of the rectifiers, for example, by means of installation of a synchronous compensator.

24.5.4 Direct current valve-type generator set intended for operation as a part of the ship electric power system with electrical power distribution for direct current shall also comply with the requirements of Section 23.

24.6 COOLING AND LUBRICATING SYSTEMS

24.6.1 For calculating the cooling and lubricating systems of drive movers and generators of the valve-type generator set, decrease of cooling medium and lubricant feed from the appurtenant machinery at the reduction of rotation speed as compared with the rated one shall be considered.

24.7 VOLTAGE REGULATION

24.7.1 The valve-type generator set shall contain a generator voltage regulator and/or semiconductor converter voltage regulator.
24.7.2 On changing of the prime mover rotation speed in accordance with the accepted algorithms, the generator voltage regulator and/or semiconductor converter voltage regulator shall ensure the regulation performance of the output voltage of the valve-type generator set complying the requirements of 10.6 and 10.7.

24.8 SPEED REGULATION

24.8.1 Drive mover of the valve-type generator set shall be fitted with speed limiter. The requirements for the speed limiter of the prime mover shall be specified by the manufacturer of the valve-type generator set based on the accepted algorithms of speed regulation.

24.9 VOLTAGE FREQUENCY REGULATION

24.9.1 Semiconductor frequency converter being a part of the alternating current valve-type generator set shall be fitted with a frequency regulator that shall ensure regulation performance of the output frequency of the valve-type generator set in compliance with the requirements of 2.11.3, Part IX "Machinery".

24.10 PROTECTIVE DEVICES

24.10.1 For valve-type generator set, at least the following protective devices shall be provided.

For generator:

from overloads;

from short circuits;

from inner short circuits for generators with the power output of 1000 kVA.

For semiconductor converter:

from minimum input voltage;

from maximum input voltage;

from maximum voltage in direct current link (if present);

from power modules overheating;

from overloads;

from inner short circuits;

from an output short circuit.

24.10.2 Valve-type generator sets shall withstand short circuits at the switchboard busbars undamaged. At the short circuit in the ship power mains the valve-type generator (synchronous condenser) shall ensure the short circuit current value sufficient for the activation of protective devices, or else other technical measures ensuring the activation of such devices shall be provided.

24.11 OVERLOAD

24.11.1 All power elements of a valve-type generator set, including generators and semiconductor converters, shall have the overload capacity complying with the requirements of 10.5.

24.12 SYNCHRONIZATION

24.12.1 Alternating and direct current valve-type generator sets shall be capable of synchronizing and continuously operating in parallel with other generator sets, including those of valve type.

24.12.2 Synchronization of a valve-type generator set shall be ensured by the impact on the voltage regulator of the generator and/or semiconductor converter, and in case of an alternating current valve-type generator set — also by the impact on the voltage frequency regulator of the semiconductor converter.

24.13 POWER DISTRIBUTION WHEN OPERATING IN PARALLEL

24.13.1 When a valve-type generator set operates in parallel with another generator set, including that of a valve type, distribution of active power not in proportion with the rated power output of prime movers is permitted, provided the required ship power mains voltage is ensured, at gradual or abrupt load change and/or variation in the rotational speed of the prime mover.

24.13.2 When a valve-type generator set operates in parallel with another generator set, including that of a valve type, distribution of reactive power not in proportion with the rated power output of prime movers is permitted, provided the required ship power mains voltage is ensured, at gradual or abrupt load change and/or variation in the rotational speed of the prime mover.

24.14 CONNECTION DIAGRAMS AND OPERATION MODES

24.14.1 Bypass circuit connection.

24.14.1.1 Alternating current valve-type generator set with electromagnetic excitation may have a bypass circuit allowing to connect the generator to the switchboard directly, not via a semiconductor converter. In case of bypass circuit connection, the generator set shall operate at a constant rotational speed across the load variation range and comply with the requirements of this Part for power sources operating at a constant speed.

24.14.1.2 Maintaining the constant ship power mains voltage frequency while operating via a bypass circuit is ensured by means of a prime mover speed regulator, maintaining voltage — by means of a generator voltage regulator.

24.14.1.3 Transfer from bypass circuit to semiconductor converter operation (and vice versa) shall be performed while maintaining the connection of the generator set to the switchboard. Disconnection is permitted, provided no overload of other power sources operating at the switchboard busbars is caused.

24.14.2 Motor operation mode.

24.14.2.1 Valve-type generator may operate in the motor mode, if such operation mode is provided for the semiconductor converter, generator and other elements.

24.14.2.2 Motor operation mode is possible for shaft generators either autonomously or together with the main engine for the propeller if fed from other ship power sources.

24.14.2.3 A generator may be used in motor operation mode for the starting of the prime mover of the valve-type generator set using power generated by other mains power sources and then switching into the generator mode. When starting, the parameters of power supply in the ship mains shall comply with the requirements of 2.1.3. In this case, a compressed starting air system or another main starting method shall be invariably provided for the valve-type generator set.

24.15 MEASUREMENT INSTRUMENTS

24.15.1 For each alternating current valve-type generator the following measurement instruments shall be installed at the switchboard:

.1 an ammeter with a selector switch for generator current measurement in each phase;

.2 an ammeter with a selector switch for converter output current measurement in each phase;

.3 a voltmeter with a selector switch for measurement of generator line voltages;

.4 a voltmeter with a selector switch for measurement of line voltages at the converter output;

.5 a frequency indicator at the generator output;

.6 a frequency indicator at the converter output;

.7 a wattmeter at the generator output;

.8 a wattmeter at the converter output;

.9 a tach-generator.

24.15.2 For each direct current valve-type generator (with an alternating current generator and a semiconductor rectifier) the following measurement instruments shall be installed at the switchboard:

.1 an ammeter with a selector switch for generator current measurement in each phase;

.2 an ammeter with a selector switch for converter output current measurement in each phase;

.3 a voltmeter with a selector switch for measurement of generator line voltages;

.4 a voltmeter for measurement of direct current voltages at the converter output;

.5 a frequency indicator at the generator output;

.6 a wattmeter at the generator output;

.7 a wattmeter at the converter output;

.8 a tach-generator.

The requirements of this Section apply to the ships contracted for construction or conversion on or after 1 July 2020.

25 SPECIAL REQUIREMENTS FOR COMPOSITE (HYBRID) PROPULSIVE SYSTEMS

25.1 DEFINITIONS AND EXPLANATIONS

25.1.1 For the purpose of this Part, the following definitions and explanations have been adopted.

Composite (hybrid) propulsive system (CPS) means a propulsive system where the power for ship's motion is generated in two or more different ship's engines (heat and electric) mechanically linked and driving a common propeller.

25.2 GENERAL

25.2.1 The requirements of this Section apply to composite (hybrid) propulsive systems that comprise main heat engine and electric propulsion motor mechanically linked and driving a common propeller.

25.2.2 Unless otherwise specified in this Section, heat main engines shall comply with the requirements of Part IX "Machinery", electric machines — with the requirements of this Part, control systems — with the requirements of Part XV "Automation" and CPS as a whole — with the requirements of Part VII "Machinery installations".

25.2.3 Requirements of Section 17 do not apply to electric propulsion plants driven by CPS if heat main engine is capable of ensuring ship's motion without overload with the speed sufficient for manoeuvrability and safety of navigation. In other cases, electric propulsion plants driven by CPS shall comply with all applicable requirements specified in Section 17.

25.2.4 If electric propulsion plant comprises a semiconductor converter, it shall comply with the requirements of Section 12.

25.2.5 If electric propulsion plant comprises semiconductor converter and propulsion motor capable of operating in generator operation mode, this electric propulsion plant shall additionally comply with the requirements specified in Section 24.

25.2.6 Firm (manufacturer) or firm responsible for overall operation of CPS shall take into account the nature of physical processes in the equipment being part of CPS and shall ensure its compatibility and system integration.

25.3 STRUCTURE

25.3.1 The configuration and structure of CPS and electric propulsion plant are determined by provided functions and operation modes taking into account the requirements of 25.2.3.

25.3.2 The electric propulsion plant shall have electromagnetic compatibility with ship's power plant system and consumers. This may be provided by installing an impedance matching transformer or a noise filter.

25.4 ELECTRIC PROPULSION MOTORS

25.4.1 Electric propulsion motor design is determined by provided functions and operation modes taking into account the requirements of 25.2.3.

25.4.2 The electric propulsion motor shall be capable to withstand overload in torque without damage that occurs when the heat main engine is suddenly disconnected in joint operation mode of heat main engine and propulsion motor driving a common propeller.

25.4.3 For electric propulsion d.c. motors provision shall be made for an independent overspeed (runaway) protection device as required in 2.11, Part IX "Machinery". The electric propulsion motor shall be capable to withstand overspeed up to the trip setting value of overspeed protection device.

25.4.4 The electric propulsion motor shall be capable to withstand a sudden short-circuit currents at its terminals under nominal load without damage.

25.4.5 Propulsion motor capable of running in generator mode shall additionally:

be designed for currents and speeds of motor and generator operation modes considering possible overloads and overspeed;

comply with the requirements of 3.2.3.

25.5 SEMICONDUCTOR CONVERTERS

25.5.1 If the electric propulsion plant comprises semiconductor converters, they shall be capable to withstand over-current without damage that occur when the heat main engine is suddenly disconnected in joint mode of heat main engine and propulsion motor driving the propeller.

25.6 VOLTAGE REGULATION

25.6.1 Automatic voltage regulation systems in propulsion motor generator operation mode with a semiconductor converter shall comply with the requirements of 24.7.
25.6.2 Automatic voltage regulation systems in propulsion motor generator operation mode without a semiconductor converter shall comply with the applicable requirements of 3.2.3.

25.7 VOLTAGE FREQUENCY REGULATION

25.7.1 Automatic voltage frequency regulation systems in propulsion motor generator operation mode with a semiconductor converter shall comply with the requirements of 24.9.
25.7.2 Automatic voltage frequency regulation systems in propulsion motor generator operation mode without a semiconductor converter shall comply with the applicable requirements of 3.2.3.

25.8 PROTECTION

25.8.1 Automatic limitation of power consumed by the propulsion motor from ship's electric power plant shall be provided to avoid generator overload.

25.8.2 Excitation systems and automatic control systems shall protect electric propulsion motors from overspeeding in the event of the propeller breaking down or working clear of water.

25.8.3 If power recuperation into the ship mains is provided at braking, this recuperation shall not activate overspeed and reverse power protection and disconnect ship's electric power plant generators.

25.8.4 For electric propulsion motors, at least the following protective devices shall be provided:

from overloads;

from short circuits;

from inner short circuits for motors with the power output of 1000 kW and more.

25.8.5 For semiconductor converter (if any), at least the following protective devices shall be provided:

from minimum input voltage;

from maximum input voltage;

from maximum voltage in direct current link (if present);

from power modules overheating;

from overloads;

from inner short circuits.

25.8.6 For electric propulsion plant with propulsion motor capable of running in generator operation mode and with semiconductor converter, additional protective devices as specified in 24.10 shall be provided.

25.9 CONTROL STATIONS

25.9.1 CPS control stations shall comply with the requirements of Section 3, Part VII "Machinery Installations".

25.9.2 Local control stations of heat main engine and propulsion motor shall (if possible) be positioned in close proximity to each other.

25.9.3 Operating controls of main engine and propulsion motor on the remote control stations of CPS shall be positioned in close proximity to each other and the possibility of simultaneous control by one person shall be provided.

25.9.4 Each control station shall be equipped with an engine emergency shutdown device.

25.9.5 Control stations shall be provided with necessary light alarm and indication showing currently operating engines, their applied operation modes and parameter values.

25.10 OPERATION MODES

25.10.1 Motor operation mode of propulsion motor and heat main engine.

25.10.1.1 In CPS different motor operation modes including autonomous or joint mode of main engine and propulsion motor driving a common propeller are available. The switch from one mode to another shall not result in loss of power or steering of the ship.

25.10.1.2 CPS shall provide acceleration, speed regulation, braking and reversing of the ship.

25.10.1.3 To use motor operation modes, CPS shall be provided with the relevant algorithms of automatic control and (if necessary) mechanical devices (transmission, controlled couplings, etc.).

25.10.1.4 In set modes disproportional distribution of mechanical stress between heat main engine and propulsion motor is permitted if neither of motors is overloaded and the requirements of 2.1.11, Part VII "Machinery Installations" are met.

25.10.1.5 In transient modes including acceleration and braking, distribution of mechanical stress between heat main engine and propulsion motor shall be carried out in such a way that no motor and engine overloads occur.

25.10.1.6 Reversing the ship at CPS operation shall be carried out in such a way that the requirements of 2.1.3 — 2.1.5, Part VII "Machinery Installations" are met.

25.10.2 Propulsion motor generator operation mode

25.10.2.1 When propulsion motor is in generator operation mode, the requirements of 3.2.3 shall be met.

25.10.2.2 When propulsion motor is in generator operation mode, disconnection of propeller via controlled coupling or another similar device (if provided by the design) is permitted. In this case the heat main engine is covered by the requirements for generator prime movers including those of 2.11.3, Part IX "Machinery".

25.10.2.3 If electrical propulsion plant comprises a semiconductor converter, in propulsion motor generator operation mode, the requirements of Section 24 shall be met.

25.10.2.4 Switch of propulsion motor from motor to generator operation mode and vice versa shall not result in blackout of ship's electric power plant, loss of power and steering of the ship.

25.10.3 Electric starting of heat main engine and propulsion motor.

25.10.3.1 Electric starting of heat main engine by electric propulsion motor is permitted. To use this mode in CPS, relevant algorithms of automatic control and mechanical devices (controlled couplings, etc.) shall be provided.

25.10.3.2 Electric starting of heat main engine by propulsion motor shall not result in overload of ship's electric power plant.

26 SPECIAL REQUIREMENTS FOR STATIC SOURCES OF ELECTRICAL POWER

26.1 DEFINITIONS, ABBREVIATIONS AND EXPLANATIONS

26.1.1 For the purpose of this section the following definitions, abbreviations and explanations have been adopted.

Auxiliary source of electrical power is a source of electrical power intended for provision of output reserve of shipboard electrical power system.

Static source of electrical power (SPS) is a source of electrical power with no moving parts intended for production and storage of electrical power being a part of ship power system and used as main, emergency, emergency transient or auxiliary power source.

Valve-type static source of electrical power is a static source of electrical power consisting of a semiconductor converter for implementation of its functions and regulation (maintenance) of output power parameters.

Lithium-ion battery (LIB) is a static source of electrical power consisting of one or more lithium-ion batteries connected with each other and used as a power source.

Lithium-ion battery system (LIBS) is a static source of electrical power consisting of one or more lithium-ion batteries with charging-discharging units, control, management, protection and alarm system connected with each other and used as a power source.

Supercapacitor (SC) is a static source of electrical power that is charged and stores energy by forming of electrical field in the double electrical layer at the interface between n-type conductor and ionic conductivity conductor (electrolyte).

Supercapacitor system (SCS) is a static source of electrical power consisting of two or more supercapacitors, with charging-discharging units, control, management, protection and alarm system connected with each other and used as a power source.

Fuel cell (FC) is a static source of electrical power that is an electrochemical device in which the chemical energy of a fuel and oxidizing agent is converted into electrical (direct current) energy, thermal energy and other chemical reaction products.

Solar-cell (photovoltaic) array (SA) is a static source of electrical power that is a device, comprised of electrically connected photovoltaic modules, circuits or groups, generating flow of direct current initiated from electromagnetic radiation and comprising all components enabling electrical and mechanical connections both in the battery and with external devices and structures.

26.2 GENERAL

26.2.1 The requirements of this Section apply to static sources of electrical power (SPS) and their components:

Li-Ion battery systems (LIBS);

supercapacitor systems (SCS);

fuel cells (FC);

solar arrays (SA).

26.2.2 In respect of all the parameters not specified in this Section, SPS shall meet the requirements of this Part and Part XV "Automation".

26.3 MODES OF OPERATION

26.3.1 In accordance with 3.1.1, Li-Ion battery systems (LIBS) may be used as main power source on board the ships. LIBS may be used as an emergency and emergency transient power source. LIBS, SCS, FC and SA may be used as an auxiliary power source.

26.3.2 Where LIBS is a main power source, at least two LIBS shall be provided that shall be arranged in separate spaces and shall meet the requirements of 3.1.6.

26.4 CHARGING AND DISCHARGING MODES

26.4.1 Static source of electrical power (SPS) shall be so designed that the temperature build-up shall not exceed the specified maximum value. SPS shall be operated within the limits of voltage, current and temperature rated by the manufacturer. Technical documentation containing the requirements to charging modes shall be provided for SPS; the appropriate charging units shall be designed to maintain the charging mode within the specified limits of voltage, current and temperature.

26.4.2 Charging-discharging units shall be so designed that voltage, current rate and temperature during charging and discharging shall be maintained within the limits specified by the manufacturer.

26.4.3 Charging-discharging units shall be controlled by a local control, management, protection and alarm system.

26.5 PROTECTION, CONTROL AND ALARM ARRANGEMENTS

26.5.1 LIBS shall be fitted with a local control, management, protection and alarm system (LCS).

The following protection functions shall be provided by the system:
charging and discharging current limitation;
overcurrent protection;
overvoltage and under-voltage protection;
overheating protection.

The following parameters shall be measured:
cell voltage;
cell or module voltage;
output current.

The following parameters shall be displayed at local control stations:
output voltage;
maximum, minimum and average cell voltage;
maximum, minimum and average temperature of cells or modules;
output current.

The following signals shall be given to the ship alarm system:
high temperature of a cell or module;
overvoltage or undervoltage;
battery disconnection;
circuit breaker activation;
data transmission failure;
coolant leakage.

LCS shall be permanently in operation. In case of LCS power interruption, alarm signal shall be activated.

26.5.2 Supercapacitor systems shall be fitted with LCS.

The following parameters shall be measured:
cell voltage;
cell temperature;
module current;
module voltage.

LCS shall be permanently in operation. In case of power interruption, alarm signal shall be activated.

The following parameters shall be displayed at local control stations:
cell overvoltage;
cell overheating;
charging current of reverse polarity;

The following signals shall be given to the ship alarm system:
cell overvoltage;
high ambient temperature;
voltage unbalance of components;
cell overheating;
short circuit to earth;
data transmission failure;
SCS failure or failure of a particular module;
charging current of reverse polarity;
state of charge below the prescribed limit;
coolant temperature above the prescribed upper limit;
cooling system failure;
internal short-circuit of supercapacitor.

26.5.3 Fuel cells (FS) shall be fitted with LCS. The appropriate instrumentation shall apply for measuring the critical parameters enabling safe control of fuel and gas system including bunkering.

The following parameters shall be displayed at local control stations:

cell voltage;

deviations of cell voltage;

exhaust gas temperature;

fuel oil temperature;

current rate.

The following signals shall be given to the ship alarm system:

fuel oil tank level;

overflow;

bunkering;

fuel pump operation;

operation parameters of fuel cells (cell voltage, deviation of cell voltage, exhaust gas temperature, fuel oil temperature and current rate);

ventilation system functioning;

availability of hazardous gases;

availability of vapors;

availability of fluid leakages;

emergency shutdowns;

fire outbreak.

26.5.4 Solar arrays (SA) shall be fitted with LCS.

The following parameters shall be measured:

voltage;

current;

temperature.

26.6 SAFETY

26.6.1 Li-Ion battery system (LIBS) room shall be considered as a machinery space differ from category A, as specified in Part VII "Machinery Installations". LIBS room shall be equipped with the appropriate fixed fire-extinguishing system recommended by the battery manufacturer.

26.6.2 Supercapacitator system (SCS) room shall be considered as a machinery space other than category A, as specified in Part VII "Machinery Installations". SCS room shall be equipped with the appropriate fixed fire-extinguishing system recommended by the supercapacitor manufacturer and complying with the chemical composition of supercapacitor cell electrolyte.

26.6.3 Fuel cells (FC) room shall be equipped with a fixed fire-extinguishing system. Fire-extinguishing system shall comply with the proposed particular FC technology. For minimizing gas explosion probability in FC room, it shall be so designed that to minimize the danger under any operational conditions. Due to the risk of explosive gas leakage, FC room shall be classified as hazardous location referred to zone 1. Thus, equipment and components located in this room shall be of safe type.

26.6.4 During SA choice and installation, the safety of technical maintenance shall be provided taking into account the availability of direct current voltage on SA even in case of deenergizing at a.c. side.

26.7 DESIGN

26.7.1 Mechanical protection of batteries, their connections and control circuits inside the battery shall be provided to avoid damage. Mechanical protection may be provided by a battery case or housing of equipment for batteries intended for installation in the final housing of equipment.

LIB case shall be so designed as to allow changing of battery dimensions during charging and discharging, as recommended by the battery manufacturer.

26.8 SERVICEABILITY

26.8.1 Static source of electrical power (SPS) shall be so designed that to provide easy access to replaceable components and units for repair and technical maintenance.

During repair, ship transport and hoisting equipment and machinery may be used where necessary. SPS shall be arranged taking into consideration the service zones as specified in technical documentation.

26.9 SHIPBOARD OPERATIONAL CONDITIONS

26.9.1 SPS shall be resistant to operational conditions onboard the ships specified in 2.1.

26.10 ARRANGEMENT ONBOARD

26.10.1 No heat sources or flammable materials shall be available in LIBS room.

To avoid loss of way or steering in case of possible SPS failure, no essential devices shall be located in LIBS room, including piping and cables servicing such devices.

Ventilation system shall be provided in LIBS room. LIBS ventilation system, as well as the capacity thereof, shall meet the requirements of 12.10, Part VIII "Systems and Piping".

Ventilation duct walls shall be tight and withstand the temperature of discharged gas.

The following parameters shall be displayed at the local and remote control stations of the ventilation system:

ambient temperature in the room;

alarm signal of ventilation system operation.

Ventilation system shall be supplied by two separate feeders from the main switchboard in accordance with 4.3.1.16.

Where the room temperature exceeds the maximum permissible value, at the failure of ventilation system or fan power interruption, the alarm shall be activated.

In case of failure of ventilation system remote control, there shall be a possibility of control from local station located immediately at the entrance to LIBS room. Failures or faults of ventilation system shall not result in LIBS failures or faults.

LIBS room shall be provided with gas detection system that shall activate the alarm signal upon detection of gas concentrations above the alarm setpoint.

Gas detectors shall be so located that to be capable of gas emission detection as early as possible. Taking into consideration that the evolved gases may be lighter or heavier than air, at least two detectors shall be provided in each room, one detector shall be located in the upper part of LIBS room, and the other one in its lower part. Where LIBS is the main power source, duplication of detectors shall be provided both in the upper and lower parts of the room.

The setpoint of gas detection system activation shall not exceed 30 % LEL, where LEL is the lower explosive limit of gas. With the setpoint exceeded, the following shall be performed automatically:

LIBS shall be disconnected (where LIBS is the main power source, it shall be disconnected only in case of activation of both detectors duplicating each other);

alarm signal shall be given at the navigation bridge;

ventilation in LIBS room shall start to operate;

The following parameters shall be displayed on alarm control panels located in accordance with 7.11.3:

current gas concentration in LIBS room;

setpoint of gas detection system activation;

alarm signal of gas detection system operation.

Gas detection systems shall be supplied by two separate feeders (from the main switchboard and from emergency switchboard).

Failures or faults of gas detection system shall not result in LIBS failures or faults.

26.10.2 No heat sources or flammable materials shall be available in SCS room.

To avoid loss of way or steering in case of possible SCS failure, no equipment of other systems intended for safe navigation, including piping and cables servicing such systems shall be located in SCS rooms.

SCS room shall fitted with the appropriate ventilation system.

The requirements to ventilation systems of SCS rooms are similar to those of LIBS rooms.

SCS room shall be fitted with gas detection system that shall activate alarm signal on the gas detection alarm control panels located in accordance with 7.11.3, upon detection of gas concentrations above the alarm setpoint. The requirements to gas detection systems of SCS rooms are similar to those of LIBS rooms.

26.10.3 FC room shall be considered as a machinery space of category A, in accordance with the provisions of Part VII "Machinery Installations". In addition, it shall be separated by class A-60 structures around the perimeter from all sides adjacent to control stations, escape routes, accommodations, stairs, corridors and other machinery spaces.

FC room shall be fitted with gas detection system that shall activate alarm signal on the gas detection alarm control panels located in accordance with 7.11.3 upon detection of gas concentrations above the alarm setpoint.

26.10.4 In compliance with the recommendations of manufacturer, solar array (SA) installation shall allow for the maximum expansion/contraction of photovoltaic modules within the expected working temperature.

All SA structures shall be made of corrosion-resistant materials.

When calculating SA supporting structures, wind loads and snow loads shall be considered.

26.11 STORAGE

26.11.1 During the storage of SPS spare parts in shipboard condition the requirements specified in the appropriate technical documentation of the manufacturers shall be complied with.

26.12 DISPOSAL

26.12.1 Instructions for disposal shall be marked on SPS or indicated in the operational documentation.

26.13 ACCIDENT CONTAINMENT ONBOARD THE SHIP

26.13.1 A list of organizational and technical measures for SPS accident containment onboard the ship shall be developed by the ship's designer taking into account their structure, characteristics of physical processes, arrangement and other factors.

Russian Maritime Register of Shipping

Rules for the Classification and Construction of Sea-Going Ships
Part XI
Electrical Equipment

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